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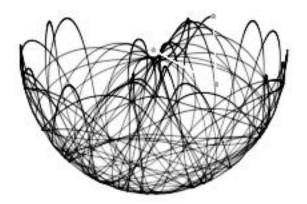
ICS 4UI

Double Pendulum Designer

June 19th, 2018

Project Overview

The Double Pendulum Designer is a user interface application that allows the user to input a set of values and observe the movement of a double pendulum.



What is a Double Pendulum?

The double pendulum consists of one pendulum attached to another. It demonstrates a simple system that exhibits a complex behavior. The chaotic movement of the double pendulum makes it unpredictable.

What do u mean by "chaotic"?

To provide an example, if two pendula with only a difference of initial speed of 0.1, is swung at the same condition their behaviour quickly diverges. This is called chaotic as each pendulum are sensitive to their own conditions.

How Does the Double Pendulum Work?

The motion of the pendulums is governed by a pair of coupled differential equations.

$$\theta_{1}" = \frac{-g\left(2\,m_{1} + m_{2}\right)\sin\theta_{1} - m_{2}\,g\sin(\theta_{1} - 2\,\theta_{2}) - 2\sin(\theta_{1} - \theta_{2})\,m_{2}\left(\theta_{2}^{\;'2}\,L_{2} + \theta_{1}^{\;'2}\,L_{1}\cos(\theta_{1} - \theta_{2})\right)}{L_{1}\left(2\,m_{1} + m_{2} - m_{2}\cos(2\,\theta_{1} - 2\,\theta_{2})\right)}$$

$$\theta_{2}" = \frac{2\sin(\theta_{1} - \theta_{2})\left(\theta_{1}^{\;'2}\,L_{1}\left(m_{1} + m_{2}\right) + g(m_{1} + m_{2})\cos\theta_{1} + \theta_{2}^{\;'2}\,L_{2}\,m_{2}\cos(\theta_{1} - \theta_{2})\right)}{L_{2}\left(2\,m_{1} + m_{2} - m_{2}\cos(2\,\theta_{1} - 2\,\theta_{2})\right)}$$

Input & Output

The user will input values for mass and length. After clicking the [CREATE] button, the screen will display a double pendulum created by a set of uniquely inputted values.

Classes

Main Class - (DoublePendulum.java)

| Fields | |
|------------------------------------|--|
| Int xStart, Int yStart | The x and y value of where the pendulum will be positioned |
| Int l1,Int l2 | The two lengths of the double pendulum |
| Int m1, Int m2 | The two masses of the double pendulum |
| Double angle1,Double angle2 | The starting angles of the pendulum |
| Double angle1Vel, Double angle2Vel | The velocities of the two angles that will change the movement of the pendulum |
| Weight Weight1, Weight Weight2 | Accelerations of the two masses |
| ArrayList array | Array list that keeps track of the second mass |

| | to draw the path |
|---|---|
| ArrayList weight1Acc, ArrayList, weight2Acc | Arraylist that stores the angles and uses it to animate the double pendulum |
| Int time | Index needed to animate the pendulum |
| Int g | Gravity |

Class - (Weight.java)

| Fields | |
|--------------|--------------------------------|
| length | Length connecting the pendulum |
| velocity | Velocity of the weight |
| angle | Angle of the weight |
| acceleration | Acceleration of the weight |
| x2,y2 | x and y values of the pendulum |

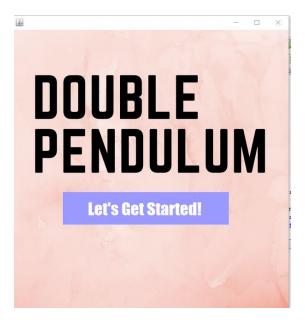
JFrame - OpeningScreen.java

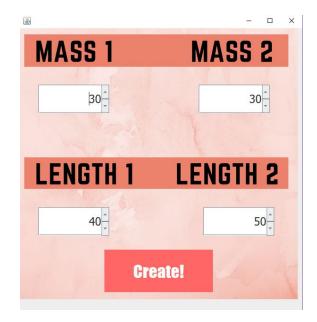
Opening screen for the program

JFrame - Selection.java

JFrame where the user will choose values (two masses, and lengths) for the double pendulum and when the CREATE button is clicked, the main class (DoublePendulum.java) is run.

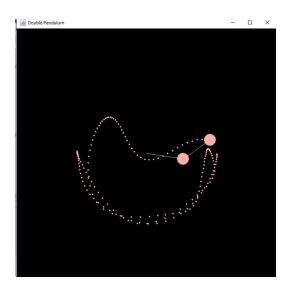
DEMO





First screen of the program

User input the values from the double pendulum



Animates the pendulum