Hidden Markov Random Field model for GWAS

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Introduction

Introduction

- GWAS analysis have been limited to the single SNP or SNP-SNP pair analysis
- If multiple SNPs are all in LD with the true disease variants, using the information from LD can increase power.
- In the paper of Li., LD information among the SNPs derived from the data is incorporated into identifying the disease - associated SNPS.

Introduction

- First build a weighted LD graph based on pairwise LD measures among the SNPs.
- Propose Hidden Markov Random Field model (HMRF) on LD graph in order to compute the posterior probability that an SNP is associated with the disease.
- 3 Propose Empirical Bayes in estimating model parameters.
- Use Iterative Conditional Mode (ICM) algorithm to estimate the parameters and Gibbs sampling for estimating the posterior probabilities.
- **5** Define a FDR to select the relevant SNPs.

Hidden Markov Random Field

Model

Hidden Markov Model

- Hidden Markov Random Field is a generalization of a hidden Markov model. Instead of having an underlying Markov chain, hidden Markov random fields have an underlying Markov random field.
- Markov model is assumed that future states is independent of its history.
- HMM is defined as stochastic processes generated by a Markov chain whose sequence cannot be observed directly ("hidden"), only through a sequence of observations.

Markov Random Field

- Markov Random Field(Undirected Graphical Model) is a probablility distribution p over variables x₁, ..., x_n defined by an undirected graph G which nodes correspond to variables x_i.
- It is similar to Bayesian Network in its representatin of dependencies, but the difference is that Bayesian networks are directed and acyclic, while MRF are undirected and may be cyclic.
- Thus MRF can represent certain dependencies that a Bayesian network cannot.

Example

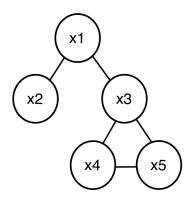


Figure 1: example of the MRF

Markov Random Field

- The probability p has the form $p(x_1,...,x_n)=\frac{1}{Z}\prod_{c\in C}\phi_c(x_c)$
- C denotes the set of cliques of G
- \bullet each factor $\phi_{\it C}$ is a non-negative function over the variables in a clique
- Z is the partition function (normalizing constant).
- Any strictly positive MRF can be written as exponential family in canonical form.

Settings

- There are m cases and n controls that are genotyped over a set of p SNPs. Denote the SNP index as S={1, ..., p}.
- $Y=(Y_1,...,Y_s,...,Y_p)$ is the observed genotype data for the p SNPs. Here, $Y_s=(y_{s1},...,y_{sm};y_{s(m+1)},...,y_{s(m+n)})$, where y_{si} is the observed genotype for the ith individual at the sth SNP.
- Goal: Determine which SNPs in S are associated with the disease.
- To account the LD information in identifying the disease-associated SNPs, develop an HMRF model.

Weighted LD graph

- Construct a weighted undirected LD graph G based on pairwise LD information.
- An edge between SNPs s and s' is drawn with weight $w_{ss'} = I(r_{ss'}^2 > \tau)r_{ss'}^2$.
- au is a given value and $r_{ss'}^2$ is the measurement of LD between SNPs s and s' if $w_{ss'} \neq 0$.

MRF model

For a given SNP s, define a random indicator variable as

$$X_s = egin{cases} 1 & ext{if SNP s is associated with the disease} \\ 0 & ext{if SNP s is not associated with the disease} \end{cases}$$

• Model dependency using a simple discrete Markov Random Field model (Besag, 1974) with the following joint probability function for $X = (X_1, ..., X_p)$:

$$p(X; \Phi) \propto exp(\gamma \sum_{s=1}^{p} X_s + \beta \sum_{s \sim s'} w_{s,s'} I(X_s = X_{s'}))$$

where γ and $\beta \geq 0$ are the two model parameters and β measures dependencies of X_s for SNPs in LD.

MRF model

- Here, assumption is required that true association state X is a realization of a locally dependent discrete MRF with a specified distribution {p(X)}.
- The conditinal association state for SNP s, given the states of all neighboring SNPs is as follows:

$$p(X_s|X_{N_s};\Phi) \propto exp(\gamma \sum_{s=1}^p X_s + \beta \sum_{s \in N_s} w_{s,s'}I(X_s = X_{s'})),$$

where N_s represents the neighbors of the SNP s on the LD graph.

Dirichlet-Multinomial model

• The Dirichlet distribution (Dir($\alpha_1,...,\alpha_K$)) is parameterized by positive scalars $\alpha_i > 0$ for i=1,...,K, where $K \ge 2$. The probability density of $p = (p_1,...,p_K)$ is

$$f(p_1,...,p_K;\alpha_1,...,\alpha_K) = \frac{\Gamma(\sum_{i=1}^K \alpha_i)}{\prod_{i=1}^K \Gamma(\alpha_i)} \prod_{i=1}^K p_i^{\alpha_i-1}.$$

• The Multinomial distribution $(\text{Mult}(p_1,...,p_K,n))$ is a discrete distribution over K dimensional non-negative integer vectors where $\sum_{i=1}^K x_i = n$. And the probability mass function is

$$f(x_{i1},...,x_{iK}; p_1,...,p_K,n) = \frac{n!}{x_{i1}! \cdots x_{iK}!} p_1^{x_{i1}} \cdots p_K^{x_{iK}}$$
$$= \frac{\Gamma(n+1)}{\prod_{k=1}^K \Gamma(x_{ik}+1)} \prod_{k=1}^K p_k^{x_{ik}}.$$

Dirchlet-Multinomial model

• Let $p \sim Dir(\alpha)$ and $x_i \sim Mult(n, p)$, with Data $X = \{x_1, ..., x_n\}$. Then the Posterior is proportional to a Dirichlet distribution:

$$p(\alpha|X) \propto \prod_{i=1}^{n} p(x_i|\alpha)p(\alpha)$$
$$p(\alpha|X) = Dir(\alpha'), \alpha'_k = \sum_{i=1}^{n} x_{ik} + \alpha_k$$

 Marginal distribution is obtained by integrating on the distribution for p as follows:

$$P(x|n,\alpha) = \int_{p} Mult(x|n,p)Dir(p|\alpha)dp$$

$$= \frac{\Gamma(\sum_{k=1}^{K} \alpha_{k})\Gamma(n+1)}{\Gamma(n+\sum_{k=1}^{K} \alpha_{k})} \prod_{k=1}^{K} \frac{\Gamma(x_{k}+\alpha_{k})}{\Gamma(\alpha_{k})\Gamma(x_{k}+1)}$$

Joint probability of the observed genotypes

- To relate the latent vector X to the observed genotypes, assume that given any particular realization of X, the random variables $Y = (Y_1, ..., Y_p)$ are conditionally independent.
- Conditional density is $I(Y|X) = \prod_{s=1}^{p} P(Y_s|X_s)$, where $P(Y_s|X_s)$ is the joint probability of the observed genotypes over m+n individuals at the SNP s given the latent state X_s .

- To specify $P(Y_s|X_s)$, let genotype frequencies at the sth SNP in the case and control population as $\theta_s = (\theta_{s1}, \theta_{s2}, \theta_{s3})$ and $\rho_s = (\rho_{s1}, \rho_{s2}, \rho_{s3})$ respectively.
- Assume that both of these frequencies across all the SNPs have a Dirichlet prior with parameter $\alpha = (\alpha_1, \alpha_2, \alpha_3)$:

$$f(\theta_s) = f(\theta_{s1}, \theta_{s2}, \theta_{s3}) = \frac{\Gamma(\sum_{j=1}^3 \alpha_j)}{\prod_{j=1}^3 \Gamma(\alpha_j)} \prod_{j=1}^3 \theta_{sj}^{\alpha_j - 1}.$$

- Denote the observed genotype counts data in the m cases as $y_{s+} = (y_{s+,1}, y_{s+,2}, y_{s+,3})$, and n controls as $y_{s-} = (y_{s-,1}, y_{s-,2}, y_{s-,3})$.
- If SNP s is not associated with the disease, cases should have the same genotype frequencies with the controls.
- In this case, the combined genotype counts data $y_{s0} = y_{s+} + y_{s-}$ are generated from a multinomial distribution with the genotype frequencies of θ_s .
- On the other hand, if SNP s is associated with the disease, cases and controls should have different genotype frequencies.

•
$$P(Y_s|X_s = 0) = \int (y_{si}; i = 1, ..., m + n | X_s = 0, \theta_s) f(\theta_s) d\theta_s$$

$$= \frac{\Gamma(\sum_{j=1}^3 \alpha_j) \prod_{j=1}^3 \Gamma(\alpha_j + y_{s+,j} + y_{s-,j})}{\prod_{j=1}^3 \Gamma(\alpha_j) \Gamma(\sum_{j=1}^3 (\alpha_j + y_{s+,j} + y_{s-,j}))}$$
• $P(Y_s|X_s = 1) = \int (y_{si}; i = 1, ..., m | X_s = 1, \theta_s) f(\theta_s) d\theta_s$

$$\times \int (y_{si}; i = m + 1, ..., m + n | X_s = 1, \rho_s) f(\rho_s) d\rho_s$$

$$= \frac{\Gamma(\sum_{j=1}^3 \alpha_j) \prod_{j=1}^3 \Gamma(\alpha_j + y_{s+,j})}{\prod_{j=1}^3 \Gamma(\alpha_j) \Gamma(\sum_{j=1}^3 (\alpha_j + y_{s+,j}))}$$

$$\times \frac{\Gamma(\sum_{j=1}^3 \alpha_j) \prod_{j=1}^3 \Gamma(\alpha_j + y_{s-,j})}{\prod_{j=1}^3 \Gamma(\alpha_j) \Gamma(\sum_{j=1}^3 (\alpha_j + y_{s-,j}))}$$

Parameter estimation

ICM algorithm

- To estimate parameters in the MRF model (γ, β) and α (Dirichlet prior parameter), ICM algorithm is used.
- ICM algorithm was introduced for image restoration process.
- It is done by iteratively maximizing the probability of each variable conditioned on the rest.
- There are two assumptions for the algorithm:
 - **1** Given x, the random variable $y_1, ..., y_n$ are conditionally independent and each y_i has the same known conditional density function $f(y_i|x_i)$. (i.e. $I(y|x) = \prod_{i=1}^n f(y_i|x_i)$)
 - The states X are assumed to constitute a Markov Random Field. (i.e. X is a random field whose local conditional probability functions satisfy the Markov property)

ICM algorithm

- Let \hat{x} be an estimate of true x.
- The goal is to update $\hat{x_i}$ at each i given all available information:

$$\underset{x_i}{\operatorname{argmax}} p(x_i|y, \widehat{x}_{S\setminus i}) \propto f(y_i|x_i) p_i(x_i|\widehat{x}_{\delta_i})$$

- Here, $f(y_i|x_i)$ is the probability of an observed data y_i given the color x_i , and $p_i(x_i|\widehat{x}_{\delta_i})$ is the probability of the color x_i given the surrounding neighbors of i.
- initial estimate of \hat{x} is given by just maximizing $f(y_i|x_i)$.
- The procedure defines a cycle when applied to each pixel i in turn.

ICM algorithm

- f 0 Obtain an initial estimate \widehat{X} (based on the single -marker trend test using p-value of 0.0001)
- **2** Estimate α with the value of $\widehat{\alpha}$ by maximizing the probability of the observed data given by $I(Y|X) = \prod_{s=1}^p P(Y_s|X_s)$.
- § Estimate Φ with the value of $\widehat{\phi}$ by maximizing the pseudo-likelihood function:

$$I(\widehat{X}; \Phi) = \prod_{s}^{p} p_{s}(\widehat{X_{s}}|\widehat{X_{N_{s}}}; \Phi) = \\ \prod_{s}^{p} \frac{exp(\gamma \widehat{X_{s}} + \beta \sum_{s' \in N_{s}} w_{s,s'} I(\widehat{X_{s}} = \widehat{X_{s'}}))}{exp(\gamma + \beta \sum_{s' \in N_{s}} w_{s,s'}) I(\widehat{X_{s'}} = 1) + exp(\beta \sum_{s' \in N_{s}} w_{s,s'}) I(\widehat{X_{s'}} = 0)}$$

- **4** Obtain new \widehat{X} based on \widehat{X} , $\widehat{\alpha}$, $\widehat{\phi}$. i.e. for s= 1,...,p, update X_s based on $P(X_s|Y,\widehat{X_{S/s}}) \propto f(Y_s|X_s;\widehat{\alpha})p_s(X_s|\widehat{X}_{N_s};\widehat{\Phi})$.
- $\textbf{ 6} \text{ repeat until } \max_{\theta \in (\alpha,\Phi)} \frac{|\theta^{(k+1)} \theta^{(k)}|}{|\theta^{(k+1)}|} < 0.001.$

FDR controlling Procedure

Gibbs Sampling

- Gibbs Sampling is one of a MCMC algorithm for obtaining a sequence of obervations which are approximated from a specified multivariate distribution, when direct sampling is difficult.
- The point is that given a multivariate distribution, it sample from a conditional distribution than to marginalize by integrating over a joint distribution.
- Gibbs sampling is a special case of Metropolis—Hastings in which the newly proposed state is always accepted with probability one.

Gibbs Sampling

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initialize Y^0, X^0 for \mathbf{j} = \mathbf{1}, \mathbf{2}, \mathbf{3}, \ldots do sample X^j \sim p(X|Y^{j-1}) sample Y^j \sim p(Y|X^j) end for
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FDR control

- After the convergence of the algorithm, sample the latent vector X M times using Gibbs sampling based on the conditional probability in page 19-(4).
- Based on these samples, estimate the posterior probability of $q_s = Pr(X_s = 0|Y)$.
- Sort q_s in descending order as $q_{(s)}$.
- Note that for SNP s, the hypothesis is

 H_{s0} : SNP s is not associated with the disease H_{s1} : SNP s is associated with the disease

FDR control

- Based on the posterior probabilities, let $k = max\{t : \frac{1}{t} \sum_{s=1}^{t} q_{(s)} \le \alpha\}.$
- Then, reject all $H_{(s)}$, s = 1, ..., k
- \bullet This posterior probablility-based definition of FDR has been used in the analysis of microarray gene expression data and has been shown to control the FDR at α

References

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- [2] Besag, J. (1986). On the statistical analysis of dirty pictures. Journal of the Royal Statistical Society Series B: Statistical Methodology, 48(3), 259-279.