

How to make a root file system

1 Preparation:

Download the newest busybox from the following website

<http://www.busybox.net/downloads/>

Currently, we have **busybox-1.20.1.tar.bz2**

The cross compiler is **arm-linux-gcc-4.3.2.tgz**

mkyaffs2image-2k.tar.bz2

2 TODO: mkdir busybox

3 Copy the **【busybox-1.20.1.tar.bz2】** to the **【busybox】** directory

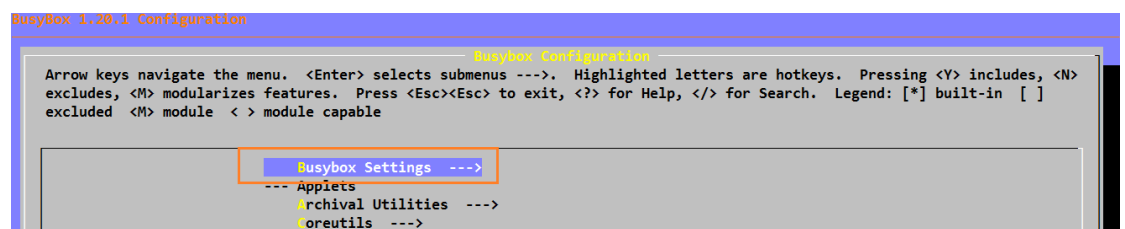
cp busybox-1.20.1.tar.bz2 busybox

4 TODO: tar xjf busybox-1.20.1.tar.bz2

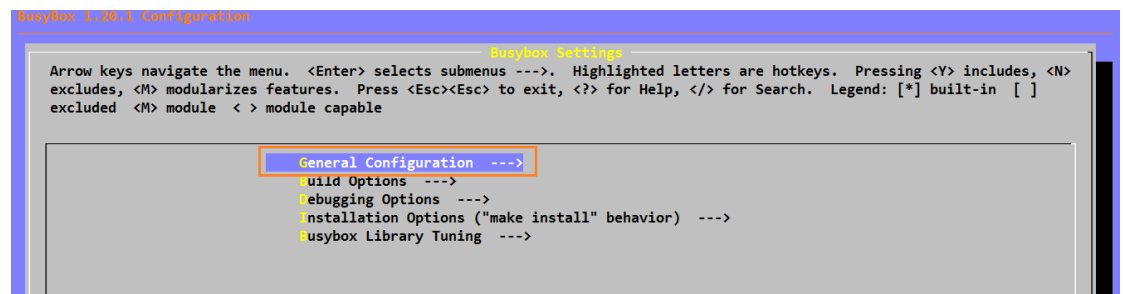
5 TODO: cd busybox-1.20.1

6 TODO: make menuconfig

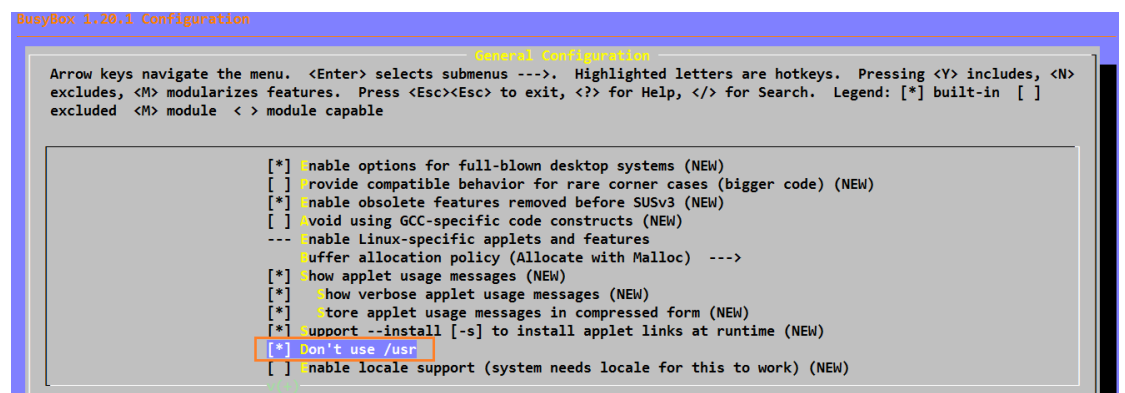
6.1 Choose Busybox Settings --->



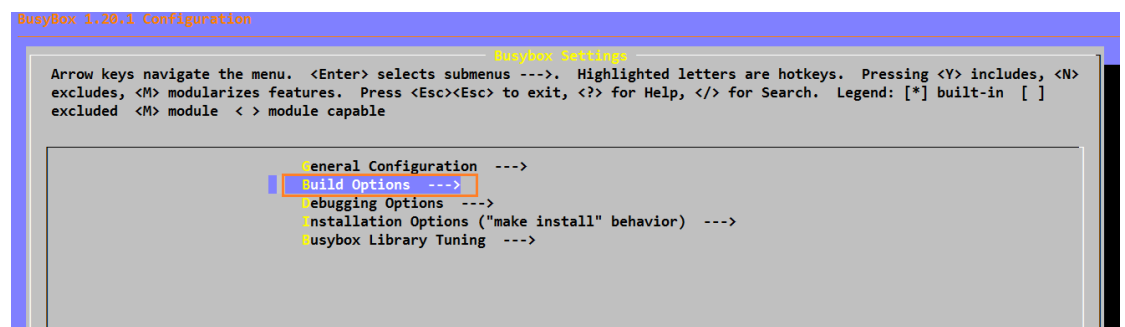
6.2 Choose General Configuration --->



Select [*] Don't use /usr



6.3 Choose Build Options --->



TODO: Enter the name of the cross compiler, in this case, we have, "arm-linux-".

```
BusyBox 1.20.1 Configuration

Build Options
Arrow keys navigate the menu. <Enter> selects submenus ---. Highlighted letters are hotkeys. Pressing <Y> includes, <N>
excludes, <M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </> for Search. Legend: [*] built-in [ ]
excluded <M> module < > module capable

[ ] Build BusyBox as a static binary (no shared libs) (NEW)
[ ] Build BusyBox as a position independent executable (NEW)
[ ] Force NOMMU build (NEW)
[ ] Build shared libbusybox (NEW)
[*] Build with Large File Support (for accessing files > 2 GB) (NEW)
(arm-linux-) Cross Compiler prefix
() Path to sysroot (NEW)
() Additional CFLAGS (NEW)
() Additional LDFLAGS (NEW)
() Additional LDLIBS (NEW)
```

6.4 Specify the busybox installation directory

a) Choose the Installation Options ("make install" behavior) --->

```
BusyBox 1.20.1 Configuration

BusyBox Settings
Arrow keys navigate the menu. <Enter> selects submenus ---. Highlighted letters are hotkeys. Pressing <Y> includes, <N>
excludes, <M> modularizes features. Press <Esc><Esc> to exit, <?> for Help, </> for Search. Legend: [*] built-in [ ]
excluded <M> module < > module capable

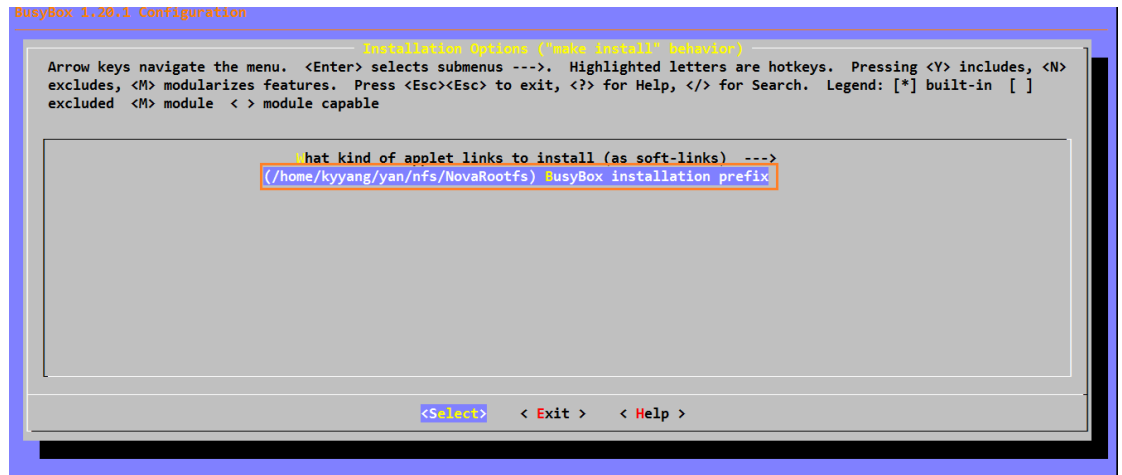
General Configuration --->
Build Options --->
Debugging Options --->
Installation Options ("make install" behavior) --->
Busybox Library Tuning --->

<Select> < Exit > < Help >
```

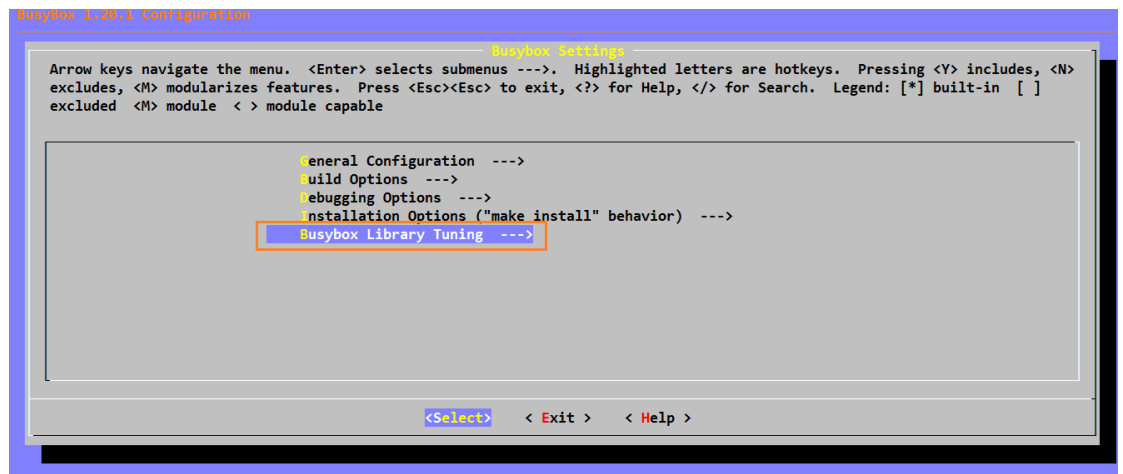
b) Enter the specific busybox installation directory.

In this case, the path is

【/home/kyyang/yan/nfs/NovaRootfs】



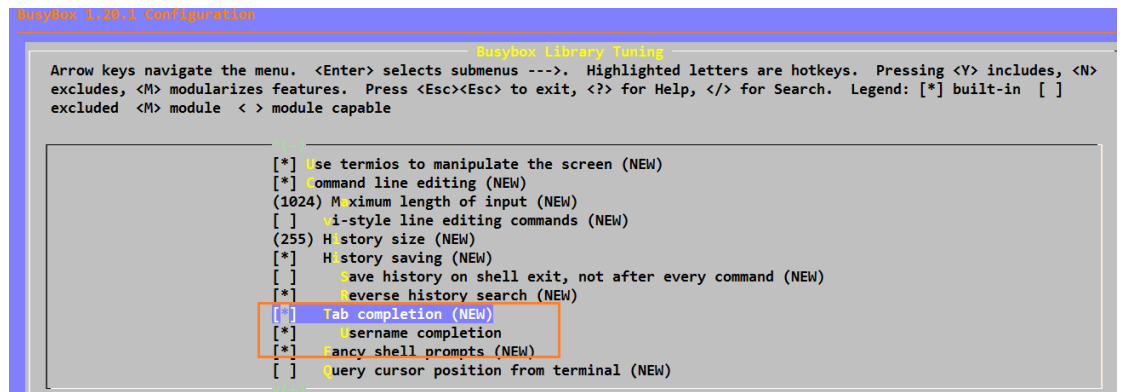
6.5 Choose the Busybox Library Tuning --->



Then, Mark the following options if they are not selected:

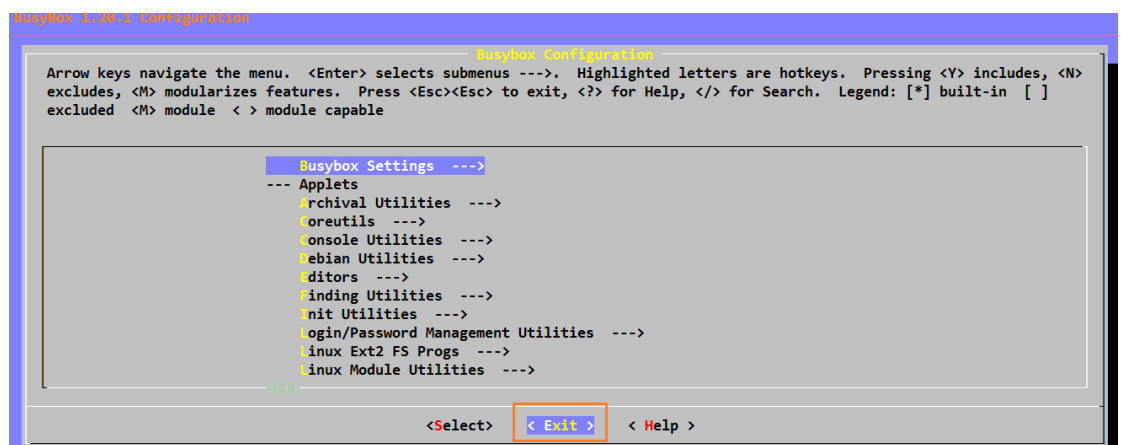
TODO:

- a) [*] Tab completion (NEW)
- b) [*] Username completion
- c) [*] Fancy shell prompts (NEW)

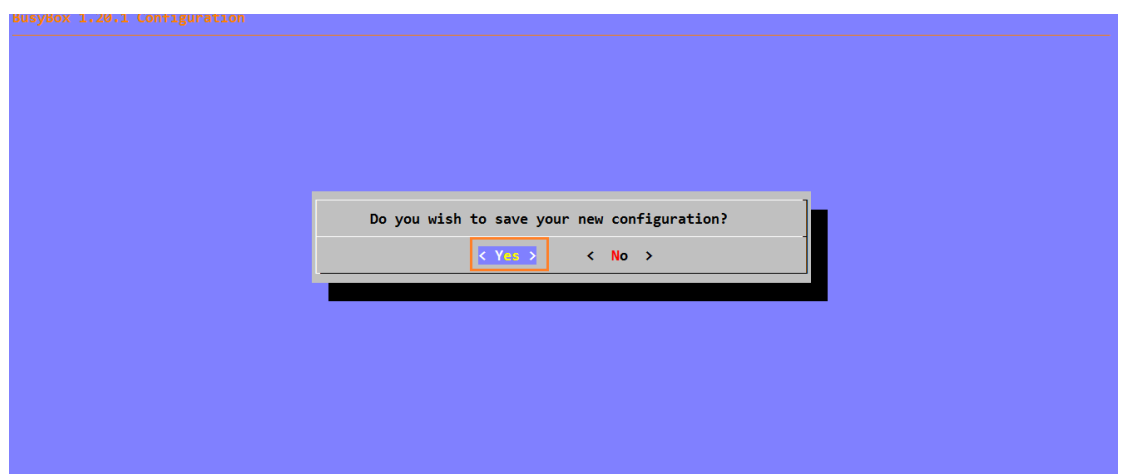


6.6 Save the new configurations and exit

Select Exit or press <Esc> to exit the busybox configuration menu.



Select < Yes > to save the new configuration.



7 Now, compile the busybox

TODO: make

8 Install the busybox to the specific directory 【See 5.4 b)】

TODO: make install

(WARNING: Make sure to specify the installation directory, otherwise, the installation will crush the system).

9 Enter the /home/kyyang/yan/nfs/NovaRootfs directory

TODO:

a) cd /home/kyyang/yan/nfs/NovaRootfs

b) mkdir dev etc home lib mnt proc sys tmp root usr

10 Copy the shared libraries to

/home/kyyang/yan/nfs/NovaRootfs/lib directory.

a) Assume the unzipped path for 【arm-linux-gcc-4.3.2.tgz】 is

【/home/kyyang/yan/cross_compiler/usr】

TODO:

To check what dynamic libraries we needed, enter the following:

arm-linux-readelf -a /home/kyyang/yan/busybox/busybox-1.20.1/busybox | grep "Shared"

```
0x00000001 (NEEDED)           Shared library: [libm.so.6]
0x00000001 (NEEDED)           Shared library: [libc.so.6]
```

//cd /home/kyyang/yan/nfs/NovaRootfs/lib

//cp -d /home/kyyang/yan/cross_compiler/usr/local/arm/4.3.2/arm-none-linux-gnueabi/libc/lib/*.so* .

//cp -d /home/kyyang/yan/cross_compiler/usr/local/arm/4.3.2/arm-none-linux-gnueabi/libc/usr/lib/*.so* .

//cp -d /home/kyyang/yan/cross_compiler/usr/local/arm/4.3.2/arm-none-linux-gnueabi/libc/armv4t/lib/*.so* .

//cp -d /home/kyyang/yan/cross_compiler/usr/local/arm/4.3.2/arm-none-linux-gnueabi/libc/armv4t/usr/lib/*.so* .

```
cd /home/kyyang/yan/nfs/NovaRootfs/lib
```

```
cp /home/kyyang/yan/cross_compiler/usr/local/arm/4.3.2/arm-none-linux-gnueabi/lib/armv4t/lib/*so* . -d
```

```
cd /home/kyyang/yan/nfs/NovaRootfs/usr/lib
```

```
cp /home/kyyang/yan/cross_compiler/usr/local/arm/4.3.2/arm-none-linux-gnueabi/lib/armv4t/usr/lib/*so* . -d
```

11 Create the basic device files under the
/home/kyyang/yan/nfs/NovaRootfs/dev directory

TODO:

a) cd /home/kyyang/yan/nfs/NovaRootfs/dev

b) sudo mknod console c 5 1

c) sudo mknod null c 1 3

d) sudo mknod ttySAC0 c 204 64

e) sudo mknod mtdevblock0 b 31 0

f) sudo mknod mtdevblock1 b 31 1

g) sudo mknod mtdevblock2 b 31 2

h) sudo mknod mtdevblock3 b 31 3

12 Create the configuration file **rcS** under
/home/kyyang/yan/nfs/NovaRootfs/etc/init.d directory

TODO:

a) cd /home/kyyang/yan/nfs/NovaRootfs/etc

b) mkdir init.d

c) vi rcS

d) In the file rcS, input the following content:

```
#!/bin/sh
/sbin/ifconfig lo 127.0.0.1
/sbin/ifconfig eth0 192.168.1.240 netmask 255.255.255.0 up

mount -a
mkdir /dev/pts
mount -t devpts devpts /dev/pts
echo /sbin/mdev > /proc/sys/kernel/hotplug
mdev -s
```

e) chmod +x rcS or sudo chmod +x rcS

13 Create the configuration file **【fstab】** under
/home/kyyang/yan/nfs/NovaRootfs/etc directory

TODO:

a) cd /home/kyyang/yan/nfs/NovaRootfs/etc

b) vi fstab

c) In the file fstab, input the following content:

proc	/proc	proc	defaults	0 0
mdev	/dev	ramfs	defaults	0 0
sysfs	/sys	sysfs	defaults	0 0
tmpfs	/tmp	tmpfs	defaults	0 0
tmpfs	/dev	tmpfs	defaults	0 0

14 Create the configuration file **【inittab】** under
/home/kyyang/yan/nfs/NovaRootfs/etc directory

TODO:

a) cd /home/kyyang/yan/nfs/NovaRootfs/etc

b) vi inittab

c) In the file fstab, input the following content:

```
::sysinit:/etc/init.d/rcS
console::askfirst:/bin/sh
::restart:/sbin/init
::ctrlaltdel:/sbin/reboot
::shutdown:/bin/umount -a -r
::shutdown:/sbin/swapoff -a
```

15 Create the configuration file **【mdev.conf】** under
/home/kyyang/yan/nfs/NovaRootfs/etc directory

TODO:

a) cd /home/kyyang/yan/nfs/NovaRootfs/etc

b) touch > mdev.conf

In order to use nfs to mount the rootfs, we need to
do the following:

16 Under pc linux(such as: Ubuntu)

TODO:

sudo apt-get install nfs-kernel-server

17 Modify the /etc/exports file, adding the following content:

TODO:

a) sudo vi /etc/exports

b) Input the content after the last line

/home/kyyang/yan/nfs/NovaRootfs *(rw,sync,no_root_squash)

18 Restart the nfs server

TODO:

sudo service nfs-kernel-server restart

19 Take effect the above configurations

TODO:

sudo exportfs -a

20 Modify the **【bootargs】** parameter of the U-BOOT.

TODO:

a) Reset the evaluation board, enter the U-BOOT shell prompt.

b) setenv bootargs "noinitrd console=ttySAC0,115200 mem=64M

init=/linuxrc root=/dev/nfs rw

nfsroot=192.168.1.103:/home/kyyang/yan/nfs/NovaRootfs

ip=192.168.1.240:192.168.1.103:192.168.1.1:255.255.255.0:Nov

a:eth0:off"

(Where 192.168.1.103 is the IP of PC, 192.168.1.240 is the IP of the evaluation board, and the 192.168.1.1 is the gateway ip)

c) save

21 Now, restart the linux kernel, the rootfs will be successfully mounted via NFS protocol.

22 If you want to make a rootfs image file (yaffs), do the following:

TODO:

a) tar xjf mkyaffs2image-2k.tar.bz2 -C /

b) sudo chmod +x /usr/local/bin/mkyaffs2image

c) cd /home/kyyang/yan/nfs/

d) sudo mkyaffs2image NovaRootfs/ NovaRootfs.yaffs

e) Copy the NovaRootfs.yaffs to NFS directory

cp NovaRootfs.yaffs /home/kyyang/yan/nfs/nfsroot

23 Under U-BOOT shell prompt

Enter the following commands

a) nfs 30008000 192.168.1.23:/home/kyyang/yan/nfs/nfsroot/NovaRootfs.yaffs
(where 192.168.1.23 is the pc linux IP, /home/kyyang/yan/nfs/nfsroot is the NFS directory).

b) nand erase 0x02D60000 (where 0x02D60000 is the start address of the rootfs)

c) nand write.yaffs 0x30008000 0x02D60000 0x77b8c0

**d) setenv bootargs "noinitrd root=/dev/mtdblock5 rw init=/linuxrc
console=ttySAC0,115200 mem=0x4000000"**

e) save

24 Reset the evaluation board, the kernel will mount the rootfs from the nandflash.