Computer Vision
CSCI 4420

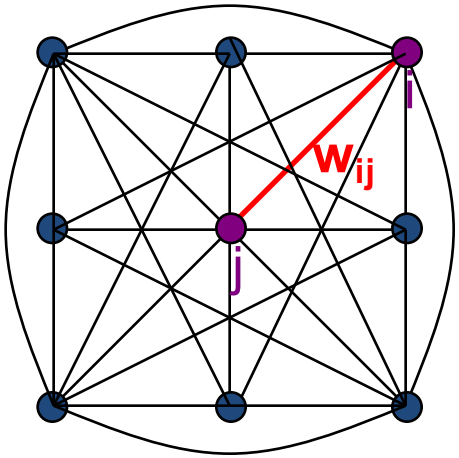
Instructor: Faisal Qureshi

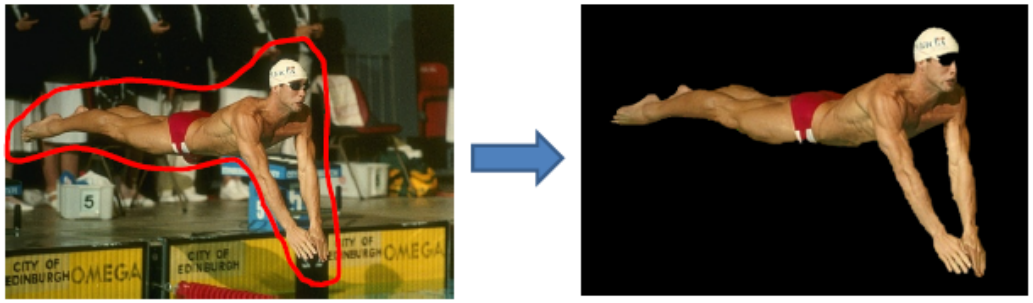
Slides Credit: These slides borrow heavily from on-line resources, particularly from other similar computer vision courses at Brown University, the University of Washington and Stanford.

Segmentation

Today's class

- Segmentation and Grouping
- Inspiration from human perception
  - Gestalt properties
- MRFs
- Segmentation with Graph Cuts



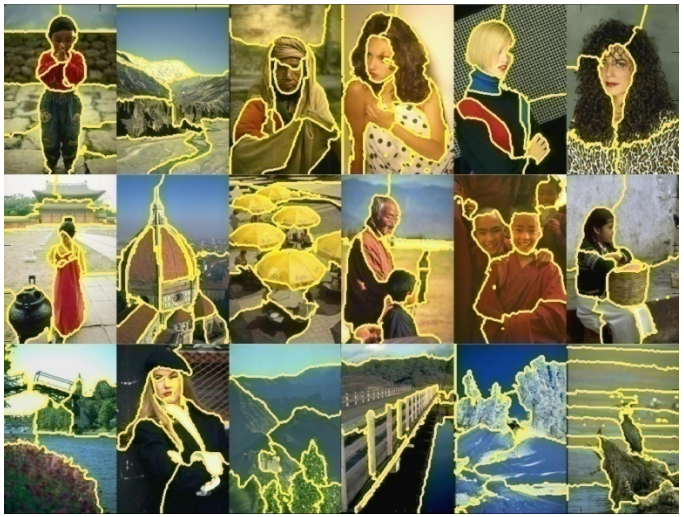


Slide: Derek Hoiem

Grouping in vision

- Goals:
  - Gather features that belong together
  - Obtain an intermediate representation that compactly describes key image or video parts

Examples of grouping in vision



[Figure by J. Shi]

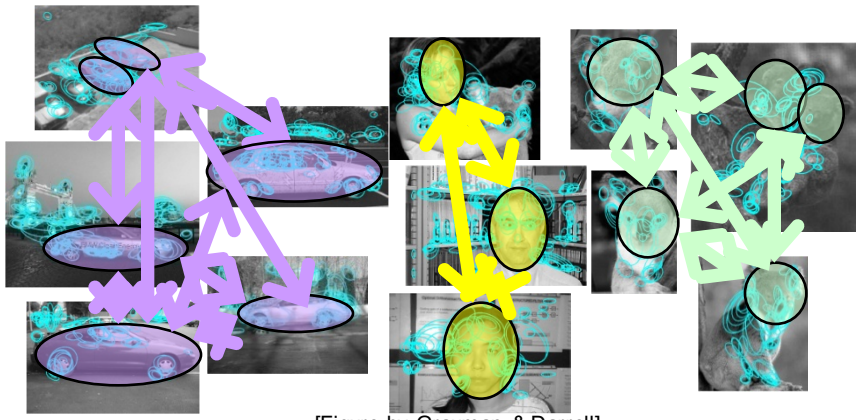
Determine image regions

[http://poseidon.csd.auth.gr/LAB_RESEARCH/Latest/imgs/SpeakDepVidIndex_img2.jpg]

Group video frames into shots

[Figure by Wang & Suter]

Figure-ground



[Figure by Grauman & Darrell]

Object-level grouping

Grouping in vision

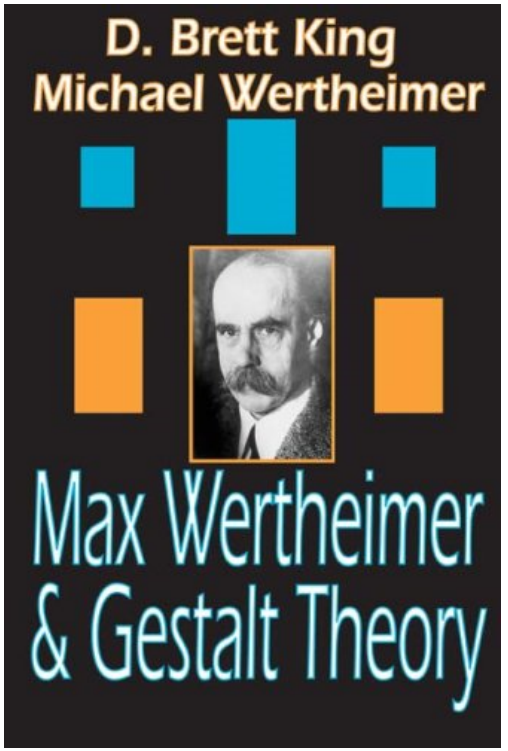
- Goals:
  - Gather features that belong together
  - Obtain an intermediate representation that compactly describes key image (video) parts
- Top down vs. bottom up segmentation
  - Top down: pixels belong together because they are from the same object
  - Bottom up: pixels belong together because they look similar
- Hard to measure success
  - What is interesting depends on the app.

Slide: Kristin Grauman

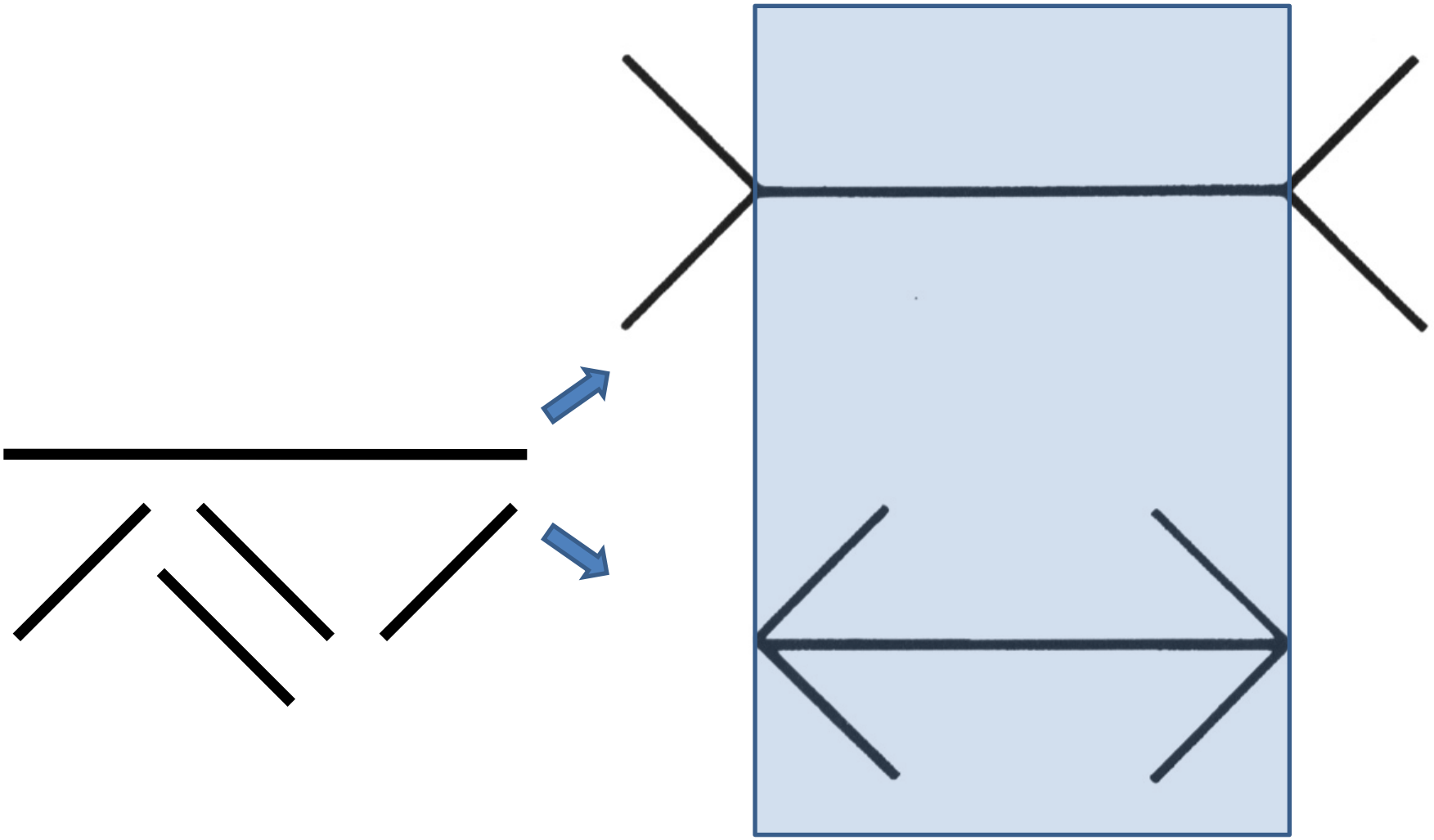
What things should be grouped?
What cues indicate groups?

Gestalt psychology or **Gestaltism**

- German: *Gestalt* - "form" or "whole"
- Berlin School, early 20th century
  - Kurt Koffka, Max Wertheimer, and Wolfgang Köhler
- Gestalt: whole or group
  - Whole is greater than sum of its parts
  - Relationships among parts can yield new properties/features
- Psychologists identified series of factors that predispose set of elements to be grouped (by human visual system)

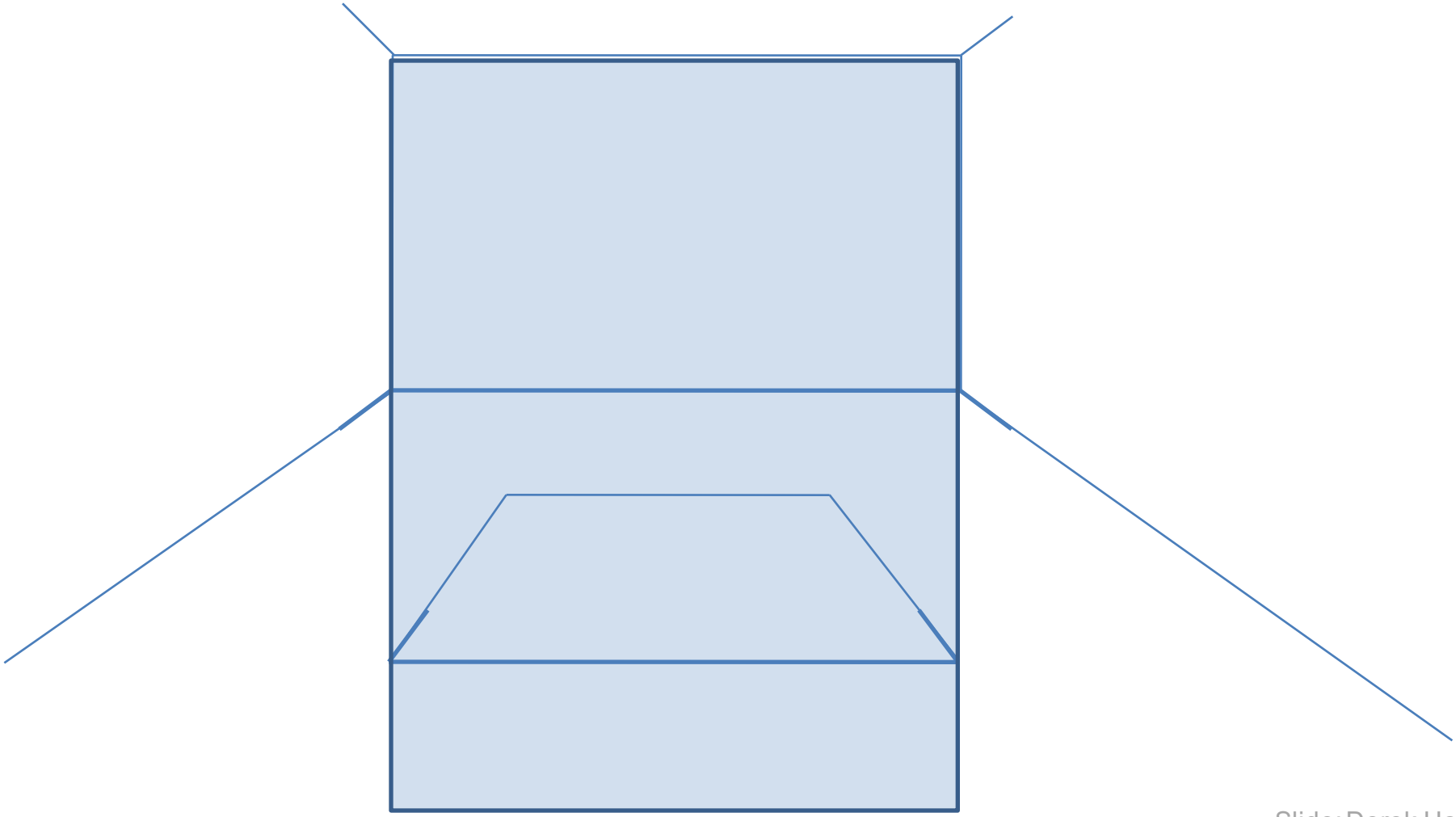


Gestaltism

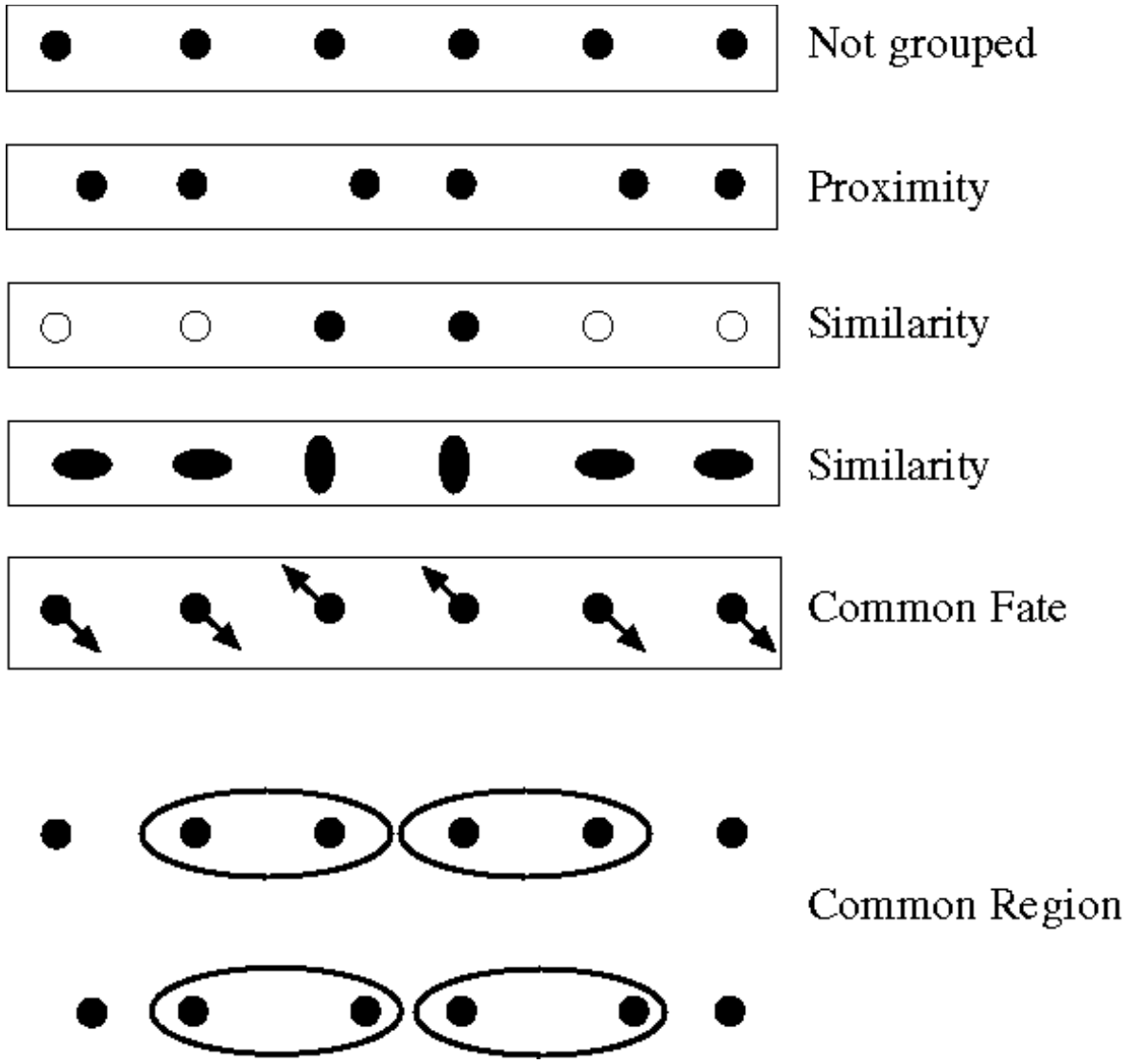


The Muller-Lyer illusion

We perceive the interpretation, not the senses

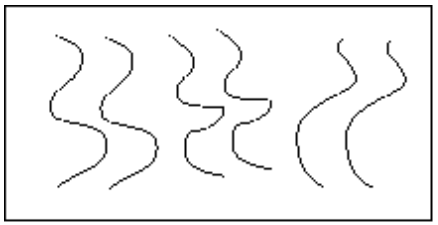


Principles of perceptual organization

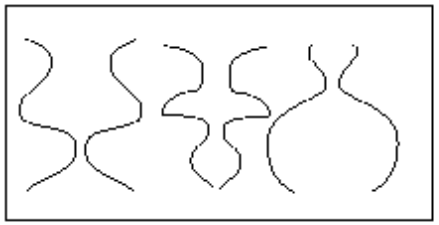


From Steve Lehar: The Constructive Aspect of Visual Perception

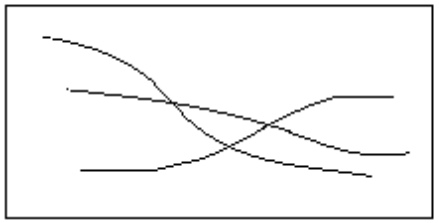
Principles of perceptual organization



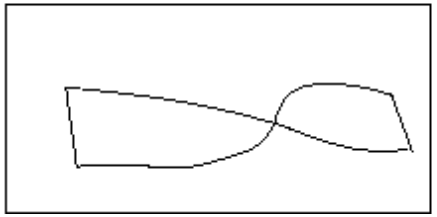
Parallelism



Symmetry



Continuity



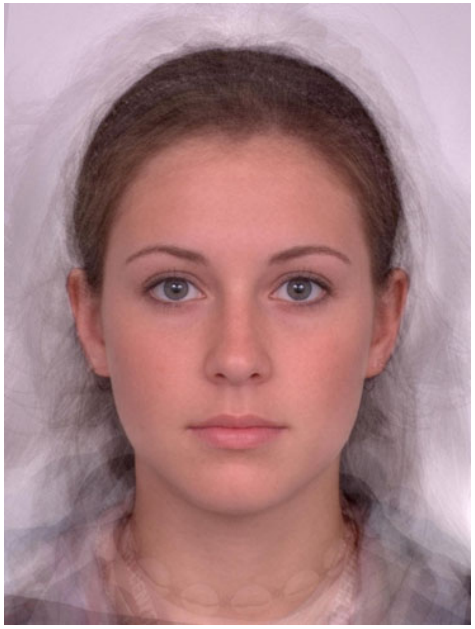
Closure

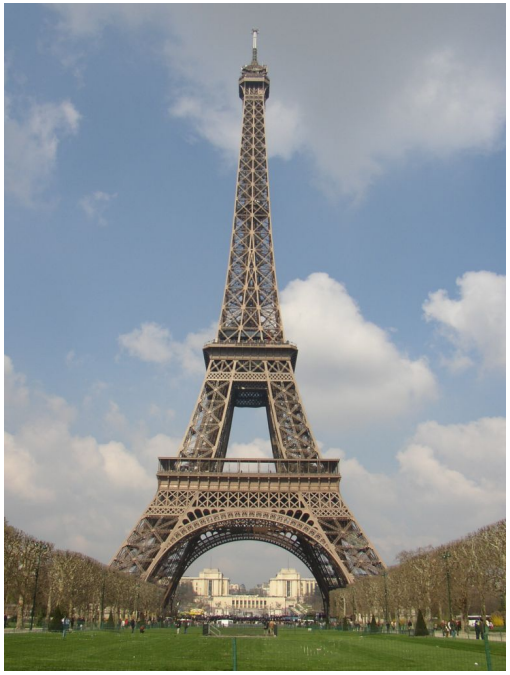
Similarity

http://chicagoist.com/attachments/chicagoist_alicia/GEESE.jpg, http://wwwdelivery.superstock.com/WI/223/1532/PreviewComp/SuperStock_1532R-0831.jpg

Slide: Kristin Grauman

Symmetry





http://seedmagazine.com/news/2006/10/beauty_is_in_the_processingtim.php

Slide: Kristin Grauman

Common fate

Image credit: Arthus-Bertrand (via F. Durand)

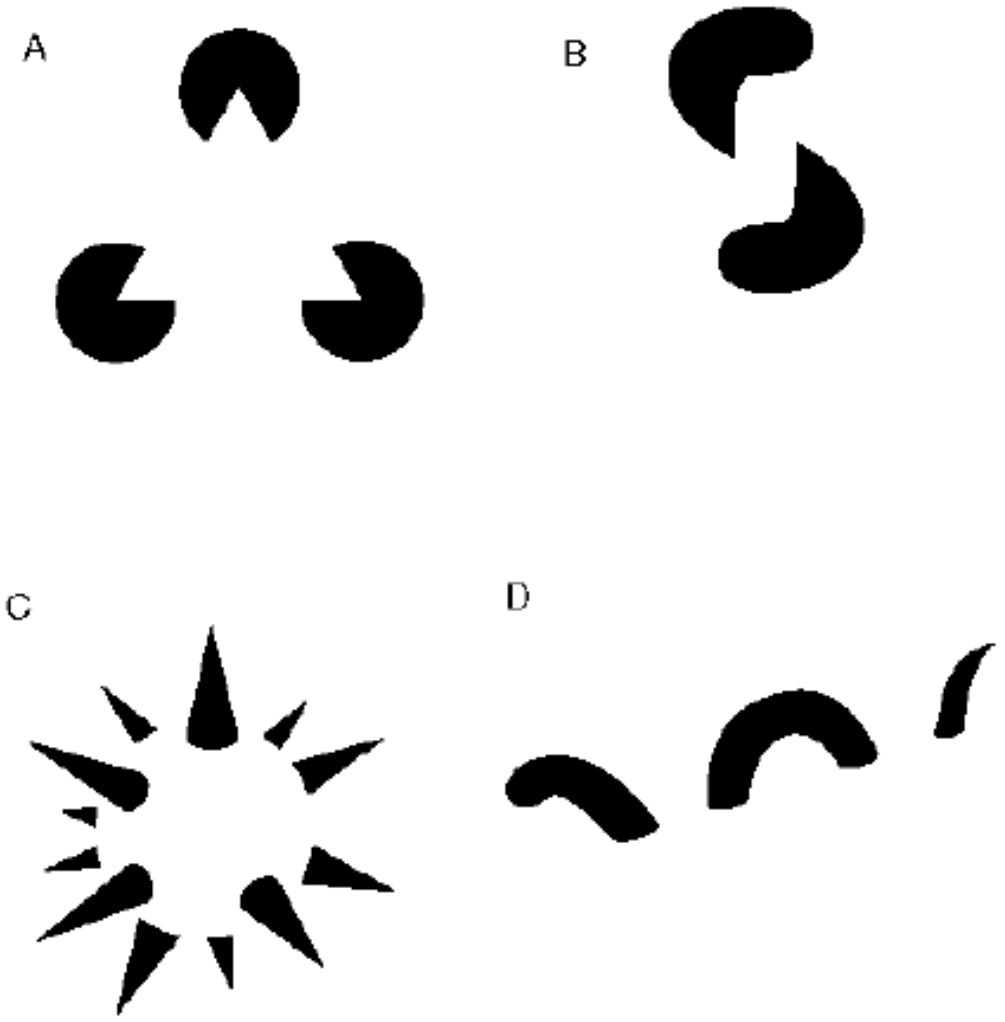
Slide: Kristin Grauman

Proximity

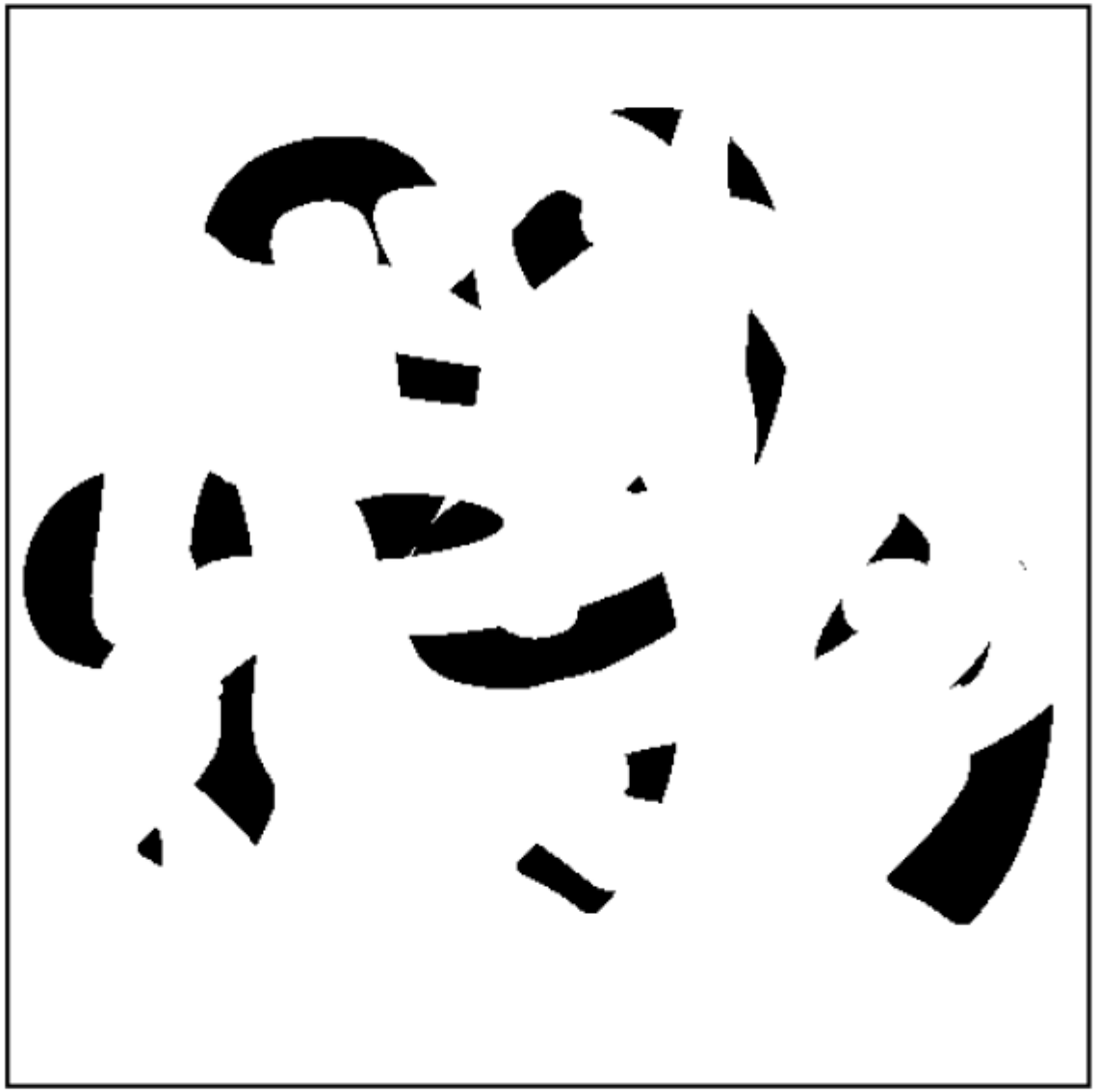
http://www.capital.edu/Resources/Images/outside6_035.jpg

Slide: Kristin Grauman

Grouping by invisible completion

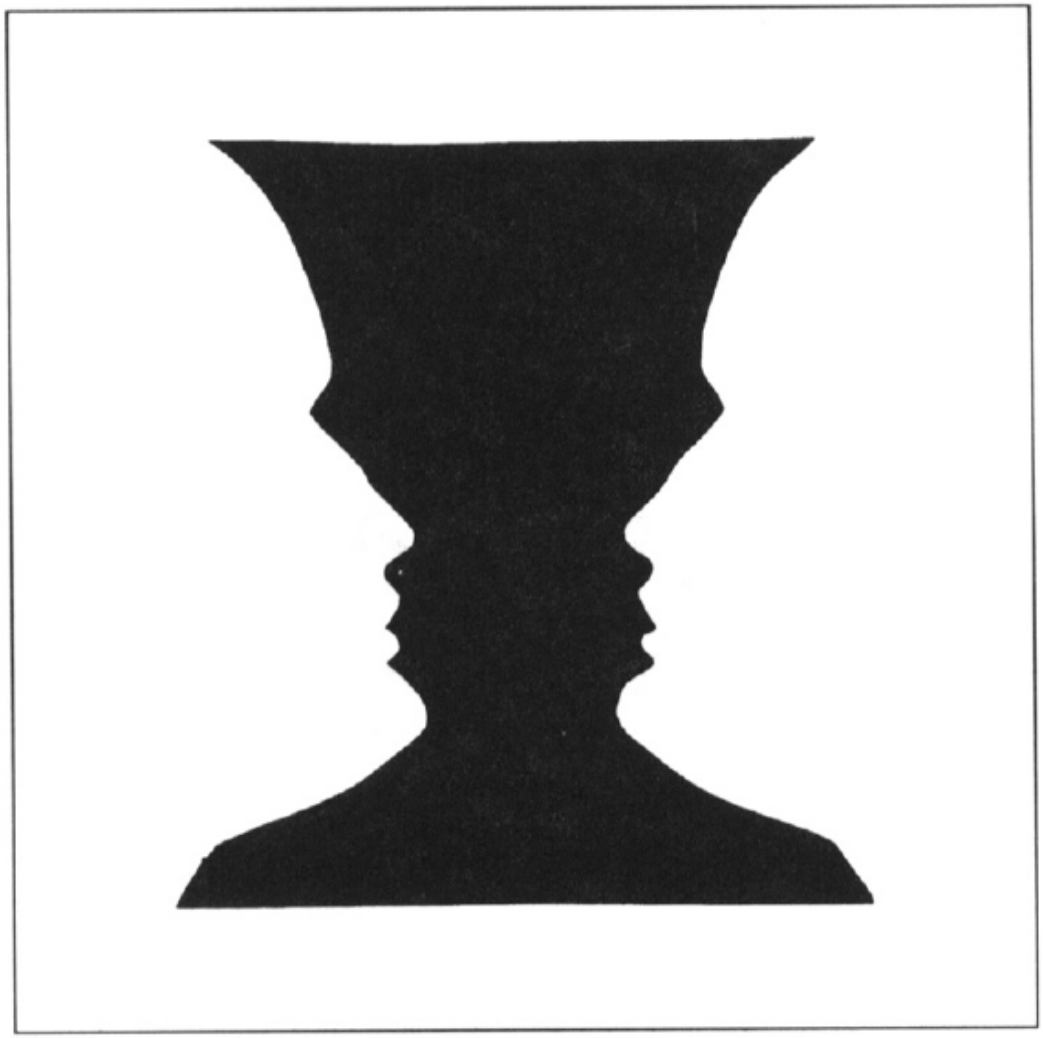


From Steve Lehar: The Constructive Aspect of Visual Perception



D. Forsyth

Figure-ground

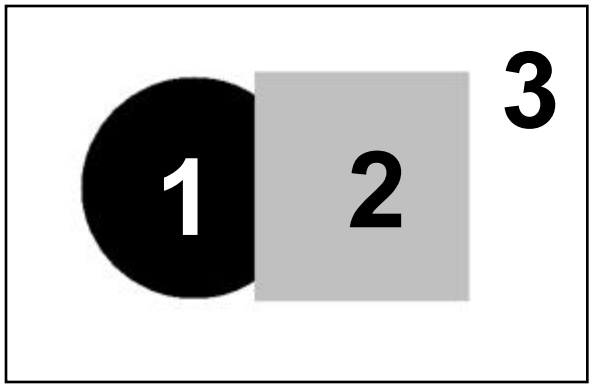


Emergence

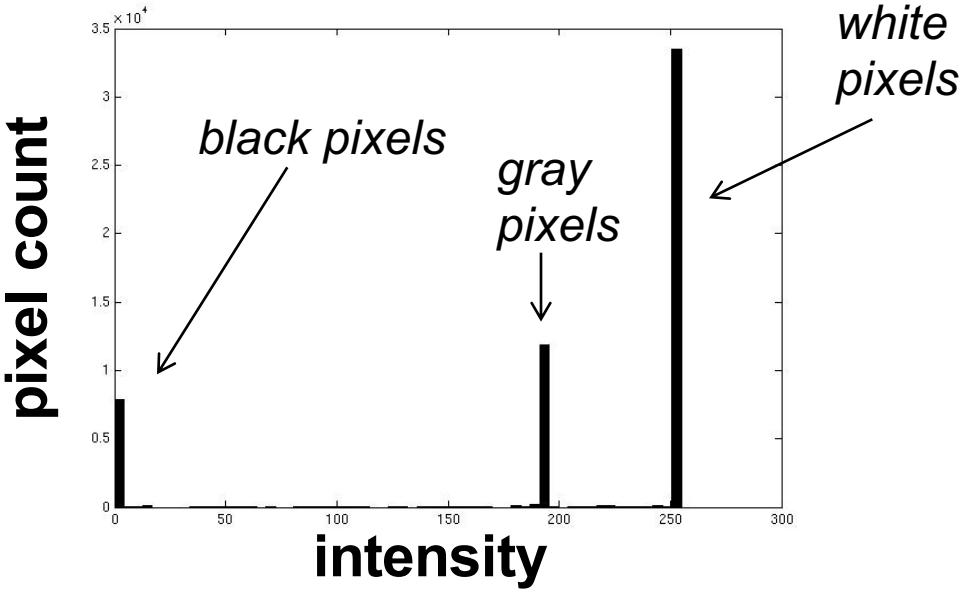
Gestalt cues

- Good intuition and basic principles for grouping
- Basis for many ideas in segmentation and occlusion reasoning
- Some (e.g., symmetry) are difficult to implement in practice

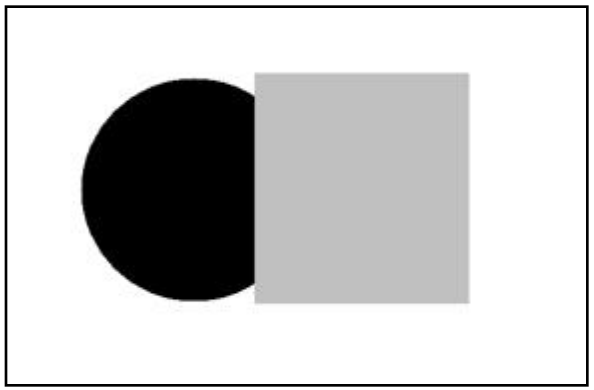
Image segmentation: toy example



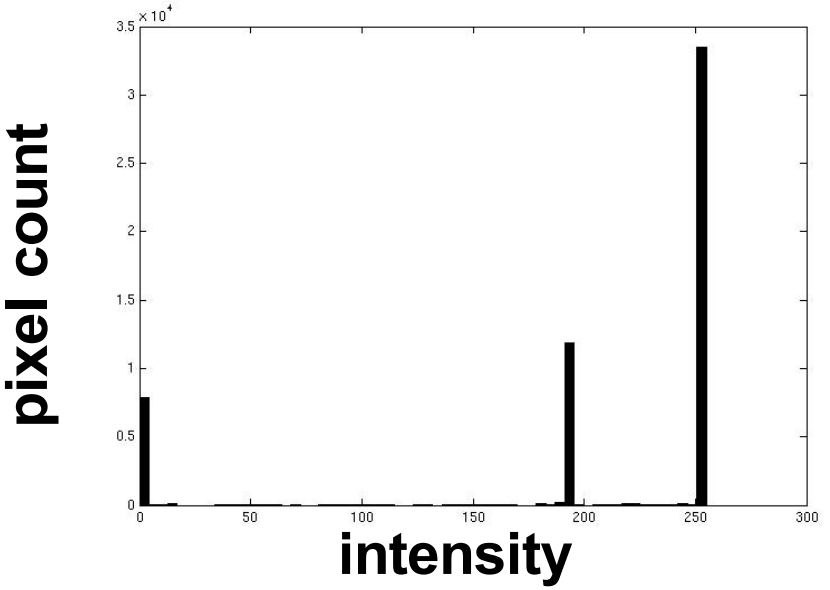
input image

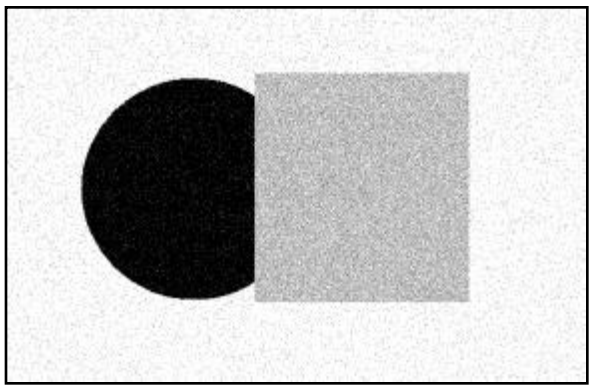


- These intensities define the three groups.
- We could label every pixel in the image according to which of these primary intensities it is.
  - i.e., *segment* the image based on the intensity feature.
- What if the image isn't quite so simple?

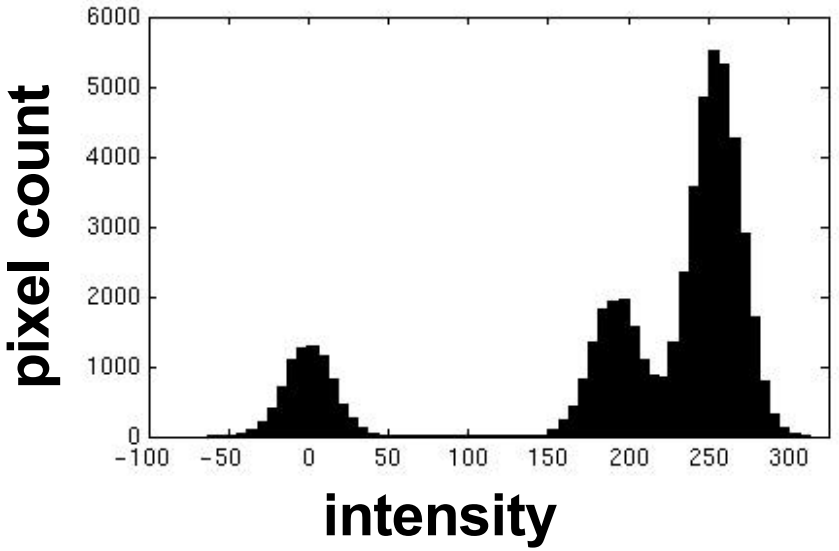


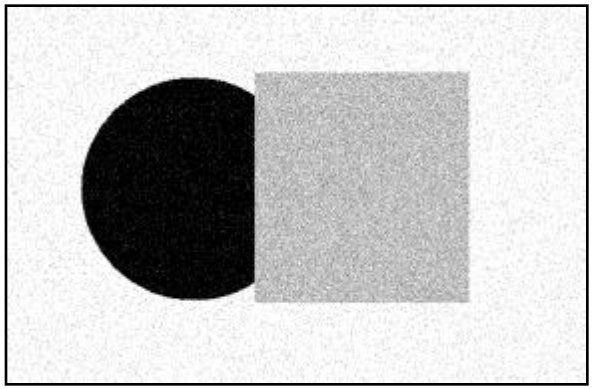
input image



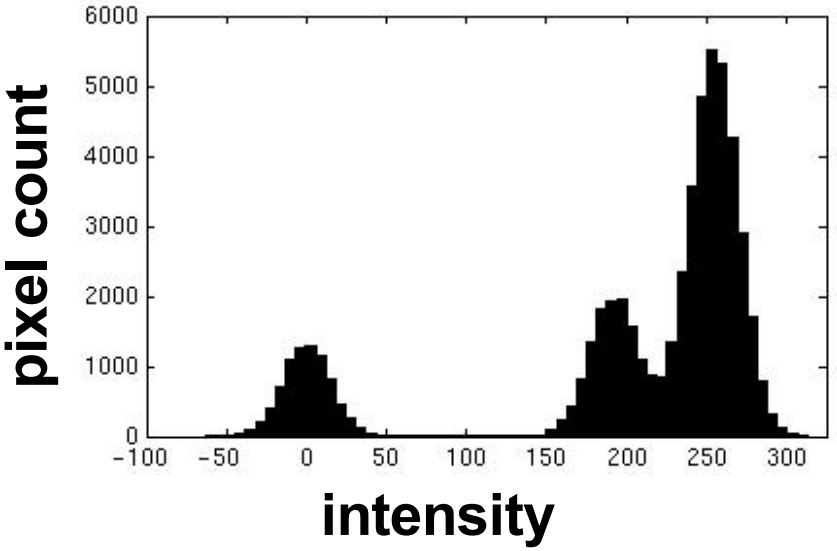


input image

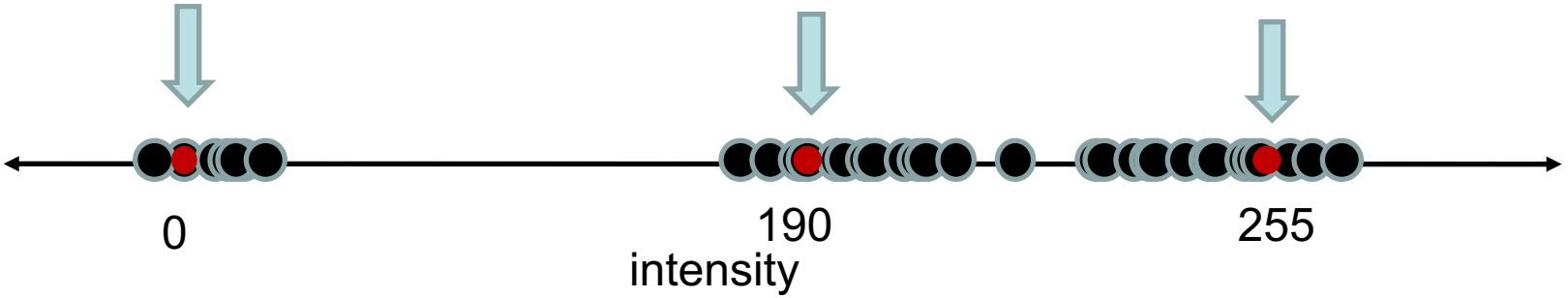


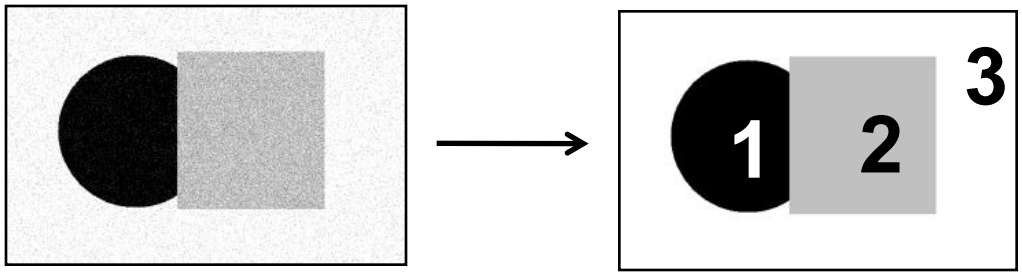


input image



- Now how to determine the three main intensities that define our groups?
- We need to ***cluster.***



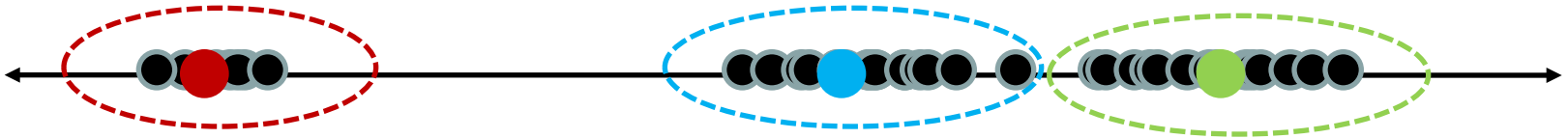


- Goal: choose three "centers" as the representative intensities, and label every pixel according to which of these centers it is nearest to.
- Best cluster centers are those that minimize SSD between all points and their nearest cluster center c_i:

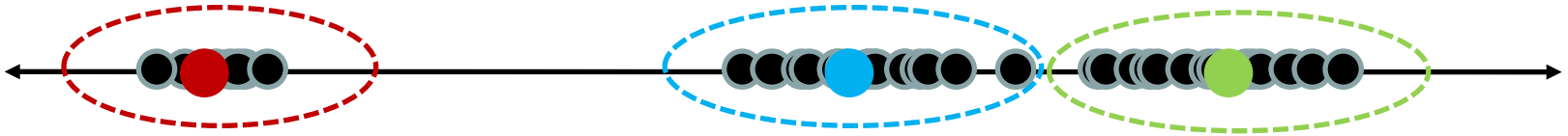
$$\sum_{\text{clusters } i} \sum_{\text{points p in cluster } i} \|p - c_i\|^2$$

Clustering

- With this objective, it is a "chicken and egg" problem:
  - If we knew the **cluster centers**, we could allocate points to groups by assigning each to its closest center.



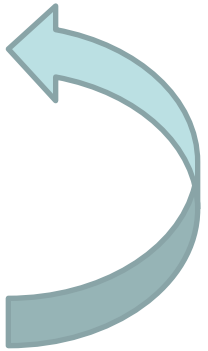
  - If we knew the **group memberships**, we could get the centers by computing the mean per group.



K-means clustering

- Basic idea: randomly initialize the *k* cluster centers, and iterate between the two steps we just saw.

1. Randomly initialize the cluster centers, $c_1, \ldots, c_K$
2. Given cluster centers, determine points in each cluster
   - For each point p, find the closest c_i. Put p into cluster i
3. Given points in each cluster, solve for c_i
   - Set c_i to be the mean of points in cluster i
4. If c_i have changed, repeat Step 2



Properties

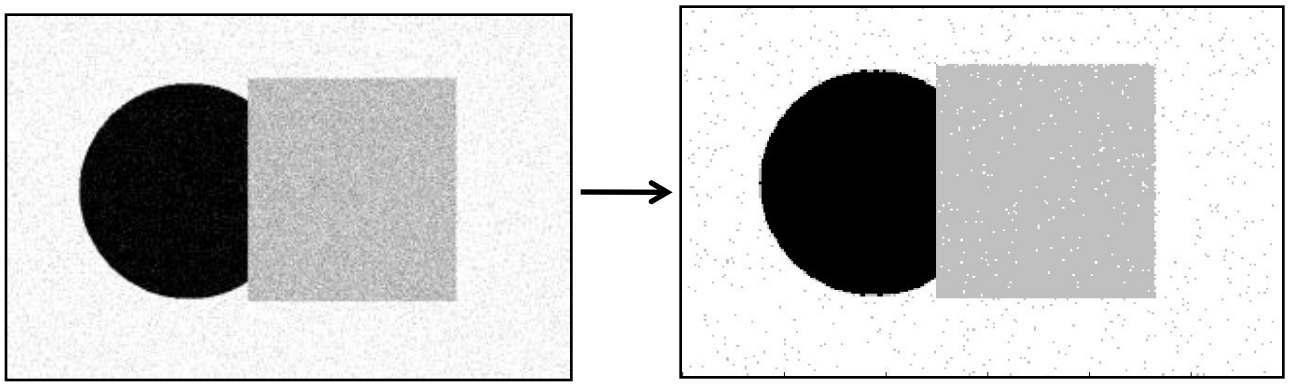
- Will always converge to *some* solution
- Can be a "local minimum"
  - does not always find the global minimum of objective function:

$$\sum_{\text{clusters } i} \sum_{\text{points p in cluster } i} \|p - c_i\|^2$$

Source: Steve Seitz

Smoothing out cluster assignments

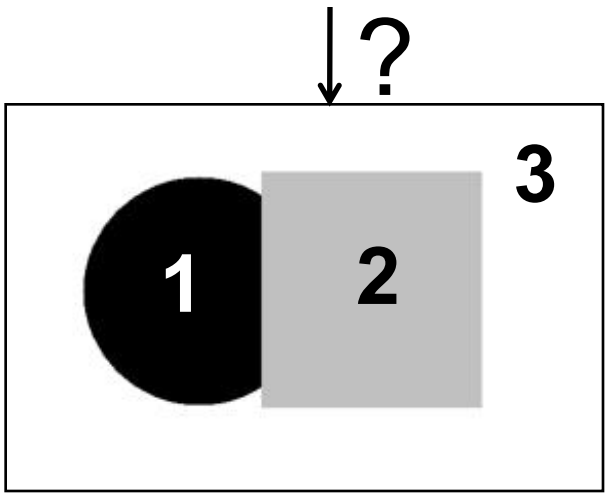
- Assigning a cluster label per pixel may yield outliers:



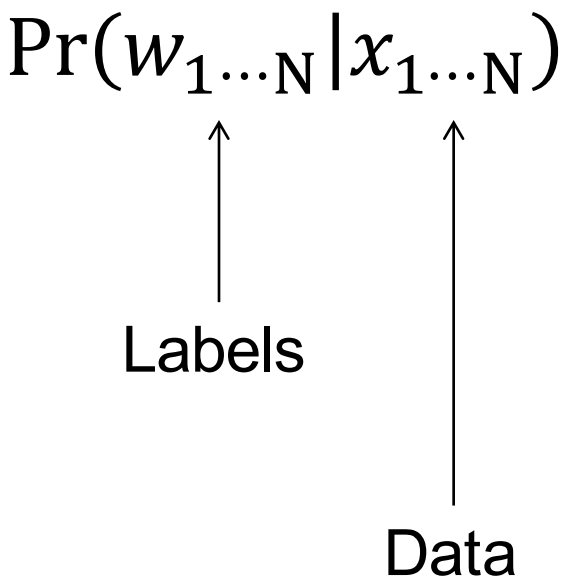
original

labeled by cluster center's intensity

- How to ensure they are spatially smooth?



How to Enforce Smoothness?



How to Enforce Smoothness?

$$\Pr(w_{1\cdots \mathrm{N}}|x_{1\cdots \mathrm{N}}) = \frac{\prod_{n=1}^{N} \Pr(x_n|w_n) \Pr(w_{1\cdots N})}{\Pr(x_{1\cdots N})}$$

Labels

Data

How to Enforce Smoothness?

$$\Pr(w_{1\cdots N}|x_{1\cdots N}) = \frac{\prod_{n=1}^{N} \Pr(x_n|w_n)\,\Pr(w_{1\cdots N})}{\Pr(x_{1\cdots N})}$$

Labels

Data

Prior

How about enforcing a smoothness prior?

How to Enforce Smoothness?

$$\Pr(w_{1\ldots N}|x_{1\ldots N}) = \frac{\prod_{n=1}^{N}\Pr(x_n|w_n)\,\Pr(w_{1\ldots N})}{\Pr(x_{1\ldots N})}$$

Example: Denoise

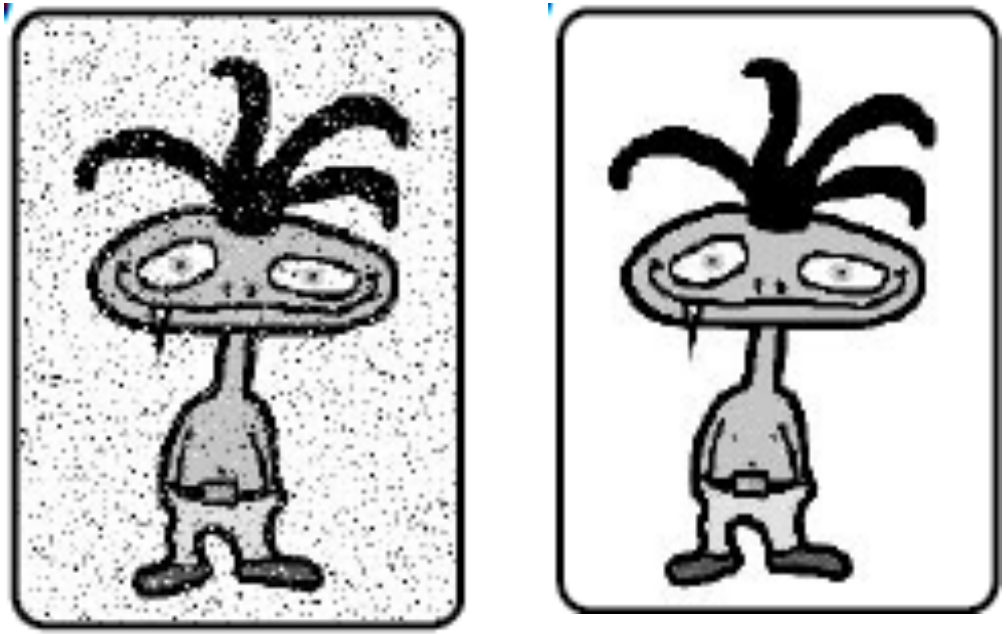
Prior

How about enforcing a smoothness prior?

How to Enforce Smoothness?

$$\Pr(w_{1\ldots N}|x_{1\ldots N}) = \frac{\prod_{n=1}^{N} \Pr(x_n|w_n)\,\Pr(w_{1\ldots N})}{\Pr(x_{1\ldots N})}$$

Example: Denoise



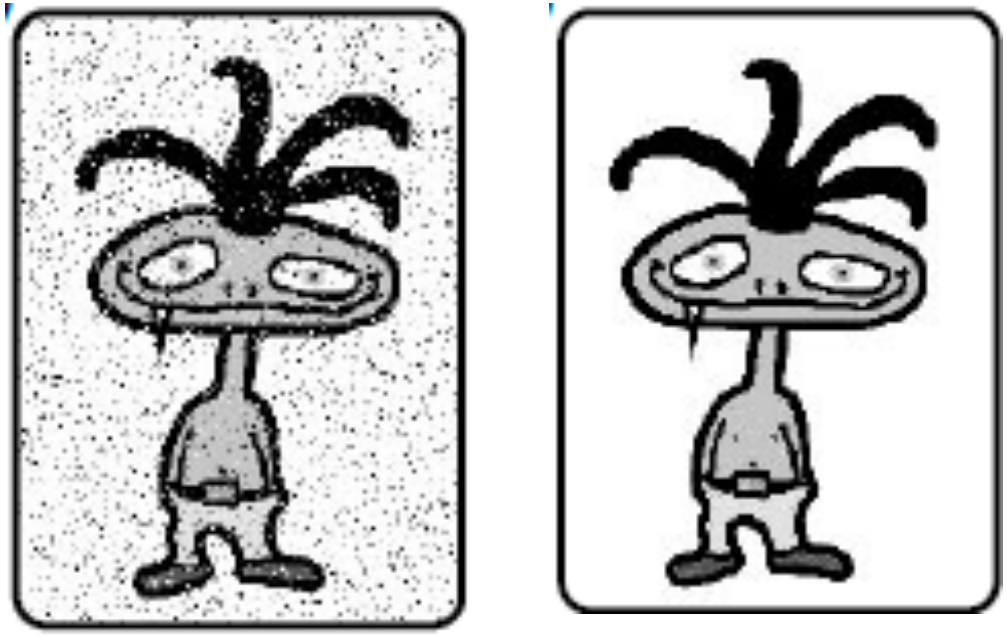
Prior

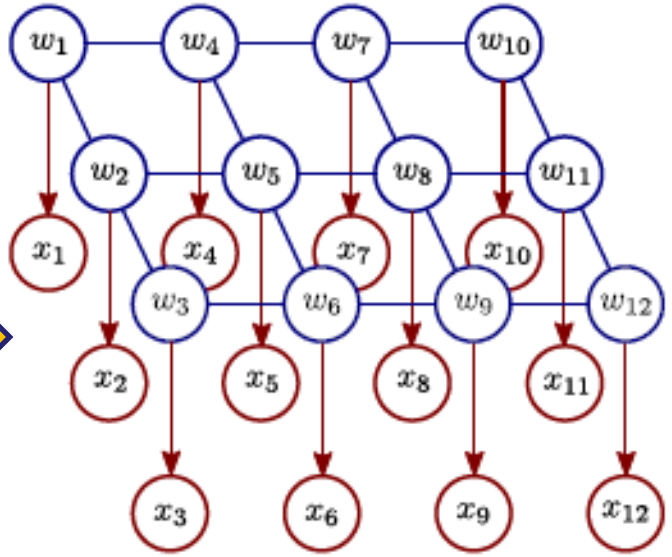
How about enforcing a smoothness prior?

How to Enforce Smoothness?

$$\Pr(w_{1\ldots N}|x_{1\ldots N}) = \frac{\prod_{n=1}^{N} \Pr(x_n|w_n)\,\Pr(w_{1\ldots N})}{\Pr(x_{1\ldots N})}$$

Example: Denoise

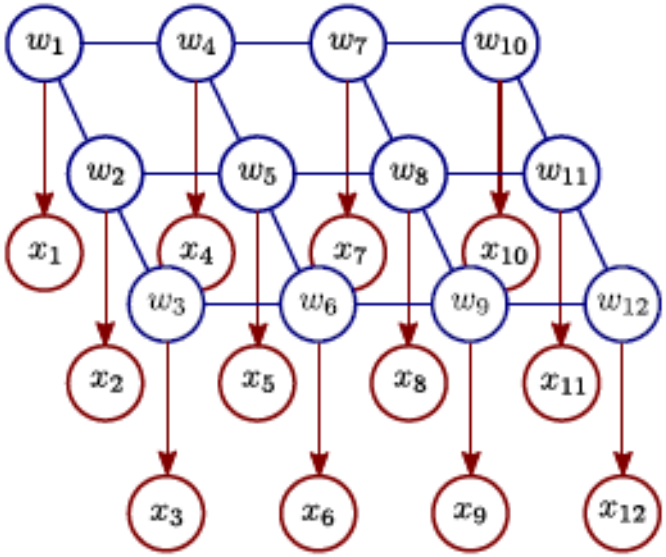




Copyright© by Simon Prince

How to Enforce Smoothness?

$$\Pr(w_{1\ldots N}|x_{1\ldots N}) = \frac{\prod_{n=1}^{N} \Pr(x_n|w_n)\,\Pr(w_{1\ldots N})}{\Pr(x_{1\ldots N})}$$

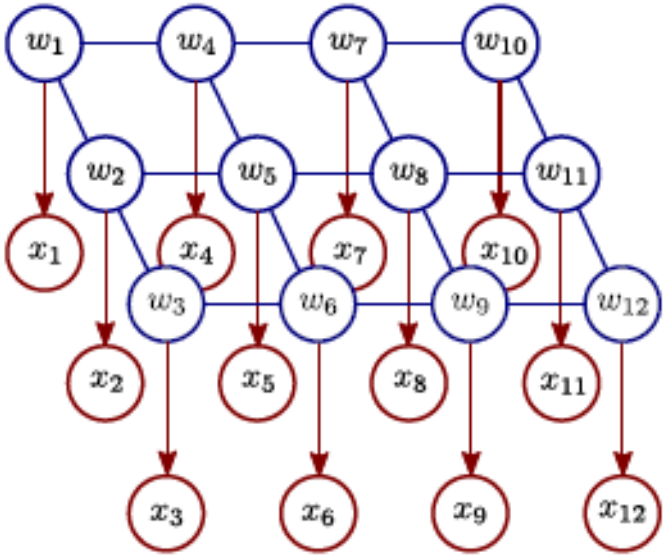


Prior

$$\Pr(w_{1\ldots N}) = \frac{1}{Z}\exp\left(-\sum_{(m,n)\in C}\varphi(w_m, w_n)\right)$$

How to Enforce Smoothness?

$$\Pr(w_{1\ldots N}|x_{1\ldots N}) = \frac{\prod_{n=1}^{N} \Pr(x_n|w_n)\,\Pr(w_{1\ldots N})}{\Pr(x_{1\ldots N})}$$



Prior

$$\Pr(w_{1\ldots N}) = \frac{1}{Z}\exp\left(-\sum_{(m,n)\in C}\varphi(w_m, w_n)\right)$$

Neighboring pixels are more likely to have similar labels

Maximum APosteriori Inference

$$\Pr(w_{1\ldots \mathrm{N}}|x_{1\ldots \mathrm{N}}) = \frac{\prod_{n=1}^{N}\Pr(x_n|w_n)\Pr(w_{1\ldots N})}{\Pr(x_{1\ldots N})}$$

MAP

We aim to find $\{w_n\}$ that maximizes the posterior probability $\Pr(w_{1\ldots \mathrm{N}}|x_{1\ldots \mathrm{N}})$.

$$\begin{aligned}
\hat{w}_{1\ldots N} &= \underset{w_{1\ldots N}}{\operatorname{argmax}}\left[Pr(w_{1\ldots N}|\mathbf{x}_{1\ldots N})\right] \\
&= \underset{w_{1\ldots N}}{\operatorname{argmax}}\left[\prod_{n=1}^{N} Pr(x_n|w_n)Pr(w_{1\ldots N})\right] \\
&= \underset{w_{1\ldots N}}{\operatorname{argmax}}\left[\sum_{n=1}^{N} \log[Pr(x_n|w_n)] + \log[Pr(w_{1\ldots N})]\right]
\end{aligned}$$

Maximum APosteriori Inference

$$\begin{aligned}
\hat{w}_{1\ldots N} &= \underset{w_{1\ldots N}}{\operatorname{argmax}} \left[Pr(w_{1\ldots N}|\mathbf{x}_{1\ldots N}) \right] \\
&= \underset{w_{1\ldots N}}{\operatorname{argmax}} \left[\prod_{n=1}^{N} Pr(x_n|w_n) Pr(w_{1\ldots N}) \right] \\
&= \underset{w_{1\ldots N}}{\operatorname{argmax}} \left[\sum_{n=1}^{N} \log[Pr(x_n|w_n)] + \log[Pr(w_{1\ldots N})] \right]
\end{aligned}$$

Our prior is a Markov Random Field (MRF) with pairwise connections

$$\begin{aligned}
\hat{w}_{1\ldots N} &= \underset{w_{1\ldots N}}{\operatorname{argmax}} \left[\sum_{n=1}^{N} \log[Pr(x_n|w_n)] - \sum_{(m,n)\in\mathcal{C}} \psi[w_m, w_n, \theta] \right] \\
&= \underset{w_{1\ldots N}}{\operatorname{argmin}} \left[\sum_{n=1}^{N} U_n(w_n) + \sum_{(m,n)\in\mathcal{C}} P_{mn}(w_m, w_n) \right],
\end{aligned}$$

Maximum APosteriori Inference

$$\begin{aligned}\hat{w}_{1\ldots N} &= \underset{w_{1\ldots N}}{\operatorname{argmax}}\left[\sum_{n=1}^{N}\log[Pr(x_n|w_n)] - \sum_{(m,n)\in\mathcal{C}}\psi[w_m, w_n, \theta]\right] \\ &= \underset{w_{1\ldots N}}{\operatorname{argmin}}\left[\sum_{n=1}^{N}U_n(w_n) + \sum_{(m,n)\in\mathcal{C}}P_{mn}(w_m, w_n)\right],\end{aligned}$$

$U_n(w_n)$ denotes the unary term at pixel n.

Cost of observing the value x_n given w_n.

$P_{mn}(w_m, w_n)$ denotes the pairwise term.

Cost of assigning labels w_n and w_m at neigboring pixels n and m.

Maximum APosteriori Inference

$$\hat{w}_{1\ldots N} = \underset{w_{1\ldots N}}{\operatorname{argmax}} \left[\sum_{n=1}^{N} \log[Pr(x_n|w_n)] - \sum_{(m,n)\in\mathcal{C}} \psi[w_m, w_n, \theta] \right]$$

$$= \underset{w_{1\ldots N}}{\operatorname{argmin}} \left[\sum_{n=1}^{N} U_n(w_n) + \sum_{(m,n)\in\mathcal{C}} P_{mn}(w_m, w_n) \right],$$

This cost function can be solved using a set of techniques called Graph Cuts.

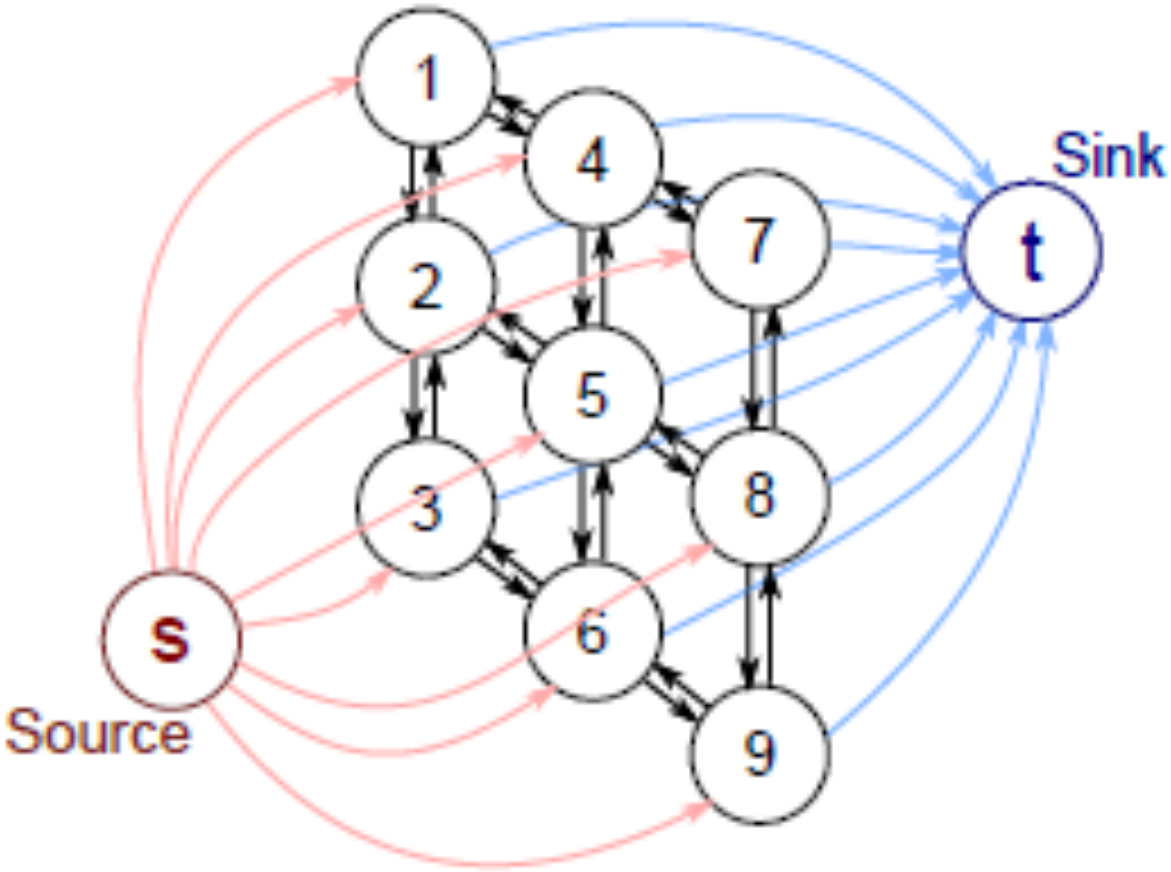
$U_n(w_n)$ denotes the unary term at pixel n.

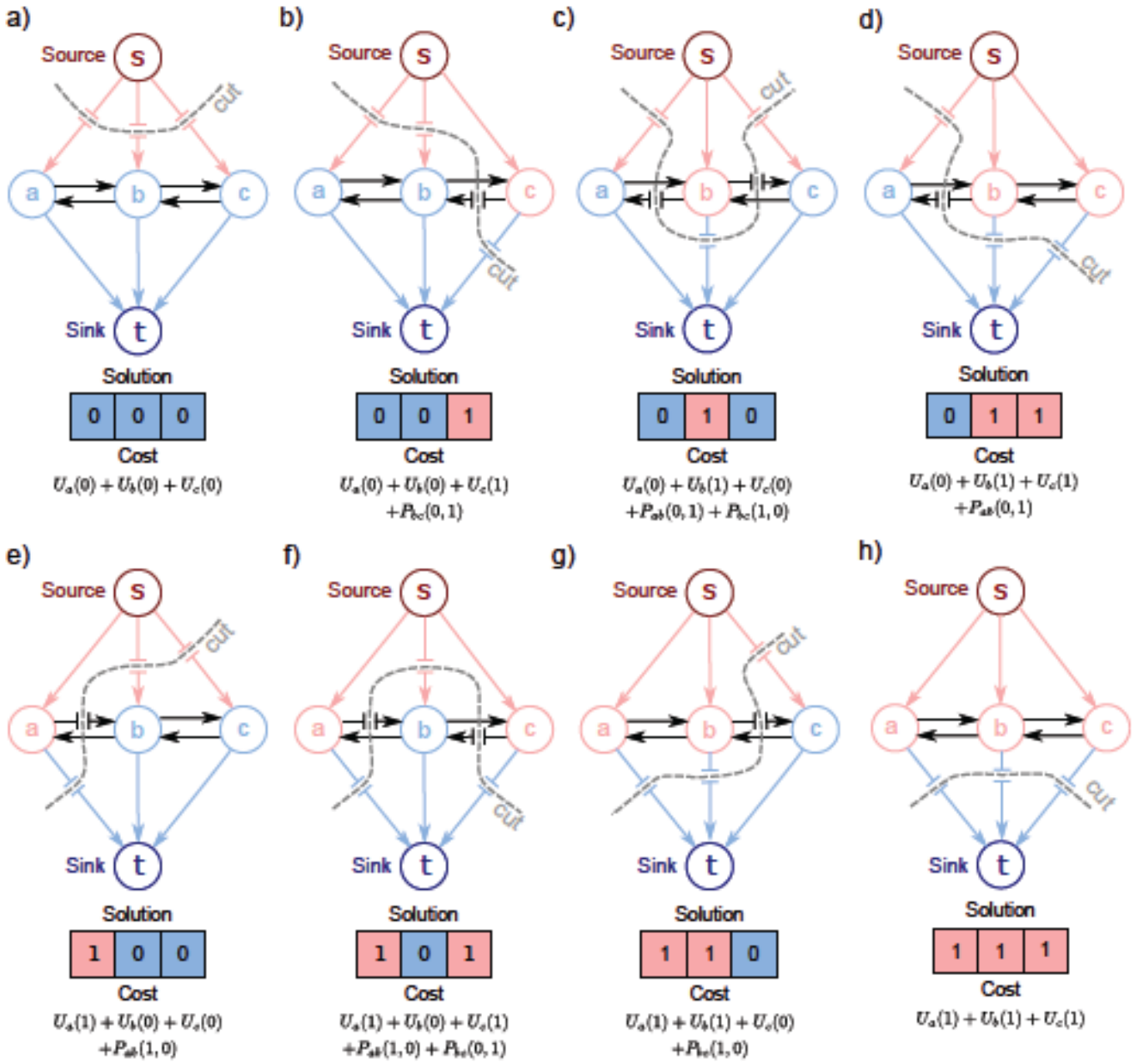
Cost of observing the value x_n given w_n.

$P_{mn}(w_m, w_n)$ denotes the pairwise term.

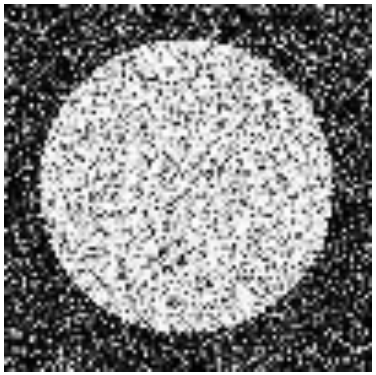
Cost of assigning labels w_n and w_m at neigboring pixels n and m.

Detour: Graph Cuts





Solution



P(foreground | image)

Encode dependencies between pixels

Normalizing constant

$$P(\mathbf{y} \mid \theta, data) = \frac{1}{Z} \prod_{i=1..N} f_1(y_i \mid \theta, data) \prod_{i,j \in edges} f_2(y_i, y_j \mid \theta, data)$$

Labels to be predicted

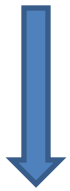
Individual predictions

Pairwise predictions

Slide: Derek Hoiem

Writing Likelihood as an "Energy"

$$P(\mathbf{y} \mid \theta, data) = \frac{1}{Z} \prod_{i=1..N} p_1(y_i \mid \theta, data) \prod_{i,j \in edges} p_2(y_i, y_j \mid \theta, data)$$

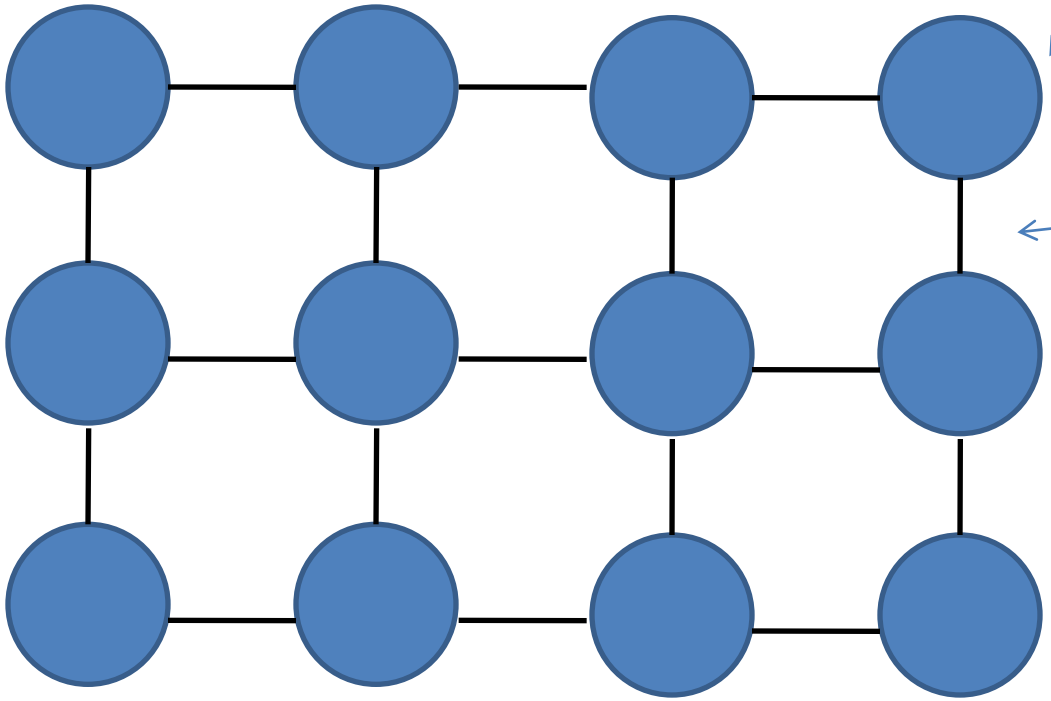


$$Energy(\mathbf{y} \mid \theta, data) = \sum_i \psi_1(y_i \mid \theta, data) + \sum_{i,j \in edges} \psi_2(y_i, y_j \mid \theta, data)$$

"Cost" of assignment y_i

"Cost" of pairwise assignment y_i ,y_j

Markov Random Fields



Cost to assign a label to each pixel

Cost to assign a pair of labels to connected pixels

$$Energy(w \mid \theta, data) = \sum_n U_n(w_n) + \sum_{(m,n) \in edges} P_{mn}(w_m, w_n)$$

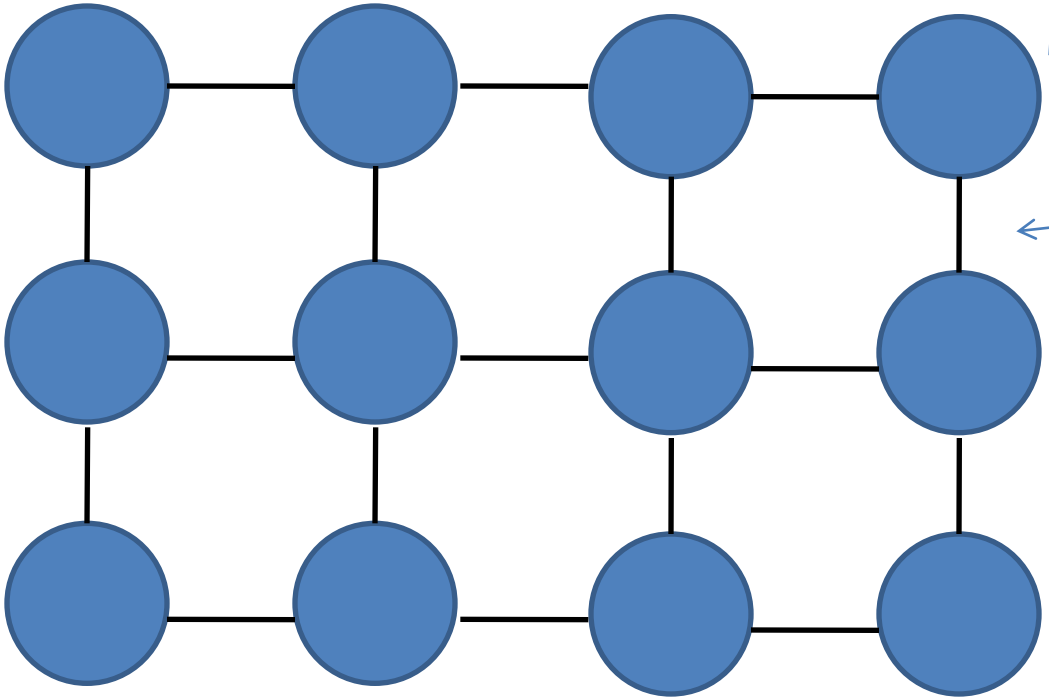
Source: Derek Hoiem

Markov Random Fields

- Example: “label smoothing” grid

Unary potential

0: -logP(w_n = 0| data)
1: -logP(w_n = 1| data)



Pairwise Potential

	0	1
0	0	K
1	K	0

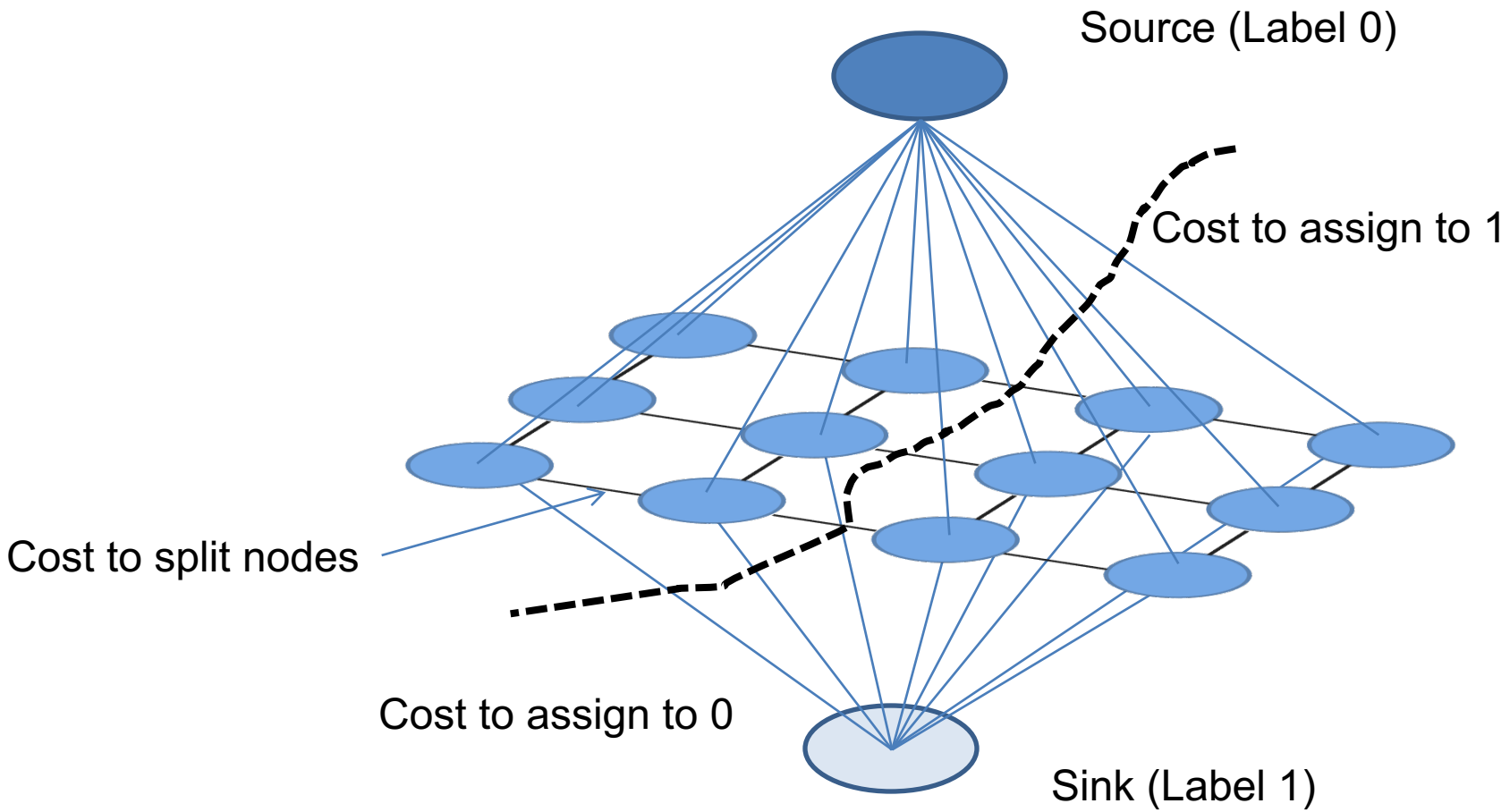
Cost to assign a label to each pixel

Cost to assign a pair of labels to connected pixels

$$Energy(w \mid \theta, data) = \sum_n U_n(w_n) + \sum_{(m,n) \in edges} P_{mn}(w_m, w_n)$$

Source: Derek Hoiem

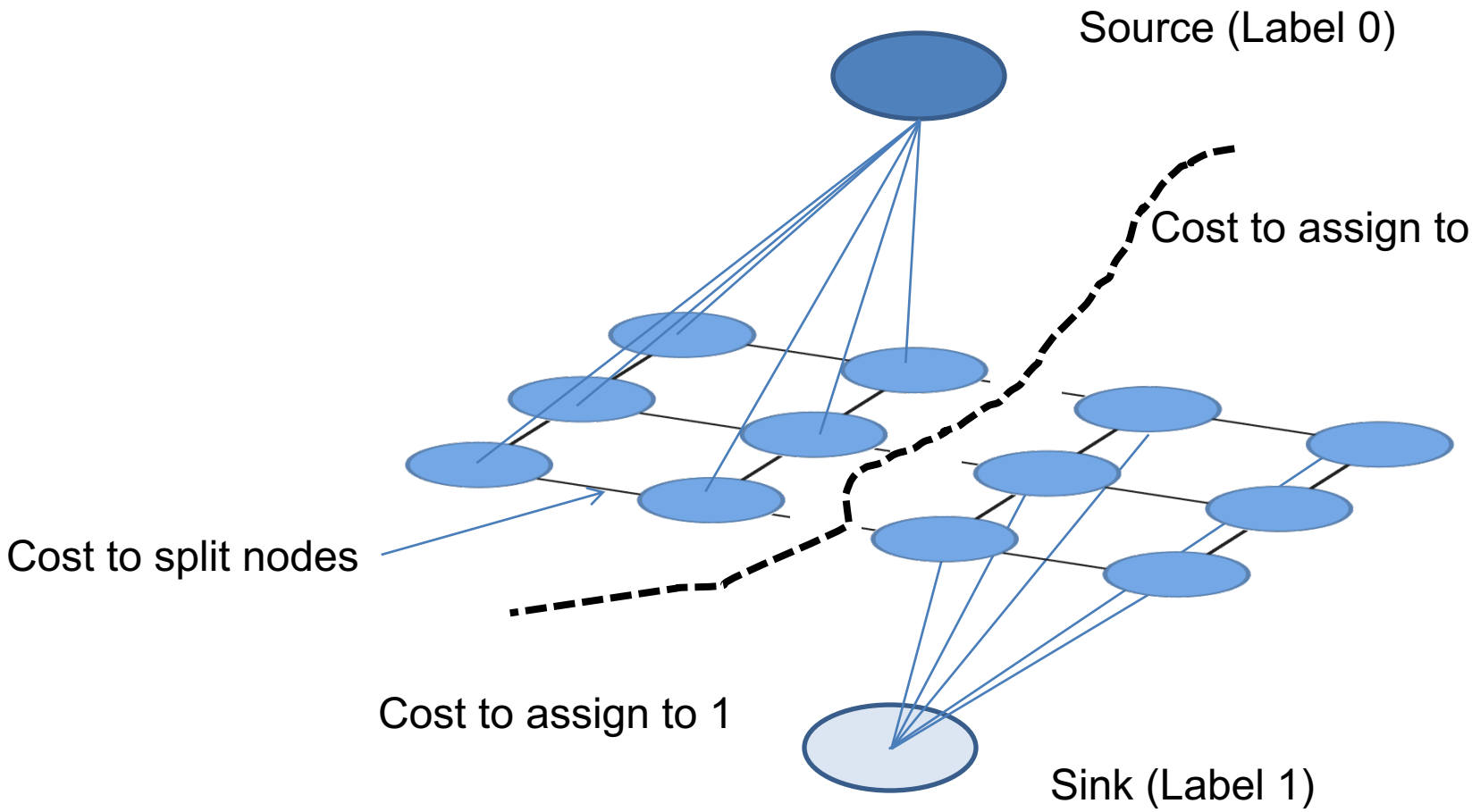
Solving MRFs with graph cuts



$$Energy(w \mid \theta, data) = \sum_{n} U_n(w_n) + \sum_{(m,n) \in edges} P_{mn}(w_m, w_n)$$

Source: Derek Hoiem

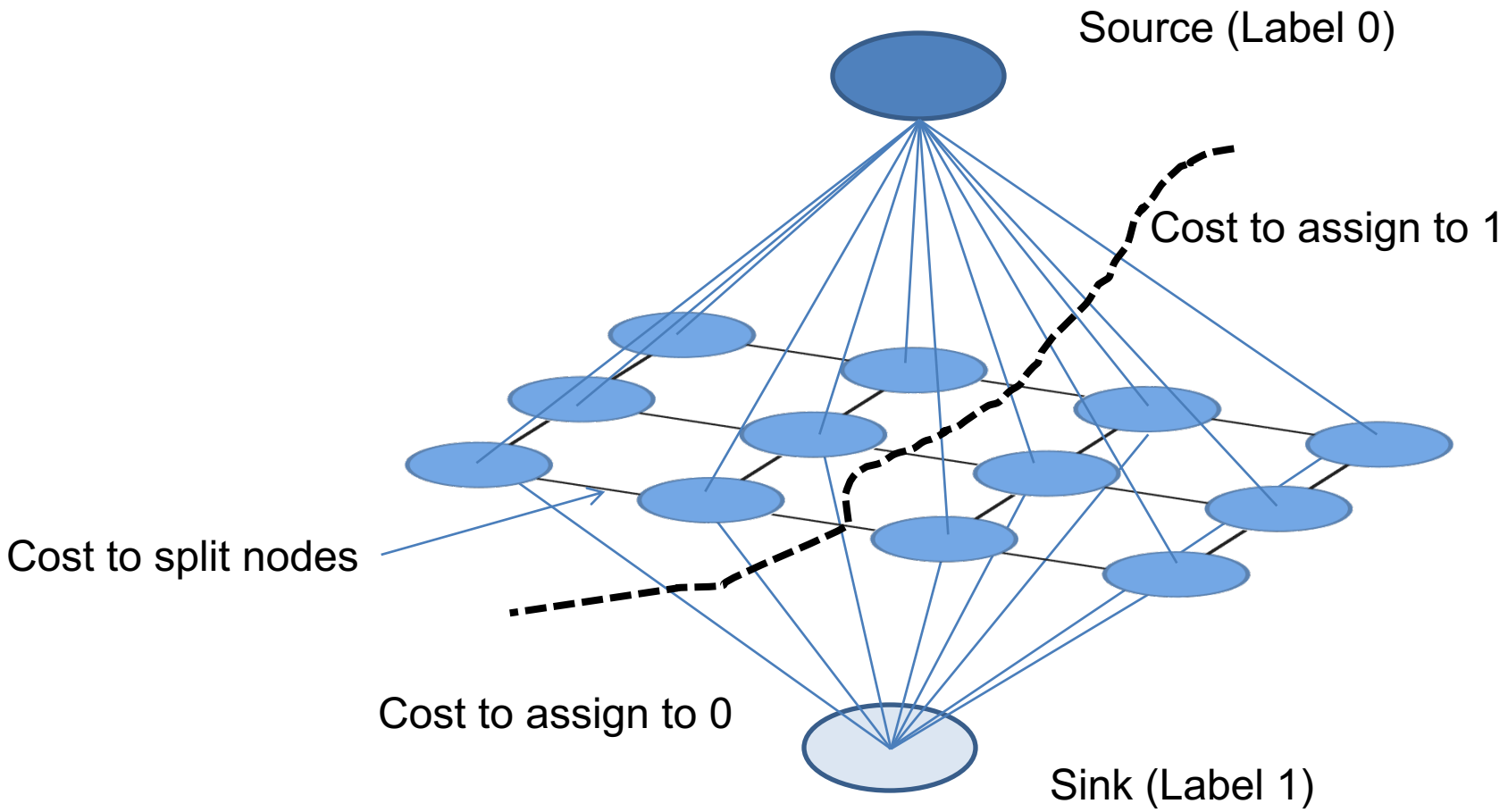
Solving MRFs with graph cuts



$$Energy(w \mid \theta, data) = \sum_{n} U_n(w_n) + \sum_{(m,n) \in edges} P_{mn}(w_m, w_n)$$

Source: Derek Hoiem

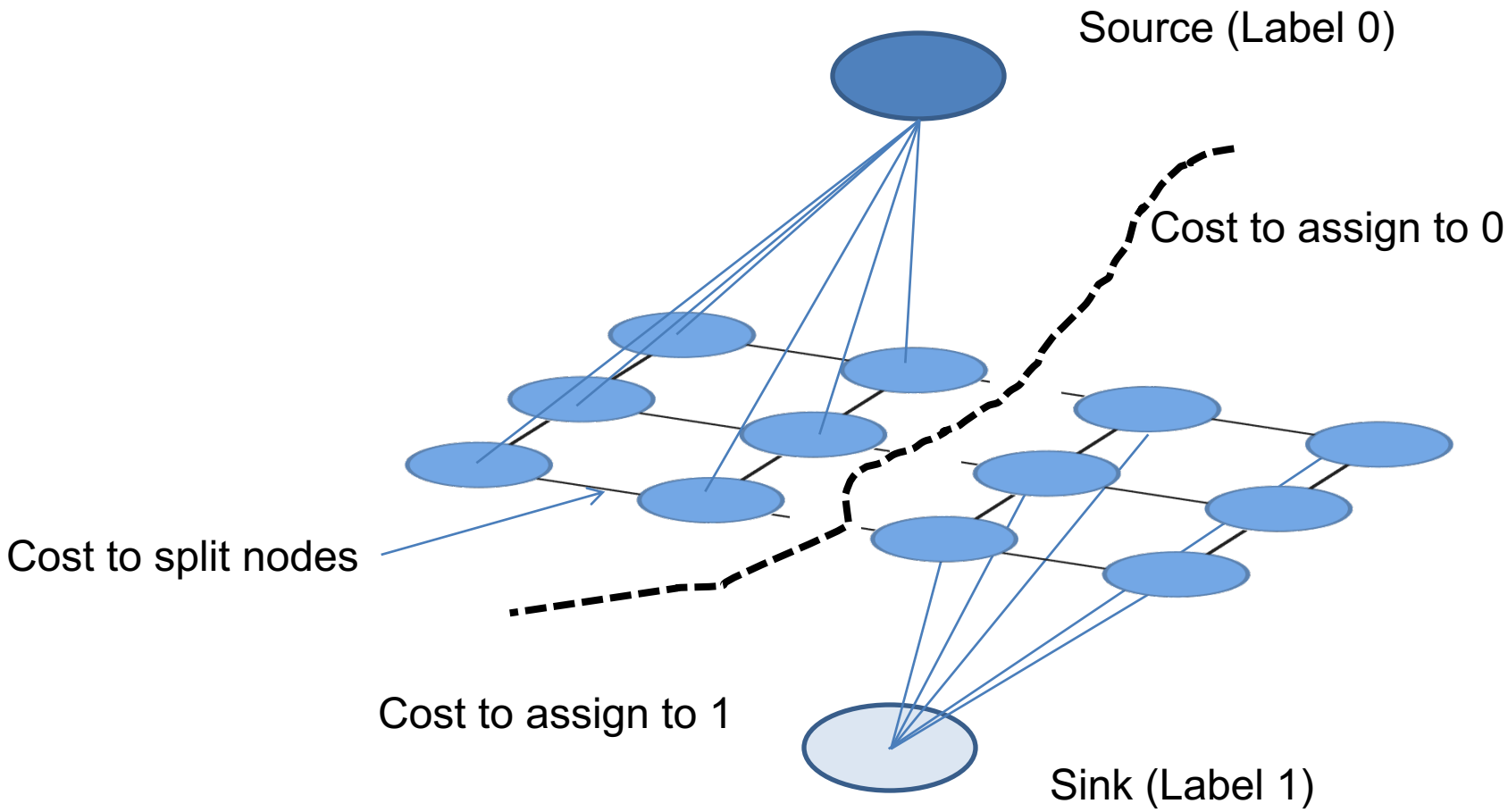
Solving MRFs with graph cuts



$$Energy(\mathbf{y} \mid \theta, data) = \sum_i \psi_1(y_i \mid \theta, data) + \sum_{i,j \in edges} \psi_2(y_i, y_j \mid \theta, data)$$

Slide: Derek Hoiem

Solving MRFs with graph cuts



$$Energy(\mathbf{y} \mid \theta, data) = \sum_i \psi_1(y_i \mid \theta, data) + \sum_{i,j \in edges} \psi_2(y_i, y_j \mid \theta, data)$$

Slide: Derek Hoiem

GrabCut segmentation

User provides rough indication of foreground region.

Goal: Automatically provide a pixel-level segmentation.

Slide: Derek Hoiem

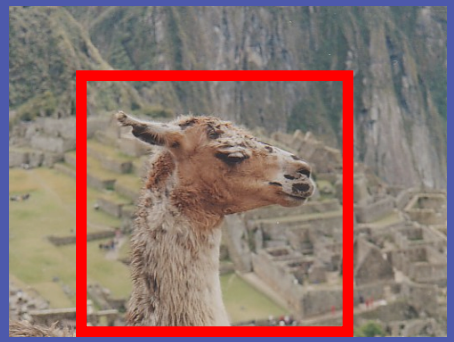
Grab cuts and graph cuts

Magic Wand
(198?)

Intelligent Scissors
Mortensen and Barrett (1995)

GrabCut

User Input



Result

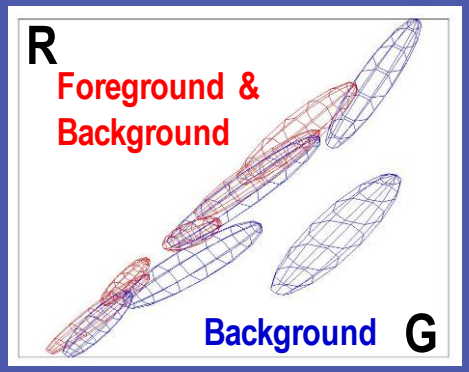
Regions

Boundary

Regions & Boundary

Source: Rother

Colour Model



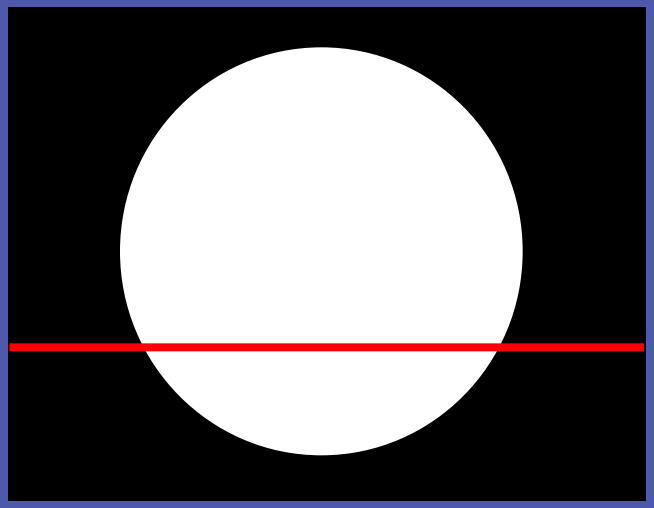
Gaussian Mixture Model (typically 5-8 components)

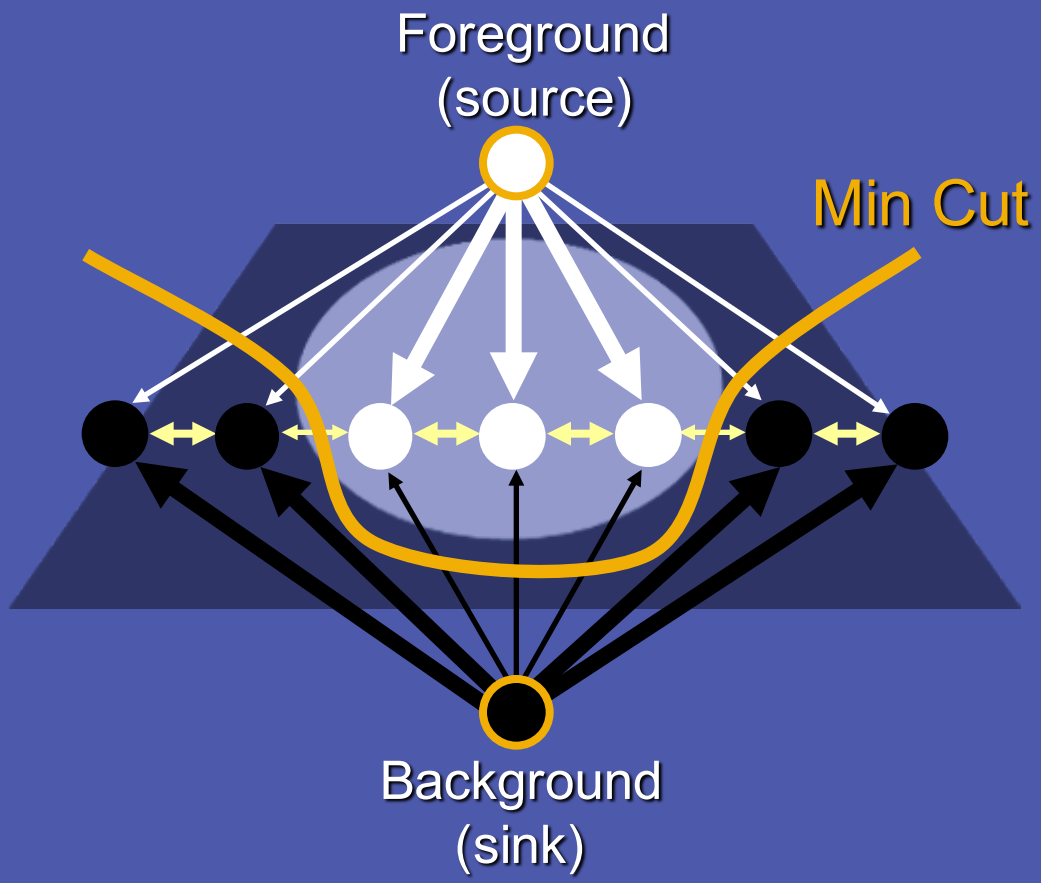
Source: Rother

Graph cuts

Boykov and Jolly (2001)

Image



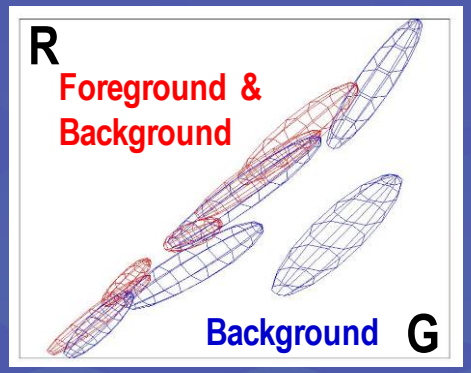


Cut: separating source and sink; Energy: collection of edges

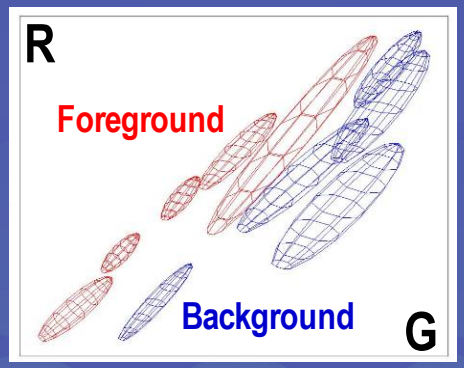
Min Cut: Global minimal enegry in polynomial time

Source: Rother

Colour Model



Iterated
graph cut



Gaussian Mixture Model (typically 5-8 components)

Source: Rother

GrabCut segmentation

1. Define graph
   - usually 4-connected or 8-connected
2. Define unary potentials
   - Color histogram or mixture of Gaussians for background and foreground

$$unary\_potential(x) = -\log\left(\frac{P(c(x);\theta_{foreground})}{P(c(x);\theta_{background})}\right)$$

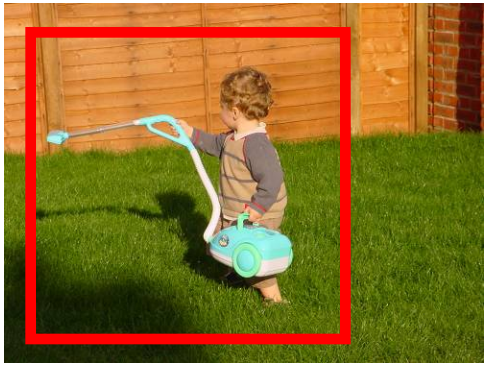
3. Define pairwise potentials

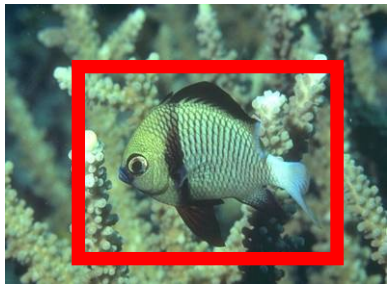
$$edge\_potential(x,y) = k_1 + k_2 \exp\left\{\frac{-\|c(x)-c(y)\|^2}{2\sigma^2}\right\}$$

4. Apply graph cuts
5. Return to 2, using current labels to compute foreground, background models

Slide: Derek Hoiem

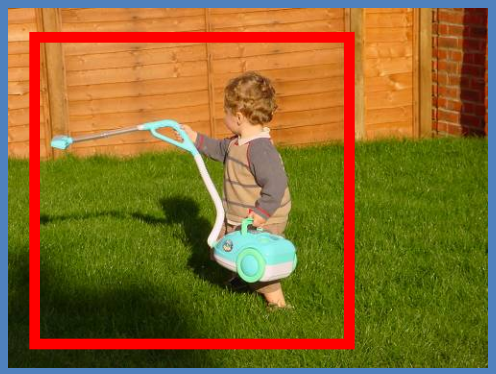
What is easy or hard about these cases for graphcut-based segmentation?

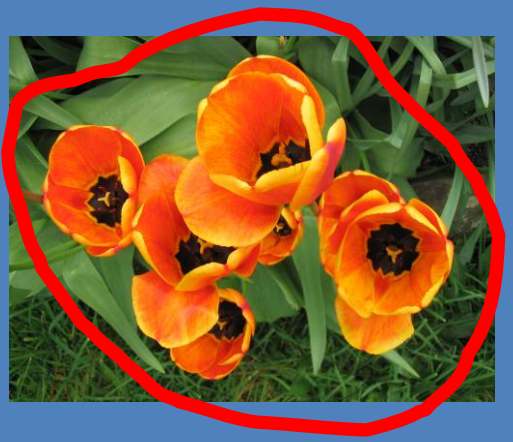




Slide: Derek Hoiem

Easier examples





More difficult Examples

Camouflage & Low Contrast

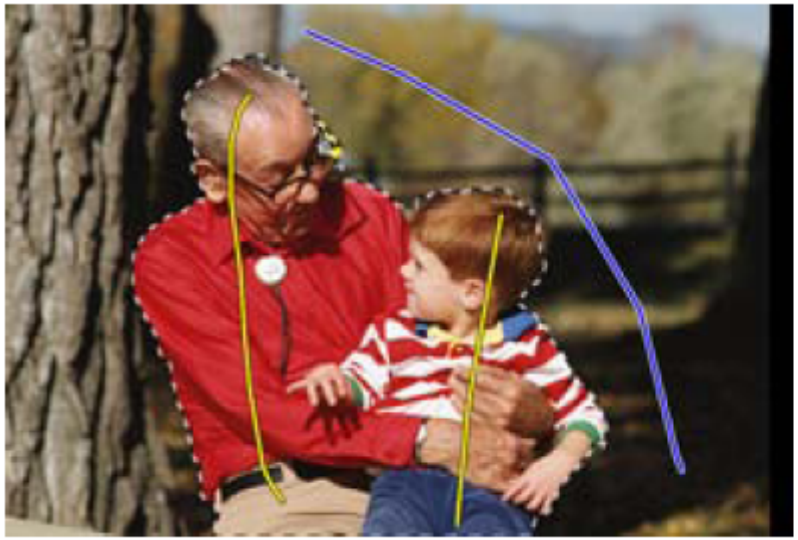
Fine structure

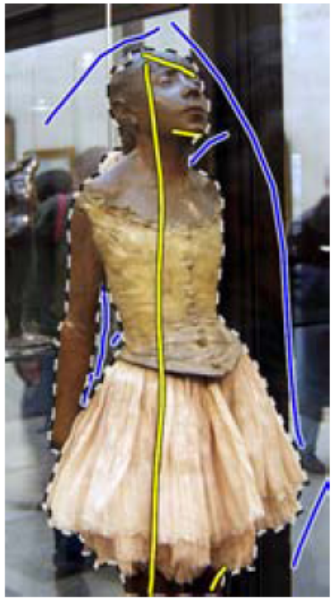
Harder Case

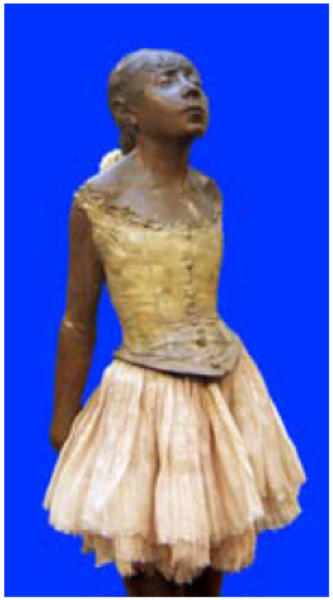
Initial Rectangle

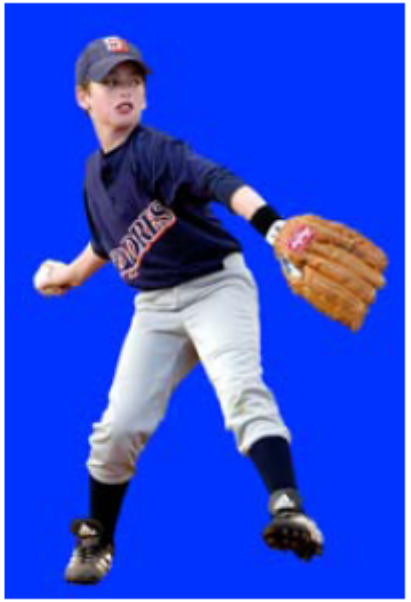
Initial Result

Lazy Snapping (Li et al. SG 2004)

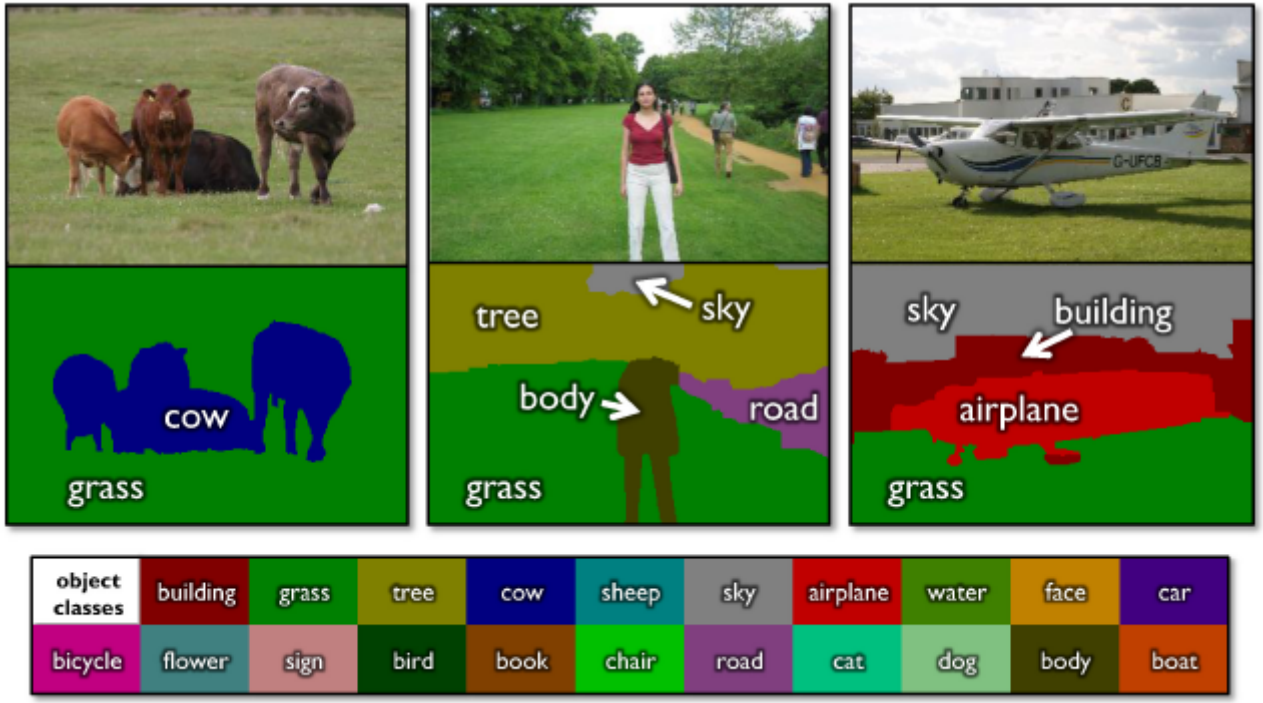






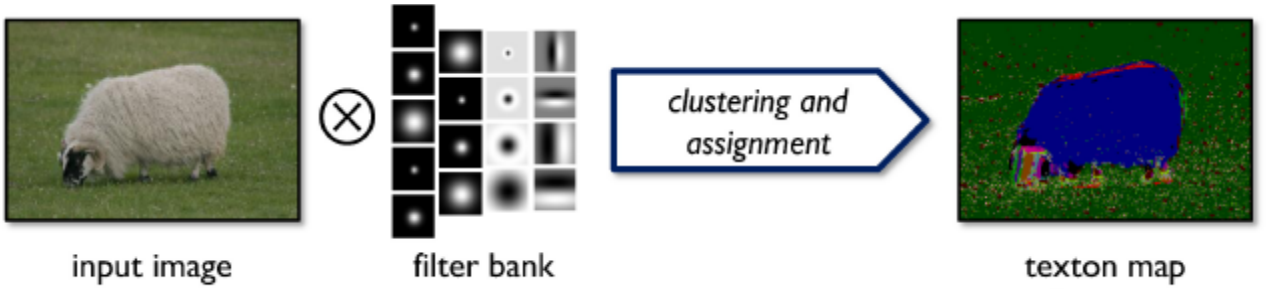


Using graph cuts for recognition



TextonBoost (Shotton et al. 2009 IJCV)

Using graph cuts for recognition



Unary Potentials

Alpha Expansion Graph Cuts

TextonBoost (Shotton et al. 2009 IJCV)

Limitations of graph cuts

- Associative: edge potentials penalize different labels

  Must satisfy

$$E^{i,j}(0,0) + E^{i,j}(1,1) \leq E^{i,j}(0,1) + E^{i,j}(1,0)$$

- If not associative, can sometimes clip potentials

- Approximate for multilabel
  - Alpha-expansion or alpha-beta swaps

Graph cuts: Pros and Cons

- Pros
  - Very fast inference
  - Can incorporate data likelihoods and priors
  - Applies to a wide range of problems (stereo, image labeling, recognition)
- Cons
  - Not always applicable (associative only)
  - Need unary terms (not used for generic segmentation)
- Use whenever applicable

More about MRFs/CRFs

- Other common uses
  - Graph structure on regions
  - Encoding relations between multiple scene elements
- Inference methods
  - Loopy BP or BP-TRW: approximate, slower, but works for more general graphs

Further reading and resources

- Graph cuts
  - http://www.cs.cornell.edu/~rdz/graphcuts.html
  - Classic paper: What Energy Functions can be Minimized via Graph Cuts? (Kolmogorov and Zabih, ECCV '02/PAMI '04)

- Belief propagation

  Yedidia, J.S.; Freeman, W.T.; Weiss, Y., "Understanding Belief Propagation and Its Generalizations", Technical Report, 2001: http://www.merl.com/publications/TR2001-022/

- Normalized cuts and image segmentation (Shi and Malik)

  *http://www.cs.berkeley.edu/~malik/papers/SM-n**cut**.pdf*

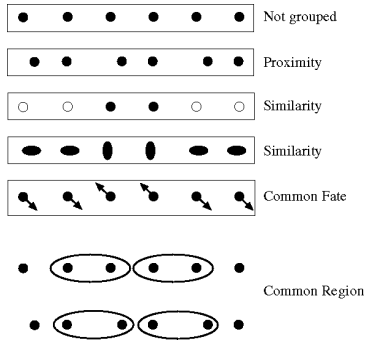
- N-cut implementation

  http://www.seas.upenn.edu/~timothee/software/ncut/ncut.html

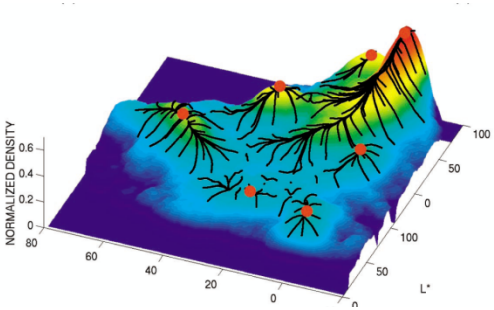
Slide: Derek Hoiem

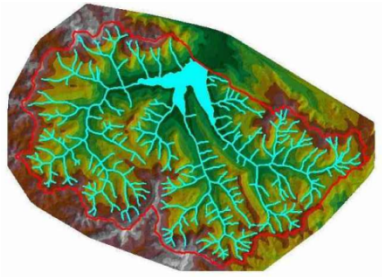
Next Class

- Gestalt grouping



- More segmentation methods



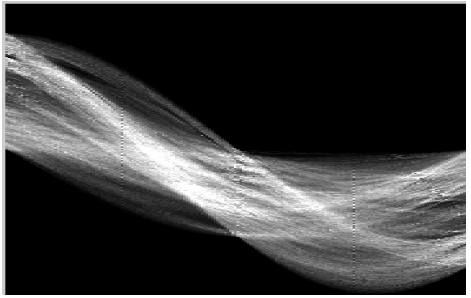


Recap of Grouping and Fitting

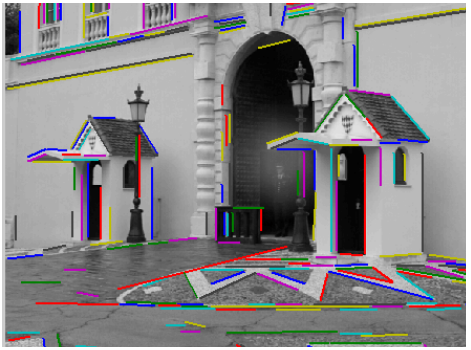
Edge and line detection

- Canny edge detector = smooth → derivative → thin → threshold → link

- Generalized Hough transform = points vote for shape parameters



- Straight line detector = canny + gradient orientations → orientation binning → linking → check for straightness

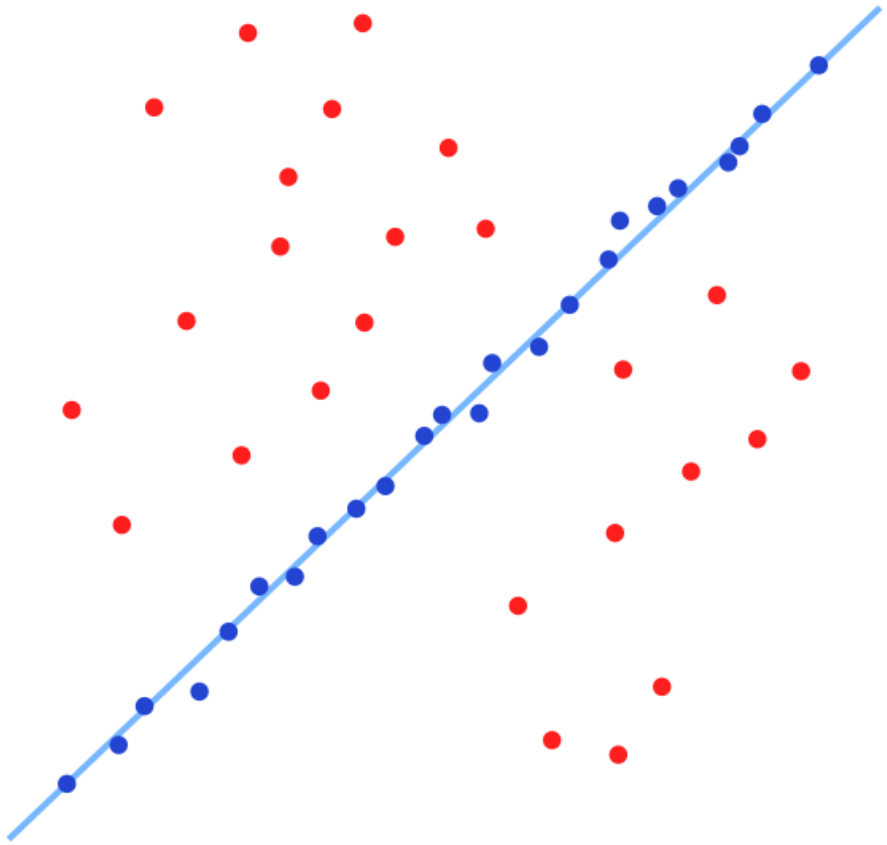


Slide: Derek Hoiem

Robust fitting and registration

Key algorithms

- RANSAC, Hough Transform

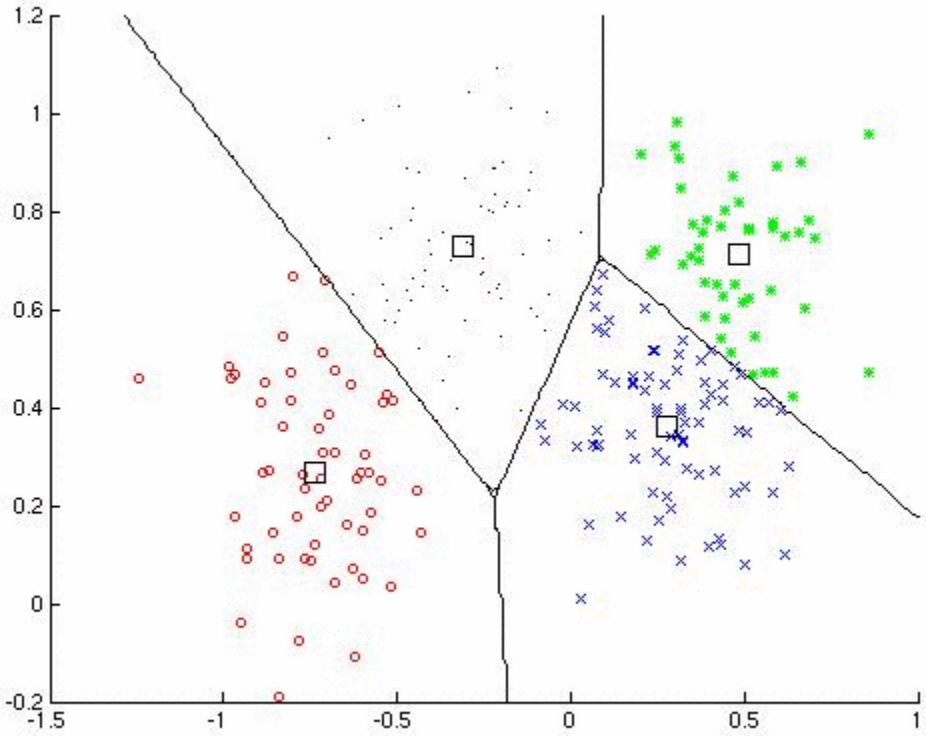


Slide: Derek Hoiem

Clustering

Key algorithm

- K-means



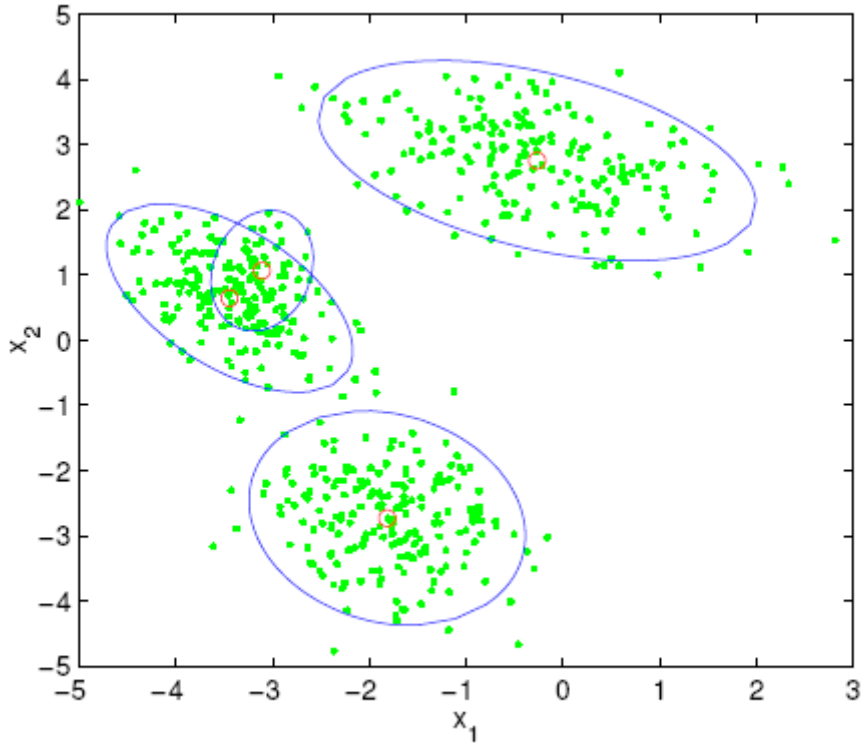
Slide: Derek Hoiem

EM and Mixture of Gaussians

Tutorials:

*http://www.cs.duke.edu/courses/spring04/cps196.1/.../**EM**/tomasiEM.pdf*

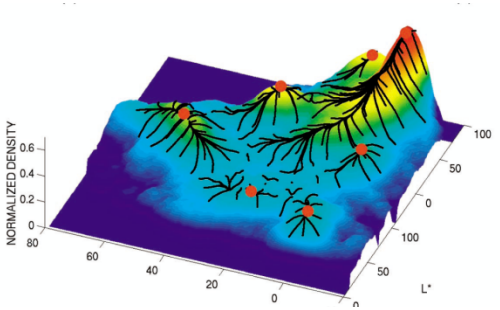
http://www-clmc.usc.edu/~adsouza/notes/mix_gauss.pdf



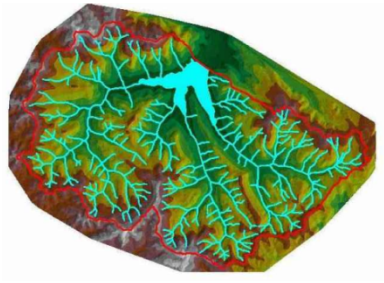
Slide: Derek Hoiem

Segmentation

- Mean-shift segmentation
  - Flexible clustering method, good segmentation



- Watershed segmentation
  - Hierarchical segmentation from soft boundaries



- Normalized cuts
  - Produces regular regions
  - Slow but good for oversegmentation

- MRFs with Graph Cut
  - Incorporates foreground/background/object model and prefers to cut at image boundaries
  - Good for interactive segmentation or recognition

Slide: Derek Hoiem

Next section: Recognition

- How to recognize
  - Specific object instances
  - Faces
  - Scenes
  - Object categories