第三章习题

T1

由题意有

$$T(e_1,e_2,e_3) = \begin{pmatrix} 2 & -1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 0 \end{pmatrix} = (e_1,e_2,e_3)A \Rightarrow A = \begin{pmatrix} 2 & -1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

T2

$$D(x_1) = ae^{at}\cos bt - be^{at}\sin bt = ax_1 - bx_2$$

$$D(x_2) = ae^{at}\sin bt + be^{at}\cos bt = ax_2 + bx_1$$

$$D(x_3) = e^{at}\cos bt + tD(x_1) = x_1 + ax_3 - bx_4$$

$$D(x_4) = e^{at} \sin bt + t D(x_2) = x_2 + ax_4 + bx_3$$

$$D(x_5) = te^{at}\cos bt + \tfrac{1}{2}t^2D(x_1) = x_3 + ax_5 - bx_6$$

$$D(x_6) = te^{at}\sin bt + \frac{1}{2}t^2D(x_2) = x_4 + ax_6 + bx_5$$

则有

$$A = \begin{pmatrix} a & b & 1 & 0 & 0 & 0 \\ -b & a & 0 & 1 & 0 & 0 \\ 0 & 0 & a & b & 1 & 0 \\ 0 & 0 & -b & a & 0 & 1 \\ 0 & 0 & 0 & 0 & a & b \\ 0 & 0 & 0 & 0 & -b & a \end{pmatrix}$$

T3

$$T_1 E_{11} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} E_{11} = \begin{pmatrix} a & 0 \\ c & 0 \end{pmatrix} = a E_{11} + c E_{21}$$

$$T_1E_{12} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} E_{12} = \begin{pmatrix} 0 & a \\ 0 & c \end{pmatrix} = aE_{12} + cE_{22}$$

$$T_1E_{13}= {\begin{pmatrix} a & b \\ c & d \end{pmatrix}}E_{13}= {\begin{pmatrix} b & 0 \\ d & 0 \end{pmatrix}}=bE_{11}+dE_{21}$$

$$T_1E_{14} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}E_{14} = \begin{pmatrix} 0 & b \\ 0 & d \end{pmatrix} = bE_{12} + dE_{22}$$

则有

$$A_1 = \begin{pmatrix} a & 0 & b & 0 \\ 0 & a & 0 & b \\ c & 0 & d & 0 \\ 0 & c & 0 & d \end{pmatrix}$$

$$T_2 E_{11} = E_{11} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a & b \\ 0 & 0 \end{pmatrix} = a E_{11} + b E_{12}$$

$$T_2E_{12} = E_{12}\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} c & d \\ 0 & 0 \end{pmatrix} = cE_{11} + dE_{12}$$

$$T_2 E_{21} = E_{21} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ a & b \end{pmatrix} = a E_{21} + b E_{22}$$

$$T_2 E_{22} = E_{22} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ c & d \end{pmatrix} = c E_{21} + d E_{22}$$

则有

$$A_2 = \begin{pmatrix} a & c & 0 & 0 \\ b & d & 0 & 0 \\ 0 & 0 & a & c \\ 0 & 0 & b & d \end{pmatrix}$$

由
$$T_1X = XA_1, T_2X = XA_2,$$
有

$$T_3X = (T_1 \circ T_2)X = XA_3 \Rightarrow T_3X = T_2(T_1X) = T_2(XA_1) = XA_1A_2 \Rightarrow A_3 = A_1A_2$$
 follows:

$$A_{3} = \begin{pmatrix} a^{2} & ac & ab & bc \\ ab & ad & b^{2} & bd \\ ac & c^{2} & ad & cd \\ bc & cd & bd & d^{2} \end{pmatrix}$$

T4

设有一组数
$$a_i$$
, $i = 1, ..., k$, 使得 $a_1x + a_2Tx + ... + a_kT^{k-1}x = 0$

上式作用一次
$$T$$
,有 $a_1Tx + a_2T^2x + ... + a_{k-1}T^{k-1}x = 0$

总共作用
$$k-1$$
 次 T 后,有 $a_1T^{k-1}x=0$

又因为
$$T^{k-1}x \neq 0$$
, 所以 $a_1 = 0$

同理可证
$$a_2 = a_3 = \dots = a_k = 0$$

所以
$$x, Tx, ..., T^{k-1}x$$
 线性无关

T5

(1)

记过渡矩阵为C

则有
$$(y_1, y_2, y_3) = (x_1, x_2, x_3)C$$

$$\Rightarrow C = (x_1, x_2, x_3)^{-1}(y_1, y_2, y_3) = \begin{pmatrix} \frac{1}{2} & -1 & \frac{1}{2} \\ \frac{1}{2} & 0 & -\frac{1}{2} \\ -\frac{1}{2} & 1 & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 & 2 & 2 \\ 2 & 2 & -1 \\ -1 & -1 & -1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -4 & -3 & 3 \\ 2 & 3 & 3 \\ 2 & -1 & -5 \end{pmatrix}$$

(2)

$$T(x_1,x_2,x_3)=(y_1,y_2,y_3)=(x_1,x_2,x_3)C$$

T 在基 x_1, x_2, x_3 下的过渡矩阵为 C

(3)

T 在基 y_1, y_2, y_3 下的过渡矩阵为 $C^{-1}CC = C$

T6

$$\det(\lambda I - A) = \begin{vmatrix} \lambda - 3 & -1 & 0 \\ 4 & \lambda + 1 & 0 \\ -4 & 8 & \lambda + 2 \end{vmatrix} = (\lambda + 2)(\lambda - 1)^2$$

计算可得 A 的特征值及对应特征向量为:

$$\lambda_1=-2, \xi_1=k_1\begin{pmatrix}0\\0\\1\end{pmatrix}, k_1\neq 0, k_1\in F$$

$$\lambda_2 = \lambda_3 = 1, \xi_2 = k_2 \begin{pmatrix} 3 \\ -6 \\ 20 \end{pmatrix}, k_2 \neq 0, k_2 \in F$$

于是T的特征值及对应特征向量为:

$$\lambda_1 = -2, \eta_1 = X\xi_1 = k_1x_3, k_1 \neq 0, k_1 \in F$$

$$\lambda_2 = \lambda_3 = 1, \eta_2 = X\xi_2 = k_2(3x_1 - 6x_2 + 20x_3), k_2 \neq 0, k_2 \in F$$

$$\det(\lambda I - A) = \begin{vmatrix} \lambda + 1 & -1 & 0 \\ 4 & \lambda - 3 & 0 \\ -1 & 0 & \lambda - 2 \end{vmatrix} = (\lambda - 2)(\lambda - 1)^2$$

取
$$\lambda = 2$$
, 对应特征向量 $p_1 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

$$\ \ \diamondsuit \ p_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, p_3 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

可得
$$P_3 = (p_1, p_2, p_3) = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$AP_3 = P_3 \begin{pmatrix} 2 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & -4 & 3 \end{pmatrix}$$

ોર
$$A_2={1\choose -4} {1\choose 3}, \det(\lambda I-A_2)=\left(\lambda-1\right)^2$$

其特征值为
$$\lambda = 1$$
,对应特征向量为 $q_1 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$

$$\diamondsuit q_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

可得
$$P_2 = (q_1, q_2) = \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix}$$

$$A_2 P_2 = P_2 \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

则

$$A = P_3 \begin{pmatrix} 2 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & -4 & 3 \end{pmatrix} P_3^{-1} = \widetilde{P}_3 \begin{pmatrix} 2 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \widetilde{P}_3^{-1}$$

其中
$$\widetilde{P}_3 = P_3 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

TΩ

$$\det(\lambda I - A) = \begin{vmatrix} \lambda - 1 & 0 & -2 \\ 0 & \lambda + 1 & -1 \\ 0 & -1 & \lambda \end{vmatrix} = \lambda^3 - 2\lambda + 1$$

则

$$2A^8 - 3A^5 + A^4 + A^2 - 4E_3 = (A^3 - 2A + 1)(2A^5 + 4A^3 - 5A^2 + 9A - 14E) + 24A^2 - 37A + 10E$$

于是

$$2A^8 - 3A^5 + A^4 + A^2 - 4E_3 = 24A^2 - 37A + 10E = \begin{pmatrix} -3 & 48 & -26 \\ 0 & 95 & -61 \\ 0 & -61 & 34 \end{pmatrix}$$

T9

$$\det(\lambda I - A) = \begin{vmatrix} \lambda - 7 & -4 & 4 \\ -4 & \lambda + 8 & 1 \\ 4 & 1 & \lambda + 8 \end{vmatrix} = (\lambda - 9)(\lambda + 9)^{2}$$

又
$$(A-9I)(A+9I) = O$$
, 则最小多项式为 $(\lambda-9)(\lambda+9)$

T10

因为
$$|\lambda I - A| = |(\lambda I - A)^T| = |\lambda I - A^T|$$

所以A和 A^T 有相同的特征多项式和最小多项式

T11

(1)

$$\det(\lambda I - A) = \lambda^3 - \lambda^2 + \lambda - 1 = (\lambda - 1)(\lambda^2 + 1)$$

所以 A 的特征值为 1, i, -i

则 Jordan 标准型为
$$\begin{pmatrix} 1 & & \\ & i & \\ & & -i \end{pmatrix}$$

(2)

$$\det(\lambda I - A) = (\lambda - 1)^4$$

所以 A 的特征值为 1

由
$$(A-I)X = 0$$
 可得对应特征向量 $\xi = (0,0,-1,1)^T$

则 $\lambda = 1$ 的几何重数为 1, J(1) 只包含一个 Jordan 块

故
$$A$$
 的 Jordan 标准型为 $\begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$

T12

设
$$A$$
 的 Jordan 标准型为 $J=\begin{pmatrix}J_1(\lambda_1)&&\\&\ddots&\\&&J_s(\lambda_s)\end{pmatrix}, J_i(\lambda_i)=\begin{pmatrix}\lambda_i&1&\dots&0\\0&\lambda_i&\ddots&0\\\vdots&\vdots&\ddots&1\\0&0&\dots&\lambda_i\end{pmatrix}$

于是存在可逆矩阵 P 使得 $A = PJP^{-1}$

$$\mathbb{M}\ J^m = P^{-1}A^mP = I \Rightarrow [J_i(\lambda_i)]^m = I_p \Rightarrow p = 1$$

则
$$J_i(\lambda_i)$$
中的 Jordan 块为 1 阶, 即 $J_i(\lambda_i) = \lambda_i$

故A相似于对角矩阵