

Traveling Salesperson Problem

:

#The next example involves drilling holes in a circuit board with an automated drill.
 #The problem is to find the shortest route for the drill to take on the board in order
 #The example is taken from TSPLIB, a library of TSP problems

```
pip install ortools
```

```
Looking in indexes: https://pypi.org/simple, https://us-python.pkg.dev/colab-whee
Collecting ortools
  Downloading ortools-9.4.1874-cp37-cp37m-manylinux_2_17_x86_64.manylinux2014_x86_64.whl (16.0 MB)
    |████████████████████████████████████████| 16.0 MB 2.1 MB/s
Collecting protobuf<=3.19.4
  Downloading protobuf-4.21.6-cp37-abi3-manylinux2014_x86_64.whl (408 kB)
    |████████████████████████████████████████| 408 kB 65.9 MB/s
Requirement already satisfied: absl-py>=0.13 in /usr/local/lib/python3.7/dist-packages (from protobuf)
Requirement already satisfied: numpy>=1.13.3 in /usr/local/lib/python3.7/dist-packages (from protobuf)
Installing collected packages: protobuf, ortools
  Attempting uninstall: protobuf
    Found existing installation: protobuf 3.17.3
    Uninstalling protobuf-3.17.3:
      Successfully uninstalled protobuf-3.17.3
ERROR: pip's dependency resolver does not currently take into account all the packages that you are installing. In this case, running pip install will fail to resolve dependencies. The following packages are being installed: tensorflow 2.8.2+zzzcolab20220719082949 requires protobuf<3.20,>=3.9.2, but you have protobuf 4.21.6. tensorflow-metadata 1.10.0 requires protobuf<4,>=3.13, but you have protobuf 4.21.6. google-cloud-bigquery-storage 1.1.2 requires protobuf<4.0.0dev, but you have protobuf 4.21.6. google-api-core 1.31.6 requires protobuf<4.0.0dev,>=3.12.0; python_version > "3", but you have protobuf 4.21.6. Successfully installed ortools-9.4.1874 protobuf-4.21.6
```

```
pip install matplotlib
```

```
Looking in indexes: https://pypi.org/simple, https://us-python.pkg.dev/colab-whee
Requirement already satisfied: matplotlib in /usr/local/lib/python3.7/dist-packages (3.5.3)
Requirement already satisfied: cycler>=0.10 in /usr/local/lib/python3.7/dist-packages (from matplotlib)
Requirement already satisfied: python-dateutil>=2.1 in /usr/local/lib/python3.7/dist-packages (from matplotlib)
Requirement already satisfied: kiwisolver>=1.0.1 in /usr/local/lib/python3.7/dist-packages (from matplotlib)
Requirement already satisfied: pyparsing!=2.0.4,!=2.1.2,!=2.1.6,>=2.0.1 in /usr/local/lib/python3.7/dist-packages (from matplotlib)
Requirement already satisfied: numpy>=1.11 in /usr/local/lib/python3.7/dist-packages (from matplotlib)
Requirement already satisfied: typing-extensions in /usr/local/lib/python3.7/dist-packages (from matplotlib)
Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.7/dist-packages (from matplotlib)
```

```
"""Simple Travelling Salesperson Problem (TSP) on a circuit board."""
```

```
import math
from ortools.constraint_solver import routing_enums_pb2
from ortools.constraint_solver import pywrapcp
import numpy as np
```

```
import numpy as np
```

```
import matplotlib.pyplot as plt
```

```
def create_data_model():
```

```
    """Stores the data for the problem."""
```

```
    data = {}
```

```
data1 = np.array([
```

```
    (288, 149), (288, 129), (270, 133), (256, 141), (256, 157), (246, 157),
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    (156, 145), (148, 145), (140, 145), (148, 169), (164, 169), (172, 169),
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    (228, 117), (228, 125), (220, 125), (212, 117), (204, 109), (196, 101),
    (188, 93), (180, 93), (180, 101), (180, 109), (180, 117), (180, 125),
    (196, 145), (204, 145), (212, 145), (220, 145), (228, 145), (236, 145),
    (246, 141), (252, 125), (260, 129), (280, 123)
```

```

    (270, 171), (272, 123), (200, 123), (200, 133),
] ) # yapf: disable
# Locations in block units
data['locations'] = data1
data['num_vehicles'] = 1
data['depot'] = 0
x,y = data1.T
plt.scatter(x,y)
plt.plot(x,y)
return data

def compute_euclidean_distance_matrix(locations):
    """Creates callback to return distance between points."""
    distances = {}
    for from_counter, from_node in enumerate(locations):
        distances[from_counter] = {}
        for to_counter, to_node in enumerate(locations):
            if from_counter == to_counter:
                distances[from_counter][to_counter] = 0
            else:
                # Euclidean distance
                distances[from_counter][to_counter] = (int(
                    math.hypot((from_node[0] - to_node[0]),
                               (from_node[1] - to_node[1]))))
    return distances

def print_solution(manager, routing, solution):
    """Prints solution on console."""
    print('Objective: {}'.format(solution.ObjectiveValue()))
    index = routing.Start(0)
    plan_output = 'Route:\n'
    route_distance = 0
    while not routing.IsEnd(index):
        plan_output += ' {} ->'.format(manager.IndexToNode(index))
        previous_index = index
        index = solution.Value(routing.NextVar(index))
        route_distance += routing.GetArcCostForVehicle(previous_index, index, 0)
    plan_output += ' {}\n'.format(manager.IndexToNode(index))
    print(plan_output)
    plan_output += 'Objective: {}m\n'.format(route_distance)

def main():
    """Entry point of the program."""
    # Instantiate the data problem.
    data = create_data_model()

    # Create the routing index manager.
    manager = pywrapcp.RoutingIndexManager(len(data['locations']),
                                           data['num_vehicles'], data['depot'])

    # Create Routing Model.
    routing = pywrapcp.RoutingModel(manager)

```

```

distance_matrix = compute_euclidean_distance_matrix(data['locations'])

def distance_callback(from_index, to_index):
    """Returns the distance between the two nodes."""
    # Convert from routing variable Index to distance matrix NodeIndex.
    from_node = manager.IndexToNode(from_index)
    to_node = manager.IndexToNode(to_index)
    return distance_matrix[from_node][to_node]

transit_callback_index = routing.RegisterTransitCallback(distance_callback)

# Define cost of each arc.
routing.SetArcCostEvaluatorOfAllVehicles(transit_callback_index)

# Setting first solution heuristic.
search_parameters = pywrapcp.DefaultRoutingSearchParameters()
search_parameters.first_solution_strategy = (
    routing_enums_pb2.FirstSolutionStrategy.PATH_CHEAPEST_ARC)

# Solve the problem.
solution = routing.SolveWithParameters(search_parameters)

# Print solution on console.
if solution:
    print_solution(manager, routing, solution)

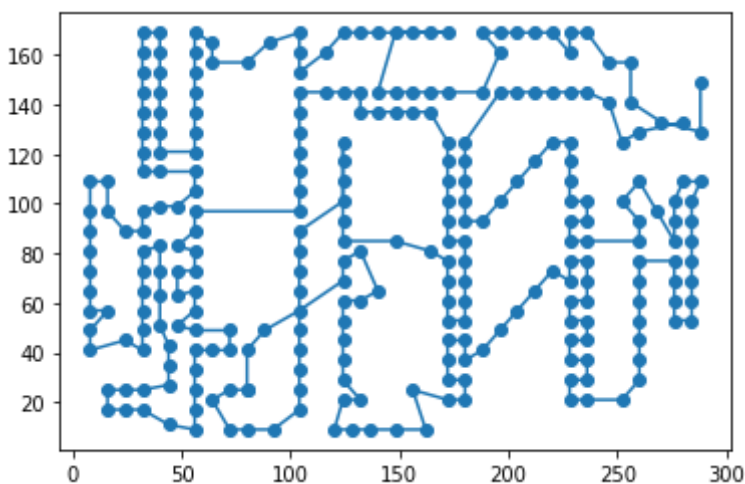
if __name__ == '__main__':
    main()
    search_parameters = pywrapcp.DefaultRoutingSearchParameters()
    search_parameters.local_search_metaheuristic = (
        routing_enums_pb2.LocalSearchMetaheuristic.GUIDED_LOCAL_SEARCH)
    search_parameters.time_limit.seconds = 30
    search_parameters.log_search = True

```

➡ Objective: 2790

Route:

0 -> 1 -> 279 -> 2 -> 278 -> 277 -> 248 -> 247 -> 243 -> 242 -> 241 -> 240 -> 23



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✓ 0s completed at 18:39

