Modified free energy and Tonks gas

Equation derivation

We have and expression for free energy

$$rac{C_{rest}}{C_{\infty}}igg(u\lnigg(rac{u}{c_{\infty}-u-v}igg)+v\lnigg(rac{v}{c_{\infty}-u-v}igg)igg)+c_{\infty}\lnigg(1-rac{u+v}{c_{\infty}}igg)$$

I denoted

$$rac{c_{rest}}{c_{\infty}} = A, R = c_{\infty} - u - v$$

We have

$$\mu_u = rac{\partial F}{\partial u} = A\left(\left(\lnrac{u}{R}
ight) + rac{R+u+v-c_\infty}{R}
ight) = A\left(\lnrac{u}{R}
ight) = A\ln(u) - A\ln(R)$$

if u,v<<1 then $R\approx c_\infty$. We would get $\mu_u=\ln u-\ln c_\infty$, which gives correct expression for diffusion term. But I'm not sure if we can approximate that early in the calculations. We have

$$\partial_x (u \partial_x \mu_u) = u'' - rac{u (RR'' - (R')^2) + R'u'R}{R^2} = u'' - g(u,v,u',v',u'',v'')$$

But if u', v' also small, then we recover diluted solution case.

$$\partial_x (u\partial_x \mu_u) pprox u'' - rac{R'u'}{R} pprox u''$$

Linearization

We want to linearize. We assume that base state is stationary and stable, ie. u'=v'=0.

So we discard any terms that contain u', v', u'', v''

There is one term that does not contain u',v' etc.

It is
$$-\frac{u}{R}(-\delta u'' - \delta v'')$$

Thus we can get modified equation

$$\delta \dot{u} = \delta u'' + rac{u}{R}(\delta u'' + \delta v'') + A \cdot (\delta u, \delta v)^T$$

The same for v but with u,v reversed.

Or with w = (u, v)

$$\delta \dot{w} = \delta w'' + P \delta w'' + A(w) \delta w$$

$$P = rac{1}{R} egin{pmatrix} u & u \ v & v \end{pmatrix}.$$

If we assume $\delta w = \vec{v_q} \exp(iqx + \sigma t)$, then we get

$$ec{v}_q \sigma = -q^2 D(\mathbb{1} + P) ec{v_q} + A ec{v_q},$$

where *D* is the diffusion coefficient.

Eigenvalues

Thus we're looking for σ s.t.

$$\det(A-q^2D(\mathbb{1}+P)-\sigma\mathbb{1})=0$$

for a given q. Denote $A-q^2D(\mathbb{1}+P)$ by A_q . Then we get

$$\sigma^2 - \operatorname{tr} A_q \sigma + \det A_q = 0$$

And

$$\sigma = rac{1}{2}igg({
m tr} A_q \pm \sqrt{({
m tr} A_q)^2 - 4\det A_q}igg)$$

Brusselator

$$\det A = a^2, \operatorname{tr} A = b - 1 - a^2$$

Stability analysis

The situation is the same as for typical brusselator except A_q looks different. So we assume that without diffusion the situation is stable ie. Also for convenience let $D=D(\mathbb{I}+P)$, ie. we'll denote by D the whole operator, along with diffusion coefficient.

- 1. $\mathrm{tr} A < 0$ and $\det A > 0$. Thus $\mathrm{tr} A_q < \mathrm{tr} A < 0$.
- 2. Unstable, stationary case (Turing pattern) must have $\det A_q < 0$.

$$\det A_q = \det A - q^2 \left(d_{uu} a_{vv} + d_{vv} a_{uu} + a_{vu} d_{uv} + d_{vu} a_{uv}
ight) + q^4 \left(d_{uu} d_{vv} - d_{vu} d_{vu}
ight),$$

where d_{ij} is just the coefficient of $D(\mathbb{1}+P)$.

Also we denote the coefficients of the polynomial by

$$egin{aligned} B &= (d_{uu}a_{vv} + d_{vv}a_{uu} + a_{vu}d_{uv} + d_{vu}a_{uv}) \ & C &= (d_{uu}d_{vv} - d_{vu}d_{vu}). \end{aligned}$$

As before the maximum is at q=0 or $q_{crit}^2=\frac{B}{2C}$. In the second case we get

$$\det A_{q_{crit}} = \det A - rac{B^2}{4C}.$$

This should be negative for instability.

Since $\det A>0$, this means that C>0 and from this we infer that B>0. But C>0 is satisfied by because

$$C=D(1+rac{u}{R})(1+rac{v}{R})-rac{uv}{R^2}=D\left(1+rac{(u+v)}{R}
ight)=Drac{c_\infty}{R}$$

And the B is equal to:

$$B = Drac{a^4 - a^3c - a^2 + abc - b^2}{aR} = Drac{a^4 - a^3c - a^2 + abc - b^2}{ca - a^2 - b}$$

We also must have

$$\det A_{q_{crit}} = \det A - rac{B^2}{4C} < 0,$$

This is equivalent to

$$B>\sqrt{4C\det A}$$

$$D\frac{a^4-a^3c-a^2+abc-b^2}{aR}>2a\sqrt{\frac{Dc}{R}}$$

or

$$D(a^4-a^3c-a^2+abc-b^2)>2a^2\sqrt{R}\sqrt{Dc}$$