

Solutions to Assignment 11

Exercise 1 [6 points]: Diffusion + chemistry: Turing instability

Consider the brusselator model

$$\begin{aligned}\partial_t u &= D_u \partial_x^2 u + a - (b+1)u + u^2 v, \\ \partial_t v &= D_v \partial_x^2 v + bu - u^2 v,\end{aligned}$$

where $u(x, t)$, $v(x, t)$ are concentration fields.

1. Determine the homogeneous stationary base state (with $u \neq 0, v \neq 0$).
2. Calculate the onset of the finite wavelength (Turing) instability, as discussed for the general case in the lecture.
HINT: In the eigenvalue problem, it is again enough to study $\sigma = 0$. Solve for the control parameter $b(q)$, minimize with respect to q and show that you get $b_c^{\text{Turing}} = (1 + a\sqrt{D_u/D_v})^2$ and $q_c = \sqrt{\frac{a}{\sqrt{D_u D_v}}}$.
3. To observe the finite wavelength pattern, the control parameter b needs to be beyond b_c^{Turing} but below the threshold of the other instability occurring in the system, the oscillatory Hopf instability having $b_c^{\text{Hopf}} = 1 + a^2$ (see lecture). What restriction do b_c^{Turing} and b_c^{Hopf} hence imply for the diffusion coefficients of the two species?

SOLUTION:

1. For the stationary *homogeneous* state, we can put all derivatives to zero and have to solve the following two equations simultaneously:

$$0 = f_u = a - (b+1)u + u^2 v \quad (1)$$

$$0 = f_v = bu - u^2 v. \quad (2)$$

The only solution we find is $\vec{w}_0 = \begin{pmatrix} u_0 \\ v_0 \end{pmatrix} = \begin{pmatrix} a \\ b/a \end{pmatrix}$.

2. The perturbation of the state is given by

$$\delta \dot{\vec{w}} = \begin{pmatrix} \delta \dot{u} \\ \delta \dot{v} \end{pmatrix} = \begin{pmatrix} \frac{\partial f_u}{\partial u} - D_u q^2 & \frac{\partial f_u}{\partial v} \\ \frac{\partial f_v}{\partial u} & \frac{\partial f_v}{\partial v} - D_v q^2 \end{pmatrix} \begin{pmatrix} \delta u \\ \delta v \end{pmatrix} = A \begin{pmatrix} \delta u \\ \delta v \end{pmatrix}, \quad (3)$$

$$\begin{aligned}
 * & -(b-1)a^2 - D_v q^2(b-1) + D_u q^2 a^2 + D_u D_v q^4 + q^2 b = 0 \\
 & = a^2 + q^2 [D_u a^2 - D_v(b-1)] + D_u D_v q^4 \\
 \Rightarrow b(q) & = \frac{a^2}{D_v q^2} + \frac{q^2 [D_u a^2 + D_v]}{D_v q^2} + \frac{D_u D_v q^4}{D_v q^2} = \frac{a^2}{D_v q^2} + \frac{D_u}{D_v} a^2 + 1 + D_u q^2
 \end{aligned}$$

with $\delta \vec{w} = \vec{w}_q e^{iqx + \sigma(q)t}$. Hence, a solution for σ can be found via the eigenvalue problem $\sigma \vec{w}_q = A \vec{w}_q$ and hence the equation for σ is:

$$\sigma_{1,2}(q) = \frac{1}{2} \text{Tr} A \pm \frac{1}{2} \sqrt{(\text{Tr} A)^2 - 4 \det A}. \quad (4)$$

Evaluating the homogenous part of matrix A at \vec{w}_0 yields:

$$A|_{\vec{w}_0} = \begin{pmatrix} -(b+1) + 2u_0 v_0 & u_0^2 \\ b - 2u_0 v_0 & -u_0^2 \end{pmatrix} \Big|_{\vec{w}_0} = \begin{pmatrix} b-1 & a^2 \\ -b & -a^2 \end{pmatrix}, \quad (5)$$

At the onset of a possible finite q_c instability, $\sigma = 0$. Therefore, we just have to solve $\det A = 0$ for the full system including the spacial derivatives. This leads to:

$$(b-1 - D_u q^2)(-a^2 - D_v q^2) + a^2 b = 0. \quad *$$

Solving this for $b(q)$ gives:

$$b(q) = \frac{a^2}{D_v q^2} + \frac{\overbrace{D_v + D_u q^2}^{D_v + D_u q^2}}{D_v} + D_u q^2. \quad (7)$$

Minimizing the function gives:

$$0 = \partial_q b(q) = -2 \frac{a^2}{D_v q^3} + 2 D_u q \quad (8)$$

$$q_c = \sqrt{\frac{a}{\sqrt{D_u D_v}}} \quad (9)$$

and plugging this back into the equation for b gives:

$$b_c = \left(1 + a \sqrt{\frac{D_u}{D_v}}\right)^2. \quad (11)$$

Note that for both instabilities $b > 1$ such that $A_{uu} = b-1 > 0$ and $A_{vv} = -a^2 < 0$. This means that u is "activated" while v is inhibited around the stationary homogeneous solution. One can also say that due to the bu -term in the equation for v , u activates v if it is small (and hence $-u^2 v$ is small).

3. b must be below the Hopf instability, i.e. one needs:

$$b < b_H = 1 + a^2. \quad (12)$$

For Turing one needs:

$$b > b_T = \left(1 + a \sqrt{\frac{D_u}{D_v}}\right)^2. \quad (13)$$

Hence we need $b_T < b < b_H$ which leads to:

$$\left(1 + a \sqrt{\frac{D_u}{D_v}}\right)^2 < 1 + a^2 \rightarrow \sqrt{\frac{D_u}{D_v}} < \frac{\sqrt{1+a^2}-1}{a}. \quad (14)$$

The r.h.s. is of order a , hence finite and rather large, hence $D_u \ll D_v$, implying again short range activation and long range inhibition.

always < 1 !
 small a : $\sim a < 1$
 large a : $\sim \frac{a-1}{a} \approx 1$
 monotonous