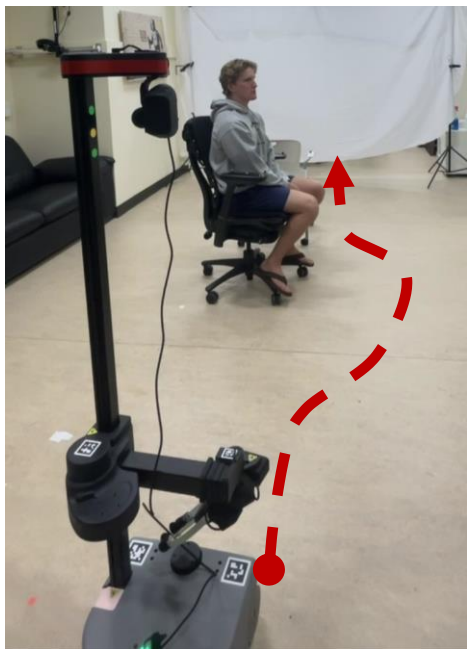


**Goal:** Move to the opposite side and monitor the human's face.

Completed Trajectory

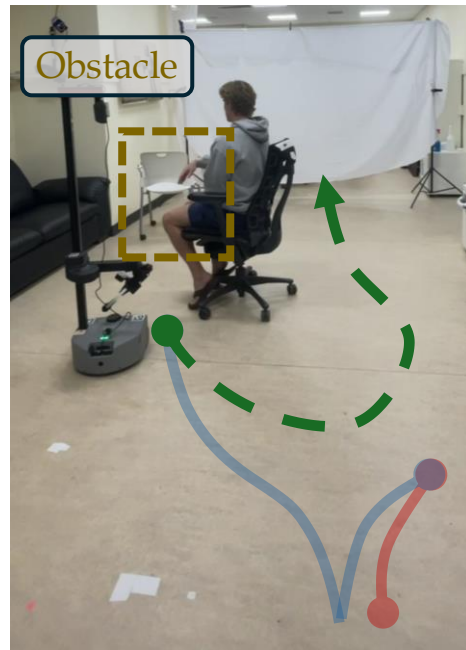
Planned Trajectory



(a) Initial path



(b) Human rotated



(c) Chair blocks the path