

**Goal:** Move to the opposite side and monitor the human's face.



Completed Trajectory



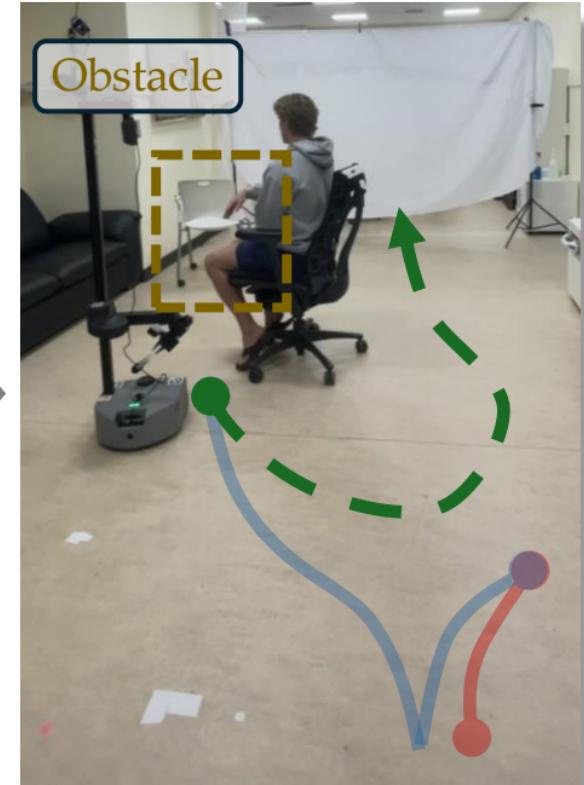
Planned Trajectory



(a) Initial path



(b) Human rotated



(c) Chair blocks the path