

# TRAITEMENT D'IMAGES

Partie Introductive

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L'INSTITUT NATIONAL D'ENSEIGNEMENT SUPÉRIEUR POUR L'AGRICULTURE, L'ALIMENTATION ET L'ENVIRONNEMENT

# 0 - PREAMBULE

Phénotypage  
(aérien et racinaire)

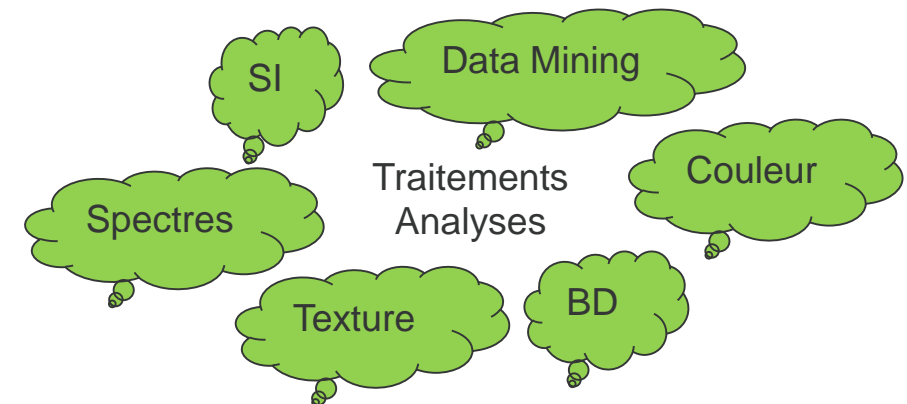
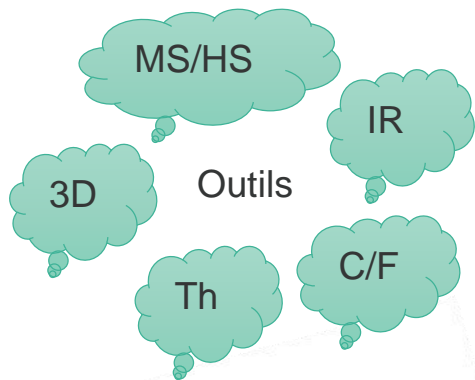
- Pois, Blé, Vigne, Maïs, Betteraves

Détection de pathologies

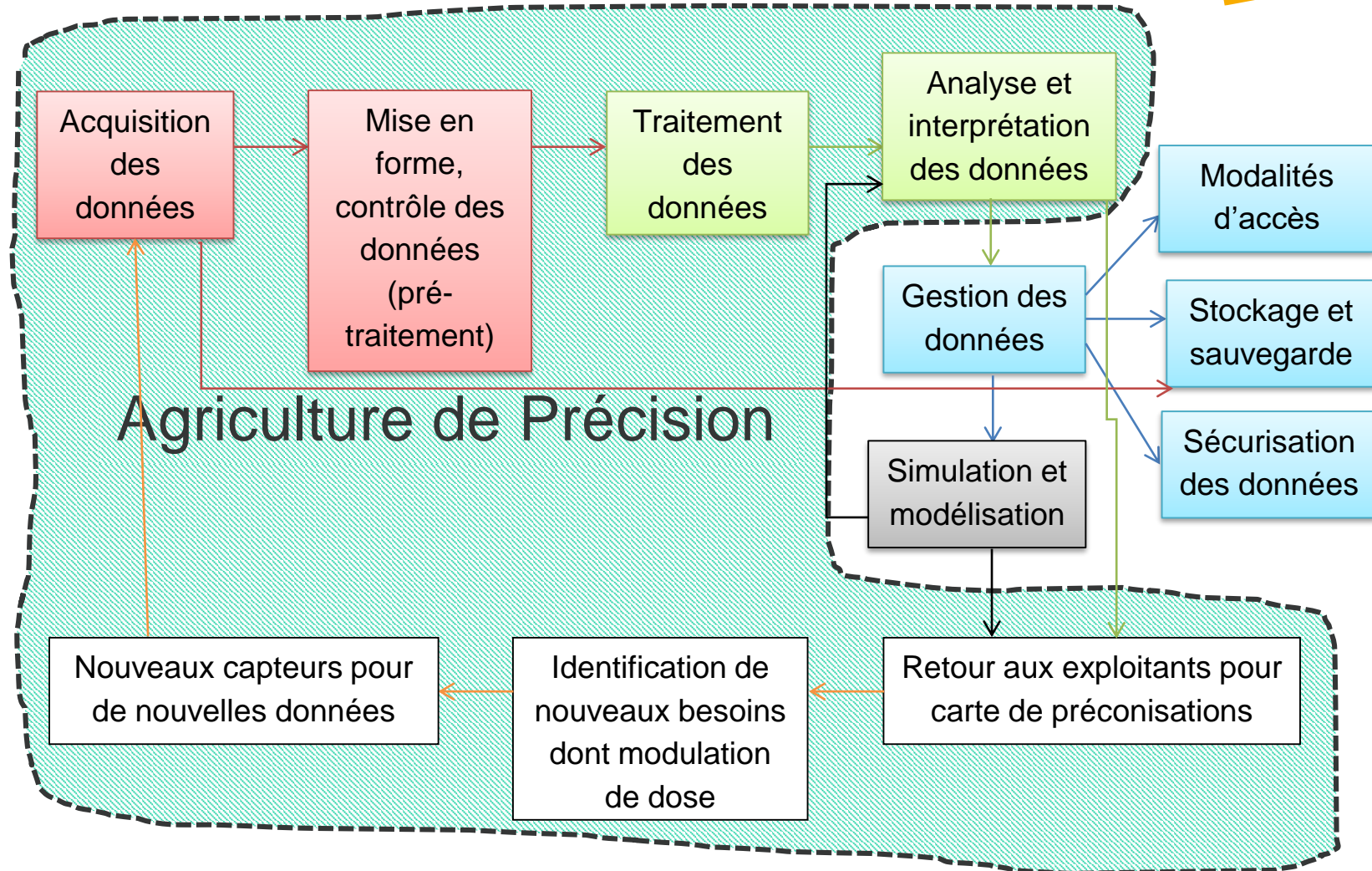
- Vigne, Blé, Betteraves

Autres projets

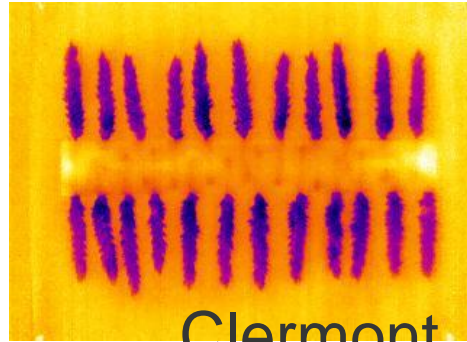
- Estimation de rendement (Blé, Colza)
- Pulvérisation de précision



# 0 - PREAMBULE



# 0 - PREAMBULE



Clermont



Montfavet



Montfavet



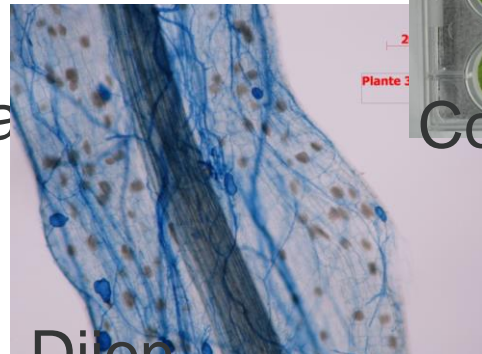
Colmar



Colmar

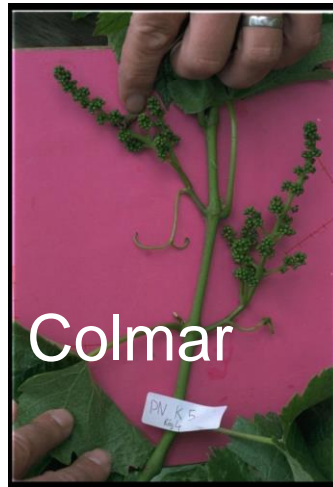


Montfavet

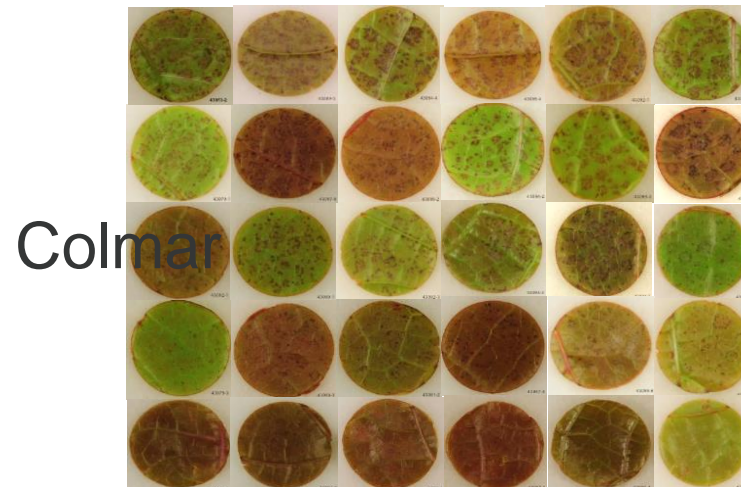


Dijon

# 0 - PREAMBULE



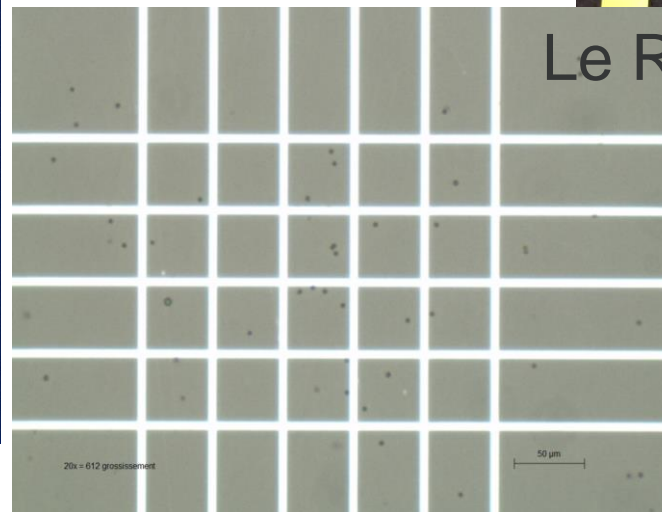
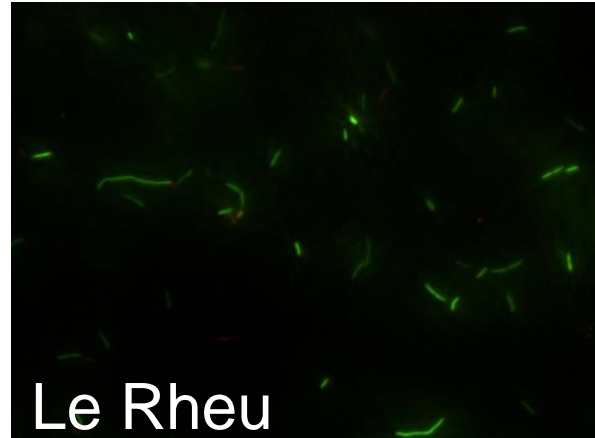
Colmar



Colmar



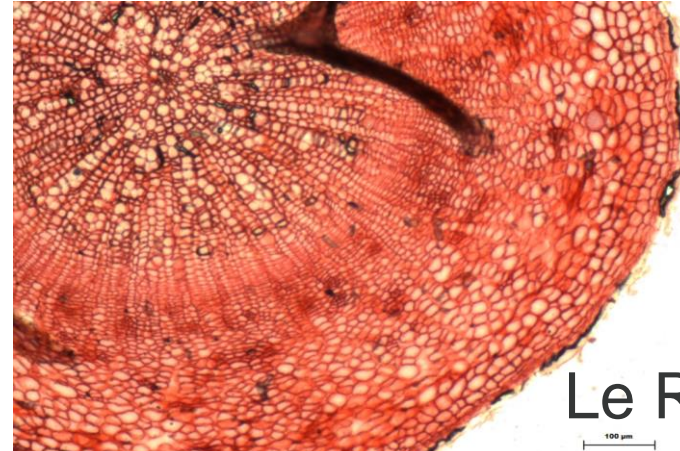
# 0 - PREAMBULE



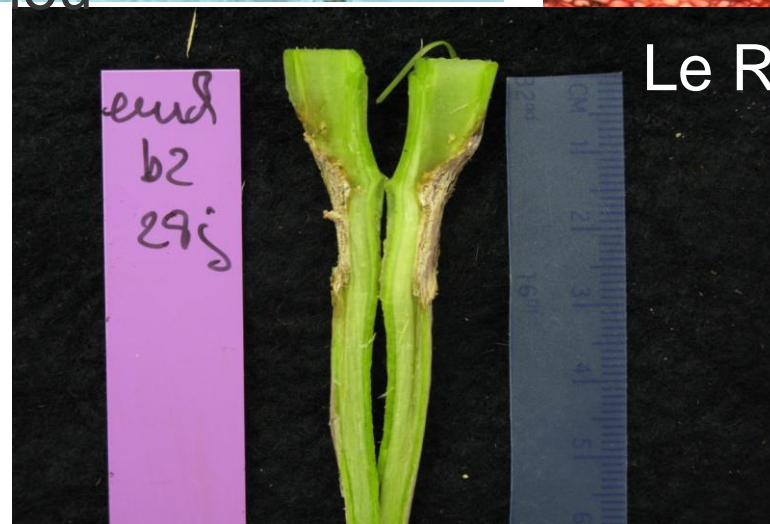
# 0 - PREAMBULE



Le Rheu



Le Rheu



Le R

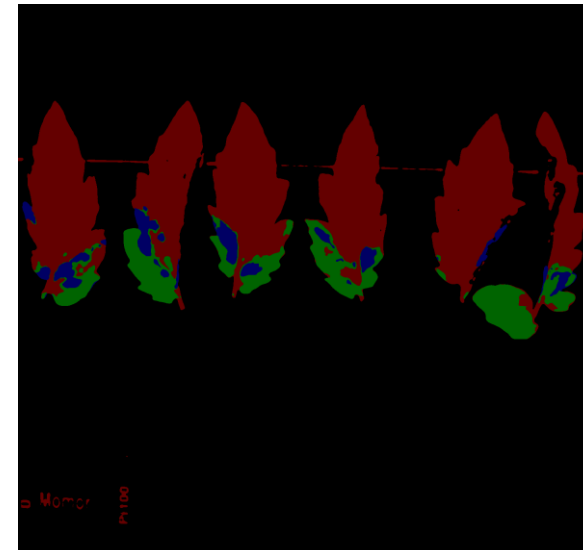
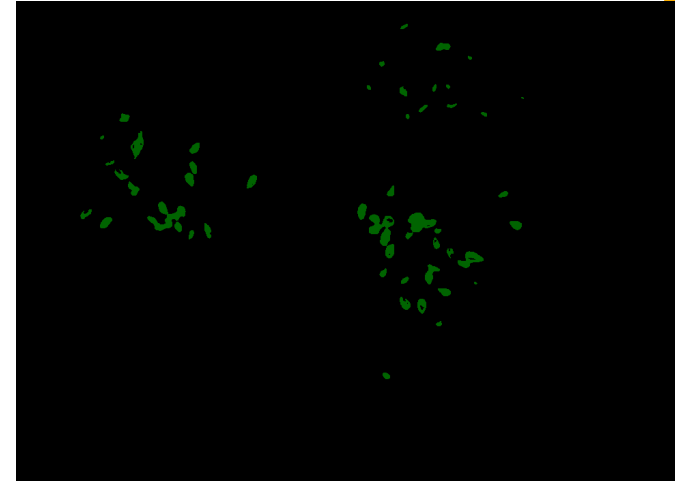
# 0 - PREAMBULE

Comment traiter ces  
images ?

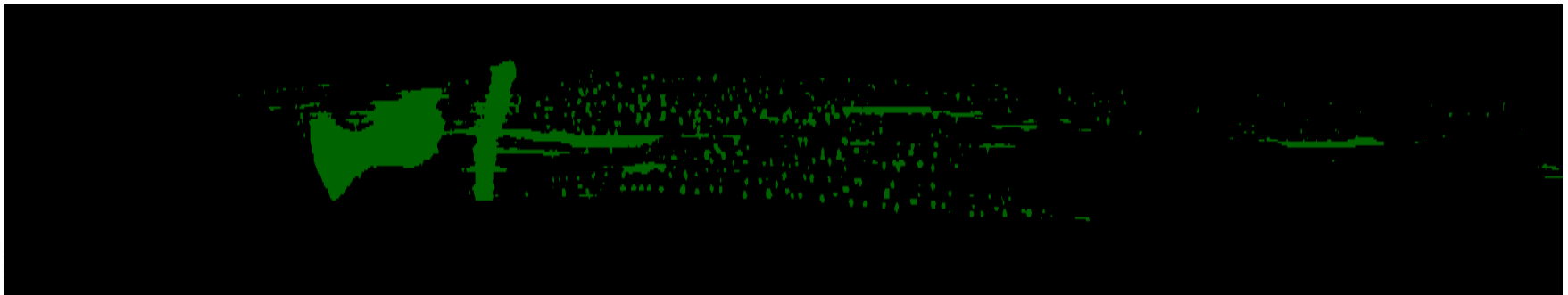
Sont-elles bien acquises ?



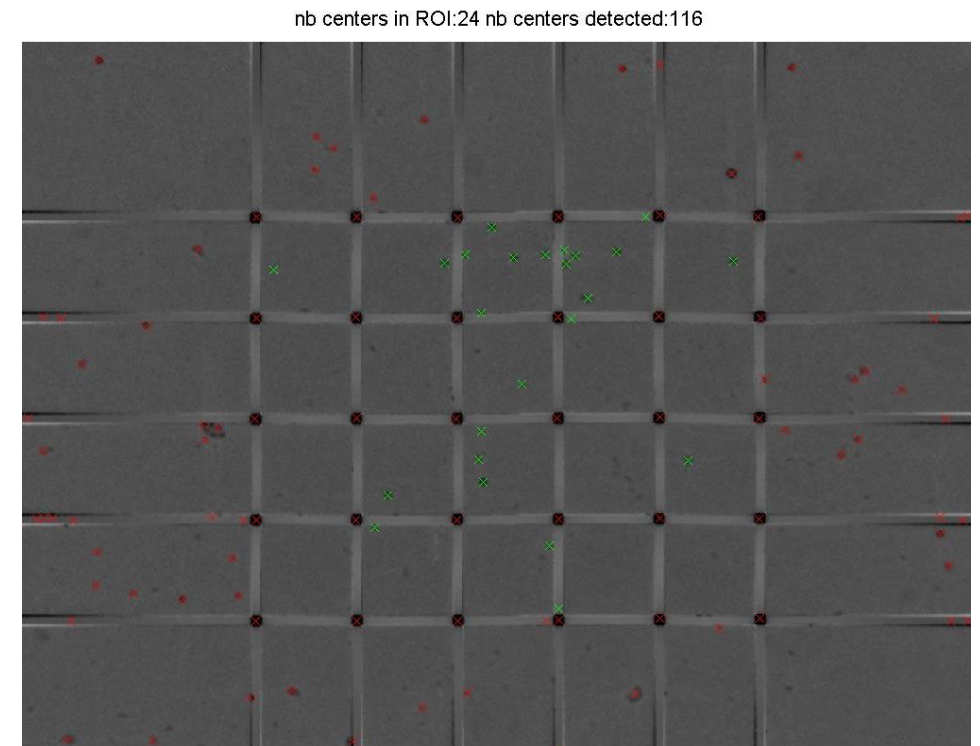
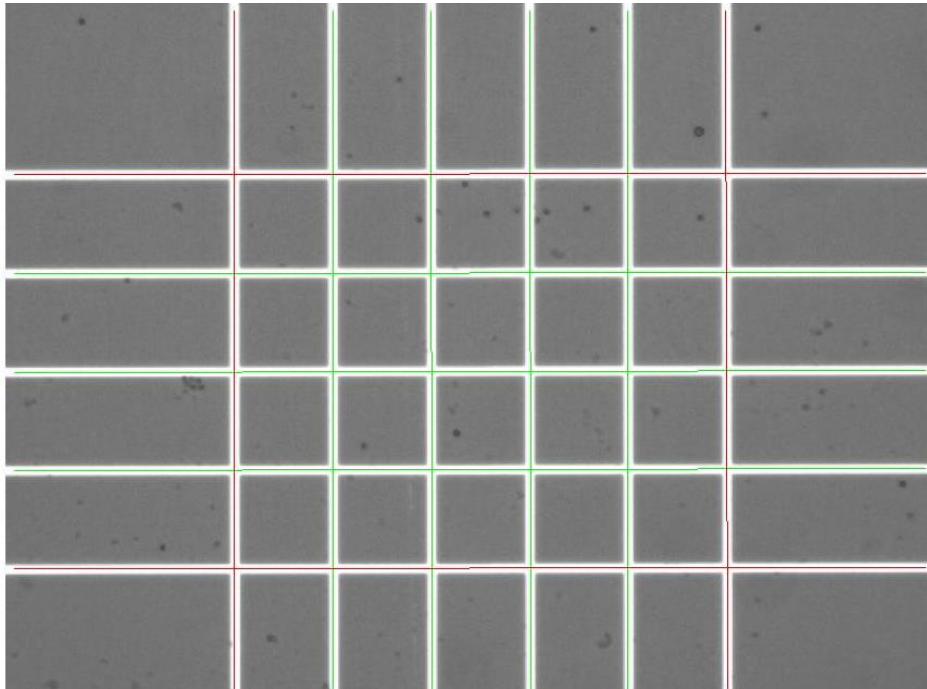
# 0 - PREAMBULE



# 0 - PREAMBULE



# 0 - PREAMBULE



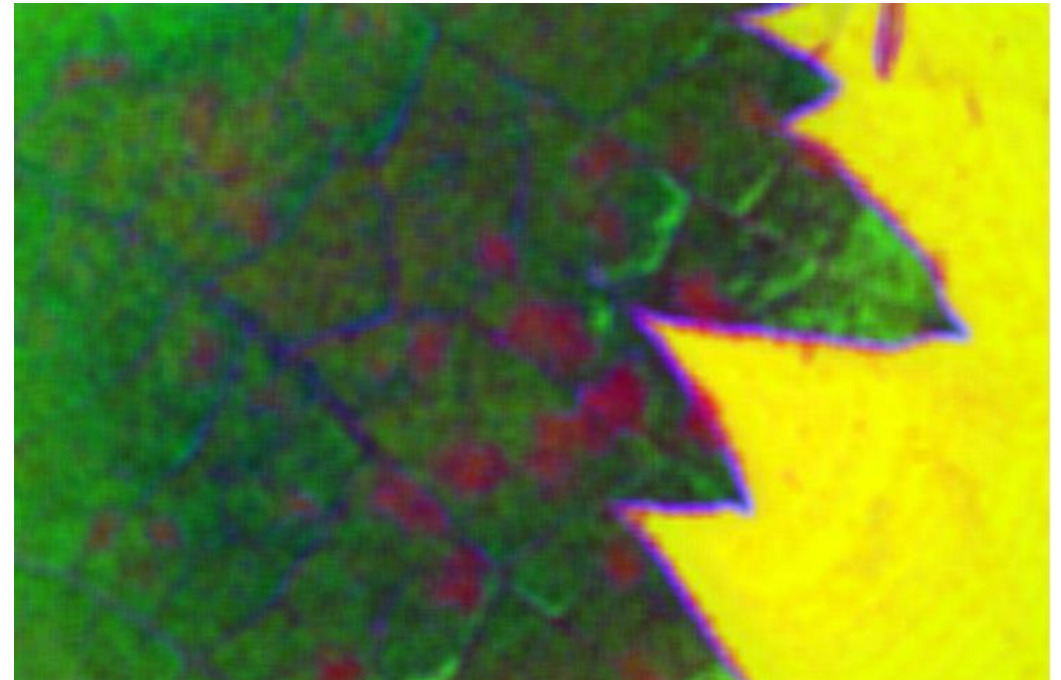
# 0 - PREAMBULE



Image d'origine



Image résultat





# 0 - PREAMBULE

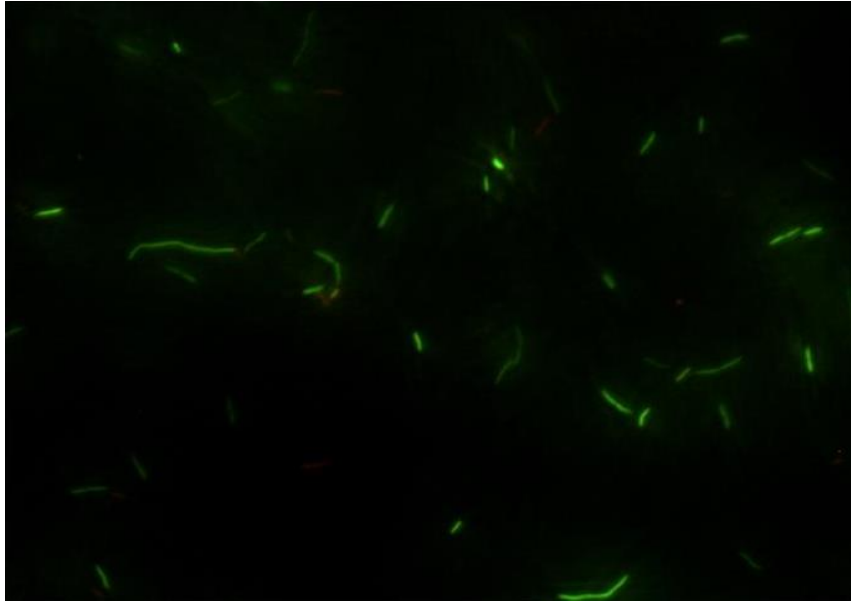
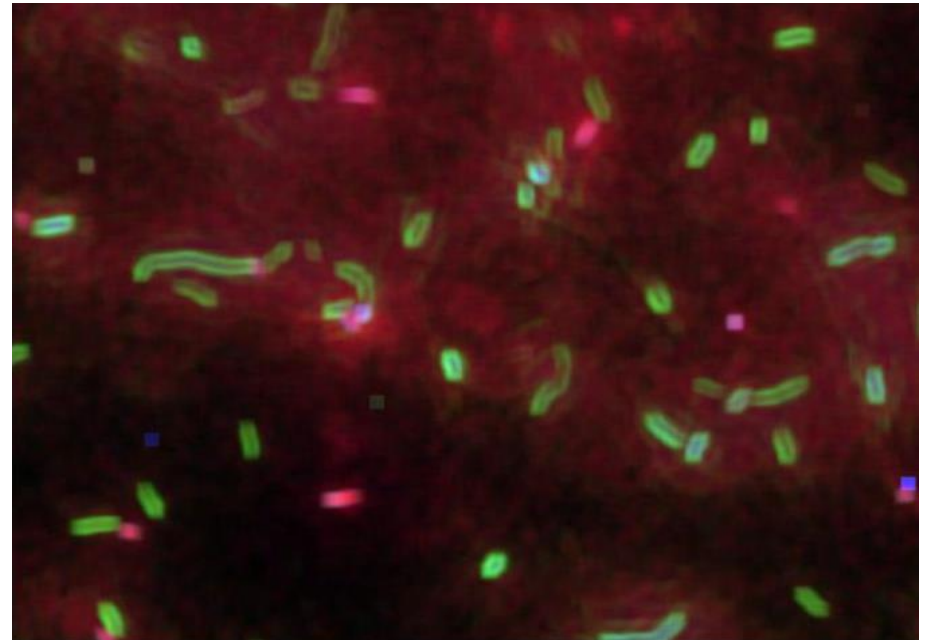


Image d'origine



Image résultat







0 - Préambule

**I - Introduction**

II - Définitions

III - Pré-traitement des images

IV - Segmentation image et contours

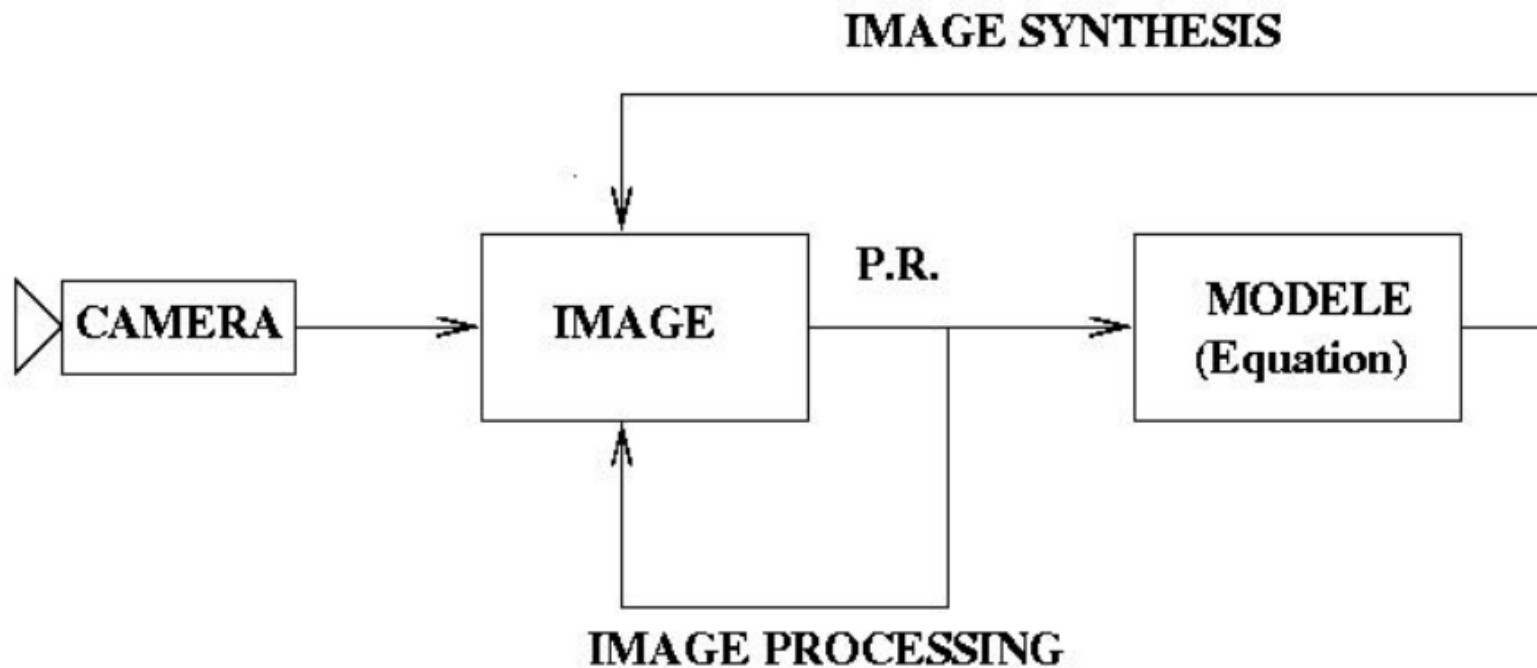
V - Hough et morphologie mathématique

VI – Analyse et Reconnaissance de formes

VII – Détection de mouvement

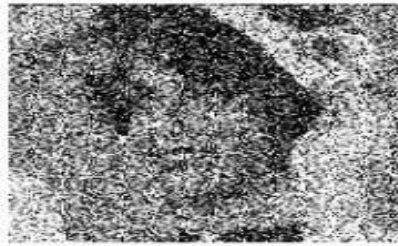
VIII – Introduction au Deep Learning

# I - INTRODUCTION



**P.R. : PATTERN RECOGNITION**

# I - INTRODUCTION



**Image Originale Bruitée**



**IMAGE PROCESSING**



**Image Traitée**

# I - INTRODUCTION



**Image Originale**



**PATTERN RECOGNITION**



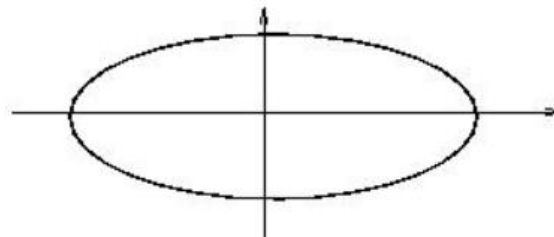
**ANSWER: WOMAN RECOGNIZED**

# I - INTRODUCTION

Equation originale:  $\frac{X^2}{a^2} + \frac{Y^2}{b^2} = 1$

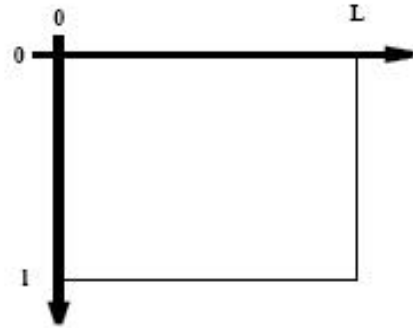


IMAGE SYNTHESIS

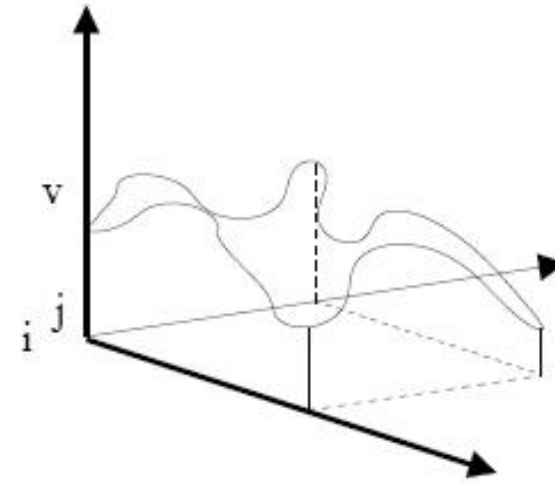




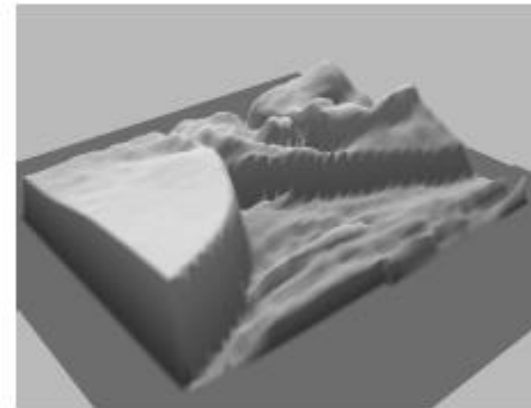
# I - INTRODUCTION



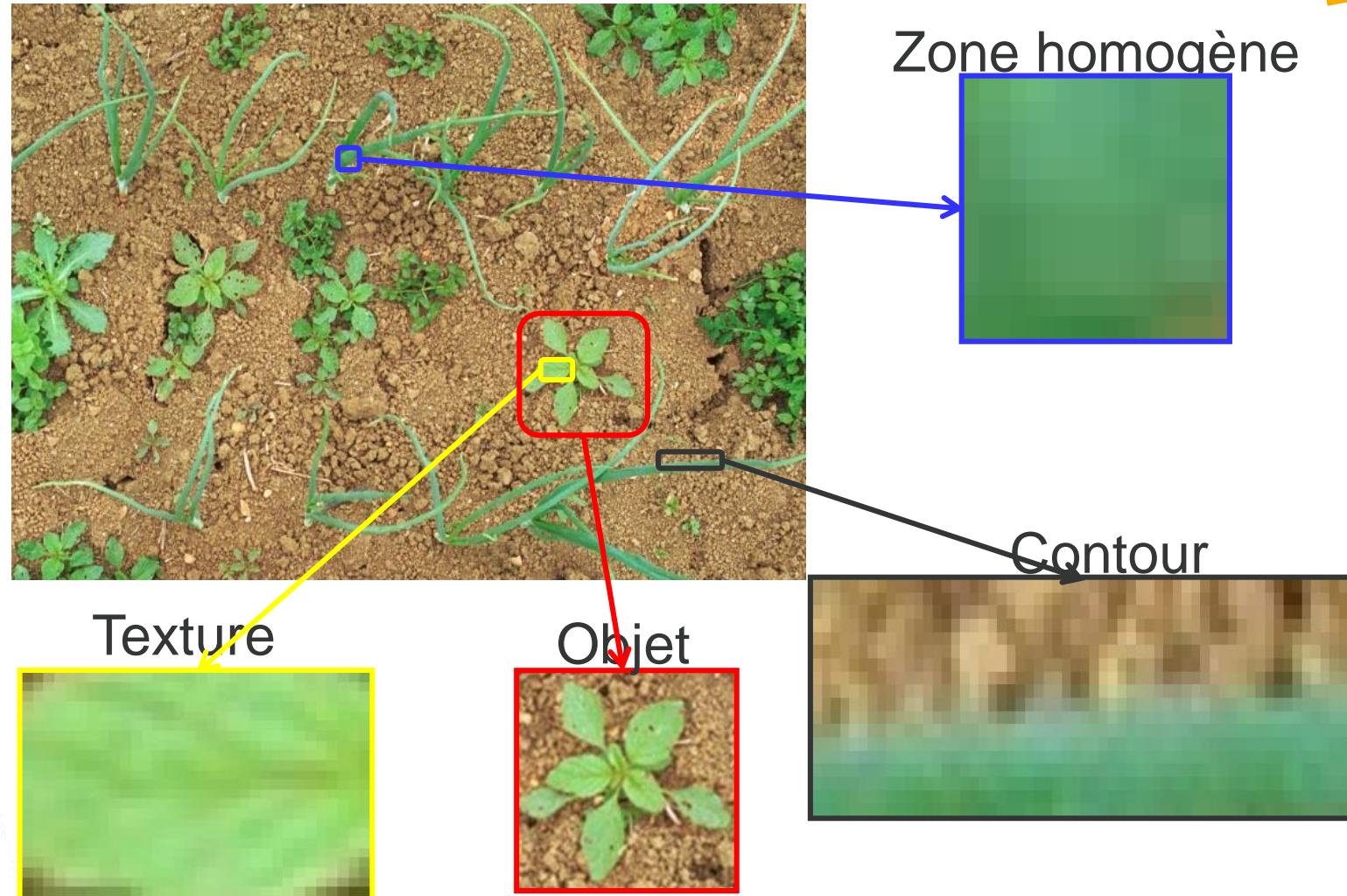
devient



donne



# I - INTRODUCTION



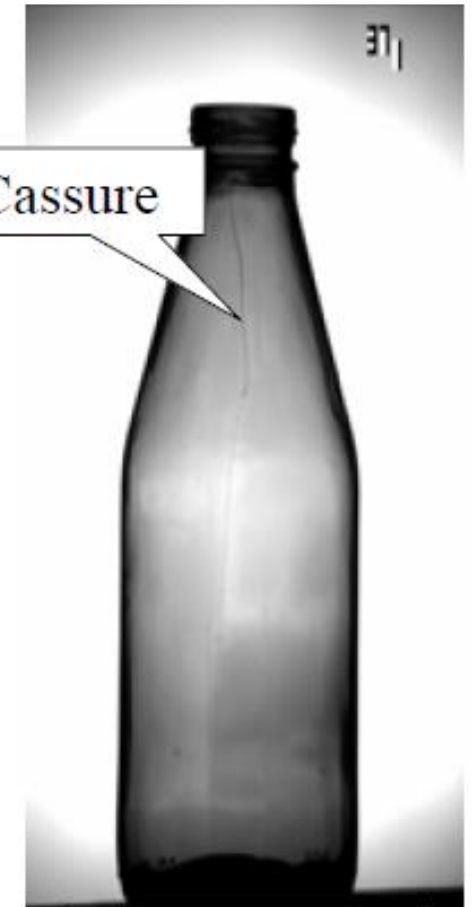
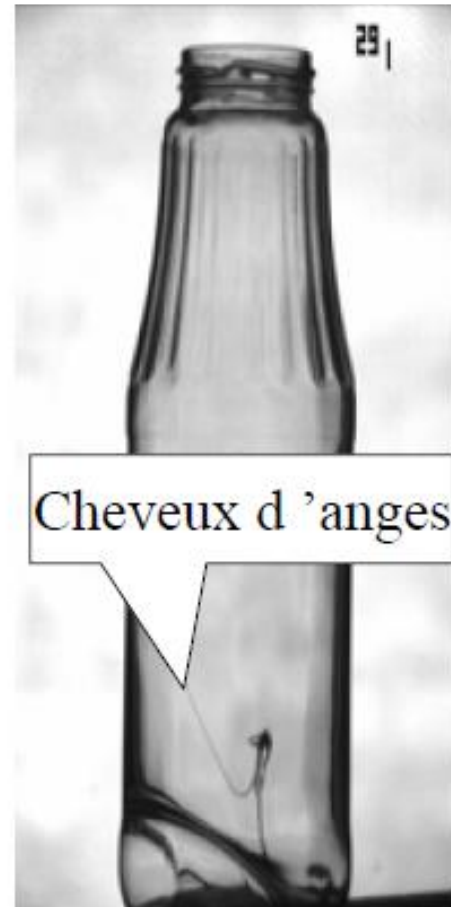
# I - INTRODUCTION

## APPLICATIONS

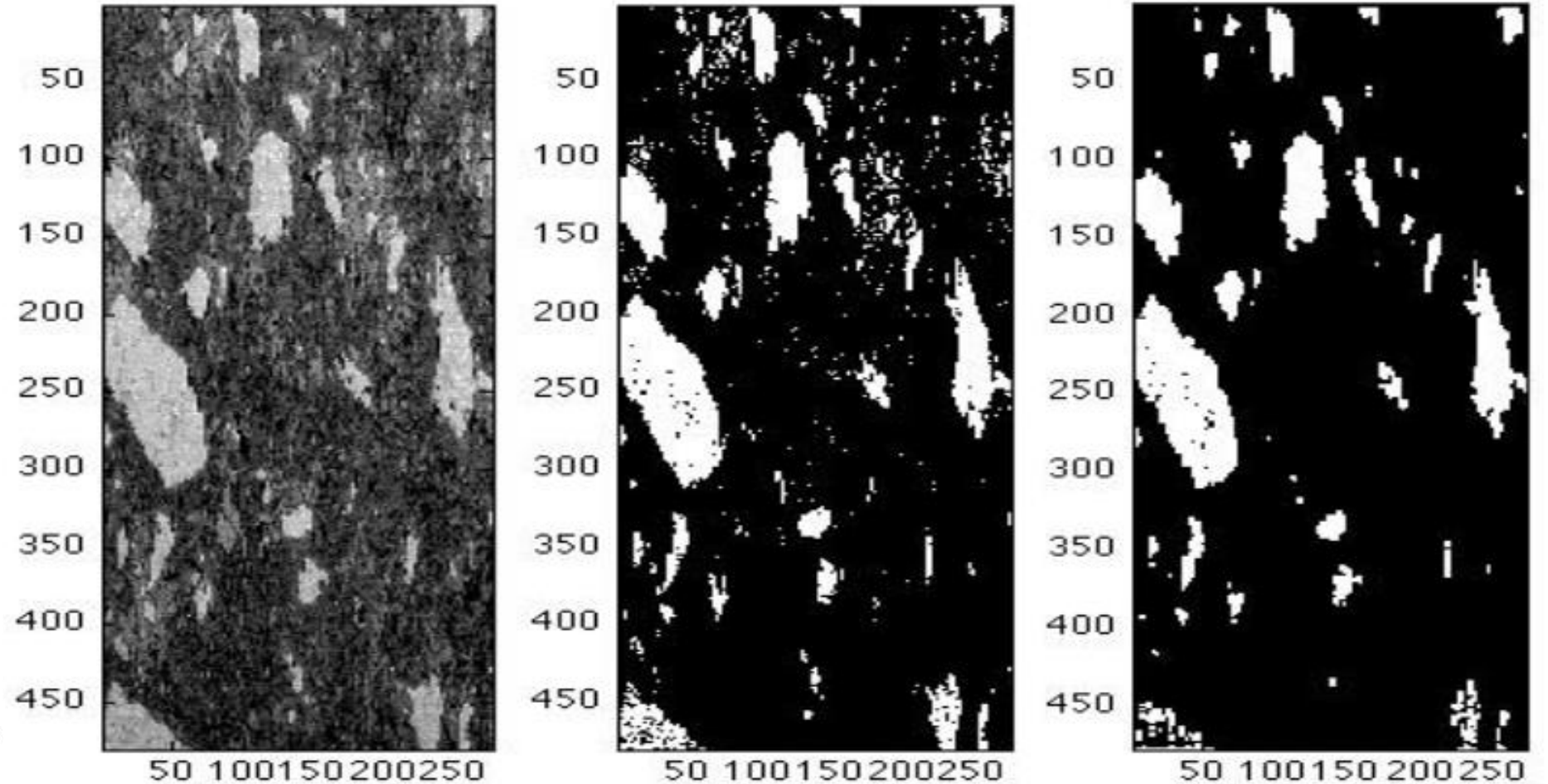
- ◆ **Détection de Défauts**
- ◆ **Reconnaissance de Formes**
- ◆ **Comptage d 'objets**
- ◆ **Analyse de Mouvements**
- ◆ **Réalité virtuelle, Synthèse d 'Image**
- ◆ **Compression et Transmission d 'Images**
- ◆ **Imagerie aérienne et spatiale**

# I - INTRODUCTION

## Détection de défauts sur des bouteilles

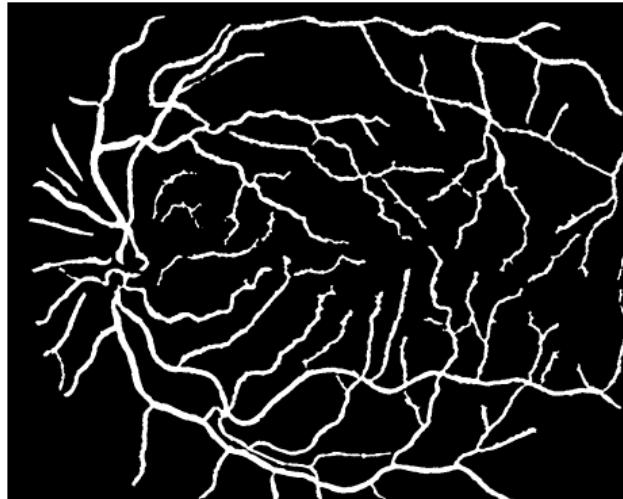


# I - INTRODUCTION

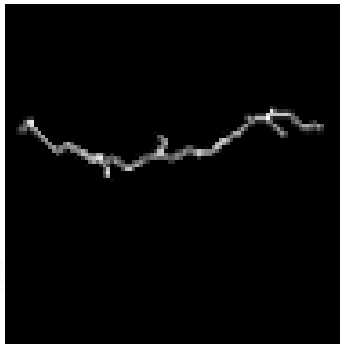
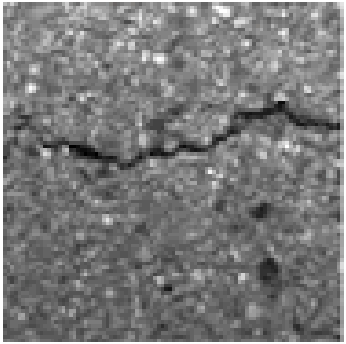




# I - INTRODUCTION



# I - INTRODUCTION



Détection de défauts

Automatisation de production



Détection de position



Tri sélectif

# I - INTRODUCTION

## Sécurité - Surveillance



Détection de Personnes



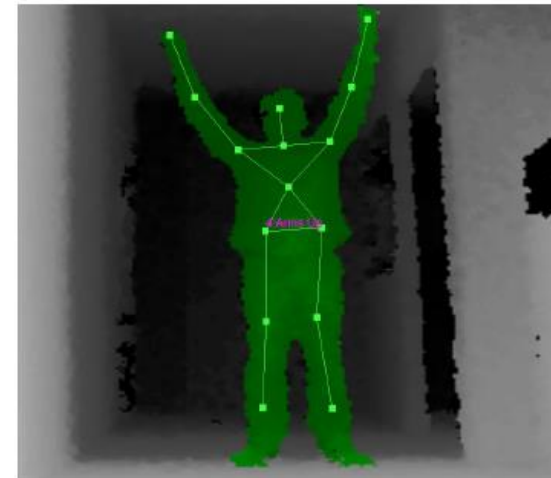
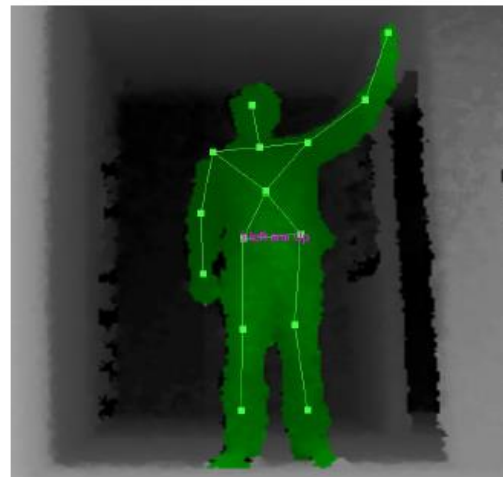
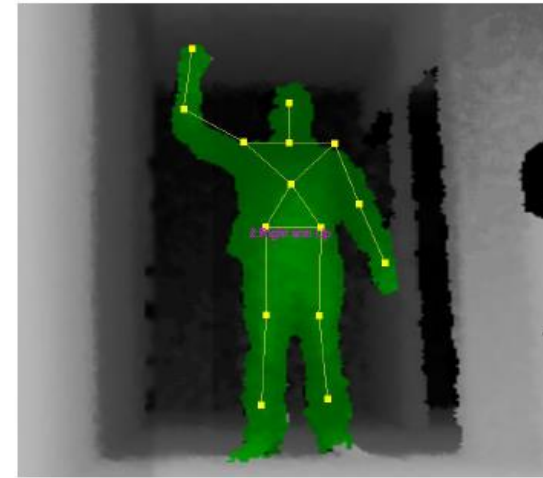
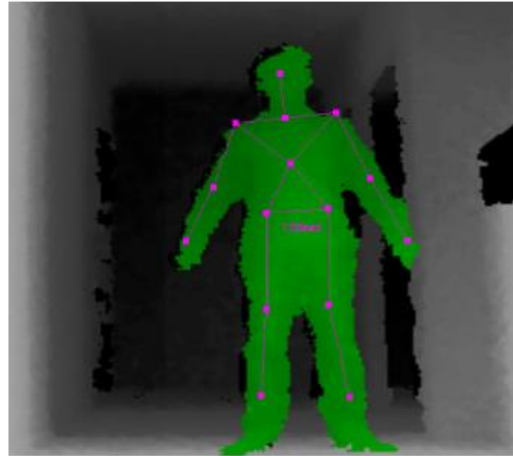
Tracking



Détection d'évènements

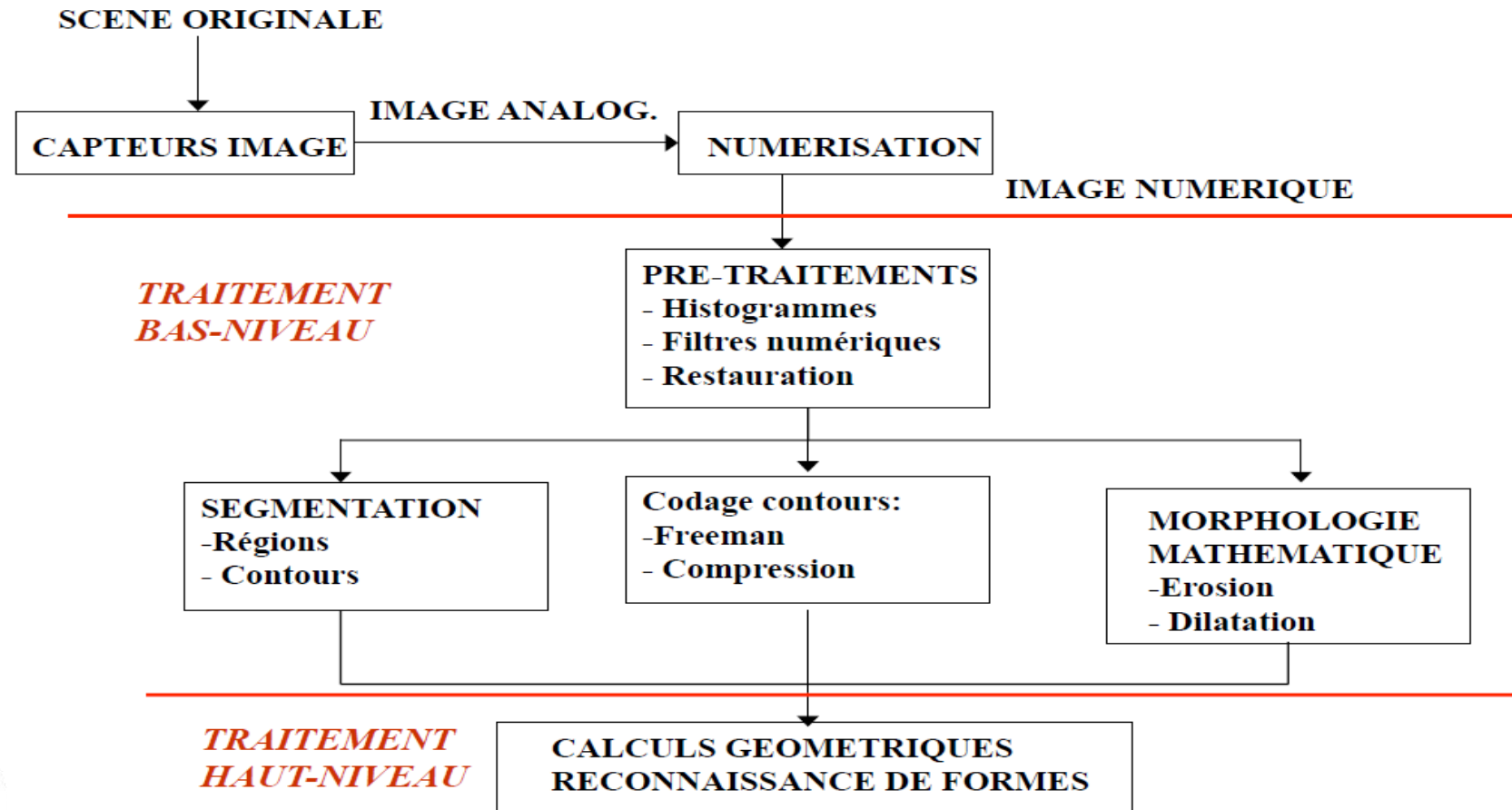
# I - INTRODUCTION

IHM



# I - INTRODUCTION

## SYNOPTIQUE DES TRAITEMENTS







0 - Préambule

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**II - Définitions**

III - Pré-traitement des images

IV - Segmentation image et contours

V - Hough et morphologie mathématique

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## II - DEFINITIONS

### Œil Humain ou Œil Artificiel?

- Résolution spatiale : Œil Humain > Œil Artificiel

#### - Œil Humain:

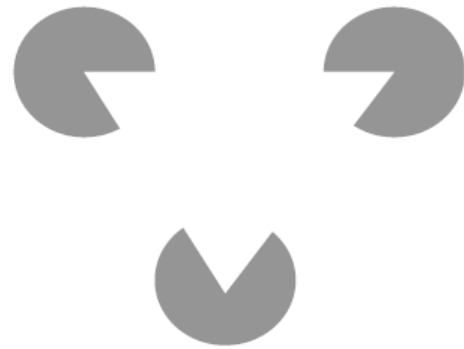
- \* Cônes rétiens sensibles couleur ~ 1 million pixels couleur
- \* Bâtonnets rétiens sensibles contraste >50 millions pixels N/B

#### - Œil Artificiel (Capteur Image):

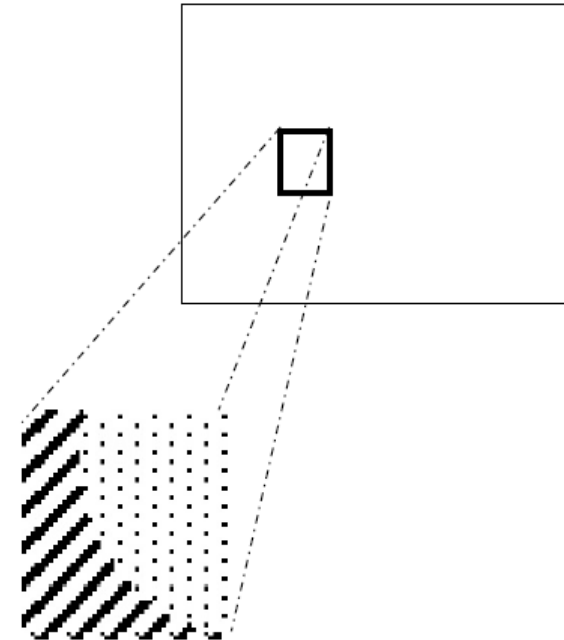
- \* Image N/B courante: 1024x1024 pixels  
~ 1 million pixels N/B
- \* Image N/B Haute-définition: 4096x4096 pixels  
~ 16 millions pixels N/B

## II - DEFINITIONS

Avantages and limits of computer visions vs **human vision**



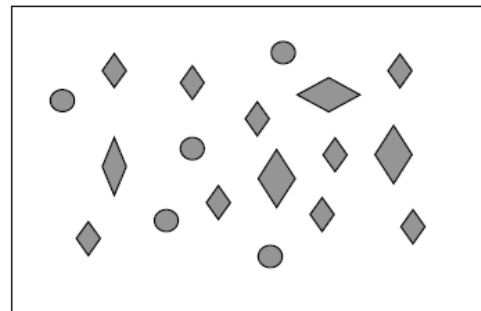
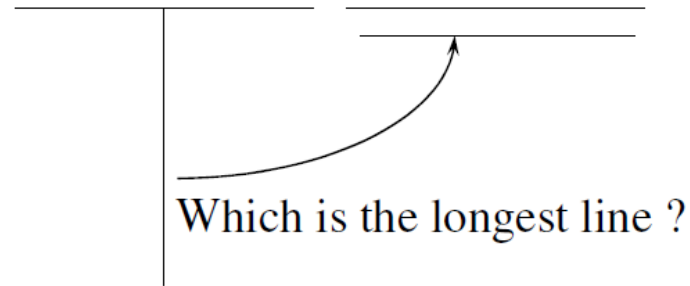
A triangle ?



Where is the limit of the circle?

## II - DEFINITIONS

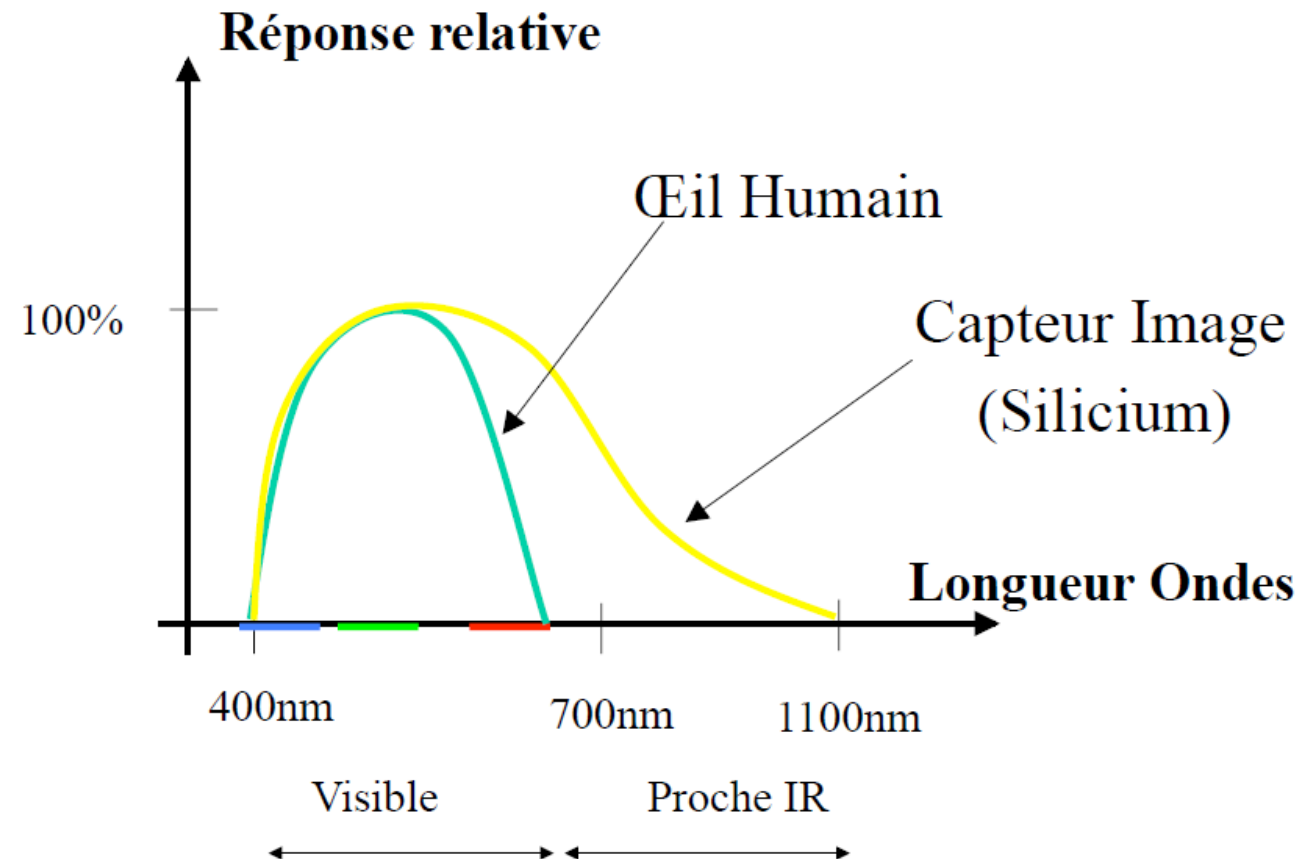
### Avantages and limits of **computer vision** vs human vision



*Be aware of what you think you see!*

## II - DEFINITIONS

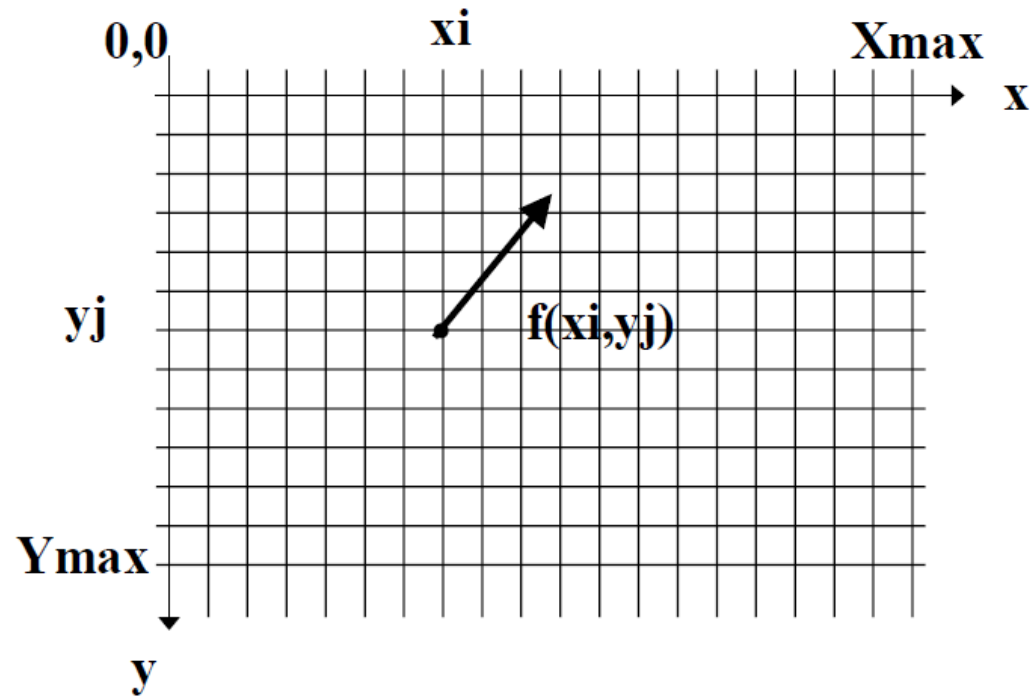
- Réponse spectrale: Œil Humain < Œil Artificiel





## II - DEFINITIONS

### Représentation d'une image numérique



$f(x_i, y_j)$ : Niveau gris pixel aux coordonnées  $(x_i, y_j)$

$f(x_i, y_j)$  entre 0 and 255

Si  $f(x_i, y_j)=0$  alors Pixel Noir

Si  $f(x_i, y_j)=255$  alors Pixel Blanc



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# III – PRE-TRAITEMENT DES IMAGES

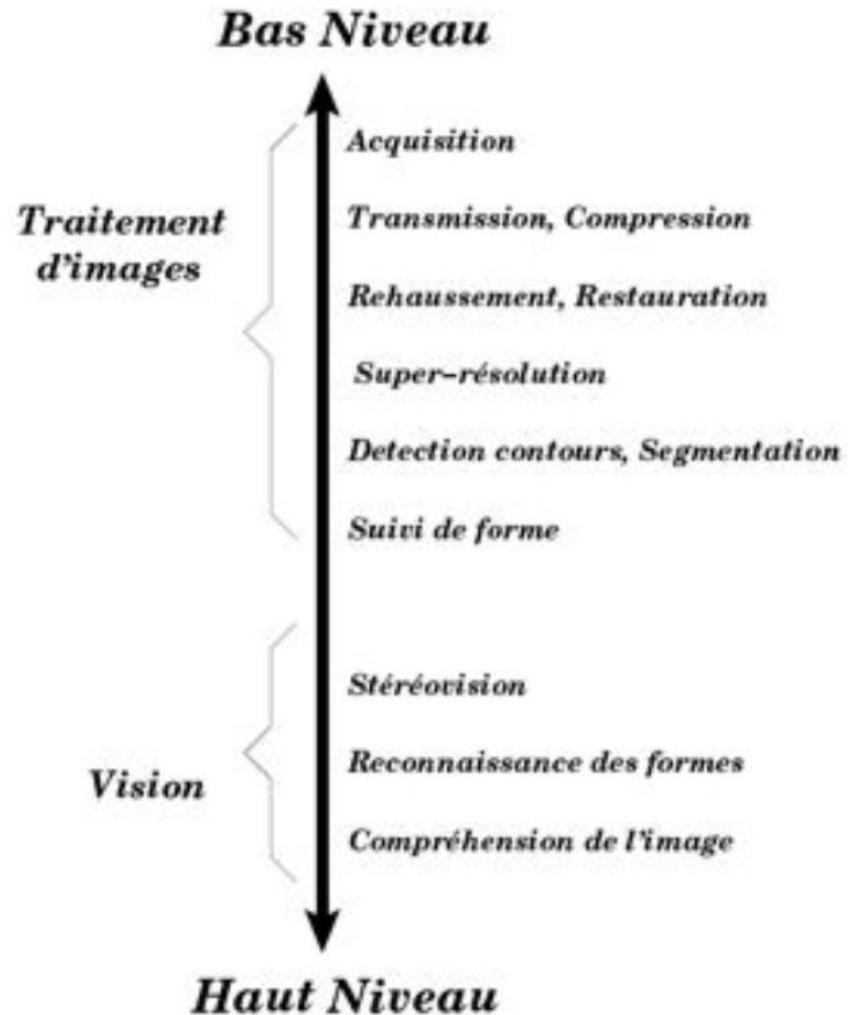
## III-1 Histogrammes

## III-2 Egalisation d 'Histogrammes

## III-3 Filtres numériques dans le domaine spatial

## III-4 Filtres numériques dans le domaine fréquentiel

# III – PRE-TRAITEMENT DES IMAGES



# III – PRE-TRAITEMENT DES IMAGES

## III – 1 Histogramme

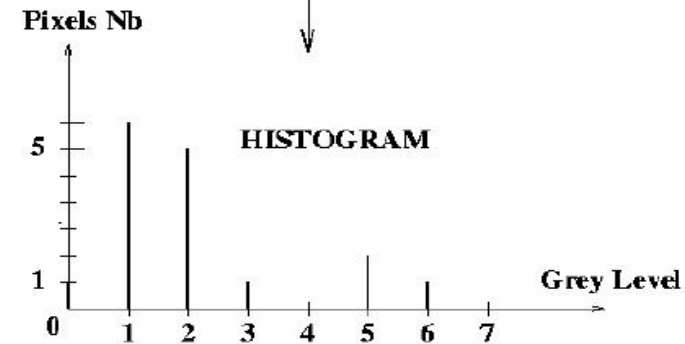
Image 4x4 Pixels

1	1	2	1
3	5	0	5
2	2	1	6
2	2	1	1

( Grey Levels between 0 and 7)



Grey Level	0	1	2	3	4	5	6	7
Pixels Nb	1	6	5	1	0	2	1	0





# III – PRE-TRAITEMENT DES IMAGES

Différents types  
d'histogrammes

Image «Claire»



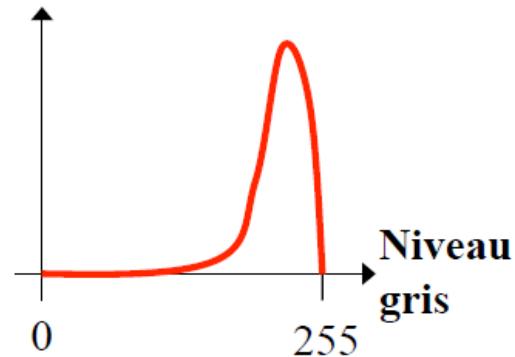
Image « Sombre »



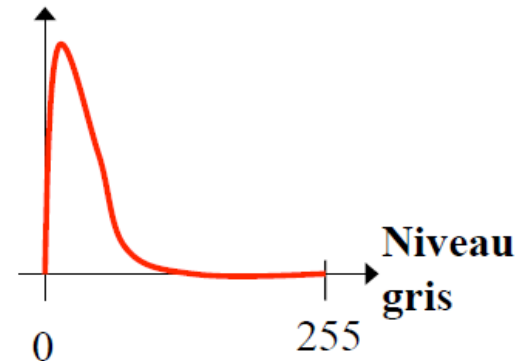
Image « Bi-Modale »



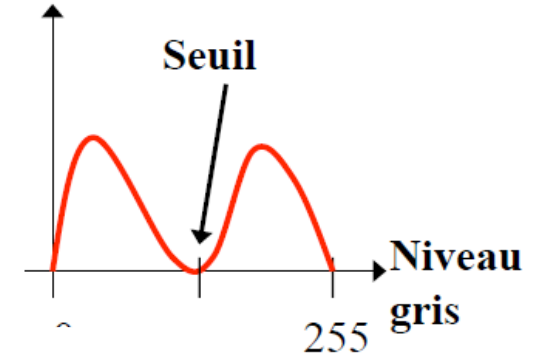
Nb Pixels



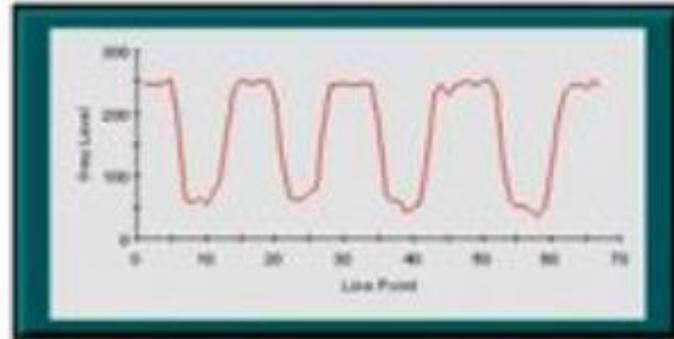
Nb Pixels



Nb Pixels

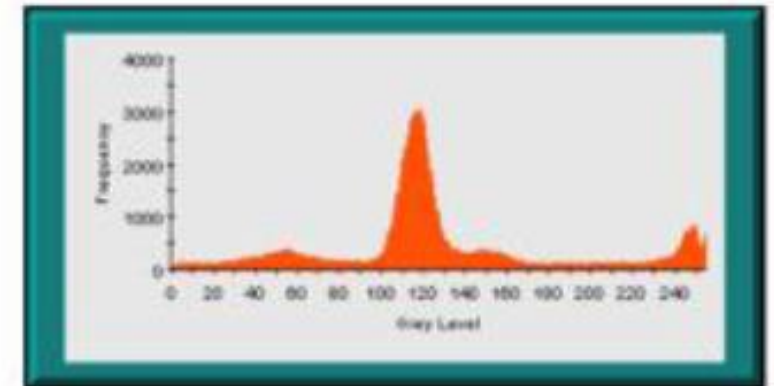


# III – PRE-TRAITEMENT DES IMAGES



1 ligne

Image  
entière



# III – PRE-TRAITEMENT DES IMAGES

Image of 512x512 Pixels coded on 8 bits ( 256 K Bytes)

( $2^8 = 256$  Grey Levels)

## Algorithme de l'histogramme

```
For Grey= 0 TO 255
  N_Pixels(Grey)=0    --> Table N_Pixels = 0
End Grey

For Y= 0 to 511    --> Image Scanning
  For X= 0 to 511
    Grey=f(X,Y)
    N_Pixels(Grey)=N_Pixels(Grey) + 1
  End X
End Y
```

Total Computations:

- 256 K Reading
- 256 K Additions
- 256 K Writing