Hybrid Precoding for Multi-Group Multicasting in mmWave Systems

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Overview •0

Overview

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Digital precoding for multicasting is a well-studied topic in the literature.



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Overview

- Digital precoding for multicasting is a well-studied topic in the literature.
- However, its benefits and challenges for hybrid precoders in mmWave systems require additional study.



Overview

- Digital precoding for multicasting is a well-studied topic in the literature.
- However, its benefits and challenges for hybrid precoders in mmWave systems require additional study.
- We investigate the joint design of hybrid transmit precoders (with an arbitrary number of finite-resolution phase shifts) and receive combiners for mmWave multi-group multicasting.



Overview

- Our proposed is based on:
 - Semidefinite relaxation (SDR) [convexification]
 - Alternating optimization [several parameters]
 - Cholesky matrix factorization [arbitrary phase shifts]
- Our proposed design does not require:
 - Code-books
 - The optimal solution obtained by solving the problem with a fully-digital precoder.



Multi-group Multicasting

Background

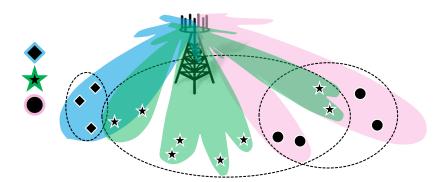


Figure: Multi-group Multicasting



Hybrid Precoder

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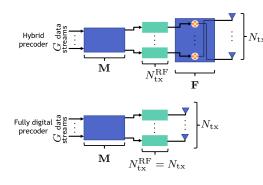


Figure: Multi-group Multicasting

 $\mathbf{M} \in \mathbb{C}^{N_{\mathrm{tx}}^{\mathrm{RF}} \times G}$: digital precoder $\mathbf{F} \in \mathcal{F}^{N_{\mathrm{tx}} \times N_{\mathrm{tx}}^{\mathrm{RF}}}$: analog precoder $\mathcal{F} = \left\{ \sqrt{\delta}, \dots, \sqrt{\delta} e^{\frac{2\pi(L-1)}{L}} \right\} : \text{ set}$ of phase shifts

 $N_{\rm tx}$: number of transmit antennas $N_{\rm tx}^{\rm RF} > G$: number of RF chains

L: number of phase shifts

G: number of multicast groups



System Model

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Downlink signal

$$\mathbf{x} = \mathbf{FMs} = \mathbf{F} \left[\mathbf{m}_1, \dots, \mathbf{m}_G \right] \left[s_1, \dots, s_G \right]^T$$
 (1)

Received signal by user $k \in \mathcal{G}_i$, $i \in \mathcal{I}$

$$y_k = \mathbf{w}_k^H (\mathbf{H}_k \mathbf{x} + \mathbf{n}_k)$$

$$y_k = \mathbf{w}_k^H \mathbf{H}_k \sum_{j=1}^G \mathbf{F} \mathbf{m}_j s_j + \mathbf{w}_k^H \mathbf{n}_k,$$
aggregate multicast signals (2)

 $\mathcal{K} = \{1, 2, \dots, K\}$: set of users $\mathcal{I} = \{1, 2, \dots, G\}$: set of groups \mathcal{G}_i : set of user indices (in multicast group i) s_i : symbol for multicast group i



System Model

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$$y_k = \underbrace{\mathbf{w}_k^H \mathbf{H}_k \mathbf{F} \mathbf{m}_i s_i}_{\text{desired multicast signal}} + \underbrace{\mathbf{w}_k^H \mathbf{H}_k \sum_{\substack{j=1\\j \neq i}}^G \mathbf{F} \mathbf{m}_j s_j}_{\text{interference}} + \underbrace{\mathbf{w}_k^H \mathbf{n}_k}_{\text{noise}},$$
(3)

$$SINR_{k} = \frac{\left|\mathbf{w}_{k}^{H}\mathbf{H}_{k}\mathbf{F}\mathbf{m}_{i}\right|^{2}}{\sum_{j\neq i}\left|\mathbf{w}_{k}^{H}\mathbf{H}_{k}\mathbf{F}\mathbf{m}_{j}\right|^{2} + \sigma^{2}\left\|\mathbf{w}_{k}\right\|_{2}^{2}}, k \in \mathcal{G}_{i}, \qquad (4)$$

 \mathbf{w}_k : combiner of the k-th user

 \mathbf{H}_k : channel between the gNodeB and the k-th user

G: number of multicast groups

K: number of users

 $\mathcal{K} = \{1, 2, \dots, K\}$: set of users $\mathcal{I} = \{1, 2, \dots, G\}$: set of groups

 G_i : set of user indices (in multicast group i)

 s_i : symbol for multicast group i



Problem Formulation

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$$\mathcal{P}_{0}^{\text{hyb}}: \min_{\substack{\mathbf{F}, \{\mathbf{m}_{i}\}_{i=1}^{G}, \\ \{\mathbf{w}_{k}\}_{k=1}^{K}, \{x_{k}\}_{k=1}^{K}}} \sum_{i=1}^{G} \|\mathbf{F}\mathbf{m}_{i}\|_{2}^{2} + \beta \sum_{k=1}^{K} x_{k}$$

$$\sum_{i=1}^{G} \|\mathbf{Fm}_{i}\|_{2}^{2} + \beta \sum_{k=1}^{K} x_{k}$$
 (5a)

$$\frac{\left|\mathbf{w}_{k}^{H}\mathbf{H}_{k}\mathbf{F}\mathbf{m}_{i}\right|^{2} + x_{k}}{\sum_{j \neq i} \left|\mathbf{w}_{k}^{H}\mathbf{H}_{k}\mathbf{F}\mathbf{m}_{j}\right|^{2} + \sigma^{2} \left\|\mathbf{w}_{k}\right\|_{2}^{2}} > \gamma_{i}, \forall k \in \mathcal{G}_{i}, \forall i \in \mathcal{I},$$

$$\|\mathbf{w}_k\|_2^2 = P_{\text{rx}}^{\text{max}}, k \in \mathcal{K}, \tag{5c}$$

$$[\mathbf{F}]_{q,r} \in \mathcal{F}, q \in \mathcal{Q}, r \in \mathcal{R},$$
 (5d)

$$x_k \ge 0,\tag{5e}$$

$$q \in \mathcal{Q} = \{1, 2, \dots, N_{\text{tx}}\}, r \in \mathcal{R} = \{1, 2, \dots, N_{\text{tx}}^{\text{RF}}\}$$





(5b)

Optimization of F

$$\mathcal{P}_{1}^{\text{hyb}} : \min_{\mathbf{F}, \{x_{k}\}_{k=1}^{K}} \quad \sum_{i=1}^{G} \|\mathbf{F}\mathbf{m}_{i}\|_{2}^{2} + \beta \sum_{k=1}^{K} x_{k}$$
s.t.
$$\gamma_{i} \left(\sum_{j \neq i} \left| \mathbf{w}_{k}^{H} \mathbf{H}_{k} \mathbf{F} \mathbf{m}_{j} \right|^{2} + \sigma^{2} \|\mathbf{w}_{k}\|_{2}^{2} \right)$$

$$- \left| \mathbf{w}_{k}^{H} \mathbf{H}_{k} \mathbf{F} \mathbf{m}_{i} \right|^{2} \leq x_{k}, \forall k \in \mathcal{G}_{i}, \forall i \in \mathcal{I},$$
 (6b)
$$[\mathbf{F}]_{q,r} \in \mathcal{F}, q \in \mathcal{Q}, r \in \mathcal{R},$$
 (6c)
$$x_{k} \geq 0,$$
 (6d)



System Model

$$\mathcal{P}_1^{ ext{hyb}}: \min_{\mathbf{f}, \{x_k\}_{k=1}^K}$$
 s.t.

Background

$$\mathcal{P}_{1}^{\text{hyb}}: \min_{\mathbf{f}, \{x_{k}\}_{k=1}^{K}} \quad \sum_{i=1}^{G} \|\mathbf{J}_{i}\mathbf{f}\|_{2}^{2} + \beta \sum_{k=1}^{K} x_{k}$$
 (7a)

$$\gamma_i \left(\sum_{j \neq i} \left| \mathbf{w}_k^H \mathbf{H}_k \mathbf{J}_j \mathbf{f} \right|^2 + \sigma^2 \left\| \mathbf{w}_k \right\|_2^2 \right)$$

$$-\left|\mathbf{w}_{k}^{H}\mathbf{H}_{k}\mathbf{J}_{i}\mathbf{f}\right|^{2} \leq x_{k}, \forall k \in \mathcal{G}_{i}, i \in \mathcal{I}, \quad (7b)$$

$$[\mathbf{f}]_n \in \mathcal{F}, n \in \mathcal{N},$$
 (7c)

$$x \ge 0,\tag{7d}$$

where $\mathbf{Fm}_i = \mathbf{J}_i \mathbf{f}$, $\mathbf{J}_i = \mathbf{m}_i^T \otimes \mathbf{I}$, $\mathbf{f} = \text{vec}(\mathbf{F})$ and $\mathcal{N} = \{1, 2, \dots, N_{\rm tx}^{\rm RF} N_{\rm tx} \}.$



Simulation Results

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Optimization of F: SDP Representation

 $\mathcal{P}_{\mathrm{SDP},1}^{\mathrm{hyb}} : \min_{\mathbf{D}, \{x_k\}_{k=1}^K} \sum_{i=1}^G \mathrm{Tr}\left(\mathbf{D}\mathbf{R}_i\right) + \beta \sum_{i=1}^K x_k$ (8a)

$$\operatorname{Tr}\left(\mathbf{D}\left(\gamma_{i} \sum_{j \neq i} \mathbf{V}_{j,k} - \mathbf{V}_{i,k}\right)\right) + \sigma^{2} \gamma_{i} \|\mathbf{w}_{k}\|_{2}^{2}$$

$$< x_{k}, \forall k \in \mathcal{G}_{i}, i \in \mathcal{I}, \tag{8b}$$

$$[\mathbf{D}]_{n,n} = \delta, n \in \mathcal{N},\tag{8c}$$

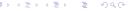
$$rank(\mathbf{D}) = 1, (8d)$$

$$\mathbf{D} \succcurlyeq \mathbf{0},$$
 (8e)

$$x_k > 0, \tag{8f}$$

where
$$\mathbf{D} = \mathbf{f}\mathbf{f}^H$$
, $\|\mathbf{J}_i\mathbf{f}\|_2^2 = \operatorname{Tr}(\mathbf{R}_i\mathbf{D})$, $\mathbf{R}_i = \mathbf{J}_i^H\mathbf{J}_i$, $\|\mathbf{w}_k^H\mathbf{H}_k\mathbf{J}_i\mathbf{f}\|^2 = \operatorname{Tr}(\mathbf{V}_{i,k}\mathbf{D})$ and $\mathbf{V}_{i,k} = \mathbf{J}_i^H\mathbf{H}_k^H\mathbf{w}_k\mathbf{w}_k^H\mathbf{H}_k\mathbf{J}_i$.





Simulation Results

Optimization of F: SDR Representation

$$\mathcal{P}_{\mathrm{SDR},1}^{\mathrm{hyb}}: \min_{\mathbf{D}, \{x_k\}_{k=1}^K} \ \mathrm{s.t.}$$

$$\mathcal{P}_{\mathrm{SDR},1}^{\mathrm{hyb}} : \min_{\mathbf{D}, \{x_k\}_{k=1}^K} \quad \sum_{i=1}^G \mathrm{Tr}\left(\mathbf{D}\mathbf{R}_i\right) + \beta \sum_{k=1}^K x_k \tag{9a}$$

$$\operatorname{Tr}\left(\mathbf{D}\left(\gamma_{i} \sum_{j \neq i} \mathbf{V}_{j,k} - \mathbf{V}_{i,k}\right)\right) + \sigma^{2} \gamma_{i} \|\mathbf{w}_{k}\|_{2}^{2} \leq x_{k}, \forall k \in \mathcal{G}_{i}, i \in \mathcal{I}, \quad (9b)$$

$$[\mathbf{D}]_{n,n} = \delta, n \in \mathcal{N},\tag{9c}$$

$$\mathbf{D} \succcurlyeq \mathbf{0},\tag{9d}$$

$$x_k \ge 0, \tag{9e}$$





Optimization of F: Phase Recovery - Stage A_1

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Stage A_1 :

- Any element (n_1, n_2) of matrix **D** can be represented as $[\mathbf{D}]_{n_1,n_2} = [\mathbf{f}]_{n_1} [\mathbf{f}]_{n_2}^*, n_1, n_2 \in \mathcal{N} = \{1, 2, \dots, N_{\text{tx}}^{\text{RF}} N_{\text{tx}}\}$
- We define a vector $\mathbf{u} \in \mathbb{C}^{N_{\mathrm{tx}}^{\mathrm{RF}}N_{\mathrm{tx}} \times 1}$ such that $\|\mathbf{u}\|_{2}^{2} = \mathbf{u}^{H}\mathbf{u} = 1.$
- We can express $[\mathbf{D}]_{n_1,n_2}$ in terms of \mathbf{u} , i.e., $[\mathbf{D}]_{n_1,n_2} = ([\mathbf{f}]_{n_1} \mathbf{u}^T) ([\mathbf{f}]_{n_2}^* \mathbf{u}^*).$
- We assume that $\mathbf{q}_n = [\mathbf{f}]_n \mathbf{u}$.
- lacksquare Thus, $ldot{D}$ can be recast as $ldot{D} = old{Q}^T old{Q}^*$ with $\mathbf{Q} = \left[\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_{N_{\mathrm{tx}}^{\mathrm{RF}} N_{\mathrm{tx}}}\right].$





Stage A_2 :

- lacksquare We denote with $\widehat{\mathbf{D}}$ the solution returned by $\mathcal{P}^{\mathrm{hyb}}_{\mathrm{SDR},1}$
- Via Cholesky matrix factorization we obtain $\widehat{\mathbf{D}} = \widehat{\mathbf{Q}}^T \widehat{\mathbf{Q}}^*$, where $\widehat{\mathbf{Q}} = \left[\widehat{\mathbf{q}}_1, \widehat{\mathbf{q}}_2, \dots, \widehat{\mathbf{q}}_{N_{\mathrm{tx}}^{\mathrm{RF}} N_{\mathrm{tx}}}\right]$.
- We have derived a relation that associates $\widehat{\mathbf{f}}$ with $\{\widehat{\mathbf{q}}_n\}_{n=1}^{N_{\mathrm{tx}}^{\mathrm{RF}}N_{\mathrm{tx}}}$ (via $\widehat{\mathbf{q}}_n = \left[\widehat{\mathbf{f}}\right]_n \widehat{\mathbf{u}}$). However, both are unknown.
- The premise that all $\widehat{\mathbf{q}}_n$ can be obtained from the same $\widehat{\mathbf{u}}$ cannot be guaranteed.



■ Thus, we aim at finding an approximate $\hat{\mathbf{f}}$ and $\hat{\mathbf{u}}$, such that $\widehat{\mathbf{q}}_n pprox \left[\widehat{\mathbf{f}}\right]_{\mathbb{R}} \widehat{\mathbf{u}}$, and whose error in the 2-norm sense is minimum.

$$\mathcal{P}_{ ext{LS}}^{ ext{hyb}}: \quad \min_{\widehat{\mathbf{u}}, [\widehat{\mathbf{f}}]_n} \quad \sum_{n=1}^{N_{ ext{tx}}^{ ext{RF}} N_{ ext{tx}}} \left\| \widehat{\mathbf{q}}_n - \left[\widehat{\mathbf{f}} \right]_n \widehat{\mathbf{u}} \right\|_2^2$$
 (10a)

s.t.
$$\|\widehat{\mathbf{u}}\|_2^2 = 1$$
, (10b)

$$\left[\widehat{\mathbf{f}}\right]_n \in \mathcal{F}, n \in \mathcal{N}.$$
 (10c)



Optimization of F: Phase Recovery - Stage A_3

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Stage A3:

• Minimizing simultaneously over both $\widehat{\mathbf{q}}_n$ and $\widehat{\mathbf{u}}$ is challenging. If we assume that $\hat{\mathbf{u}}$ is known, then we are required to solve

$$\widetilde{\mathcal{P}}_{\mathrm{LS}}^{\mathrm{hyb}}: \quad \min_{\left[\widehat{\mathbf{f}}\right]_{n}} \sum_{n=1}^{N_{\mathrm{tx}}^{\mathrm{tx}} N_{\mathrm{tx}}} \left\| \widehat{\mathbf{q}}_{n} - \left[\widehat{\mathbf{f}}\right]_{n} \widehat{\mathbf{u}} \right\|_{2}^{2}$$

$$(11a)$$

s.t.
$$\left[\widehat{\mathbf{f}}\right]_n \in \mathcal{F}, n \in \mathcal{N}$$
 (11b)

$$\begin{split} & \quad \text{By expanding (11a), we obtain} \\ & \quad \left\| \widehat{\mathbf{q}}_n - \left[\widehat{\mathbf{f}} \right]_n \widehat{\mathbf{u}} \right\|_2^2 = \widehat{\mathbf{q}}_n^H \widehat{\mathbf{q}}_n - 2 \mathfrak{Re} \left(\left[\widehat{\mathbf{f}} \right]_n \widehat{\mathbf{q}}_n^H \widehat{\mathbf{u}} \right) + \left| \left[\widehat{\mathbf{f}} \right]_n \right|^2 \widehat{\mathbf{u}}^H \widehat{\mathbf{u}}. \end{split}$$





Optimization of F: Phase Recovery - Stage A_3

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Stage A₃:

■ Thus, (11) is equivalent to

$$\widetilde{\mathcal{P}}_{\mathrm{LS}}^{\mathrm{hyb}}: \qquad \max_{\left[\widehat{\mathbf{f}}\right]_{n}} \sum_{n=1}^{N_{\mathrm{tx}}^{\mathrm{RF}} N_{\mathrm{tx}}} \mathfrak{Re}\left(\left[\widehat{\mathbf{f}}\right]_{n} \widehat{\mathbf{q}}_{n}^{H} \widehat{\mathbf{u}}\right)$$

$$\mathrm{s.t.} \quad \left[\widehat{\mathbf{f}}\right]_{n} \in \mathcal{F}, n \in \mathcal{N}.$$

$$(12a)$$

- lacksquare Since $z_n=\widehat{\mathbf{q}}_n^H\widehat{\mathbf{u}}$ is known, (12a) is maximized when $\left|\widehat{\mathbf{f}}\right|$ $\in \mathcal{F}$ is chosen with the closest phase to z_n^* .
- lacksquare We solve $\widetilde{\mathcal{P}}_{{\scriptscriptstyle \mathsf{T}}\,{\scriptscriptstyle \mathsf{Q}}}^{{\scriptscriptstyle \mathsf{hyb}}}$ for N_{rand} candidate vectors $\widehat{\mathbf{u}}$ and select the choice that attains the minimum objective function value.





Optimization of ${\bf M}$

Background

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$$\mathcal{P}_{\mathrm{SDR},2}^{\mathrm{hyb}} : \min_{\substack{\{\mathbf{M}_i\}_{i=1}^G, \\ \{x_k\}_{k=1}^K}} \qquad \sum_{i=1}^G \mathrm{Tr} \left(\mathbf{Y} \mathbf{M}_i \right) + \beta \sum_{k=1}^K x_k$$
s.t.
$$\mathrm{Tr} \left(\mathbf{X}_k \left(\gamma_i \sum_{j \neq i} \mathbf{M}_j - \mathbf{M}_i \right) \right)$$

$$+ \sigma^2 \gamma_i \| \mathbf{w}_k \|_2^2 \le x_k, \qquad (13b)$$

$$\mathbf{M}_i \succcurlyeq \mathbf{0}, \qquad (13c)$$

$$x_k \ge 0, \forall k \in \mathcal{G}_i, i \in \mathcal{I}, \qquad (13d)$$

where $\mathbf{Y} = \mathbf{F}^H \mathbf{F}$, $\mathbf{X}_k = \mathbf{F}^H \mathbf{H}_k^H \mathbf{w}_k \mathbf{w}_k^H \mathbf{H}_k \mathbf{F}$ and $\mathbf{M}_i = \mathbf{m}_i \mathbf{m}_i^H$.



$$\mathcal{P}_{\mathrm{SDR},3}^{\mathrm{hyb}} : \min_{\substack{\{\mathbf{W}_k\}_{k=1}^K, \\ \{x_k\}_{k=1}^K \}}} \quad \sum_{k=1}^K x_k$$
s.t.
$$\operatorname{Tr} \left(\mathbf{W}_k \left(\gamma_i \sum_{j \neq i} \mathbf{Z}_{k,j} - \mathbf{Z}_{k,i} \right) \right)$$

$$+ \sigma^2 \gamma_i \operatorname{Tr} \left(\mathbf{W}_k \right) \le x_k,$$

$$\operatorname{Tr} \left(\mathbf{W}_k \right) = P_{\mathrm{rx}}^{\mathrm{max}},$$

$$\mathbf{W}_k \ge \mathbf{0},$$

$$(14a)$$

 $x_k > 0, \forall k \in \mathcal{G}_i, i \in \mathcal{I}$

where $\mathbf{W}_k = \mathbf{w}_k \mathbf{w}_k^H$ and $\mathbf{Z}_{k,i} = \mathbf{H}_k \mathbf{F} \mathbf{m}_i \mathbf{m}_i^H \mathbf{F}_{\square}^H \mathbf{H}_{k^{\parallel}}^H$.



(14e)

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Goal: Evaluate the performance of the hybrid and fully-digital precoders when $N_{\rm tx}^{\rm RF}$ and γ are varied

Table: Simulation parameters

Description	Symbol	Value	Units
Number of users	K	60	-
Number of groups	G	4	-
Receive power	-	10	dBm
Noise power	σ^2	10	dBm
Number of transmit antennas	$N_{ m tx}$	12	-
Number of receive antennas	$N_{ m rx}$	2	-
Number of randomization	N_{rand}	500	-
Number of iterations	$N_{ m iter}$	3	-
Number of simulations	=	100	-
SINR requirement	$\gamma_i = \gamma$	$\{4, 6, 8\}$	-
Number of RF chains	$N_{ m tx}^{ m RF}$	$\{5,6,7,8,9,10,11\}$	-





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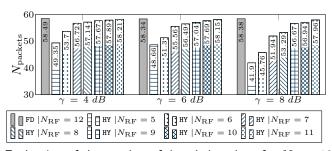


Figure: Evaluation of the number of decoded packets for $N_{\rm tx}=12$ when γ and $N_{\rm tx}^{\rm RF}$ are varied.



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Goal: Evaluate the performance of the hybrid and fully-digital precoders when $N_{\rm rx}$ is varied

Table: Simulation parameters

Description	Symbol	Value	Units
Number of users	K	60	-
Number of groups	G	4	-
Receive power	=	10	dBm
Noise power	σ^2	10	dBm
Number of transmit antennas	$N_{ m tx}$	12	-
Number of receive antennas	N_{rx}	$\{2, 3, 4, 5\}$	-
Number of iterations	$N_{ m iter}$	4	-
Number of simulations	-	100	-
SINR requirement	$\gamma_i = \gamma$	{5}	-
Number of RF chains	$N_{ m tx}^{ m RF}$	8	-





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Goal: Evaluate the performance of the hybrid and fully-digital precoders when $N_{\rm rx}$ is varied

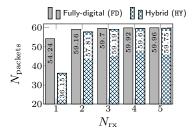


Figure: Evaluation of the number of decoded packets when $N_{\rm rx}$ is varied.



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Goal: Evaluate the performance of the hybrid and fully-digital precoders when $N_{\rm rand}$ and $N_{\rm iter}$ are varied

Table: Simulation parameters

Description	Symbol	Value	Units
Number of users	K	60	-
Number of groups	G	4	-
Receive power	-	10	dBm
Noise power	σ^2	10	dBm
Number of transmit antennas	$N_{ m tx}$	12	-
Number of receive antennas	N_{rx}	2	-
Number of randomization	$N_{ m rand}$	{1, 10, 25, 50, 75, 100, 500, 1000}	-
Number of iterations	$N_{ m iter}$	$\{1, 2, 3, 4, \}$	-
Number of iterations	$N_{ m iter}$	4	-
Number of simulations	-	100	-
SINR requirement	$\gamma_i = \gamma$	5	-
Number of RF chains	$N_{ m tx}^{ m RF}$	8	-





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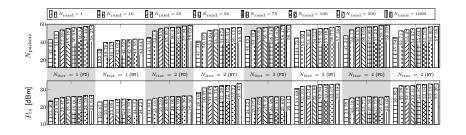


Figure: Evaluation of the number of decoded packets and transmit power for $N_{\rm tx}=12$ when $N_{\rm iter}$ and $N_{\rm rand}$ are varied.



- Our proposed solution is based on the alternating optimization, semidefinite relaxation and Cholesky decomposition.
- Our formulation allows the employment of an arbitrary number of phase shifts.
- We corroborated through simulations that the hybrid precoder can attain similar performance as its fully-digital counterpart.
- We show that having receivers with two antennas suffices to improve the number of decoded packets (up to 60% gain).





Questions

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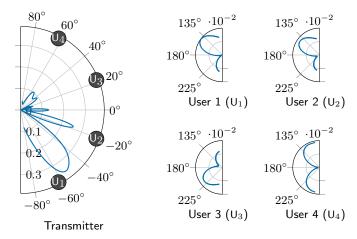


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Appendix





Background

Computational complexity: Neglecting the complexity owing to randomization and obviating the insignificant complexity increase due to the inclusion of slack parameters, the computational complexity of the proposed scheme when $N_{\rm iter}=1$ is

$$\mathcal{O}\left(\left(N_{\mathrm{tx}}^{\mathrm{RF}}N_{\mathrm{tx}}\right)^{6} + K\left(N_{\mathrm{tx}}^{\mathrm{RF}}N_{\mathrm{tx}}\right)^{2}\right) + \\
\mathcal{O}\left(G^{3}\left(N_{\mathrm{tx}}^{\mathrm{RF}}\right)^{6} + KG\left(N_{\mathrm{tx}}^{\mathrm{RF}}\right)^{2}\right) + \mathcal{O}\left(K\left(N_{\mathrm{rx}}\right)^{6} + K\left(N_{\mathrm{rx}}\right)^{4}\right).$$





Appendix

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```
Algorithm 1: Proposed Iterative Approach
Define
   Let g^{(t)} = \sum_{i=1}^{G} \|\mathbf{F}^{(t)}\mathbf{m}_{i}^{(t)}\|_{2}^{2} be the total transmit power.
   Let K^{(t)} be the number of users that satisfy (5b) at iteration t.
   Set \mathbf{w}_{k}^{(0)} \leftarrow [1 \ \mathbf{0}]^{T}, \forall k \in \mathcal{K}, \mathbf{m}_{k}^{(0)} \leftarrow [1 \ \mathbf{0}]^{T}, \forall i \in \mathcal{I}.
   Set \tilde{K} \leftarrow 0, \tilde{q} \leftarrow 10^5, t \leftarrow 1.
   Set C_1 \leftarrow 0, C_2 \leftarrow 0 and \{C_{3,k}\}_{k=1}^{K} \leftarrow 0.
          Solve P_{SDR, 1}^{hyb} to obtain D^{(t)}.
                Generate \mathbf{u} with uniform distribution in the sphere \|\mathbf{u}\|_2^2 = 1.
                 Solve \widetilde{P}_{LS}^{hyb} and compute \mathbf{F}^{(t)}.
                 If K^{(t)} > \widetilde{K} or (K^{(t)} = \widetilde{K} \text{ and } q^{(t)} < \widetilde{q})
                       Assign \mathbf{F} \leftarrow \mathbf{F}^{(t)}, \tilde{g} \leftarrow g^{(t)}, \tilde{K} \leftarrow K^{(t)}.
                 Increase the counter C_1, C_1 \leftarrow C_1 + 1.
            while C_1 \le N_{\text{rand}}
          Solve \mathcal{P}_{\mathrm{SDR},2}^{\mathrm{hyb}} and obtain \left\{\mathbf{M}_{i}^{(t)}\right\}_{i=1}^{G}
                Generate \tilde{\mathbf{m}}_{i}^{(t)} \sim \mathcal{CN}\left(\mathbf{0}, \mathbf{M}_{i}^{(t)}\right), \forall i \in \mathcal{I}.
                 if K^{(t)} > \overline{K} or (K^{(t)} = \overline{K} \text{ and } g^{(t)} \le \overline{g})
                        Assign \{\mathbf{m}_i\}_{i=1}^G \leftarrow \{\mathbf{m}_i^{(t)}\}_{i=1}^G, \tilde{g} \leftarrow g^{(t)}, \tilde{K} \leftarrow K^{(t)}.
                 Increase the counter C_2, C_2 \leftarrow C_2 + 1.
            while C_0 \le N_{cond}
   Optimize Wa
          Solve \mathcal{P}_{SDR,3}^{hyb} and obtain \left\{\mathbf{W}_{k}^{(t)}\right\}_{k=1}^{K}
            repeat for each k
                Generate \mathbf{w}_{k}^{(t)} \leftarrow \mathbf{W}_{k}^{(t)} \mathbf{v}_{k}, \forall k \in \mathcal{K} \text{ with } \mathbf{v}_{k} \text{ uniformly}
                 distributed in the sphere ||\mathbf{v}_k||_2^2 = 1.
                if K^{(t)} > \overline{K} or (K^{(t)} = \overline{K} \text{ and } g^{(t)} \leq \overline{g})
                        Assign \mathbf{w}_t \leftarrow \mathbf{w}_t^{(t)}, \tilde{a} \leftarrow a^{(t)}, \tilde{K} \leftarrow K^{(t)}
                          Increase the counter C_{3,k}, C_{3,k} \leftarrow C_{3,k} + 1
            while C_{3,k} \le \lfloor N_{rand}/K \rfloor
Until t > N_{tree}
```

Figure: Algorithm

