```
function find(v)
/* Assumes no duplicate keys, and returns pointer to the record with
 * search key value v if such a record exists, and null otherwise */
     Set C = \text{root node}
     while (C is not a leaf node) begin
          Let i = \text{smallest number such that } v \leq C.K_i
          if there is no such number i then begin
               Let P_m = last non-null pointer in the node
               Set C = C.P_m
          end
          else if (v = C.K_i) then Set C = C.P_{i+1}
          else Set C = C.P_i / * v < C.K_i * /
     end
     /* C is a leaf node */
     if for some i, K_i = v
          then return P_i
          else return null; /* No record with key value v exists*/
```

Figure 14.11 Querying a B+-tree.

At the leaf node, if there is a search-key value $K_i = v$, pointer P_i directs us to a record with search-key value K_i . The function then returns the pointer to the record, P_i . If no search key with value v is found in the leaf node, no record with key value v exists in the relation, and function *find* returns null, to indicate failure.

B⁺-trees can also be used to find all records with search key values in a specified range [*lb*, *ub*]. For example, with a B⁺-tree on attribute *salary* of *instructor*, we can find all *instructor* records with salary in a specified range such as [50000, 100000] (in other words, all salaries between 50000 and 100000). Such queries are called **range queries**.

To execute such queries, we can create a procedure findRange(lb, ub), shown in Figure 14.12. The procedure does the following: it first traverses to a leaf in a manner similar to find(lb); the leaf may or may not actually contain value lb. It then steps through records in that and subsequent leaf nodes collecting pointers to all records with key values $C.K_i$ s.t. $lb \le C.K_i \le ub$ into a set resultSet. The function stops when $C.K_i > ub$, or there are no more keys in the tree.

A real implementation would provide a version of *findRange* supporting an iterator interface similar to that provided by the JDBC ResultSet, which we saw in Section 5.1.1. Such an iterator interface would provide a method *next*(), which can be called repeatedly to fetch successive records. The *next*() method would step through the entries at the leaf level, in a manner similar to *findRange*, but each call takes only one step and records where it left off, so that successive calls to *next*() step through successive en-

```
function findRange(lb, ub)
/* Returns all records with search key value V such that lb \le V \le ub. */
     Set resultSet = {};
     Set C = \text{root node}
     while (C is not a leaf node) begin
           Let i = \text{smallest number such that } lb \leq C.K_i
           if there is no such number i then begin
                Let P_m = last non-null pointer in the node
                 Set C = C.P_m
           else if (lb = C.K_i) then Set C = C.P_{i+1}
           else Set C = C.P_{i} / * lb < C.K_{i} * /
     end
     /* C is a leaf node */
     Let i be the least value such that K_i \ge lb
     if there is no such i
           then Set i = 1 + \text{number of keys in } C; /* To force move to next leaf */
     Set done = false;
     while (not done) begin
           Let n = number of keys in C.
           if (i \le n \text{ and } C.K_i \le ub) then begin
                 Add C.P_i to resultSet
                 Set i = i + 1
           end
           else if (i \le n \text{ and } C.K_i > ub)
                 then Set done = true;
           else if (i > n \text{ and } C.P_{n+1} \text{ is not null})
                then Set C = C.P_{n+1}, and i = 1 /* Move to next leaf */
           else Set done = true; /* No more leaves to the right */
     end
     return resultSet:
```

Figure 14.12 Range query on a B+-tree.

tries. We omit details for simplicity, and leave the pseudocode for the iterator interface as an exercise for the interested reader.

We now consider the cost of querying on a B⁺-tree index. In processing a query, we traverse a path in the tree from the root to some leaf node. If there are N records in the file, the path is no longer than $\lceil \log_{\lceil n/2 \rceil}(N) \rceil$.

Typically, the node size is chosen to be the same as the size of a disk block, which is typically 4 kilobytes. With a search-key size of 12 bytes, and a disk-pointer size of