

0.5

A. Differential drive robot

0.0

0 20 40 60 80

Step size  $\Delta t$  [s]

B. Drone with pendulum

0.03

0 20 40 60

C. Trunk-like system

0.010

0 5 10 15 20 25

Stage  $k$

0

5

10

15

20

25

0

5

10

15

20

25

0

5

10

15

20

25