### Notebook

December 10, 2024

## 1 Import libraries

```
import os
import sys
import cv2
import math
import json
import joblib
import nbformat
import numpy as np
import pandas as pd
import seaborn as sns
from tqdm import tqdm
from sklearn.svm import SVC
from datetime import datetime
import matplotlib.pyplot as plt
from nbconvert.exporters import PDFExporter
from skimage.feature import hog as skimage_hog
from sklearn.preprocessing import LabelEncoder
from IPython.display import display, Javascript
from sklearn.neighbors import KNeighborsClassifier
from sklearn.model_selection import GridSearchCV
from sklearn.metrics import classification_report, confusion_matrix
from scipy.spatial.distance import cityblock, cosine, sqeuclidean
```

#### 2 Load data

```
project_dir = os.getcwd()
project_dir = os.path.dirname(project_dir)

width = 64
height = 64

data_dir = project_dir + "\\data"

train_path = os.path.join(data_dir, "train")
```

```
test_path = os.path.join(data_dir, "test")
train_images = []
test_images = []
train_labels = []
test_labels = []
for path in (train path, test path):
    if (path.split('\\')[-1] == "train"):
        for dir in os.listdir(path):
            label_path = os.path.join(path, dir)
            label = dir.split('\\')[-1]
            for image in os.listdir(label_path):
                image_path = os.path.join(label_path, image)
                image = cv2.imread(image_path)
                image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
                image = cv2.resize(image, (width, height))
                train_images.append(image)
                train_labels.append(label)
    else:
        for dir in os.listdir(path):
            label_path = os.path.join(path, dir)
            label = dir.split('\\')[-1]
            for image in os.listdir(label path):
                image_path = os.path.join(label_path, image)
                image = cv2.imread(image_path)
                image = cv2.cvtColor(image, cv2.COLOR BGR2RGB)
                image = cv2.resize(image, (width, height))
                test_images.append(image)
                test_labels.append(label)
label_encoder = LabelEncoder()
train labels encoded = label encoder.fit transform(train labels)
test_labels_encoded = label_encoder.transform(test_labels)
joblib.dump(train_images, project_dir + '\\joblib\\train_images.joblib')
joblib.dump(test_images, project_dir + '\\joblib\\test_images.joblib')
joblib.dump(train_labels_encoded, project_dir + '\\joblib\\train_labels_encoded.
 ⇔joblib')
joblib.dump(test_labels_encoded, project_dir + '\\joblib\\test_labels_encoded.
 →joblib')
```

['e:\\Documents\\CS231\\project\\Traffic-Sign-Classification-through-Images\\joblib\\label\_encoder.joblib']

joblib.dump(label\_encoder, project\_dir + '\\joblib\\label\_encoder.joblib')

# plt.imshow(test\_images[0])

<matplotlib.image.AxesImage at 0x1f6dbee0950>



plt.imshow(train\_images[1])

<matplotlib.image.AxesImage at 0x1f6dbec3f50>



## 3 Extract features

```
def blur_image(image):
    blurred_image = cv2.medianBlur(image, 5)
    return blurred_image

# plt.imshow(blur_image(test_images[0]))

# plt.imshow(blur_image(train_images[1]))

def blur_image1(image):
    blurred_image = cv2.GaussianBlur(image, (5,5), 0)
    return blurred_image

# plt.imshow(blur_image1(test_images[0]))

# plt.imshow(blur_image1(train_images[1]))

def color_histogram(image):
    # image = cv2.cvtColor(image, cv2.COLOR_RGB2LUV)
```

```
row, column, channel = image.shape[:3]
    size = row * column
    feature = []
    for k in range(channel):
        histogram = np.squeeze(cv2.calcHist([image], [k], None, [32], [0, 256]))
        histogram = histogram / size
        feature.extend(histogram)
    return feature
def hog(image):
    # image = cv2.cvtColor(image, cv2.COLOR_RGB2LUV)
    hog_features = skimage_hog(image, orientations=9, pixels_per_cell=(8, 8),__
 ⇔cells_per_block=(2, 2), visualize=False, block_norm='L2-Hys', ⊔
 →transform_sqrt=True, channel_axis=2)
    return hog_features
# _, image1 = hog(blur_image(train_images[1]))
# plt.imshow(image1, cmap=plt.cm.gray)
# _, image2 = hog(blur_image1(train_images[1]))
# plt.imshow(image2, cmap=plt.cm.gray)
def extract_features(images):
    blurred images = [blur_image(image) for image in tqdm(images, desc="Blur_i
 color_features = [color_histogram(image) for image in tqdm(blurred_images,_

→desc="Extracting Color Features")]
    hog_features = [hog(image) for image in tqdm(blurred_images,_

→desc="Extracting HOG Features")]
    combined_features = [np.concatenate((color_feature, hog_feature))
                         for color feature, hog feature in ...
  stqdm(zip(color_features, hog_features), desc="Combining Features")]
    return combined_features
train_features = extract_features(train_images)
joblib.dump(train_features, project_dir + '\\joblib\\train_features.joblib')
Blur Images: 100%
                      | 1415/1415 [00:00<00:00, 3575.41it/s]
Extracting Color Features: 100% | 1415/1415 [00:00<00:00,
25305.24it/sl
Extracting HOG Features: 100% | 1415/1415 [00:02<00:00, 599.80it/s]
Combining Features: 1415it [00:00, 41846.34it/s]
['e:\\Documents\\CS231\\project\\Traffic-Sign-Classification-through-
Images\\joblib\\train_features.joblib']
```

#### 4 Distance metrics KNN

#### 5 Load Best Model

```
knn_model = joblib.load(project_dir + '\\joblib\\best_knn_model.joblib')

svm_model = joblib.load(project_dir + '\\joblib\\best_svm_model.joblib')

y_pred_knn = knn_model.predict(test_features)

y_pred_svm = svm_model.predict(test_features)

print("Tham số của KNN Model:")

print(knn_model.get_params())

Tham số của KNN Model:
{'algorithm': 'auto', 'leaf_size': 30, 'metric': <function cityblock at
0x000001F6D4B4C360>, 'metric_params': None, 'n_jobs': None, 'n_neighbors': 4,
'p': 2, 'weights': 'distance'}

Tham số của SVM Model:
{'C': 0.1, 'break_ties': False, 'cache_size': 200, 'class_weight': None,
```

```
'coef0': 0.0, 'decision_function_shape': 'ovr', 'degree': 3, 'gamma': 0.1, 'kernel': 'poly', 'max_iter': -1, 'probability': False, 'random_state': None, 'shrinking': True, 'tol': 0.001, 'verbose': False}
```

#### 6 Gridsearch KNN

```
knn_model = KNeighborsClassifier()
knn_model.fit(train_features, train_labels_encoded)
y_pred_knn = knn_model.predict(test_features)
```

```
# param_grid = {
      'n_neighbors': [3, 4, 5, 6, 7, 10],
#
      'weights': ['uniform', 'distance'],
      'metric': [
          cityblock,
#
          cosine,
#
          sqeuclidean,
#
          chi_square_distance,
          bhattacharyya_distance,
          intersection_distance
      ]
# }
# knn_model = KNeighborsClassifier()
# grid_search_knn = GridSearchCV(
#
      knn model,
#
      param_grid,
      cv=3.
      scoring='f1_macro',
      verbose=3
# )
# grid_search_knn.fit(train_features, train_labels_encoded)
```

```
# best_knn = grid_search_knn.best_estimator_
# print(f"Best Params: {grid_search_knn.best_params_}")

# print(f"Thuật toán sử dụng: {best_knn.algorithm}")

# y_pred_knn = best_knn.predict(test_features)

# joblib.dump(best_knn, project_dir + '\\joblib\\best_knn_model.joblib')
```

#### 7 Gridsearch SVM

```
svm_model = SVC()
svm_model.fit(train_features, train_labels_encoded)
y_pred_svm = svm_model.predict(test_features)
```

```
# param_grid = {
#
      'C': [0.1, 0.2, 0.3, 0.4],
      'kernel': ['rbf', 'linear', 'poly', 'sigmoid'],
      'gamma': ['scale', 'auto', 0.1, 0.01, 0.001],
      'degree': [2, 3, 4],
# }
# sum model = SVC()
# grid_search_sum = GridSearchCV(
      estimator=svm_model,
      param_grid=param_grid,
#
      cv=3,
      scoring='f1_macro',
      verbose=3,
# )
# grid_search_sum.fit(train_features, train_labels_encoded)
```

```
# best_svm = grid_search_svm.best_estimator_
# print("Best parameters:", grid_search_svm.best_params_)

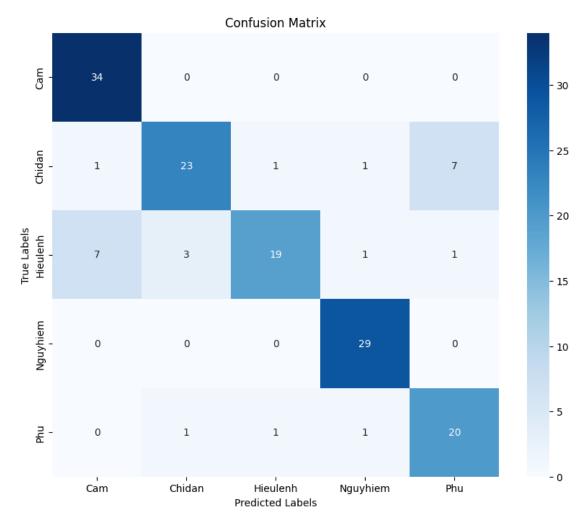
# y_pred_svm = best_svm.predict(test_features)

# joblib.dump(best_svm, project_dir + '\\joblib\\best_svm_model.joblib')
```

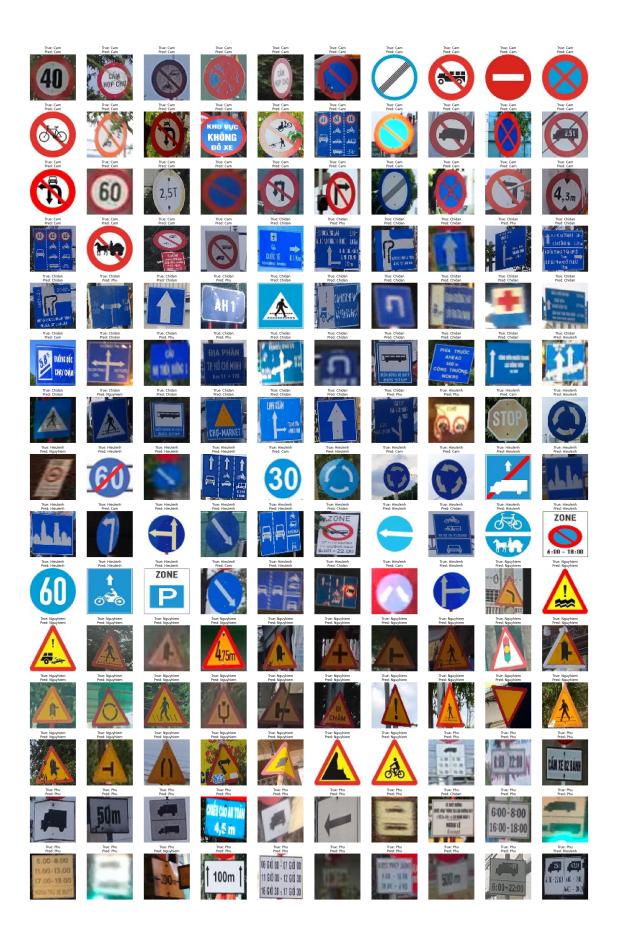
## 8 Predict on test images for KNN

	precision	recall	f1-score	support
Cam	0.81	1.00	0.89	34
Chidan	0.85	0.70	0.77	33
Hieulenh	0.90	0.61	0.73	31
Nguyhiem	0.91	1.00	0.95	29
Phu	0.71	0.87	0.78	23
accuracy			0.83	150

macro avg 0.84 0.84 0.83 150 weighted avg 0.84 0.83 0.83 150

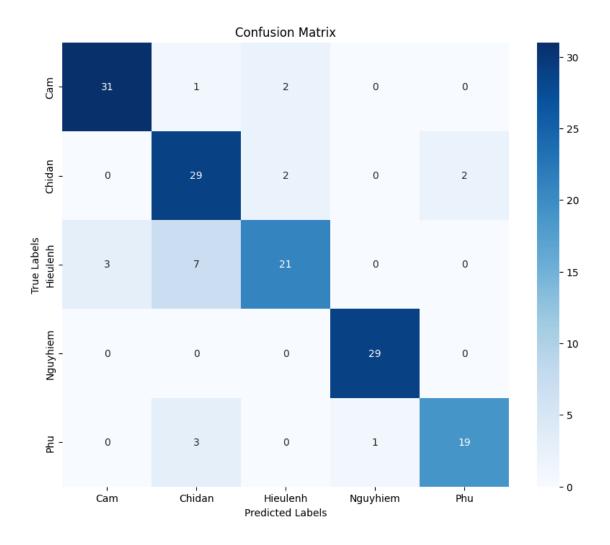


```
n_columns = 10
n_rows = math.ceil(len(test_images) / n_columns)
```



## 9 Predict on test images for SVM

	precision	recall	f1-score	support
~	0.04	2 24	0.04	0.4
Cam	0.91	0.91	0.91	34
Chidan	0.72	0.88	0.79	33
Hieulenh	0.84	0.68	0.75	31
Nguyhiem	0.97	1.00	0.98	29
Phu	0.90	0.83	0.86	23
accuracy			0.86	150
macro avg	0.87	0.86	0.86	150
weighted avg	0.87	0.86	0.86	150



```
for ax in axes.flat:
    if not ax.has_data():
        ax.axis('off')

plt.tight_layout()
plt.show()
```

## 10 Save grid search results

```
def export_notebook_to_pdf(notebook_path, project_dir):
   results_dir = os.path.join(project_dir)
   os.makedirs(results_dir, exist_ok=True)
   # Doc notebook
   with open(notebook_path, 'r', encoding='utf-8') as f:
       nb = nbformat.read(f, as_version=4)
   # Cấu hình PDF exporter
   pdf_exporter = PDFExporter()
   pdf_exporter.exclude_input_prompt = True
   pdf_exporter.exclude_output_prompt = True
    # Thêm template và style cơ bản
   pdf_exporter.template_name = 'classic'
    # Chuyển đổi sang PDF
   pdf_data, resources = pdf_exporter.from_notebook_node(nb)
   # Tao tên file với timestamp
   current_time = datetime.now().strftime('%Y-%m-%d_%H_%M_%S')
   pdf_file = os.path.join(results_dir, f"notebook_export_{current_time}.pdf")
    # Luu file PDF
   with open(pdf_file, 'wb') as f:
        f.write(pdf_data)
   print(f"Dã xuất file PDF thành công: {pdf_file}")
   return pdf_file
```

```
# project_dir = os.path.dirname(project_dir)
notebook_path = project_dir + "\\model\\main.ipynb"
proj_dir = project_dir + "\\grid_search_results"
export_notebook_to_pdf(notebook_path, proj_dir)
```

Đã xuất file PDF thành công: e:\Documents\CS231\project\Traffic-Sign-Classification-through-

 $Images \grid\_search\_results \notebook\_export\_2024-12-09\_21\_48\_35.pdf$ 

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