Notebook

November 22, 2024

1 Import libraries

```
import os
import sys
import cv2
import math
import json
import joblib
import nbformat
import numpy as np
import pandas as pd
import seaborn as sns
from tqdm import tqdm
from sklearn.svm import SVC
from datetime import datetime
import matplotlib.pyplot as plt
from nbconvert.exporters import PDFExporter
from skimage.feature import hog as skimage_hog
from sklearn.preprocessing import LabelEncoder
from IPython.display import display, Javascript
from sklearn.neighbors import KNeighborsClassifier
from sklearn.model_selection import train_test_split, GridSearchCV
from sklearn.metrics import classification_report, confusion_matrix
from scipy.spatial.distance import cityblock, cosine, correlation, sqeuclidean
```

2 Load data

```
project_dir = os.getcwd()
project_dir = os.path.dirname(project_dir)

width = 64
height = 64

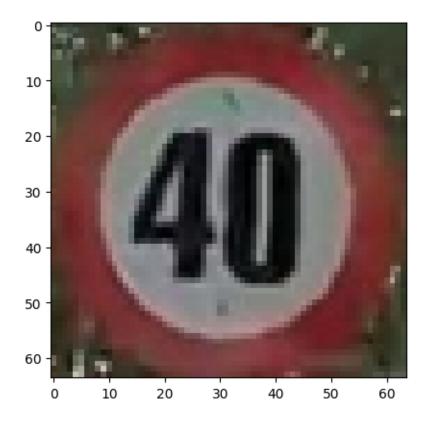
data_dir = project_dir + "\\data"

train_path = os.path.join(data_dir, "train")
```

```
test_path = os.path.join(data_dir, "test")
train_images = []
test_images = []
train_labels = []
test_labels = []
for path in (train path, test path):
    if (path.split('\\')[-1] == "train"):
        for dir in os.listdir(path):
            label_path = os.path.join(path, dir)
            label = dir.split('\\')[-1]
            for image in os.listdir(label_path):
                image_path = os.path.join(label_path, image)
                image = cv2.imread(image_path)
                image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
                image = cv2.resize(image, (width, height))
                train_images.append(image)
                train_labels.append(label)
    else:
        for dir in os.listdir(path):
            label_path = os.path.join(path, dir)
            label = dir.split('\\')[-1]
            for image in os.listdir(label path):
                image_path = os.path.join(label_path, image)
                image = cv2.imread(image_path)
                image = cv2.cvtColor(image, cv2.COLOR BGR2RGB)
                image = cv2.resize(image, (width, height))
                test_images.append(image)
                test_labels.append(label)
label_encoder = LabelEncoder()
train labels encoded = label encoder.fit transform(train labels)
test_labels_encoded = label_encoder.transform(test_labels)
joblib.dump(train_images, project_dir + '\joblib\\train_images.joblib')
joblib.dump(test_images, project_dir + '\joblib\\test_images.joblib')
joblib.dump(train_labels_encoded, project_dir + '\joblib\\train_labels_encoded.
 ⇔joblib')
joblib.dump(test_labels_encoded, project_dir + '\joblib\\test_labels_encoded.
 →joblib')
joblib.dump(label_encoder, project_dir + '\joblib\\label_encoder.joblib')
['d:\\ASUS\\Deploy-Traffic-Sign-Classification-through-
```

plt.imshow(test_images[0])

<matplotlib.image.AxesImage at 0x20aa4a5ce90>



plt.imshow(train_images[1])

<matplotlib.image.AxesImage at 0x20aa49db7d0>



3 Extract features

```
def blur_image(image):
   blurred_image = cv2.medianBlur(image, 5)
   return blurred_image
```

```
def color_histogram(image):
    # image = cv2.cvtColor(image, cv2.COLOR_RGB2LUV)
    row, column, channel = image.shape[:3]
    size = row * column
    feature = []
    for k in range(channel):
        histogram = np.squeeze(cv2.calcHist([image], [k], None, [32], [0, 256]))
        histogram = histogram / size
        feature.extend(histogram)
    return feature
```

```
def hog(image):
    # image = cv2.cvtColor(image, cv2.COLOR_RGB2LUV)
```

```
hog_features = skimage_hog(image, orientations=9, pixels_per_cell=(8, 8),__
  ocells_per_block=(2, 2), visualize=False, block_norm='L2-Hys', ∟
  →transform_sqrt=True, channel_axis=2)
    return hog features
def extract_features(images):
    blurred_images = [blur_image(image) for image in tqdm(images,_

desc="Sharpening Images")]

    color_features = [color_histogram(image) for image in tqdm(blurred_images,__

→desc="Extracting Color Features")]
    hog_features = [hog(image) for image in tqdm(blurred_images,__

→desc="Extracting HOG Features")]
    combined features = [np.concatenate((color feature, hog feature))
                         for color_feature, hog_feature in_
  otqdm(zip(color_features, hog_features), desc="Combining Features")]
    return combined_features
train_features = extract_features(train_images)
joblib.dump(train_features, project_dir + '\joblib\\train_features.joblib')
Sharpening Images: 100% | 1415/1415 [00:00<00:00, 1929.53it/s]
Extracting Color Features: 100% | 1415/1415 [00:00<00:00,
14334.57it/s]
Extracting HOG Features: 100% | 1415/1415 [00:05<00:00, 253.05it/s]
Combining Features: 1415it [00:00, 30002.78it/s]
['d:\\ASUS\\Deploy-Traffic-Sign-Classification-through-
Images\\joblib\\train_features.joblib']
test_features = extract_features(test_images)
joblib.dump(test_features, project_dir + '\joblib\\test_features.joblib')
                           | 150/150 [00:00<00:00, 2158.15it/s]
Sharpening Images: 100%
Extracting Color Features: 100% | 150/150 [00:00<00:00, 11513.75it/s]
Extracting HOG Features: 100% | 150/150 [00:00<00:00, 294.02it/s]
Combining Features: 150it [00:00, ?it/s]
['d:\\ASUS\\Deploy-Traffic-Sign-Classification-through-
Images\\joblib\\test_features.joblib']
```

4 Distance metrics KNN

```
def bhattacharyya_distance(x, y):
    return cv2.compareHist(np.array(x, dtype=np.float32), np.array(y, dtype=np.
    float32), cv2.HISTCMP_BHATTACHARYYA)

def intersection_distance(x, y):
    return 1 - cv2.compareHist(np.array(x, dtype=np.float32), np.array(y,u)
    odtype=np.float32), cv2.HISTCMP_INTERSECT)
```

5 Load Best Model

```
# knn_model = joblib.load_model(project_dir + '\\joblib\\best_knn_model.joblib')
# svm_model = joblib.load_model(project_dir + '\\joblib\\best_svm_model.joblib')
# y_pred_knn = knn_model.predict(test_features)
# y_pred_svm = svm_model.predict(test_features)
```

6 Gridsearch KNN

```
knn_model = KNeighborsClassifier()
knn_model.fit(train_features, train_labels_encoded)
y_pred_knn = knn_model.predict(test_features)
```

```
# param_grid = {
      'n_neighbors': [3, 4, 5, 6, 7, 10],
#
      'weights': ['uniform', 'distance'],
      'leaf_size': [5, 10, 20, 30, 40, 50],
#
      'metric': [
#
          cityblock,
#
          cosine,
#
          # correlation,
#
          sqeuclidean,
#
          chi_square_distance,
          bhattacharyya_distance,
          intersection distance
# }
# knn_model = KNeighborsClassifier()
# grid_search_knn = GridSearchCV(
#
      knn_model,
#
      param_grid,
#
      cv=3,
      scoring='f1_macro',
#
      verbose=3
# )
```

```
# grid_search_knn.fit(train_features, train_labels_encoded)
```

```
# best_knn = grid_search_knn.best_estimator_
# print(f"Best Params: {grid_search_knn.best_params_}")

# y_pred_knn = best_knn.predict(test_features)

# joblib.dump(best_knn, project_dir + '\joblib\\best_knn_model.joblib')
```

7 Gridsearch SVM

```
svm_model = SVC()
svm_model.fit(train_features, train_labels_encoded)
y_pred_svm = svm_model.predict(test_features)
```

```
# param_grid = {
      'C': [0.1, 0.2, 0.3, 0.4],
      'kernel': ['rbf', 'linear', 'poly', 'sigmoid'],
      'gamma': ['scale', 'auto', 0.1, 0.01, 0.001],
#
      'degree': [2, 3, 4],
# }
# svm model = SVC()
# grid_search_svm = GridSearchCV(
      estimator=svm_model,
#
     param_grid=param_grid,
#
     cv=3.
      scoring='f1_macro',
      verbose=3,
# )
# grid_search_sum.fit(train_features, train_labels_encoded)
```

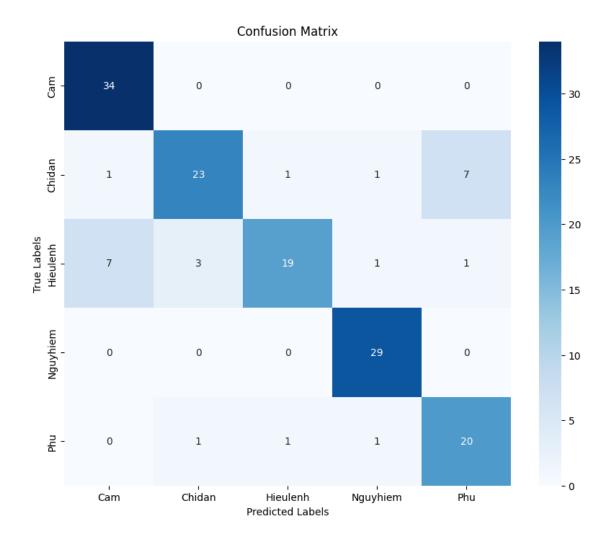
```
# best_svm = grid_search_svm.best_estimator_
# # Get the best parameters and score
# print("Best parameters:", grid_search_svm.best_params_)

# y_pred_svm = best_svm.predict(test_features)

# joblib.dump(best_svm, project_dir + '\joblib\\best_svm_model.joblib')
```

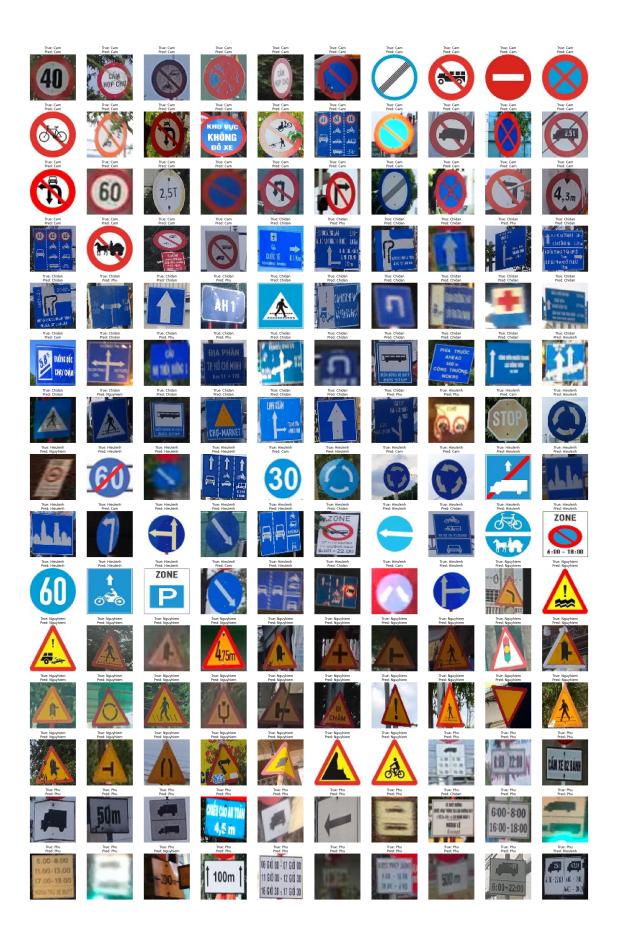
8 Predict on test images for KNN

	precision	recall	f1-score	support
Cam	0.81	1.00	0.89	34
Chidan	0.85	0.70	0.77	33
Hieulenh	0.90	0.61	0.73	31
Nguyhiem	0.91	1.00	0.95	29
Phu	0.71	0.87	0.78	23
accuracy			0.83	150
macro avg	0.84	0.84	0.83	150
weighted avg	0.84	0.83	0.83	150



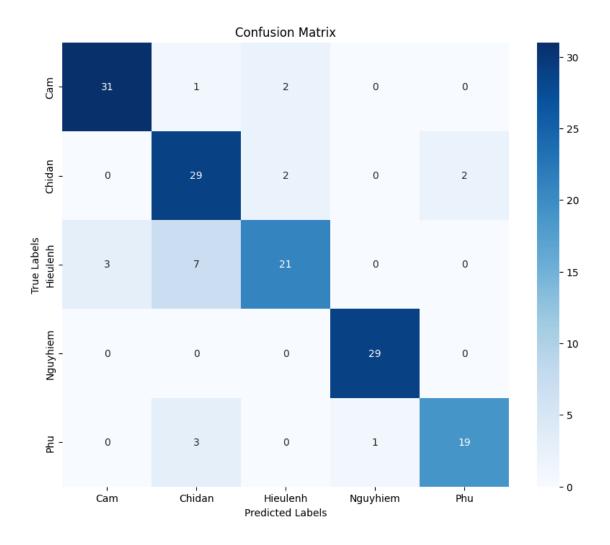
```
for ax in axes.flat:
    if not ax.has_data():
        ax.axis('off')

plt.tight_layout()
plt.show()
```



9 Predict on test images for SVM

	precision	recall	f1-score	support
~	0.04	2 24	0.04	0.4
Cam	0.91	0.91	0.91	34
Chidan	0.72	0.88	0.79	33
Hieulenh	0.84	0.68	0.75	31
Nguyhiem	0.97	1.00	0.98	29
Phu	0.90	0.83	0.86	23
accuracy			0.86	150
macro avg	0.87	0.86	0.86	150
weighted avg	0.87	0.86	0.86	150



```
for ax in axes.flat:
    if not ax.has_data():
        ax.axis('off')

plt.tight_layout()
plt.show()
```

10 Save grid search results

```
def export_notebook_to_pdf(notebook_path, project_dir):
   results_dir = os.path.join(project_dir)
   os.makedirs(results_dir, exist_ok=True)
   # Doc notebook
   with open(notebook_path, 'r', encoding='utf-8') as f:
       nb = nbformat.read(f, as_version=4)
   # Cấu hình PDF exporter
   pdf_exporter = PDFExporter()
   pdf_exporter.exclude_input_prompt = True
   pdf_exporter.exclude_output_prompt = True
   # Thêm template và style cơ bản
   pdf_exporter.template_name = 'classic'
   # Chuyển đổi sang PDF
   pdf_data, resources = pdf_exporter.from_notebook_node(nb)
   # Tao tên file với timestamp
   current_time = datetime.now().strftime('%Y-%m-%d_%H_%M_%S')
   pdf_file = os.path.join(results_dir, f"notebook_export_{current_time}.pdf")
    # Luu file PDF
   with open(pdf_file, 'wb') as f:
        f.write(pdf_data)
   print(f"Dã xuất file PDF thành công: {pdf_file}")
   return pdf_file
```

```
# project_dir = os.path.dirname(project_dir)
notebook_path = project_dir + "\\model\\main.ipynb"
proj_dir = project_dir + "\\grid_search_results"

export_notebook_to_pdf(notebook_path, proj_dir)
```