## Jeux de la classe perturbé

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#### Sommaire



Explication du problème



Présentation de l'implémentation



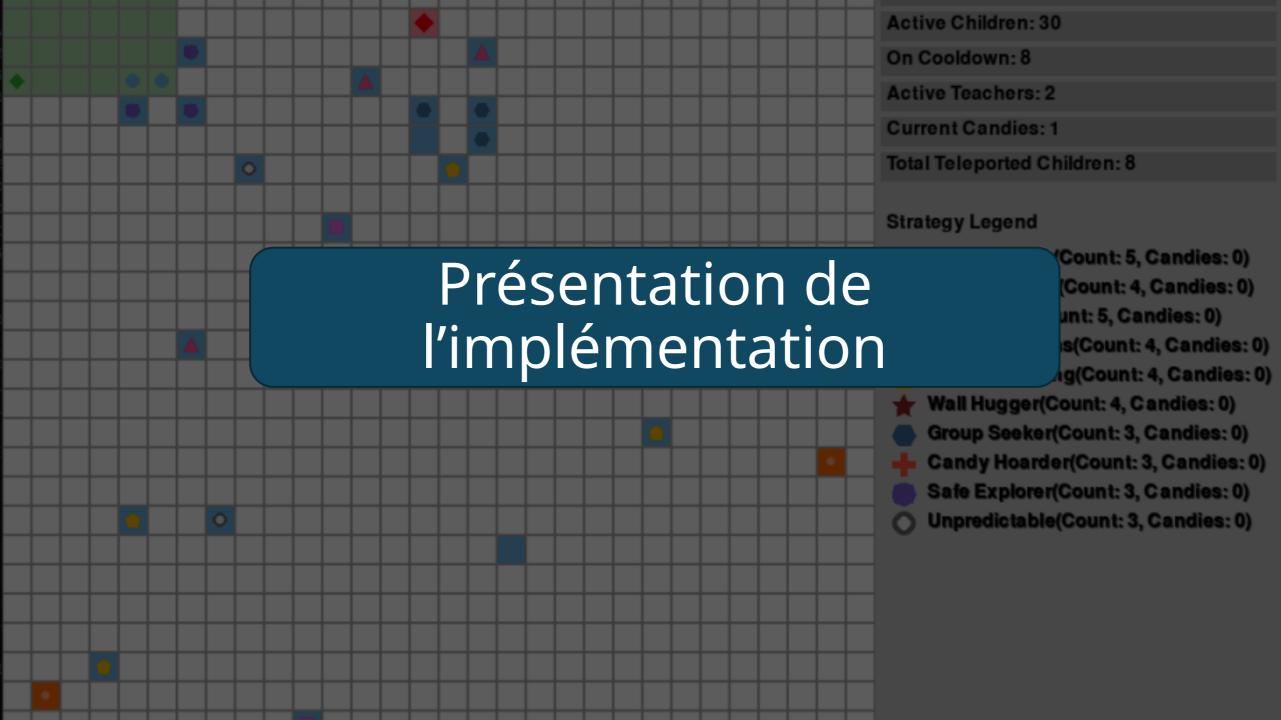
Présentation des différentes stratégies



Conclusion

#### Explication du problème

This project implements a reactive multi-agent system simulating the dynamic interactions between teachers and children in a classroom environment. The simulation models a rich scenario where children employ various strategies to move around the classroom while teachers work to maintain order by pursuing and capturing the children.



#### Explication graphique

Zone verte de base des enfants

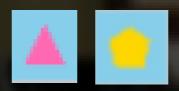
Zone en blanc correspondant à la classe

Différents types d'enfants avec un fond bleu

**Maitresse fond orange** 

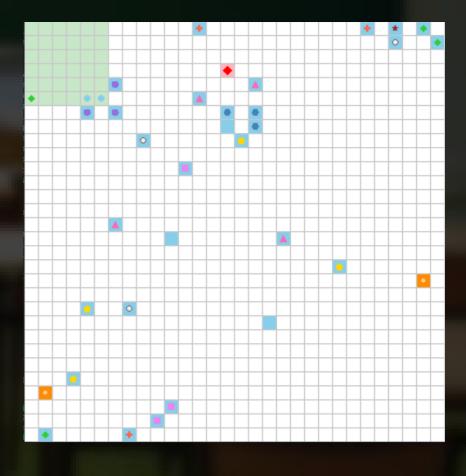
Bonbon avec un losange rouge











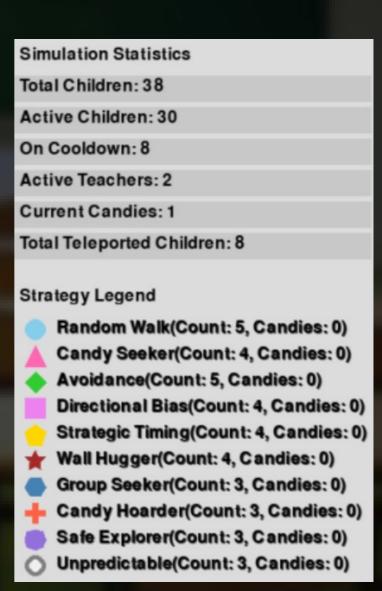
#### Spécificité

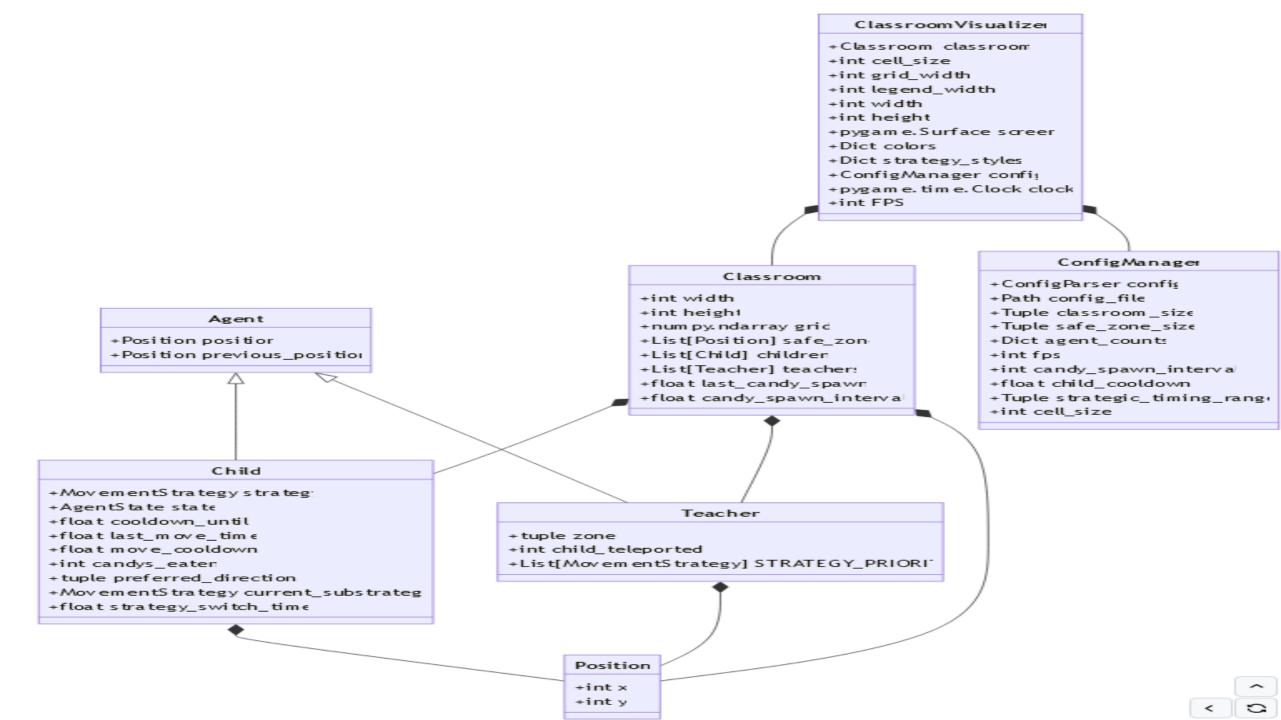
Les enfants et la maitresse se déplace en même temps.

La partie dure un temps donné.

Analyse du nombre de bonbon récupéré par chaque type d'enfant.

Statistique en temps réel.





### Présentation des stratégies

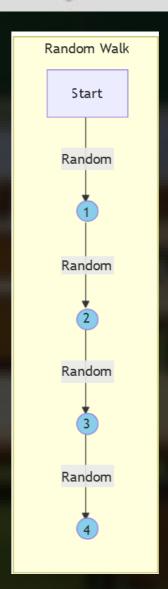
#### Strategy Legend

- Random Walk(Count: 5, Candies: 0)
- Candy Seeker(Count: 4, Candies: 0)
- Avoidance(Count: 5, Candies: 0)
- Directional Bias(Count: 4, Candies: 0)
- Strategic Timing(Count: 4, Candies: 0)
- ★ Wall Hugger(Count: 4, Candies: 0)
- Group Seeker(Count: 3, Candies: 0)
- Candy Hoarder(Count: 3, Candies: 0)
- Safe Explorer(Count: 3, Candies: 0)
- Unpredictable(Count: 3, Candies: 0)

#### Random Walk

Random Walk(Count: 5, Candies: 0)

The child chooses a random direction to move in each turn, leading to an unpredictable path through the classroom.

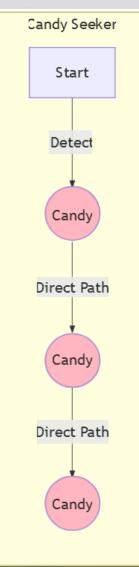


#### Candy Seeker



Candy Seeker(Count: 4, Candies: 0)

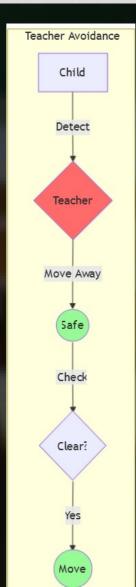
The child actively looks for the nearest candy and moves towards it, prioritizing candy collection over other considerations.



#### Avoidance



The child tries to maintain a safe distance from all teachers, moving in a way that minimizes the risk of capture.

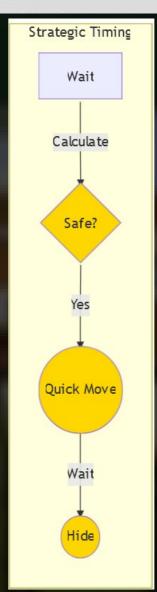


#### Strategic Timii



Strategic Timing(Count: 4, Candies: 0)

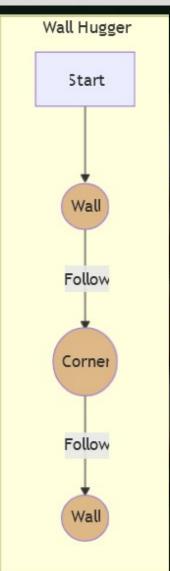
The child moves at carefully timed intervals, pausing and waiting at times, in an attempt to confuse teachers and avoid detection.



#### Wall Hugger



The child stays close to the classroom walls, moving along the perimeter to avoid being surrounded by teachers.

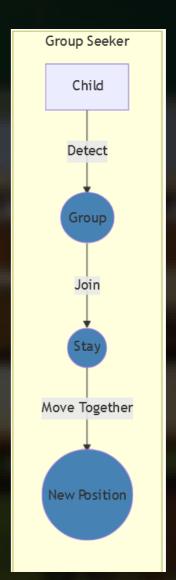


#### Group Seeker



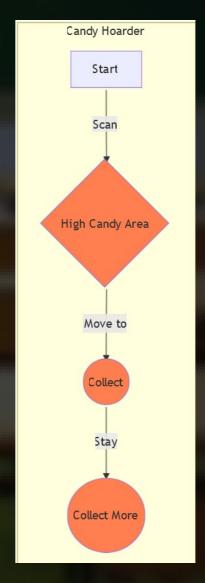
Group Seeker(Count: 3, Candies: 0)

The child tries to stay close to other children, forming protective groups to reduce the chances of being singled out by a teacher.



#### Candy Hoarder(Count: 3, Candies: 0)

The child seeks out areas with a high density of candies and attempts to collect as many as possible in a short time.

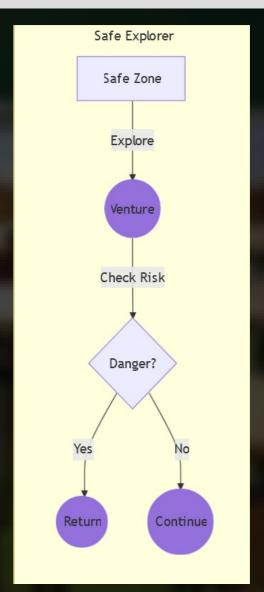


#### Safe Explorer



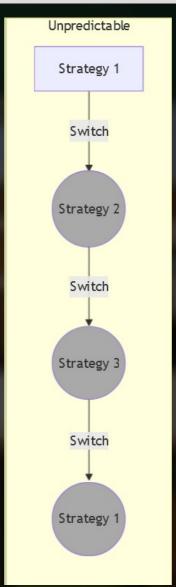
Safe Explorer(Count: 3, Candies: 0)

The child alternates between exploring the classroom and returning to the safety of the safe zone, trying to balance risk and reward.



#### Un predictable (Count: 3, Candies: 0)

The child switches between the other strategies at random intervals, making its behavior hard to predict and counter.

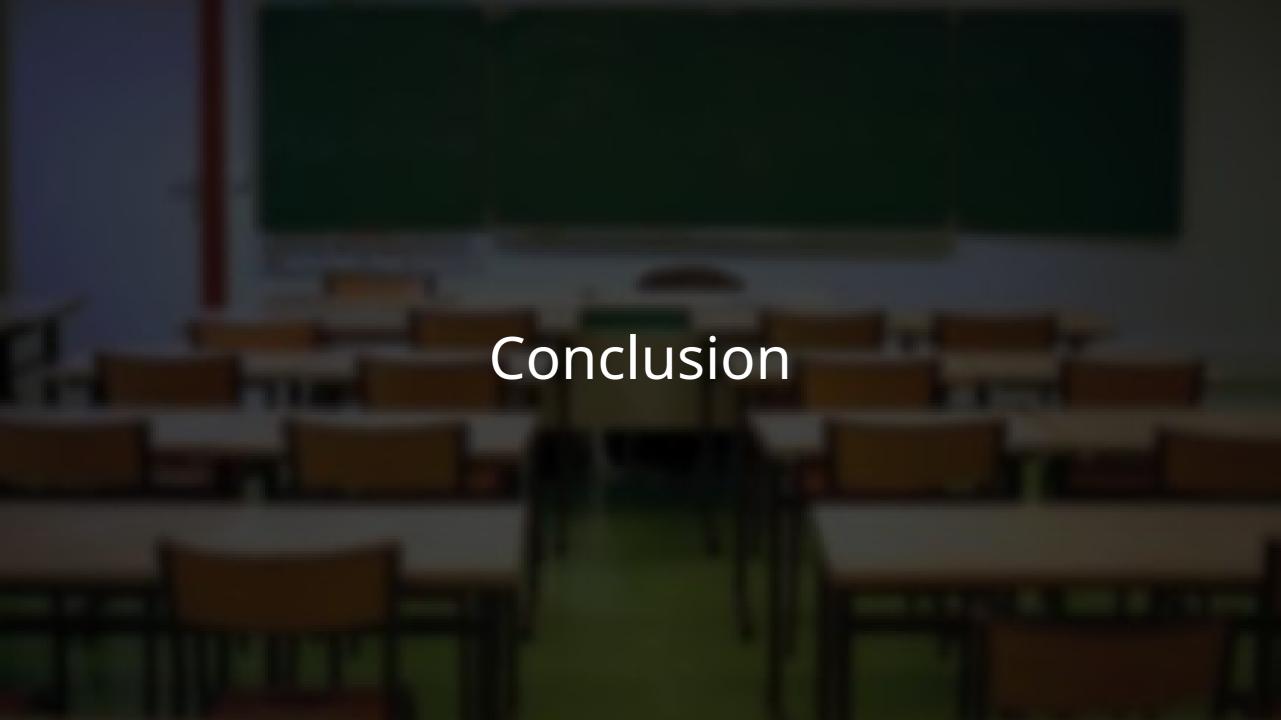


#### Teacher strategy

**Strategy Prioritization**: Teachers analyze the strategies being used by the children in the classroom and prioritize pursuing the children employing the most disruptive strategies first. This allows them to focus on the biggest threats to classroom order.

#### Teacher strategy

**Area Patrolling**: Teachers are assigned specific zones within the classroom to patrol. They will focus their efforts on their assigned area, only leaving it to pursue high-priority targets identified by the strategy analysis.



# Conclusion Merci pour votre