python + AI

Introduction to Artificial Intelligence with Python

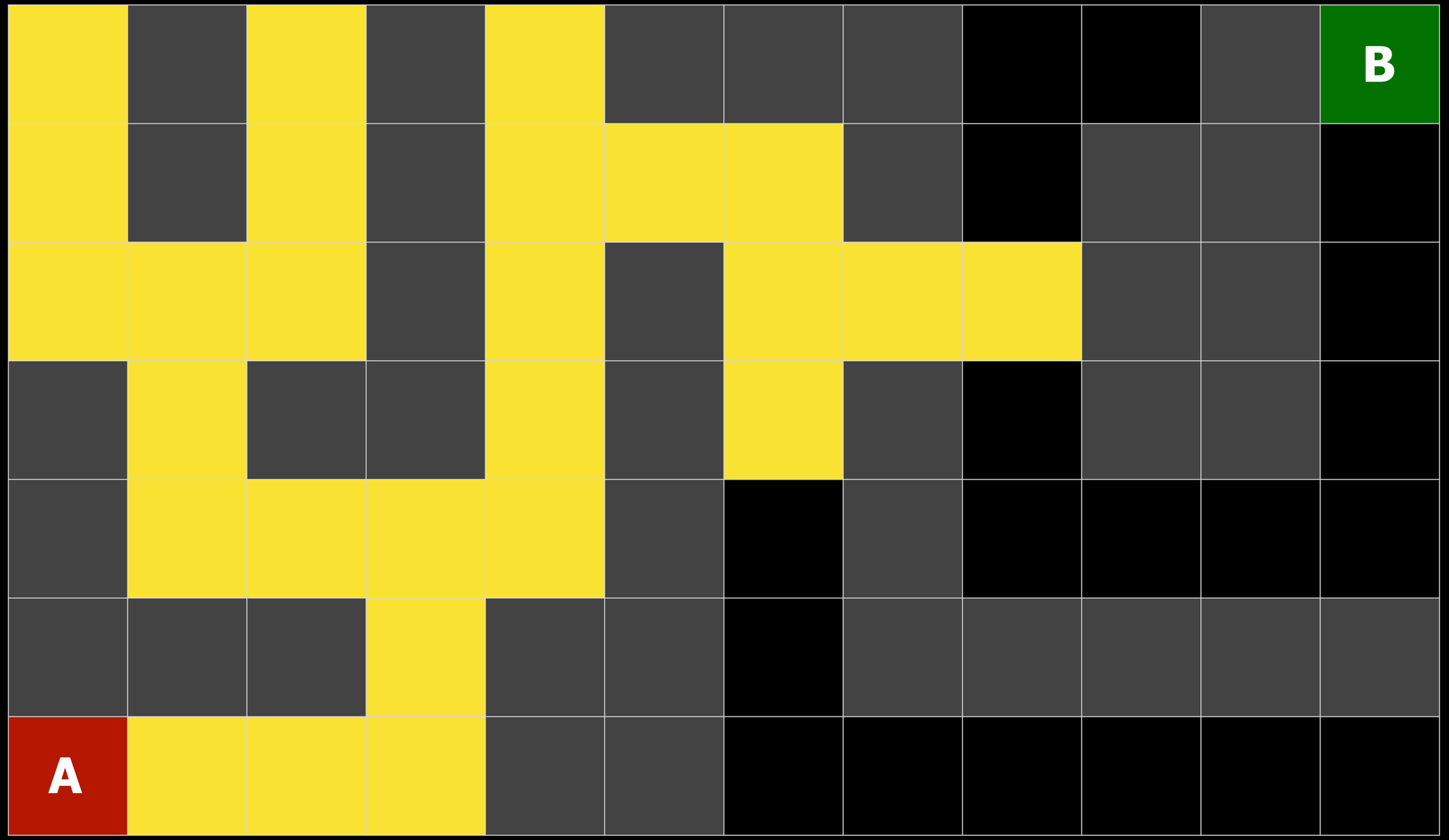
Optimization

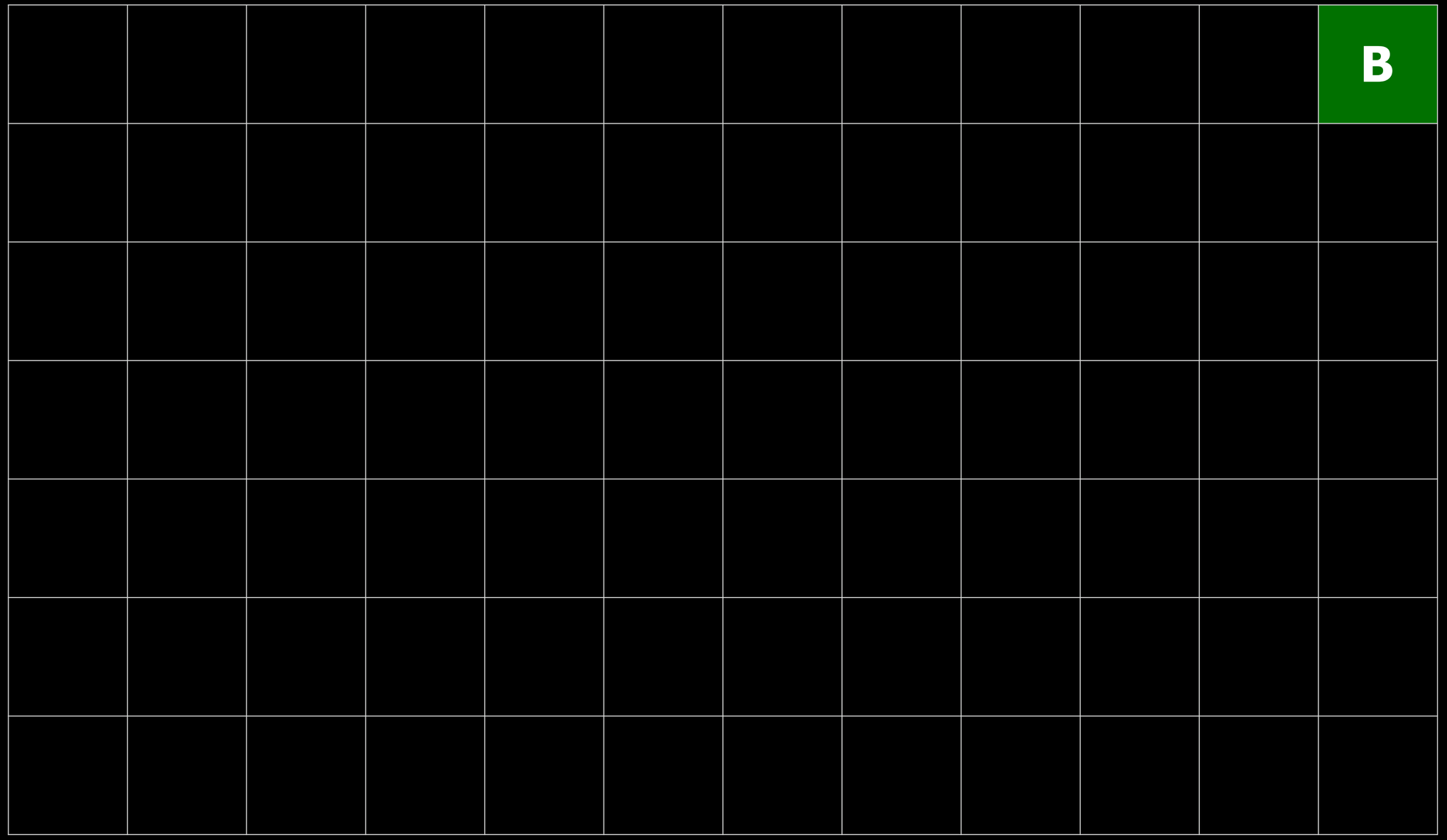
optimization

choosing the best option from a set of options

local search

search algorithms that maintain a single node and searches by moving to a neighboring node


B
A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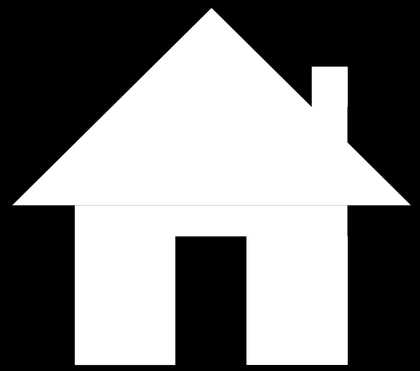

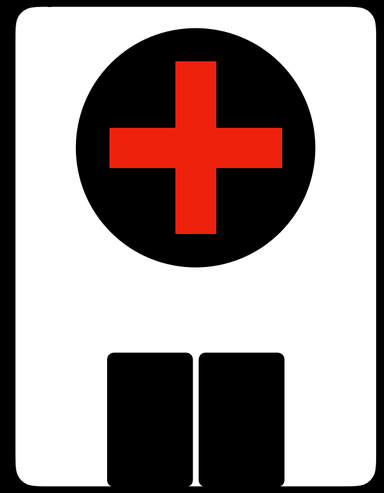

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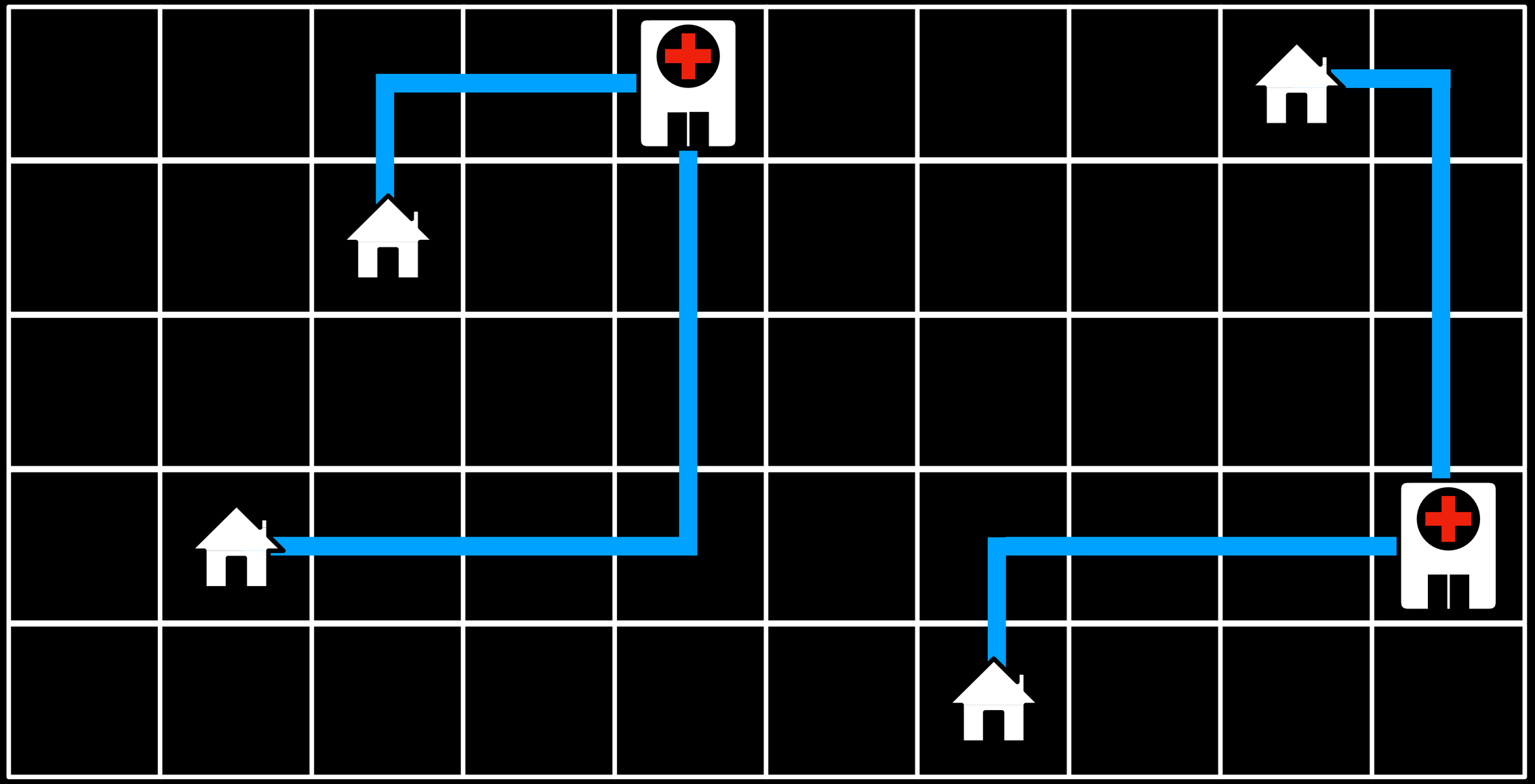
Cost: 17



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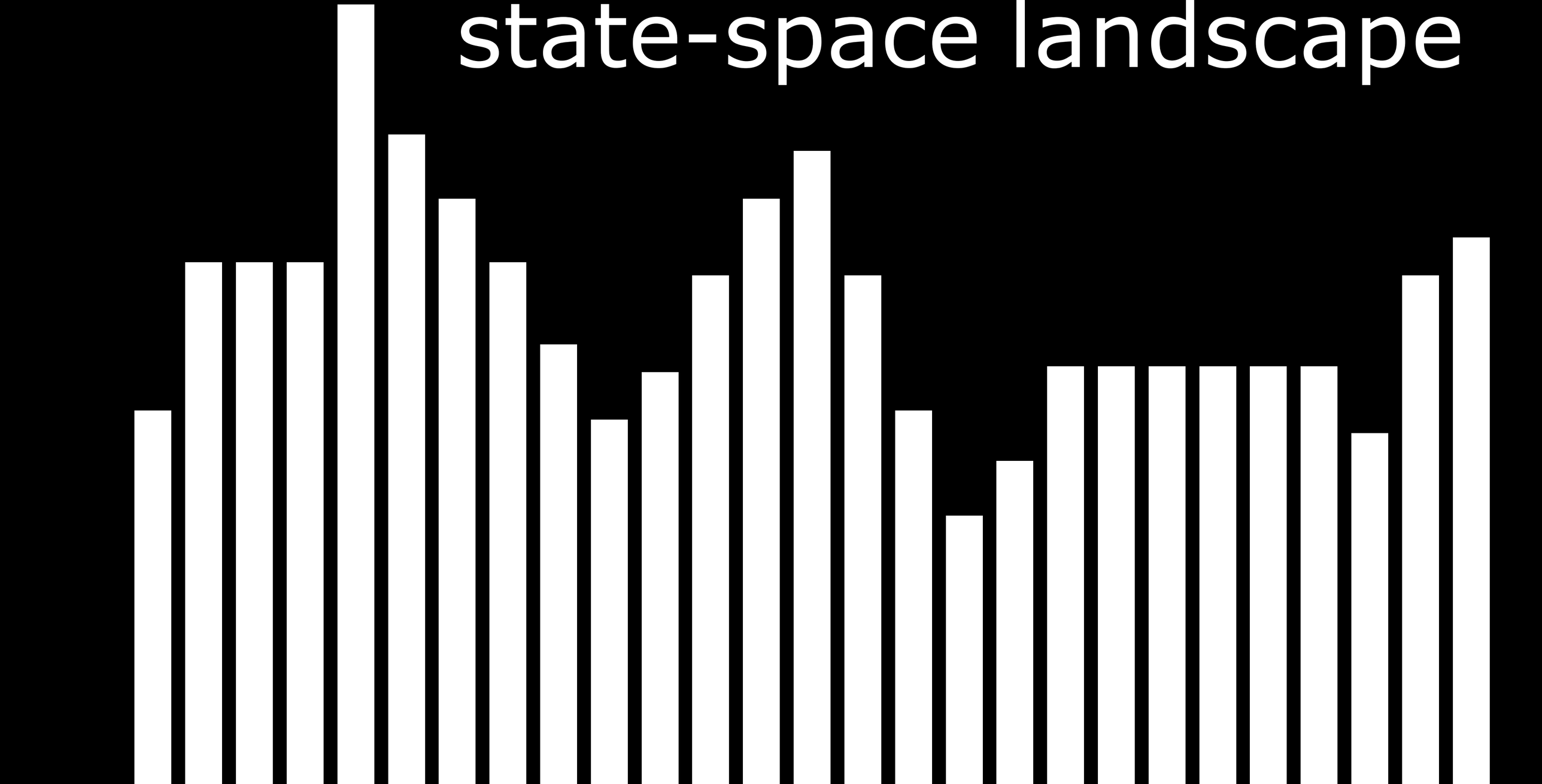
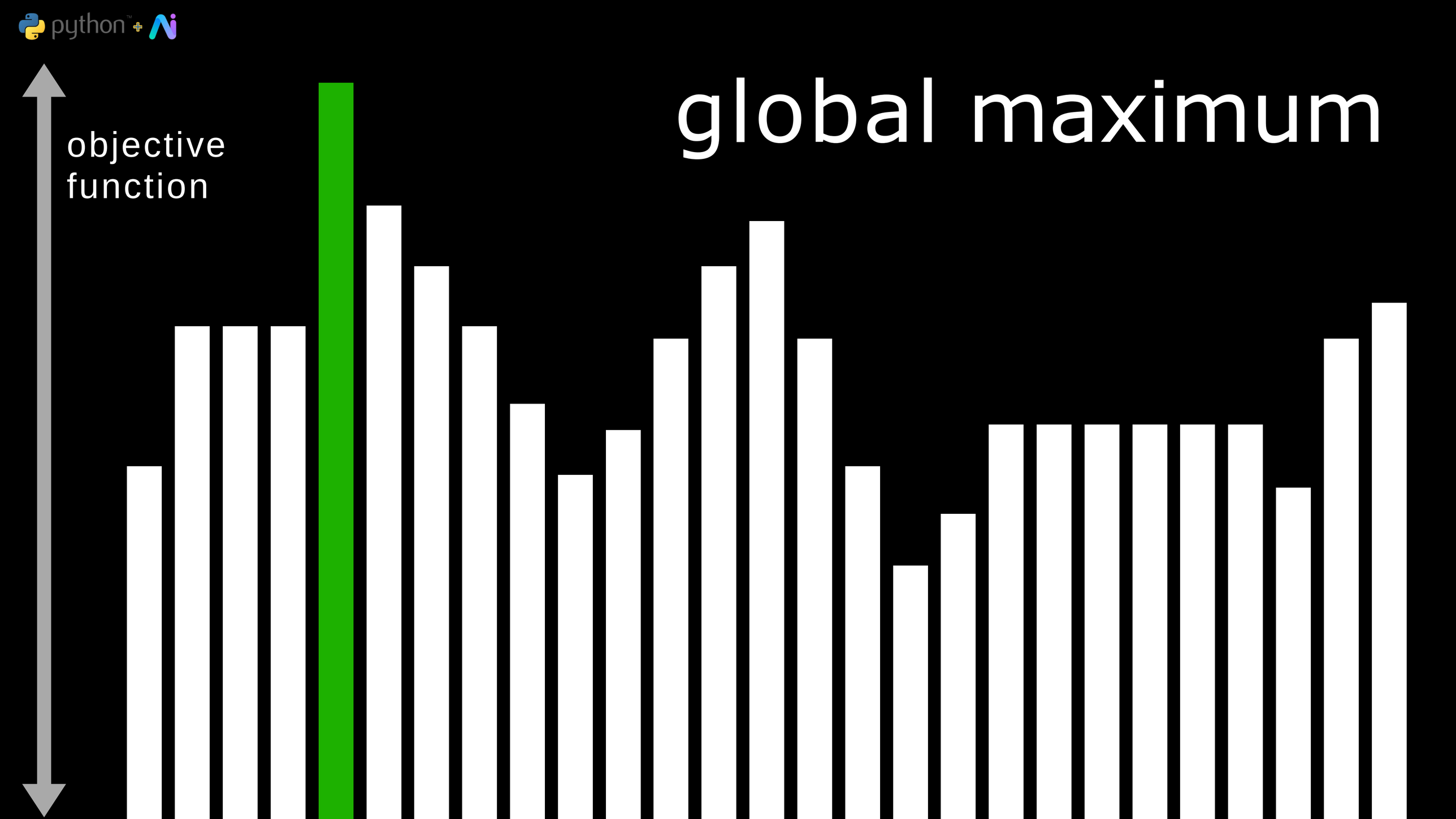
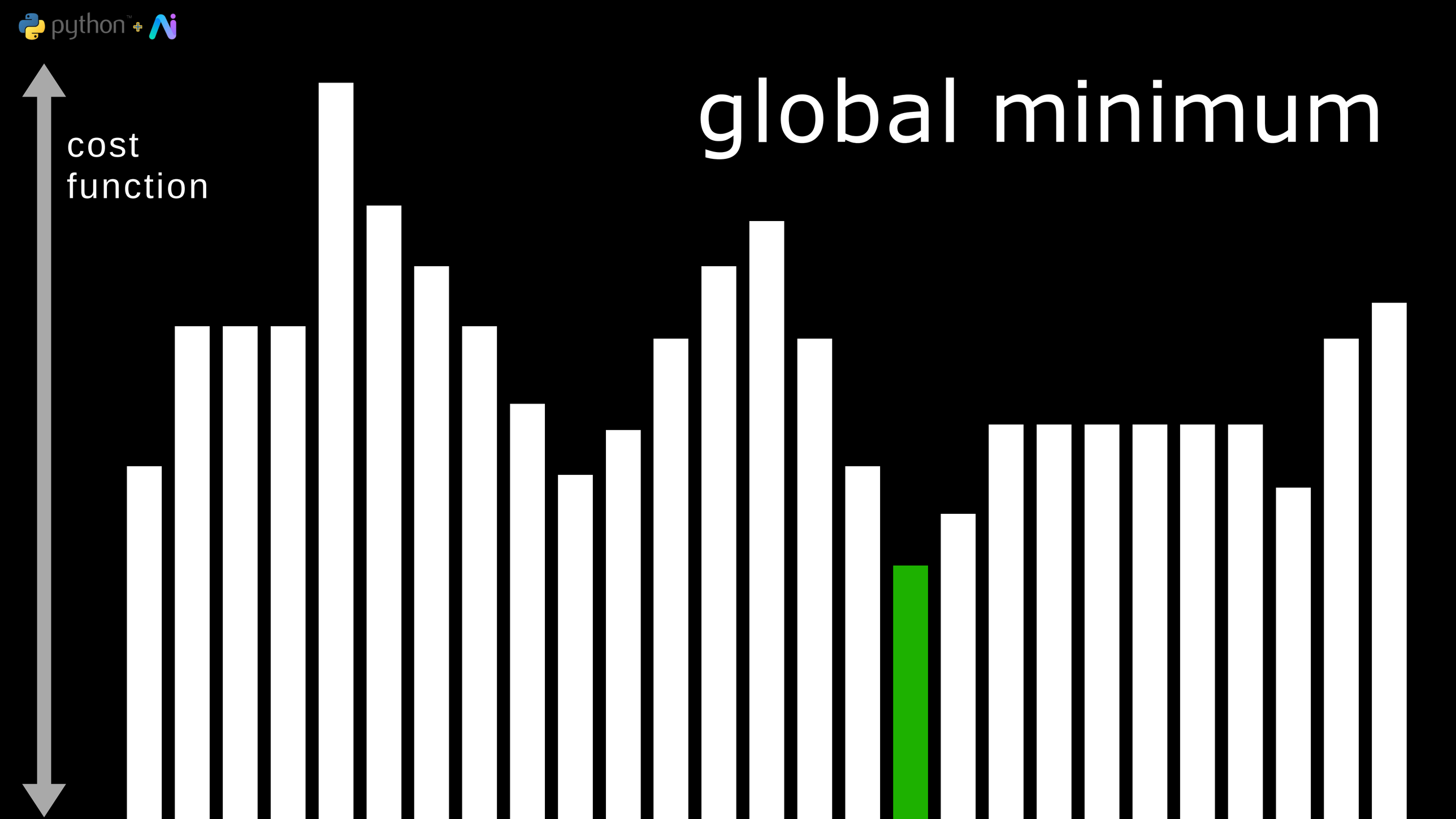
state-space landscape




python
objective function
global maximum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cost
function
global minimum

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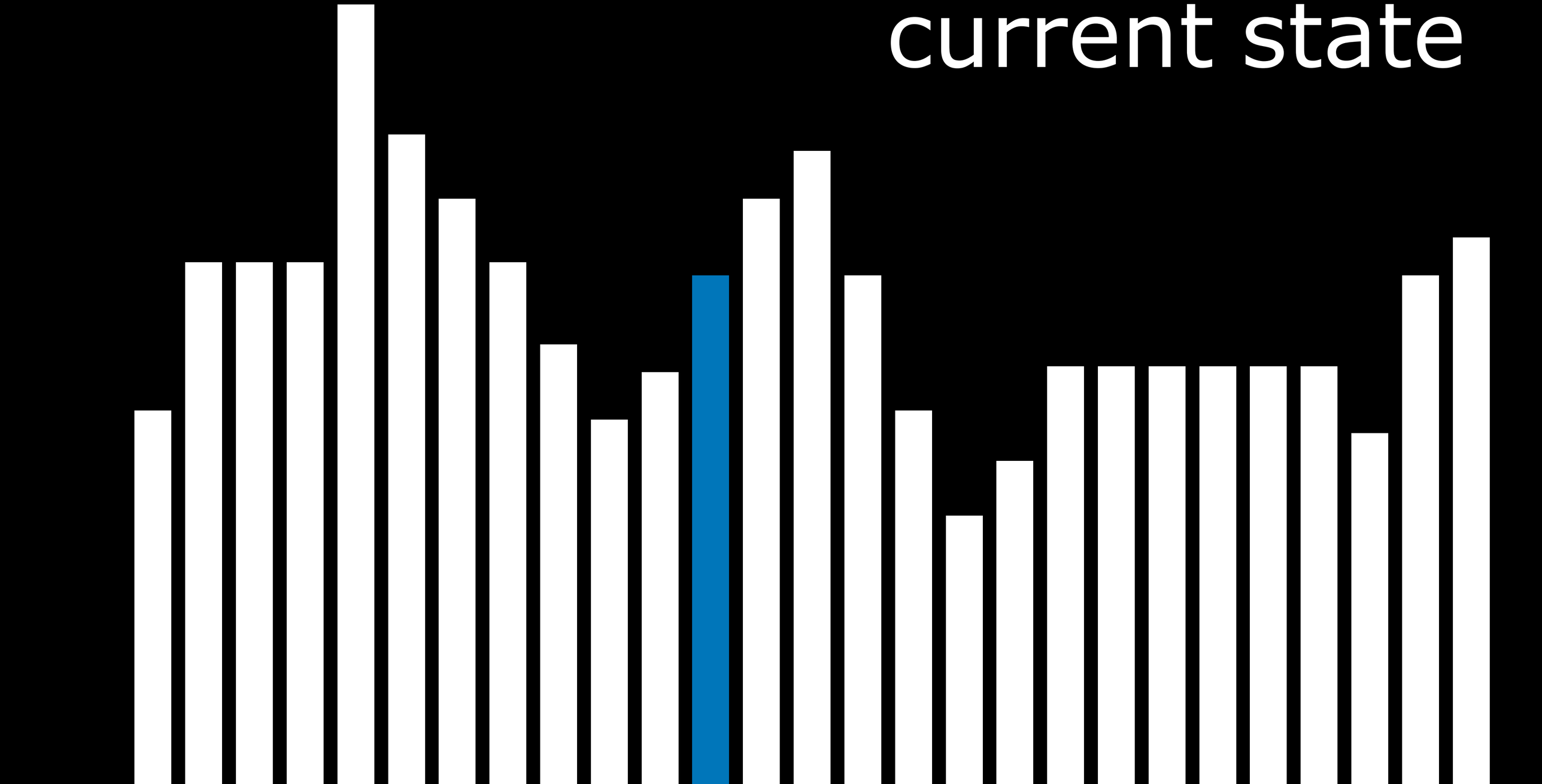
current state



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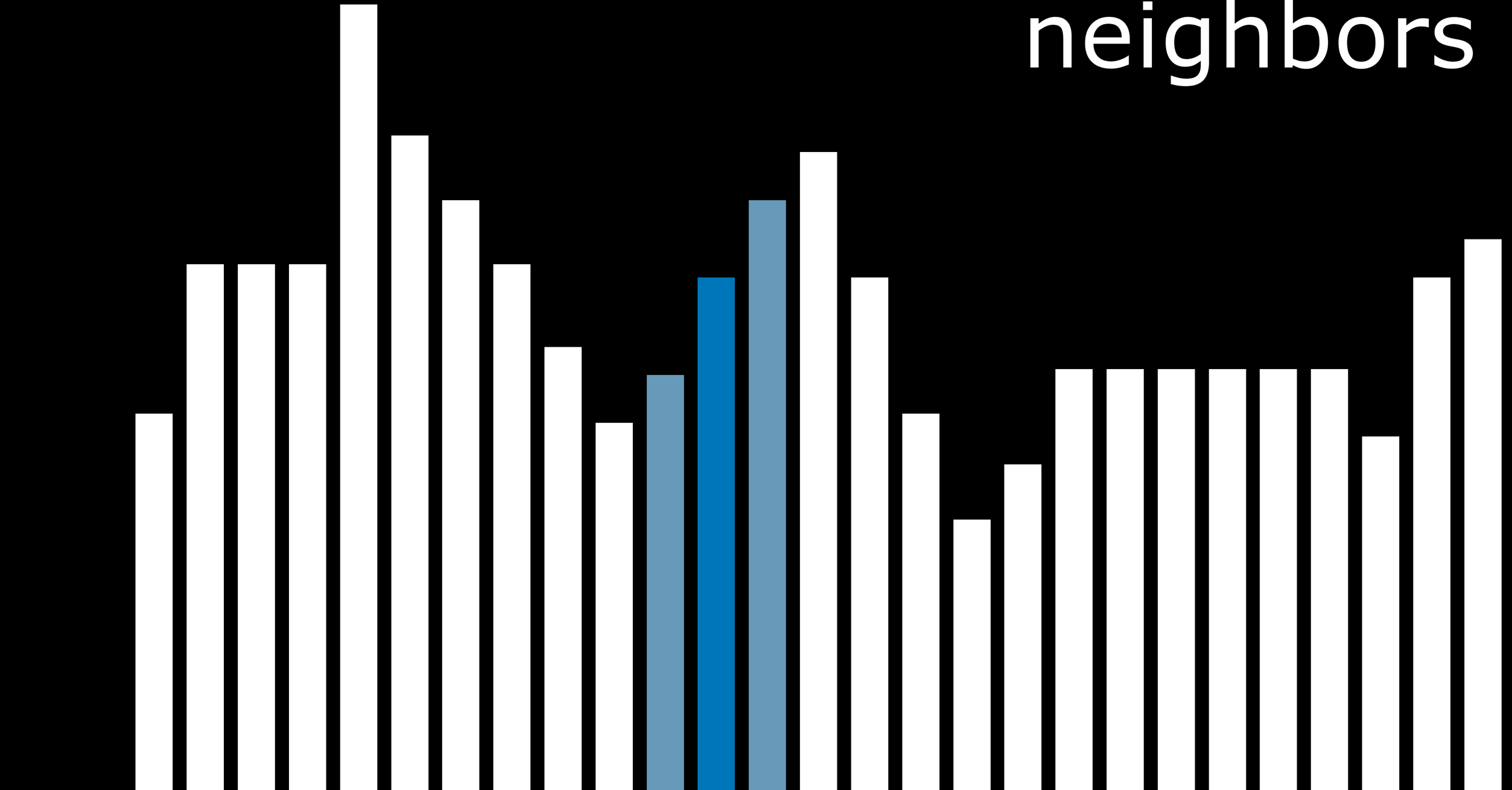
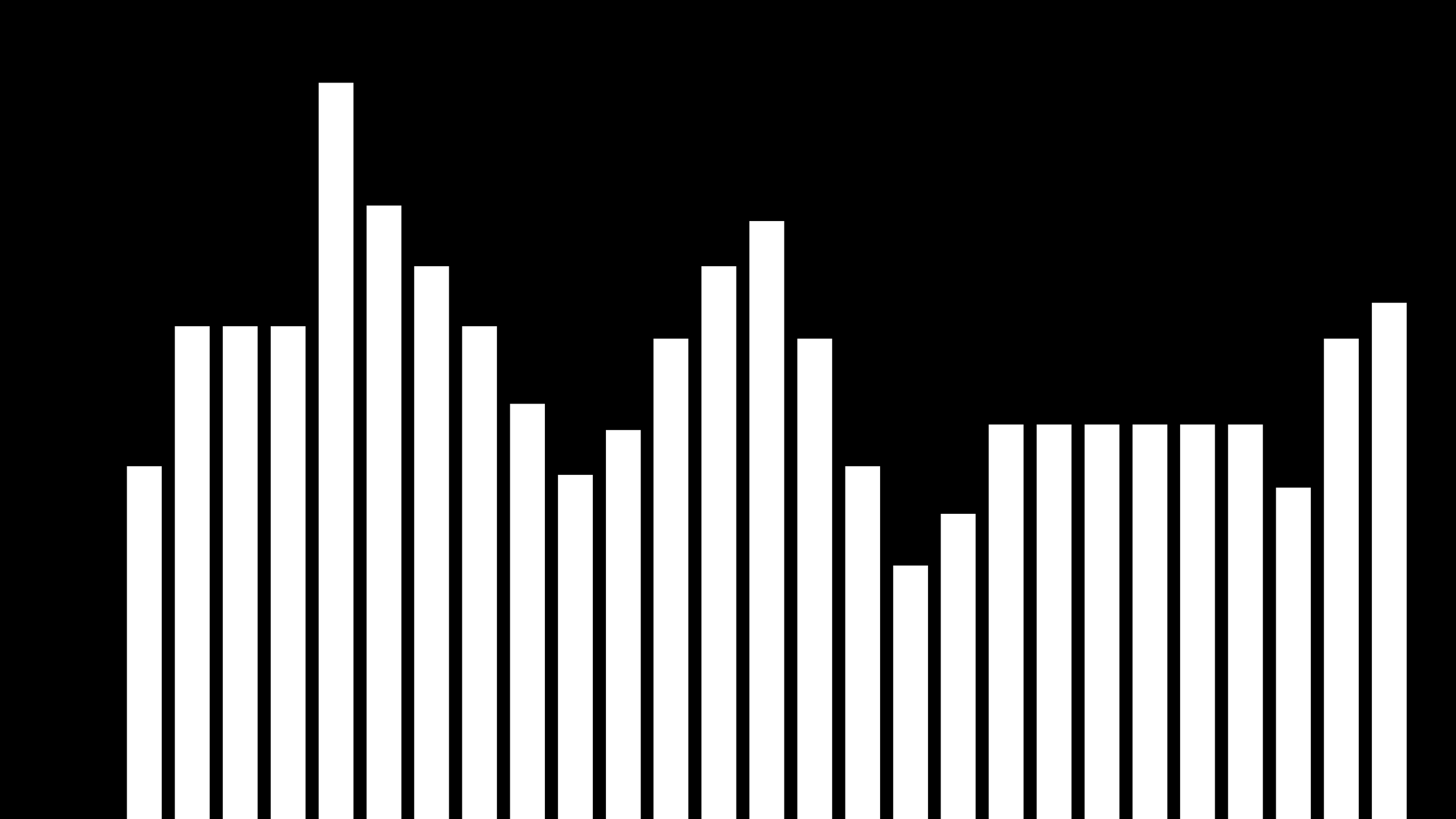
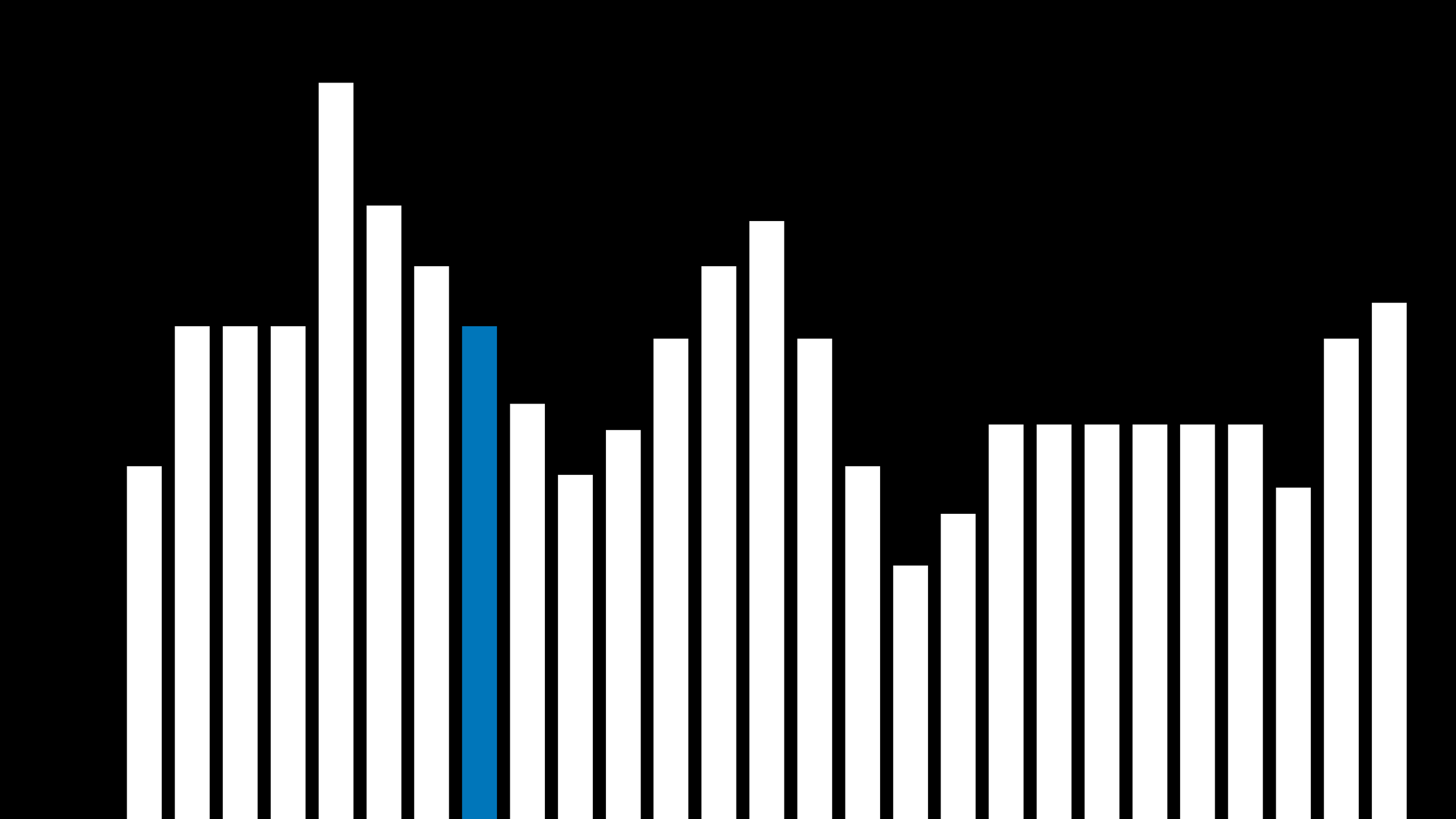
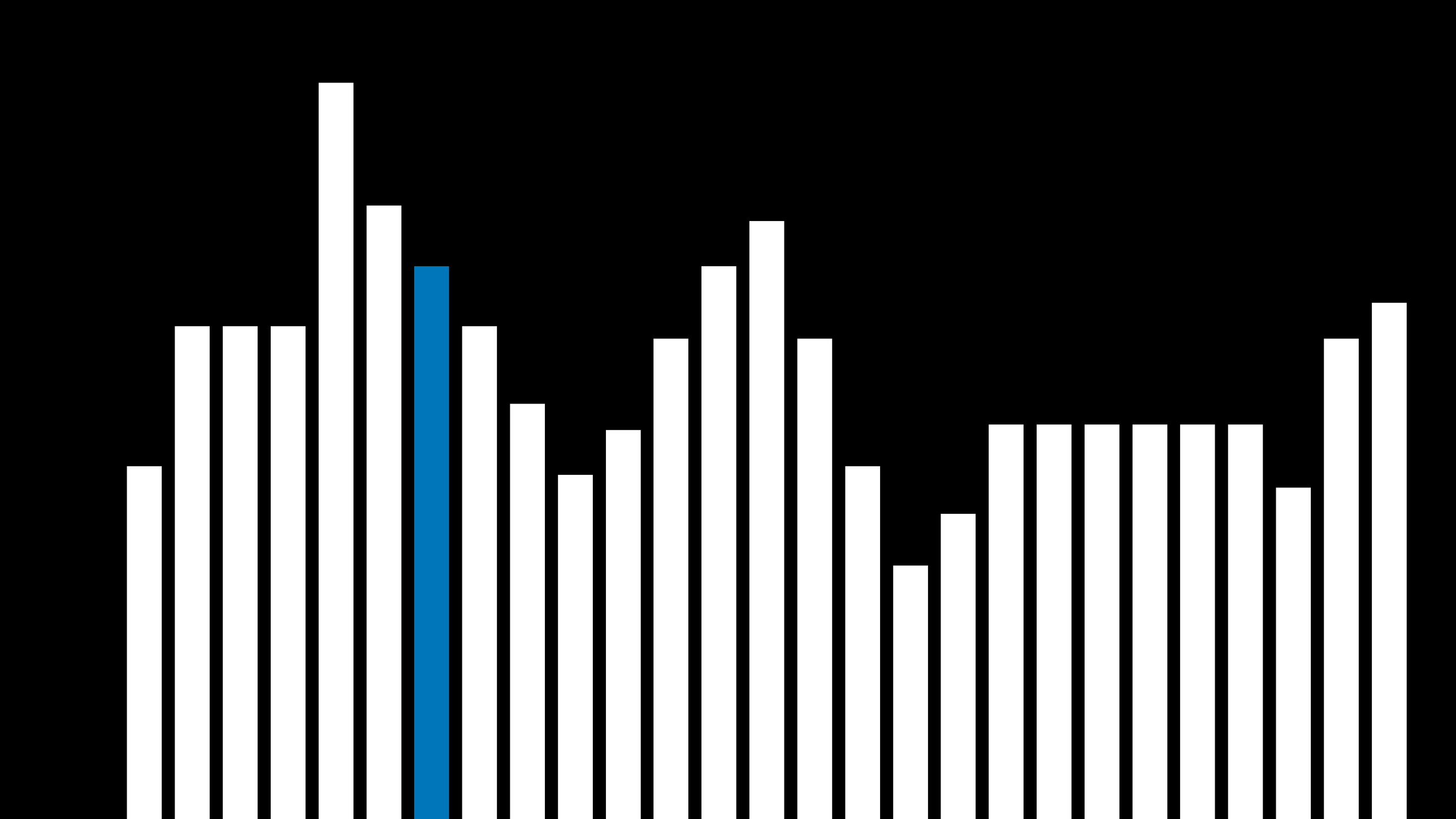
neighbors

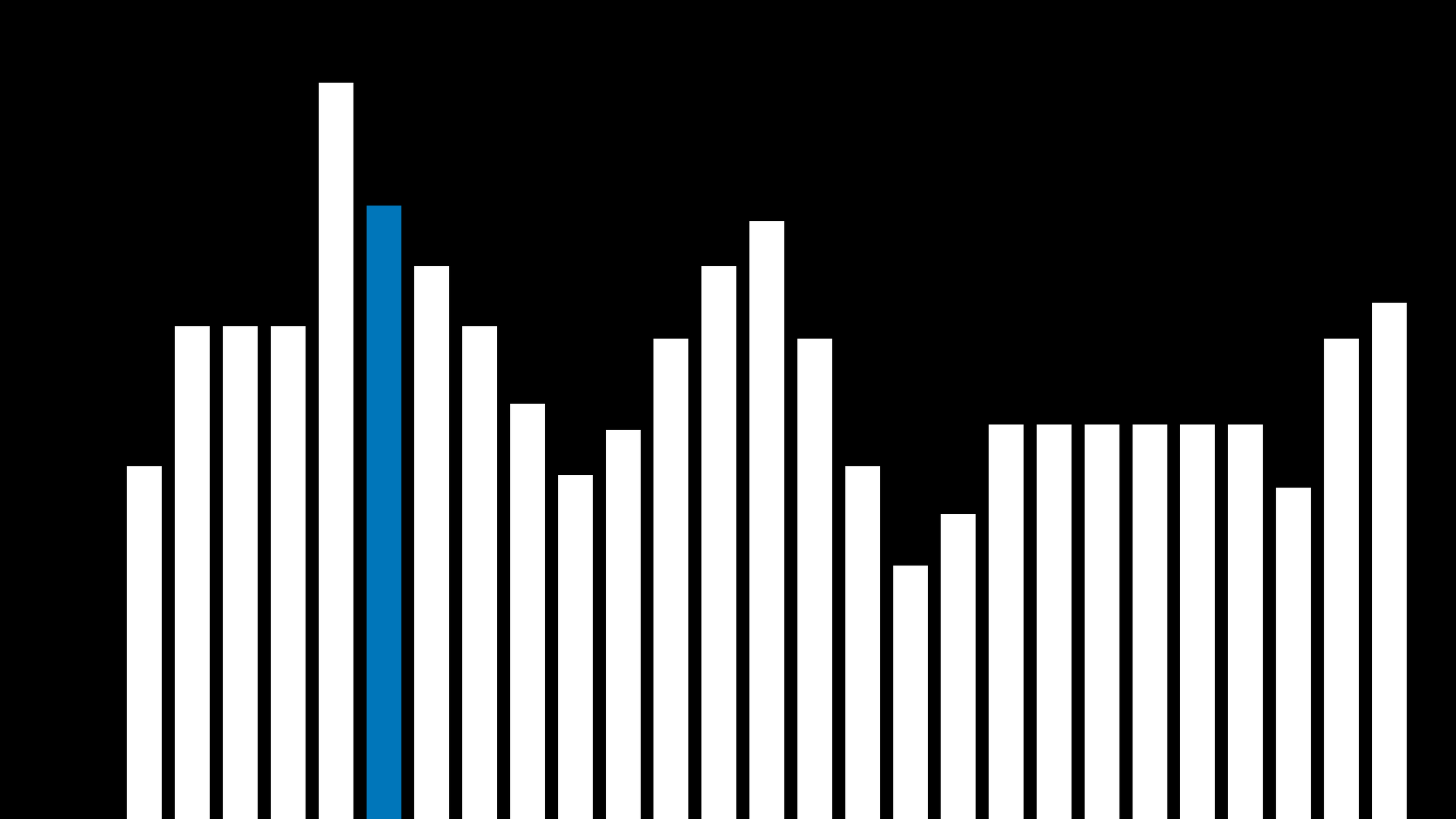


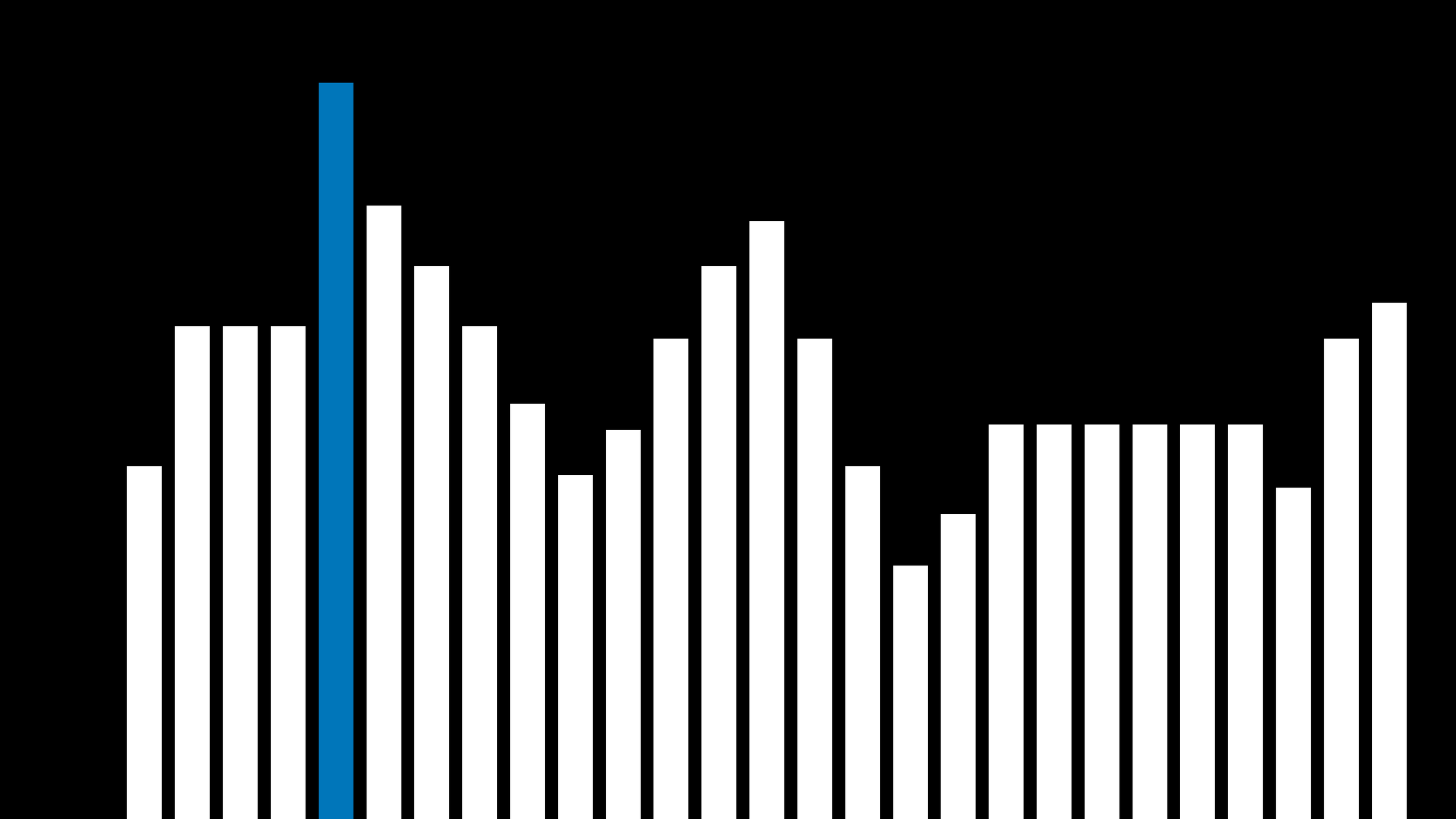
Hill Climbing

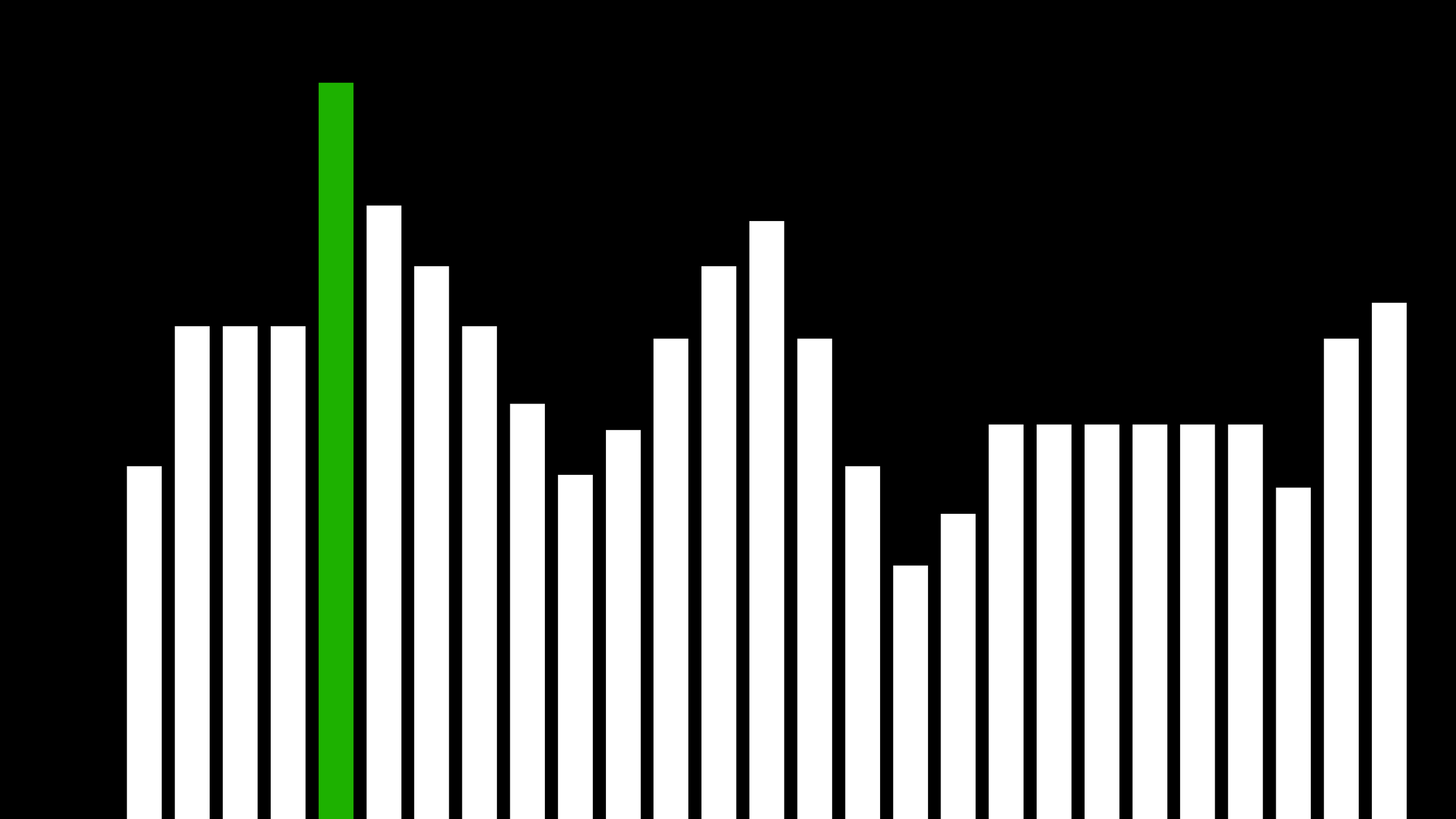


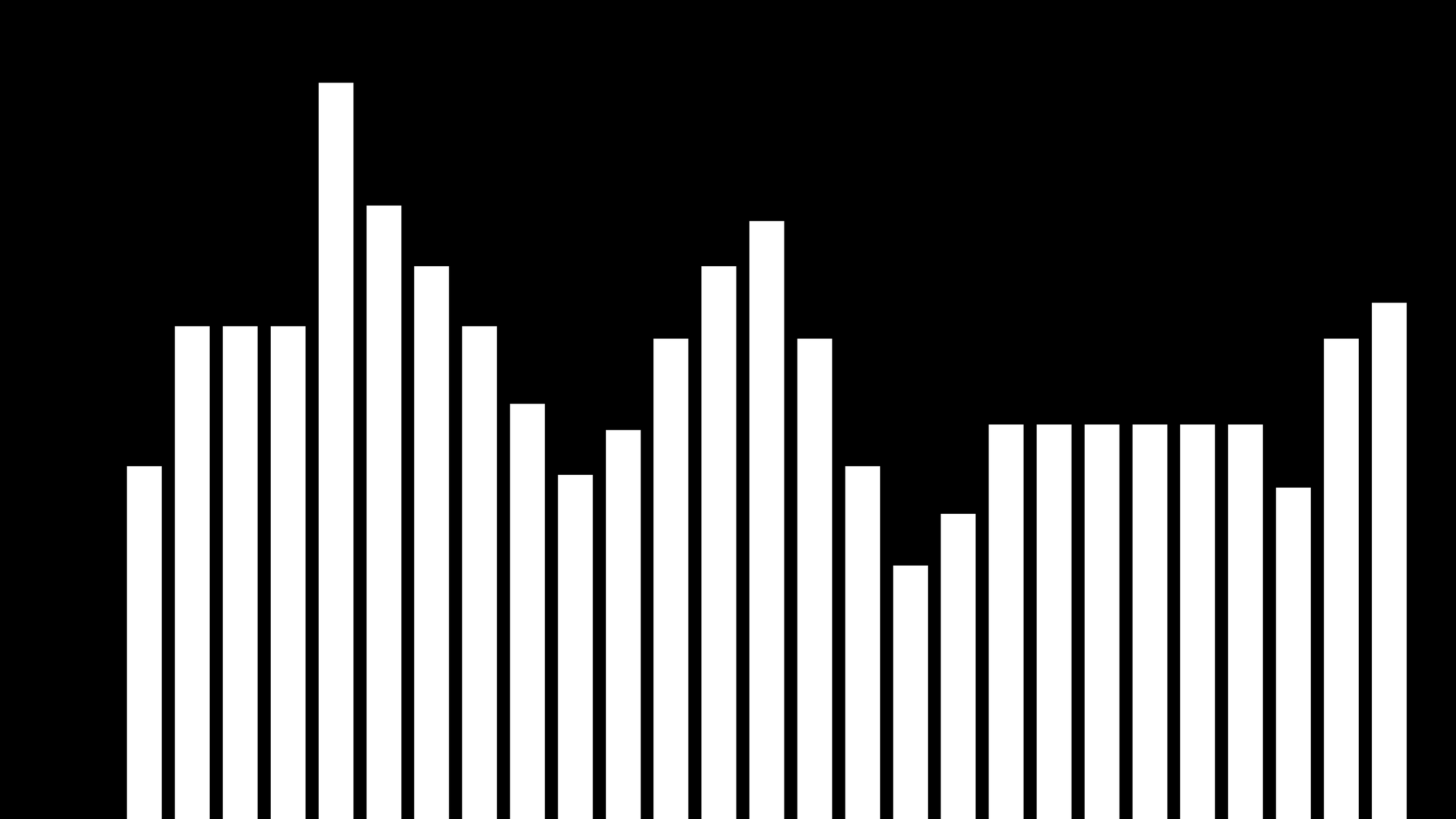


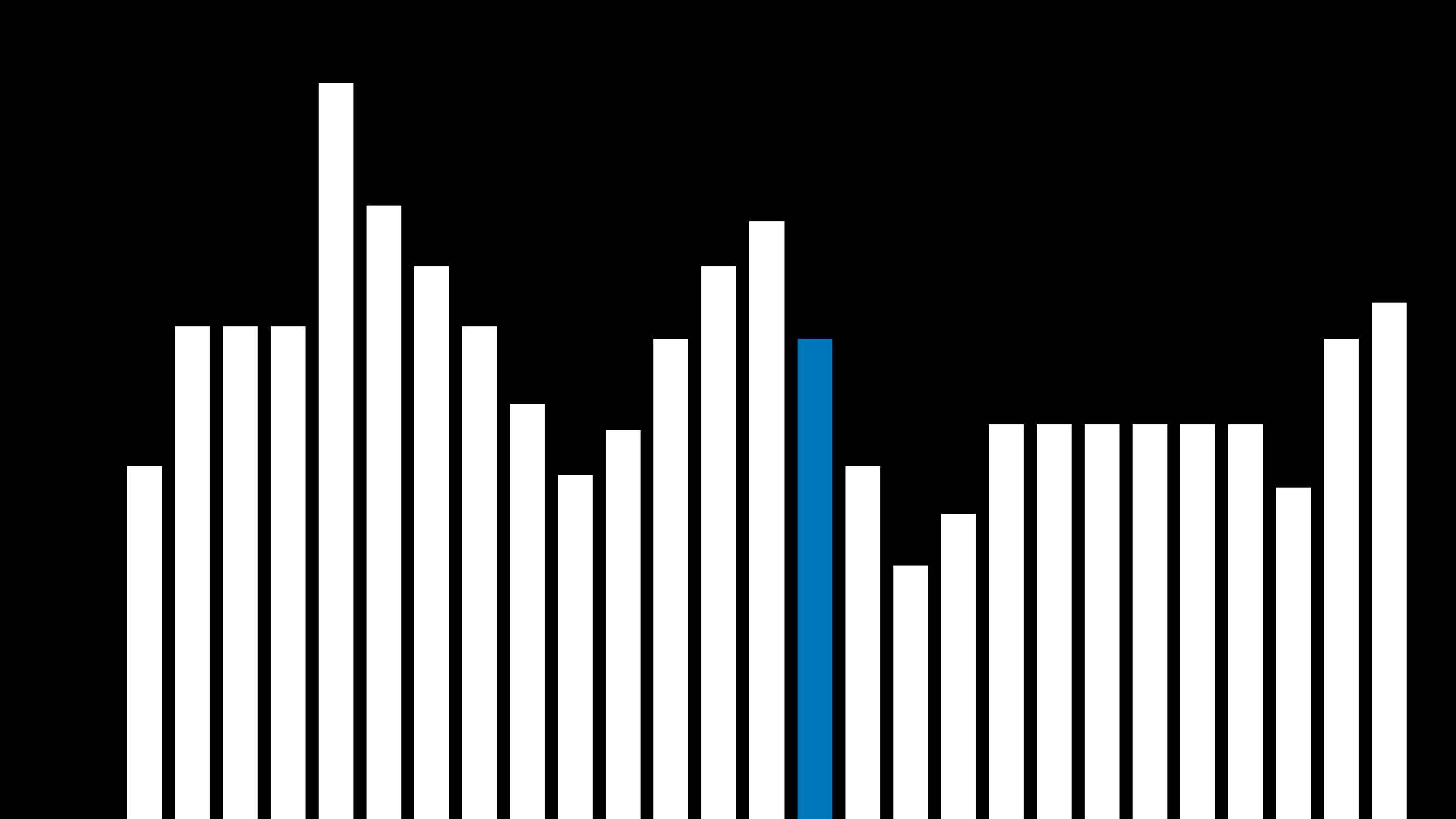


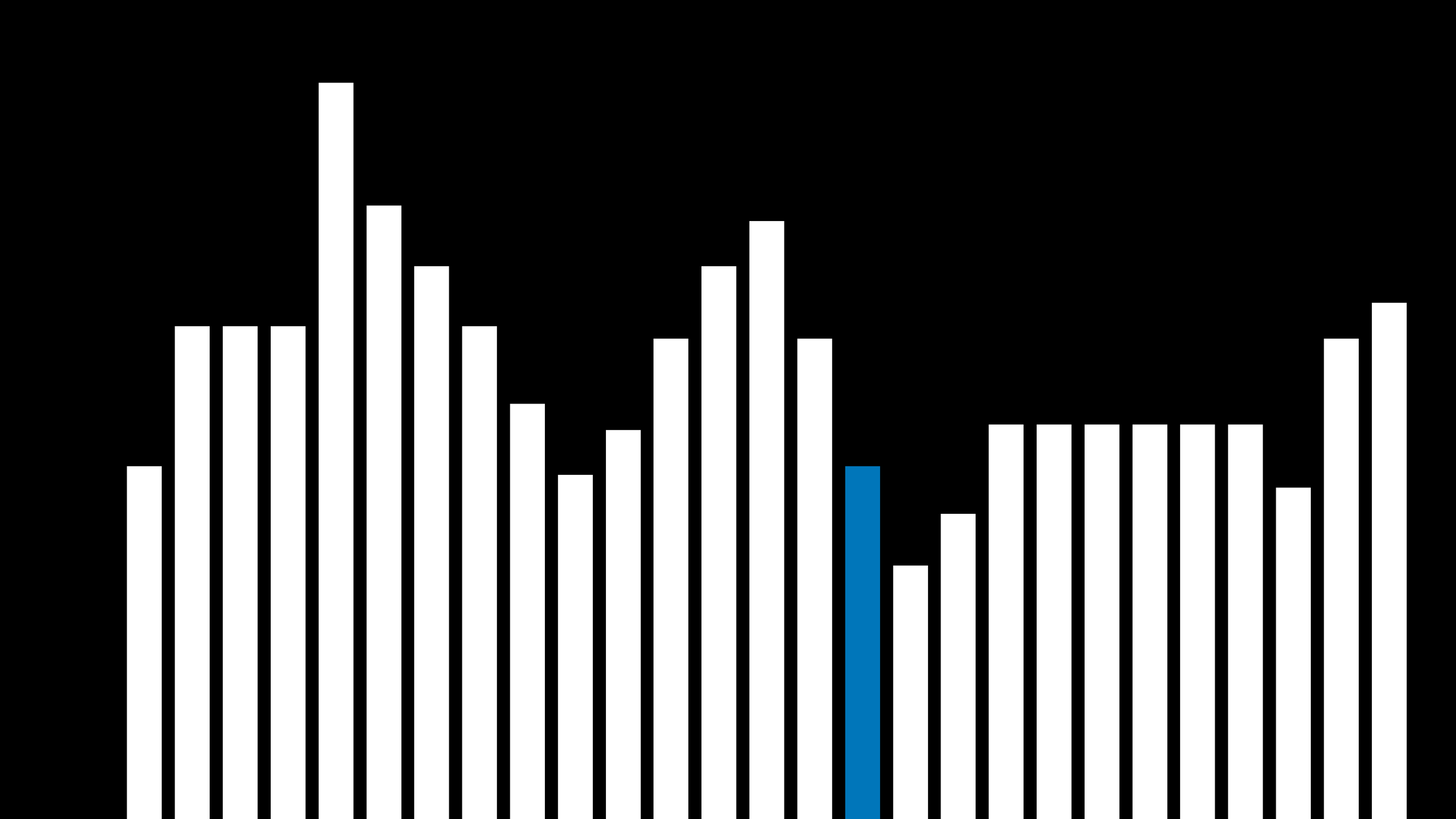


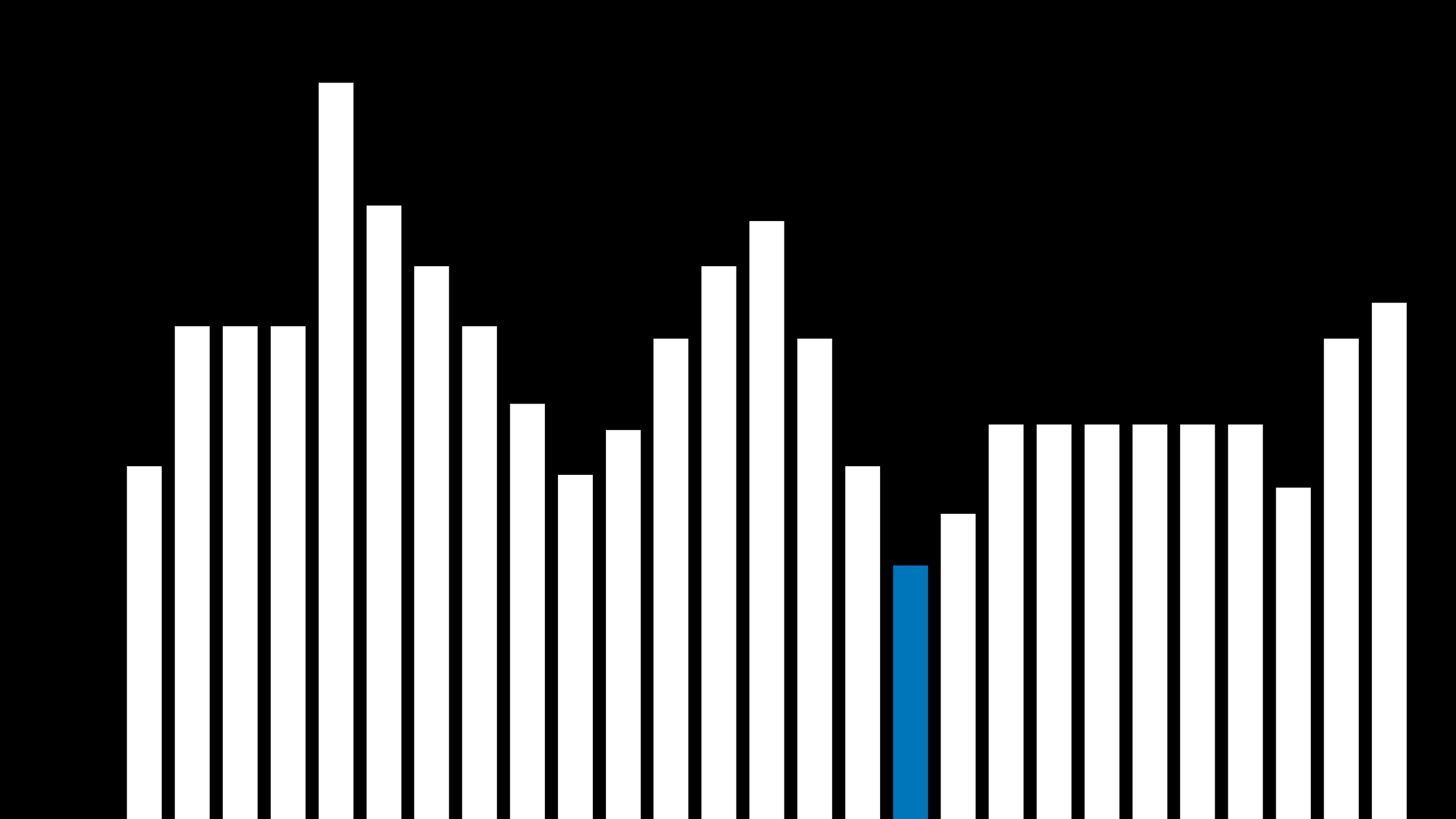


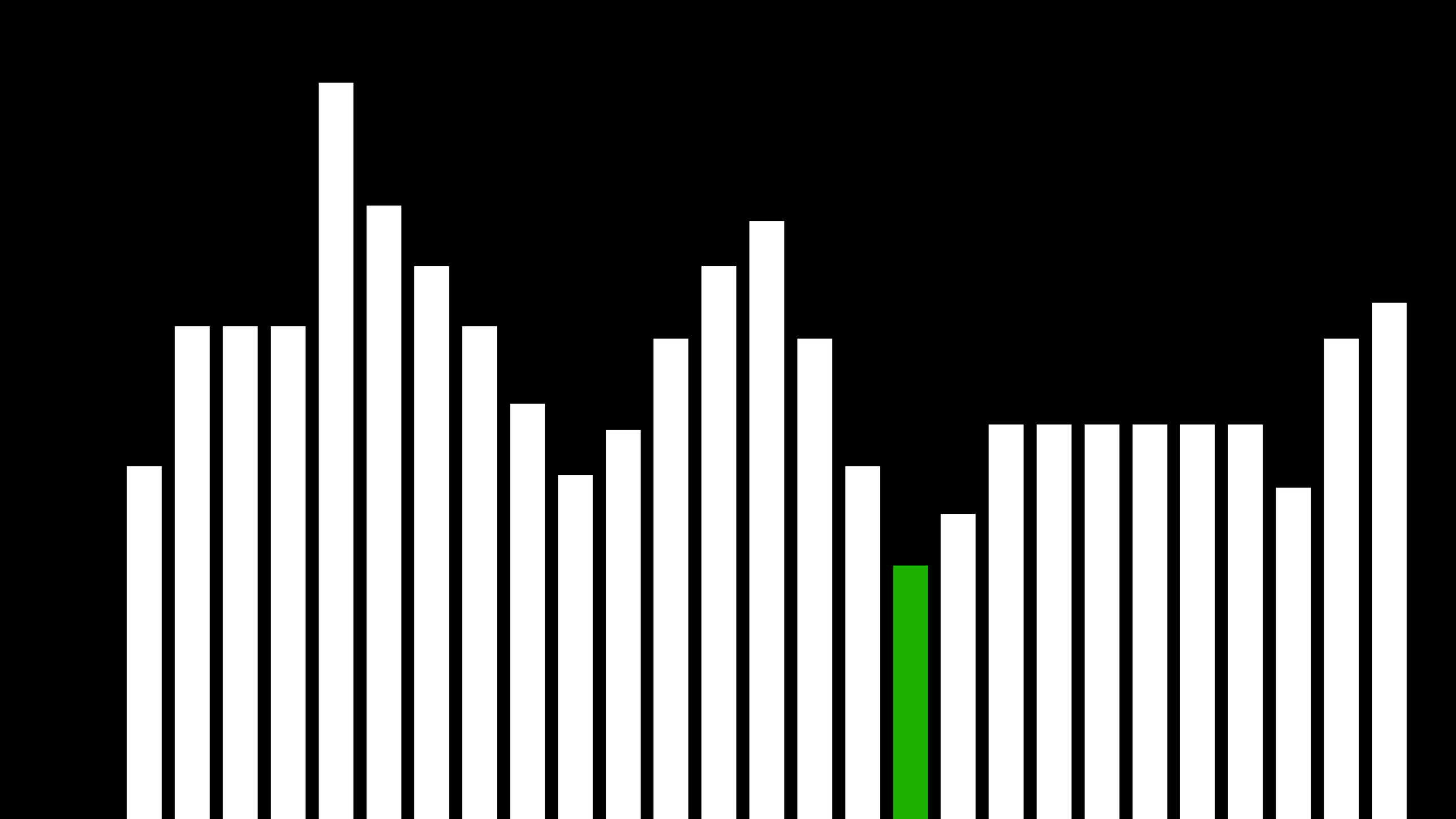






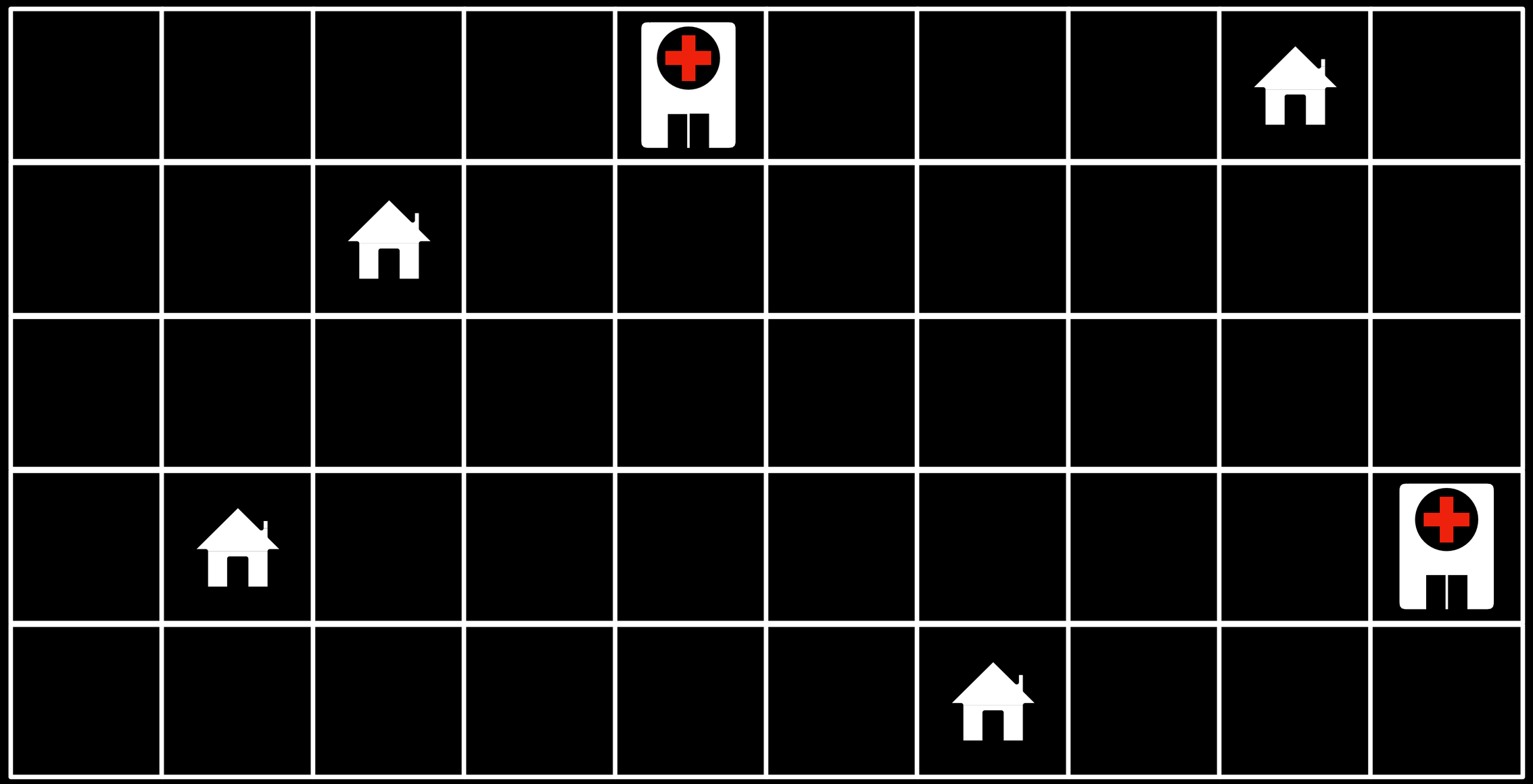






Hill Climbing

```
function HILL-CLIMB(problem):
    current = initial state of problem
    repeat:
        neighbor = highest valued neighbor of current
        if neighbor not better than current:
            return current
        current = neighbor
```


Cost: 17

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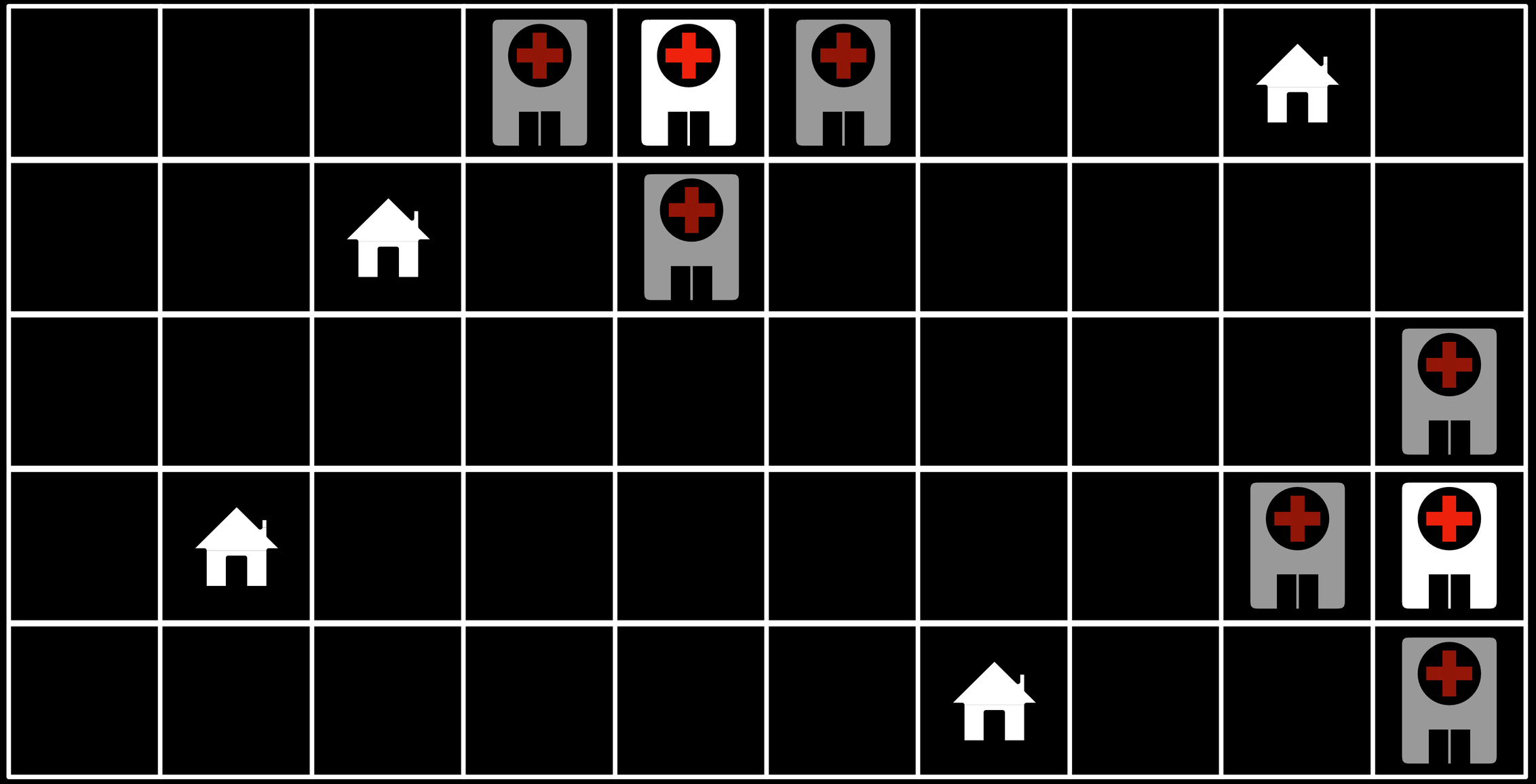
Cost: 17



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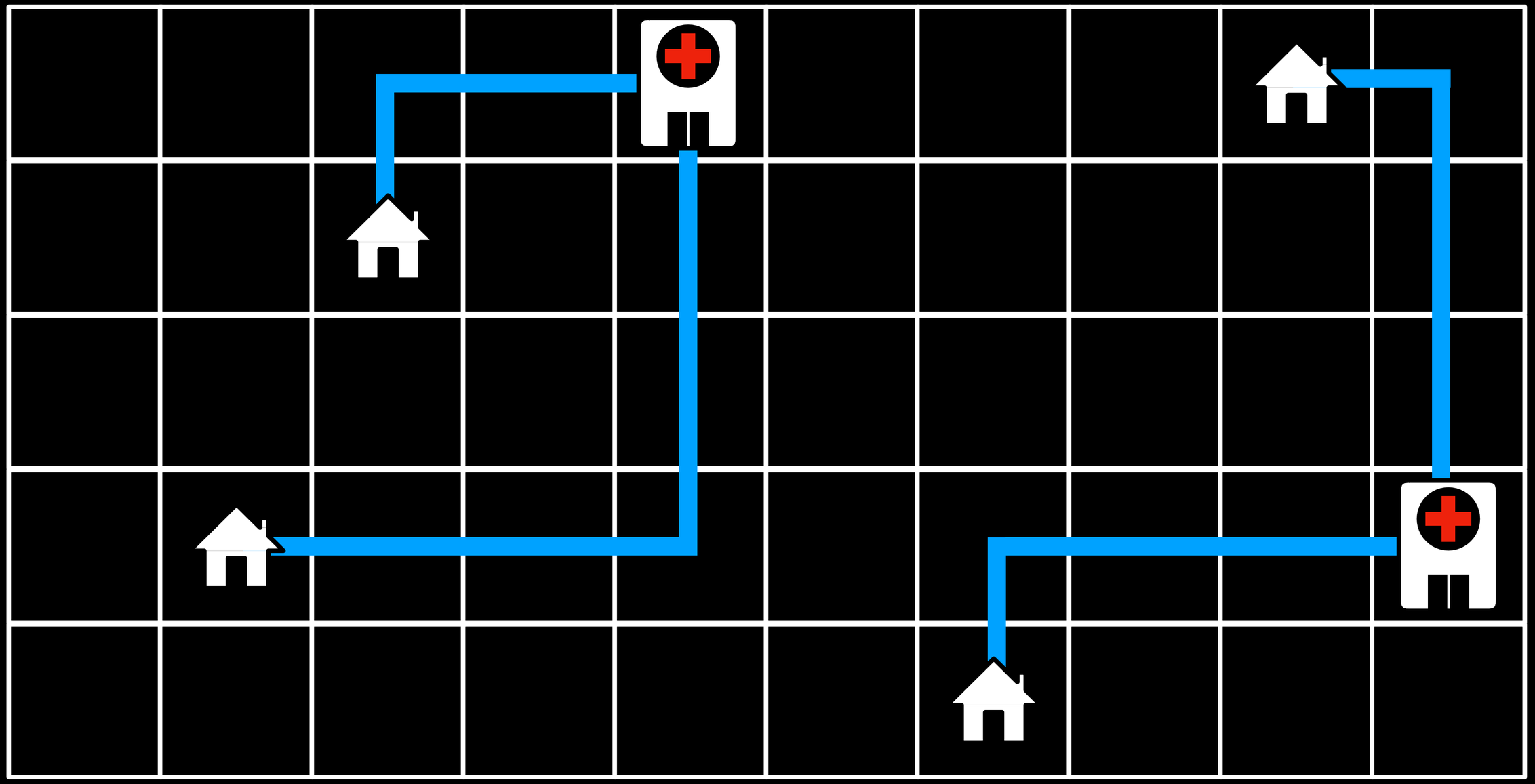
Cost: 17



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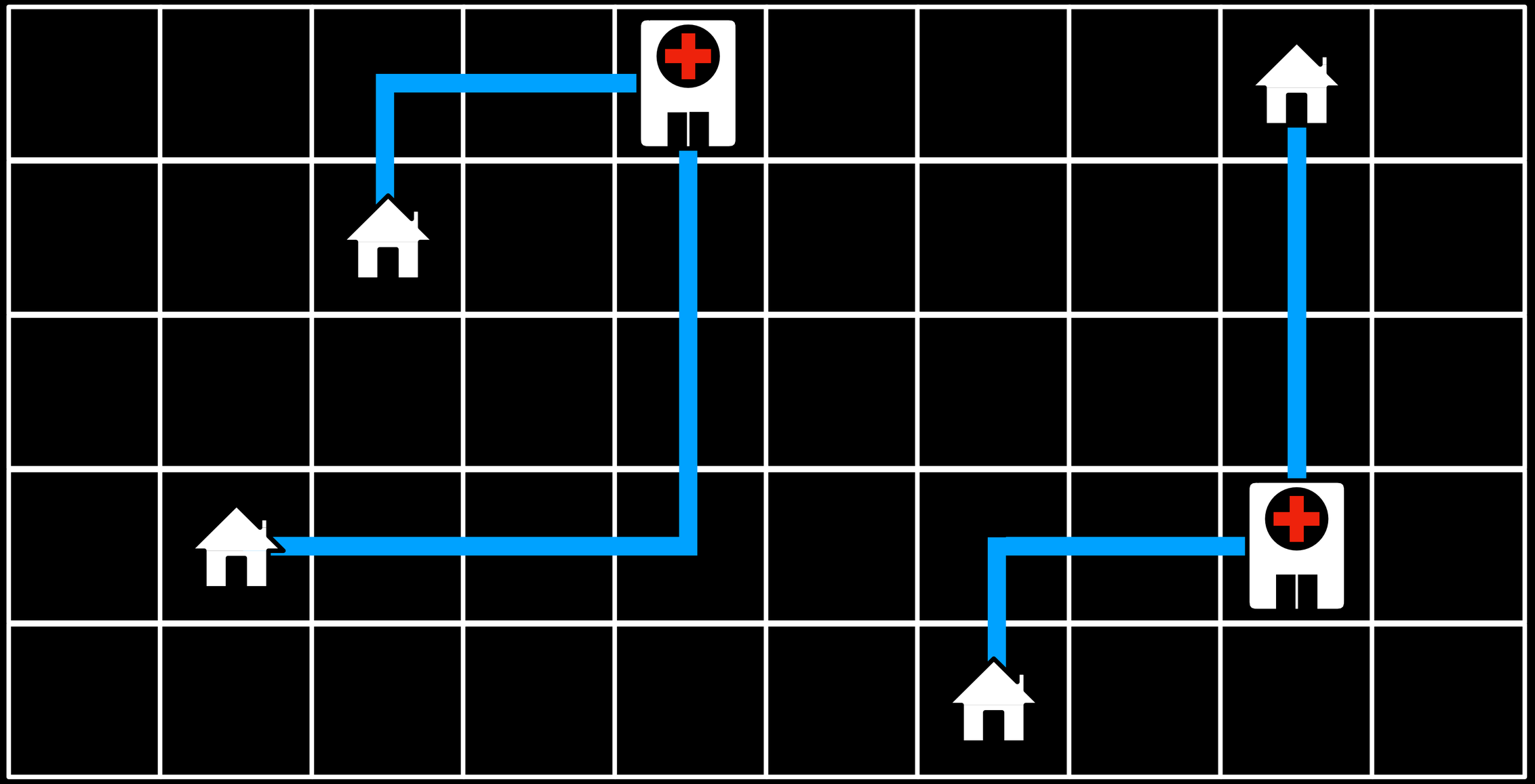
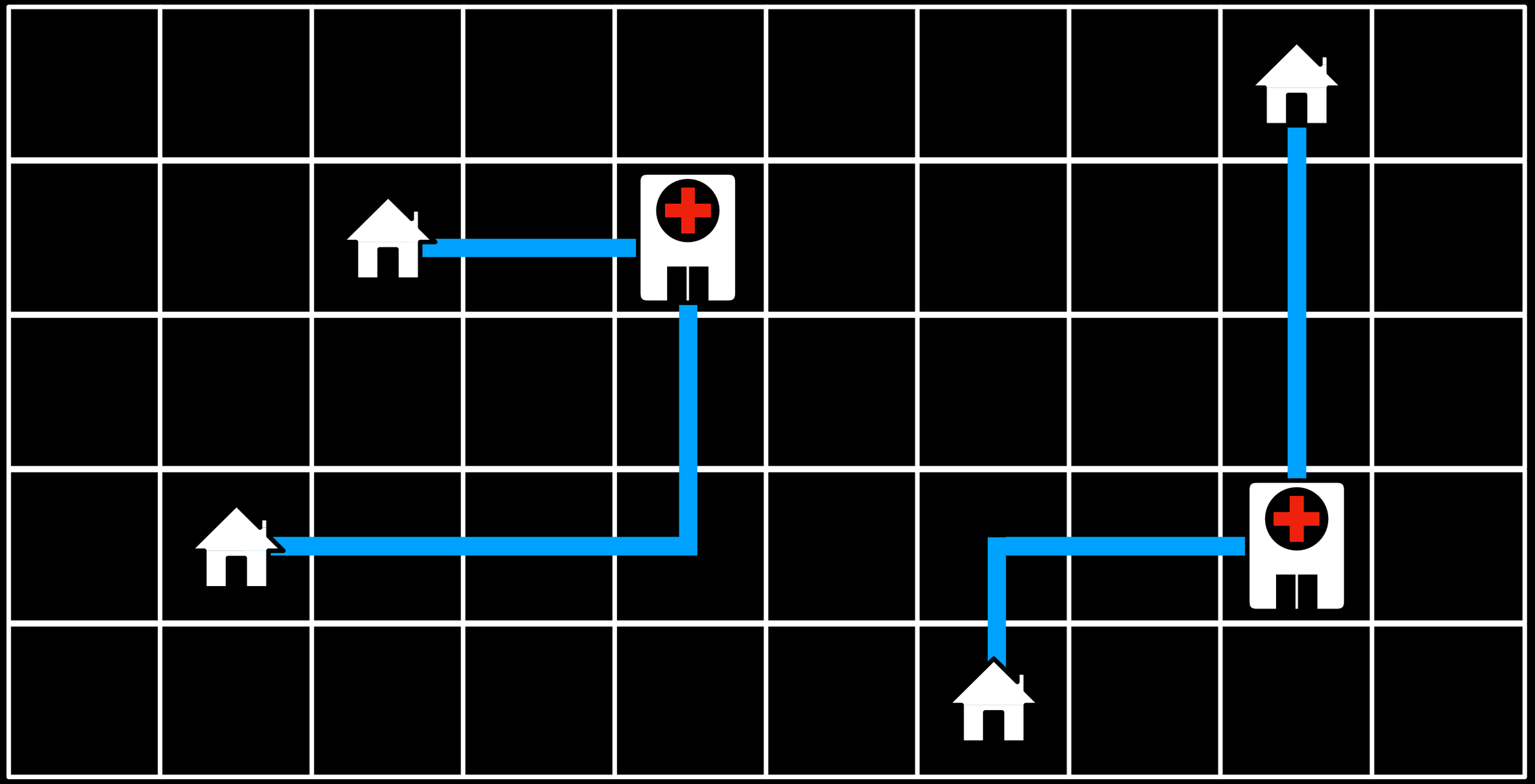
Cost: 15



Cost: 13



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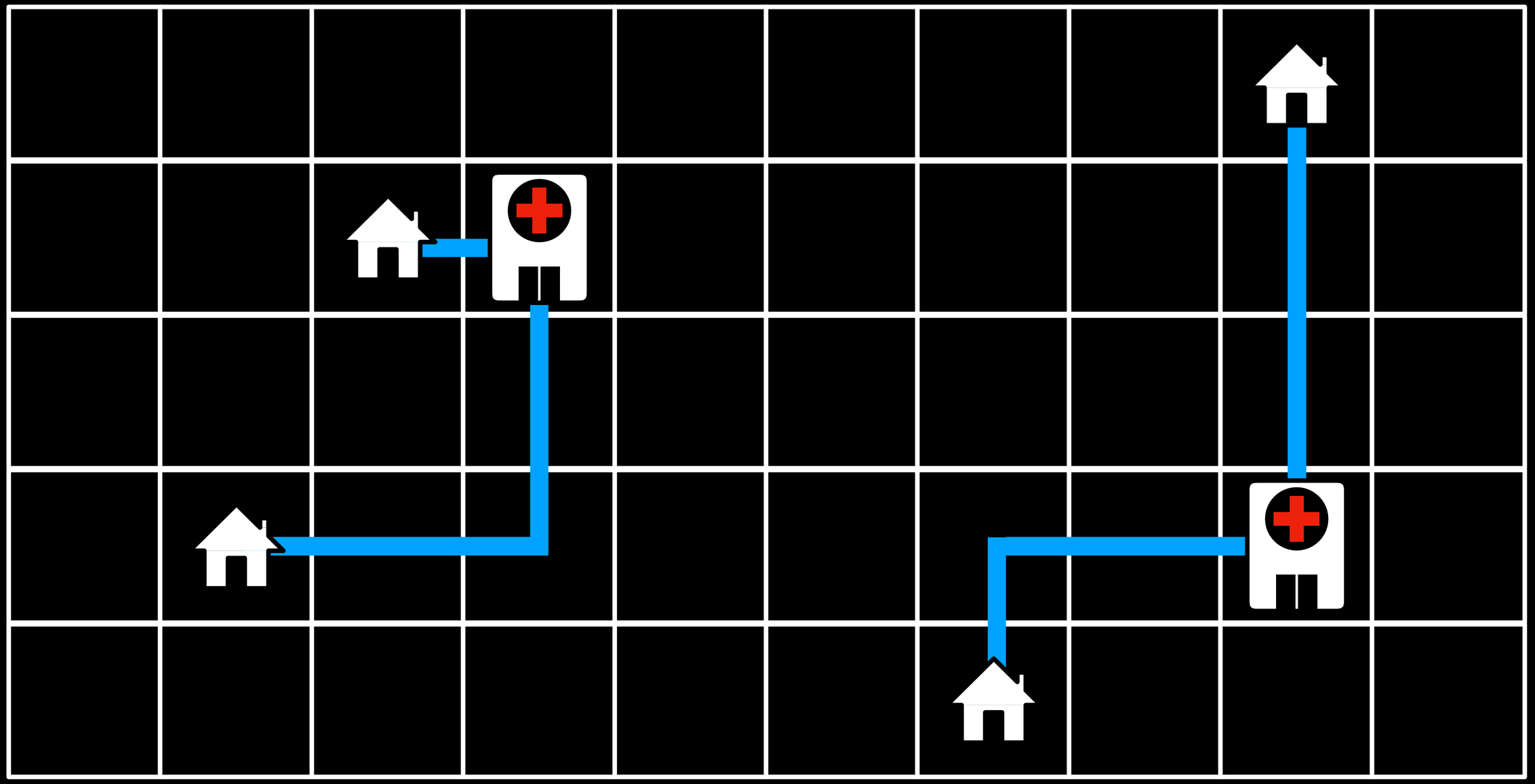
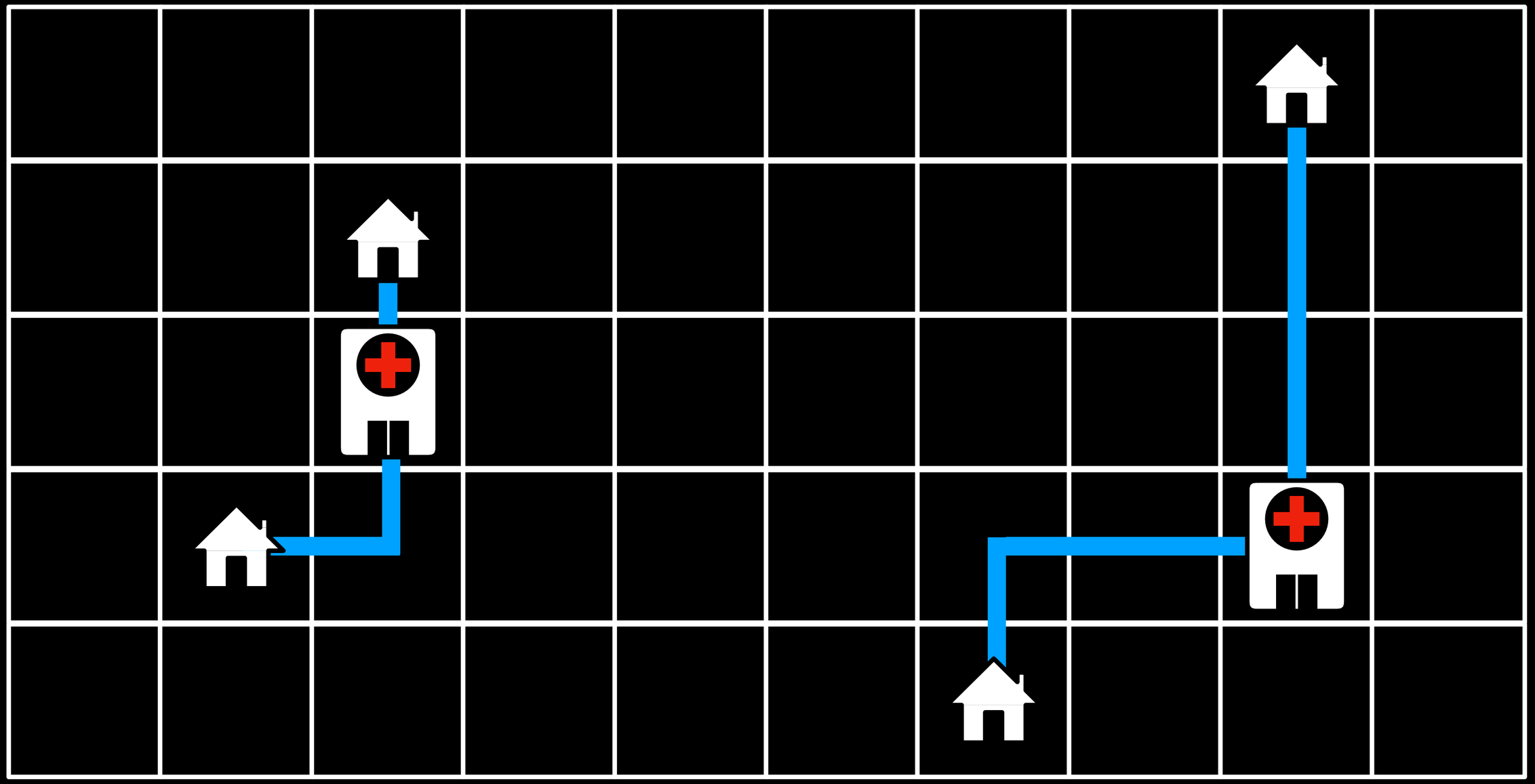
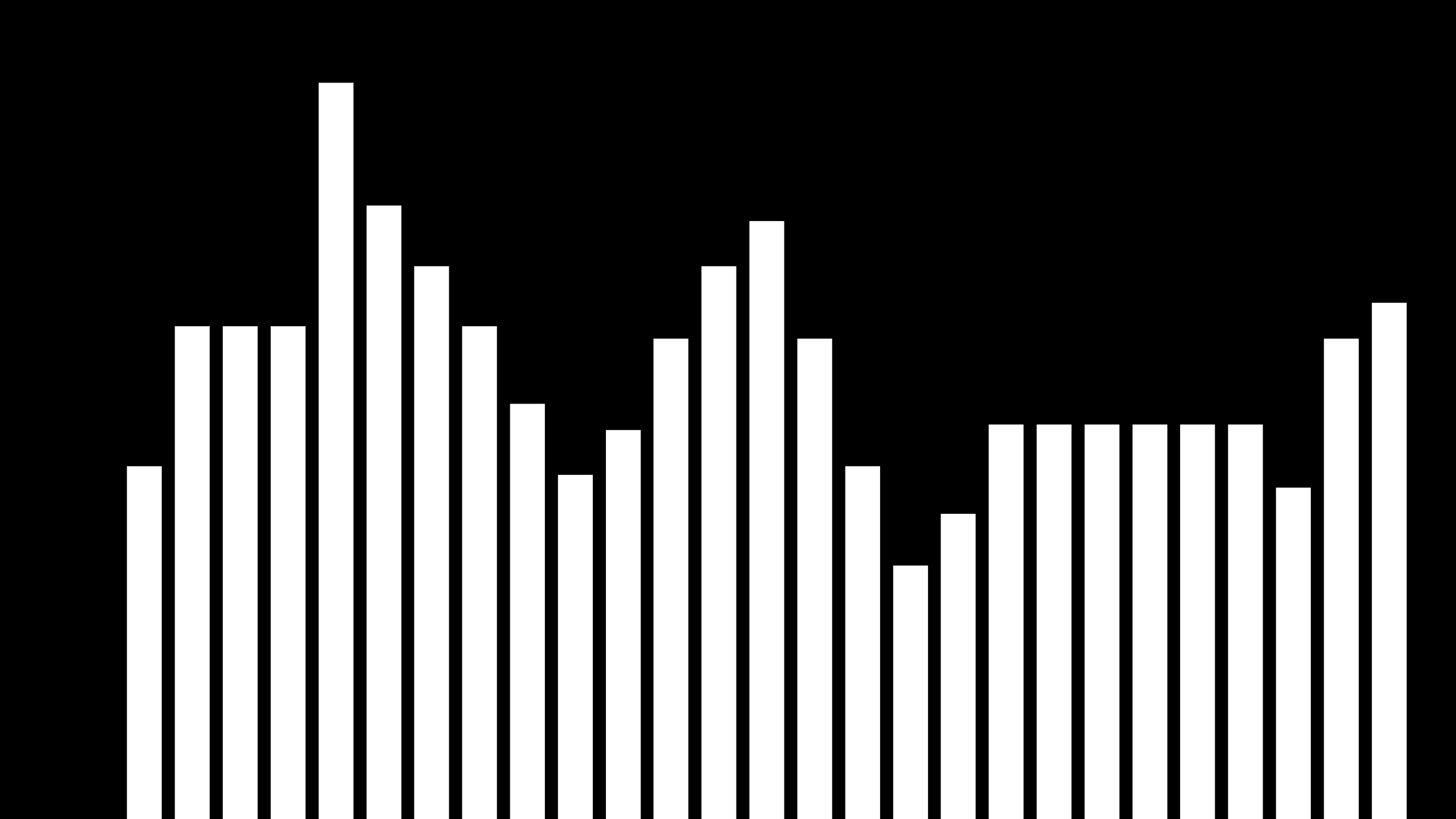
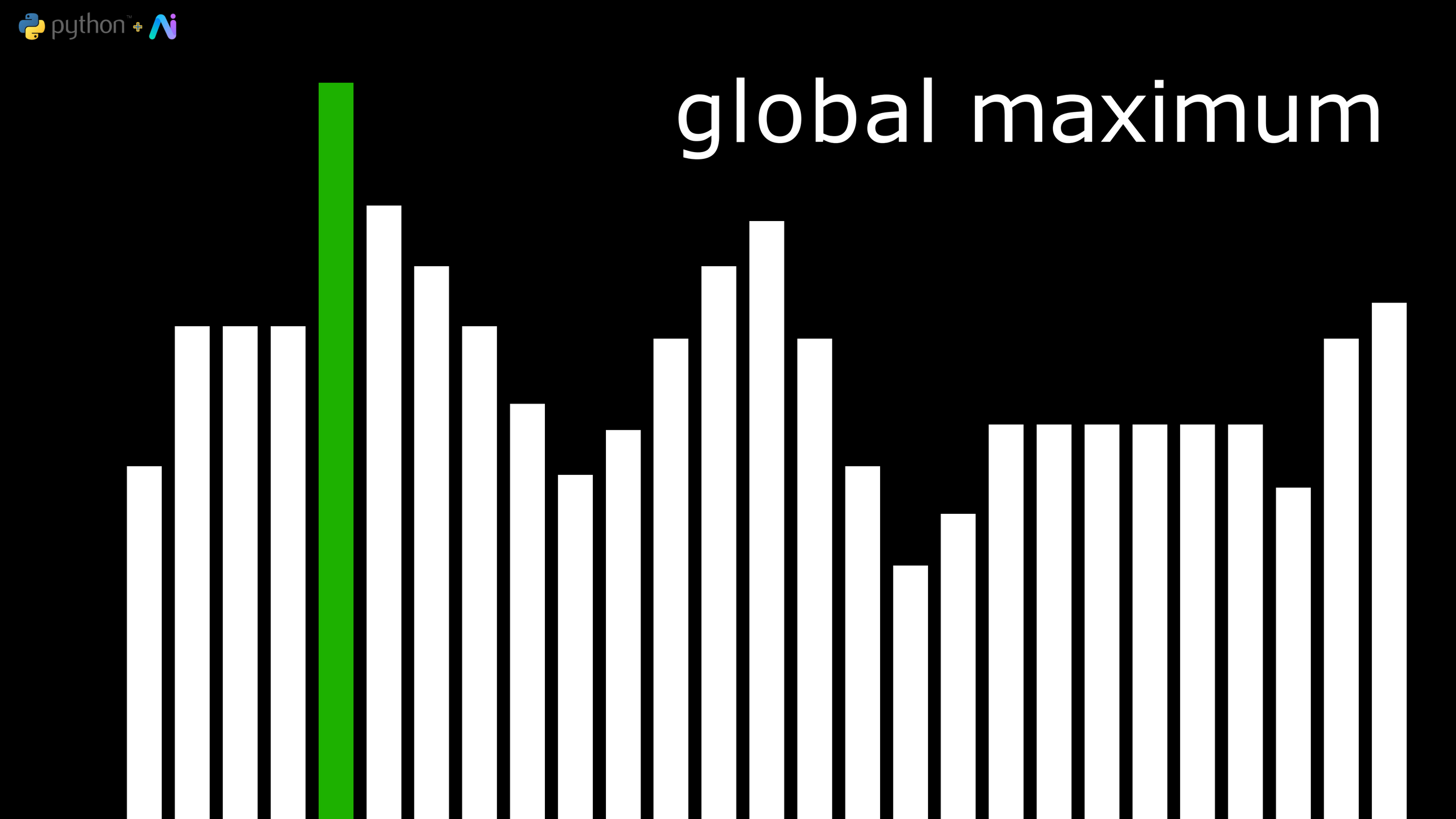
Cost: 11



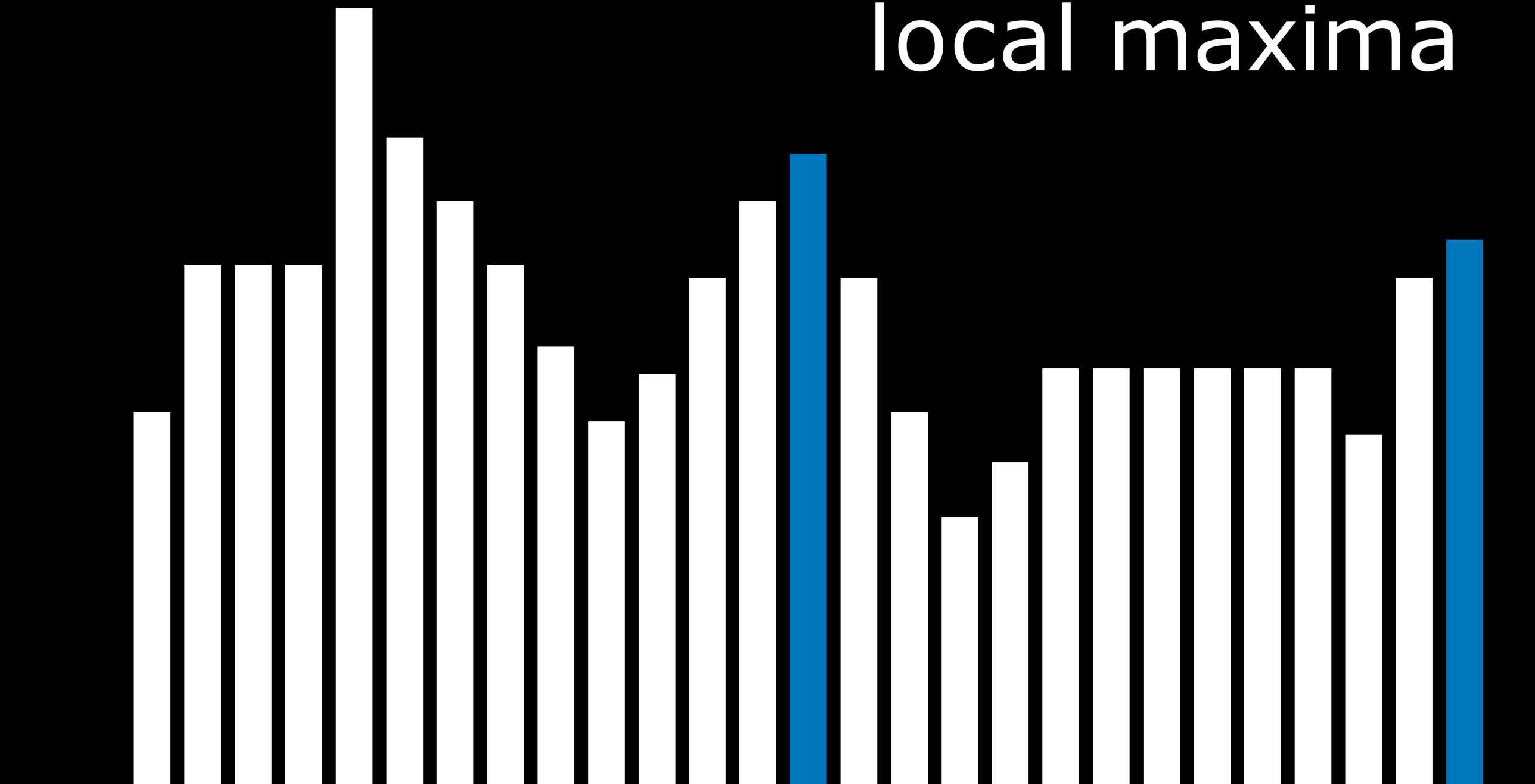
Cost: 9

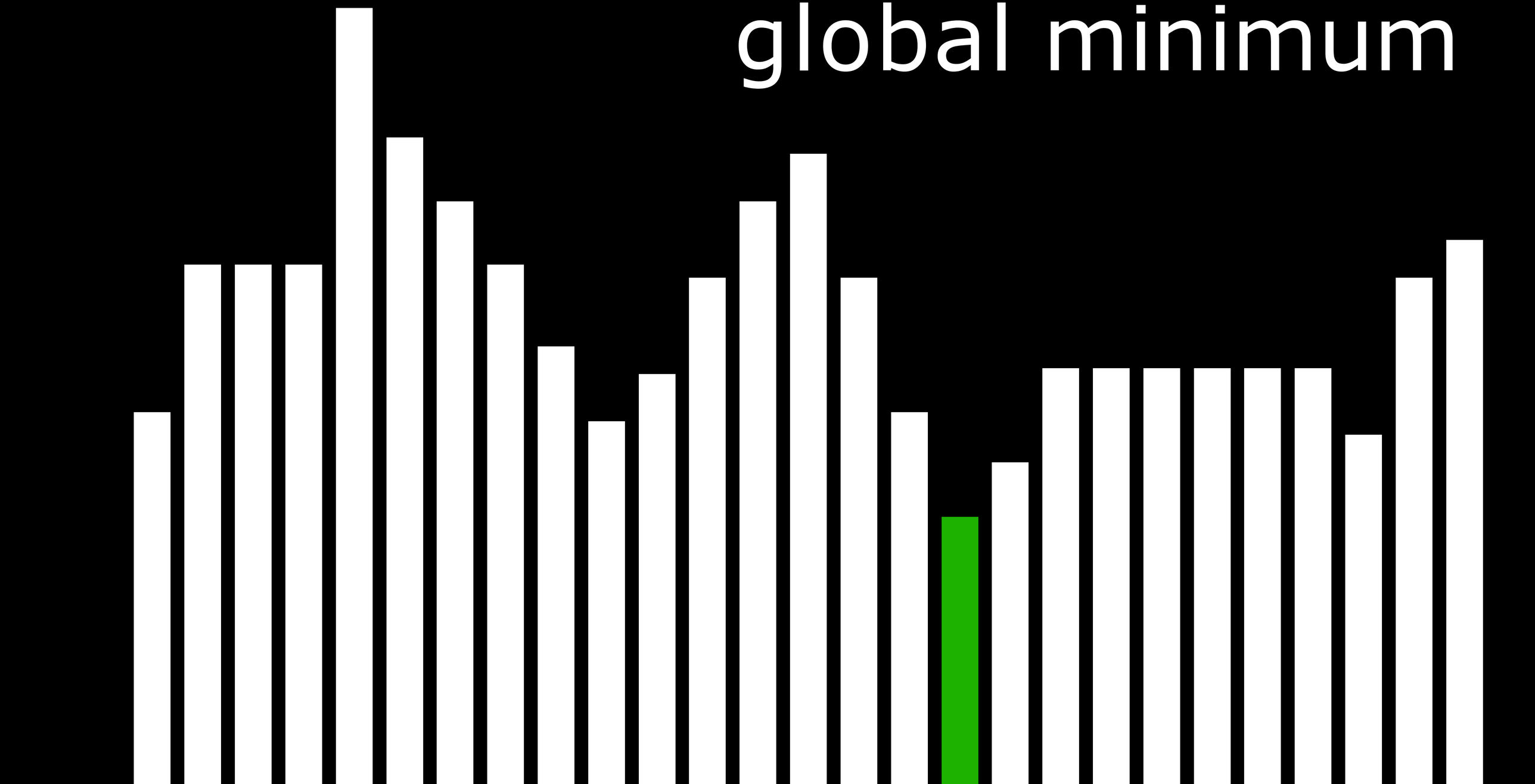




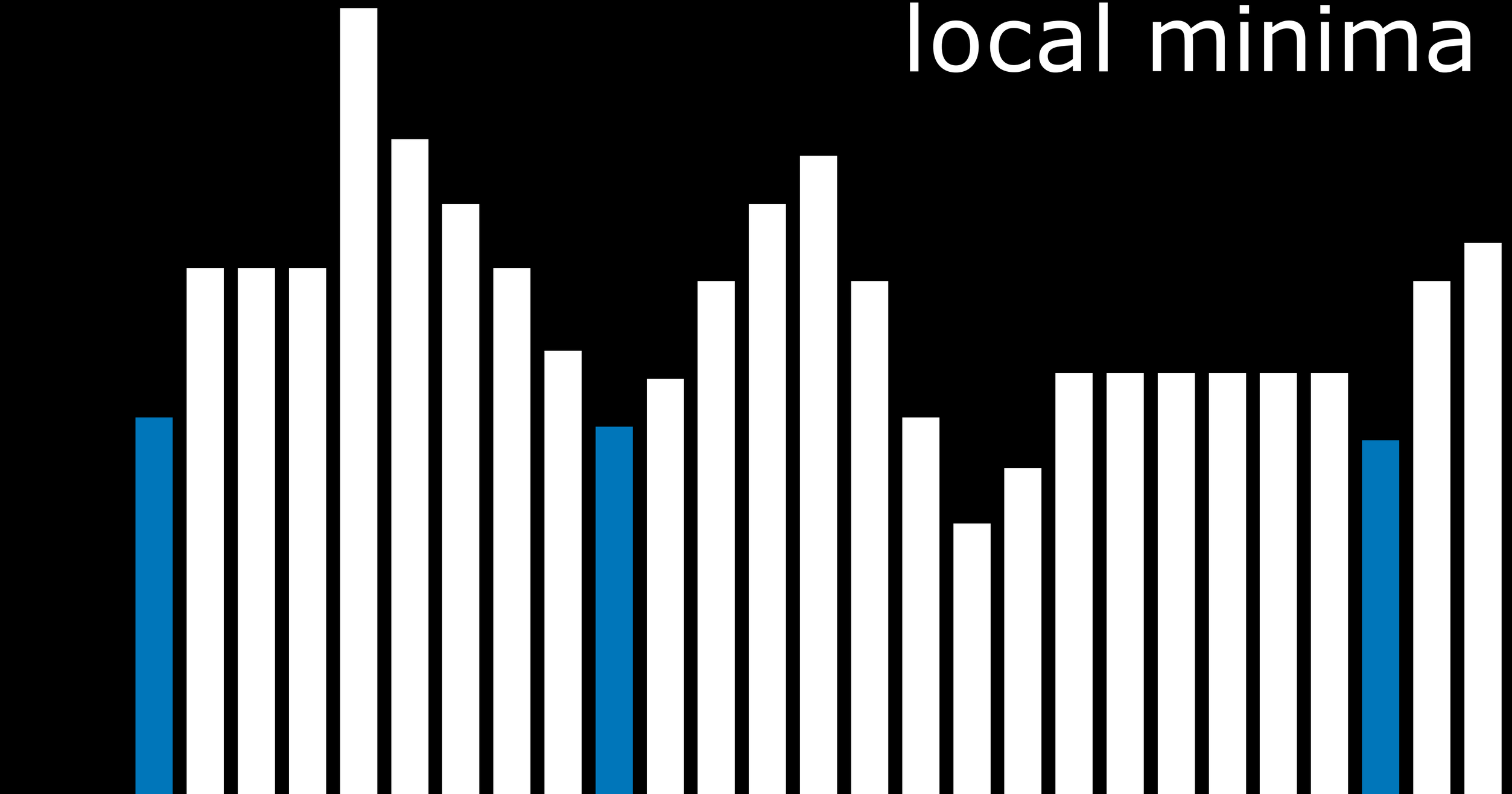

global maximum

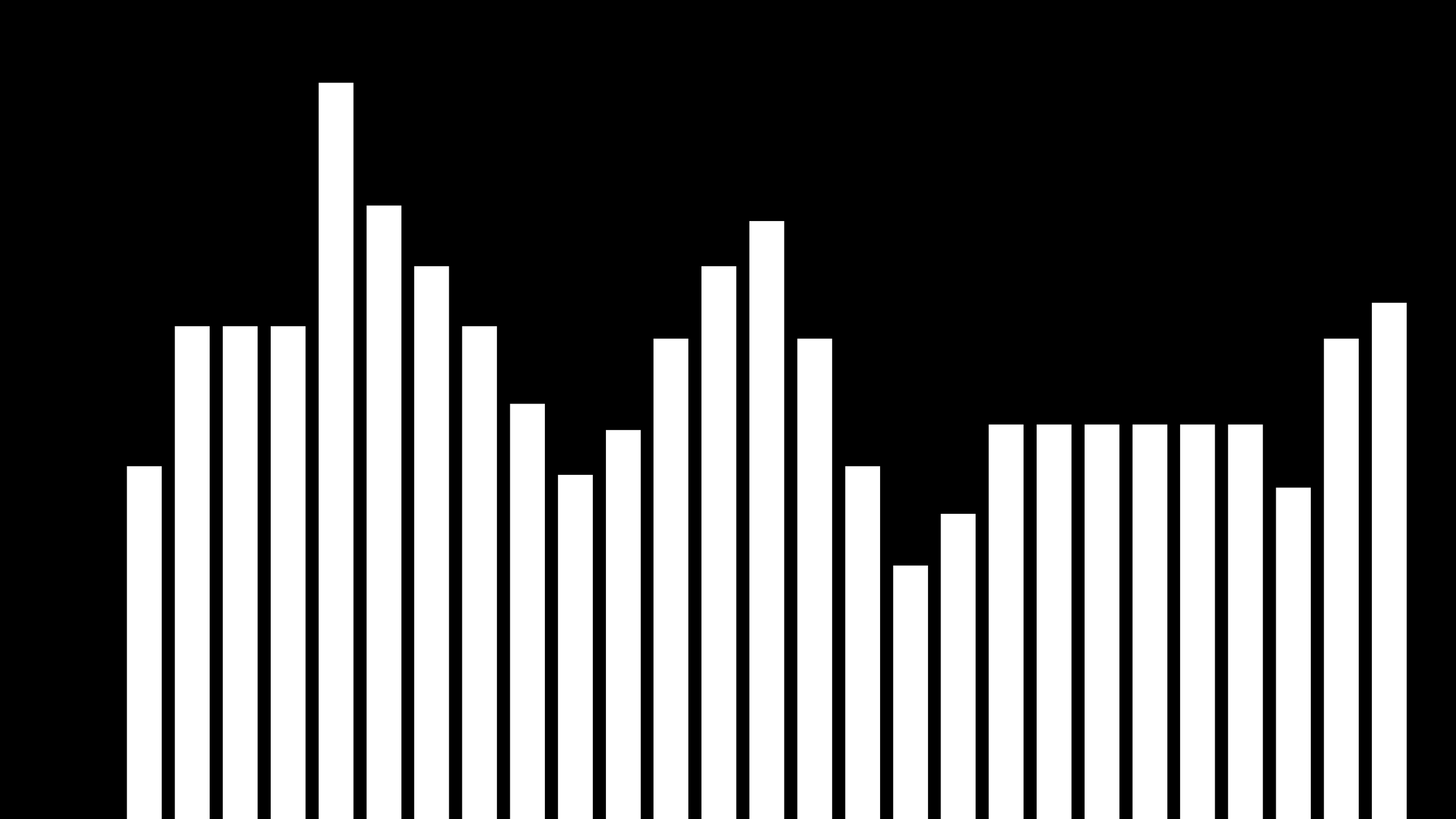
local maxima

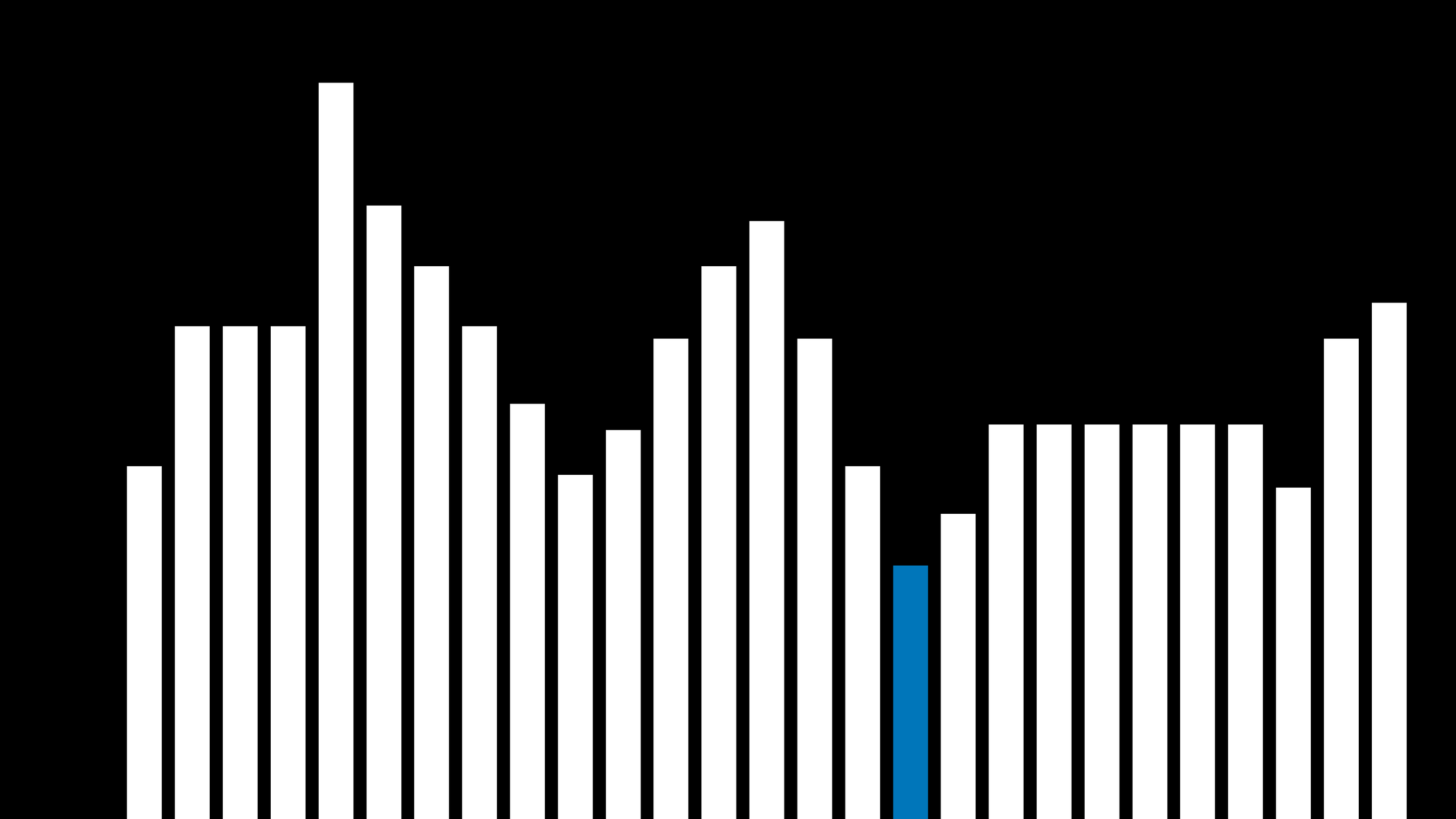


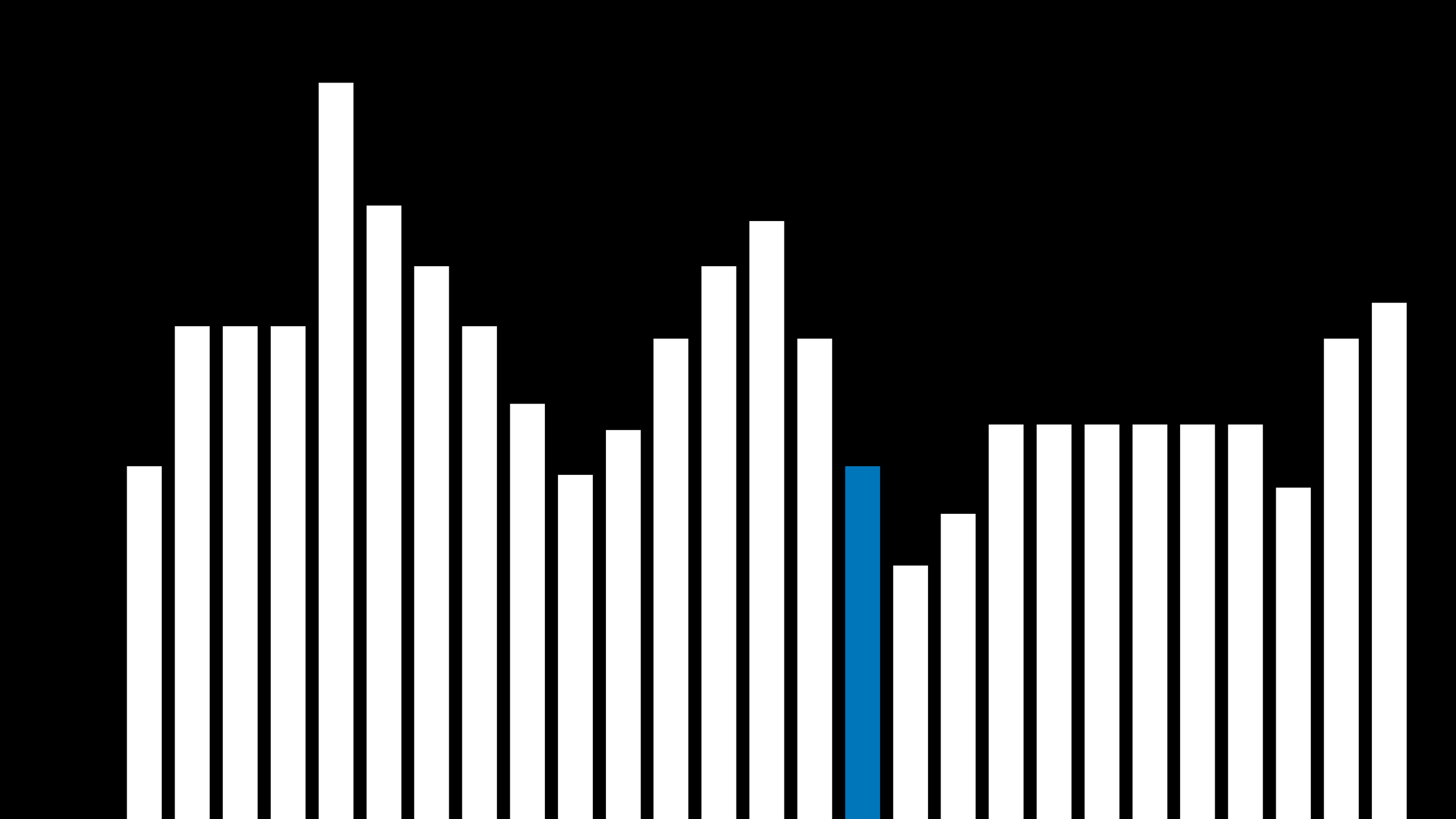

global minimum

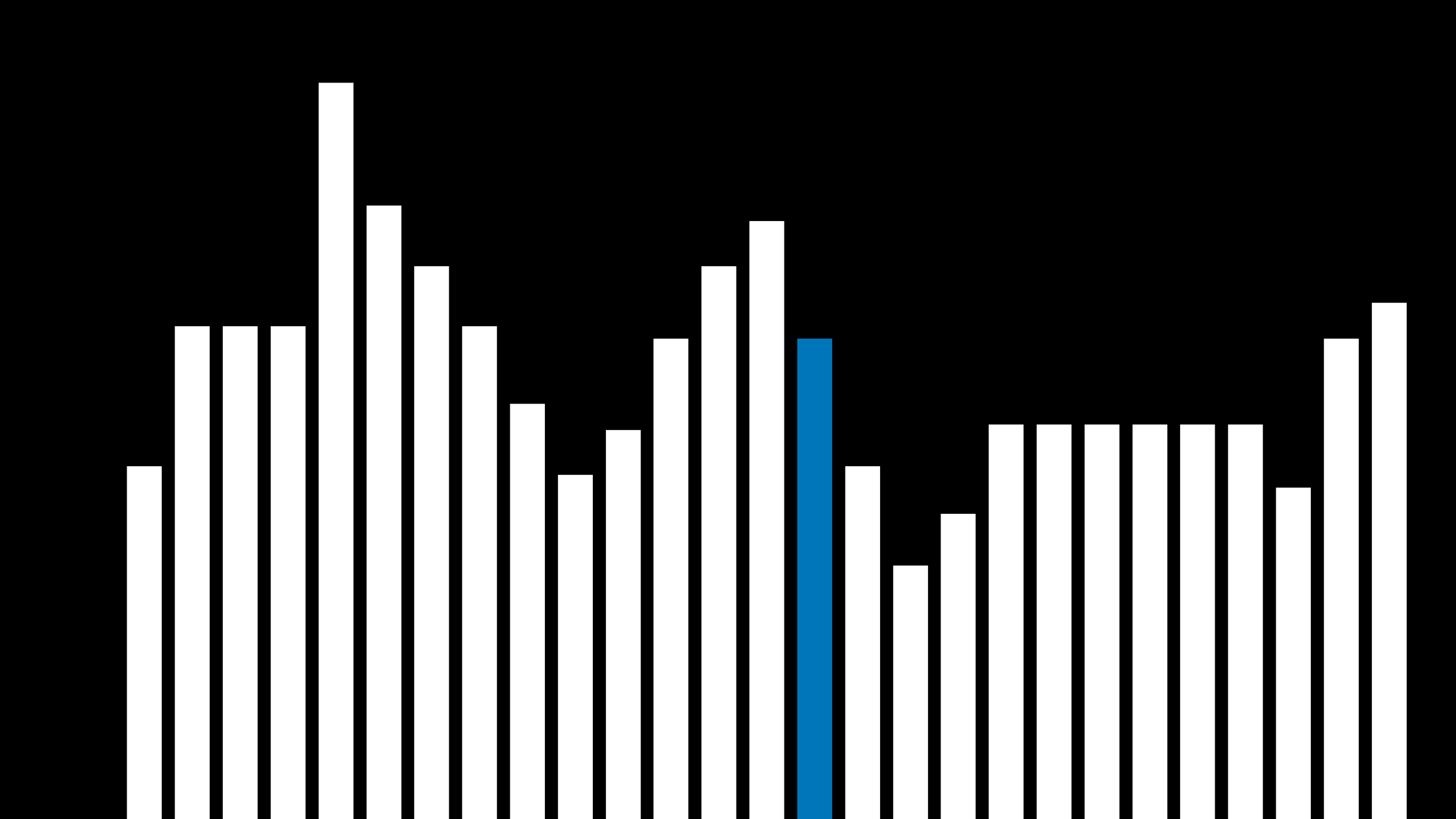
local minima

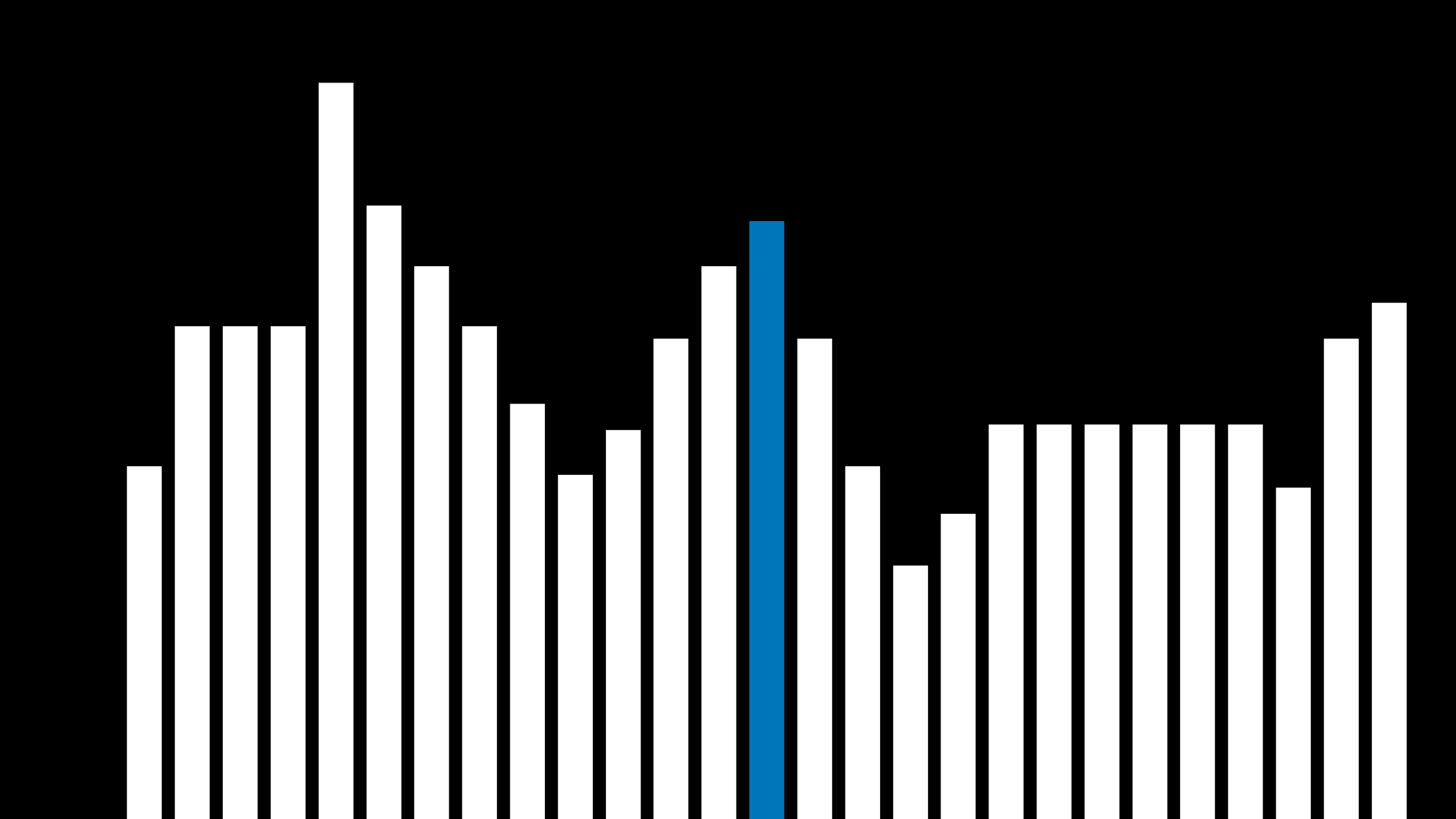












flat local maximum

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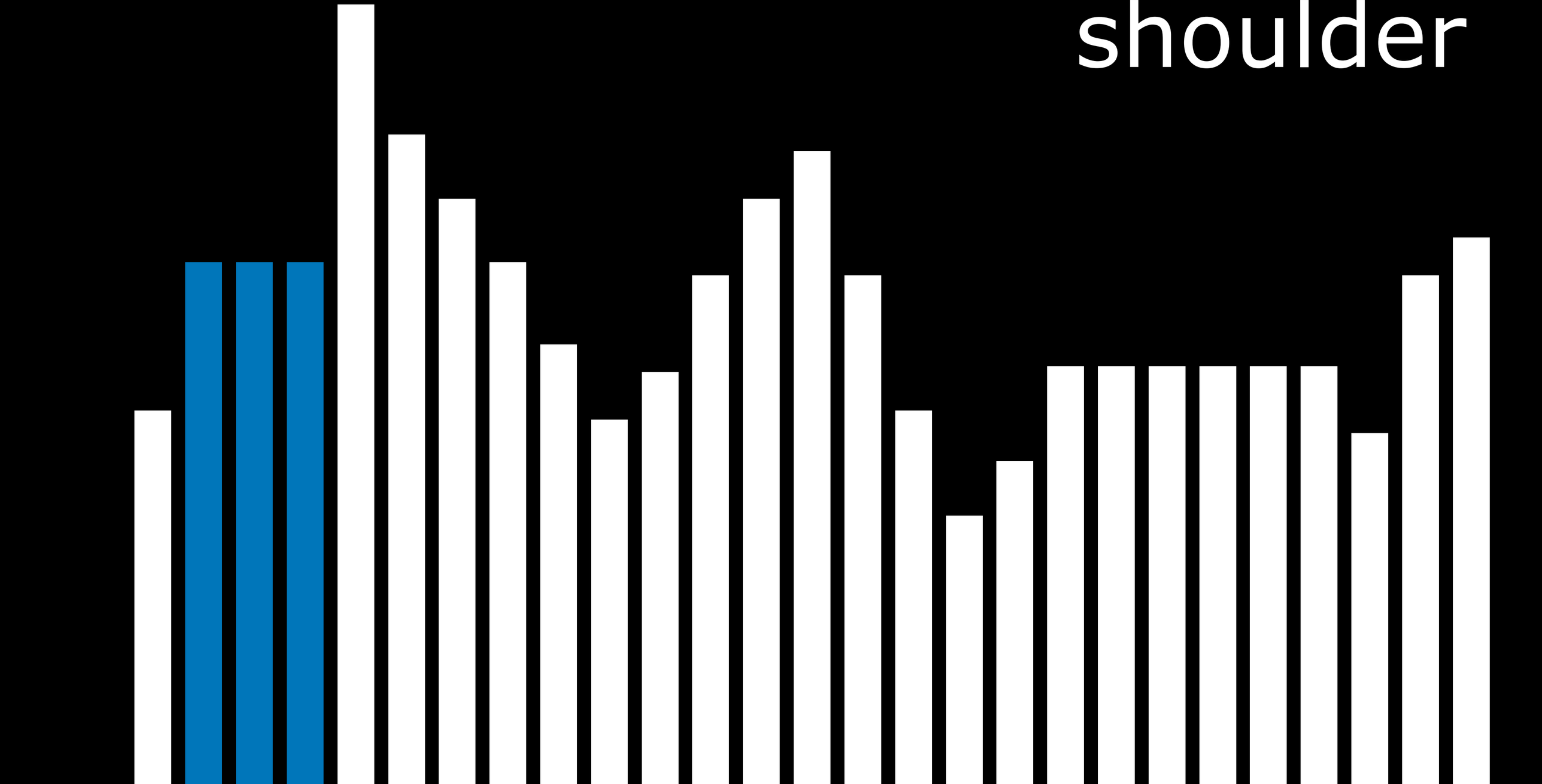
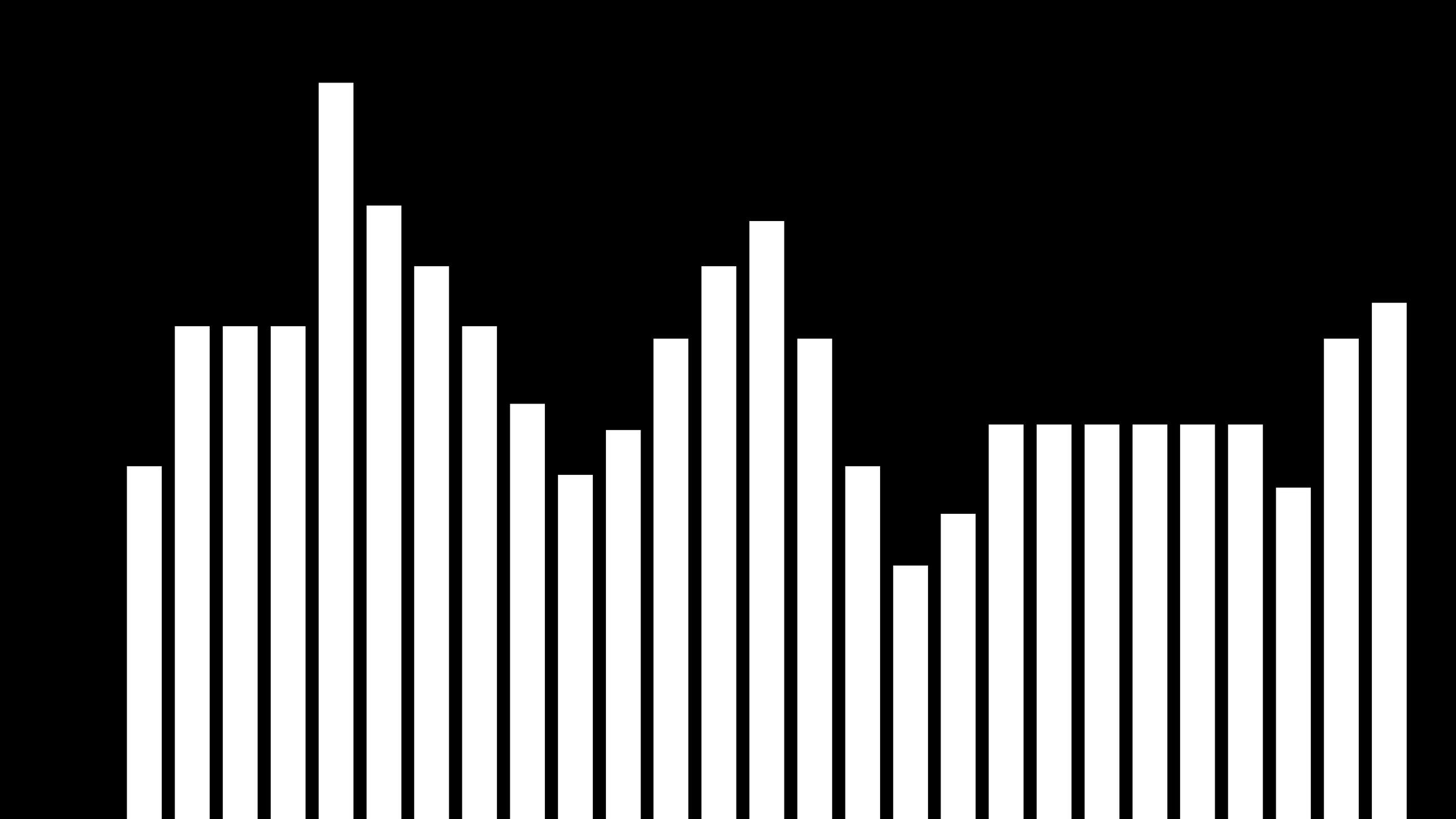
shoulder

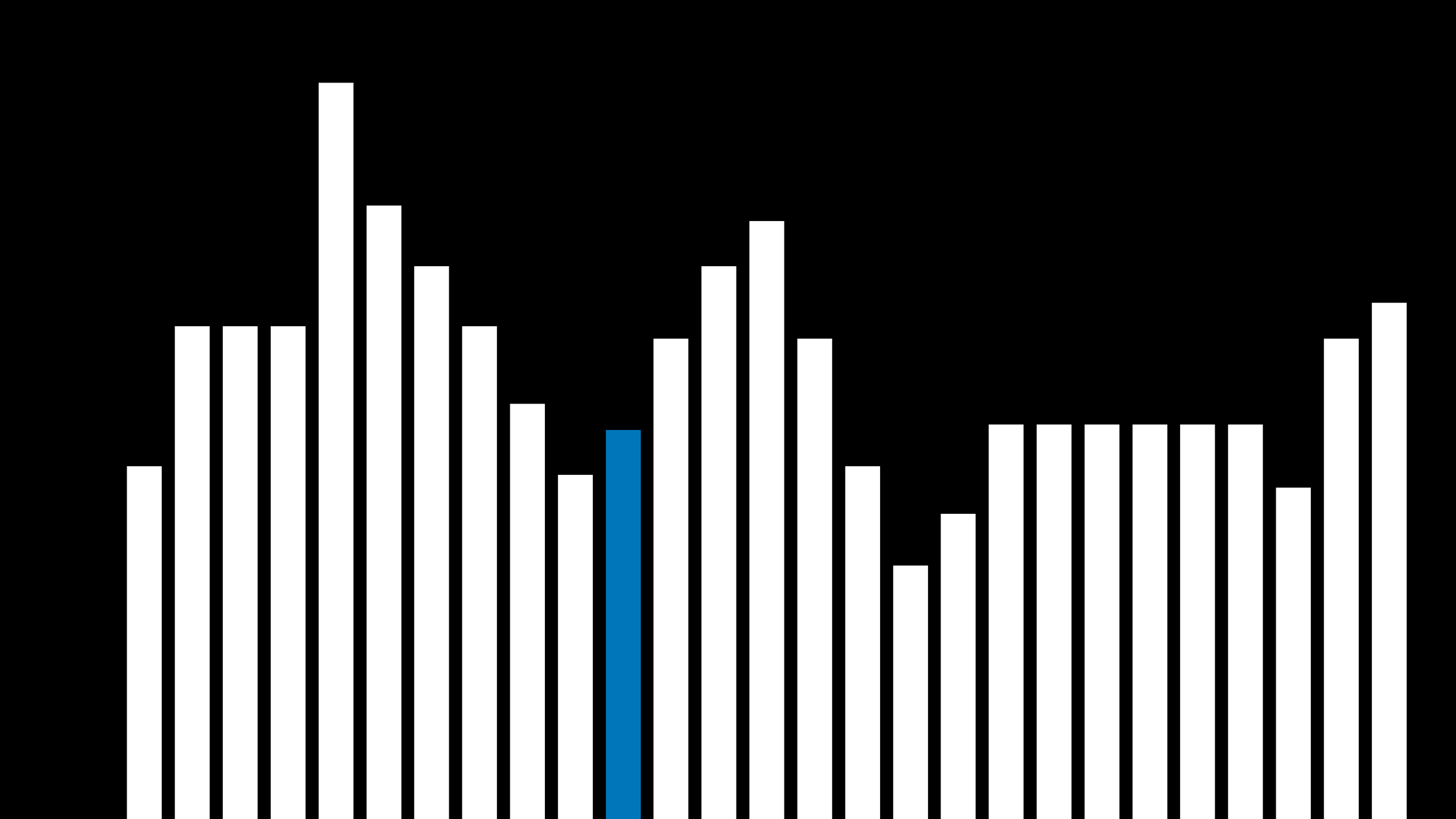


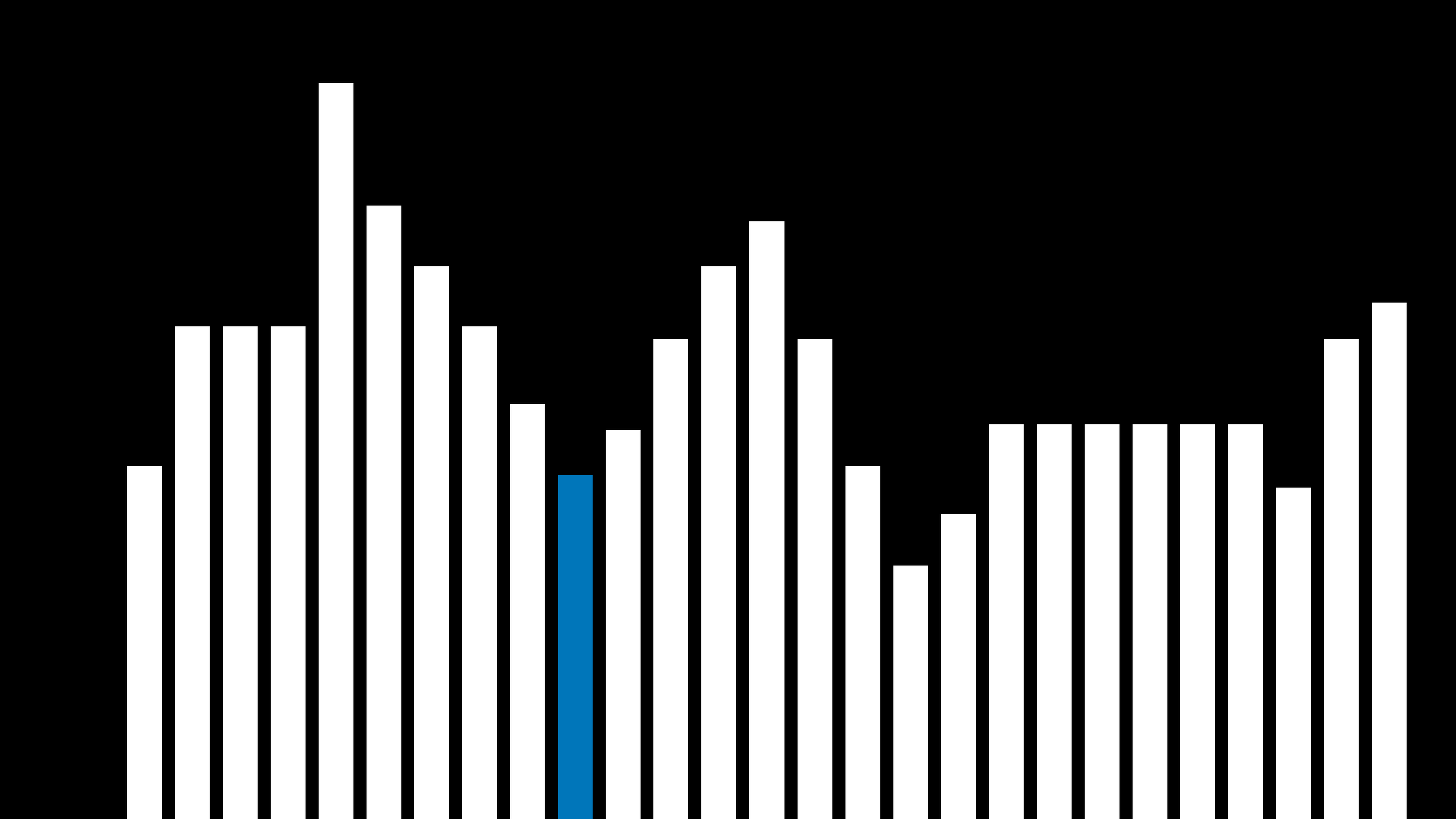
Hill Climbing Variants

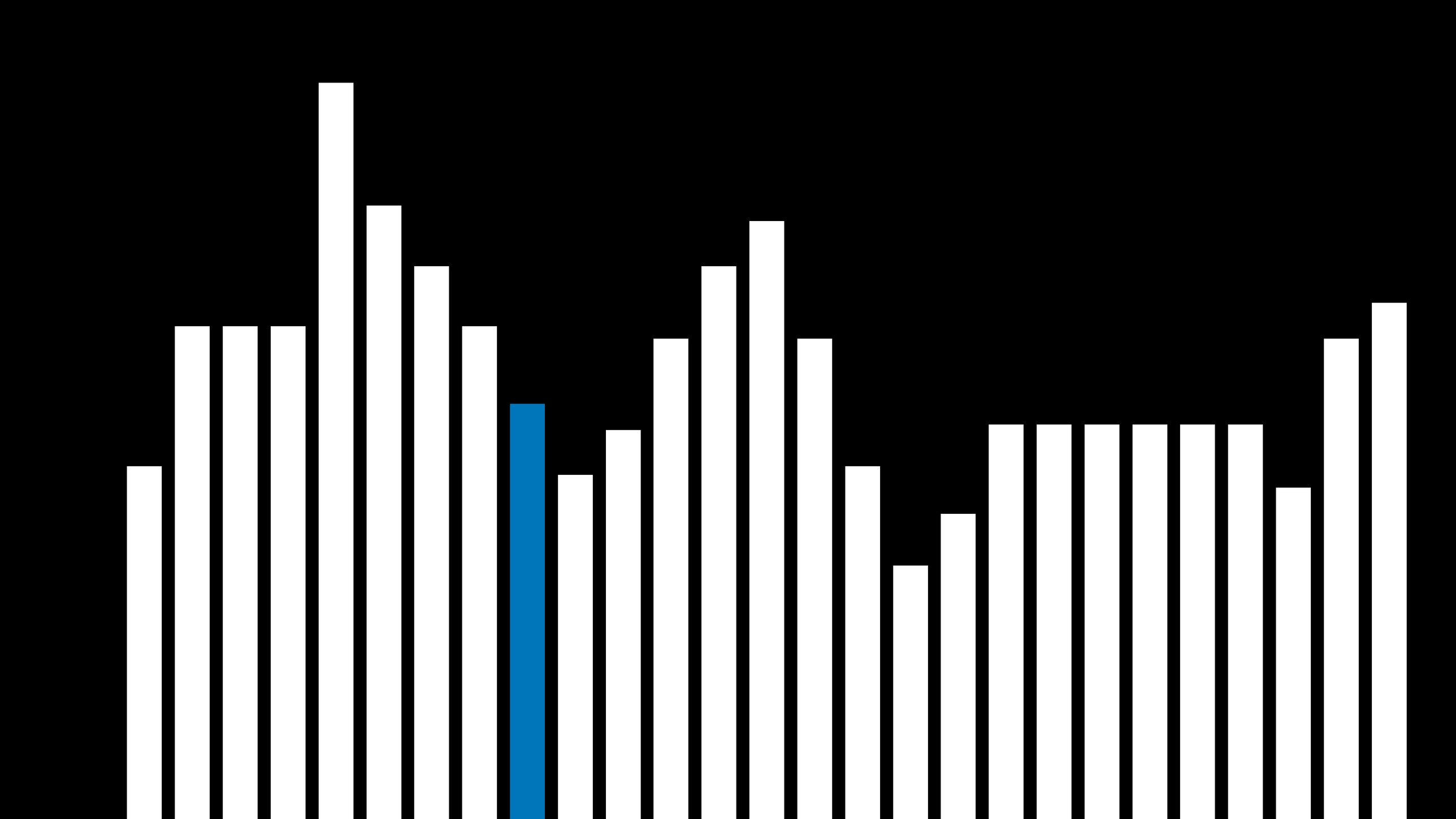
Variant	Definition
steepest-ascent	choose the highest-valued neighbor
stochastic	choose randomly from higher-valued neighbors
first-choice	choose the first higher-valued neighbor
random-restart	conduct hill climbing multiple times
local beam search	chooses the *k* highest-valued neighbors

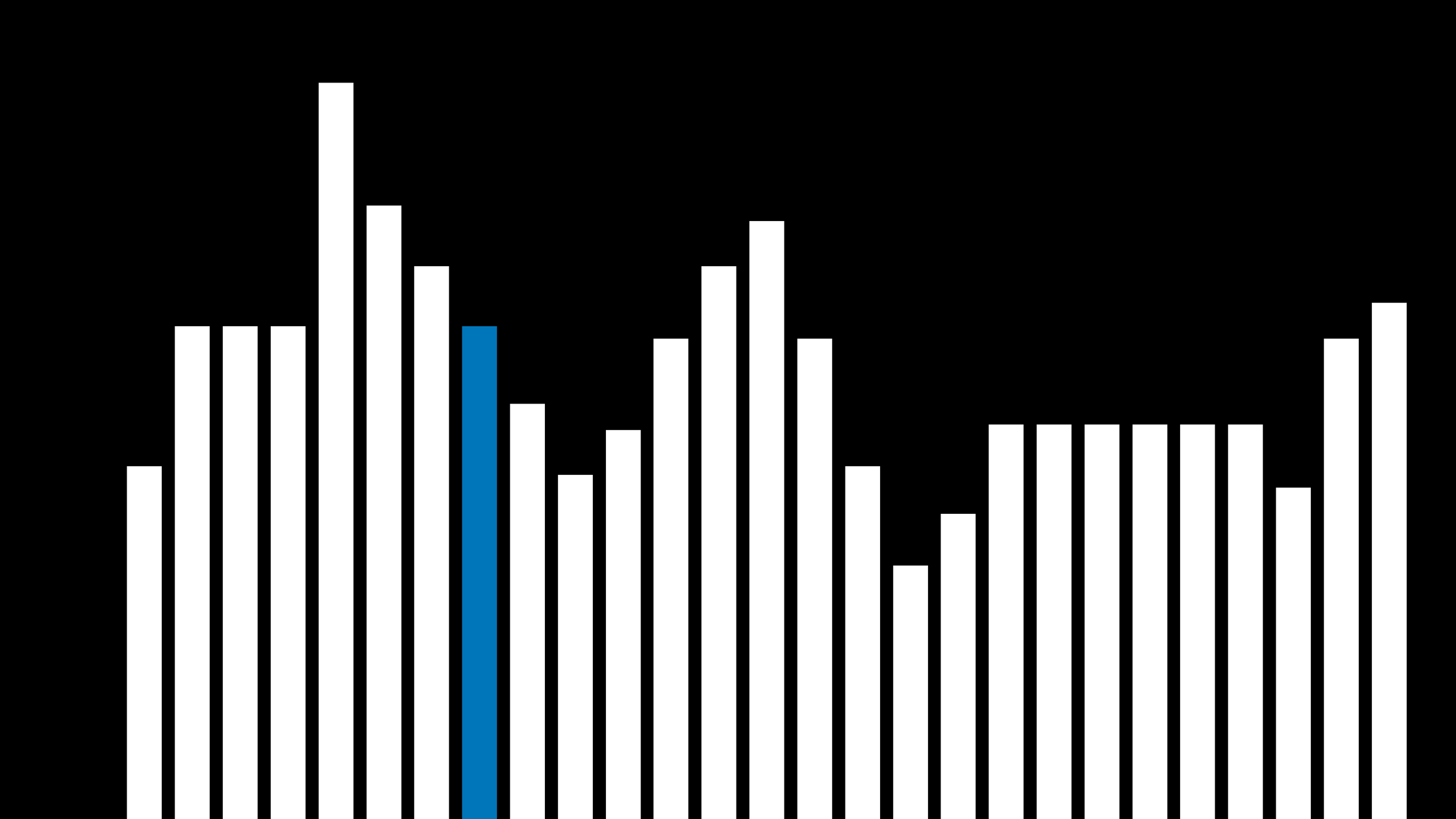
Simulated Annealing

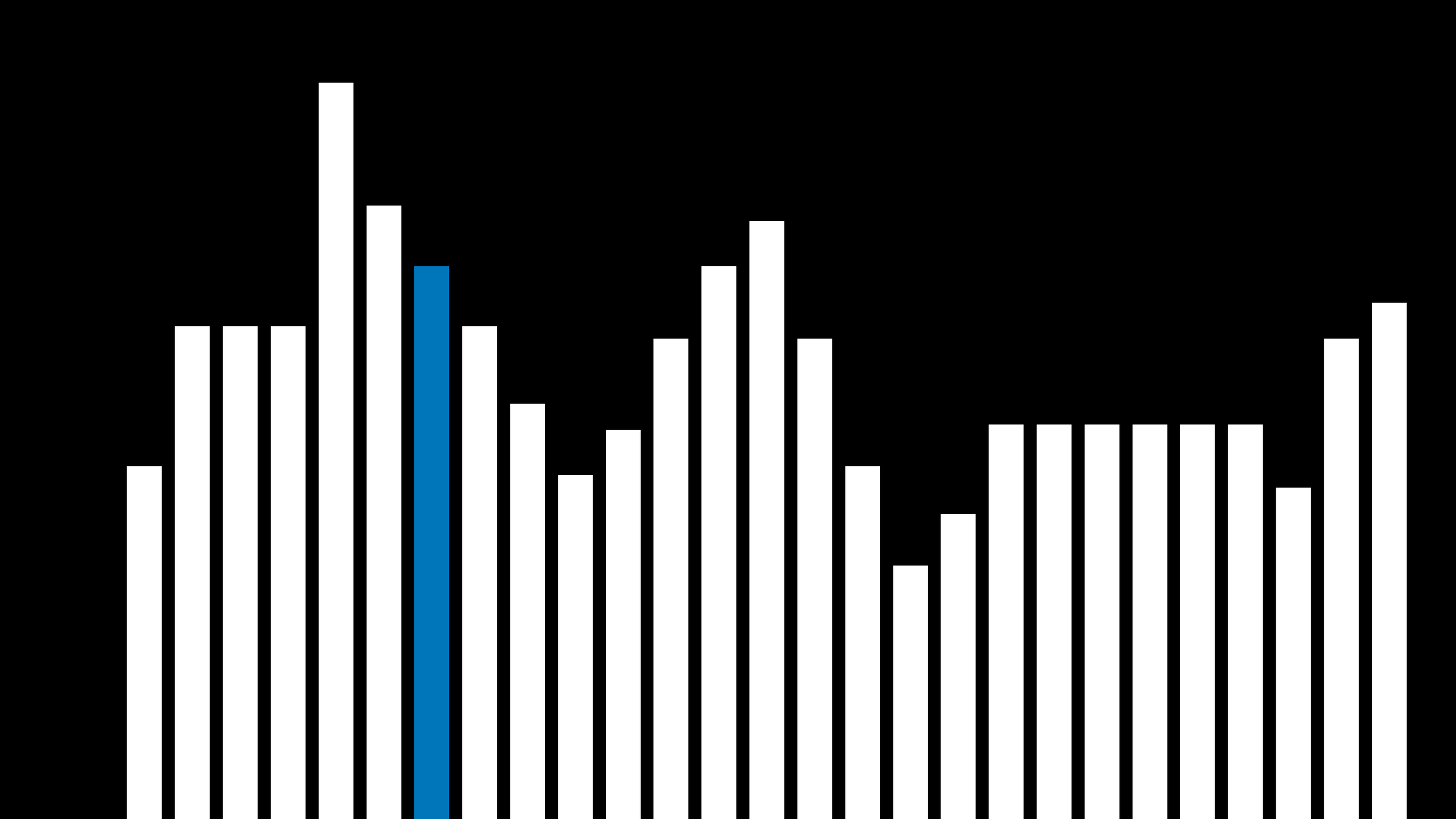


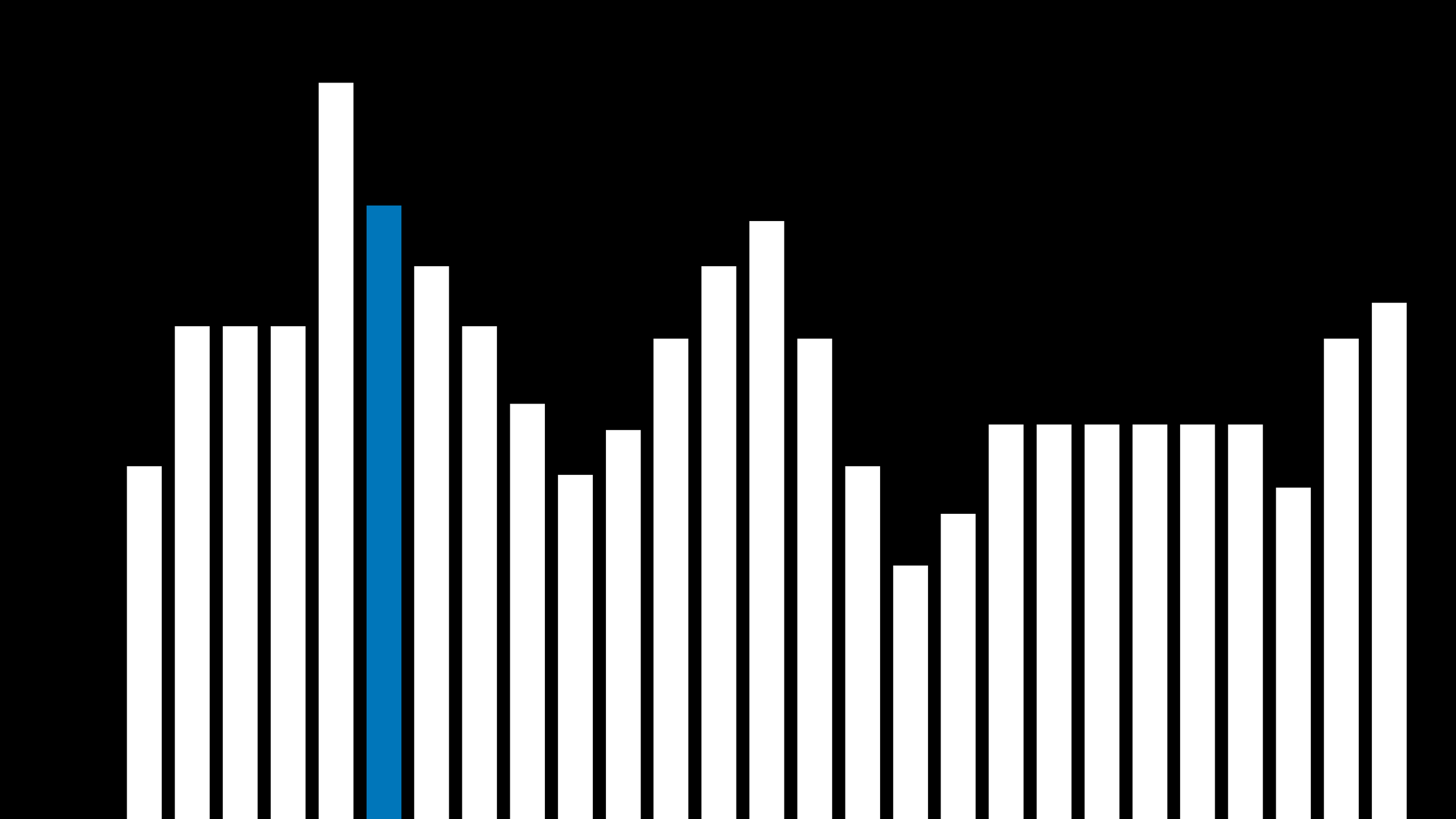


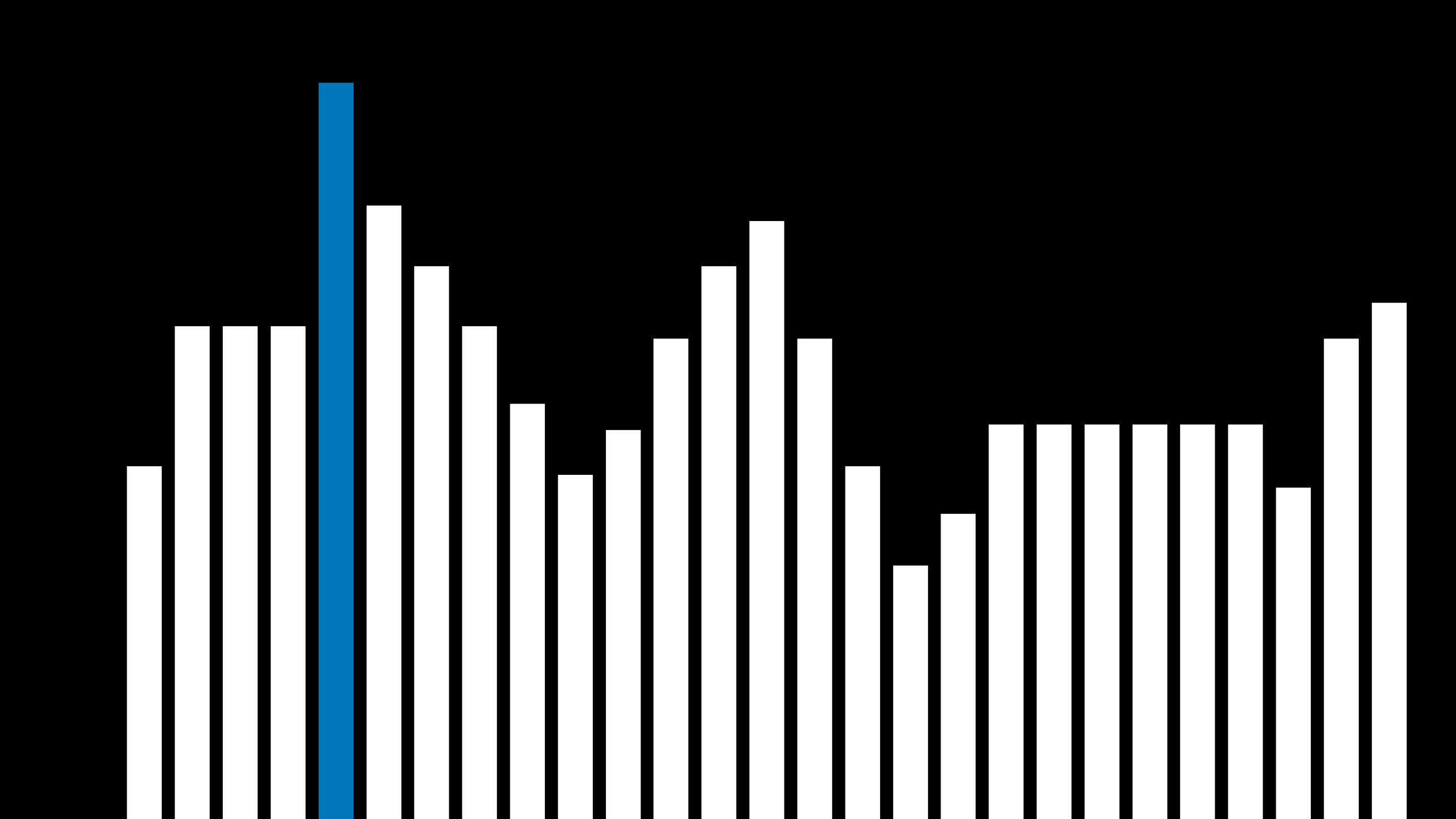












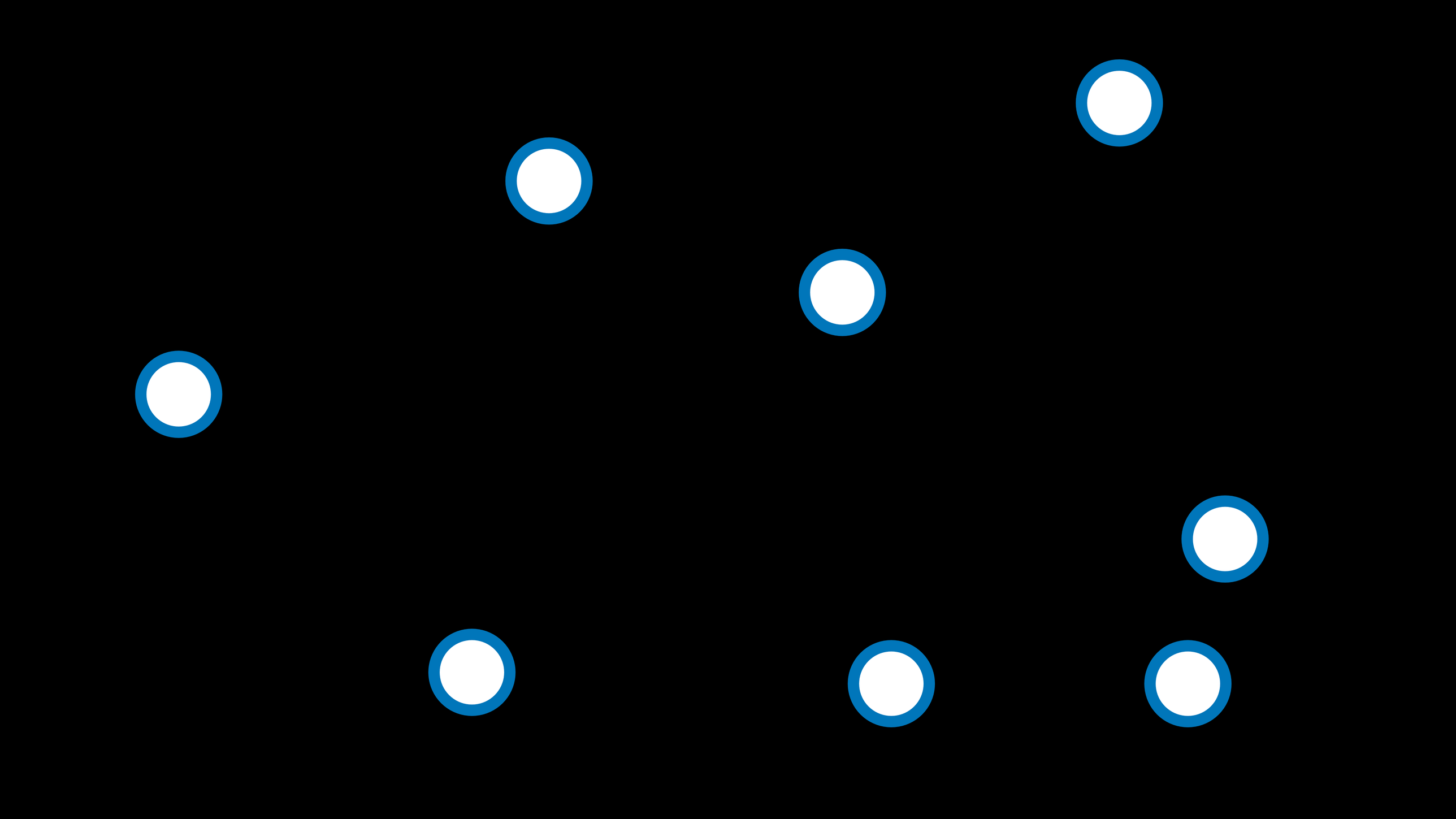
Simulated Annealing

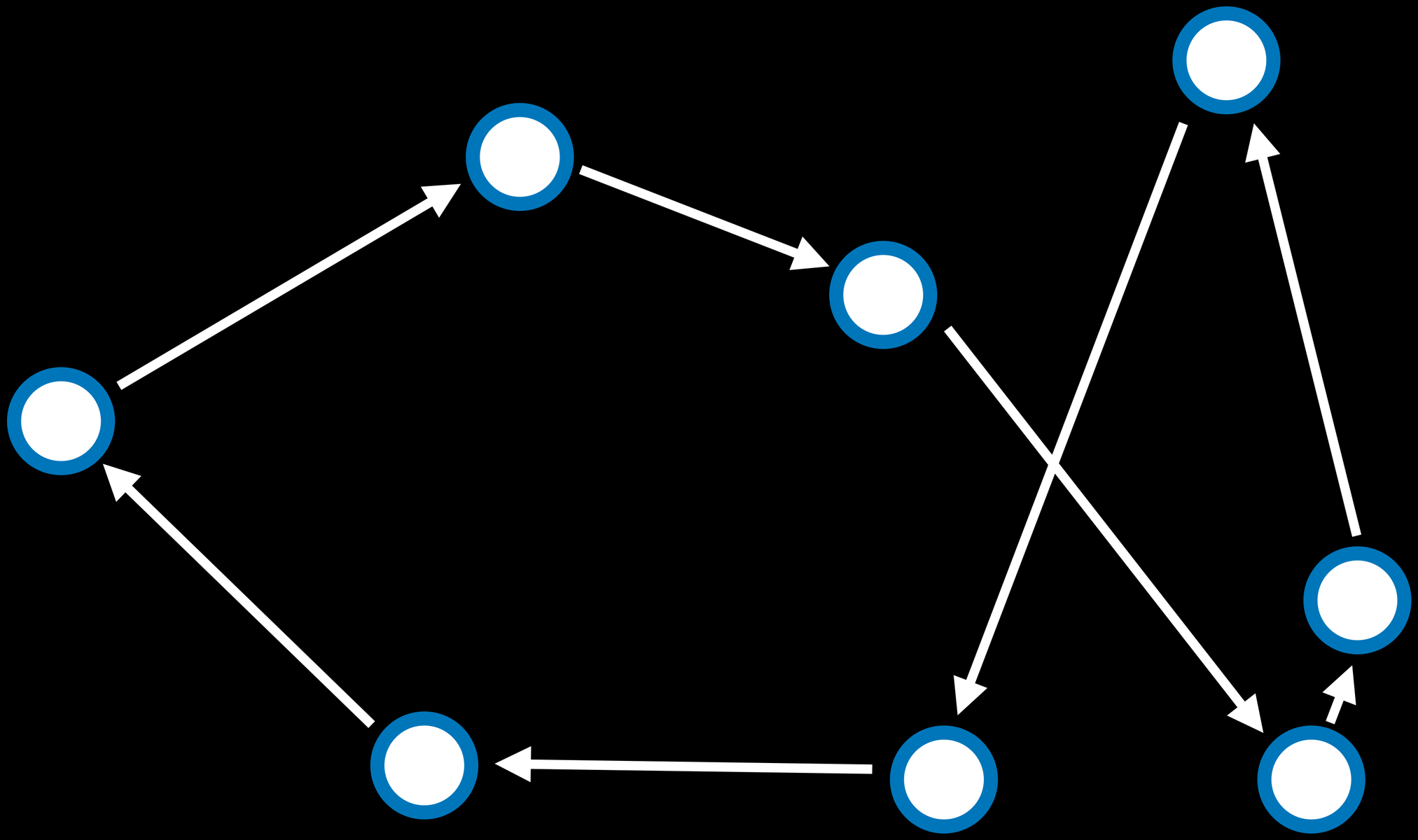
- Early on, higher "temperature": more likely to accept neighbors that are worse than current state
- Later on, lower "temperature": less likely to accept neighbors that are worse than current state

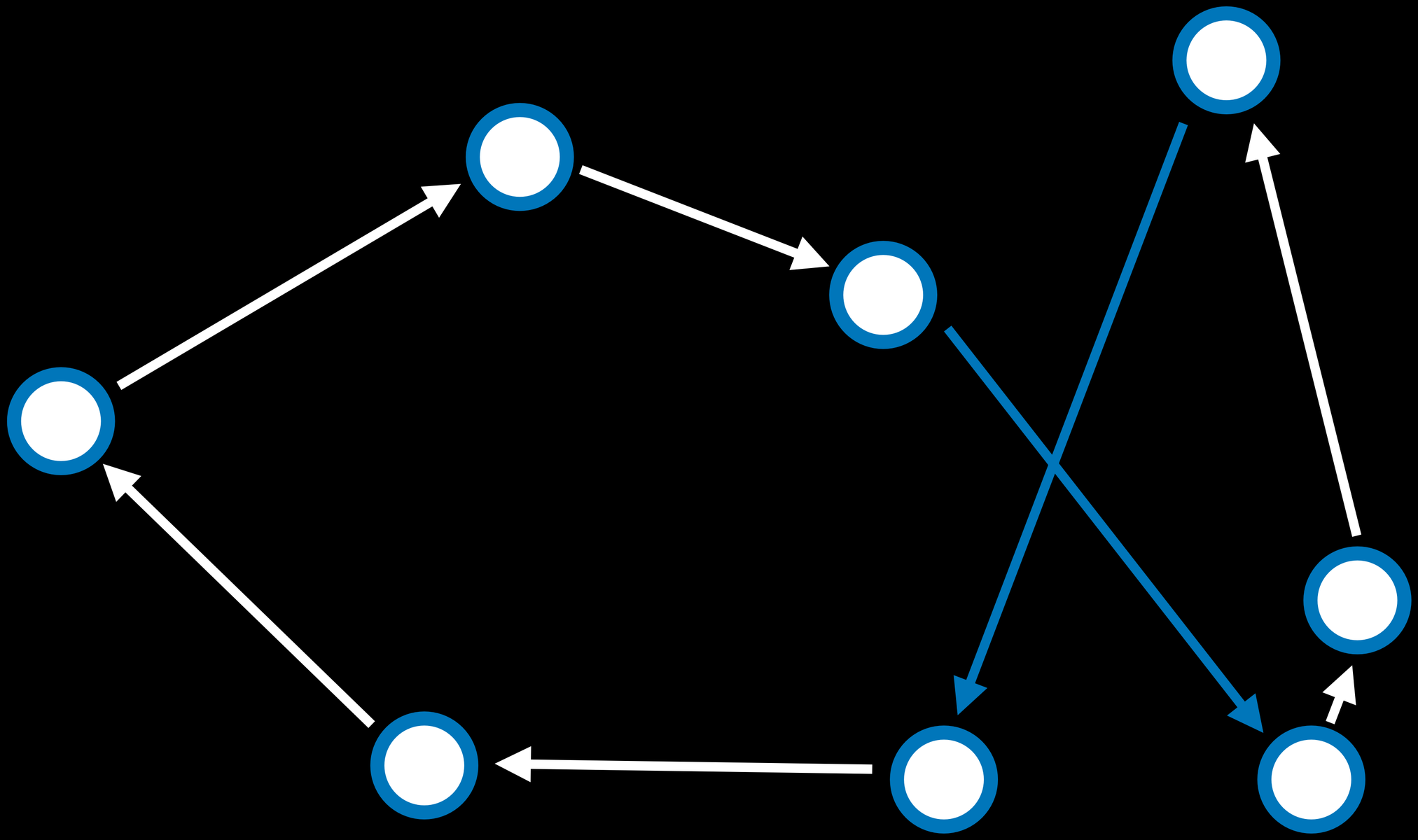
Simulated Annealing

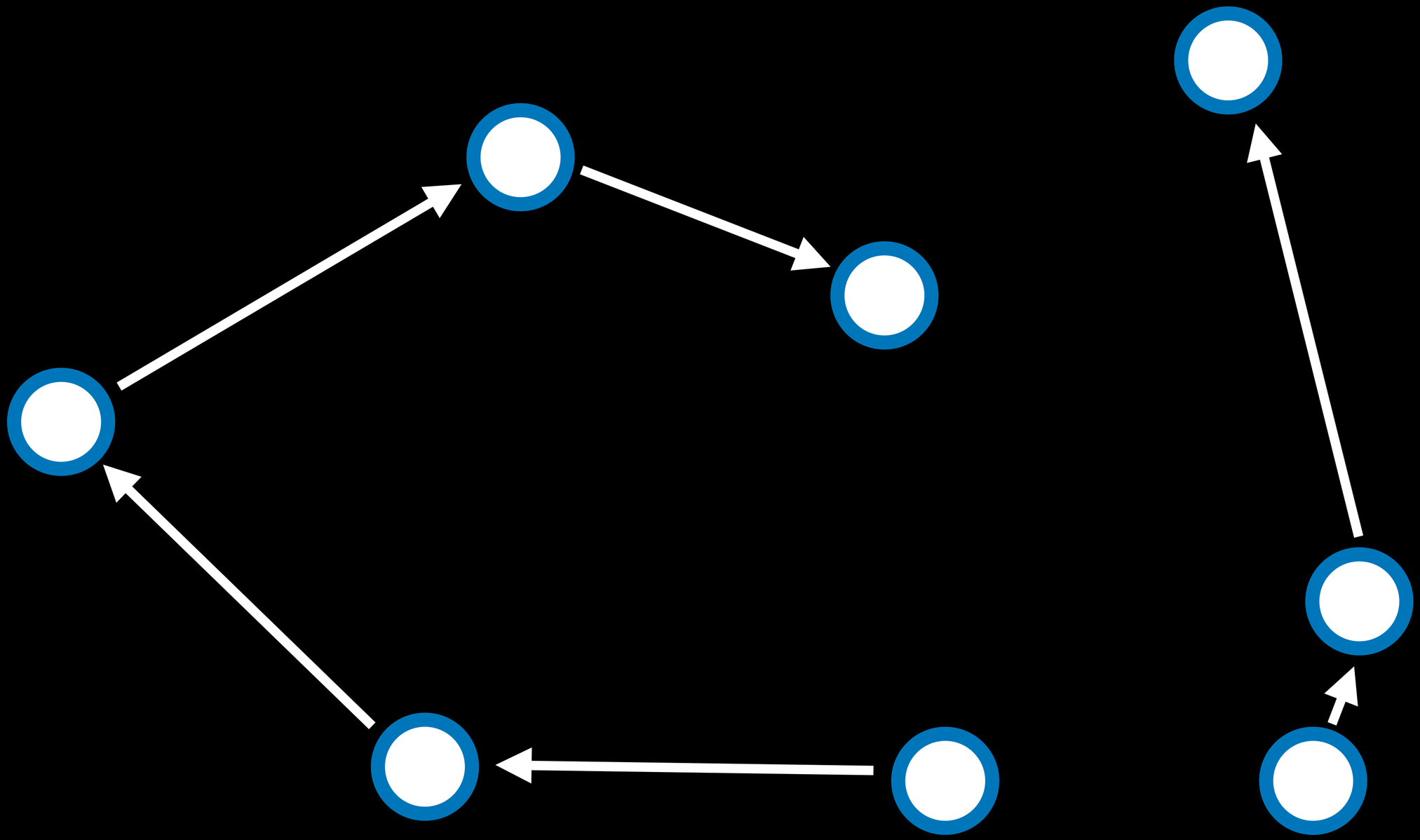
function SIMULATED-ANNEALING(*problem*, *max*):
    current = initial state of *problem*
    for *t* = 1 to *max*:
        T = TEMPERATURE(*t*)
        neighbor = random neighbor of *current*
        ΔE = how much better *neighbor* is than *current*
        if $\Delta E > 0$:
            current = *neighbor*
        with probability $e^{\Delta E/T}$ set *current* = *neighbor*
    return *current*

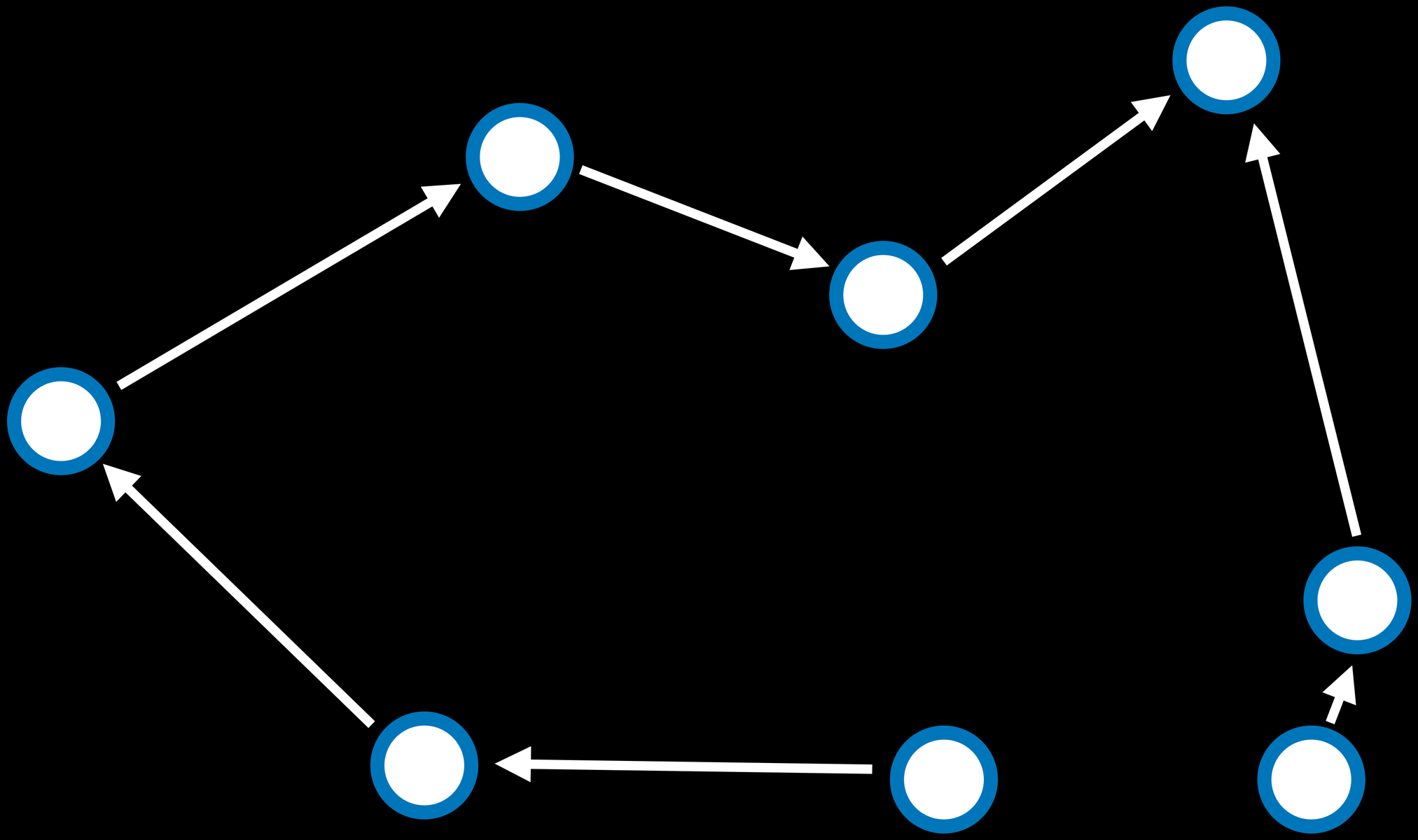
Traveling Salesman Problem

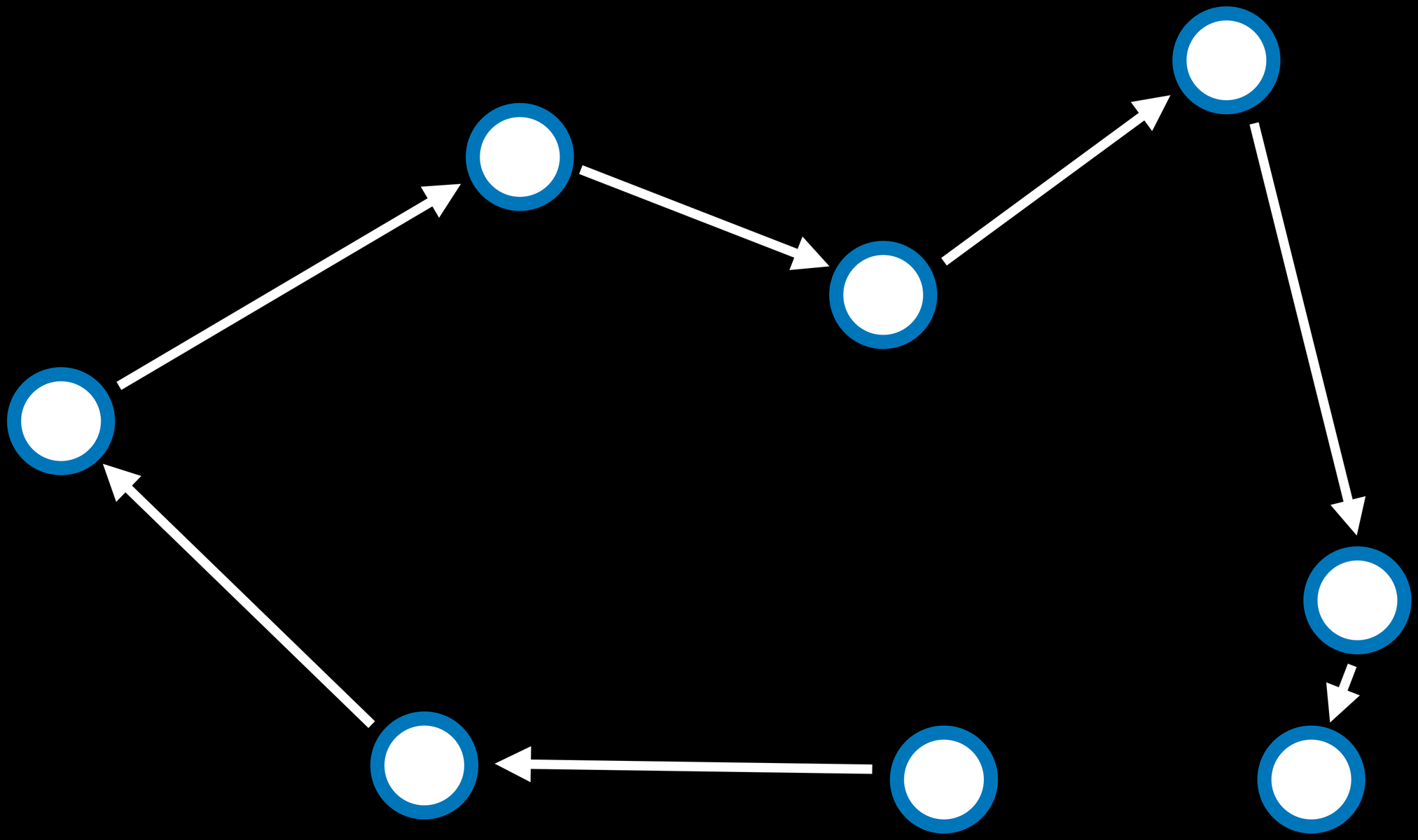


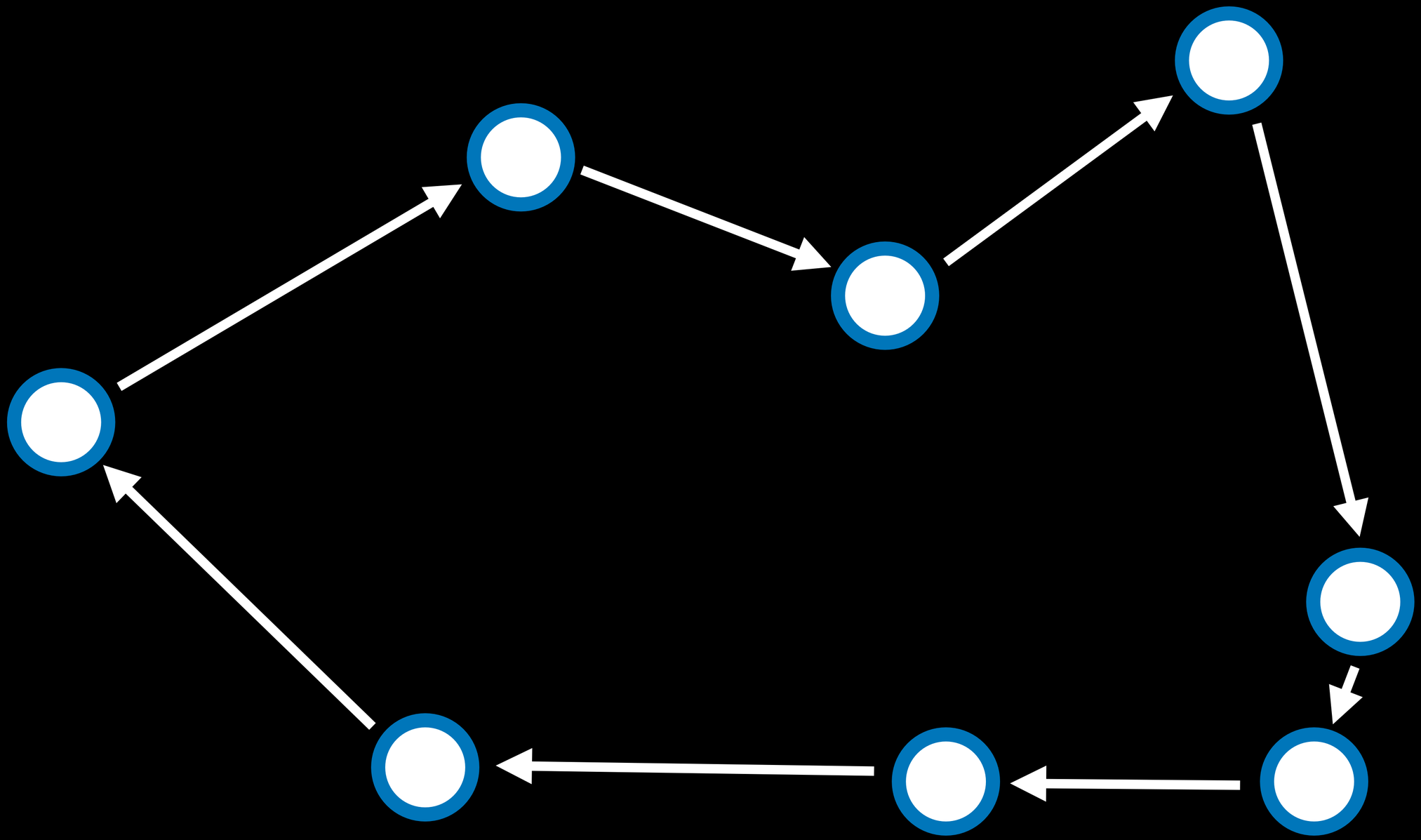












Optimization

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