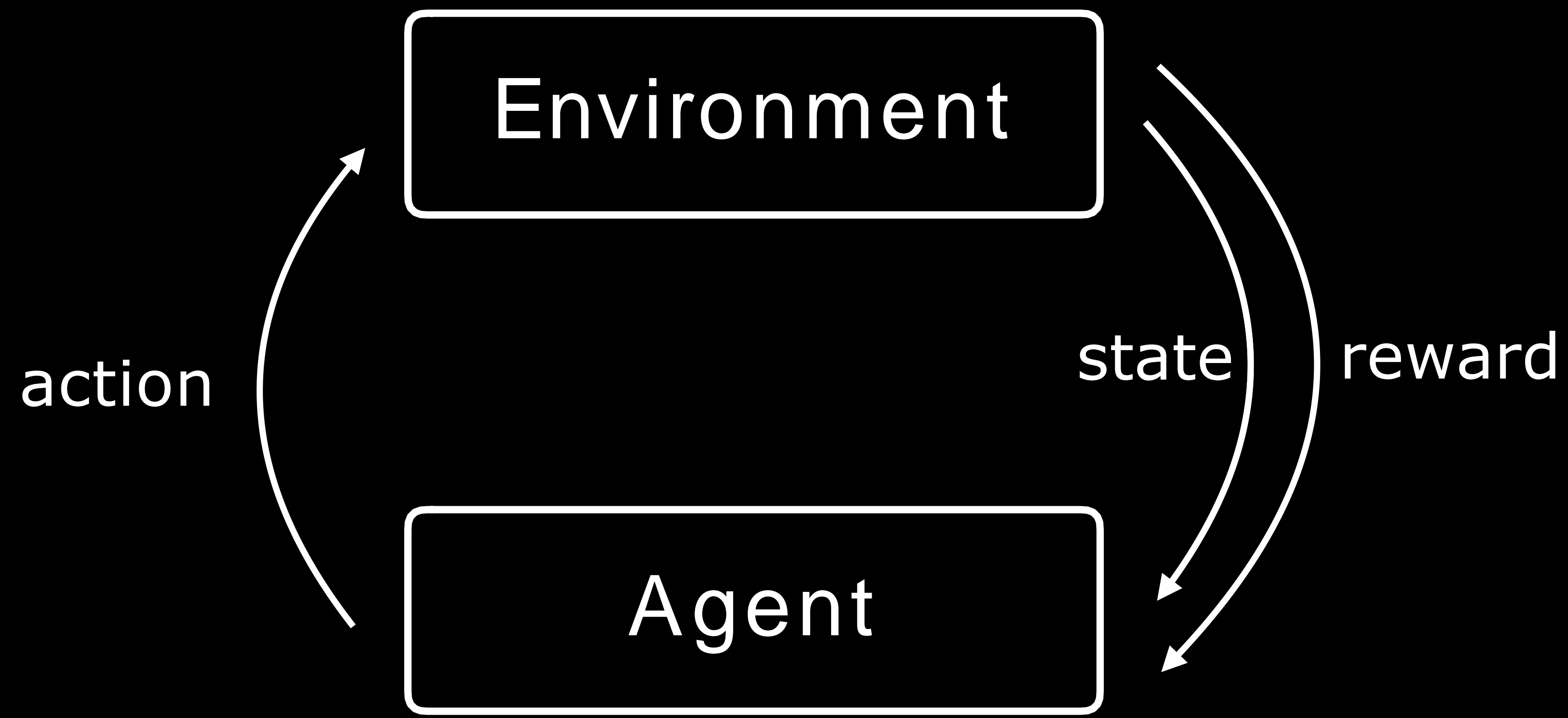
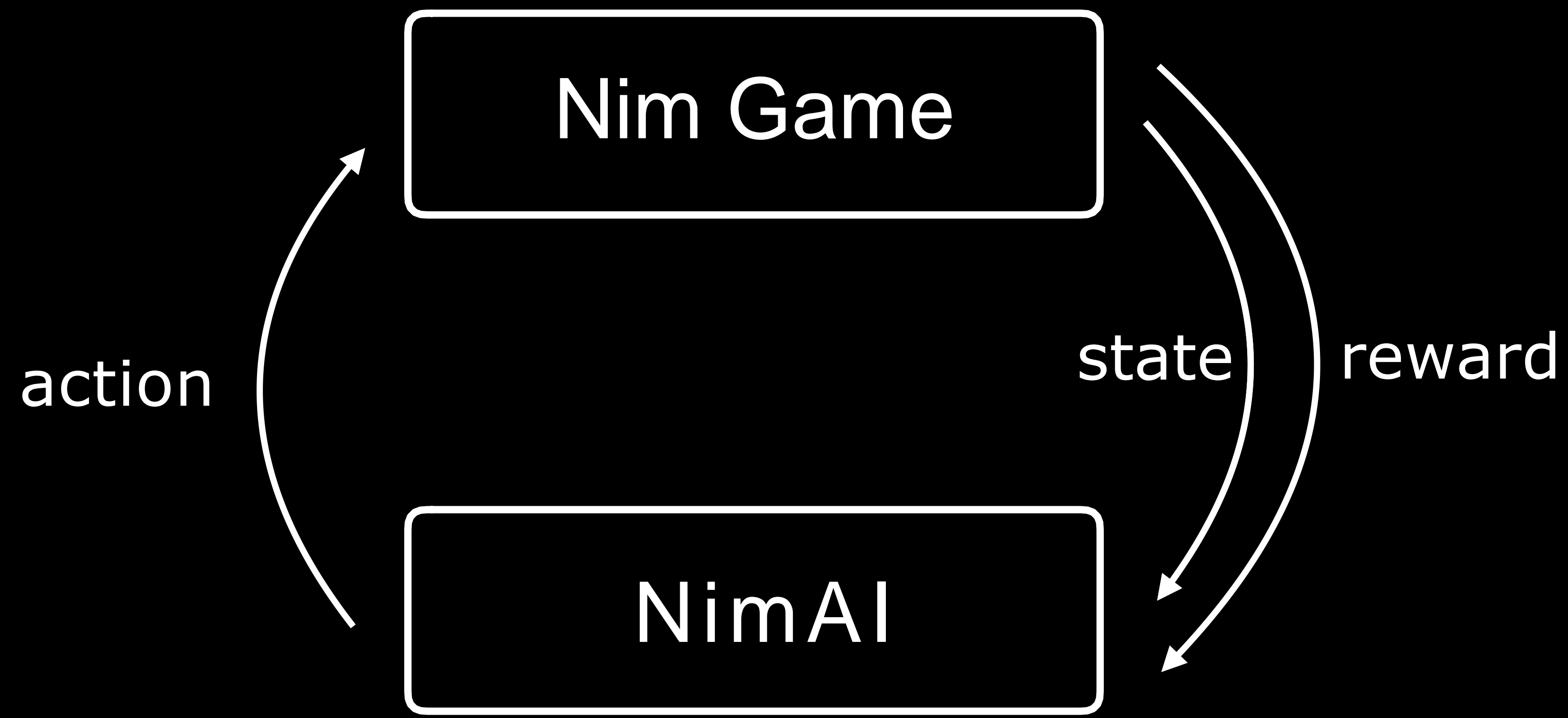


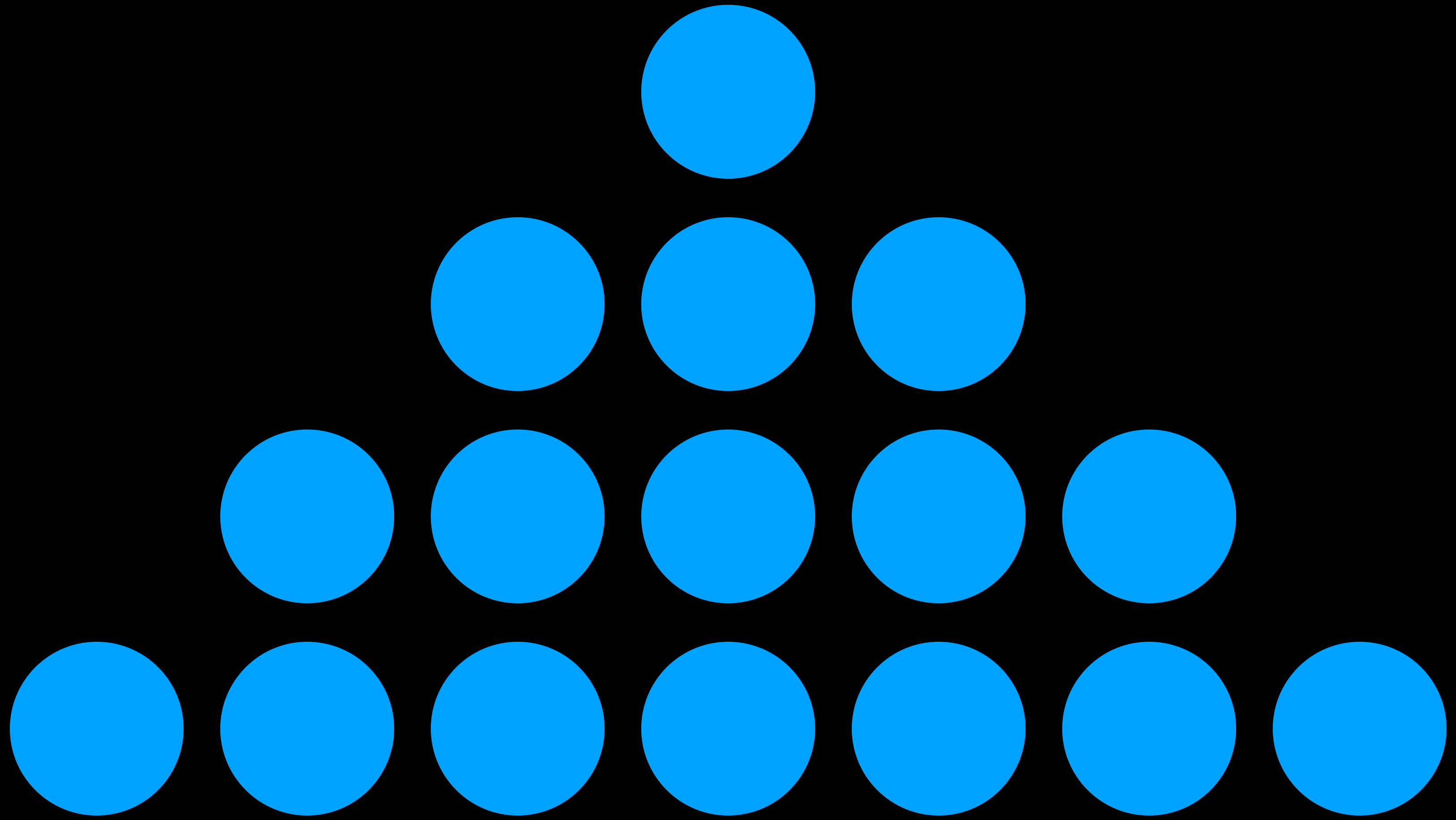
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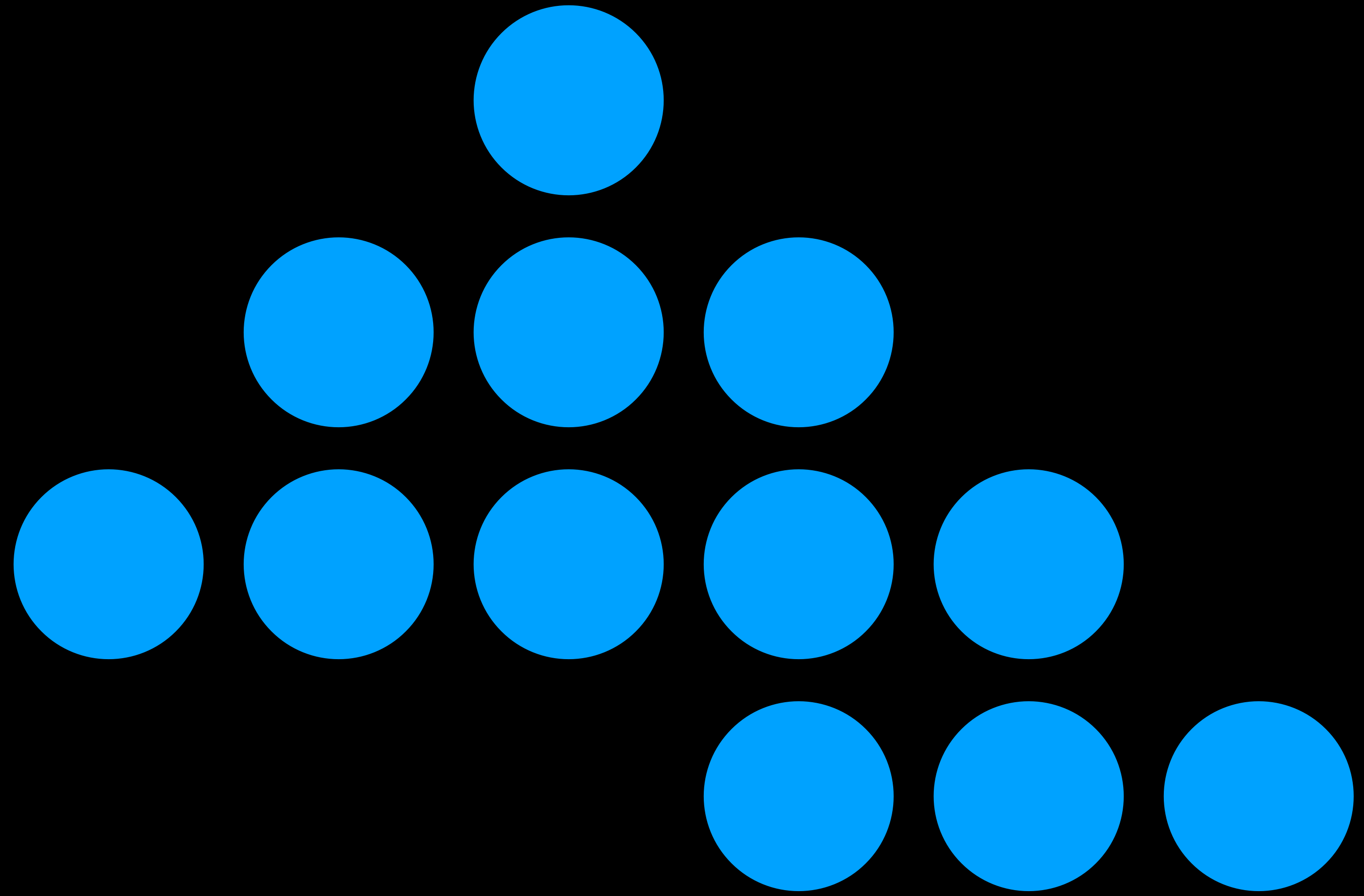
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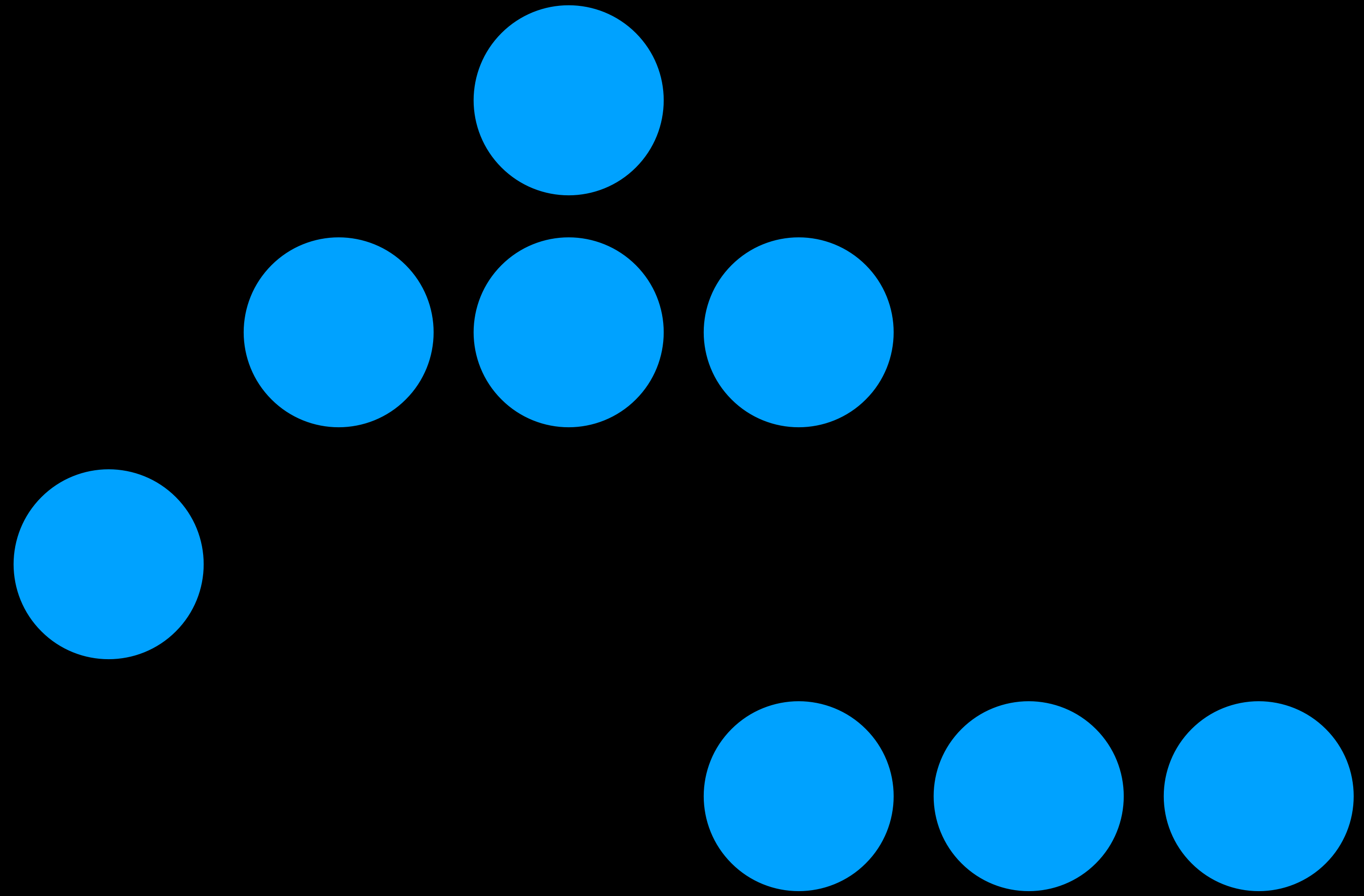


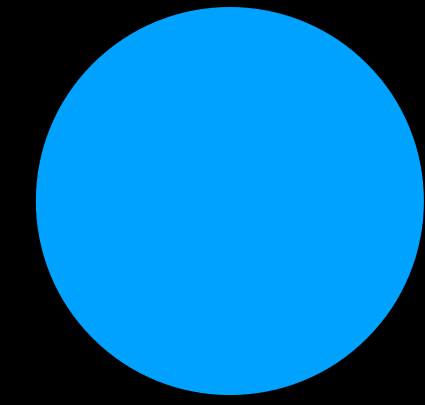
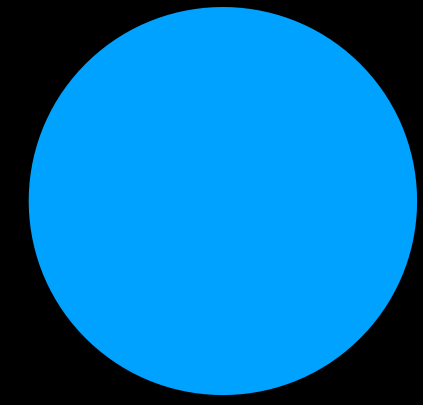
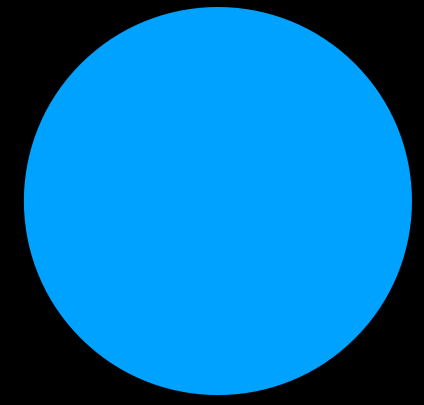
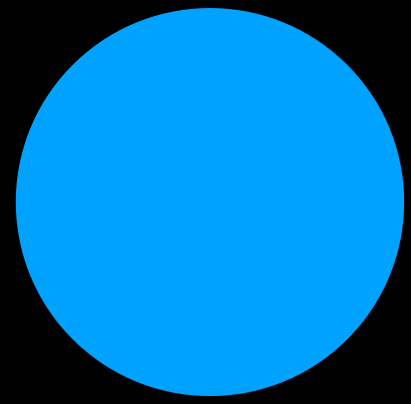
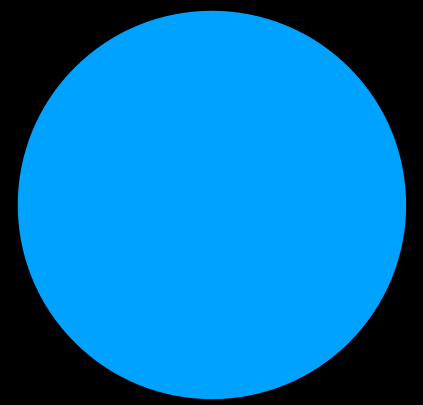
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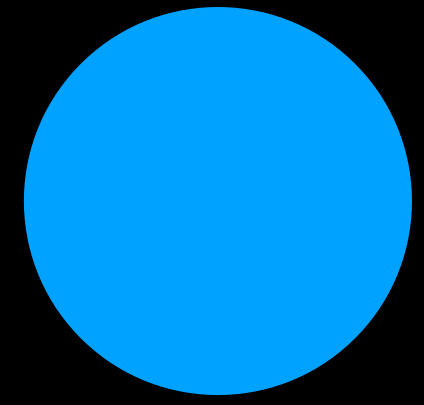
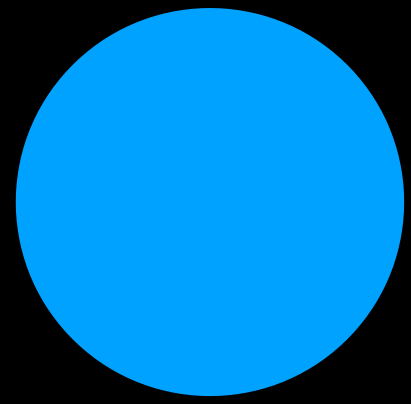
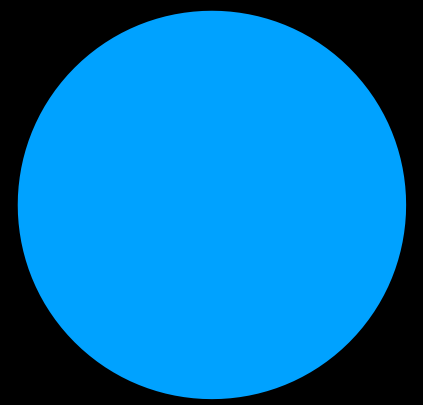


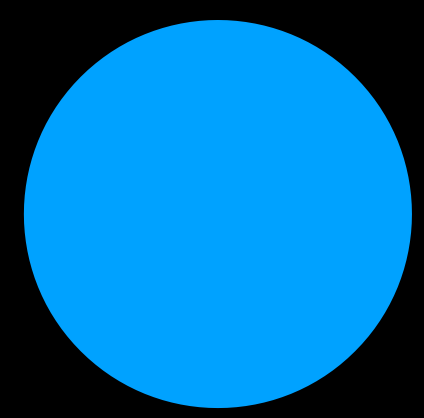
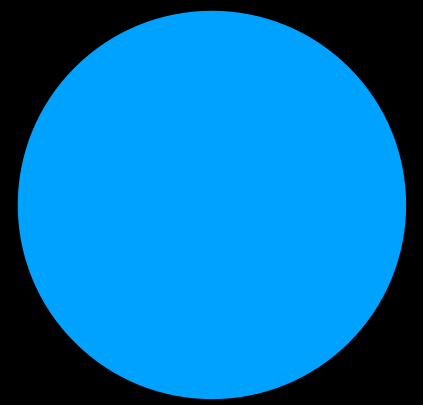


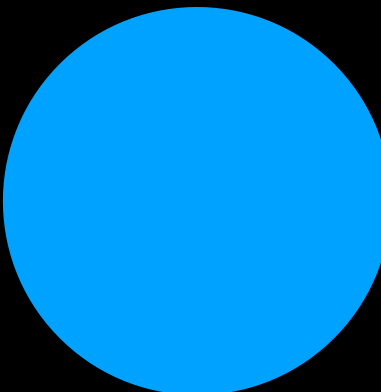








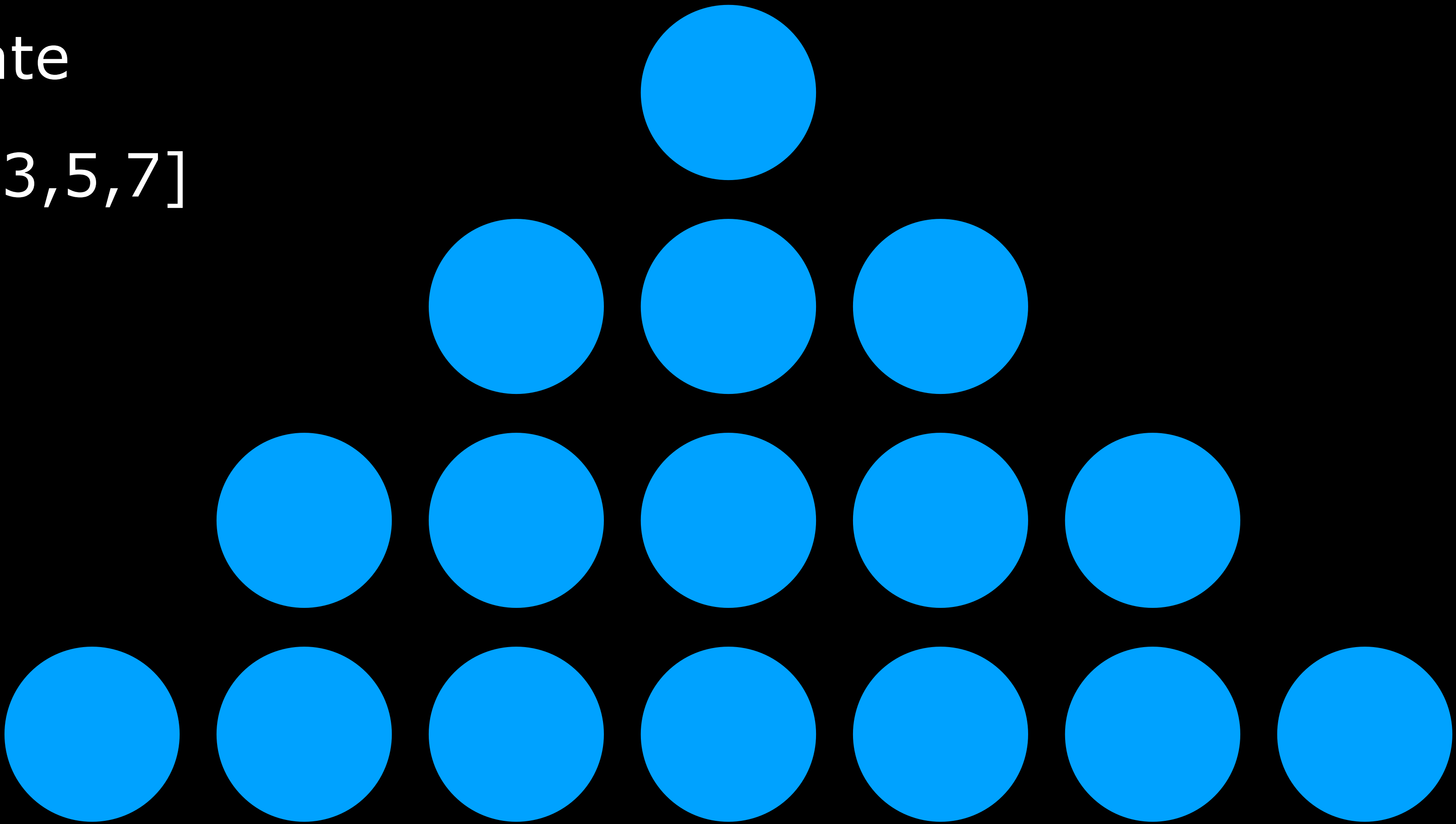




Data Model

State

[1,3,5,7]



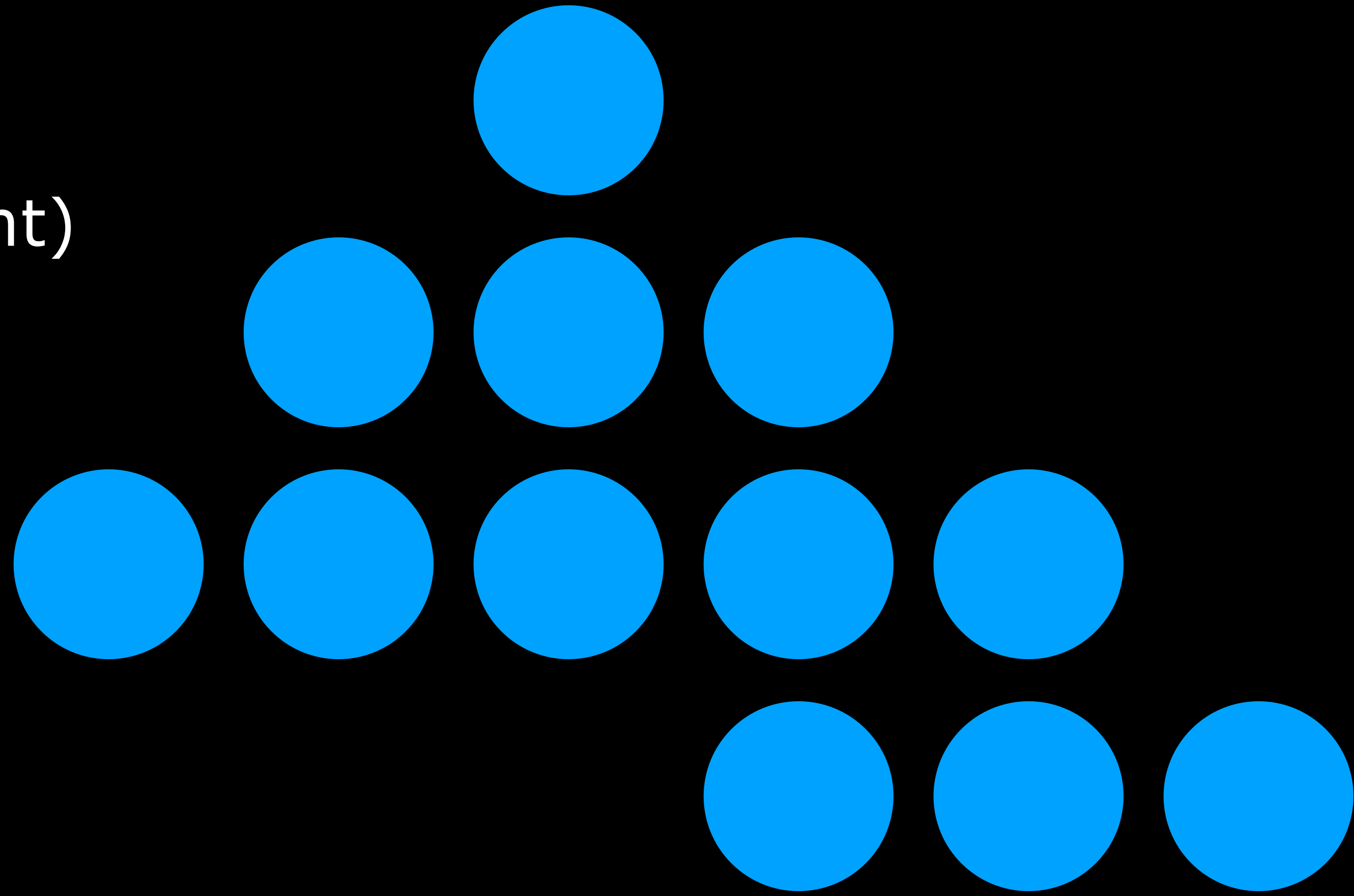
Action

(3,4)

(pile, count)

State

[1,3,5,3]



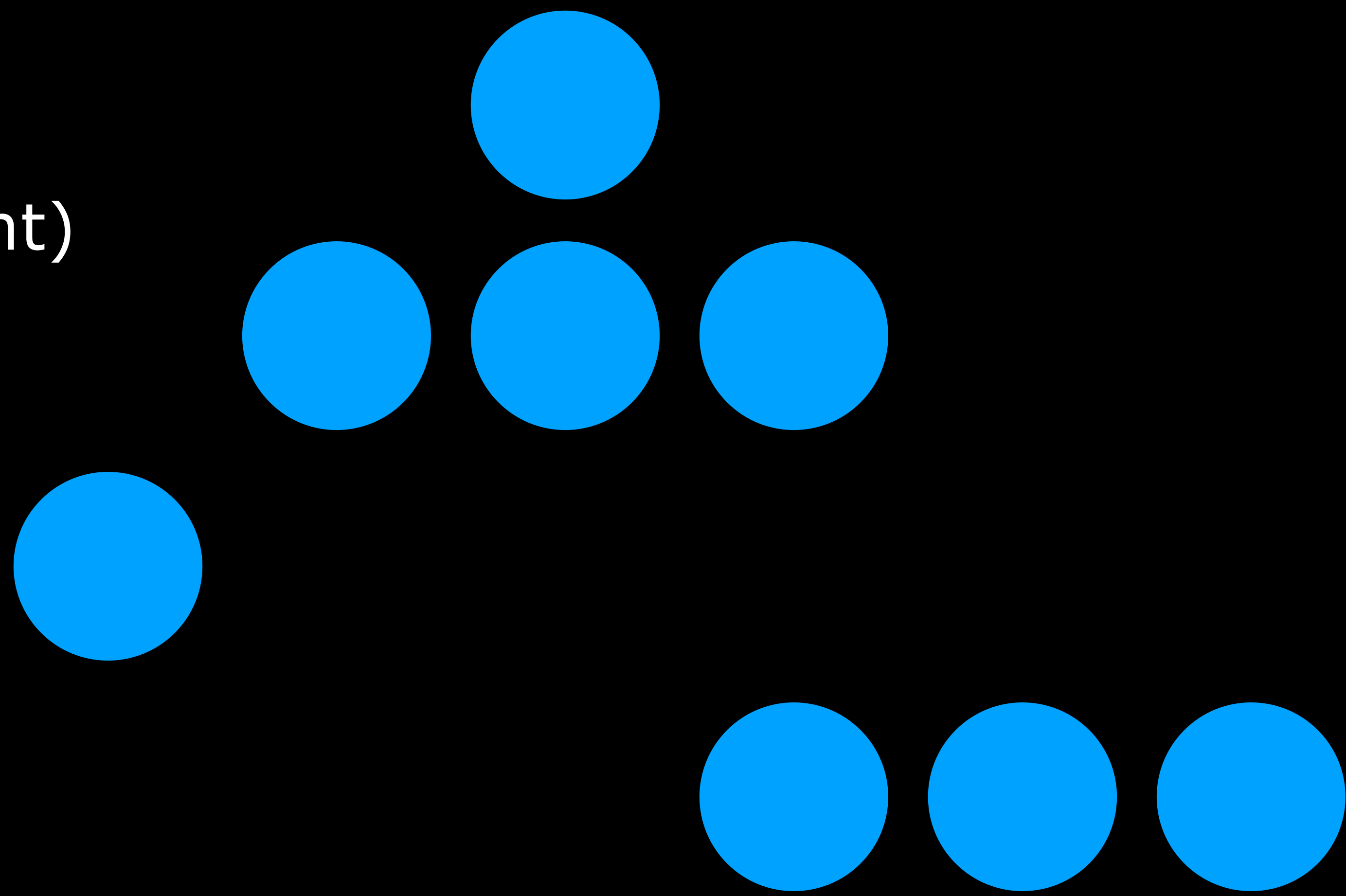
Action

(2,4)

(pile, count)

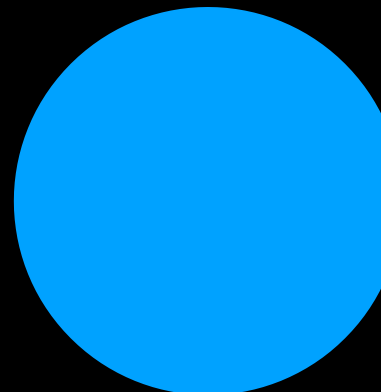
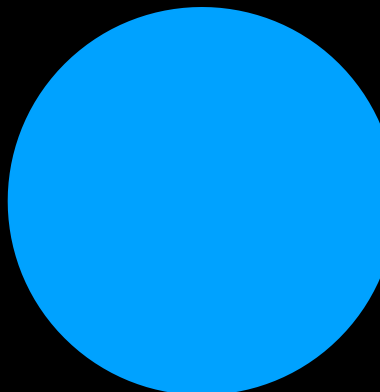
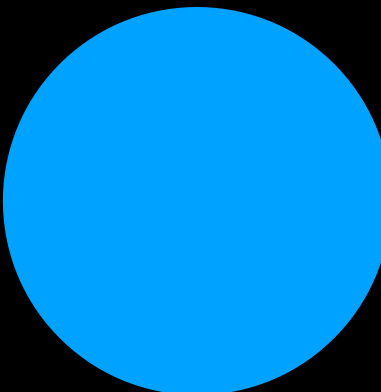
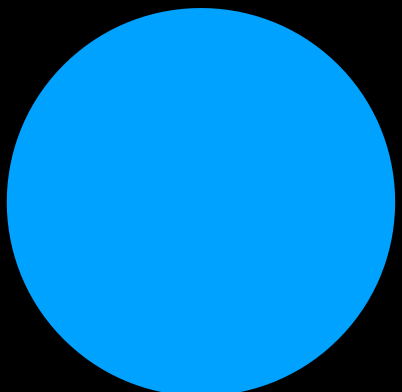
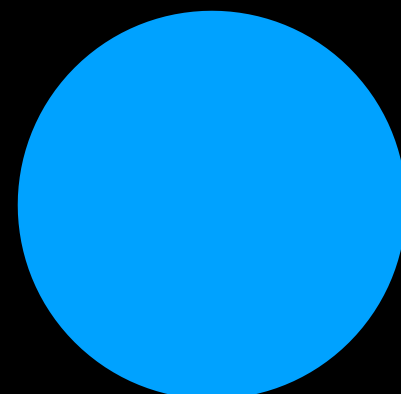
State

[1,3,1,3]



Possible Actions

- (0,1)
- (3,1)
- (3,1)
- (3,2)
- (3,3)



Reward

(state, action) : q value

((1,0,0,1,3), (4,2)) : 0.75

Reinforcement Learning

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