# **Can Large Language Models Infer Causation from Correlation?**

Zhijing Jin<sup>1,2,\*</sup> Jiarui Liu<sup>3</sup> Zhiheng Lyu<sup>4</sup> Spencer Poff<sup>5</sup>

Mrinmaya Sachan<sup>2</sup> Rada Mihalcea<sup>3</sup> Mona Diab<sup>5,†</sup> Bernhard Schölkopf<sup>1,†</sup>

<sup>1</sup>Max Planck Institute for Intelligent Systems, Tübingen, Germany, <sup>2</sup>ETH Zürich,

<sup>3</sup>University of Michigan, <sup>4</sup>University of Hong Kong, <sup>5</sup>Meta AI

# **Abstract**

Causal inference is one of the hallmarks of human intelligence. While the field of CausalNLP has attracted much interest in the recent years, existing causal inference datasets in NLP primarily rely on discovering causality from empirical knowledge (e.g. commonsense knowledge). In this work, we propose the first benchmark dataset to test the pure causal inference skills of large language models (LLMs). Specifically, we formulate a novel task CORR2CAUSE, which takes a (set of) correlational statements and determines the causal relationship between the variables. We curate a large-scale dataset of more than 400K samples, on which we evaluate seventeen existing LLMs. Through our experiments, we identify a key shortcoming of LLMs in terms of their causal inference skills, and show that these models achieve almost close to random performance on the task. This shortcoming is somewhat mitigated when we try to re-purpose LLMs for this skill via finetuning, but we find that these models still fail to generalize – they can only perform causal inference in in-distribution settings when variable names and textual expressions used in the queries are similar to those in the training set, but fail in out-of-distribution settings generated by perturbing these queries. CORR2CAUSE is a challenging task for LLMs, and would be helpful in guiding future research on improving LLMs' pure reasoning skills and generalizability.<sup>1</sup>

# 1 Introduction

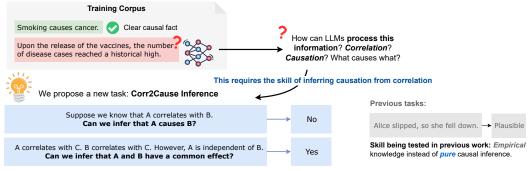
Causal inference is a crucial reasoning ability of human intelligence. It is a fundamental aspect of reasoning that involves establishing the correct causal relationships between variables or events. Roughly, there are two distinct ways to obtain causality: one through empirical knowledge, e.g., we know from common sense that preparing a birthday party for a friend will make them happy; the other through *pure causal reasoning*, as causality can be formally argued and reasoned about using known procedures and rules from causal inference (Spirtes et al., 2000; Pearl, 2009; Peters et al., 2017). For example, we know that only knowing that A correlates with B does not mean that A causes B. We also know another property from pure causal inference, specifically the study of causal discovery (Spirtes et al., 2000; Spirtes and Zhang, 2016; Glymour et al., 2019), that if A and B are originally independent of each other, but become correlated given C, then we can infer that, in this closed system, C is a common effect of A and B, as illustrated in Figure 1. This collider phenomenon can be used to deny the causation between A and B, regardless of what realizations the variables A, B, and C take.

We formulate this task as a new task for NLP, namely *correlation-to-causation inference* (CORR2CAUSE), and argue that this is a must-have skill for large language models (LLMs). Imagine

<sup>\*</sup>This work originated during Zhijing's internship at Meta AI. Email: jinzhi@ethz.ch.

<sup>†</sup>Equal supervision.

Our data is at https://huggingface.co/datasets/causalnlp/corr2cause. Our code is at https://github.com/causalNLP/corr2cause.



\*Assumption that we explicitly mention in the samples: We suppose a close system of the given variables and correlations.

Figure 1: Illustration of the motivation behind our task and dataset.

the scenario in Figure 1, where in the training corpus there are a large number of correlations, such as the word *vaccine* correlating with an increased number of disease cases. If we take the position that the success of LLMs (Radford et al., 2019; Devlin et al., 2019; Ouyang et al., 2022; Zhang et al., 2022; OpenAI, 2023, *inter alia*) lies in capturing a vast set of statistical correlations among terms (Bender et al., 2021), then the crucial yet missing step is *how to process such correlations* and infer causal relationships, for which a fundamental building block is this CORR2CAUSE inference skill.

To this end, we collect the first dataset, CORR2CAUSE, to test the pure causal reasoning abilities of large language models. All the questions in this dataset are centered around testing when it is valid or invalid to infer causation from correlation. To systematically compose this dataset, we ground our generalization process in the formal framework of causal discovery (Spirtes et al., 1993, 2000; Glymour et al., 2016; Spirtes and Zhang, 2016; Glymour et al., 2019), which provides rules about how to deduce causal relations among variables given their statistical correlation in the observational data. We generate more than 400K data points, and label a correlation-causation statement pair as valid if and only if there is a bijective mapping between the statistical correlation and the underlying causality.

Based on our CORR2CAUSE dataset with 400K samples, we investigate two main research questions: (1) How well do existing LLMs perform on this task? (2) Can existing LLMs be re-trained or re-purposed on this task and obtain robust causal inference skills? Through extensive experiments, we show empirically that none of the seventeen existing LLMs we investigate perform well on this pure causal inference task. We also show that although LLMs can demonstrate better performance after being finetuned on the data, the causal inference skills attained by them are not robust. In summary, our contributions are as follows:

- 1. We propose the novel task of CORR2CAUSE, to probe an aspect of LLMs reasoning ability, *pure causal inference*;
- 2. We compose a dataset of over 400K samples, using insights from causal discovery;
- 3. We evaluate the performance of seventeen LLMs on our dataset, finding that all of them perform poorly, close to the random baseline.
- 4. We further explored whether LLMs can learn the skill through finetuning, and find that but LLMs fail to robustly manage the skill with out-of-distribution perturbations, and suggest future work to explore more ways to enhance the pure causal inference skill in LLMs.

# 2 Preliminaries: Causal Inference

# 2.1 Directed Graphical Causal Models (DGCMs)

A directed graphical causal model (DGCM) is a commonly used representation to express the causal relations among a set of variables. Given a set of N variables  $\mathbf{X} = \{X_1, \dots, X_N\}$ , we can encode the causal relations among them using a directed graph  $\mathcal{G} := (\mathbf{X}, \mathbf{E})$ , where  $\mathbf{E}$  is the set of directed edges. Each edge  $e_{i,j} \in \mathbf{E}$  represents a causal link  $X_i \to X_j$ , meaning that  $X_i$  is a direct cause of  $X_j$ . In the context of this work, we take the common assumption of directed acyclic graphs (DAGs), which most causal discovery methods use (Glymour et al., 2019), as graphs with cycles can make the causal discovery process arbitrarily hard.

Following the graph-theoretic terminology, we use an analogy of the ancestry tree to denote the relations between two variables. For example, we call  $X_i$  as a parent of  $X_j$  if there is a directed edge  $X_i \to X_j$  in the graph, and, thus,  $X_j$  is a child of  $X_i$ . Similarly, we denote  $X_i$  as an ancestor of  $X_j$  if there exists a directed path from  $X_i$  to  $X_j$ , and, thus,  $X_j$  is a descendent of  $X_i$ . Note that a parent is a special case of an ancestor where the directed path has a length of 1.

For convenience, we also introduce the notions for some special three-variable relations. Given two variables  $X_i$  and  $X_j$ , we call a third variable  $X_k$  a confounder (i.e., common cause) if  $X_k$  is a parent of both  $X_i$  and  $X_j$ ; a collider (i.e., common effect) if  $X_k$  is a child of both  $X_i$  and  $X_j$ ; and a mediator if  $X_k$  is both a child of  $X_i$ , and a parent of  $X_j$ .

# 2.2 D-Separation and Markov Property

**D-Separation** D-separation (Pearl, 1988) is a fundamental concept in graphical models used to determine whether two sets of nodes X and Y in a DAG  $\mathcal G$  are conditionally independent given a third set of nodes Z, where the three sets are disjoint. We say that X and Y are d-separated by Z if all paths between any node in X and any node in Y are blocked by the conditioning set Z. A path between X and Y is blocked by Z if there exists a node  $A \in Z$  which satisfies one of the following conditions: A is the parent node in a fork structure on the path (i.e.,  $\cdot \leftarrow A \rightarrow \cdot$ ); A is the mediator node in a chain structure on the path (i.e.,  $\cdot \rightarrow A \rightarrow \cdot$ ); or in any collider structure on the path (i.e.,  $\cdot \rightarrow A \leftarrow \cdot$ ), Z does not contain A or its descendants.

**Markov Property** The Markov property in a DAG  $\mathcal G$  states that each node  $X_i$  is conditionally independent of its non-descendants given its parents, namely  $X_i \perp \operatorname{NonDe}(X_i) | \operatorname{Pa}(X_i)$ , where  $\operatorname{NonDe}(X_i)$  denotes the non-descendants of  $X_i$  excluding itself, and  $\operatorname{Pa}(X_i)$  denotes the parents of  $X_i$ . Using the Markov property, we can factorize the joint distribution of all the nodes in the graph into  $P(X_1,\ldots,X_N) = \prod_{i=1}^N P(X_i|\operatorname{PA}(X_i))$ . To infer the causal graph from probability distributions, a common assumption is faithfulness, namely the validity to infer all the d-separation sets in the graph from the independence relations in the probability distribution. In our work, we also take this broadly taken assumption which holds for most real-world scenarios.

**Markov Equivalence of Graphs** We denote two DAGs as Markov equivalent if they induce the same joint distribution  $P(\boldsymbol{X})$ . The set of DAGs that are Markov equivalent to each other is called a Markov equivalence class (MEC). Causal graphs in the same MEC can be easily identified since they have the same skeleton (i.e., undirected edges) and V-structures (i.e., structures in the form of  $A \to B \leftarrow C$  where A and C are not connected).

Obviously, there is a one-to-many mapping (i.e., surjection) between the causal graph and statistical distribution. Namely, each causal graph sufficiently determines a statistical distribution, but from a statistical distribution, we cannot necessarily induce a unique causal graph. This is why we say "correlation does not necessarily mean causation".

# 2.3 Causal Discovery

Causal discovery aims to learn the causal relations by analyzing statistical properties in the observational data (Spirtes et al., 1993, 2000; Glymour et al., 2016; Spirtes and Zhang, 2016; Glymour et al., 2019). It can be achieved through constraint-based methods (Spirtes et al., 2000), score-based methods (Chickering, 2002), or other methods taking advantage of the functional causal models (Shimizu et al., 2006; Hoyer et al., 2008; Zhang and Hyvärinen, 2009).

To fit for the spirit of this paper to infer from correlation (expressed in natural language) to causation, we base our dataset design on the widely-used Peter-Clark (PC) algorithm (Spirtes et al., 2000). The PC algorithm is based on the principles of conditional independence and the causal Markov assumption, which allows it to efficiently identify causal relationships among variables in a given dataset. The algorithm first starts with a fully connected undirected graph among all the variables. Then it removes the edge between two variables if there is an unconditional or conditional independence relationship between them. Afterwards, it orients the directed edges whenever there is a V-structure. And finally, it iteratively checks the direction of the other edges until the entire causal graph is consistent with all the statistical correlations.

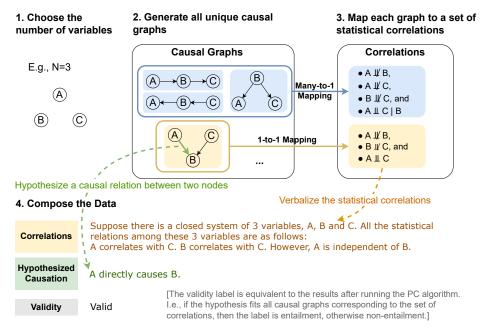


Figure 2: Pipeline of the data construction process.

### 3 Dataset Construction

We introduce the construction of our dataset in this section. We start with our task formulation for CORR2CAUSE, and then briefly give an overview of the data generation process, followed by detailed descriptions of each step. We conclude the section with the overall statistics of the dataset.

#### 3.1 Task Formulation

Given a set of N variables  $X = \{X_1, \ldots, X_N\}$ , we have a statement s about all the correlations among the variables, and a hypothesis h describing the causal relation r between the pair of variables  $X_i$  and  $X_j$ . The task is to learn a function  $f: (s, h) \mapsto v$  which maps the correlation statement s and the causal relation hypothesis h to their validity  $v \in \{0, 1\}$ , which takes the value 0 if this inference is invalid, and the value 1 if this inference is valid.

# 3.2 Overview of the Data Generation Process

We base the construction our dataset on several concepts of causal inference, including the DGCM, d-separation, and MECs, as introduced in Section 2.

As in the overview of our data generation process in Figure 2, we first choose the number N of variables (Step 1) and generate all the unique DGCMs with N nodes (Step 2), which we will introduce in the Section 3.3. Then we collect all the d-separation sets from these graphs to identify MECs (Step 3) in Section 3.4. Then, in Step 4, we create the formal form of data in Section 3.5. For each correspondence of the MEC to causal graphs, we compose the correlation statement based on the statistical relations in the MEC, and hypothesize a causal relation between two variables, and produce the validity v=1 if the hypothesis is a shared property of all causal graphs in the MEC, and v=0 if the hypothesis is not necessarily true for all the MEC graphs. Finally, we introduce the verbalization process in Section 3.6.

#### 3.3 Constructing the Graphs with Isomorphism Checks

The first step of the data generation is to compose the causal graphs, as in Step 1 and 2 of Figure 2. For a set of N variables  $\mathbf{X} = \{X_1, \dots, X_N\}$ , there are N(N-1) possible directed edges, since each node can link to any node other than itself. To remove cycles in the graph, we make the nodes in topological order, which only allows edges  $X_i \to X_j$ , where i < j. We achieve this by limiting the adjacency matrix of the graph to only having non-zero values above the diagnal, resulting in N(N-1)/2 possible directed edges for the DAGs.

At the first glance, for N nodes, there should be  $2^{N(N-1)/2}$  possible DAGs (i.e., the power set of all edges). However, there could be isomorphic graphs in this set. To avoid this, we perform a graph isomorphism check (McKay and Piperno, 2014), and reduce the set so that only unique DAGs are retained, and we show their statistics in Table 1. Although we can handle large graphs, we mostly focus on smaller graphs that can still lead to a reasonably sized dataset, so we empirically set N=6, but future work can use our open-sourced codes to extend to more nodes.

# Nodes	# Unique DAGs	# Edges/DAG	# MECs	# DAGs/MEC
2	2 out of 2	0.50	2	1.0
3	6 out of $2^3$	1.67	5	1.2
4	31 out of $2^6$	3.48	20	1.55
5	$302 \text{ out of } 2^{10}$	5.89	142	2.13
6	$5,984$ out of $2^{15}$	8.77	2,207	2.71
Total	6,325	8.60	2,376	2.66

Table 1: Statistics about the source causal graphs in our dataset. Given the number of nodes, we report the number of unique DAGs, average number of edges per DAG, number of MECs, and average number of DAGs per MEC.

#### 3.4 Programmatically Generating the D-Separation Sets

Based on the set of unique DAGs, we then programmatically generate the d-separation sets by graph theoretical conditions, as in Step 3 of Figure 2. To realize this step, we code an efficient graph-theoretic algorithm to check for all the chain, fork, and collider structures to automatically identify the set of nodes that d-separate each pair of nodes. Using the d-separation sets and the faithfulness assumption, we form the statistical correlations as follows. For each pair of nodes, they are conditionally independent given the variables in the d-separation set. If the d-separation set is empty, then the two nodes are unconditionally independent. If no d-separation set can be found for the two nodes, then they are directly correlated.

Moreover, using the d-separation sets, we are able to cluster causal graphs to MECs. We achieve it by tracing the mapping between the causal graphs and the set of statistical correlations, and backtracking the graphs with the same d-separation sets to group them in the same MEC. We show in Table 1 that each MEC contains on average 2.66 DAGs.

### 3.5 Composing the Hypotheses and Label

After generating the set of correlations based on the d-separation sets, we now generate the causal hypotheses. For the causal relation r, we focus on six common causal relations between two nodes introduced in Section 2.1: Is-Parent, Is-Child, Is-Ancestor (excluding the parents), Is-Descendant (excluding the children), Has-Confounder (i.e., there exists a confounder, or common cause, of the two nodes), and Has-Collider (i.e., there exists a collider, or common effect, of the two nodes). In this way, the set of hypotheses contains all six meaningful causal relations between every pair of variables, resulting in a total size of  $6 \cdot N(N-1)/2 = 3N(N-1)$  hypotheses for a graph with N variables.

To generate the ground-truth validity label, we start from the correlation sets in Step 3, then look up all the causal graphs in the same MEC corresponding to the given set of correlations, and check the necessity of the hypothesized causal relation. If the causal relationship proposed in the hypothesis is valid for all causal graphs within the MEC, then we generate the validity v=1; otherwise, we generate v=0. A special case of valid samples is that when the size of the MEC is 1, then there is a bijective mapping between the causal graph and the d-separation sets, so any hypothesis stating the causal properties of that unique causal graph is valid.

### 3.6 Verbalizing into Natural Language

Finally, as in the last step of Figure 2, we convert all the information above to text data for our CORR2CAUSE task. For the correlation statement, we verbalize the set of correlations in Step 3 into a natural language statement s. When two variables can not be d-separated, i.e.,  $A \not\perp \!\!\! \perp B$ , then we describe them as "A correlates with B" since they are directly correlated and cannot be independent by any condition. And if two variables have a valid d-separation set C, then we describe them as "A is independent of B given C." In the special case when the d-separation set is empty, we directly say "A is independent of B." In addition, we disambiguate the setting by starting the correlation statement with the setup of a closed system of the given variables, and no hidden variables: "Suppose

there is a closed system of N variables, A, B, ... All the statistical relations among these N variables are as follows:". Finally, to verbalize the hypothesis, we feed the causal relation triplet  $(X_i, r, X_j)$  into their hypothesis templates in Table 2. For example, we turn the triplet (A, Is-Parent, B) into "A directly causes B", as in the example of Figure 2.

Causal Relation	Hypothesis Template
Is-Parent	{Var i} directly causes {Var j}.
Is-Ancestor	{Var i} causes something else which causes {Var j}.
Is-Child	{Var j} directly causes {Var i}.
Is-Descendant	{Var j} is a cause for {Var i}, but not a direct one.
Has-Collider	There exists at least one collider (i.e., common effect) of {Var i} and {Var j}.
Has-Confounder	There exists at least one confounder (i.e., common cause) of {Var i} and {Var j}.

Table 2: Templates for each causal relation in the hypothesis. We use {Var i} and {Var j} as placeholders for the two variables.

# 3.7 Statistics of the Resulting Data

We show the statistics of our CORR2CAUSE dataset in Table 3. Overall, our dataset contains 415,944 samples, with 18.57% in valid samples. The average length of the premise is 424.11 tokens, and hypothesis 10.83 tokens. We split the data into 411,452 training samples, 2,246 development and test samples, respectively. Since the main purpose of the dataset is to benchmark the performance of LLMs, we prioritize the test and development sets to have a comprehensive coverage over all sizes of graphs. Specifically, we iterate through the subset of our data for each N, and split it entirely for only the test and development sets if the data is less than 1K, which is the case for N=2 and 3. For the other subsets that are larger, we randomly sample up to 1K or 10% of the data, whichever is smaller, to the test and development sets. We set the cap to be 1K in order to form a reasonable computation budget, since many LLMs are expensive to query in the inference mode. Aside from the test and valid sets, all the rest of the data goes into the training set.

	Overall	Statistics by the Number of Nodes $N$					
	Overall	N=2	N=3	N = 4	N = 5	N = 6	
# Samples	415,944	24	180	1,440	17,040	397,260	
# Test	2,246	12	90	144	1,000	1,000	
# Dev	2,246	12	90	144	1,000	1,000	
# Train	411,452	0	0	1,152	15,040	395,260	
# Tokens/Premise	424.11	31.5	52.0	104.0	212.61	434.54	
# Tokens/Hypothesis	10.83	10.83	10.83	10.83	10.83	10.83	
% Valid Labels	18.57	0.00	3.33	7.50	13.01	18.85	
Vocab Size	65	49	53	55	57	61	

Table 3: Statistics of our CORR2CAUSE dataset, and by subsets. We report the total number of samples; splits of the test, developement and training sets; number of tokens per premise and hypothesis; percentage of the entailment labels, and vocabulary size. Note that the number of unique graphs and MECs are in Table 1.

# 4 Experiments

#### 4.1 Experimental Setup

We set up a diverse list of LLMs for the experiments on our CORR2CAUSE dataset. To *test existing LLMs*, we first include six commonly used BERT-based NLI models in the transformers library (Wolf et al., 2020) with the most number of downloads: BERT (Devlin et al., 2019), RoBERTa (Liu et al., 2019), BART (Lewis et al., 2020), DeBERTa (He et al., 2021), DistilBERT (Sanh et al., 2019), and DistilBART (Shleifer and Rush, 2020). Apart from these BERT-based NLI models, we also evaluate the general-purpose autoregressive LLMs based on GPT (Radford et al., 2019): GPT-3 Ada, Babbage, Curie, Davinci (Brown et al., 2020); its instruction-tuned versions (Ouyang et al., 2022), text-davinci-001, text-davinci-002, and text-davinci-003; and GPT-3.5 (i.e., ChatGPT), and the latest GPT-4 (OpenAI, 2023), using the OpenAI API<sup>2</sup> with temperature 0. We also evaluate the recent, more efficient models LLaMa (Touvron et al., 2023) and Alpaca (Taori et al., 2023).

<sup>&</sup>lt;sup>2</sup>https://openai.com/api/

	F1	Precision	Recall	Accuracy
Random Baselines				
Always Majority	0.0	0.0	0.0	84.77
Random (Proportional)	13.5	12.53	14.62	71.46
Random (Uniform)	20.38	15.11	31.29	62.78
BERT-Based Models				
BERT MNLI	2.82	7.23	1.75	81.61
RoBERTa MNLI	22.79	34.73	16.96	82.50
DeBERTa MNLI	14.52	14.71	14.33	74.31
DistilBERT MNLI	20.70	24.12	18.13	78.85
DistilBART MNLI	26.74	15.92	83.63	30.23
BART MNLI	33.38	31.59	35.38	78.50
LLaMa-Based Models				
LLaMa-6.7B	26.81	15.50	99.42	17.36
Alpaca-6.7B	27.37	15.93	97.37	21.33
GPT-Based Models				
GPT-3 Ada	0.00	0.00	0.00	84.77
GPT-3 Babbage	27.45	15.96	97.95	21.15
GPT-3 Curie	26.43	15.23	100.00	15.23
GPT-3 Davinci	27.82	16.57	86.55	31.61
GPT-3 Instruct (text-davinci-001)	17.99	11.84	37.43	48.04
GPT-3 Instruct (text-davinci-002)	21.87	13.46	58.19	36.69
GPT-3 Instruct (text-davinci-003)	15.72	13.4	19.01	68.97
GPT-3.5	21.69	17.79	27.78	69.46
GPT-4	29.08	20.92	47.66	64.60

Table 4: Overall performance. We report F1 (main metric), precision, recall and accuracy. For the main metric, F1 score, we use the **bold** font to highlight the overall best performance, and <u>underline</u> to highlight the best performance within each category of models.

When inspecting the behavior of *finetuned models*, we adopt a large set of models, including GPT-based models (GPT-3 Ada, Babbage, Curie, and Davinci) using the OpenAI finetuning API for classification,<sup>3</sup> BERT-based models from scratch (BERT-Base, BERT-Large, RoBERTa-Base, and RoBERTa-Large), and BERT-Based NLI models (BERT-Base MNLI, BERT-Large MNLI, RoBERTa-Base MNLI, and RoBERTa-Large MNLI) using the transformers library (Wolf et al., 2020). Our training details are available in Appendix A.

For the *random baselines*, we provide "always majority" to predict the majority class 100% of the time, "random (uniform)" which randomly samples a label with 50% chance for each, and "random (proportional)" which samples a label from a Bernouli distribution proportional to the development set label distribution.

#### 4.2 The CORR2CAUSE Skill in Existing LLMs

We show the performance of LLMs in Table 4. We can see that pure causal inference is a very challenging task across all existing LLMs. Among all the LLMs, the best performance is 33.38% F1 by BART MNLI, which is even higher than latest GPT-based model, GPT-4. Notably, many models are worse than random guess, which means that they totally fail at this pure causal inference task.

#### **4.3** Finetuned Performance

Next, we address the question: Can we re-purpose LLMs to learn this task?

The experimental results in Table 5a of 12 models finetuned on our CORR2CAUSE seem very strong at first sight. Most models see a substantial increase, among which the finetuned BERT-based NLI models demonstrate the strongest performance. The best-performing one, RoBERTa-Large MNLI, achieves 94.74% F1 score on this task, as well as very high precision, recall and accuracy scores.

# 4.4 Fine-Grained Performance by Causal Relation

In addition to the overall results mentioned above, we also conduct a fine-grained analyze to check the performance of the strongest model, RoBERTa-Large MNLI, by our six causal relation types.

<sup>3</sup>https://platform.openai.com/docs/guides/fine-tuning

	F1	Precison	Recall	Accuracy	-	F1 (Paraph.)	F1 (Var. Ref.)	
Finetuned GPT-Based M	-							
GPT-3 Ada	79.85	70.47	92.11	92.92		61.73	41.57	
GPT-3 Babbage	78.19	69.98	88.60	92.48		62.34	43.28	
GPT-3 Curie	81.23	75.00	88.60	93.77		64.93	45.32	
GPT-3 Davinci	85.52	80.26	91.52	95.28		65.01	46.96	
Finetuned BERT-Based	Finetuned BERT-Based Models							
BERT-Base	69.29	54.42	95.32	87.13		61.13	35.20	
BERT-Large	85.26	77.51	94.74	95.01		63.64	38.54	
RoBERTa-Base	87.60	78.47	99.12	95.73		65.58	53.12	
RoBERTa-Large	89.10	82.54	96.78	96.39		65.05	60.20	
Finetuned BERT-Based	NLI Mod	lels						
BERT-Base MNLI	89.88	85.49	94.74	86.51		65.56	31.50	
BERT-Large MNLI	90.19	84.44	96.78	96.79		67.24	52.04	
RoBERTa-Base MNLI	94.27	90.35	98.54	98.17		57.42	62.83	
RoBERTa-Large MNLI	94.74	92.24	97.37	98.35		55.45	67.87	

<sup>(</sup>a) Performance of finetuned models on the original test set.

Table 5: Performance of finetuned models on the original test set and perturbed test sets.

As in Table 6a, the model is very good at judging relations such as Is-Parent, Is-Descendant and Has-Confounder, all with more than 96% F1 scores, whereas it is several points weaker on the Has-Collider relations. This could be due to that the collider relation is the most special type, requiring identification of the V-structure based on both the unconditional independence based on the two variables only and correlations whenever conditioned on a common descendant.

# 4.5 Robustness Analysis

Looking at the very high performance of the finetuned models, we raise the next question: Did the models really robustly learn the causal inference skills?

**Two Robustness Tests** We design two simple robustness tests: (1) paraphrasing, and (2) variable refactorization. For (1) paraphrasing, we simply paraphrase the hypothesis by changing the text template for each causal relation to some semantically-equivalent alternatives in Appendix B. For (2) variable refactorization, we reverse the alphabet of the variable names, namely flipping A, B, C, to Z, Y, X and so on. The inspiration behind the two robustness tests comes from the spurious correlation analysis described in Appendix C.

Specifically, we adopt the common setup of text adversarial attack (Morris et al., 2020; Jin et al., 2020) to preserve the training set and keep the same saved models, but run the inference n the perturbed test set. In this way, we separate the possibilities of the models only overfitting on the training data vs. mastering the reasoning skills.

**Results After Perturbation** We can see from Table 5b that all the models drop drastically, by up to 39.29 when we paraphrase the test set, and they decrease substantially by up to 58.38 when we refactor the variable names. The best-performing model, RoBERTa-Large MNLI, is especially sensitive towards paraphrasing, demonstrating the most drop among all models; however, it is the most robust against the variable refactorization, maintaining a high F1 score of 67.87. We conduct fine-grained analysis for RoBERTa-Large MNLI under perturbation in Table 6b. We can see the the main source of the performance drop of the model comes from the two classes, Is-Ancestor (decreasing to 45.45%) and Is-Descendant (decreasing to 29.41%), while the other classes stay relatively robust, keeping their F1 scores over 70%.

From this analysis, we make the following suggestions to future studies testing this CORR2CAUSE skill of LLMs. First, it is safe to use it as a test set to benchmark existing LLMs' performance, since the data we generate is out-of-distribution from the training data of the current LLMs. Then, when testing finetuned models, it is very important to accompany adversarial attack together with the i.i.d. test set. We also provide our perturbed versions of the test set in our data for future work to test the generalizability skill.

<sup>(</sup>b) F1 scores of finetuned models on the perturbed test sets by paraphrasing (Paraph.) and variable refactorization (Var. Ref.).

Relation Type	F1	Precision	Recall	Accuracy	F1	Precision	Recall	Accuracy
Is-Parent	96.18	95.45	96.92	98.67	74.80	79.31	70.77	91.73
Is-Ancestor	93.94	93.94	93.94	98.93	45.45	90.91	30.30	93.60
Is-Child	95.73	94.92	96.56	98.67	73.39	78.43	68.97	92.27
Is-Descendant	96.55	93.33	100	99.47	29.41	83.33	17.86	93.60
Has-Collider	92.19	87.41	97.52	94.64	70.70	75.00	66.90	82.04
Has-Confounder	98.67	97.37	100	99.73	70.42	73.53	67.57	94.37

<sup>(</sup>a) Fine-grained performance of RoBERTa-Large by causal relation (b) Its fine-grained performance by relation type on the original test set.

Table 6: Fine-grained analysis of the best-performing model, RoBERTa-Large MNLI.

#### Related Work

Existing Causal Reasoning Tasks A large body of existing research of causal reasoning in NLP focuses on leveraging empirical knowledge to do tasks such as inferring the cause and effect of why an agent perform certain tasks (Sap et al., 2019a), the motivation and emotional reaction in a social context (Sap et al., 2019b), how people achieve a given goal with a set of concrete steps (Zhang et al., 2020), the development of a story given a different beginning (Qin et al., 2019), and how in general LLMs serve as a knowledge base of cause and effect (Willig et al., 2023; Kıcıman et al., 2023). In contrast, our CORR2CAUSE task focuses on the pure causal inference skill of models, which is a knowledge-dependent reasoning skill based on formally correct rules from causal inference.

**Existing Logical and Inference Tasks** Another related area of literature is logical and inference tasks. A well-established task is natural language inference (NLI), which identifies the semantic relationship between a pair of sentences (MacCartney and Manning, 2008; Bowman et al., 2015). NLI datasets mainly focus on the set and paraphrase relations, such as "a group of boys are playing football" can entail "some guys are playing football," where "boys" are a sub-concept of "guys" and "a group of" and "some" are paraphrases. Existing datasets cover entailment in news articles (Dagan et al., 2006), image captions (Bowman et al., 2015), and across multiple genres (Williams et al., 2018). Recently, there has been increasing efforts to extend the inference task to various logical inference skills such as deductive logic and propaganda techniques (Jin et al., 2022; Alhindi et al., 2022). Our CORR2CAUSE dataset is the first dataset testing the correlation-to-causation inference skill, which is unique of its type.

### **Limitations and Future Work**

We identify several limitations of this work and open future directions: First, in the context of this work, we limit the causal graphs to two to six nodes, but future work can feel free to explore larger graphs. Another aspect is that we do not assume hidden confounders in this inference problem, so we welcome future work to generate an even more challenging dataset to infer the existence of hidden confounders, analogous to the causal discovery algorithm of fast causal inference (FCI) (Spirtes et al., 2000). Finally, a lot of motivation behind proposing this task is inspired by the problem of invalid reasoning patterns in our daily reasoning (Jin et al., 2022), which could fertilize the ground for more pervasive spread of fake news. We believe false causal inference is a prevalent type of fallacious beliefs, and welcome future work to connect the idea of this benchmark to more real-world false beliefs based on confusing correlation with causation.

#### 7 Conclusion

In this work, we introduced a novel task, CORR2CAUSE, to infer causation from correlation, and collected a large-scale dataset of more than 400K samples. We evaluated an extensive list of LLMs on this new task, and showed that off-the-shelf LLMs perform poorly on this task. We also show that it is possible to re-purpose LLMs on this task by finetuning, but future work needs to be aware of the out-of-distribution generalization problem. To avoid the Goodhart's law, we recommend using this dataset to benchmark the pure causal inference skills for LLMs that have not seen this dataset. Given the limited reasoning abilities of current LLMs, and the difficulty of separating actual reasoning from training-corpus-derived knowledge, it is imperative that our community focus on work aiming to accurately disentangle and measure both abilities. We believe that the present work is a first such step.

type after variable refactorization.

# Acknowledgment

We thank Riley Goodside for valuable suggestions to improve the our prompts to LLMs. We thank Luigi Gresele and Amir Hossein Karimi for their suggestions to help us improve the formulation of our causal discovery questions.

This material is based in part upon works supported by the German Federal Ministry of Education and Research (BMBF): Tübingen AI Center, FKZ: 01IS18039B; by the Machine Learning Cluster of Excellence, EXC number 2064/1 – Project number 390727645; by the Precision Health Initiative at the University of Michigan; by the John Templeton Foundation (grant #61156); by a Responsible AI grant by the Haslerstiftung; and an ETH Grant (ETH-19 21-1). Zhijing Jin is supported by PhD fellowships from the Future of Life Institute and Open Philanthropy. We also thank OpenAI for granting Zhijing quota to their API of GPT series through the Researcher Access Program.

#### References

- Tariq Alhindi, Tuhin Chakrabarty, Elena Musi, and Smaranda Muresan. 2022. Multitask instruction-based prompting for fallacy recognition. In *Proceedings of the 2022 Conference on Empirical Methods in Natural Language Processing*, pages 8172–8187, Abu Dhabi, United Arab Emirates. Association for Computational Linguistics. 9
- Emily M. Bender, Timnit Gebru, Angelina McMillan-Major, and Shmargaret Shmitchell. 2021. On the dangers of stochastic parrots: Can language models be too big? In *Proceedings of the 2021 ACM Conference on Fairness, Accountability, and Transparency*, FAccT '21, page 610–623, New York, NY, USA. Association for Computing Machinery. 2
- Samuel R. Bowman, Gabor Angeli, Christopher Potts, and Christopher D. Manning. 2015. A large annotated corpus for learning natural language inference. In *Proceedings of the 2015 Conference on Empirical Methods in Natural Language Processing*, pages 632–642, Lisbon, Portugal. Association for Computational Linguistics. 9
- Tom Brown, Benjamin Mann, Nick Ryder, Melanie Subbiah, Jared D Kaplan, Prafulla Dhariwal, Arvind Neelakantan, Pranav Shyam, Girish Sastry, Amanda Askell, Sandhini Agarwal, Ariel Herbert-Voss, Gretchen Krueger, Tom Henighan, Rewon Child, Aditya Ramesh, Daniel Ziegler, Jeffrey Wu, Clemens Winter, Chris Hesse, Mark Chen, Eric Sigler, Mateusz Litwin, Scott Gray, Benjamin Chess, Jack Clark, Christopher Berner, Sam McCandlish, Alec Radford, Ilya Sutskever, and Dario Amodei. 2020. Language models are few-shot learners. In *Advances in Neural Information Processing Systems*, volume 33, pages 1877–1901. Curran Associates, Inc. 6
- David Maxwell Chickering. 2002. Optimal structure identification with greedy search. *J. Mach. Learn. Res.*, 3:507–554. 3
- Ido Dagan, Oren Glickman, and Bernardo Magnini. 2006. The pascal recognising textual entailment challenge. In Machine Learning Challenges. Evaluating Predictive Uncertainty, Visual Object Classification, and Recognising Tectual Entailment: First PASCAL Machine Learning Challenges Workshop, MLCW 2005, Southampton, UK, April 11-13, 2005, Revised Selected Papers, pages 177–190. Springer.
- Jacob Devlin, Ming-Wei Chang, Kenton Lee, and Kristina Toutanova. 2019. BERT: Pre-training of deep bidirectional transformers for language understanding. In Proceedings of the 2019 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies, Volume 1 (Long and Short Papers), pages 4171–4186, Minneapolis, Minnesota. Association for Computational Linguistics. 2, 6
- Clark Glymour, Kun Zhang, and Peter Spirtes. 2019. Review of causal discovery methods based on graphical models. *Frontiers in Genetics*, 10:524. 1, 2, 3
- Madelyn Glymour, Judea Pearl, and Nicholas P Jewell. 2016. *Causal inference in statistics: A primer*. John Wiley and Sons. 2, 3
- Pengcheng He, Xiaodong Liu, Jianfeng Gao, and Weizhu Chen. 2021. Deberta: Decoding-enhanced Bert with disentangled attention. In 9th International Conference on Learning Representations, ICLR 2021, Virtual Event, Austria, May 3-7, 2021. OpenReview.net. 6

- Patrik O. Hoyer, Dominik Janzing, Joris M. Mooij, Jonas Peters, and Bernhard Schölkopf. 2008. Nonlinear causal discovery with additive noise models. In Advances in Neural Information Processing Systems 21, Proceedings of the Twenty-Second Annual Conference on Neural Information Processing Systems, Vancouver, British Columbia, Canada, December 8-11, 2008, pages 689–696. Curran Associates, Inc. 3
- Di Jin, Zhijing Jin, Joey Tianyi Zhou, and Peter Szolovits. 2020. Is BERT really robust? A strong baseline for natural language attack on text classification and entailment. In *The Thirty-Fourth AAAI Conference on Artificial Intelligence, AAAI 2020, The Thirty-Second Innovative Applications of Artificial Intelligence Conference, IAAI 2020, The Tenth AAAI Symposium on Educational Advances in Artificial Intelligence, EAAI 2020, New York, NY, USA, February 7-12, 2020*, pages 8018–8025. AAAI Press. 8
- Zhijing Jin, Abhinav Lalwani, Tejas Vaidhya, Xiaoyu Shen, Yiwen Ding, Zhiheng Lyu, Mrinmaya Sachan, Rada Mihalcea, and Bernhard Schölkopf. 2022. Logical fallacy detection. In *Findings of the Association for Computational Linguistics: EMNLP 2022*, pages 7180ââ,¬â€œ–7198, Abu Dhabi, United Arab Emirates. Association for Computational Linguistics. 9
- Emre Kıcıman, Robert Ness, Amit Sharma, and Chenhao Tan. 2023. Causal reasoning and large language models: Opening a new frontier for causality. *arXiv preprint arXiv:2305.00050*. 9
- Mike Lewis, Yinhan Liu, Naman Goyal, Marjan Ghazvininejad, Abdelrahman Mohamed, Omer Levy, Veselin Stoyanov, and Luke Zettlemoyer. 2020. BART: Denoising sequence-to-sequence pre-training for natural language generation, translation, and comprehension. In *Proceedings of the 58th Annual Meeting of the Association for Computational Linguistics*, pages 7871–7880, Online. Association for Computational Linguistics. 6
- Yinhan Liu, Myle Ott, Naman Goyal, Jingfei Du, Mandar Joshi, Danqi Chen, Omer Levy, Mike Lewis, Luke Zettlemoyer, and Veselin Stoyanov. 2019. RoBERTa: A robustly optimized BERT pretraining approach. *CoRR*, abs/1907.11692. 6
- Bill MacCartney and Christopher D. Manning. 2008. Modeling semantic containment and exclusion in natural language inference. In *Proceedings of the 22nd International Conference on Computational Linguistics* (Coling 2008), pages 521–528, Manchester, UK. Coling 2008 Organizing Committee. 9
- Brendan D. McKay and Adolfo Piperno. 2014. Practical graph isomorphism, II. *J. Symb. Comput.*, 60:94–112. 5
- John Morris, Eli Lifland, Jin Yong Yoo, Jake Grigsby, Di Jin, and Yanjun Qi. 2020. TextAttack: A framework for adversarial attacks, data augmentation, and adversarial training in NLP. In *Proceedings of the 2020 Conference on Empirical Methods in Natural Language Processing:* System Demonstrations, pages 119–126, Online. Association for Computational Linguistics. 8
- OpenAI. 2023. GPT-4 technical report. CoRR, abs/2303.08774. 2, 6
- Long Ouyang, Jeff Wu, Xu Jiang, Diogo Almeida, Carroll L. Wainwright, Pamela Mishkin, Chong Zhang, Sandhini Agarwal, Katarina Slama, Alex Ray, John Schulman, Jacob Hilton, Fraser Kelton, Luke Miller, Maddie Simens, Amanda Askell, Peter Welinder, Paul F. Christiano, Jan Leike, and Ryan Lowe. 2022. Training language models to follow instructions with human feedback. *CoRR*, abs/2203.02155. 2, 6
- Judea Pearl. 1988. Probabilistic reasoning in intelligent systems: Networks of plausible inference. Morgan Kaufmann. 3
- Judea Pearl. 2009. Causality: Models, reasoning and inference (2nd ed.). Cambridge University Press. 1
- Jonas Peters, Dominik Janzing, and Bernhard Schölkopf. 2017. *Elements of causal inference: Foundations and learning algorithms.* The MIT Press. 1

- Lianhui Qin, Antoine Bosselut, Ari Holtzman, Chandra Bhagavatula, Elizabeth Clark, and Yejin Choi. 2019. Counterfactual story reasoning and generation. In *Proceedings of the 2019 Conference on Empirical Methods in Natural Language Processing and the 9th International Joint Conference on Natural Language Processing (EMNLP-IJCNLP)*, pages 5043–5053, Hong Kong, China. Association for Computational Linguistics. 9
- Alec Radford, Jeffrey Wu, Rewon Child, David Luan, Dario Amodei, and Ilya Sutskever. 2019. Language models are unsupervised multitask learners. *OpenAI Blog*, 1(8). 2, 6
- Victor Sanh, Lysandre Debut, Julien Chaumond, and Thomas Wolf. 2019. DistilBERT, a distilled version of BERT: Smaller, faster, cheaper and lighter. *CoRR*, abs/1910.01108. 6
- Maarten Sap, Ronan Le Bras, Emily Allaway, Chandra Bhagavatula, Nicholas Lourie, Hannah Rashkin, Brendan Roof, Noah A. Smith, and Yejin Choi. 2019a. ATOMIC: an atlas of machine commonsense for if-then reasoning. In *The Thirty-Third AAAI Conference on Artificial Intelligence, AAAI 2019, The Thirty-First Innovative Applications of Artificial Intelligence Conference, IAAI 2019, The Ninth AAAI Symposium on Educational Advances in Artificial Intelligence, EAAI 2019, Honolulu, Hawaii, USA, January 27 February 1, 2019*, pages 3027–3035. AAAI Press. 9
- Maarten Sap, Hannah Rashkin, Derek Chen, Ronan Le Bras, and Yejin Choi. 2019b. Social iqa: Commonsense reasoning about social interactions. In *EMNLP 2019*. 9
- Shohei Shimizu, Patrik O. Hoyer, Aapo Hyvärinen, and Antti J. Kerminen. 2006. A linear non-gaussian acyclic model for causal discovery. *J. Mach. Learn. Res.*, 7:2003–2030. 3
- Sam Shleifer and Alexander M. Rush. 2020. Pre-trained summarization distillation. CoRR, abs/2010.13002. 6
- Peter Spirtes, Clark Glymour, and Richard Scheines. 1993. Causation, prediction, and search. 2, 3
- Peter Spirtes, Clark Glymour, and Richard Scheines. 2000. *Causation, Prediction, and Search, Second Edition*. Adaptive computation and machine learning. MIT Press. 1, 2, 3, 9
- Peter Spirtes and Kun Zhang. 2016. Causal discovery and inference: Concepts and recent methodological advances. In *Applied informatics*, volume 3, pages 1–28. SpringerOpen. 1, 2, 3
- Rohan Taori, Ishaan Gulrajani, Tianyi Zhang, Yann Dubois, Xuechen Li, Carlos Guestrin, Percy Liang, and Tatsunori B. Hashimoto. 2023. Stanford alpaca: An instruction-following llama model. https://github.com/tatsu-lab/stanford\_alpaca. 6
- Hugo Touvron, Thibaut Lavril, Gautier Izacard, Xavier Martinet, Marie-Anne Lachaux, Timothée Lacroix, Baptiste Rozière, Naman Goyal, Eric Hambro, Faisal Azhar, Aurélien Rodriguez, Armand Joulin, Edouard Grave, and Guillaume Lample. 2023. Llama: Open and efficient foundation language models. *CoRR*, abs/2302.13971. 6
- Adina Williams, Nikita Nangia, and Samuel Bowman. 2018. A broad-coverage challenge corpus for sentence understanding through inference. In *Proceedings of the 2018 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies, Volume 1 (Long Papers)*, pages 1112–1122, New Orleans, Louisiana. Association for Computational Linguistics. 9
- Moritz Willig, Matej Zečević, Devendra Singh Dhami, and Kristian Kersting. 2023. Probing for correlations of causal facts: Large language models and causality. 9
- Thomas Wolf, Lysandre Debut, Victor Sanh, Julien Chaumond, Clement Delangue, Anthony Moi, Pierric Cistac, Tim Rault, Remi Louf, Morgan Funtowicz, Joe Davison, Sam Shleifer, Patrick von Platen, Clara Ma, Yacine Jernite, Julien Plu, Canwen Xu, Teven Le Scao, Sylvain Gugger, Mariama Drame, Quentin Lhoest, and Alexander Rush. 2020. Transformers: State-of-the-art natural language processing. In *Proceedings of the 2020 Conference on Empirical Methods in Natural Language Processing: System Demonstrations*, pages 38–45, Online. Association for Computational Linguistics. 6, 7, 14

- Kun Zhang and Aapo Hyvärinen. 2009. Causality discovery with additive disturbances: An information-theoretical perspective. In *Machine Learning and Knowledge Discovery in Databases: European Conference, ECML PKDD 2009, Bled, Slovenia, September 7-11, 2009, Proceedings, Part II 20*, pages 570–585. Springer. 3
- Li Zhang, Qing Lyu, and Chris Callison-Burch. 2020. Reasoning about goals, steps, and temporal ordering with WikiHow. In *Proceedings of the 2020 Conference on Empirical Methods in Natural Language Processing (EMNLP)*, pages 4630–4639, Online. Association for Computational Linguistics. 9
- Susan Zhang, Stephen Roller, Naman Goyal, Mikel Artetxe, Moya Chen, Shuohui Chen, Christopher Dewan, Mona T. Diab, Xian Li, Xi Victoria Lin, Todor Mihaylov, Myle Ott, Sam Shleifer, Kurt Shuster, Daniel Simig, Punit Singh Koura, Anjali Sridhar, Tianlu Wang, and Luke Zettlemoyer. 2022. OPT: open pre-trained transformer language models. *CoRR*, abs/2205.01068. 2

# **A** Implementation Details

When finetuning on our data, for GPT-based models, we use the default settings of the OpenAI finetuning API; and for BERT-based models, we use the transformers library (Wolf et al., 2020) and train the models on a server with an NVIDIA Tesla A100 GPU with 40G of memory. To fit for the GPU memory, we set the batch size to be 8. We use the validation set to tune the learning rate, which takes value in {2e-6, 5e-6, 1e-5, 2e-5, 5e-5}; dropout rate, which takes value in {0, 0.1, 0.2, 0.3}; and weight decay, which takes value in {1e-4, 1e-5}. We train the models until convergence, which is usually around five epochs.

# **B** Templates and Paraphrases

We use the verbalization templates in Table 7 to compose the hypotheses for all six causal relations.

Causal Relation	Hypothesis Template
Is-Parent	{Var i} directly causes {Var j}.
Is-Ancestor	{Var i} causes something else which causes {Var j}.
Is-Child	{Var j} directly causes {Var i}.
Is-Descendant	{Var j} is a cause for {Var i}, but not a direct one.
Has-Collider	There exists at least one collider (i.e., common effect) of {Var i} and {Var j}.
Has-Confounder	There exists at least one confounder (i.e., common cause) of {Var i} and {Var j}.
Paraphrases	
Is-Parent	{Var i} directly affects {Var j}.
Is-Ancestor	{Var i} influences {Var j} through some mediator(s).
Is-Child	{Var j} directly affects {Var i}.
Is-Descendant	{Var j} influences {Var i} through some mediator(s).
Has-Collider	{Var i} and {Var j} together cause some other variable(s).
Has-Confounder	Some $variable(s)$ cause(s) both {Var i} and {Var j}.

Table 7: Templates and their paraphrases for each causal relation in the hypothesis. We use {Var i} and {Var j} as placeholders for the two variables.

# C Spurious Correlation Analysis

The inspirations of our two robustness tests (paraphrasing and variable refactorization) come from our data analysis. We check for spurious correlations in the data by reporting in Table 8 the point-wise mutual information (PMI) between the label and any n-gram with no more than four tokens. In addition, we also report the difference of the PMI with the two labels in the |Diff| column of Table 8, and report the top 10 n-grams.

The design spirit for our robustness test is that if the models' correct judgment relies on exploiting these spurious correlations, then such reliance will be broken in our perturbations.

N-Gram	PMI w/ Non-Ent. Label	PMI w/ Ent. Label	Diff
a cause	1.692209	-1.025611	2.717820
a cause for	1.663640	-0.983790	2.647430
A causes	1.640679	-0.951610	2.592289
A causes something	1.621820	-0.926075	2.547895
a direct	1.606052	-0.905316	2.511369
a direct one	1.592673	-0.888107	2.480781
for D	1.584826	-0.878180	2.463006
for D but	1.583897	-0.877014	2.460911
for E	1.582980	-0.875864	2.458844
for E but	1.582074	-0.874728	2.456802

Table 8: PMI between the labels and n-grams. The labels include non-entailment (Non-Ent.) and entailment (Ent.). And the n-grams include all with no more than four words. The |Diff| column shows the absolute value of the difference between the PMIs with two labels. We show the top 10 n-grams with the largest differences of their PMIs with the two classes in the |Diff| column.

We can see that some spurious correlations are rooted in the framing of the hypothesis, such as "a cause (for)", and "a direct (one)" (which we use the paraphrasing task to break), and others are

connected to the variable names, such as "for D (but)" and "for E (but)" (which we use the variable refactorization to break).