# **RUL-Based Policy as Classification**





#### **An Alternative Formulation**

### Let's consider an alternative formulation for our policy

- Rather than building a RUL estimator
- ...And triggering maintenance when the estimate is too low

...We could train a single model to do all the work instead

#### Such a model may work as follows

- If the RUL is larger than  $\theta$ , the output is 1 (all fine)
- Otherwise, the output is 0 (we need to stop)

Rather than a numerical quantity, we have a discrete one

#### We say that our model is a classifier

- A typical classifier would be an image recognizer
- ...But this one fits the definition, too

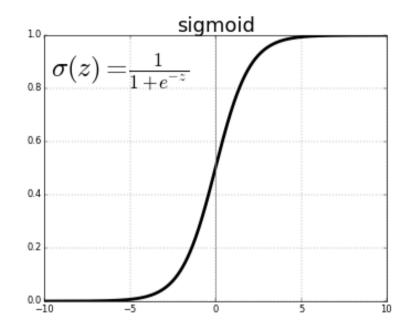




#### **NN Classifier**

#### As we have seen, we can easily define a NN classifier

...By using a sigmoid activation function on the output layer



### With this change, we can view the NN output as a probability

Specifically, as the probability that the class is 1

- If this is > 0.5, we say the class is 1
- If it is < 0.5, then the class is 0

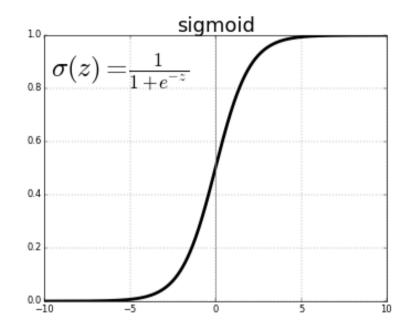




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- Rather than targets (i.e. numerical quantities to estimate)
- We have categorical values (a.k.a. labels)





# **Labels vs Targets**

#### Our ground truth changes

- Rather than targets (i.e. numerical quantities to estimate)
- We have categorical values (a.k.a. labels)

We obtain them by just comparing the RUL with our chosen heta

```
In [2]: class_thr = 18
    tr_lbl = (tr['rul'] >= class_thr)
    ts_lbl = (ts['rul'] >= class_thr)
```

The resulting vector contain the outcome of the comparison

- I.e.  $tr_lbl$  contains True if the RUL was larger than  $\theta$
- ...And False otherwise





## A Logistic Regression Model

#### We will start by building the simpler possible NN classifier

```
In [3]: hidden = []
nn = util.build_ml_model(input_size=(len(dt_in),), output_size=1, hidden=hidden, output_activatil.plot_ml_model(nn)

Out[3]:

dense (Dense)

Input shape: (None, 24)

Output shape: (None, 1)
```

- It's the same as our Liner Regressor
- ...Except that we have a sigmoid activation on the output function



# A Logistic Regression Model

#### Next, we trigger the training process

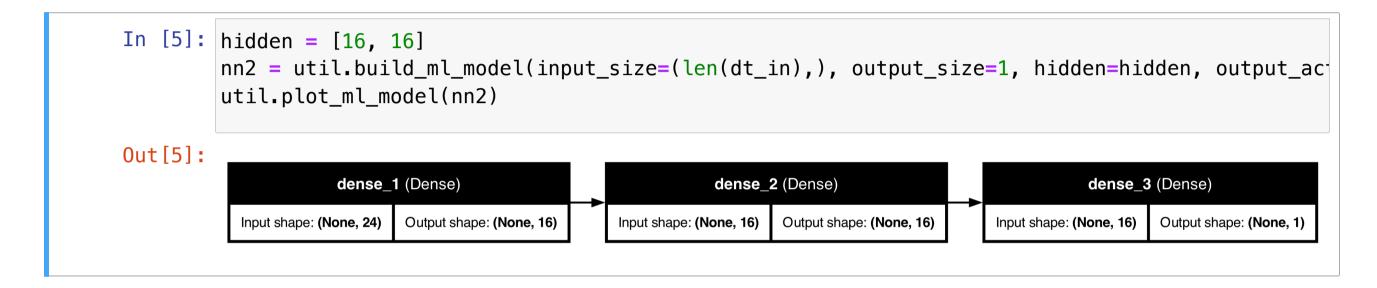
In [4]: history = util.train\_ml\_model(nn, tr\_s[dt\_in], tr\_lbl, epochs=40, validation\_split=0.2, los:
 util.plot\_training\_history(history, figsize=figsize)





#### **An MLP Classifier Model**

#### Now, let's try with a deeper model



Once again, we have introduced two hidden layers

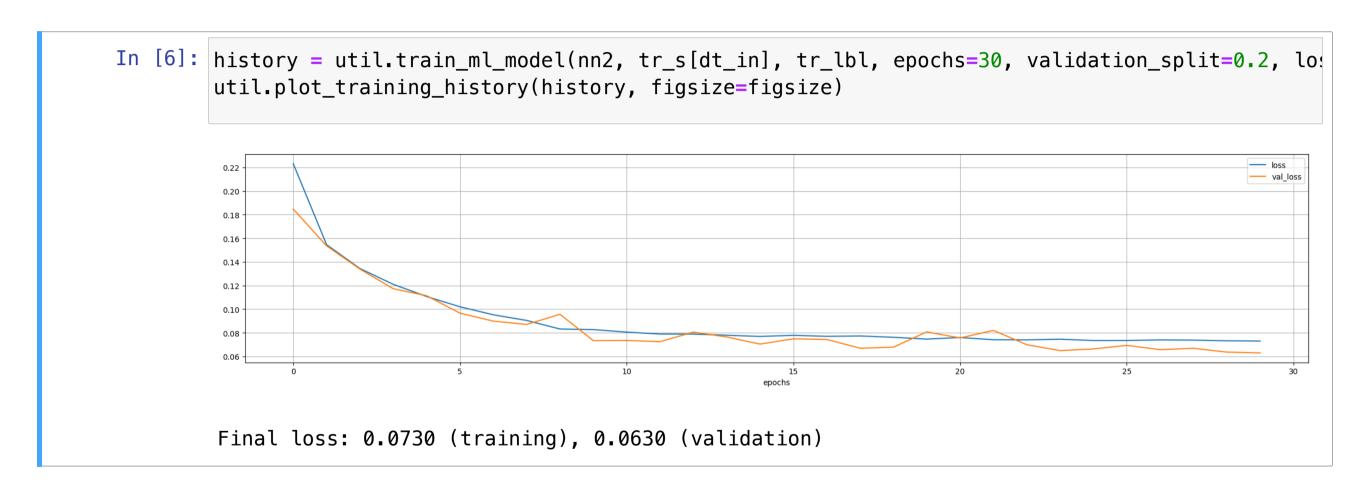
- We can view each layer as a function which transforms its input
- The last layer then is a Logistic Regressor on the transformed data





#### **An MLP Classifier Model**

#### Let's perform training and check the results



A deeper network in this case works much better





# **Inspecting the Predictions**

### Let's check our raw predictions (probabilities) over time

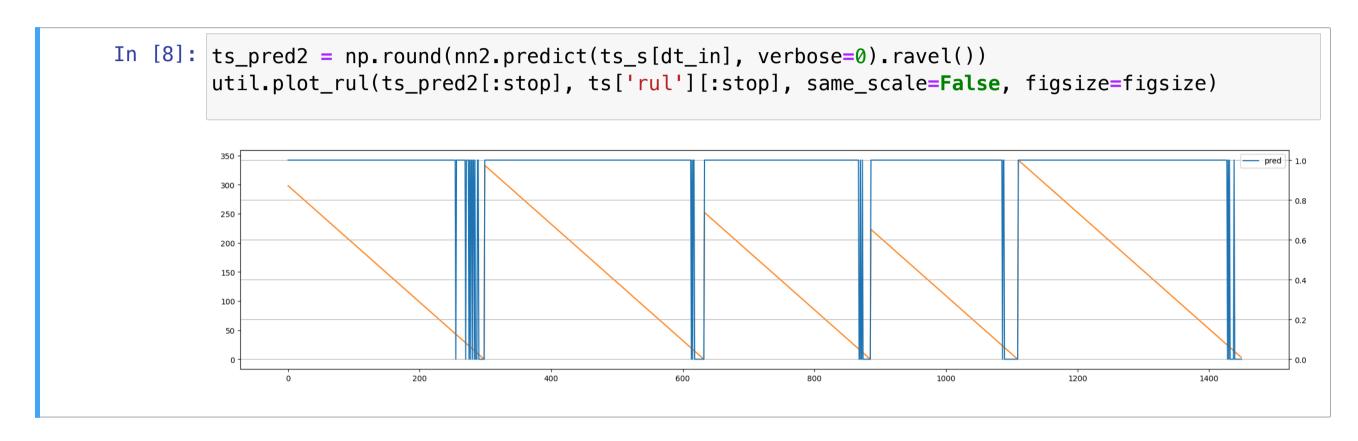
```
In [7]: ts_prob2 = nn2.predict(ts_s[dt_in], verbose=0).ravel()
stop = 1450
util.plot_rul(ts_prob2[:stop], ts['rul'][:stop], same_scale=False, figsize=figsize)
```





# **Inspecting the Predictions**

### After rounding is applied, this is what we get







# **Evaluating the Policy**

#### We can evaluate the classifier directly

...Because it defines the whole policy, with no need for additional calibration

```
In [9]: tr_pred2 = np.round(nn2.predict(tr_s[dt_in], verbose=0).ravel())
    ts_pred2 = np.round(nn2.predict(ts_s[dt_in], verbose=0).ravel())

    tr_c2, tr_f2, tr_s2 = cmodel.cost(tr['machine'].values, tr_pred2, 0.5, return_margin=True)
    ts_c2, ts_f2, ts_s2 = cmodel.cost(ts['machine'].values, ts_pred2, 0.5, return_margin=True)

    print(f'Cost: {tr_c2/len(tr_mcn):.2f} (training), {ts_c2/len(ts_mcn):.2f} (test)')
    print(f'Avg. fails: {tr_f2/len(tr_mcn)} (training), {ts_f2/len(ts_mcn)} (test)')
    print(f'Avg. slack: {tr_s2/len(tr_mcn):.2f} (training), {ts_s2/len(ts_mcn):.2f} (test)')

    Cost: -88.11 (training), -98.13 (test)
    Avg. fails: 0.0 (training), 0.0 (test)
    Avg. slack: 28.32 (training), 25.81 (test)
```

Which is comparable with our earlier results



