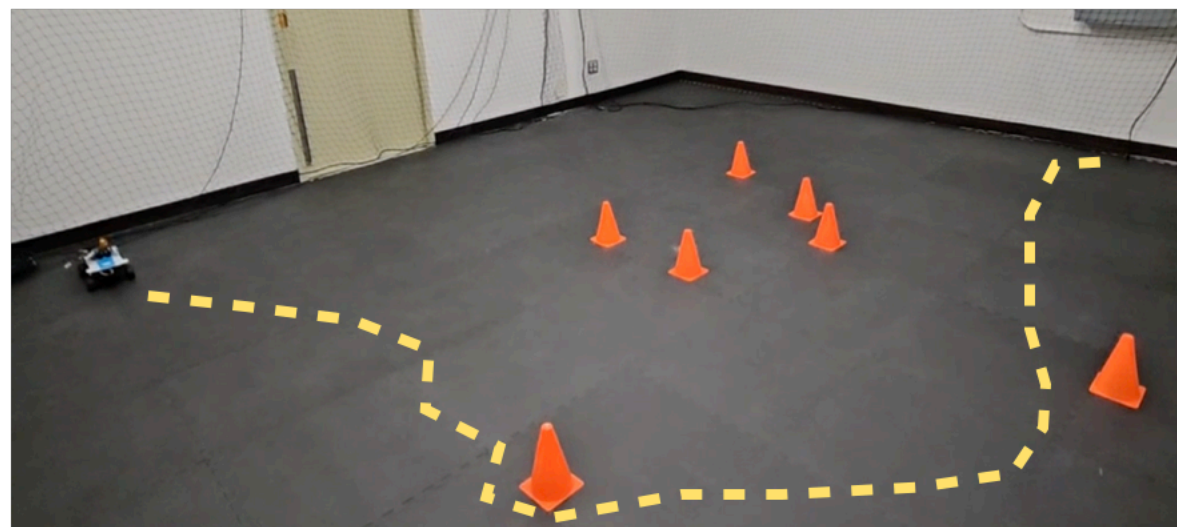
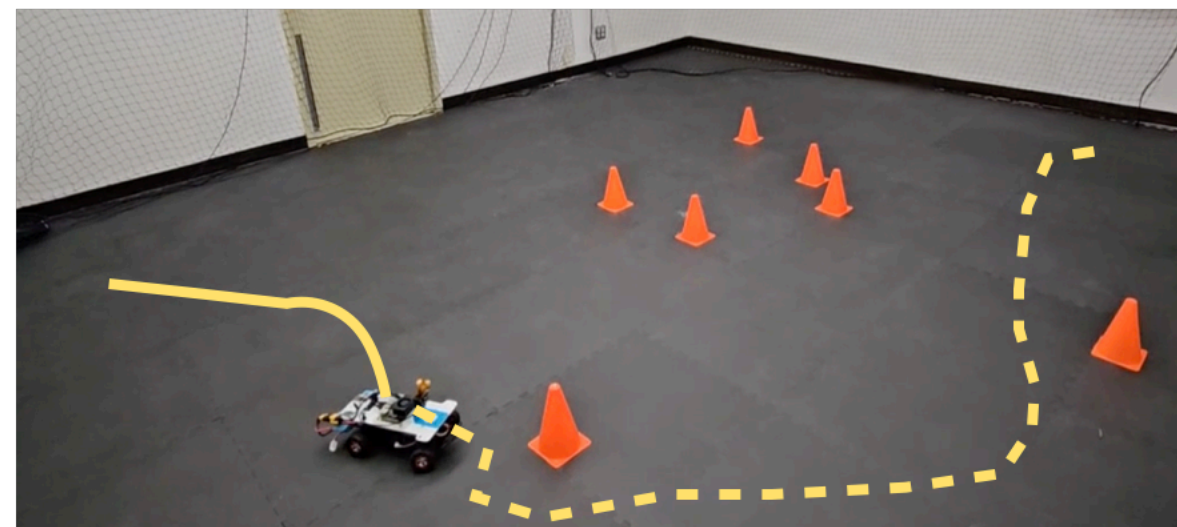
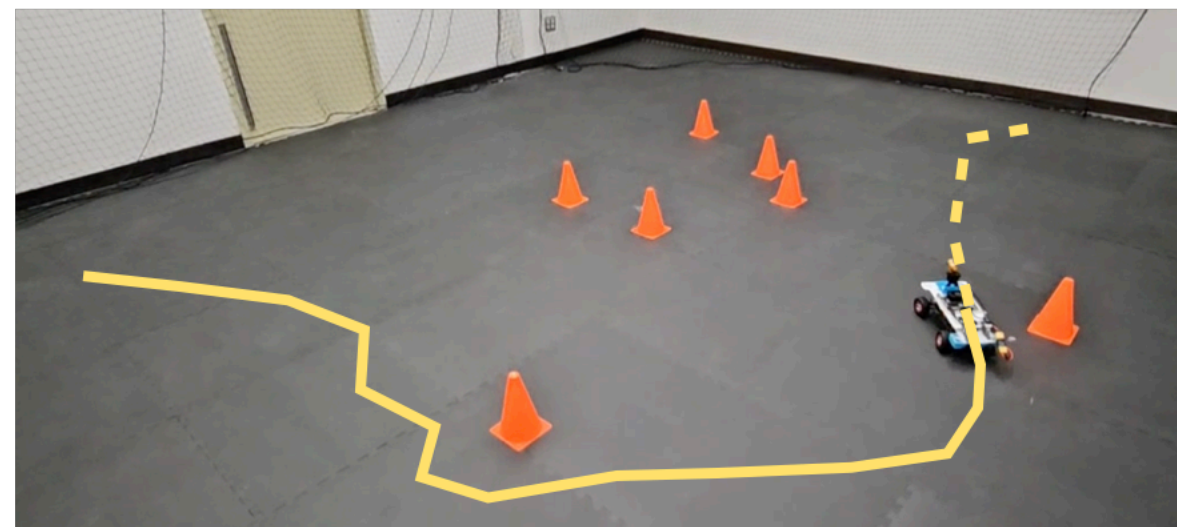
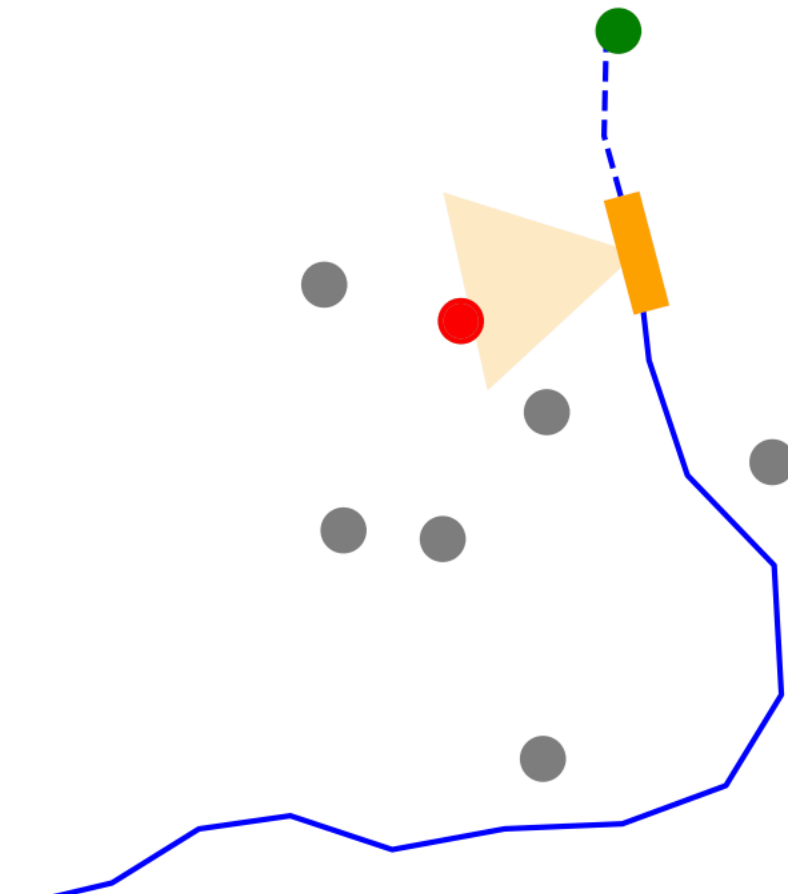
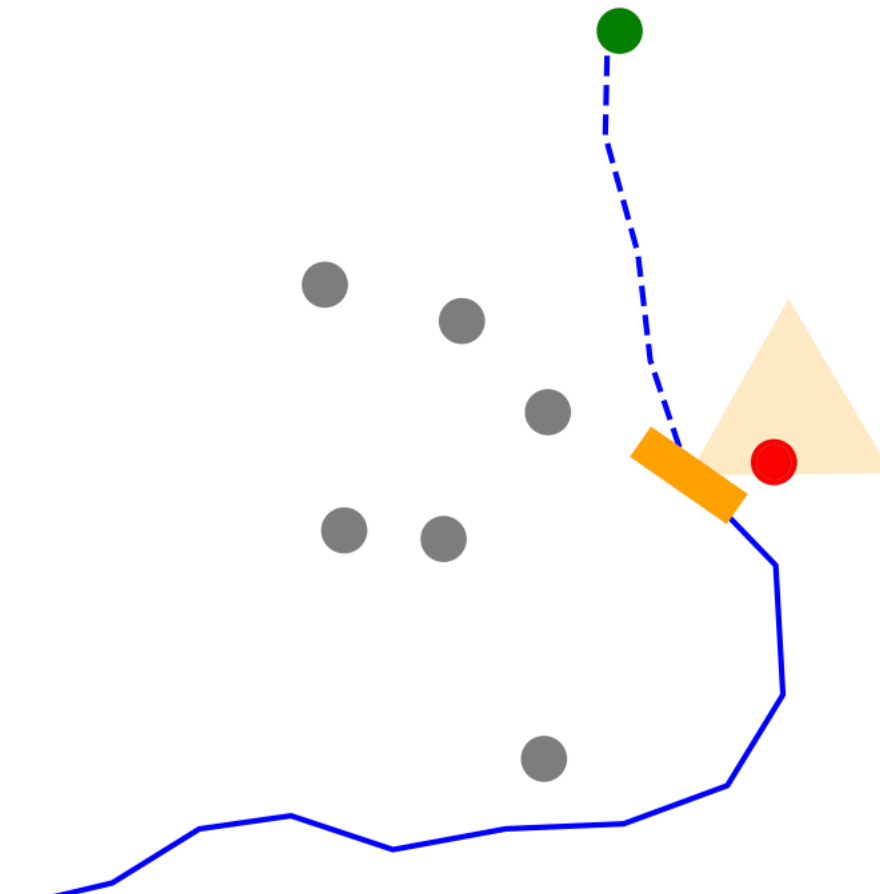
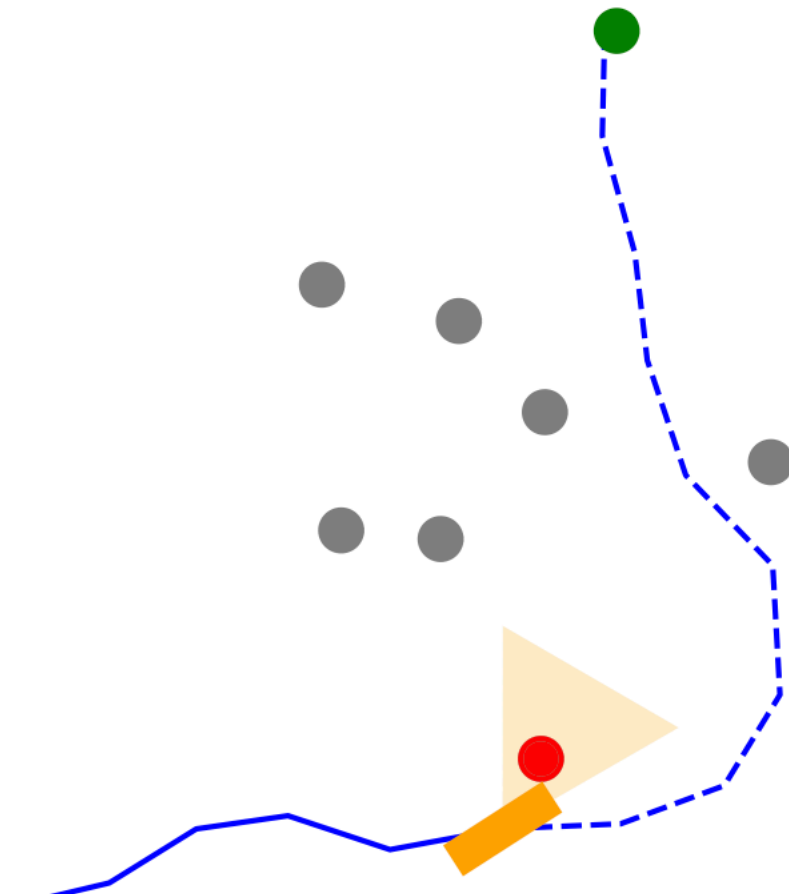
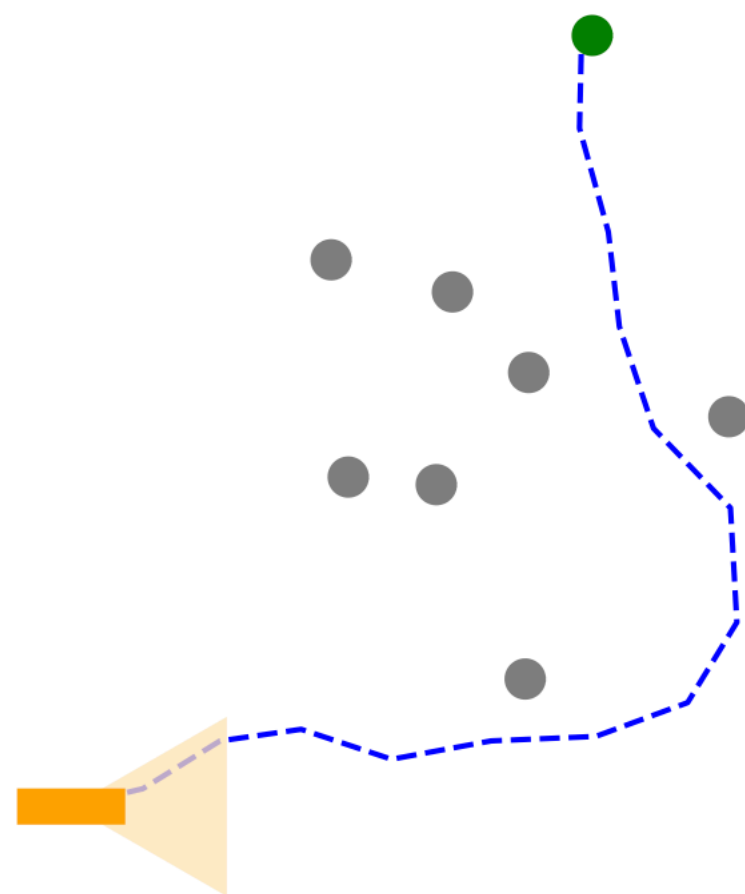
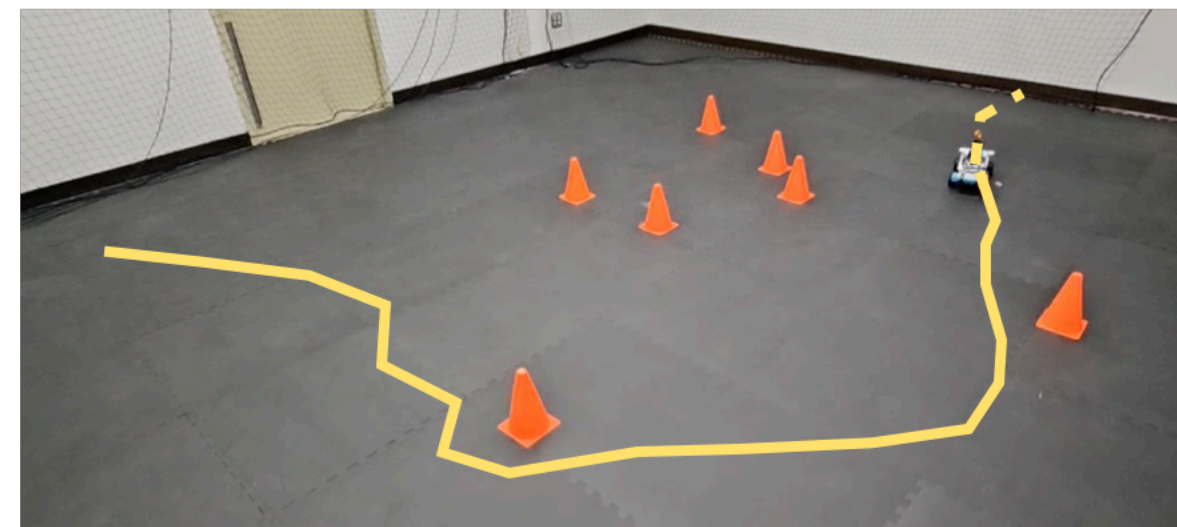
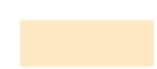


$t = 0$  $t = 7$  $t = 12$  $t = 14$ 

Obstacles



Sensor Skirt



Detected Obstacles



Robot



Goal



Trajectory



Final Trajectory