1 Strong Form

In the case of incompressible material, i.e., $\nu = 0.5$, the strong form is posed as:

$$\begin{cases}
\nabla \cdot \sigma + \mathbf{b} = 0 \\
& \text{in } \Omega_3 \\
-\nabla \cdot \mathbf{u} = \frac{1}{\kappa} p
\end{cases} \tag{1}$$

where \mathbf{u} is the displacement, \mathbf{b} is the body force, κ is the material bulk modulus, σ is the Cauchy stress tensor defined as:

$$\sigma = 2\mu\epsilon - p\mathbf{I},$$

where λ and μ are the Lame parameters, **I** is the indentity matrix, the pressure p is defined as $p = \frac{1}{3}Tr(\sigma)$ and ϵ is the strain tensor defined as:

$$\epsilon(\mathbf{u}) = \frac{\nabla \mathbf{u} + \nabla \mathbf{u}^T}{2}$$

The problem boundary conditions can be stated as:

$$\mathbf{u} = \mathbf{u}_D \quad \text{on } \partial\Omega_D$$

$$\sigma \mathbf{n} = \mathbf{g} \quad \text{on } \partial\Omega_N$$
 (2)

where \mathbf{u}_D is the imposed displacemente and \mathbf{g} is the imposed traction.

It is noted the material bulk modulus might be different for differente dimensions as defined next:

$$\begin{cases}
\kappa = \lambda + \frac{2}{3}\mu & \text{for 3D} \\
\kappa = \lambda + \mu & \text{for plane strain} \\
\kappa = \mu \frac{(2\mu + 3\lambda)}{\lambda + 2\mu} & \text{for plane stress}
\end{cases}$$
(3)

2 Weak Form

Define the following spaces:

$$\mathcal{V} = \{ \mathbf{v} \in H^1(\Omega) \mid \mathbf{v} = 0 \text{ on } \partial \Omega_D \}$$

$$\mathcal{U} = \{ \mathbf{u} \in H^1(\Omega) \mid \mathbf{u} = \mathbf{u}_D \text{ on } \partial \Omega_D \}$$

We multiply the strong form by test functions $v \in \mathcal{V}$ and $q \in L^2(\Omega)$ and pose to find $\mathbf{u} \in \mathcal{U}$ and $p \in L^2(\Omega)$, such that:

$$\begin{cases}
\int_{\Omega} \mathbf{v} \nabla \cdot \boldsymbol{\sigma} \, \partial\Omega + \int_{\Omega} \mathbf{v} \cdot \mathbf{b} \, \partial\Omega &= 0 & \forall \mathbf{v} \in \mathcal{V} \\
-\int_{\Omega} q \nabla \cdot \mathbf{u} \, \partial\Omega - \int_{\Omega} q \frac{1}{\kappa} p \, d\Omega &= 0 & \forall q \in L^{2}(\Omega)
\end{cases}$$
(4)

Integrating by parts:

$$\begin{cases}
\int_{\Omega} \nabla \mathbf{v} \cdot \boldsymbol{\sigma} \, \partial\Omega &= \int_{\partial\Omega_{N}} \mathbf{v} \cdot \mathbf{g} \, d\partial\Omega + \int_{\Omega} \mathbf{v} \cdot \mathbf{b} \, \partial\Omega & \forall \mathbf{v} \in \mathcal{V} \\
-\int_{\Omega} q \nabla \cdot \mathbf{u} \, \partial\Omega - \int_{\Omega} q \frac{1}{\kappa} p \, d\Omega &= 0 & \forall q \in L^{2}(\Omega)
\end{cases} \tag{5}$$

Plugging the formula for σ :

$$\begin{cases}
\int_{\Omega} \nabla \mathbf{v} \cdot (2\mu\epsilon - p\mathbf{I}) \, \partial\Omega &= \int_{\partial\Omega_N} \mathbf{v} \cdot \mathbf{g} \, d\partial\Omega + \int_{\Omega} \mathbf{v} \cdot \mathbf{b} \, \partial\Omega & \forall \mathbf{v} \in \mathcal{V} \\
-\int_{\Omega} q \nabla \cdot \mathbf{u} \, \partial\Omega - \int_{\Omega} q \frac{1}{\kappa} p \, d\Omega &= 0 & \forall q \in L^2(\Omega)
\end{cases}$$
(6)

And rearranging:

$$\begin{cases}
\int_{\Omega} \nabla \mathbf{v} \cdot 2\mu \epsilon - \nabla \mathbf{v} \cdot p \mathbf{I} \, \partial\Omega &= \int_{\partial\Omega_N} \mathbf{v} \cdot \mathbf{g} \, d\partial\Omega + \int_{\Omega} \mathbf{v} \cdot \mathbf{b} \, \partial\Omega & \forall \mathbf{v} \in \mathcal{V} \\
-\int_{\Omega} q \nabla \cdot \mathbf{u} \, \partial\Omega - \int_{\Omega} q \frac{1}{\kappa} p \, d\Omega &= 0 & \forall q \in L^2(\Omega)
\end{cases}$$
(7)

Or, using the strain tensor:

$$\begin{cases}
\int_{\Omega} \epsilon(\mathbf{v}) \cdot 2\mu \epsilon(\mathbf{v}) - p \nabla \cdot \mathbf{v} \, \partial \Omega &= \int_{\partial \Omega_N} \mathbf{v} \cdot \mathbf{g} \, d \partial \Omega + \int_{\Omega} \mathbf{v} \cdot \mathbf{b} \, \partial \Omega & \forall \mathbf{v} \in \mathcal{V} \\
- \int_{\Omega} q \nabla \cdot \mathbf{u} \, \partial \Omega - \int_{\Omega} q \frac{1}{\kappa} p \, d \Omega &= 0
\end{cases} \qquad (8)$$

Note also that the space of p could be $H^1(\Omega)$ since $H^1(\Omega) \in L^2(\Omega)$.