

A PRIMAL HYBRID FINITE ELEMENT METHOD TO SOLVE GENERAL COMPRESSIBLE, QUASI-INCOMPRESSIBLE AND INCOMPRESSIBLE ELASTICITY USING STABLE H(DIV)-L2 SPACES

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Key words: Hybrid finite element method, incompressible elasticity, De Rham compatible spaces

Abstract. Hybrid methods are usually derived from an extended variational principle, in which the interelement continuity of the functions subspace is removed and weakly enforced by means of a Lagrange multiplier. In this context, a new primal hybrid finite element formulation is presented, which uses H(div) conforming displacement functions and discontinuous L2 approximation for pressure together with shear traction functions to weakly enforce tangential displacement. This combination allows the simulation of compressible, quasi-incompressible and fully incompressible elastic solids, with convergence rates independent of its bulk modulus. The proposed approach benefits from the property that the divergence of the H(div) displacement functions is De Rham compatible with the (dual) pressure functions. The hybridization of the tangential displacements is weakly enforced through a lower order shear stress space. This leads to a saddle-point problem that is stable over the full range of poisson coefficient (large compressibility up to incompressible). Moreover, a boundary stress (normal and shear) can be recovered that satisfies elementwise equilibrium. Hybridizing the tangent stresses and condensing the internal degrees of freedom, a positive-definite matrix with improved spectral properties can be recovered. The stability, consistency and local conservation features are discussed in details. The formulation is tested and verified for different test cases.

1 INTRODUCTION

2 GOVERNING EQUATIONS

In general elasticity, the governing equation of a continuum body $\Omega \in \mathbb{R}^3$ is given by:

$$-\nabla \cdot \boldsymbol{\sigma} - \mathbf{b} = \mathbf{0} \text{ in } \Omega, \quad (1)$$

where $\boldsymbol{\sigma}$ denotes the Cauchy stress tensor and \mathbf{b} is the body forces vector. For the well-posedness sake, proper boundary conditions need to be imposed on the Dirichlet boundary ($\partial\Omega_D$) and on the Neumann boundary ($\partial\Omega_N$), as said,

$$\mathbf{u} = \mathbf{u}_D \text{ on } \partial\Omega_D, \quad (2)$$

$$\boldsymbol{\sigma} \cdot \mathbf{n} = \mathbf{h} \text{ on } \partial\Omega_N. \quad (3)$$

The Generalized Hook law relates the stresses and strains by:

$$\boldsymbol{\sigma} = 2\mu\boldsymbol{\varepsilon} + \lambda\text{tr}(\boldsymbol{\varepsilon})\mathbf{I}, \quad (4)$$

where μ and λ are known as Lamé constants, $\boldsymbol{\varepsilon}$ is the infinitesimal strain tensor, computed as:

$$\boldsymbol{\varepsilon} = \frac{1}{2}(\nabla\mathbf{u}^T + \nabla\mathbf{u}), \quad (5)$$

and \mathbf{I} is the identity matrix. By recalling that the hydrostatic pressure is defined as

$$p = -\frac{\text{tr}(\boldsymbol{\sigma})}{3} = -\frac{(2\mu + \lambda)}{3}\text{tr}(\boldsymbol{\varepsilon}), \quad (6)$$

and considering that $\boldsymbol{\sigma} = \boldsymbol{\sigma}' - p\mathbf{I}$, Eq. (1) can be rewritten in a mixed form so the boundary-valued problem reads:

$$\begin{cases} -\nabla \cdot \boldsymbol{\sigma}'(\mathbf{u}) + \nabla p - \mathbf{b} = \mathbf{0} & \text{in } \Omega \\ -\nabla \cdot \mathbf{u} - \frac{3}{2\mu+\lambda}p = 0 & \text{in } \Omega \\ \mathbf{u} = \mathbf{u}_D & \text{on } \partial\Omega_D \\ \boldsymbol{\sigma} \cdot \mathbf{n} = \mathbf{h} & \text{on } \partial\Omega_N \end{cases} \quad (7)$$

where $\boldsymbol{\sigma}' = \mathcal{D}' : \boldsymbol{\varepsilon}$ is the deviatoric stress tensor and \mathcal{D}' is the fourth-order deviatoric part of the elasticity tensor.

One notices that when $\lambda \rightarrow \infty$, Eq. (7) recovers the classical mass conservation form of an incompressible material i.e. $\nabla \cdot \mathbf{u} = 0$.

3 WEAK FORM AND FINITE ELEMENT DISCRETIZATION

The variational form of Eqs. (7) can be obtained by means of the weighted residual method. Depending on the choice of test functions and approximation spaces, different formulations can be derived. We shall start from the most simplistic one, the primal displacement formulation and then move to the fully hybrid scheme.

Let $\mathcal{T} = \{\Omega_e, e = 1, \dots, n_e\}$ be a partition of Ω in n_e finite elements Ω_e with hexahedral shape for $d = 3$. The set \mathcal{E} contains all the element edges E and $\mathcal{E}_0 = \{E \in \mathcal{E} : E \subset \Omega\}$ denotes the internal edges or element interfaces. Let introduce the following function spaces:

3.1 Primal displacement formulation

The primal displacement formulation is obtained by multiplying Eq. (1) by test functions $\mathbf{v} \in \mathbf{V} | \mathbf{V} \subset H^1(\mathcal{T})$ and integrating over the discretized domain \mathcal{T} [1]. The weak statement reads: find $\mathbf{u} \in \mathbf{V}$ such that for all $\mathbf{v} \in \mathbf{V}$,

$$\sum_{\Omega_e \in \mathcal{T}} \int_{\Omega_e} \boldsymbol{\epsilon}(\mathbf{u}) : \mathcal{D}' : \boldsymbol{\epsilon}(\mathbf{v}) d\Omega_e = \sum_{\Omega_e \in \mathcal{T}} \left(\int_{\Omega_e} \mathbf{b} \cdot \mathbf{v} d\Omega_e + \int_{\Gamma_N} \mathbf{h} \cdot \mathbf{v} d\partial\Omega_e \right) \quad (8)$$

is satisfied. Although the primal displacement formulation is simple to implement, it has some limitations i.e. locking phenomena under bending and incompressibility. To overcome these limitations, a shall introduce next the semi-hybrid formulation.

3.2 Semi-hybrid formulation

In [3], the authors proposed a semi-hybrid formulation for Stokes-Brinkman flows that use $H(\text{div})$ conforming velocity functions and discontinuous L^2 approximation for pressure. The same idea can also be applied to elasticity. Let $\mathcal{V} = \mathbf{V} \cap H(\text{div}, \Omega)$, $\Psi \subset L^2(\Omega)$ be spaces of vector functions and piece-wise scalars, respectively, for which the relation $\nabla \cdot \mathcal{V} \in \Psi$ holds. As $H(\text{div})$ approximation only guarantees the continuity of normal components of a vector across elements interface, a hybridization of the tangential velocity is performed. We introduce a third space defined as $\Lambda^t \subset H^{-1/2}(\partial\Omega_e)$, for which the Lagrange multiplier $\boldsymbol{\lambda}^t \in \Lambda^t$ has the meaning of a shear traction to weakly enforce the tangential displacement continuity.

The weak statement for the semi-hybrid formulation thus reads: find $\{\mathbf{u}, p, \boldsymbol{\lambda}^t\} \in \mathcal{V} \times \Psi \times \Lambda^t$ such that for all $\mathbf{v}, q, \boldsymbol{\eta}^t \in \mathcal{V} \times \Psi \times \Lambda^t$:

$$\begin{aligned} \sum_{\Omega_e \in \mathcal{T}} \left(\int_{\Omega_e} \boldsymbol{\epsilon}(\mathbf{v}) : \mathcal{D}' : \boldsymbol{\epsilon}(\mathbf{u}) d\Omega_e + \int_{\Omega_e} p(\nabla \cdot \mathbf{v}) d\Omega_e + \int_{\mathcal{E}^0} \boldsymbol{\lambda}^t \cdot [\![\mathbf{v}]\!] d\partial\Omega_e \right) = \\ \sum_{\Omega_e \in \mathcal{T}} \left(\int_{\Omega_e} \mathbf{v} \cdot \mathbf{f} d\Omega_e + \int_{\Gamma} \mathbf{v} \cdot \boldsymbol{\sigma}_N d\partial\Omega_e \right) \end{aligned} \quad (9)$$

$$\sum_{\Omega_e \in \mathcal{T}} \left(- \int_{\Omega_e} (\nabla \cdot \mathbf{u}) q d\Omega_e - \int_{\Omega_e} \frac{3}{2\mu + \lambda} p q d\Omega_e \right) = \mathbf{0} \quad (10)$$

$$\sum_{\Omega_e \in \mathcal{T}} \int_{\mathcal{E}^0} [\![\mathbf{u}]\!] \cdot \boldsymbol{\eta}^t d\partial\Omega_e = \mathbf{0}, \quad (11)$$

where \mathbf{v} , q and $\boldsymbol{\eta}^t$ are test functions for velocity, pressure and tangential traction, respectively, $[\![\cdot]\!]$ stands for the jump operator on the interface \mathcal{E}^0 between two neighbour elements Ω_1 and Ω_2 ,

defined as $\llbracket \mathbf{v} \rrbracket = \mathbf{v}|_{\Omega_1} - \mathbf{v}|_{\Omega_2}$. Equation (11) plays the role of weakly enforcing the tangential displacement continuity over the element interfaces.

4 NUMERICAL EXAMPLES

4.1 Cantilever beam subjected to an end shear load

Figure ?? shows a cantilever beam. The analysis is carried out with $L = 5$, $a = 0.5$, $b = 0.5$ as in [2]. The beam is assumed to be fixed at $z = 0$ and subjected to an unitary shear-force $F = \int_{-b}^b \int_{-a}^a \sigma_{yz} dx dy = 1$ at $z = L$. The Young modulus is $E = 1$ and different values for the poisson coefficient is used to test the formulation in different compressibility regimes, ie. $\nu = 0.3$, $\nu = 0.4999$ and $\nu = 0.5$.

The analytical solutions for the stresses and displacements are available in [2] and written below:

$$\begin{aligned} \sigma_{xx} &= \sigma_{xy} = \sigma_{yy} = 0, \\ \sigma_{zz} &= \frac{F}{I} yz, \\ \sigma_{xz} &= \frac{F}{I} \frac{2a^2}{\pi^2} \frac{\nu}{1+\nu} \sum_{n=1}^{\infty} \frac{(-1)^n}{n^2} \sin(n\pi x/a) \frac{\sinh(n\pi y/a)}{\cosh(n\pi b/a)}, \\ \sigma_{yz} &= \frac{F}{I} \frac{b^2 - y^2}{2} + \frac{F}{I} \frac{\nu}{1+\nu} \left[\frac{3x^2 - a^2}{6} - \frac{2a^2}{\pi^2} \sum_{n=1}^{\infty} \frac{(-1)^n}{n^2} \cos(n\pi x/a) \frac{\cosh(n\pi y/a)}{\cosh(n\pi b/a)} \right], \end{aligned} \quad (12)$$

and

$$\begin{aligned} u_x &= -\frac{F\nu}{EI} xyz, \\ u_y &= \frac{F}{EI} \left[\frac{\nu}{2} (x^2 - y^2) z - \frac{1}{6} z^3 \right], \\ u_z &= \frac{F}{EI} \left[\frac{1}{2y} (\nu x^2 + z^2) z + \frac{1}{6} \nu y^3 + (1+\nu) \left(b^2 y - \frac{1}{3} y^3 \right) - \frac{1}{3} a^2 \nu y \right. \\ &\quad \left. - \frac{4a^3 \nu}{\pi^3} \sum_{n=1}^{\infty} \frac{(-1)^n}{n^3} \cos(n\pi x/a) \frac{\sinh(n\pi y/a)}{\cosh(n\pi b/a)} \right]. \end{aligned} \quad (13)$$

where $I = 4ab^3/3$ is the second moment of area about the x -axis, and the series above are evaluated with a finite number of terms $n = 5$.

The beam is discretized using hexahedral elements, where the element size is computed as $h_e = 1/2^N$, with $N = \{0, 1, 2, 3, 4\}$. The coarsest ($h_e = 1$) and finest ($h_e = 0.0625$) meshes are shown in Figure 1. A convergence test is performed for displacement, pressure, stress and mass conservation, where the error is computed according to the L^2 norm defined as:

$$\|\mathbf{u} - \mathbf{u}^h\|_{L^2} \doteq \left[\sum_{e=1}^n \int_{\Omega_e} (\mathbf{u} - \mathbf{u}^h)^2 d\Omega_e \right]^{1/2}. \quad (14)$$

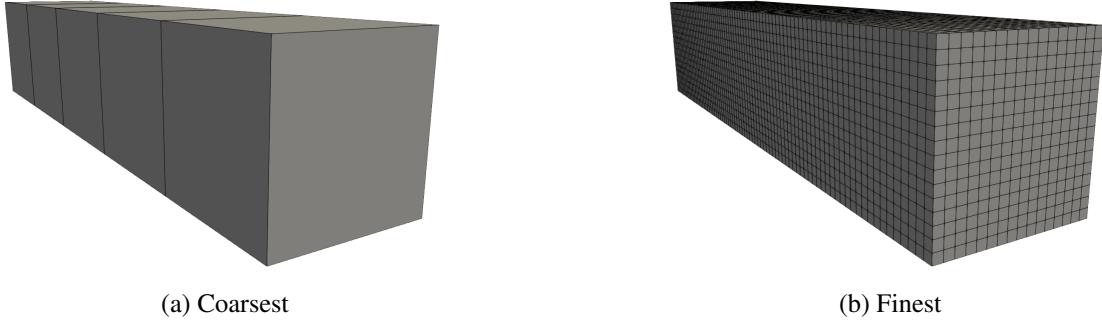


Figure 1: Cantilever beam subjected to an end shear load - meshes used for the convergence test

The results are depicted in Figures 2-4 and present optimal convergence rates of $k + 1$ for the displacement and k for the remaining variables independently of the poisson coefficient. This is a nice feature as many formulations present a locking phenomena under quasi and full incompressibility. For the incompressible case ($\nu = 0.5$), a divergence free displacement field is obtained even for the coarsest mesh thanks to the stable pair $H(\text{div}, \Omega)$ - $L^2(\Omega)$, with the error bounded to the machine precision.

Figure 5 plots the displacement, pressure, normal and shear stresses distributions obtained with the finest mesh using $k = 2$ over the deformed configuration of the beam for the compressible case. The results qualitatively agrees with the reference solution of [2].

5 CONCLUSIONS

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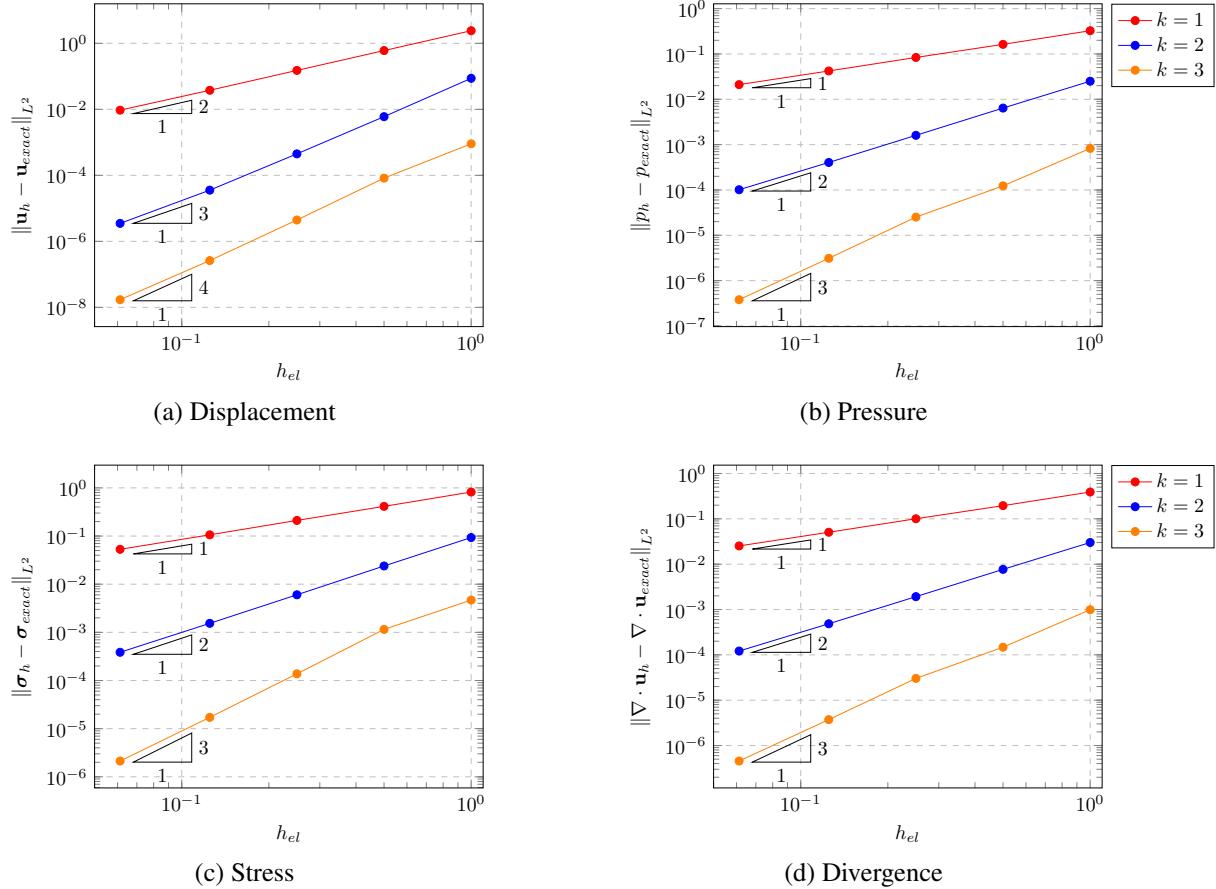


Figure 2: Cantilever beam subjected to an end shear load - convergence analysis for the compressible case ($\nu = 0.3$)

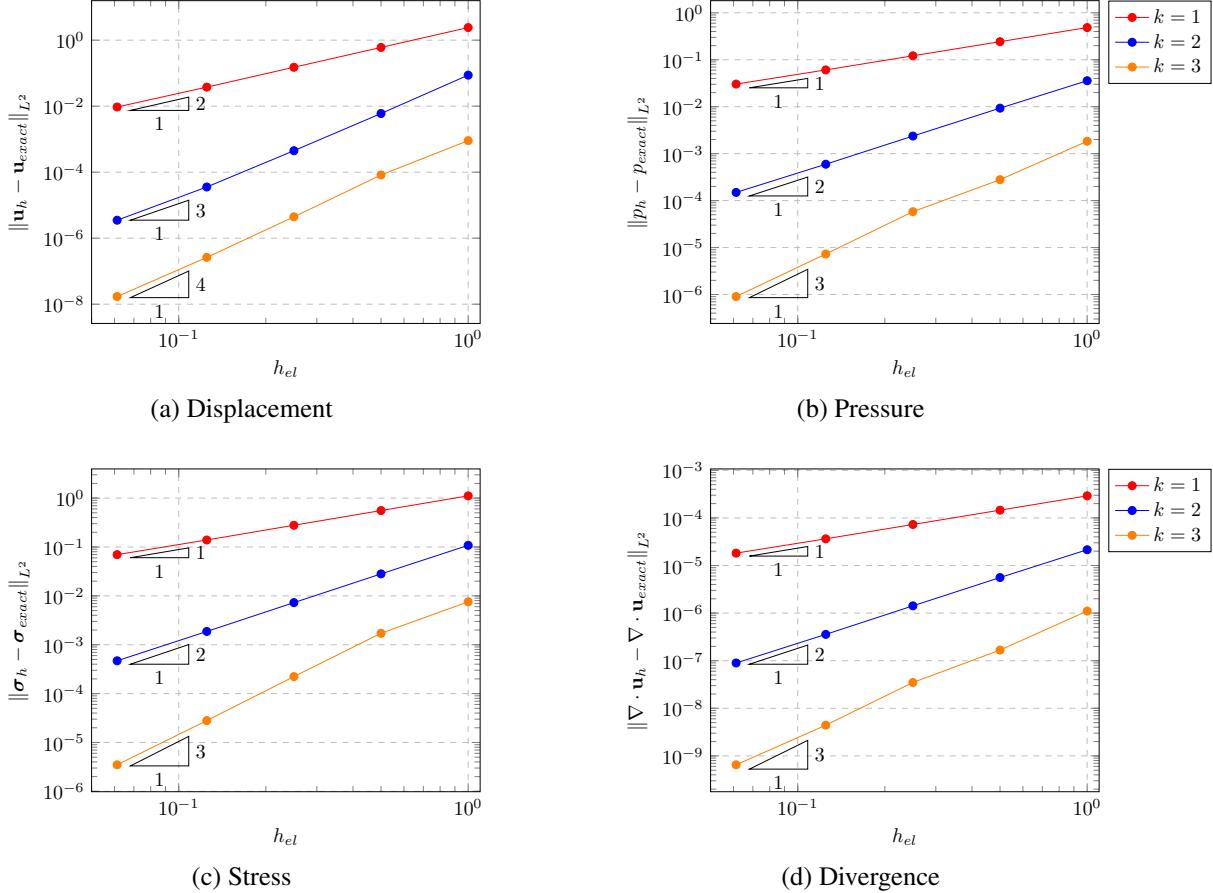


Figure 3: Cantilever beam subjected to an end shear load - convergence analysis for the quasi-incompressible case ($\nu = 0.4999$)

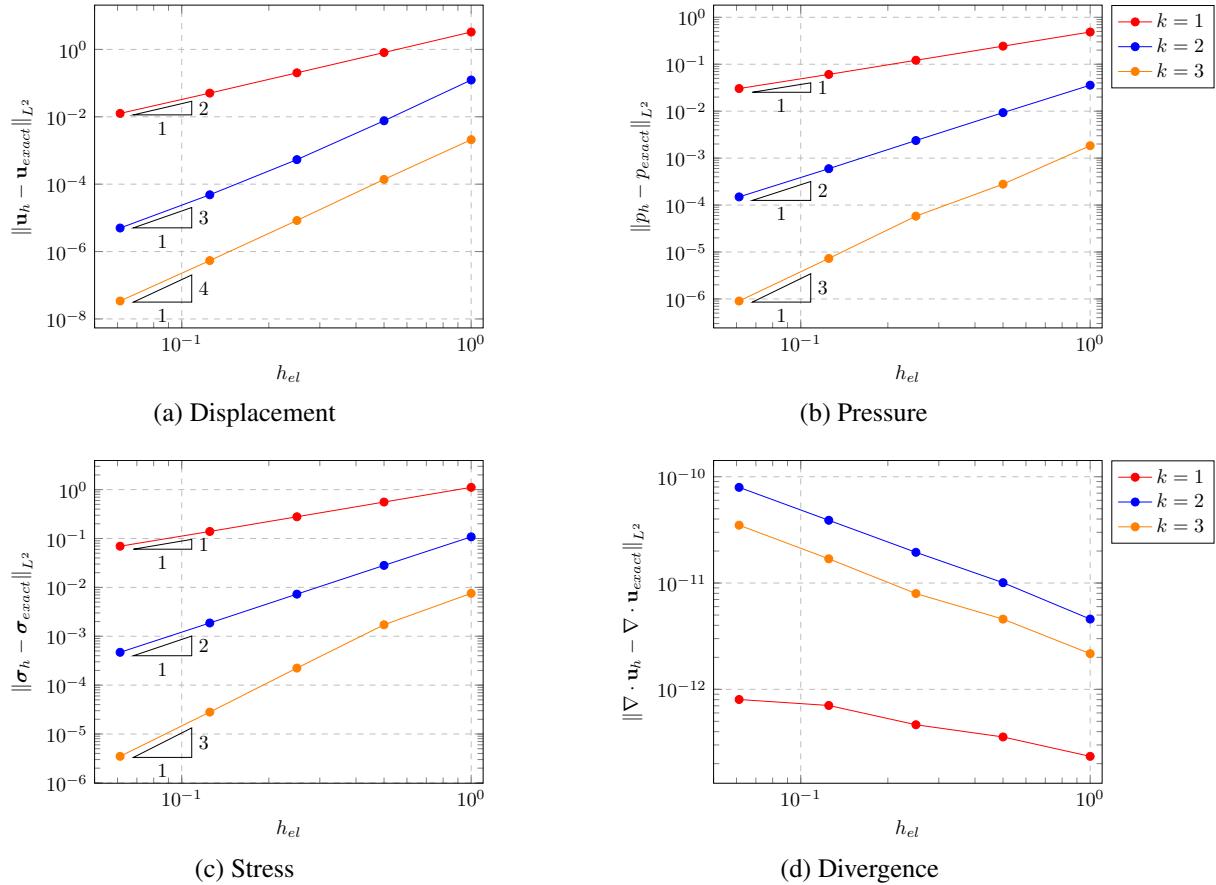


Figure 4: Cantilever beam subjected to an end shear load - convergence analysis for the incompressible case ($\nu = 0.5$)

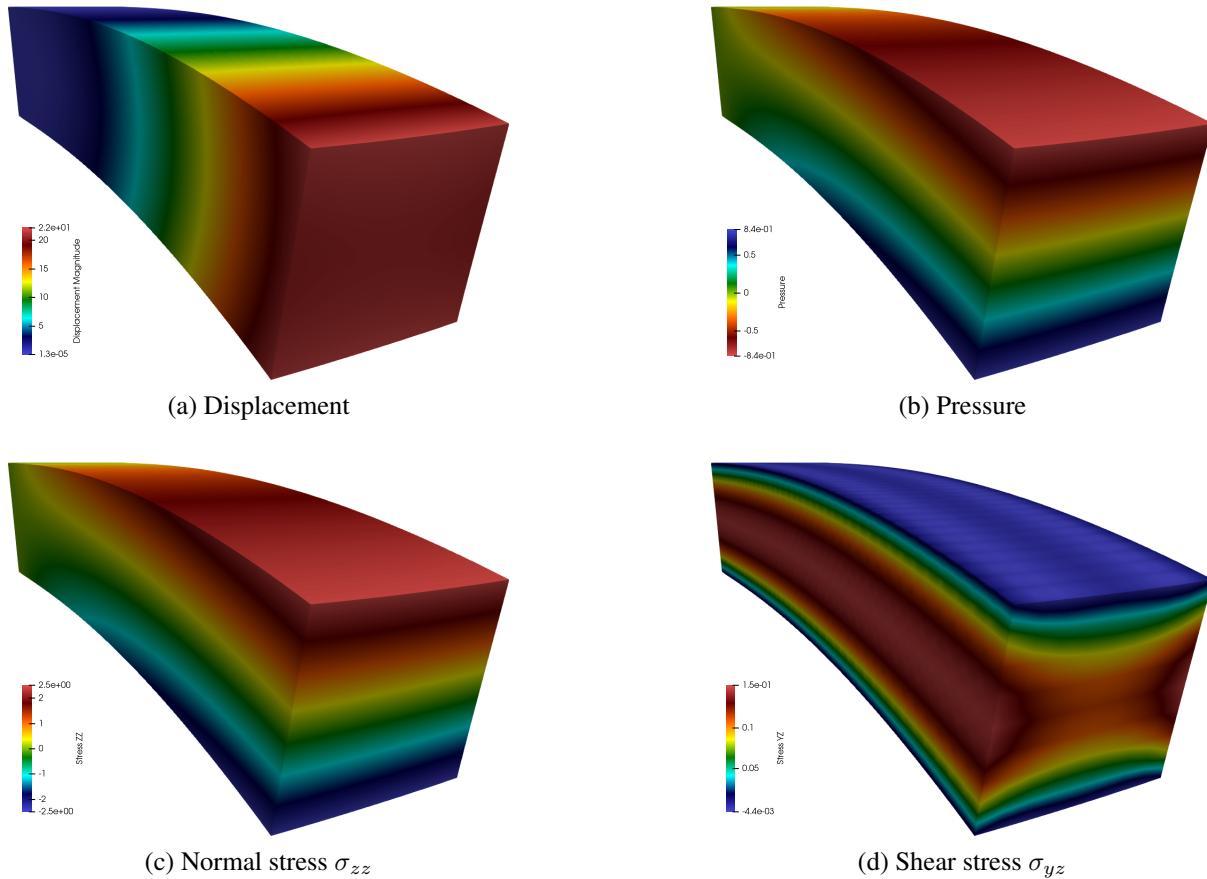


Figure 5: Cantilever beam subjected to an end shear load - snapshots for $\nu = 0.3$