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FRIDAY

Binary \rightarrow groups \rightarrow Ring \rightarrow field \rightarrow vector space

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LINEAR ALGEBRA :: MATRIX

(ii) $f(A) = 0, 1, 2$

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}_{2 \times 3}$$

(iii) $f(B) = 0, 1, 2$

$$B = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}_{3 \times 2}$$

$f: S \rightarrow T$

$f: N \rightarrow R$

$f: N \rightarrow C$

$f: \langle x_n \rangle = \frac{n}{n+1} \text{ or } (-1)^n : \text{ Sequences}$

$f: R \rightarrow R$

$f: R^2 \rightarrow R$

$f: R \times R \rightarrow R$

$f(x, y) = z$

func of one variable

function of two variables

$|R^{n \times n}| = M_n(R) \rightarrow$ Matrix of order n^2 have Real no.'s

TOPICS:- Countable, Uncountable, Countable infinite

(x COUNTABLE INFINITE $\Rightarrow T + 2^{\aleph_0}$)

$N = \{1, 2, 3, 4, 5, \dots\} \quad |Z| = \{-\infty, -2, -1, 0, 1, 2, \dots, \infty\}$

$Q = \left\{ \frac{a}{b} \mid a, b \in Z, b \neq 0 \right\}$

UNCOUNTABLE

$R = Q \cup Q^C \Rightarrow$ Rational \cup Irrational

* Algebra is composition and by composition we mean two objects coming together to form a new object.

* $N = \{1, 2, 3, \dots\}$ set of Natural numbers comes equipped with 2 natural operations $+$ & $*$.

* $Z = \{\dots -2, -1, 0, 1, 2, \dots\}$ the set of integers, comes equipped with 2 natural operations $+$ & \times

* Also Z has a particular property of ADDITIVE inverses i.e. for $a \in Z$, $\exists -a \in Z$ such that $a + (-a) = -a + a = 0$
Where $[0]$ is ADDITIVE IDENTITY

* $Q_1 = \left\{ \frac{a}{b} \mid a, b \in Z, b \neq 0 \right\}$ the set of rationals, also comes equipped with 2 natural operations $+$ & \times

* Also they've property of multiplicative inverse i.e. for $q \in Q_1 \exists \frac{1}{q} \in Q_1$ such that $q \times \frac{1}{q} = 1$

where $[1]$ is the multiplicative identity.

* Functions: $f: S \rightarrow T$ is defined as $x \mapsto f(x)$

1. let $S = T = IN$

then $f: IN \rightarrow IN \Rightarrow x \mapsto x^2$

2. let $S = IN \times IN, T = IN$

Then $f: IN \times IN \rightarrow IN$ st $(a, b) \mapsto (a+b)$ $\forall a, b \in IN$
or $(a, b) \in IN \times IN$

NOTE: $(Z, +) \rightarrow$ Group
 $(Z, +, \cdot) \rightarrow$ Ring
 $(Q, +, \cdot) \rightarrow$ field

BINARY OPERATIONS (B.O.)

Let S be a non-empty set Then a Binary operation

* On S is defined as

$$S \times S \rightarrow S$$

We often write $a * b$ for all $(a, b) \in S$ instead of $*(a, b)$

EXAMPLES:

i) The sets IN, Q, Z, IR, \mathbb{C} and $M_n(IR)$ $(IR^{n \times n})$
All the sets are B.O. under the operation $+$ and \times

ii) For the sets $Z \& IR$, $x * y = x^2 + 2y + 1$ is B.O.

iii) The set $S = \{-1, 0, 1, 2, \dots\}$ is not a B.O. under addition since $-1 \in S$ st $(-1) + (-1) = -2 \notin S$

GROUPS (Base of Abstract Algebra)

Any BO on a set G gives a way of combining the elements.

FUNDAMENTAL DEFINITION: A group G is a non-empty set together with BO

'*' st the following axioms hold:

i) CLOSURE PROPERTY: $\forall a, b \in G \quad a * b \in G$

ii) ASSOCIATIVITY: $\forall a, b, c \in G \quad (a * b) * c = a * (b * c)$

iii) EXISTENCE OF IDENTITY: $\forall a \in G, \exists e \in G$ st
 $e =$ identity element $a * e = e * a = a$

iv) EXISTENCE OF INVERSE: $\forall a \in G \exists a^{-1} \in G$ st
 $a * a^{-1} = a^{-1} * a = e$

EXAMPLES

- (i) $(\mathbb{N}, +)$ not a grp
- (ii) $(\mathbb{Z}, +)$ grp
- (iii) (\mathbb{Z}, \times) not a grp
- (iv) $(\mathbb{Q}_1, +)$ grp
- (v) (\mathbb{Q}_1, \times) not a grp
- (vi) $(\mathbb{Q}_1 - \{0\}, \times)$ grp
- (vii) $(\mathbb{R}_1, +)$ group
- (viii) (\mathbb{R}_1, \times) not a group
- (ix) $(\mathbb{R} - \{0\}, \times)$ not a group
- (x) $(\mathbb{R}^n, +)$ under addition defined as for $x, y \in \mathbb{R}^n$

$$x+y = (x_1+y_1, x_2+y_2, \dots, x_n+y_n)$$

where $x = (x_1, x_2, \dots, x_n)$ belongs to group
 $y = (y_1, y_2, \dots, y_n)$ identity element = 0

- (xi) $(\mathbb{R}^{m \times n}, +)$ under componentwise addition

- (i) Additive identity & Additive inverse not exist
- (ii) all 4 postulates satisfied
- (iii) Multiplicative inverse not exist. 4th not satisfied
- (iv) All 4 postulates satisfied.
- (v) Since 0, belongs to G inverse of 0 not exist
- (vi) " Same reason

$$(X) (x_1+x_2+\dots+x_n) + (e_1+e_2+\dots+e_n) = (x_1+x_2+\dots+x_n)$$

$$(x_1+e_1, x_2+e_2, \dots, x_n+e_n) = (x_1+x_2+\dots+x_n)$$

$$\Rightarrow x_1+e_1=x_1 \text{ or } x_2+e_2=x_2 \dots \text{ etc}$$

$$e_1=e_2=e_3=\dots e_n=0$$

- (xi)

ABELIAN GROUPS

If a group G with BO * satisfies $a * b = b * a \forall a, b \in G$, i.e. commutative property, then G is said to be a (ABELIAN GROUP)

ORDER OF A GROUP

For a finite group G , the number of elements in G is said to be the order of the group.

For an infinite group, the order is infinite.

RINGS Suppose R is a non-empty set equipped with a BO '+' and '.' resp., i.e.

$\forall a, b \in R$, $a+b \in R$ and $a \cdot b \in R$. Then this algebraic structure $(R, +, \cdot)$ is called a ring if the following axioms are satisfied.

- (i) $(R, +)$ is an abelian group
- (ii) In (R, \cdot) multiplication is associative, i.e.
- (iii) $a \cdot (b \cdot c) = (a \cdot b) \cdot c \forall a, b, c \in R$
- (iv) Multiplication is distributive wrt addition i.e.

$$a \cdot (b+c) = a \cdot b + a \cdot c \quad \forall a, b, c \in R$$

$$(b+c)a = b \cdot a + c \cdot a$$

NOTE 1: If there is an element 1 in R st $a \cdot 1 = 1 \cdot a = a \forall a \in R$ then R is a ring with unity (RU)

2. If multiplication in R is st $a \cdot b = b \cdot a \forall a, b \in R$ then we call R is a commutative ring (CR)

FIELD: A ring R with atleast two elements is called a field if (i) it is commutative (ii) has unity (iii) is such that each non-zero element possess multiplicative inverse CRU where each non-zero element has multiplicative inverse.

$CR + RU = CRU$ = Commutative Ring with unity

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* = Union of all operations exist in the world
o = operator

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GROUP (single operation)	RING (TWO operations)	Field ($R, +, \cdot$)
$*: G \times G \rightarrow G$	$(R, +, \cdot)$	+ Multiplicative Inverse
$(G, *)$	$(R, +)$. Abelian grp	All the properties of Ring
i) Closure	ii) closure	iii) All the properties of Ring
ii) Associative	iii) Associative	iv) Multiplicative Identity (RU)
iii) Identity	iv) $a \cdot b = b \cdot a$ (Commutative Ring)	CRU
IV Inverse		
V Commutative (Abelian)		

Example i) The set \mathbb{Z} of all integers with two Binary operation + and . i.e. addition and multiplication, written as $(\mathbb{Z}, +, \cdot)$ → This is called as ring of integers

Homework ii) The set \mathbb{Z}_2 of all even integers → CR

iii) The set $(IR, +, \cdot)$ → Field

iv) The set $(B, +, \cdot)$ → Field

Note * i) CRYPTOGRAPHY extensively uses group and ring theory.

ii) vector spaces are generally considered as n-tuples (in which manner data is stored)

: $F \times V \rightarrow V$, i.e. multiply a scalar with vector, we get a vector

HW (Imp) ✓ $M_n(IR, +, \cdot)$ - Field / Ring - ?
(i) If the set of all the invertible matrices - field / ring?

INTERNAL COMPOSITION: Let A be any set. If (diff. from B.O.) $a \ast b \in A \forall a, b \in A$ and $a \ast b$ is unique, then \ast is said to be an internal composition in A. vector addition

EXTERNAL COMPOSITION: Let V and F be any two sets (on diff. sets) If $a \otimes x \in V \forall x \in F$ and $\forall a \in F$

and $a \otimes x$ is unique, then

is it an external composition in V over F

* : $A \times A \rightarrow A$

o : $F \times V \rightarrow V$

$G \rightarrow 1$

$R \rightarrow 2$

$V \rightarrow 4$ (scalar multiplication)

$S \rightarrow 2$ (vector space operations)

$F \rightarrow 2$ (field operations)

NOTE: $(F, +, \cdot), (V, *, o), (F, +, \cdot), (V, +, \cdot)$

VECTOR SPACE: Let $(F, +, \cdot)$ be a field. The elements of F will be scalars. Let V be a non-empty set whose elements will be called vectors. Then V is called a vector space over a field F, if:

i) There is defined an internal composition in V called addition of vectors and denoted by '+'.

Also for this combination V forms an abelian group.

$\Rightarrow +: V \times V \rightarrow V$

ii) There is an external composition in V over F called scalar multiplication and denoted multiplicatively i.e. $a \cdot x \in V \quad \forall a \in F, x \in V$

The other words V is closed with respect to scalar multiplication. The 2 composition i.e. vector addition and scalar multiplication satisfy the following axioms:-

(a) $a \cdot (x + y) = a \cdot x + a \cdot y \quad \forall x, y \in V, a \in F$

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(b) $(a+b)x = a \cdot x + b \cdot x \forall a, b \in F, x \in V$

(c) $(ab)x = a(bx) \forall a, b \in F, x \in V$

(d) $1 \cdot x = x \forall x \in V$ where 1 is the unity element of field F.

Then V is called a vector space over F, denoted as $V(F)$ or simply V.

EXAMPLES: (i) $\mathbb{R}^n(\mathbb{R}) \rightarrow$ Vector Space (VS)

(ii) $\mathbb{Q}(\mathbb{R}) \rightarrow$ not a VS (scalar multiplication fails)

(iii) $\mathbb{R}(\mathbb{C}) \rightarrow$ not a VS

(iv) $\mathbb{C}(\mathbb{R}) \rightarrow$ VS

(v) $\mathbb{R}^n(\mathbb{R}) \rightarrow$ VS

(w.r.t componentwise addition in \mathbb{R}^n and scalar multiplication)

(vi) $\mathbb{R}^{m \times n}(\mathbb{R}) \rightarrow$

have same field like vectors

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VECTOR SUBSPACES: Let $W \subseteq V$. Then the necessary and sufficient condition for a non-empty subset W of a vector space $V(F)$ to be a subspace is

(i) $W \neq \emptyset$ i.e. in particular $0 \in W$.

(ii) CLOSURE OF W: (a) with respect to the external composition: $\forall \lambda \in F \text{ and }$

$$x \in W \Rightarrow \lambda x \in W$$

(b) w.r.t internal composition: $\forall x, y \in W \text{ (i.e. } x, y \text{ are vectors)}$

$$\text{or } \forall a, b \in F, x, y \in W \quad ax+by \in W$$

$$ax + by \in W \Rightarrow x, y \in W$$

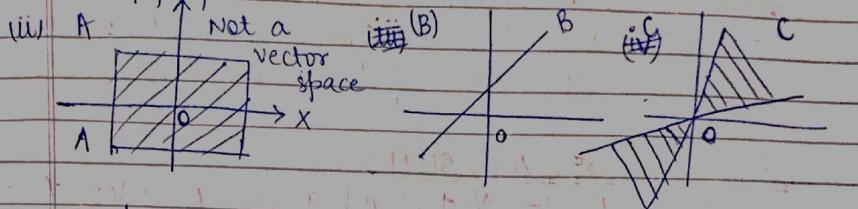
$$x, y \in W \Rightarrow ax + by \in W$$

$$x, y \in W \Rightarrow ax + by \in W$$

Vector Space $\left\{ \begin{array}{l} \text{scalar multiplication} \\ \text{vector addition} \end{array} \right.$

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ii) For every vector space V, the ~~total~~ ^{trivial} subspaces are V



(iii) Suppose, field $\rightarrow \mathbb{R}$
 0 (trivial subspace)

(iv) The solution set of Homogeneous system of LF $AX=0$ with n unknowns

$$x = [x_1, x_2, \dots, x_n]^T \text{ is a subspace of } \mathbb{R}^n$$

(v) The solution of a non-homogeneous system of LF is not a subspace of \mathbb{R}^n where the system is

$$Ax = b, b \neq 0 \Rightarrow 0 \notin W$$

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LINEAR COMBINATION OF VECTORS

Let $V(F)$ be a VS. If $x_1, x_2, \dots, x_n \in V$, then any vector $\alpha = a_1x_1 + a_2x_2 + \dots + a_nx_n$ where $a_1, a_2, \dots, a_n \in F$ is a linear combination of the vectors x_1, x_2, \dots, x_n .

GENERATING SET AND SPAN

Consider a VS $V = (V, +, \cdot)$ and a set of vectors $A = \{x_1, x_2, \dots, x_n\} \subseteq V$. If every vectors $v \in V$ can be expressed as a linear combination of x_1, x_2, \dots, x_n , then A is called a generating set of V .

The set of all linear combinations of vectors in A is called the span of A .

If A spans the VS V , then we write

$$V = \text{span}[A] \text{ or } V = \text{span}(x_1, x_2, \dots, x_n)$$

Smallest generating set

BASIS: Consider a VS, $V = (V, +, \cdot)$ and $A \subseteq V$. A

generating set A of V is called minimal / smallest if \exists no smaller set $A' \subset A \subseteq V$ that spans V .

Note:- Every linearly independent generating set of V is minimal & is called as BASIS of V .

VI result: Let $V = (V, +, \cdot)$ be a vector space and $\beta \subseteq V$, $\beta \neq \emptyset$. Then the following statements are equivalent.

(i) β forms a Basis of V .

(ii) β is a minimal generating set.

(iii) β is a maximal linearly independent set of vectors.

(iv) Every vector $x \in V$ is a linear combination of vectors from β and every linear combination is unique i.e.

$$x = \sum_{i=1}^k \lambda_i b_i = \sum_{i=1}^k \psi_i b_i \quad \& \quad \lambda_i, \psi_i \in F \quad \& \quad b_i \in \beta, \text{ then}$$

$$\lambda_i = \psi_i \quad \# \quad i=1, 2, \dots, k$$

LINEAR DEPENDENCE OF VECTORS

Let us consider a V.S V with $R \in N$ and $x_1, x_2, \dots, x_k \in V$. If there is a non-trivial linear combination such that

(zero) $0_2 = \sum_{i=1}^k \lambda_i x_i$ with atleast one $\lambda_i \neq 0$, then the vectors x_1, x_2, \dots, x_k are LD otherwise LI, i.e.

When $0 = \sum_{i=1}^k \lambda_i x_i$ has only trivial solution such that $\lambda_i = 0 \quad \forall i = 1, 2, \dots, k$, then the vectors x_1, x_2, \dots, x_k are stb LI

Examples:

Ques 1) In $\mathbb{R}^3(\mathbb{R})$ (3-D), the standard basis in $\beta = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$
 $\forall x, y, z \in \mathbb{R}$

$$\text{Sol 1: } xv_1 + yv_2 + zv_3 = x \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + y \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + z \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow x=0, y=0, z=0$$

$$\mathbb{R}^3 = \{(x, y, z) | (x, y, z \in \mathbb{R})\}$$

(iii) In $\mathbb{R}^3(\mathbb{R})$, the basis are $\beta_2 = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\}$

- (Imp)
- NOTE: (i) Every VS $V(F)$ possess a basis.
(ii) A basis is not unique but the elements in bases remains same.
- ** (iii) Basis of $\mathbb{R}^n(\mathbb{R})$ always has n numbers of elements
(iv) For a finite-dimensional VS $V(F)$, the dimension of V is the number of basis vectors of V , and we denote it as $\dim(V)$
- # For example, $\mathbb{R}^3 \oplus (\mathbb{R})$ has dimension 3
or $\dim(\mathbb{R}^3(\mathbb{R})) = 3$
- (v) If $U \subseteq V$ is a subspace of V .
 $\dim(U) \leq \dim(V)$
and $\dim(U) = \dim(V)$ iff $U = V$

RANK: Number of linearly independent rows or columns of a matrix $A \in \mathbb{R}^{m \times n}$ is called rank of A or $r(A)$

NOTE: No. of LI rows in A called rank of A

No. of LI columns in A

Example: $A = \begin{bmatrix} 1 & 2 & 3 & 5 \\ 2 & 4 & 6 & 8 \\ 3 & 6 & 7 & 8 \end{bmatrix} \in \mathbb{R}^{3 \times 4}$ and $r(A) = 2$

$$B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix} \in \mathbb{R}^{4 \times 3}, r(B) = 3$$

NOTE: $\rho(PLA) = \rho(AT)$

(ii) $A_{n \times n}$ is non-singular iff $\rho(A) = n$

(iii) The system of LF $AX+B, b \neq 0$ is consistent or always has a solution iff $\rho(A) = \rho(A|b)$ where $(A|b)$ is called as augmented matrix.

LINEAR TRANSFORMATION: The special func() defined on VS that in some sense "preserve" the structure are called linear transformations.

Example: (i) In calculus, operations of differentiation and integration
(ii) In geometry, rotations, reflections & projections are linear transformation.

DEFINITION: Let V and W be two VS over the same field F . Then a function

$T: V \rightarrow W$ is called a linear transformation from V to W if $x, y \in V$ and $c \in F$, it satisfies

$$(i) T(x+y) = T(x) + T(y)$$

$$(ii) T(cx) = CT(x) \text{ OR } (iii) T(ax+by) = aT(x) + bT(y) \quad \forall a, b \in F$$

EXAMPLE: Define $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ over the field of \mathbb{R} by

$$T(a_1, a_2) = (2a_1 + a_2, a_1)$$

Show that T is a linear transformation

Sol For any $x, y \in \mathbb{R}^2$ let $x = (b_1, b_2)$

$$y = (c_1, c_2)$$

$$x+y = (b_1, b_2) + (c_1, c_2)$$

$$T(x+y) = T(b_1+c_1, b_2+c_2)$$

$$= (2(b_1+c_1) + b_2 + c_2, b_1 + c_1)$$

$$T(x) + T(y) = (2b_1 + b_2, b_1) + (2c_1 + c_2, c_1)$$

$$(2b_1 + b_2 + 2c_1 + c_2, b_1 + c_1)$$

$$T(cx) = CT(x)$$

$$2b_1 + b_2 + 2c_1 + c_2$$

Hence, T is a LT.

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ROTATIONS:

$T_\theta(x_1, x_2)$

(x_1, x_2)

(x_1, α_2)

REFLECTION:

$(\alpha_1, -\alpha_2)$

(x_1, x_2)

PROJECTION:

$(x_1, 0)$

Reflection: Define $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ over the field of Real nos \mathbb{R} such that $T(x_1, x_2) = (x_1, -x_2) \forall (x_1, x_2) \in \mathbb{R}^2$

Then, T is called reflection on x -axis and T is LT (prove)

Projection: Define $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ over the field of \mathbb{R} , such that $T(x_1, x_2) = (x_1, 0) \forall (x_1, x_2) \in \mathbb{R}^2$

Then T is called a projection on x -axis & T is LT (prove)

Let $\alpha_1, \alpha_2 \in \mathbb{R}$ $x_1 = (a, b)$

$\alpha_1 + \alpha_2 = (a, b) + (c, d) = (a+c, b+d)$

$T(x_1 + \alpha_2) = T[(a+c), (b+d)]$

$T[a+c, -(b+d)]$

$T(x_1) + T(\alpha_2) = (a, -b) + (c, -d)$

$(a+c, -(b+d))$

$T(x_1 + \alpha_2) = T(x_1 + \alpha_2)$

$T(c\alpha) = cT(\alpha)$

PROJECTION: Let $x, y \in \mathbb{R}^2$

$x = a_1, a_2$

$y = b_1, b_2$

$$x+y = (a_1, a_2) + (b_1, b_2) = (a_1+b_1, b_2+a_2)$$

$$T(x+y) = (a_1+b_1, 0)$$

$$T(x) + T(y) = (a_1, 0) + (b_1, 0) = (a_1+b_1, 0)$$

$$\therefore T(x+y) = T(x) + T(y)$$

$$T(cx) = cT(x)$$

$$\text{Let } x = (a, b)$$

$$T(cx) = T[ca, cb] = [ca]$$

$$cT(x) = cT(a, b) = ca, 0$$

Q3. Define $T: M_{m \times n}(F) \rightarrow M_{m \times n}(F)$ such that $T(A) = A^t \forall A \in M_{m \times n}(F)$ where t denotes transpose and F is the field of real numbers \mathbb{R} . Prove that T is LT.

For any $A, B \in M_{m \times n}(\mathbb{R})$

$$T(A+B) = (A+B)^t = A^t + B^t = T(A) + T(B)$$

$$T(CA) = (CA)^t = C(A^t) = CT(A), \text{ for any } C \in \mathbb{R}$$

$\therefore T$ is LT

Q4. Define $T: V \rightarrow V$ such that $T(f) = f'' \forall f \in V$ where f'' is derivative of f . Prove T is LT.

(Here, V is the set of all real valued $f(x)$ defined on real line which have derivatives of all orders)

Then $V(\mathbb{R})$ is a VS??

Q5. Let $V = C(\mathbb{R})$ the set of all continuous real valued functions defined on (\mathbb{R}) . Define $T: V \rightarrow \mathbb{R}$ by

$$T(f) = \int_a^b f(t) dt, \text{ for } a, b \in \mathbb{R}, a < b$$

Prove T is LT.

(6) Identity transformation: Define $I_V: V \rightarrow V$ by $I_V(x) = x \forall x \in V$.

Then I_V is LT (prove)

(7) Zero Transformation: Define $T_0: V \rightarrow W$ by $T_0(x) = 0 \forall x \in V$ where V & W are VS. Prove T is LT

RANGE AND NULL SPACE.

Let $T: V \rightarrow W$ be a LT where V & W are vector spaces. We define [NULL space] (or Kernel), $N(T)$ of T to be the set of all vectors ' x ' in V such that

$$T(x) = 0$$

$$\text{i.e. } N(T) = \{x \in V \mid T(x) = 0\}$$

We define the [RANGE space] (or image) of T to be the subset of W consisting of all images (under T) of vectors in V i.e.

$$R(T) = \{T(x) \mid x \in V\}$$

i) Identity Transf: $N(I_V) = \{0\}$

$$R(I_V) = V$$

ii) Zero Transf: $N(T_0) = V$

$$R(T_0) = \{0\}$$

iii) Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ over \mathbb{R} be LT defined by $T(a_1, a_2, a_3) = N(T) = \{x \in \mathbb{R} \mid T(x) = 0\}$

$$\text{Let } x = (a_1, a_2, a_3)$$

$$\Rightarrow T(a_1, a_2, a_3) = (0, 0) \Rightarrow (a_1 - a_2, 2a_3) = (0, 0)$$

$$\Rightarrow a_1 - a_2 = 0 \quad 2a_3 = 0$$

$$\Rightarrow a_1 = a_2 \quad a_3 = 0$$

$$\Rightarrow N(T) = \{(a_1, a_1, 0)\}$$

$$\Rightarrow R(T) = \mathbb{R}^2$$

Result i) The null space & range space for $T: V \rightarrow W$ where V and W are VS, are the subspaces of V & W resp

ii) Let V & W be VS, let $T: V \rightarrow W$ be LT. If $\beta = \{v_1, v_2, \dots, v_n\}$

$= \alpha$

is a basis for V , then $R(T) = \text{span}\{T(\beta)\} = \text{span}\{T(v_1), T(v_2), \dots, T(v_n)\}$ i.e. any LT can be analysed by its action on basis of V .

Definitions Let V and W be VS and let $T: V \rightarrow W$ be LT of $\text{if } N(T)$ and $R(T)$ are finite dimensional, then we define the Nullity of T and Rank of T as dimension of $N(T)$ & $R(T)$ respectively.

RANK NULLITY THEOREM: Let V and W be 2 VS and let $T: V \rightarrow W$ be LT. If V is finite dimensional, then

$$\text{Nullity}(T) + \text{Rank}(T) = \dim(V)$$

to be
under T)

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Q1. If $A \in \mathbb{R}^{5 \times 6}$ with $\rho(A) = 2$ what is the dimension of null space of A? using rank-nullity theorem

Soln. $\rho(A) + \text{Nullity}(A) = \dim(\mathbb{R}^6)$
 $2 + \text{Nullity}(A) = 6$
 $\boxed{\text{Nullity}(A) = 4}$

Matrix of a LT: Let $A \in \mathbb{R}^{m \times n}$ or $\mathbb{C}^{m \times n}$ where rows of $A \in \mathbb{R}^n$ or \mathbb{C}^n & $\begin{bmatrix} c_1 & c_2 & \dots & c_n \end{bmatrix}^T$ columns of $A \in \mathbb{R}^m$ or \mathbb{C}^m . If $x \in \mathbb{R}^n$ then $Ax \in \mathbb{R}^m$ \therefore a matrix $A_{m \times n}$ maps the elements in \mathbb{R}^n into the elements in \mathbb{R}^m $\therefore [T = A : \mathbb{R}^n \rightarrow \mathbb{R}^m]$ with $[Tx = Ax]$. Here, T , defines a linear transformation.

$\boxed{Ax = b}$ $A_{m \times n} x_{n \times 1} = b_{m \times 1}$

PROOF: Let $x_1, x_2 \in \mathbb{R}^n$ $T(x_1 + x_2) = A(x_1 + x_2)$
 $A(x_1) + A(x_2) = T(x_1) + T(x_2)$

For any $c \in \mathbb{R}$ or \mathbb{C}

$$T(cx_1) = Acx_1 = C(Ax_1) = CT(x_1)$$

$\therefore T$ is a linear transformation.

Eg 1. Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT defined by $Tx = Ax$, $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$. Find Tx , when x is given by $\begin{bmatrix} 3 & 4 & 5 \end{bmatrix}^T$.

$$\text{Sol 1. } Tx = Ax = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix} = \begin{bmatrix} 3+8+15 \\ 12+20+30 \end{bmatrix} = \begin{bmatrix} 26 \\ 62 \end{bmatrix}$$

Domain dim Co-domain
Dimension

Eg 2. Write down a basis of $\mathbb{R}^{2 \times 2}(\mathbb{R})$.
 $B = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$ it will generate all the matrices of order 2×2 .

$$x \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + y \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + z \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + w \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} x & y \\ z & w \end{bmatrix}$$

linear combinations

$$\begin{bmatrix} x & y \\ z & w \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \Rightarrow x = y = z = w = 0$$

Hence, it is LI

Eg 3. Let T be a LT defined by $T \begin{bmatrix} 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$, $T \begin{bmatrix} 0 & 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$, $T \begin{bmatrix} 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$, $T \begin{bmatrix} 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$, $T \begin{bmatrix} 0 & 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$, $T \begin{bmatrix} 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$. Find $T \begin{bmatrix} 4 & 3 \\ 5 & 8 \end{bmatrix}$.

The matrices $v_1 = \begin{bmatrix} 1 & 1 \end{bmatrix}$, $v_2 = \begin{bmatrix} 0 & 1 \end{bmatrix}$, $v_3 = \begin{bmatrix} 1 & 0 \end{bmatrix}$, $v_4 = \begin{bmatrix} 0 & 0 \end{bmatrix}$ are LI & generate $\mathbb{R}^{2 \times 2}$.

$$\therefore \begin{bmatrix} 4 & 3 \\ 5 & 8 \end{bmatrix} = x_1 \begin{bmatrix} 1 & 1 \end{bmatrix} + x_2 \begin{bmatrix} 0 & 1 \end{bmatrix} + x_3 \begin{bmatrix} 1 & 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 & 0 \end{bmatrix}$$

$$x_1 = 4$$

$$x_1 + x_2 = 5 \Rightarrow x_2 = 1$$

$$x_1 + x_2 + x_3 = 3 \Rightarrow x_3 = -2$$

$$x_1 + x_2 + x_3 + x_4 = 8 \Rightarrow x_4 = 5$$

$$\therefore \begin{bmatrix} 4 & 3 \\ 5 & 8 \end{bmatrix} = 4v_1 + v_2 - 2v_3 + 5v_4$$

$$T \begin{bmatrix} 4 & 3 \\ 5 & 8 \end{bmatrix} = 4T(v_1) + T(v_2) - 2T(v_3) + 5(T(v_4))$$

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$$A = \left\{ \begin{pmatrix} x & y \\ z & w \end{pmatrix} \mid x, y, z, w \in \mathbb{R} \right\} \dim(A) = 4$$

$$B = \left\{ \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \mid a_{12} = a_{21}, a_{11}, a_{12}, a_{21}, a_{22} \in \mathbb{R} \right\} \dim(B) = 3$$

Symmetric Matrices

$$C = \left\{ \begin{pmatrix} a_{11} & 0 \\ 0 & a_{22} \end{pmatrix} \mid a_{11}, a_{22} \in \mathbb{R} \right\} \dim(C) = 2$$

$$D = \left\{ \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \mid a_{12} = -a_{21}, a_{11}, a_{12}, a_{21}, a_{22} \in \mathbb{R} \right\} \dim(D) = 1$$

Skew-symmetric
all diagonal elements are zero

Order as well as dimensions

$$\beta = \left\{ \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

check it forms a basis of $\mathbb{R}^{2 \times 2}(\mathbb{R})$
Smallest generating set

$$\mathbb{R}^{2 \times 2}(\mathbb{R}) = \left\{ \begin{bmatrix} x & y \\ z & w \end{bmatrix} \mid x, y, z, w \in \mathbb{R} \right\}$$

$$\text{Let } x_1 \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} + x_2 \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} + x_3 \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix} + x_4 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} x_1 & x_1+x_2 \\ x_1+x_2+x_3 & x_1+x_2+x_3+x_4 \end{bmatrix} \therefore \text{This will generate complete } \mathbb{R}^{2 \times 2}$$

Now to check, smallest generating set $\because \mathbb{R}$ forms abelian group under addition
 Let us assume that v_1, v_2, v_3 form a generating set of $\mathbb{R}^{2 \times 2}$.

$$\therefore \{v_1, v_2, v_3\} = \left\{ \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix} \right\}$$

$$x_1 v_1 + x_2 v_2 + x_3 v_3 = x_1 \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} + x_2 \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} + x_3 \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}$$

$$\begin{pmatrix} x_1 & x_1+x_2 \\ x_1+x_2+x_3 & x_1+x_2+x_3 \end{pmatrix} \text{ get same elements in last row}$$

This means, β is the smallest generating set & no other set smaller than β . like $\begin{pmatrix} 1 & 0 \\ 2 & 3 \end{pmatrix} \in \mathbb{R}^{2 \times 2}$ cannot be written as a LC of $\{v_1, v_2, v_3\}$.

Largest LI of v_1, v_2, v_3, v_4 for any x_1, x_2, x_3, x_4

$$x_1 v_1 + x_2 v_2 + x_3 v_3 + x_4 v_4 = 0$$

$$\Rightarrow \begin{bmatrix} x_1 & x_1+x_2 & x_1+x_2+x_3 & x_1+x_2+x_3+x_4 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 \end{bmatrix}$$

$$x_1 = x_2 = x_3 = x_4 = 0$$

To check: Largest LI set of vectors

Let any other vector v_5 i.e. $\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$

$$x_1 v_1 + x_2 v_2 + x_3 v_3 + x_4 v_4 + x_5 v_5 = 0$$

$$x_1 \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} + x_2 \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} + x_3 \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix} + x_4 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} + x_5 \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} = 0$$

$$\begin{bmatrix} x_1+x_5 & x_1+x_2+x_5 \\ x_1+x_2+x_3 & x_1+x_2+x_3+x_4 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$x_2 = x_4 = 0$$

$$x_1 = -x_3 = -x_5$$

\Rightarrow We have a non-trivial solution for the vectors v_1, v_2, v_3, v_4 & v_5 .

$$T \begin{bmatrix} 4 & 3 \\ 5 & 8 \end{bmatrix} = 4 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + \begin{bmatrix} 1 \\ -2 \end{bmatrix} - 2 \begin{bmatrix} 1 \\ -2 \end{bmatrix} + 5 \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 4+1-2-5 \\ 8-2+4+10 \end{bmatrix} = \begin{bmatrix} -2 \\ 20 \end{bmatrix}$$

$$12+3+6+15 = 36$$

Q2. Let T be a LT from $\mathbb{R}^3 \rightarrow \mathbb{R}^2$ over \mathbb{R} where $Tx = Ax$ where $A = \begin{bmatrix} 1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$, $x = [x \ y \ z]^T$. find $\text{ker}(T)$ & Null space (T) dimension range (T) and their dimensions.

Sol2. Null space (T) = $\{V \in \mathbb{R}^3 \mid T(V) = 0\}$

$$TV = 0 \Rightarrow T[v_1, v_2, v_3]^T = 0$$

$$A[v_1, v_2, v_3] = 0$$

$$\begin{bmatrix} 1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$v_1 + v_2 = 0$$

$$-v_1 + v_3 = 0$$

$$\therefore N(T) = \{(v_1, -v_1, v_1) \mid v_1 \in \mathbb{R}\} = \text{Ker}(T)$$

$$\therefore \text{Nullity}(T) = 1 = \{(1, -1, 1)\}$$

$$\therefore \text{Range}(T) = \mathbb{R}^2$$

$$\dim(\text{Range}(T)) = \text{Rank}(T) = 2$$

Also $\text{Range}(T) = \{T(v) \mid v \in \mathbb{R}^3\} = \{Av \mid v \in \mathbb{R}^3\}$

$$\Rightarrow \text{for } v = [v_1, v_2, v_3]^T$$

$$Av = \begin{bmatrix} v_1 + v_2 \\ -v_1 + v_3 \end{bmatrix} = v_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} + v_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + v_3 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\text{Also, } \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} = (1) \begin{bmatrix} 1 \\ -1 \end{bmatrix} + (-1) \begin{bmatrix} 1 \\ 0 \end{bmatrix} + (0) \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\dim(\text{Range}(T)) = \text{Rank}(T) = \{\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}\}$$

Q3. Let T be a LT, $Tx = Ax$ from $\mathbb{R}^2 \rightarrow \mathbb{R}^3$ where $A = \begin{bmatrix} 2 & 1 \\ 1 & 1 \\ 3 & 2 \end{bmatrix}$ & $x = \begin{pmatrix} x \\ y \end{pmatrix}$ find $\text{ker}(T)$, $\text{range}(T)$ & their dimension

Q4. Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT defined by $T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} y+z \\ y-z \end{pmatrix}$ Determine the matrix of T w.r.t. ordered basis $\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \}$ in \mathbb{R}^3 & $y = \{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \}$ in \mathbb{R}^2

Hint 4: $T \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ $T \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ $T \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}$

Linear combination

NOTE: Every domain has linear combination wrt its image in f

$$0 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + 0 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$T(v_1) T(v_2) T(v_3)$

$$\begin{bmatrix} 0 & 1 & 1 \end{bmatrix} \rightarrow w_1$$

$$1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + 1 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\begin{bmatrix} 0 & 1 & -1 \end{bmatrix} \rightarrow w_2$$

$$1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} - 1 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

Rows = $T(v)$

Column = co-domain (y)

Q2. Let V & W be VS in \mathbb{R}^3 let $T: V \rightarrow W$ be defined by

$$T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ x+y \\ x+y+z \end{pmatrix}$$

find the matrix representation of T wrt the ordered pairs basis

$$X = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\} \text{ in } \mathbb{R}^3 (N)$$

$$Y = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\} \text{ in } \mathbb{R}^3 (W)$$

element of a domain images

$$\text{soln. } T \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix} \quad T \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \\ 2 \end{pmatrix} \quad T \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$$

Linear combination

$$\boxed{0} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \boxed{1} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + \boxed{2} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} \text{ (Ans) with }$$

$$\boxed{0} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \boxed{2} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + \boxed{2} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \\ 4 \end{pmatrix} \text{ (Ans) with }$$

$$\boxed{0} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \boxed{1} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + \boxed{2} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} \text{ (Ans) with }$$

$$\begin{bmatrix} 0 & 0 & 0 \end{bmatrix} \text{ after 1 to 3rd row}$$

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 1 \\ 2 & 2 & 2 \end{bmatrix} \text{ 3x3} \rightarrow \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow X$$

Q3. Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT defined by $T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x+y \\ x-z \end{pmatrix}$ find the matrix of T wrt ordered basis.

$$X = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\} \in \mathbb{R}^3 \quad Y = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\} \in \mathbb{R}^2$$

$$\text{Sol3. } T \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad T \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix} \quad T \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\text{LC } \boxed{1} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \boxed{0} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & -1 \end{bmatrix} = T$$

$$\boxed{1} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \boxed{1} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\boxed{2} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \boxed{-1} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Matrix representation of LT

Let V & W be VS over same field F and let $B_1 = (v_1, v_2, \dots, v_n)$ be an ordered basis for V and $B_2 = (w_1, w_2, \dots, w_m)$ be an ordered basis for W . Let $T: V \rightarrow W$ be a LT. We can give a matrix representation

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Examples of group

(i) The set $GL_n(\mathbb{R})$ of all $n \times n$ invertible matrices wrt usual multiplication forms a group. This group is called as General linear group.

(ii) $SL_n(\mathbb{R})$ - Special linear Group is the gp of all $n \times n$ invertible matrices under usual matrix multiplication, consisting of all the matrices whose $\det = 1$.

(iii) The set of matrices

$S = \{e \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, a \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, b \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, c \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}\}$ forms a gp wrt usual matrix multiplication.

*	e	a	b	c
e	e	a	b	c
a	a	e	c	b
b	b	c	e	a
c	c	b	a	e

Composition table

Every row and column consists of all the matrices & no matrix element is repeated.

(iv) The set of C $S = \{1, -1, i, -i\}$ forms a group wrt usual multiplication

*	1	-1	i	-i
1	1	-1	i	-i
-1	-1	1	-i	i
i	i	-i	-1	1
-i	-i	i	1	-1

Quaternion group: Let $S = \{\pm 1, \pm i, \pm j, \pm k\}$ be the set of elements and the binary operation of multiplication is set as $i^2 = j^2 = k^2 = -1$

$$ij = -ji = k, \quad jk = -kj = i, \quad ki = -ik = j$$

S forms a group.

*	1	-1	i	$-i$	j	$-j$	k	$-k$
1	1	-1	i	$-i$	j	$-j$	k	$-k$
-1	-1	1	$-i$	i	$-j$	j	$-k$	k
i	i	$-i$	-1	$+1$	k	$-k$	j	$-j$
$-i$	$-i$	i	1	-1	k	$-k$	$-j$	j
j	j	$-j$	k	$-k$	1	-1	i	$-i$
$-j$	$-j$	k	$-k$	i	-1	i	$-i$	1
k	k	$-k$	j	$-j$	i	$-i$	-1	$+1$
$-k$	$-k$	j	$-j$	i	$-i$	-1	$+1$	-1

e = identity element (1)

This forms a group of numbers. But it is not an abelian group.

(V) The set $\text{Sym}(X)$ of one-one & onto functions on the n -element set X , with multiplication defined to be

the composition of functions. Then $\text{Sym}(X)$ forms a group.

* The elements of $\text{Sym}(X)$ are called permutations and $\text{Sym}(X)$ is called the symmetric group on X .

PERMUTATIONS: Suppose S is a finite having n distinct elements. Then a one-one mapping of S into itself is called a permutation of degree n .

Symbol for a permutation: Let $S = \{a_1, a_2, \dots, a_n\}$ be elements of $S : S \rightarrow S$ is a finite set of n distinct

such that $f(a_1) = b_1, f(a_2) = b_2, \dots, f(a_n) = b_n$. Where the set $\{b_1, b_2, \dots, b_n\} = \{a_1, a_2, \dots, a_n\}$ i.e. $\{b_1, b_2, \dots, b_n\}$ is just an arrangement of $\{a_1, a_2, \dots, a_n\}$. Then f is written as or denoted as

$$f = \begin{pmatrix} a_1 & a_2 & \dots & a_n \\ b_1 & b_2 & \dots & b_n \end{pmatrix}$$

Total number of distinct permutations of degree n . If S is a finite set of n distinct elements then total number of $n!$ or n^n arrangements of elements of S are possible. There will be $n!$ distinct permutations of degree n .

If P_n be the set of all permutations of degree n , then P_n will have $n!$ elements. The set P_n is called the symmetric set of permutations of degree n .

$$S = \{1, 2, 3\} \text{ or } \{a_1, a_2, a_3\}$$

$$f_1 = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix} \quad f_2 = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} \quad f_3 = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} \quad f_4 = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}$$

Example Let S be a finite set with 3 distinct elements $\{1, 2, 3\}$ or $\{a_1, a_2, a_3\}$. Then the set of permutation of degree 3 will be

$$\text{Composition of } f_1 \circ f_2 = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} \quad f_{(123)}$$

$$f_2 \circ f_3 = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix} \quad f_{(132)}$$

$$f_3 \circ f_4 = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} \quad f_{(123)}$$

$$f_5 \circ f_4 = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix} \quad f_{(1)(2)(3)}$$

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Q1. Let $f = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 2 & 3 & 4 & 5 & 1 \end{pmatrix}$ and $g = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 4 & 5 & 3 \end{pmatrix}$
be permutations of degree 5. Find fog &
 gof and check whether $fog = gof$ or not

Sol1. $fog = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 2 & 3 & 5 & 1 & 4 \end{pmatrix}$

$gof = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 2 & 4 & 5 & 3 & 1 \end{pmatrix}$

$\Rightarrow fog \neq gof$

∴ Symmetric groups are in general non-abelian
wrt composition of function.

Task: Prove $\text{Sym}(S)$ is a grp wrt composition of functions
where S is a set of n elements

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symmetric group

$\text{Sym}(S)$, where $S = \{1, 2, 3\}$ i.e. a set of 3 forms
a group wrt. It is denoted by S_3 .
 $\therefore \text{Sym}(S)$ or $S_3 = \{I, (12), (13), (23), (123), (132)\}$

where

$$I = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix} \quad (12) = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} = (12)(3)$$

$$(13) = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix} \quad (13)(2)$$

$$(23) = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} \quad (1)(23)$$

$$(123) = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} \quad (132) = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix}$$

Q1. $f = (123)$ - a permutation of degree 3

$$g = (1, 2, 3) \quad 5$$

Sol1. $f = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} \quad g = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 2 & 3 & 1 & 4 & 5 \end{pmatrix}$
 $\Rightarrow f \neq g$

Q2. $f = (123)$ - a permutation of degree 3

$$g = (123) \quad 5$$

$$h = (123)(45) \quad 5$$

Sol2. $f = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} \quad g = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 2 & 3 & 1 & 4 & 5 \end{pmatrix} \quad h = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 2 & 3 & 1 & 5 & 4 \end{pmatrix}$
 $f \neq g \neq h$

COMPOSITION TABLE FOR S_3

*	I	(12)	(13)	(23)	(123)	(132)
I	I	(12)	(13)	(23)	(123)	(132)
(12)	(12)	I	(123)	(132)	(13)	(23)
(13)	(13)	(132)	I	(23)	(12)	(123)
(23)	(23)	(23)	(132)	I	(12)	(13)
(123)	(123)	(123)	(23)	(12)	I	(132)
(132)	(132)	(132)	(12)	(13)	(132)	I

Q1. Find the inverse of the following permutation

$$(ii) f = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 7 & 5 & 4 & 1 & 2 & 3 & 6 & 8 \end{pmatrix}$$

(iii) (1435) - a permutation degree of 9

$$(iii) (123) = \begin{pmatrix} & & 3 \\ 3 & & \end{pmatrix}$$

NOTE: (i) The inverse 'f⁻¹' of a permutation of degree n, is given by f⁻¹ where

$$f = \begin{pmatrix} a_1 & a_2 & \dots & a_n \\ b_1 & b_2 & \dots & b_n \end{pmatrix}$$

then

$$f^{-1} = \begin{pmatrix} b_1 & b_2 & \dots & b_n \\ a_1 & a_2 & \dots & a_n \end{pmatrix}$$

(ii) A group is stb finite/infinite if it has finite/infinite no. of elements in it and is called as a finite/infinite group.

ORDER OF AN ELEMENT

Let $(G, *)$ be a group. Then an element $a \in G$ has order n if n is the smallest +ve integer such that

$$\underbrace{a * a * \dots * a}_{n\text{-times}} = e \text{ where } e \text{ is the identity element of } (G, *)$$

$$\text{Sol: } (i) f^{-1} = \begin{pmatrix} 7 & 5 & 4 & 1 & 2 & 3 & 6 & 8 \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 4 & 5 & 6 & 3 & 2 & 7 & 1 & 8 \end{pmatrix}$$

$$(ii) f^{-1} = \begin{pmatrix} 4 & 2 & 5 & 3 & 1 & 6 & 7 & 8 & 9 \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 5 & 2 & 4 & 1 & 3 & 6 & 7 & 8 & 9 \end{pmatrix}$$

$$(iii) f^{-1} = \begin{pmatrix} 2 & 3 & 1 \\ 1 & 2 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix}$$

A 2 cycle is always transposition, like
 $(2, 5) = (5, 2)$

* Order of gp (\mathbb{Z}^+) = infinite
 (\mathbb{Z}_+) = not a group

$(\pm 1, \pm i, \pm j, \pm k)$ Quaternion group = 8

* $\{0, 1, 2, 3, 4\} + 5\}$ group of addition module 5
 $a +_m b = r$

$$\frac{0+0}{5}, \frac{1+1}{5}, \frac{2+2}{5}, \frac{3+3}{5}, \frac{4+4}{5} \\ \frac{3+2}{5} = 0$$

Remainder 0, 2, 4, 1, 3

$$0+0=0$$

For eg. (i) If B.O. is taken to be multiplication then 5 | 0(a)
is stb n if $a^n = e$, the identity element and where n is the smallest +ve integer.

(ii) If B.O. is taken to be addition then 0(a) is stb n if $na = e$ (the identity) & where n is smallest positive integer.

NOTE:- If no such n exist, then 0(a) is stb ∞ .

Q1: If the additive group of integers $0(1), 0(-1)$ order of 0, 0(2) ∞

Q2: In the multiplication group of non-zero rational numbers

$$O(2) = \infty$$

$$O(1) = 1$$

$$O(-1) = 2$$

Q3. addition modulo 5
 $\{(0, 1, 2, 3, 4) + 5\} : O(0) = 5, O(1) = 5, O(2) = 5$
 $O(3) = 5, O(4) = 5$

Q4. Quaternion grp: $\{\pm 1, \pm i, \pm j, \pm k\}$

$$O(1) = 1, O(-1) = 2, O(\pm i) = 4, O(\pm j) = 4, O(\pm k) = 4$$

RESULT: i) Order of an element of a finite group is always finite & is less than or equal to the order of the group.

ii) Order of (ab) is always equal to order of (ba) where a and b are elements of a grp.

iii) In the additive group of integers, every element has infinite order except 0.

iv) In the multiplicative group of non-zero rational numbers, only 1 and -1 have finite order.

Subgroups: A subset S of a group $(G, *)$ is said to be a subgroup if the set S itself forms a group wrt $*$.

Result: ii) A subset S of a group $(G, *)$ forms a subgroup if

(a) Identity element $\in S$

(b) for $a \in S \Rightarrow a^{-1} \in S$

(c) for $a, b \in S \Rightarrow a * b \in S$

iii) A subset S of a group $(G, *)$ forms a subgroup of G iff S is non-empty & for $a, b \in S \Rightarrow a * b^{-1} \in S$

Examples: - i) The set $S = \{1, -1\}$ forms a subgroup of $G = \{1, -1, i, -i\}$ wrt multiplication.
 ii) The set of even integers will form a subgroup of additive group of integers.
 Check for a set of odd integers that whether it forms a subgroup of additive group of integers or not ?? (No, because '0' is not in the set).
 iii) In S_3 check which of the following forms a subgroup?

- (a) $\{I\} (12) \} : \text{It forms a subgroup}$
- (b) $\{I, (13)\} : \checkmark$
- (c) $\{I, (23)\} : \checkmark$
- (d) $\{I, (123)\} : (132) \notin D \text{ (inverse)}$
- (e) $\{I, (123), (132)\} : \checkmark$
- (f) $\{(12), (13)\} : I \notin F$
- (g) $\{I, (13), (12)\} : \text{composition of } (13)(12) \notin G$
- (h) $\{(123)\} : \text{Identity } \notin H$
- (i) $\{I\} : \text{Trivial subgroup}$
- (j) $\{S_3\} : \text{Subgroups of subgroups}$

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Sol (a) $I \in A, (21) \in A$
 (Identity element) (Inverse)

Some practice questions

Q1. Write down the order of each element of symmetric group S_3 .

Q2. Check whether the set $S = \{(1, 2, 3, 4, 5, 6), X_7\}$ wrt multiplication modulo 7 forms a group or not. If yes, write down the order of each element.

Q3. Check whether the set $S = \{(1, 2, 3, 4, 5, 6, 0), +_6\}$ forms a group or not. If yes, write down the order of the group.

Cyclic groups : Let G be a group with $BO \neq G$.
 is stb cyclic if \exists an element
 $a \in G$ such that every element $x \in G$ can be written
 in the form $a * a * \dots * a$ or a^n (if * is multi-
 plication) for some integer n .

Also 'a' is called a generator of G .

For Example (i) The group $G_1 = \{1, -1, i, -i\}$ is a cyclic group?

Example G_1 can be written as $G_1 = \{i^0, i^1, i^2, i^3, i^4\}$
 also, $G_1 = \{-i\}, (-i)^2, (-i)^3, (-i)^4\} \therefore i, -i$ are
 generators
 Hence, it forms a cyclic group

(iii) The group of integers with addition forms a cyclic group
 $a + a + \dots + a = na \quad \because n \in \mathbb{Z}$

$a = 1$ generator

(iv) Check whether the following groups are cyclic or not.

(a) $\{1, \omega, \omega^2\}$ wrt multiplication generators are $\underline{\omega^2}$

(b) S_3

(c) $(IR, +)$

(d) $(\{0, 1, 2, 3, 4, 5\}, +_6)$ generators are $(1, 5)$
 $\{1, 1^2, 1^3, 1^4, 1^5, 1^6\} = \{1, 2, 3, 4, 5, 0\}$

HOMOMORPHISM & ISOMORPHISM

* The concept of homomorphism & isomorphism is the most common notation in abstract algebra. Here we are interested in talking about the like algebraic structures.

Particularly, in homomorphism. We say a group $(G, *)$ is homomorphic to another group.

(G', \cdot) when \exists a mapping $f: G \rightarrow G'$ such that f preserves the structure.

$$f(a * b) = f(a) f(b) \quad \forall a, b \in G$$

ISOMORPHISM OF GROUPS

Isomorphic mapping. Suppose $(G, *)$ and (G', \cdot) be two groups A mapping f of $[G \text{ into } G']$ is stb isomorphic groups mapping of G into G' if

ii) f is one-one

$$iii) f(a * b) = f(a) \cdot f(b) \quad \forall a, b \in G$$

If f is an isomorphic mapping of G into G' , then f is called an isomorphism of $[G \text{ into } G']$.

ISOMORPHIC GROUPS

Suppose $(G, *)$ and (G', \cdot) are two groups. We say G is isomorphic to the group $'G'$, if \exists a 1-1 mapping of $[G \text{ onto } G']$ such that

$$f(a * b) = f(a) \cdot f(b) \quad \forall a, b \in G$$

Symbolically we write it as $|G \cong G'|$ or simply

Q1. If \mathbb{R} is an additive group of real numbers and \mathbb{R}_+ the multiplicative group of +ve real no's, prove that the mapping $f: \mathbb{R} \rightarrow \mathbb{R}_+$ defined by $f(x) = e^x \quad \forall x \in \mathbb{R}$ is an isomorphism of \mathbb{R} onto \mathbb{R}_+

Soln. $f: \mathbb{R} \rightarrow \mathbb{R}_+$ such that $f(x) = e^x \quad \forall x \in \mathbb{R}$

$$ii) \text{ Let } x_1, x_2 \in \mathbb{R} \Rightarrow f(x_1 + x_2) = e^{x_1 + x_2} = e^{x_1} e^{x_2} = f(x_1) f(x_2)$$

$$iii) \text{ Let us consider } f(x_1) = f(x_2) \\ e^{x_1} = e^{x_2}$$

taking log on both the sides

$$\Rightarrow \log e^{x_1} = \log e^{x_2} \\ \Rightarrow x_1 = x_2$$

Q2(iii) To show f is onto.

$$\text{Let } y \in \mathbb{R}_+ \Rightarrow \log y \in \mathbb{R}$$

$\Rightarrow f(\log y) = e^{\log y} = y$
This holds true for any $y \in \mathbb{R}_+$

$\Rightarrow f$ is onto

Hence, f is an isomorphism from G onto G'

Task (ii)

Q2. Let \mathbb{R}_+ be the multiplication group of all the real no's of \mathbb{R} be the additive group of all real no's

Show that the mapping

$$g: \mathbb{R}_+ \rightarrow \mathbb{R} \text{ defined by } g(x) = \log(x) \quad \forall x \in \mathbb{R} \text{ is an isomorphism.}$$

Q3. Show that the additive groups of integers

$$G = \dots, -2, -1, 0, 1, 2, 3, \dots$$

is isomorphic to the additive group

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is any fixed integer not equal to zero.

Ques:- Some Important properties of isomorphic groups
Let f be a mapping from G onto G' where $G \cong G'$

- (a) The f -image of the neutral identity e of G is the identity of G' .
- (b) The f -image of the inverse of an element a of G is the inverse of the f -image of a . i.e. $f(a^{-1}) = [f(a)]^{-1}$
- (iii) The order of an element a of G is equal to the order of image of a . i.e. $O(a) = O(f(a))$

Sol:- (a) To show f is 'onto'.

$$\text{Let } y \in G' \Rightarrow \frac{y}{m} \in G \Rightarrow f\left(\frac{y}{m}\right) = y \forall y \in G'$$

Hence, f is onto.

(b) To show f is one-one

$$\text{Let } f(x_1) = f(x_2) \Rightarrow mx_1 = mx_2 \Rightarrow x_1 = x_2 \text{ (onto)}$$

This exists $\forall x_1, x_2 \in G$

$\therefore f$ is one-one

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MATHS

COSETS Let H be a subgroup of a group $(G, *)$ assuming the B.O to be multiplication, then the set $Hx = \{hx : h \in H, x \in G\}$ is said to be a right coset of ' H ' in ' G ', for any $x \in G$ & in, xH is called left coset of ' H ' in ' G ' for any $x \in G$. Cosets may not be subgroups of G but they are the complexes of G , also Hx Complexes: A subset H of group $(G, *)$ is called a complex. It may or may not be a subgroup.

Hx may not be equal to xH ($Hx \neq xH$).

Remark (i) For an abelian group G : $Hx = xH$, for any subgroup H of G .

(ii) For $e \in G$, $eH = He = H$.

Example: Let $G = (\mathbb{Z}, +)$ and let $H = (3\mathbb{Z}, +) \Rightarrow H \subset G$. Write down the distinct right cosets of H & G .

$$H = \{\dots, -9, -6, -3, 0, 3, 6, 9, \dots\}$$

$$\text{Identity} = H+0 = \{-9, -6, -3, 0, 3, 6, 9, \dots\} = H$$

$$H+1 = \{\dots, -8, -5, -2, 1, 4, 7, 10, \dots\} \neq H$$

$$H+2 = \{\dots, -7, -4, -1, 2, 5, 8, 11, \dots\} \neq H$$

$$H+3 = \{\dots, -6, -3, 0, 6, 9, 12, \dots\} \quad \text{H in } 0 \in H+$$

$\therefore H, H+1, H+2$ are the distinct right cosets of G .
 $(\mathbb{Z}, +) = (H) \cup (H+1) \cup (H+2)$ (right cosets)

$$(H) \cup (H+1) \cup (H+2) \quad (\because G \text{ is abelian group})$$

Result: No. of distinct right cosets = No. of distinct left cosets
No matter Group is abelian

Q1: For the symmetric group S_3 & the subgroup $H = \{I, (12)\}$. Write down all the right cosets.

Sol1: Let $S_3 = \{f_1, f_2, f_3, f_4, f_5, f_6\}$

$$\begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix}$$

find left cosets

where $f_1 = I$, $f_2 = (12)$, $f_3 = (23)$, $f_4 = (13)$, $f_5 = (123)$, $f_6 = (132)$

Let $H = \{f_1, f_2\}$

$$H_0 f_1 = \{f_1 \circ f_1, f_2 \circ f_1\} = \{f_1, f_2\}$$

$$H_0 f_2 = \{f_1 \circ f_2, f_2 \circ f_2\} = \{f_2, f_1\}$$

$$H_0 f_3 = \{f_1 \circ f_3, f_2 \circ f_3\} = \{f_3, f_5\}$$

$$H_0 f_4 = \{f_1 \circ f_4, f_2 \circ f_4\} = \{f_4, f_6\}$$

$$H_0 f_5 = \{f_1 \circ f_5, f_2 \circ f_5\} = \{f_5, f_3\}$$

$$H_0 f_6 = \{f_1 \circ f_6, f_2 \circ f_6\} = \{f_6, f_4\}$$

$$S_3 = (H_0 f_1) \cup (H_0 f_3) \cup$$

$$(H_0 f_6)$$

i.e. there are 3 distinct right cosets of 'H' in 'G'.

Q2: For symmetric group S_3 , find the distinct right cosets of $H = \{I, (12), (132)\}$

Sol

$$S_3 = \{f_1, f_2, f_3, f_4, f_5, f_6\}$$

$$f_1 = I$$

$$f_2 = (12)$$

$$f_3 = (23)$$

$$f_4 = (13)$$

$$f_5 = (123)$$

$$f_6 = (132)$$

$$H = \{f_1, f_2, f_6\}$$

$$H_0 f_1 = \{I_0 I, (12)_0 I, (132)_0 I\} = \{I, (12), (132)\} = H$$

$$H_0 f_2 = \{I_0 (12), (12)_0 (12), (132)_0 (12)\} = \{(12), I, (13)\}$$

$$H_0 f_3 = \{I_0 (23), (12)_0 (23), (132)_0 (23)\} = \{(23), (132), (12)\}$$

$$H_0 f_4 = \{I_0 (13), (12)_0 (13), (132)_0 (13)\} = \{(13), (123), (23)\}$$

$$H_0 f_5 = \{I_0 (123), (12)_0 (123), (132)_0 (123)\} = \{(123), (13), I\}$$

$$H_0 f_6 = \{I_0 (132), (12)_0 (132), (132)_0 (132)\} = \{(132), (23), (123)\}$$

INDEX OF A SUBGROUP: Let H be a subgroup of a group G , then the index of H in G is equal to number of distinct right or left cosets in of H in G . It is denoted as $[G:H]$ or $i_{G(H)} = \frac{|G|}{|H|}$

Lagrange's Theorem: The order of a subgroup of finite group G is a divisor of order of the group.

NOTE: But the converse of the thm is not true.
 $S_4 = \{I, (12), (13), (14), (23)\}$

Factors of $24 = 1, 2, 3, 4, 6, 8, 12, 24\}$ subgroup of order 6 don't have cosets.

Abelian groups are always cyclic \Rightarrow they must have the grp of order 6.

** ALTERNATING GROUPS: The cycles in a permutations are called odd(even) acc. as the no. of transpositions are odd(even) resp. The alternating group A_n of S_n is the collection of all even cycles of S_n .

$S_3 = \{I, (12), (13), (23), (123), (132)\}$ length on basis of transposition.

$A_3 = \{I, (132), (123)\}$

NOTE: The order of A_n is always half of the S_n .

Cayley's Theorem: Every finite group G is isomorphic to a group of permutation.

Cayley's theorem even hold true for ∞ group and we restate it as: every group G is isomorphic to a group of one-one, onto fns.

Normal Subgroups: A subgroup $H(G)$ is said to be a normal subgroup of G , if $\forall x \in G$ and $\forall h \in H$,

$$xhx^{-1} \in H$$

Results: Every subgroup of a cyclic grp is normal.
 (ii) A grp having no proper normal subgroups is a simple group.

- (iii) A subgroup H of a group ' G ' is normal iff $xHx^{-1} = H \forall x$
- (iv) $xH = Hx \forall x \in G$. A subgrp ' H of a G ' is a normal subgroup of ' G ' iff every right const of H in G is equal to the every left const of H in G .
- (v) Intersection of 2 normal subgroups is always normal.
- (vi) If ' G ' is a gp & H is a subgp of G with index 2, H is always a normal subgp of G , but converse not true.

Q3. Show that $H = \{1, -1\}$ is normal subgp of $G^3 = \{1, -1, i, -i\}$

$$\text{Sol 3. Let } x = 1 \quad xHx^{-1} = 1 \{1, -1\} 1 = \{1, -1\} = H$$

$$x = -1 \quad xHx^{-1} = -1 \{1, -1\} -1 = \{1, -1\} = H$$

$$x = i \quad xHx^{-1} = i \{1, -1\} i = \{i, -i\} -i = \{1, -1\} = H$$

$$x = -i \quad xHx^{-1} = -i \{1, -1\} i = \{-i, i\} i = \{1, -1\} = H$$

$$\forall x \in G, xHx^{-1} = H$$

Q4. Show that in S_3 , $H_1 = \{I, (12)\}$ is not a normal subgp while $H_2 = \{I, (123), (132)\}$ is a normal subgp (HW)

Q5. Name a non-abelian group & find whose every subgroup is normal
Q6. find the permutation group isomorphic to the multiplicative group $G = \{1, \omega, \omega^2\}$, $G_1 = \{1, -1, i, -i\}$

Q7. Verify Cayley's thm for a cyclic group of order 3

Let G_1 be the cyclic group of order 3. $\therefore G_1 = \{a, a^2, a^3 = e\}$

Then the permutation gp of G_1 is given by $\bar{G}_1 = \{fa, fa^2, fe\}$

$$fa(e) = a \cdot e = a \quad fa^2(a) = e \quad fa(a) = a = e \cdot a$$

$$fa(a) = a \cdot a = a^2 \quad fa^2(a^2) = e \cdot a = a \quad fa(a^2) = a^2 = a \cdot a^2$$

$$fa(a^2) = a \cdot a^2 = e \quad fa^2(e) = a^2 \quad fa(e^2) = e = a^3 = e \cdot a^3$$

$$\begin{pmatrix} a & a^2 & a^3 = e \\ a^2 & e & a \end{pmatrix} \quad fa^2 = \begin{pmatrix} a & a^2 & a^3 = e \\ e & a & a^2 \end{pmatrix} \quad fa^3 = \begin{pmatrix} a & a^2 & a^3 \\ a & a^2 & a^3 \end{pmatrix}$$

Ans 4. Let $S_3 = \{ f_1, f_2, f_3, f_4, f_5, f_6 \} = \{ I, (12), (23), (13), (123) \}$
(i) $H_1 = \{ f_1, f_2 \}$
 $f_2 \circ H_1 \circ f_2^{-1} = (12) \{ I, (12) \} (12) = \{ (12), I \} (12)$
 $= \{ I, (12) \} = H$

$$f_1 \circ H_1 \circ f_1^{-1} = I \{ I, (12) \} I = \{ I, (12) \} I = \{ I, (12) \} = H$$

$$f_5 \circ H_1 \circ f_5^{-1} = (123) \{ I, (12) \} (132) = \{ (123), (23) \} (132) = \{ I, (12) \} = H$$

$$f_3 \circ H_1 \circ f_3^{-1} = (23) \{ I, (12) \} (23) = \{ (23), (123) \} (23) = \{ I, (13) \} \neq H$$

$H_1 = \{ I, (12) \}$ does not form a normal subgroup
 $\therefore f_3 H_1 f_3^{-1} \neq H$

(ii) $H_2 = \{ I, f_5, f_6 \}$

$$f_1 H_2 f_1^{-1} = I \{ I, f_5, f_6 \} I = \{ I, f_5, f_6 \} = H$$

$$f_2 H_2 f_2^{-1} = (12) \{ I, f_5, f_6 \} = \{ (12), (13), (23) \} (12)$$

$$= \{ I, (132), (123) \}$$

$$f_3 H_2 f_3^{-1} = (23) \{ I, (123), (132) \} (23) = \{ (23), (12), (13) \} (23)$$

$$\{ I, (132), (123) \} = H$$

$$f_4 H_2 f_4^{-1} = (123) \{ I, (123), (132) \} (132) = \{ (123), (132), I \} (132)$$

$$\{ I, (123), (132) \} = H$$

$$f_5 H_2 f_5^{-1} = (13) \{ I, (123), (132) \} (13) = \{ (13), (23), (12) \} (13)$$

$$\{ I, (132), (123) \} = H$$

$$f_6 H_2 f_6^{-1} = (132) \{ I, (123), (132) \} (132) = \{ (132), I, (123) \} (132)$$

$$\{ I, (123), (132), I \} = H$$

Therefore, H_2 forms a normal subgroup.

Ans

Let G' is a regular isomorphic to G , $G' = \{f_1, f_2, f_3, f_4\}$

$f_1(1) = 1$	$f_2(1) = -1$	$f_3(1) = i$	$f_4(1) = -i$
$f_1(-1) = -1$	$f_2(-1) = 1$	$f_3(-1) = -i$	$f_4(-1) = i$
$f_1(i) = i$	$f_2(i) = -i$	$f_3(i) = -1$	$f_4(i) = 1$
$f_1(-i) = -i$	$f_2(-i) = i$	$f_3(-i) = 1$	$f_4(-i) = -1$

$$f_1 = \begin{pmatrix} 1 & -1 & i & -i \\ 1 & -1 & i & -i \end{pmatrix}, \quad f_2 = \begin{pmatrix} 1 & -1 & i & -i \\ -1 & 1 & -i & i \end{pmatrix}$$

$$f_3 = \begin{pmatrix} 1 & -1 & i & -i \\ i & -i & -1 & 1 \end{pmatrix}, \quad f_4 = \begin{pmatrix} 1 & -1 & i & -i \\ -i & i & 1 & -1 \end{pmatrix}$$

$$G' = \{f_1, f_{\omega}, f_{\omega^2}\}$$

$f_1(1) = 1$	$f_{\omega}(1) = \omega$	$f_{\omega^2}(1) = \omega^2$
$f_1(\omega) = \omega$	$f_{\omega}(\omega) = \omega^2$	$f_{\omega^2}(\omega) = 1$
$f_1(\omega^2) = \omega^2$	$f_{\omega}(\omega^2) = 1$	$f_{\omega^2}(\omega^2) = \omega$

$$f_1 = \begin{pmatrix} 1 & \omega & \omega^2 \\ 1 & \omega & \omega^2 \end{pmatrix}, \quad f_{\omega} = \begin{pmatrix} 1 & \omega & \omega^2 \\ \omega & \omega^2 & 1 \end{pmatrix}, \quad f_{\omega^2} = \begin{pmatrix} 1 & \omega & \omega^2 \\ \omega^2 & 1 & \omega \end{pmatrix}$$

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i. - i
ii) The set S consisting of a single element 0 with the binary operations defined as $0+0=0$ and $0 \cdot 0=0$ forms a ring. This ring is called a null ring or zero ring.

iii) The set $R = (\{0, 1, 2, 3, 4, 5\}, +_6, \times_6)$

$$S = (\{1, 2, 3, 4, 5\} \times 6)$$

Ring
RUS

CR

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Field

Some special types of rings

* Rings with ^{without} zero divisors

Definition :- A non-zero element of a ring R is called a zero divisor or a divisor of zero if \exists an element $b \neq 0 \in R$ such that either $ab = 0$ or $ba = 0$.

Ring without zero divisors

A ring R is without zero divisors if the product of no two non-zero elements of R is zero. i.e.

$if ab = 0 \Rightarrow either a = 0 \text{ or } b = 0.$

Else, a ring is called as ring with zero divisors

Ex1. $M_2(\mathbb{Z})$ w.r.t usual multiplication & addition
(This is a ring with zero divisors)

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \quad B = \begin{bmatrix} -1 & -1 \\ 1 & 1 \end{bmatrix} \quad 0 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$A \cdot B = 0 \quad A \neq 0, B \neq 0$$
$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

$(\mathbb{Z}, +, \cdot)$ is a ring without zero divisors

Integral Domains - A ring is called an integral domain (ID) if:
i) it is commutative
ii) it has unit elements i.e. it is without zero divisors.

Ex: Every field is an integral domain (ID) but not conversely.

$(\mathbb{Z}, +, \cdot)$: Inverse doesn't exist that's why doesn't form a field but it ID because it is without zero divisors.

Ex: iii) $R = \{0, 1, 2, 3, 4\}$, $+_5$, \times_5

This is a field hence also an ID

the following sets form ID's wrt addition & multiplication, state if they are fields.

set of numbers of the form $b\sqrt{2}$ where $b \in \mathbb{Q}$

set of even integers

set of tve integers.

Date
30/12/22
Friday

UNIT - 2

Date: 1/1

INNER PRODUCT SPACE

The inner product or dot product of \mathbb{R}^n is a function $\langle \cdot, \cdot \rangle$ defined as two entries in the functions $\langle u, v \rangle = a_1 b_1 + a_2 b_2 + a_3 b_3 + \dots + a_n b_n$ where $u = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ \vdots \\ a_n \end{bmatrix} \in \mathbb{R}^n$ and $v = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_n \end{bmatrix} \in \mathbb{R}^n$

The inner product $\langle \cdot, \cdot \rangle$ satisfies the following axioms

- Linearity $\langle au + bv, w \rangle = a \langle u, w \rangle + b \langle v, w \rangle$ where $a, b \in \mathbb{R}$ OR
- Symmetric $\langle u, v \rangle = \langle v, u \rangle$
- Positive definite property: For any $u \in V$, this is always true $\langle u, u \rangle \geq 0$ and more precisely

$$\langle u, u \rangle = 0 \text{ iff } u = 0$$

($V \times V \rightarrow F$)

Inner Product spaces, let V be a VS over F and inner product on V is a function that assigns, to every ordered pairs of $(x, y) \in V$ and a scalar in F , denoted by $\langle x, y \rangle$, such that if $x, y, z \in V$ and $a, b \in F$ we have

$$(i) \langle ax + by, z \rangle = a \langle x, z \rangle + b \langle y, z \rangle$$

$$(ii) \langle \bar{x}, y \rangle = \langle y, x \rangle, \text{ where } \bar{b} \text{ represents the complex conjugate.}$$

$$(iii) \langle x, x \rangle \geq 0 \text{ and } \langle x, x \rangle = 0 \text{ iff } x = 0$$

Q1: Let $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, y = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \in \mathbb{R}^2$ define $\langle x, y \rangle = 2x_1 y_1 + 5x_2 y_2$

Prove that $\langle \cdot, \cdot \rangle$ is an inner product on \mathbb{R}^2

Ans: LINEARITY: Let $a, b \in F$ & let $z = \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} \in \mathbb{R}^2$ then

$$\begin{aligned} \langle ax + by, z \rangle &= 2(ax_1 + by_1)z_1 + 5(ax_2 + by_2)z_2 \\ &= 2(a \langle x, z \rangle + b \langle y, z \rangle) + 5(a \langle x, z \rangle + b \langle y, z \rangle) \\ &= a(2 \langle x, z \rangle + 5 \langle x, z \rangle) + b(2 \langle y, z \rangle + 5 \langle y, z \rangle) \\ &= a \langle x, z \rangle + b \langle y, z \rangle \end{aligned}$$

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$$\text{tr}(AB) = \text{tr}(BA)$$

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$$\begin{bmatrix} ax_1 + by_1 \\ ax_2 + by_2 \end{bmatrix}, z = [z_1, z_2]^T$$

$$\text{RHS: } a \langle x, z \rangle + b \langle y, z \rangle$$

$$a(2x_1z_1 - x_2z_1 - x_1z_2 + 5x_2z_2) +$$

$$b(2y_1z_1 - y_2z_1 - y_1z_2 + 5y_2z_2)$$

$$(iii), \langle x, x \rangle = 2x_1^2 - 2x_1x_2 + 5x_2^2$$

$$\therefore (x_1 - x_2)^2 + x_1^2 + 4x_2^2 \geq 0$$

$$\Leftrightarrow x_1 - x_2 = 0, x_1 = 0, x_2 = 0$$

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\langle x, y \rangle = 2x_1y_1 - x_2y_1 - x_1y_2 + 5x_2y_2$$

$$= 2y_1x_1 - y_2x_1 - y_1x_2 + 5y_2x_2$$

Defn: Let $A \in M_{m \times n}(F)$. We define the conjugate, transpose, or adjoint of A to be the $n \times m$ matrix A^* such that $(A^*)_{ij} = \overline{A_{ji}}$ if i, j are indices.

Q2. Let $V = M_{m \times n}(F)$ & define $\langle A, B \rangle = \text{trace}(B^*A) \forall A, B$.
Prove that \langle , \rangle is IPS on $M_{m \times n}(F)$.

Inner Product Space

$$\Rightarrow A^* = \begin{bmatrix} i & 2+i \\ 5i & 5 \end{bmatrix}$$

$$A^* = \begin{bmatrix} -i & -5i \\ 2-i & 5 \end{bmatrix}$$

$$\text{Sol 2. } \langle A+B, C \rangle = \text{tr}(C^*(A+B))$$

Linearity

$$= \text{tr}(C^*A + C^*B)$$

$$= \text{tr}(C^*A) + \text{tr}(C^*B)$$

$$= \langle A, C \rangle + \langle B, C \rangle$$

$$\langle nA, C \rangle = \text{tr}(C^*(nA)) = n\text{tr}(C^*A) = n \langle A, C \rangle$$

$$\begin{array}{l} (AB)^T = B^T A^T \\ (AB)^* = B^* A^* \end{array} \quad \begin{array}{l} (B^* A)^* = A^* B \\ \text{tr}(A^* B) = \text{tr}(B^* A) \end{array} \quad \begin{array}{l} \langle A, B \rangle = \overline{\text{tr}(B^* A)} \\ \text{Value?} \end{array} \quad \text{IPS}$$

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Symmetric: $\langle A, B \rangle = \text{tr}(B^* A)$

$$\begin{aligned} \langle \bar{A}, B \rangle &= \text{tr}(A^* B) \\ &= \langle B, A \rangle \\ \Rightarrow \langle A, B \rangle &= \langle B, A \rangle \end{aligned}$$

Hence, symmetric is proved.

iii) $\langle A, A \rangle \geq 0$

$$\langle A, A \rangle = \text{tr}(A^* A) = \sum_{i=1}^n (A^* A)_{ii}$$

$$\sum_{i=1}^n \sum_{k=1}^n (A^*)_{ik} A_{ki}$$

$$\sum_{i=1}^n \sum_{k=1}^n (\bar{A}_{ki}) A_{ki}$$

$$\sum_{i=1}^n \sum_{k=1}^n |A_{ki}|^2$$

Now, $\sum_{i=1}^n \sum_{k=1}^n |A_{ki}|^2 = 0 \iff A=0$ and $\sum_{i=1}^n \sum_{k=1}^n |A_{ki}|^2 > 0$ otherwise

NOTE

(i) For each vector $u \in V$, the norm (or the length) of vector u is defined as $\text{norm of } u = \sqrt{\langle u, u \rangle} \rightarrow \|u\|$ in the terms of real numbers.

(ii) If $\|u\|=1$, then u is called as a unit vector

(iii) for any non-zero vector $v \in V$, $u = \frac{v}{\|v\|}$ this process is called the process of normalisation of a vector.

Let V be an inner product space over the field F

Properties then $\forall x, y \in V$ and $c \in F$ we have

(a) $\|cx\| = |c| \|x\|$

(b) $\|x\| = 0 \iff x=0$ in any case $\|x\| \geq 0$

(c) Cauchy-Schwarz inequality
 $| \langle x, y \rangle | \leq \|x\| \|y\|$

(d) Triangle inequality
 $\|x+y\| \leq \|x\| + \|y\|$

02-01-2023

Ques:- In $C[0,1]$. Let $f(t) = t$ and $g(t) = e^t$ compute $\langle f, g \rangle$,
linearity $\|f\|$, $\|g\|$, $\|f+g\|$. Then verify Cauchy-Schwarz's
inequality and triangle inequality.

$$\text{Sol 1. } \langle f, g \rangle = \int_0^1 f(t)g(t)dt = \int_0^1 te^t dt = [e^t(t-1)]_0^1 = 1$$

$$\langle g, f \rangle = \int_0^1 g(t)f(t)dt = \int_0^1 e^t t dt = [e^t(t-1)]_0^1 = 1$$

$$\langle f, f \rangle = \int_0^1 f(t)^2 dt = \int_0^1 t^2 dt = \left[\frac{t^3}{3} \right]_0^1 = \frac{1}{3} = 0.333$$

$$\langle g, g \rangle = \int_0^1 g^2(t)dt = \int_0^1 e^{2t} dt = \left[\frac{e^{2t}}{2} \right]_0^1 = \frac{e^2}{2} - \frac{1}{2} = 3.194$$

$$\|f\| = \sqrt{\langle f, f \rangle} = \sqrt{\frac{1}{3}} = 0.577 \quad \|g\| = \sqrt{\langle g, g \rangle} = \sqrt{e^2 - 1} = 1.786$$

$$f+g = t + e^t$$

$$\langle f(t) + g(t), f(t) + g(t) \rangle = \int_0^1 t^2 + e^{2t} + 2te^t dt$$

$$\left[\frac{t^3}{3} + \frac{e^{2t}}{2} + 2[e^t(t-1)] \right]_0^1 = \frac{e^2}{2} - \frac{13}{6}$$

$$\|f+g\| = \sqrt{\langle f+g, f+g \rangle} = \sqrt{\frac{3e^2 - 13}{6}} = 1.527$$

Δ inequality $\|x+y\| \leq \|x\| + \|y\|$

$$1.527 \leq 0.577 + 1.786$$

$1.527 \leq 2.363$ Hence verified

Cauchy-Schwarz $|\langle f, g \rangle| \leq \|f\| \|g\|$

$$1 \leq 1.03 \quad \text{Hence verified}$$

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Monday

Cauchy-Schwarz inequality

$$|\langle x, y \rangle| \leq \|x\| \|y\|$$

IPS \longleftrightarrow norm
 \longleftrightarrow Mode

$$\|x\| = \sqrt{\langle x, x \rangle}$$

IPS

Definition of norm

Q1. For $x = (a_1, a_2, \dots, a_n)$ & $y = (b_1, b_2, \dots, b_n)$ in F^n define
 $\langle x, y \rangle = \sum_{i=1}^n a_i b_i$. Prove that \langle , \rangle is IPS on F^n .

Sol 1. Linearity: $\langle \alpha x + \beta y, z \rangle = \sum_{i=1}^n (\alpha x_i + \beta y_i) \bar{z}_i$

$$= \sum_{i=1}^n \alpha x_i \bar{z}_i + \sum_{i=1}^n \beta y_i \bar{z}_i = \alpha \sum_{i=1}^n x_i \bar{z}_i + \beta \sum_{i=1}^n y_i \bar{z}_i$$

$$= \alpha \langle x, z \rangle + \beta \langle y, z \rangle$$

Hence, linearity proved.

Symmetry: $\langle \bar{x}, \bar{y} \rangle = \sum_{i=1}^n \bar{x}_i \bar{y}_i = \sum_{i=1}^n \bar{x}_i y_i = \langle y, x \rangle$

$$\langle \bar{x}, \bar{y} \rangle = \langle y, x \rangle$$

Hence, symmetry proved

Positive definite: $\langle x, x \rangle \geq 0$

$$\sum_{i=1}^n x_i \bar{x}_i = \sum_{i=1}^n |x_i|^2 \geq 0 \quad \therefore x \bar{x} = |x|^2$$

$$\sum_{i=1}^n |x_i|^2 = 0 \quad \text{iff} \quad x_i = 0$$

Hence positive definite proved

Q2. In $V = C[0,1]$, the VS of real valued continuous functions on $[0,1]$. For $f, g \in V$, define $\langle f, g \rangle = \int_0^1 f(t)g(t)dt$.
Prove that \langle , \rangle is IPS on V .

Sol 2. $V = C[0,1]$

Linearity: $\langle af(t) + bg(t), h(t) \rangle$

$$= \int_0^1 (af(t) + bg(t)) h(t) dt$$

$$\int_0^1 a f(t) h(t) dt + \int_0^1 b g(t) h(t) dt$$

$$a \langle f, h \rangle + b \langle g, h \rangle$$

Symmetric :- $\langle f(t), g(t) \rangle = \int_0^1 f(t) g(t) dt$

$$= \int_0^1 g(t) f(t) dt = \langle g(t), f(t) \rangle$$

Hence, symmetric proved.

Positive definite :- $\langle f(t), f(t) \rangle = \int_0^1 f(t) f(t) dt = \int_0^1 f(t)^2 dt \geq 0$

$$\int_0^1 f^2(t) dt = 0 \text{ iff } f(t) = 0$$

NOTE: In real valued continuous function over the domain $[0, 1]$ no need to take conjugate complex, to prove symmetric.

ORTHOGONAL AND ORTHONORMAL

Let V be an inner product space (IPS). The vectors $x, y \in V$ are said to be orthogonal (or \perp) if $\langle x, y \rangle = 0$.

A subset S of V is orthogonal if any two distinct vectors in S are orthogonal. A vector $x \in V$ is a unit vector if $\|x\| = 1$. So, finally a subset S of V is orthonormal if S is orthogonal and consists of entirely unit vectors.

$x \quad y \quad z$

Q1. In F^3 prove that $S = \{(1, 1, 0), (1, -1, 1), (-1, 1, 2)\}$ is an orthogonal subset.

$$\langle x, y \rangle = x \cdot y = 1 \cdot 1 + 1 \cdot (-1) + 0 \cdot 1 = 1 - 1 + 0 = 0$$

$$\langle y, z \rangle = y \cdot z = 1 \cdot (-1) + (-1) \cdot 1 + 1 \cdot 2 = -1 + 2 - 1 = 0$$

$$\langle z, x \rangle = z \cdot x = -1 \cdot 1 + 1 \cdot 1 + 2 \cdot 0 = -1 + 1 + 0 = 0$$

Hence S is an orthogonal subset.

(iii) Check whether S is an orthonormal set.

$$\|x\| = \sqrt{(1)^2 + (1)^2 + (0)^2} = \sqrt{2}$$

$$\|y\| = \sqrt{(1)^2 + (-1)^2 + (1)^2} = \sqrt{3}$$

$$\|z\| = \sqrt{(-1)^2 + (1)^2 + (2)^2} = \sqrt{6}$$

$\|x\| = \|y\| = \|z\| \neq 1$ None of the norm is 1.
Hence S is not an orthonormal set.

(iii) In F^3 prove that $S = \left\{ \frac{1}{\sqrt{2}}(1, 1, 0), \frac{1}{\sqrt{3}}(1, -1, 1), \frac{1}{\sqrt{6}}(-1, 1, 2) \right\}$

$$\langle x, y \rangle = x \cdot y = \frac{1}{\sqrt{2}} \cdot \frac{1}{\sqrt{3}} + \frac{1}{\sqrt{2}} \cdot \left(-\frac{1}{\sqrt{3}}\right) + 0 \cdot \frac{1}{\sqrt{3}} = \frac{1}{\sqrt{6}} - \frac{1}{\sqrt{6}} + 0 = 0$$

$$\langle y, z \rangle = y \cdot z = \frac{1}{\sqrt{3}} \cdot \frac{-1}{\sqrt{6}} + \left(\frac{-1}{\sqrt{3}}\right) \cdot \frac{1}{\sqrt{6}} + \frac{1}{\sqrt{3}} \cdot \frac{2}{\sqrt{6}} = \frac{-2}{3\sqrt{2}} + \frac{2}{3\sqrt{2}} = 0$$

$$\langle z, x \rangle = z \cdot x = -\frac{1}{\sqrt{6}} \cdot \frac{1}{\sqrt{2}} + \frac{1}{\sqrt{6}} \cdot \frac{1}{\sqrt{2}} + \frac{2}{\sqrt{6}} \cdot 0 = -\frac{1}{2\sqrt{3}} + \frac{1}{2\sqrt{3}} + 0 = 0$$

$$\|x\| = \frac{1}{\sqrt{2}} \sqrt{(1)^2 + (1)^2 + (0)^2} = 1$$

$$\|y\| = \frac{1}{\sqrt{3}} \sqrt{(1)^2 + (-1)^2 + (1)^2} = 1$$

$$\|z\| = \frac{1}{\sqrt{6}} \sqrt{(-1)^2 + (1)^2 + (2)^2} = 1$$

Hence the $\langle x, y \rangle, \langle y, z \rangle, \langle z, x \rangle = 0$ and $\|x\|, \|y\|, \|z\|$ all are equal to 1. Hence the S is orthonormal subset.

Q2. Let $x = (2, 1+i, i)$, $y = (2-i, 2, 1+2i)$ be the vectors in C^3 . Compute $\langle x, y \rangle, \|x\|, \|y\|, \|x+y\|$.

$$\text{Soln. Linearity: } \langle ax+by, z \rangle = a \langle x, z \rangle + b \langle y, z \rangle$$

$$\begin{aligned} \langle x, y \rangle &= x_1 y_1 + x_2 y_2 + x_3 y_3 \\ &= 2(2-i) + (1+i)2 + i(1+2i) \end{aligned}$$

$$4 - 2i + 2 + 2i + i - 2 = 4 + i$$

$$\|x\| = \sqrt{(2)^2 + (1+i)^2 + (i)^2} = \sqrt{4 + 1 - 1 + 2i - 1} = \sqrt{3+2i}$$

$$\|y\| = \sqrt{(2-i)^2 + (2)^2 + (1+2i)^2} \\ = \sqrt{4+i^2 - 4i + 4 + 1 + 4i^2 + 4i} = \sqrt{4} = 2$$

$$\|x+y\| = \sqrt{\langle x+y, x+y \rangle}$$

$$x+y = 2+2-i, 1+i+2, i+1+2i \\ 4-i, 3+i, 1+3i$$

$$\langle x+y, x+y \rangle = (4-i)^2 + (3+i)^2 + (1+3i)^2 \\ = 16+i^2 - 8i + 9+i^2 + 6i + i + 9i^2 + 6i \\ 26 + 11i^2 + 4i = 4i + 15$$

$$\|x+y\| = \sqrt{\langle x+y, x+y \rangle} = \sqrt{4i+15} = 4i+15$$

Q3. In \mathbb{C}^3 show that $\langle x, y \rangle = x A y^*$ is an IP where

$$A = \begin{bmatrix} 1 & i \\ -i & 2 \end{bmatrix} \text{ compute } \langle x, y \rangle \text{ for } x = (1-i, 2+3i) \\ y = (2+i, 3-2i)$$

$$\text{Sol3. } \langle x, y \rangle = x_1 y_1 + x_2 y_2 + x_3 y_3 \\ (1-i)(2+i) + (2+3i)(3-2i) \\ 2+i - 2i - i^2 + 6 - 4i + 9i - 6i^2 = 15 + 4i$$

GRAM-SCHMIDT ORTHOGONALISATION PROCESS

Let V be an IPS a subset of V is an orthonormal basis of V if it is an ordered basis i.e. orthonormal.

Result: Let V be an inner product space and $S = \{w_1, w_2, \dots, w_n\}$ be a LI subset of V define $S' = \{v_1, v_2, \dots, v_n\}$ such that $v_1 = w_1$ and $v_k = w_k - \sum_{j=1}^{k-1} \frac{\langle w_k, v_j \rangle}{\|v_j\|^2} \cdot v_j$

Q1. In \mathbb{R}^4 let $w_1 = (1, 0, 1, 0)$ and $w_2 = (1, 1, 1, 1)$ and $w_3 = (0, 1, 2, 1)$ then check that w_1, w_2, w_3 is LI and use the gram schmidt orthogonalisation process to compute the orthogonal vectors v_1, v_2, v_3 and further normalize these vectors to obtain the orthonormal set.

$$\text{Sol1. } v_1 = w_1 = (1, 0, 1, 0)$$

$$v_2 = w_2 - \frac{\langle w_2, v_1 \rangle}{\|v_1\|^2} \cdot v_1$$

$$(1, 1, 1, 1) - \frac{(1, 0, 1, 0) \cdot (1, 0, 1, 0)}{(1, 0, 1, 0)^2} (1, 0, 1, 0)$$

$$(1, 1, 1, 1) - \frac{2}{2} (1, 0, 1, 0) = (0, 1, 0, 1)$$

$$v_3 = w_3 - \frac{\sum_{j=1}^2 \langle w_3, v_j \rangle}{\|v_j\|^2} \cdot v_j = (0, 1, 2, 1) - \frac{\sum_{j=1}^2 \langle (0, 1, 2, 1), (0, 1, 0, 1) \rangle}{(\sqrt{2})^2}$$

$$(0, 1, 2, 1) - \left[\frac{2}{2} (0, 1, 0, 1) + \frac{2}{2} (1, 0, 1, 0) \right] = (0, 1, 2, 1) - (1, 1, 1, 1)$$

The orthonormal set of vectors is $\left\{ \frac{v_1}{\|v_1\|}, \frac{v_2}{\|v_2\|}, \frac{v_3}{\|v_3\|} \right\}$

ordered basis of $P_2(\mathbb{R}) = \{1, x, x^2\}$

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Q2. Let V be $P_2(\mathbb{R})$ IP with $\langle f(x), g(x) \rangle = \int_{-1}^1 f(x)g(x) dx$ and consider the subspace $P_2(\mathbb{R})$ with the standard ordered basis β . Use the Gram Schmidt orthogonalisation process to obtain the orthonormal basis for $P_2(\mathbb{R})$.

Soln. As we know, $\beta = \{1, x, x^2\}$

$$\begin{aligned} \therefore v_1 &= w_1 = 1 \\ v_2 &= w_2 - \frac{\langle w_2, v_1 \rangle}{\|v_1\|^2} v_1 = x - \frac{\langle x, 1 \rangle}{\|v_1\|^2} \cdot 1 \\ &= x - \frac{\int_{-1}^1 x dx}{\int_{-1}^1 1 dx} \cdot 1 = x - \frac{\left[\frac{x^2}{2} \right]_{-1}^1}{\left[x \right]_{-1}^1} = x - \frac{0}{2} = x \\ \boxed{v_2 = x} \end{aligned}$$

$$\begin{aligned} v_3 &= w_3 - \frac{\langle w_3, v_1 \rangle}{\|v_1\|^2} v_1 - \frac{\langle w_3, v_2 \rangle}{\|v_2\|^2} v_2 \\ &= x^2 - \frac{\langle x^2, 1 \rangle}{\|v_1\|^2} - \frac{\langle x^2, x \rangle}{\|v_2\|^2} \cdot x \\ &= x^2 - \frac{2/3}{2} - 0 \cdot x = \frac{x^2 - 1}{3} = v_3 \end{aligned}$$

$$\|v_1\| = \sqrt{\langle 1, 1 \rangle} = \left(\int_{-1}^1 dx \right)^{1/2} = \left[x \right]_{-1}^1 = \sqrt{1 - (-1)} = \sqrt{2}$$

$$\|v_2\| = \sqrt{\langle x, x \rangle} = \left(\int_{-1}^1 x^2 dx \right)^{1/2} = \left[\frac{x^3}{3} \right]_{-1}^1 = \sqrt{\frac{1+1}{3}} = \sqrt{\frac{2}{3}}$$

$$\begin{aligned} \|v_3\| &= \sqrt{\left\langle \frac{x^2-1}{3}, \frac{x^2-1}{3} \right\rangle} = \left(\int_{-1}^1 \left(\frac{x^2-1}{3} \right)^2 dx \right)^{1/2} = \left(\int_{-1}^1 x^4 + 1 - \frac{2x^2}{3} dx \right)^{1/2} \\ &= \left(\left[\frac{x^5}{5} + x \right]_{-1}^1 - \frac{2}{3} \left[\frac{x^3}{3} \right]_{-1}^1 \right)^{1/2} = \left(\frac{2}{5} + \frac{2}{9} - \frac{4}{9} \right)^{1/2} = \frac{2-2}{5 \cdot 9} = \frac{2\sqrt{2}}{3\sqrt{5}} \end{aligned}$$

$$\text{Orthogonal set of vectors} = \left(\frac{v_1}{\|v_1\|}, \frac{v_2}{\|v_2\|}, \frac{v_3}{\|v_3\|} \right) = \left(\frac{1}{\sqrt{2}}, \frac{\sqrt{3}x}{\sqrt{2}}, \frac{\sqrt{5}(x^2-1)}{\sqrt{18}} \right)$$

* PROOF OF CAUCHY-SCHWARTZ INEQUALITY

$$|\langle x, y \rangle| \leq \|x\| \|y\|$$

Proof:- Case 1: If $y = 0$, obviously result hold true
Case 2: If $y \neq 0$, then we have $0 \leq \|x - cy\|^2 = \langle x - cy, x - cy \rangle$

$$\langle x, x \rangle + \langle x, -cy \rangle + \langle -cy, x \rangle + \langle -cy, -cy \rangle \quad *$$

without loss of generality (WLOG), let

$$c = \frac{\langle x, y \rangle}{\langle y, y \rangle}$$

$$\begin{aligned} \therefore \langle cx, y \rangle &= c \langle x, y \rangle \\ \langle x, cy \rangle &= \bar{c} \langle x, y \rangle \\ \text{if } F \text{ of } c \end{aligned}$$

$$\begin{aligned} &= \langle x, x \rangle + (-\bar{c}) \langle x, y \rangle + (-c) \langle y, x \rangle + c\bar{c} \langle y, y \rangle \\ &= \|x\|^2 + \left(-\frac{\langle x, y \rangle}{\langle y, y \rangle} \right) \langle x, y \rangle - \left(\frac{\langle x, y \rangle}{\langle y, y \rangle} \right) \langle y, x \rangle + \underline{c\bar{c} \|y\|^2} \\ &= \|x\|^2 - \frac{|\langle x, y \rangle|^2}{\|y\|^2} \Rightarrow 0 \leq \|x\|^2 - \frac{|\langle x, y \rangle|^2}{\|y\|^2} \\ &\Rightarrow 0 \leq \|x\|^2 - \frac{|\langle x, y \rangle|^2}{\|y\|^2} \\ &\Rightarrow |\langle x, y \rangle| \leq \|y\| \|x\| \end{aligned}$$

* Proof of triangle inequality $\|x+y\| \leq \|x\| + \|y\|$

$$\begin{aligned} \|x+y\|^2 &= \langle x+y, x+y \rangle \\ &= \langle x, x \rangle + \langle x, y \rangle + \langle y, x \rangle + \langle y, y \rangle \\ &= \|x\|^2 + \langle x, y \rangle + \langle y, x \rangle + \|y\|^2 \\ &= \|x\|^2 + 2 \operatorname{Re}(\langle x, y \rangle) + \|y\|^2 \\ &\leq \|x\|^2 + 2|\langle x, y \rangle| + \|y\|^2 \quad \text{using Cauchy-Schwarz} \\ &\leq \|x\|^2 + 2\|x\| \|y\| + \|y\|^2 = (\|x\| + \|y\|)^2 \end{aligned}$$

$$\|x+y\| \leq \|x\| + \|y\|$$