

### Eigenvalue Problems:

Let  $A$  be  $n \times n$  square matrix.  $A$  may be singular.

Or non-singular. Consider the hom. system of equations

$$Ax = \lambda x \Rightarrow (A - \lambda I)x = 0 \quad (1)$$

(1) always has a unique or trivial solution. The values of  $\lambda$  for which (1) has a non-trivial solution, are called the eigenvalues or characteristic values of  $A$ . The corresponding non-trivial solution  $x$  are called eigenvectors or characteristic vectors of  $A$ .

- The problem of determining the eigenvalues and eigenvectors of a square matrix  $A$  is called an eigenvalue problem.

- If the hom. system (1) has a non-trivial solution, then the rank of  $(A - \lambda I) < n$

$\Rightarrow (A - \lambda I)$  is a singular matrix

$$\Rightarrow \det(A - \lambda I) = 0$$

$$\Rightarrow \begin{vmatrix} a_{11} - \lambda & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} - \lambda & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} - \lambda \end{vmatrix} = 0$$

Expanding the determinant gives the polynomial of degree  $n$

$$\text{in } \lambda; \quad P_n(\lambda) = |A - \lambda I| = 0 \quad (2)$$

is called characteristic equation of matrix  $A$ .

The roots of (2) are called the eigenvalues.

- Sum of eigenvalues = Trace( $A$ )

- Product of eigenvalues =  $|A|$

- If any one of the eigenvalue is zero then  $|A| = 0 \Rightarrow A$  is Singular matrix.

- If  $A$  is singular  $\Rightarrow |A| = 0 \Rightarrow$  one of the eigenvalues is zero.

- If  $A$  is diagonal or upper triangular or lower triangular matrix, then the diagonal elements of  $A$  are the eigenvalues of  $A$ .
- Let  $\lambda$  be an eigenvalue of  $A$  and  $x$  be the corresponding eigen vector. Then
  - (1)  $\alpha A$  has eigenvalue  $\alpha\lambda$  and the corr. eigenvector is  $x$ .  

$$Ax = \lambda x \Rightarrow \alpha Ax = \alpha \lambda x$$

$$\Rightarrow (\alpha A)x = (\alpha\lambda)x$$
  - (2)  $A^m$  has eigenvalue  $\lambda^m$  and the corr. eigenvector is  $x$  for any positive integer  $m$ .  

$$Ax = \lambda x$$

$$A(Ax) = A(\lambda x) = \lambda(Ax) (= \lambda(\lambda x) = \lambda^2 x)$$

$$\Rightarrow A^2 x = \lambda^2 x$$

Similarly  $A^m x = \lambda^m x$ .
  - (3)  $A^T$  has the eigenvalue  $(1/\lambda)$  and the corresponding eigen vector is  $x$ ; Provided  $A^T$  exists.  

$$\because Ax = \lambda x$$

$$\Rightarrow A^T(Ax) = A^T(\lambda x)$$

$$\Rightarrow (A^T A)x = \lambda(A^T x)$$

$$\Rightarrow Ix = \lambda(A^T x)$$

$$\Rightarrow \frac{1}{\lambda}x = A^T x \text{ or } A^T x = \left(\frac{1}{\lambda}\right)x.$$
  - (4)  $A$  and  $A^T$  have the same eigenvalues.
  - (5) For a real matrix  $A$ , If  $\alpha + i\beta$  is an eigenvalue then  $\alpha - i\beta$  is also an eigenvalue of  $A$ .

Ques Find the eigenvalues and the corresponding eigenvectors of the following matrices.

(1)  $A = \begin{bmatrix} 1 & 4 \\ 3 & 2 \end{bmatrix}$   $(A - \lambda I)x = 0$  — System

characteristic equation of  $A$  is

$$|A - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} 1-\lambda & 4 \\ 3 & 2-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (1-\lambda)(2-\lambda) - 12 = 0$$

$$\Rightarrow 2 - \lambda - 2\lambda + \lambda^2 - 12 = 0$$

$$\Rightarrow \lambda^2 - 3\lambda - 10 = 0$$

$$\Rightarrow \lambda^2 - 5\lambda + 2\lambda - 10 = 0$$

$$\Rightarrow \lambda(\lambda - 5) + 2(\lambda - 5) = 0$$

$$\Rightarrow \lambda = -2, 5. \quad \text{— Two eigen values.}$$

Corresponding to eigen value  $\lambda = -2$

$$(A + 2I)x = 0$$

$$\Rightarrow \begin{bmatrix} 3 & 4 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow 3x + 4y = 0$$

$$\Rightarrow x = -\frac{4}{3}y$$

$$\text{let } y = 1 \Rightarrow x = -\frac{4}{3}$$

$$\therefore \text{or } y = 3, \Rightarrow x = -4.$$

So Eigen Vector is  $\begin{bmatrix} -4 \\ 3 \end{bmatrix}$  or  $\begin{bmatrix} -4/3 \\ 1 \end{bmatrix}$ .

$$\lambda = 5$$

$$(A - 5I)x = 0$$

$$\begin{bmatrix} 4 & 4 \\ 3 & -3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow -4x + 4y = 0$$

$$\Rightarrow x = y \quad \text{let } x = y = 1$$

So Eigen vector is  $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$$\text{Ques: } A = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$

$(A - \lambda I)x = 0 \rightarrow$  System of hom. equation

$$|A - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} 1-\lambda & 1 \\ -1 & 1-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (1-\lambda)^2 + 1 = 0$$

$$\Rightarrow \lambda^2 - 2\lambda + 2 = 0$$

$$\Rightarrow \lambda = 1 \pm i$$

Corr. to  $\lambda = 1+i$

$$(A - \lambda I)x = 0$$

$$\Rightarrow \left( \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} - (1+i) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \begin{bmatrix} -i & 1 \\ -1 & -i \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow -ix + y = 0 \Rightarrow x = +i y \quad (-iy)$$

$$\text{and } -x - iy = 0$$

$$y = 1, \quad x = -i$$

So Eigen vector is  $\begin{bmatrix} -i \\ 1 \end{bmatrix}$

Corr. to  $\lambda = 1-i$

$$(A - \lambda I)x = 0$$

$$\begin{bmatrix} i & 1 \\ -1 & i \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$ix + y = 0 \Rightarrow y = -ix$$

$$x = 1; \quad y = -i$$

So eigenvector is  $\begin{bmatrix} 1 \\ -i \end{bmatrix}$  or  $\begin{bmatrix} i \\ 1 \end{bmatrix}$

→ Eigenvectors corresponding to distinct eigenvalues are linearly independent.

Ques (1)  $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \\ 2 & 0 & 3 \end{bmatrix}$

(3)  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

(2)  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$

(4)  $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Cayley - Hamilton Thm: Every matrix 'A' satisfies its own characteristic equation.

— Verify Cayley Hamilton Thm for  $A = \begin{bmatrix} 1 & 2 & 0 \\ -1 & 1 & 2 \\ 1 & 2 & 1 \end{bmatrix}$ .

Also obtain  $A^1$  and  $A^3$ .

Sol  $A = \begin{bmatrix} 1 & 2 & 0 \\ -1 & 1 & 2 \\ 1 & 2 & 1 \end{bmatrix}$

The char. equation of A is

$$|A - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} 1-\lambda & 2 & 0 \\ -1 & 1-\lambda & 2 \\ 1 & 2 & 1-\lambda \end{vmatrix} = 0$$

$$\Rightarrow -\lambda^3 + 3\lambda^2 - \lambda + 3 = 0$$

$$A^2 = \begin{bmatrix} 1 & 4 & 4 \\ 0 & 3 & 4 \\ 0 & 6 & 5 \end{bmatrix}; A^3 = \begin{bmatrix} -1 & 10 & 12 \\ 1 & 11 & 10 \\ -1 & 16 & 17 \end{bmatrix}$$

$$-A^3 + 3A^2 - A + 3I = 0$$

$$So A^3 = 3A^2 - A + 3I$$

$$= \begin{bmatrix} -1 & 10 & 12 \\ 1 & 11 & 10 \\ -1 & 16 & 17 \end{bmatrix}$$

And  $A' = \frac{1}{3} [A^2 - 3A + I]$

$$= \frac{1}{3} \begin{bmatrix} -3 & -2 & 4 \\ 3 & 1 & -2 \\ -3 & 0 & 3 \end{bmatrix}$$

→ Eigen values of  $A$  are the roots of

$$\lambda^3 - 3\lambda^2 + \lambda - 3 = 0$$

$$\Rightarrow \lambda = 3, i, -i$$

⇒ Eigen values of  $A^2$  are  $\lambda^2$

$$\Rightarrow 9, i^2, (-i)^2$$

$$= 9, -1, -1.$$

- Spectral radius of a matrix  $A$  is  $\delta(A) =$

largest eigenvalue in magnitude.

$$= \max |\lambda_i|$$

Eg. Spectral radius of  $A$  used in above question is 3.

→ Algebraic multiplicity of an eigenvalue is the no. of times the eigen value repeats itself.

Eg.  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow$  upper triangular matrix  
 $\Rightarrow \lambda_1 = 1, 1, 1$  (diagonal Entries)

$$|A - \lambda I| = 0 \quad - \text{char. equation}$$

$$\text{Char. Egu. is } (1-\lambda)^3 = 0$$

$\lambda = 1$  repeats 3 times

⇒ A.M. of  $\lambda = 1$  is 3.

To find the eigen vector corresponding to  $\lambda = 1$ ,

$$(A - I)X = 0$$

$$\left( \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) X = 0$$

$$\Rightarrow \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0$$

$$\Rightarrow y = 0$$

$z = 0$  and  $x$  arbitrary.

$\Rightarrow (1, 0, 0)$  if  $x=1$  will be an Eigen vector.

$\Rightarrow$  Corresponding to  $\lambda=1$ , we have only one L.I. Eigen vector.

(2)  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$  Again upper Triangular matrix

$$\Rightarrow \lambda = 1, 1, 1$$

$$\Rightarrow A.M. \text{ of } \lambda = 1 \text{ is } 3.$$

To find Eigen Vector corr. to  $\lambda = 1$

$$(A - I)X = 0$$

$$\left( \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow y = 0, x \text{ and } z \text{ are arbitrary}$$

choose  $x=0, z=1$

$$(0, 0, 1)$$

choose  $z=0, x=1$

$$(1, 0, 0)$$

$\Rightarrow (0, 0, 1) \text{ & } (1, 0, 0) \rightarrow$  Two L.I. Eigen vectors

corr. to  $\lambda = 1$ .

$$(3) A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow \text{diagonal Matrix} \Rightarrow d=1, 1, 1$$

A.M. of  $d=1$  is 3.

To find Eigen vector corr. to  $d=1$ ;

$$(A - I)x = 0$$

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0$$

$\Rightarrow x, y, z$  all are arbitrary.

$$\Rightarrow x=1, y=0, z=0$$

$$x=0, y=1, z=0$$

$$x=0, y=0, z=1$$

$\Rightarrow (1, 0, 0), (0, 1, 0), (0, 0, 1) \rightarrow 3$  L.I. Eigen vectors.

Hence, If A.M. of any  $\lambda$  is  $> 1$  i.e.  $d$  is repeating more than once, then how many L.I. vectors are there corresponding to that particular  $d$ ?

$$\underline{\underline{\text{Any}}} \quad n - \text{Rank}(A - \lambda I)$$

$$\text{In (1)}, \quad \text{Rank}(A - \lambda I) = 2$$

$\Rightarrow 3 - 2 = 1$  L.I. Eigen vector

$$\text{In (2)}, \quad \text{Rank}(A - \lambda I) = 1$$

$\Rightarrow 3 - 1 = 2$  L.I. Eigen vector

$$\text{In (3)}, \quad \text{Rank}(A - \lambda I) = 0$$

$\Rightarrow 3 - 0 = 3$  L.I. Eigen vector.

$\rightarrow$  The no. of L.I. Eigen vectors corresponding to  $d$  is called the geometric multiplicity (G.M.) of  $d$ .

Diagonalizable Matrix :  $\rightarrow$  A Square matrix of order  $n$  is diagonalizable iff it has  $n$  L.T. Eigen vectors.

- $\rightarrow$  If  $A_{n \times n}$  matrix and has all the  $n$  eigen values as distinct i.e.  $\lambda_1, \lambda_2, \dots, \lambda_n$  are  $n$  eigen values of  $A$  and  $\lambda_i \neq \lambda_j \forall i, j$
- $\Rightarrow A$  has  $n$  L.T. Eigen vector corresponding to each  $\lambda$
- $\Rightarrow A$  is diagonalizable matrix.

Thus If  $A$  has distinct Eigenvalues  $\Rightarrow A$  is diagonalizable.

But Converse need not to be true.

i.e. If  $A$  is diagonalizable then  $A$  can have repeated eigenvalues as well.

E.g. In (3) above,  $\lambda = 1, 1, 1 \rightarrow A.M. \text{ is } 3$

But we have 3 L.T. Eigen vectors corr. to  $\lambda = 1$

$\Rightarrow A$  is diagonalizable

- $\rightarrow$  Every diagonal matrix is diagonalizable matrix, but Converse need not to be true.

i.e. A diagonalizable matrix need not to be a diagonal matrix.

E.g.  $A = \begin{bmatrix} 3 & 1 & -1 \\ -2 & 1 & 2 \\ 0 & 1 & 2 \end{bmatrix} \rightarrow$  Not diagonal matrix.

But  $|A - \lambda I| = 0$

$$\Rightarrow \lambda^3 - 6\lambda^2 + 11\lambda - 6 = 0$$

$$\Rightarrow \lambda = 1, 2, 3$$

$\Rightarrow$  All eigen values are distinct

$\Rightarrow A$  is diagonalizable.

- $\rightarrow A$  is diagonalizable if  $A$  is similar to a diagonal matrix.

$\Rightarrow \exists$  an invertible matrix  $P$  S.t.  $P^{-1}AP = D$

$$\text{or } A = PDP^{-1}$$

Note that this P matrix can be obtained by using the L.T. Eigenvectors Correspond to eigenvalues of A.

Ex The eigenvectors of  $3 \times 3$  matrix A correspond to eigenvalues 1, 1, 3 are  $(1, 0, -1)^T$ ,  $(0, 1, -1)^T$ ,  $(1, 1, 0)^T$  respectively. Find A.

$$\text{Soln} \rightarrow P = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ -1 & -1 & 0 \end{bmatrix} \rightarrow \text{Matrix consisting of eigenvectors.}$$

$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{bmatrix} \rightarrow \text{Matrix consisting of Eigenvalues.}$$

$$\text{We find } P^T = \frac{1}{2} \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & -1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\begin{aligned} A &= P D P^T \\ &= \frac{1}{2} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ -1 & -1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & -1 \\ 1 & 1 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix} \end{aligned}$$

Ques Find the matrix A if

- (1) Eigenvalues are 2, 2, 4 and Eigenvectors are  $(-2, 1, 0)^T$ ,  $(1, 0, 1)^T$ ,  $(1, 0, 1)^T$

Ans  $A = \begin{bmatrix} 3 & 2 & 1 \\ 0 & 2 & 0 \\ 1 & 2 & 3 \end{bmatrix}$

- (2) Eigenvalues are 1, -1, 2 and Eigenvectors are  $(1, 1, 0)^T$ ;  $(1, 0, 1)^T$ ;  $(3, 1, 1)^T$ .

Ans:- 
$$\begin{bmatrix} 6 & -5 & -7 \\ 1 & 0 & -1 \\ 3 & -3 & -4 \end{bmatrix}$$

(3) Eigenvalues are 1, 1, 1 and Eigenvectors are

$(-1, 1, 1)^T, (1, -1, 1)^T, (1, 1, -1)^T$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

→ Symmetric matrix: If  $A = A^T$

i.e.  $a_{ij} = a_{ji} \forall i, j$

- All eigenvalues of  $A$  and  $A^T$  are same.

- The eigenvalues of a Symmetric matrix are real.

Skew Symmetric matrix: If  $A = -A^T$  or  $A^T = -A$ .

i.e.  $a_{ij} = -a_{ji} \forall i, j$

i.e.  $a_{ii} = -a_{ii} \forall i$

$\Rightarrow 2a_{ii} = 0$

$\Rightarrow a_{ii} = 0$

⇒ all the diagonal entries are zero.

→ The eigenvalues of a Skew symmetric matrix are zero or Pure Imaginary.

i.e. Skew Symmetric matrix Cannot have Real eigenvalues.

Orthogonal Matrix: A real matrix  $A$  is orthogonal if

$A^T A = I$

e.g.  $A = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$  is orthogonal matrix

- The eigenvalues of an orthogonal matrix are of magnitude 1 and are real or complex conjugate pairs.  
i.e. If  $\lambda$  is an eigenvalue of an orthogonal matrix  $A$   
Then  $|\lambda| = 1$ .  
 $\Rightarrow \lambda$  could be 1 or -1 or  $i, -i$
- If  $A$  is an orthogonal matrix then  $|A| = \pm 1$ ,  
 $\because (|\lambda| = 1 \forall \lambda \text{ Eigenvalues of } A)$   
and product of eigenvalues =  $|A|$ .

## Homogeneous System of Linear Equations:

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = 0$$

$$a_{g_1}x_1 + a_{g_2}x_2 + \dots + a_{g_n}x_n = 0$$

$$| \alpha + b | = (\alpha + b) - (+) \quad (1)$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = 0$$

$$\Rightarrow Ax = 0$$

$$\text{where } A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}; X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

→ System (i) is always consistent since  $x=0$  is always a solution, known as Trivial solution.

$\Rightarrow$  homogeneous system can have either

- (a) Unique Solution i.e. Trivial solution
  - (b) Infinite no. of solutions.

→ System (i) has a unique solution if  $\text{Rank}(A) = \text{no. of unknowns } (n)$ .

→ If  $\text{Rank}(A) < \text{no. of unknowns } (n)$ , then System (1) has  
Infinite no. of solutions.

$$\rightarrow \text{As } \text{Rank}(A) \leq \min\{m, n\}$$

If  $m < n$ , Then System (i) always possesses a non-trivial solution  $\Rightarrow$  Infinite no. of Solutions.

Ex

A) Solve  $2x + y = 0$

$$\dot{x} - y = 0$$

$$3x + 2y = 0.$$

$$3x + 2y = 0.$$

$$3x + 2y = 0.$$

Sol<sup>7</sup>

$$A = \begin{bmatrix} 2 & 1 \\ 1 & -1 \\ 3 & 2 \end{bmatrix}; \quad x = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$AX = 0$$

$$A = \begin{bmatrix} 2 & 1 \\ 1 & -1 \\ 3 & 2 \end{bmatrix}$$

$$R_2 \leftarrow R_2 - R_1/2$$

$$R_3 \leftarrow R_3 - 3R_1/2$$

$$= \begin{bmatrix} 2 & 1 \\ 0 & -\frac{3}{2} \\ 0 & \frac{1}{2} \end{bmatrix} \quad R_3 \leftarrow R_3 + \frac{R_2}{3} = \begin{bmatrix} 2 & 1 \\ 0 & -\frac{3}{2} \\ 0 & 0 \end{bmatrix}$$

$\Rightarrow \text{Rank}(A) = 2 = \text{no. of unknowns}$

$\Rightarrow$  System has only a trivial solution.

Ques Solve  $x+y-z+w=0$

$$2x+3y+z+4w=0$$

$$3x+2y-6z+w=0$$

Soln

$$\left[ \begin{array}{cccc|c} 1 & 1 & -1 & 1 \\ 2 & 3 & 1 & 4 \\ 3 & 2 & -6 & 1 \end{array} \right] \left[ \begin{array}{c} x \\ y \\ z \\ w \end{array} \right] = \left[ \begin{array}{c} 0 \\ 0 \\ 0 \end{array} \right]$$

As A is  $3 \times 4$  matrix.  $\Rightarrow m < n$

$\Rightarrow$  System has infinite no. of solutions.

$$R_2 \leftarrow R_2 - 2R_1$$

$$R_3 \leftarrow R_3 - 3R_1$$

$$= \left[ \begin{array}{cccc|c} 1 & 1 & -1 & 1 \\ 0 & 1 & 3 & 2 \\ 0 & -1 & -3 & -2 \end{array} \right]$$

$$R_3 \leftarrow R_3 + R_2$$

$$= \left[ \begin{array}{cccc|c} 1 & 1 & -1 & 1 \\ 0 & 1 & 3 & 2 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$\Rightarrow \text{Rank}(A) = 2 < \text{no. of unknowns}$

$$x+y-z+w=0$$

$$y + 3z + 2w = 0$$

$$\Rightarrow y = -3z - 2w$$

$$\text{and } x = -y + z - w$$

$$\Rightarrow x = 3z + 2w + z - w = 4z + w.$$

$z$  and  $w$  are arbitrary.

Ques Find the Solution of the following hom. System  $Ax=0$  where  $A$  is given by

$$(1) \begin{bmatrix} 3 & 1 & 2 \\ 1 & -2 & 3 \\ 1 & 5 & -4 \end{bmatrix} \quad \text{Ans: } [-d, d, d]; d \text{ arbitrary}$$

$$(2) \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 1 & 1 & 1 \\ 1 & 2 & 6 & 12 \end{bmatrix} \quad \text{Ans: } \left[ -\frac{9d}{3}, \frac{7d}{3}, \frac{-8d}{3}; d \right]; d \text{ arbitrary.}$$

$$(3) \begin{bmatrix} 3 & -11 & 5 \\ 4 & 1 & -10 \\ 4 & 9 & -6 \end{bmatrix} \quad \text{Ans: } [0, 0, 0]$$

$$(4) \begin{bmatrix} 1 & 1 & +2 \\ 3 & 4 & -7 \\ -1 & -2 & 11 \end{bmatrix} \quad \text{Ans: } [-15d, 13d, d]; d \text{ arbitrary.}$$

Gauss Jordan Method  $\rightarrow$  Let  $A$  be a non-singular matrix of order  $n$ .

Form the augmented matrix  $[A|I]$

Using elementary row operations, we obtain

$$[A|I] \xrightarrow{\text{Row Operations}} [I|B]$$

$$\text{Thus } B = A^{-1}$$

Ques: Using Gauss Jordan method, find the inverse of the matrix

$$A = \begin{bmatrix} -1 & 1 & 2 \\ 3 & -1 & 1 \\ -1 & 3 & 4 \end{bmatrix}$$

Soln: Write the augmented matrix  $[A|I]$ .

$$[A|I] = \left[ \begin{array}{ccc|ccc} -1 & 1 & 2 & 1 & 0 & 0 \\ 3 & -1 & 1 & 0 & 1 & 0 \\ -1 & 3 & 4 & 0 & 0 & 1 \end{array} \right]$$

Using elementary row operations, Convert  $[A|I]$  into  $[I|B]$ .

$$R_1 \leftarrow -R_1 \quad \text{Then}$$

$$R_2 \leftarrow R_2 - 3R_1$$

$$R_3 \leftarrow R_3 + R_1$$

$$[A|I] = \left[ \begin{array}{ccc|ccc} 1 & -1 & -2 & -1 & 0 & 0 \\ 0 & 2 & 7 & 3 & 1 & 0 \\ 0 & 2 & 2 & -1 & 0 & 1 \end{array} \right]$$

$$R_2 \leftarrow R_2/2$$

$$= \left[ \begin{array}{ccc|ccc} 1 & -1 & -2 & -1 & 0 & 0 \\ 0 & 1 & 7/2 & 3/2 & 1/2 & 0 \\ 0 & 2 & 2 & -1 & 0 & 1 \end{array} \right]$$

$$R_3 \leftarrow R_3 - 2R_2$$

$$= \left[ \begin{array}{ccc|ccc} 1 & -1 & -2 & -1 & 0 & 0 \\ 0 & 1 & 7/2 & 3/2 & 1/2 & 0 \\ 0 & 0 & -5 & -4 & -1 & 1 \end{array} \right]$$

$$R_3 \leftarrow (R_3)/5$$

$$= \left[ \begin{array}{ccc|ccc} 1 & -1 & -2 & -1 & 0 & 0 \\ 0 & 1 & \frac{7}{2} & \frac{3}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 1 & \frac{4}{5} & \frac{1}{5} & -\frac{1}{5} \end{array} \right]$$

$$R_1 \leftarrow R_1 + R_2$$

$$= \left[ \begin{array}{ccc|ccc} 1 & 0 & \frac{3}{2} & \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 1 & \frac{7}{2} & \frac{3}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 1 & \frac{4}{5} & \frac{1}{5} & -\frac{1}{5} \end{array} \right]$$

$$R_1 \leftarrow R_1 - 3R_3$$

$$= \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -\frac{7}{10} & \frac{2}{10} & \frac{3}{10} \\ 0 & 1 & \frac{7}{2} & \frac{3}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 1 & \frac{4}{5} & \frac{1}{5} & -\frac{1}{5} \end{array} \right]$$

$$R_2 \leftarrow R_2 - \frac{7}{2}R_3$$

$$= \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -\frac{7}{10} & \frac{2}{10} & \frac{3}{10} \\ 0 & 1 & 0 & -\frac{13}{10} & -\frac{2}{10} & \frac{7}{10} \\ 0 & 0 & 1 & \frac{4}{5} & \frac{1}{5} & -\frac{1}{5} \end{array} \right]$$

$$\therefore A' = \frac{1}{10} \begin{bmatrix} -7 & 2 & 3 \\ -13 & -2 & 7 \\ 8 & 2 & -2 \end{bmatrix}$$

Ques Find the Inverse of the matrix

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 4 \end{bmatrix}$$

Soln

$$[A|I] = \left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 1 & 2 & 3 & 0 & 1 & 0 \\ 1 & 3 & 4 & 0 & 0 & 1 \end{array} \right]$$

$$R_2 \leftarrow R_2 - R_1$$

$$R_3 \leftarrow R_3 - R_1$$

$$= \left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 2 & -1 & 1 & 0 \\ 0 & 2 & 3 & -1 & 0 & 1 \end{array} \right]$$

$$R_3 \leftarrow R_3 - 2R_2$$

$$\left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 2 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 & -2 & 1 \end{array} \right]$$

$$R_2 \leftarrow R_2 + R_3$$

$$R_2 \leftarrow R_2 + 2R_3$$

$$\left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & -3 & 2 \\ 0 & 0 & -1 & 1 & -2 & 1 \end{array} \right]$$

$$R_3 \leftarrow (-R_3)$$

$$\left[ \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & -3 & 2 \\ 0 & 0 & 1 & -1 & 2 & -1 \end{array} \right]$$

$$R_1 \leftarrow R_1 - R_2$$

$$R_1 \leftarrow R_1 - R_3$$

$$\left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & -1 \\ 0 & 1 & 0 & 1 & -3 & 2 \\ 0 & 0 & 1 & -1 & 2 & -1 \end{array} \right]$$

$$A^T = \begin{bmatrix} 1 & 1 & -1 \\ 1 & -3 & 2 \\ -1 & 2 & -1 \end{bmatrix} \text{ Ans}$$

Ques

$$A = \begin{bmatrix} 2 & 3 & 1 \\ 1 & 3 & 3 \\ 0 & 1 & 2 \end{bmatrix}$$

Ans

$$\begin{bmatrix} 3 & -5 & 6 \\ -2 & 4 & -5 \\ 1 & -2 & 3 \end{bmatrix}$$

### Linear Independence of Vectors:

Let  $V$  be a vector space,  $v_1, v_2, \dots, v_n$  be  $n$  vectors of  $V$ . Then  $d_1 v_1 + d_2 v_2 + \dots + d_n v_n$  is called a linear combination of vectors where  $d_1, d_2, \dots, d_n \in F (\text{R or C})$

→ The set of vectors  $\{v_1, v_2, \dots, v_n\}$  is said to be linearly dependent if there exist scalars  $d_1, d_2, \dots, d_n$ , not all zero such that

$$d_1 v_1 + d_2 v_2 + \dots + d_n v_n = 0.$$

→ The set of vectors  $\{v_1, v_2, \dots, v_n\}$  is said to be linearly independent if  $d_1 v_1 + \dots + d_n v_n = 0$   
 $\Rightarrow d_1 = d_2 = \dots = d_n = 0$ .

In other words, the set of vectors  $\{v_1, \dots, v_n\}$  is linearly dependent iff atleast one element/vector can be written as a linear combination of the other vectors.

i.e. Let  $d_i \neq 0$

$$\text{Then } v_i = -\frac{1}{d_i} [d_1 v_1 + d_2 v_2 + \dots + d_{i-1} v_{i-1} + d_{i+1} v_{i+1} + \dots + d_n v_n].$$

Ex

Let  $v_1 = (1, -1, 0)$ ,  $v_2 = (0, 1, -1)$ ,  $v_3 = (0, 0, 1) \in \mathbb{R}^3$ .

S.T.  $\{v_1, v_2, v_3\}$  is linearly independent.

Sol

$$\text{Let } d_1 v_1 + d_2 v_2 + d_3 v_3 = 0.$$

$$\Rightarrow d_1(1, -1, 0) + d_2(0, 1, -1) + d_3(0, 0, 1) = 0$$

$$\Rightarrow (d_1, -d_1 + d_2, -d_2 + d_3) = 0 \Rightarrow (0, 0, 0)$$

$$\Rightarrow d_1 = 0, -d_1 + d_2 = 0 \Rightarrow d_2 = 0$$

$$-d_2 + d_3 = 0 \Rightarrow d_3 = 0$$

$$\Rightarrow d_1 = d_2 = d_3 = 0$$

$\Rightarrow \{v_1, v_2, v_3\}$  is L.I.

Ex

Let  $v_1 = (1, -1, 0)$ ,  $v_2 = (0, 1, -1)$ ,  $v_3 = (0, 0, 1)$ ,  $v_4 = (1, 0, 3) \in \mathbb{R}^3$

Then S.T.  $\{v_1, v_2, v_3, v_4\}$  is L.D.

Soln

Consider the Equation  $\alpha_1 v_1 + \alpha_2 v_2 + \alpha_3 v_3 + \alpha_4 v_4 = 0$

$$\Rightarrow \alpha_1(1, -1, 0) + \alpha_2(0, 1, -1) + \alpha_3(0, 2, 1) + \alpha_4(1, 0, 3) = 0$$

$$\Rightarrow (\alpha_1 + \alpha_4, -\alpha_1 + \alpha_2 + 2\alpha_3, -\alpha_2 + \alpha_3 + 3\alpha_4) = 0$$

$$\Rightarrow \alpha_1 + \alpha_4 = 0 \Rightarrow \alpha_1 = -\alpha_4$$

$$-\alpha_1 + \alpha_2 + 2\alpha_3 = 0 \Rightarrow \alpha_2 + 2\alpha_3 = -\alpha_4$$

$$-\alpha_2 + \alpha_3 + 3\alpha_4 = 0 \Rightarrow \alpha_2 - \alpha_3 = -3\alpha_4$$

$$3\alpha_3 = -4\alpha_4$$

$$\alpha_3 = -\frac{4}{3}\alpha_4$$

$$\Rightarrow \alpha_2 = \alpha_3 + 3\alpha_4$$

$$= \left(-\frac{4}{3} + 3\right)\alpha_4 = \frac{5}{3}\alpha_4$$

$$\therefore \alpha_1 = -\alpha_4, \alpha_2 = \frac{5}{3}\alpha_4, \alpha_3 = -\frac{4}{3}\alpha_4.$$

$$\text{If } \alpha_4 = 1, \alpha_1 = -1, \alpha_2 = \frac{5}{3}, \alpha_3 = -\frac{4}{3}$$

So not all scalars are zero

$\Rightarrow \{v_1, v_2, v_3, v_4\}$  are L.I.

$\rightarrow$

Singleton Set is L.I. Set

$\because$  let  $A = \{\alpha\}$  be a Singleton Set,  $A \neq \emptyset, \alpha \neq 0$

let  $\alpha \cdot 0 = 0$ ;  $\alpha$  is a scalar

Either  $\alpha = 0, 0 = 0$

$\alpha \neq 0 \Rightarrow 0 = 0$

$\Rightarrow A = \{\alpha\}$  is Singleton Set

$\rightarrow$

Every Subset of L.I. Set is L.I.

i.e. Let  $S = \{v_1, v_2, \dots, v_n\}$  be a L.I. Set

Then S.T.  $S_1 = \{v_1, v_2, \dots, v_k\}, k < n$  is also L.I.

Soln

Let  $\alpha_1 v_1 + \dots + \alpha_k v_k = 0$

$$\Rightarrow \alpha_1 v_1 + \dots + \alpha_k v_k + 0 \cdot v_{k+1} + \dots + 0 \cdot v_n = 0$$

And  $\{v_1, \dots, v_n\}$  is L.I.

$$\Rightarrow \alpha_1 = \alpha_2 = \dots = \alpha_k = 0$$

$\Rightarrow S_1$  is also L.I. Set.

→  $\emptyset$  is subset of every set.

→ Empty set is linearly independent.

→ Superset of Every linearly dependent set is linearly dependent.

8 i.e. let  $S = \{v_1, \dots, v_k\}$  be a LD set.

Then S.T.  $S' = \{v_1, \dots, v_n\}, n > k$  is also LD set.

Pf If  $S' = \{v_1, \dots, v_n\}, n > k$  is linearly independent.

→ Every subset of  $S'$  is also linearly independent.

⇒  $S$  is also LI.

— Contradiction.

⇒  $S'$  is LD set.

Que Examine whether the following set of vectors is LI or LD.

(1)  $(1, 2, 3, 4), (2, 0, 1, -2), (3, 2, 4, 2)$

(2)  $(1, 1, 0, 1), (1, 1, 1, 1), (-1, 1, 1, 1), (1, 0, 0, 1)$

Elementary Row and Column operations: →

(1) Interchange of any two rows ( $R_i \leftrightarrow R_j$ )

(2) Multiplication / division of any row by a non-zero scalar ( $\alpha R_i$ )

(3) Adding / Subtracting a scalar multiple of any row to another row ( $R_i \leftarrow R_i + \alpha R_j$ )

Echelon form of a matrix: → An  $m \times n$  matrix is called a row Echelon matrix if the no. of zeros preceding the first non-zero entry of a row increases row by row until a row having all zeros entries is obtained.

↳ i.e. (1) If  $i$ th row contains all zeros, then it is true for all subsequent ~~subsequent~~ rows.

(2) If a column contains a non-zero entry of any row then every subsequent entry in this column is zero.

(3) Rows containing all zeros occur only after all non-zero rows.

for ex.  $\begin{bmatrix} 1 & 3 & 5 & 7 \\ 0 & 5 & 4 & 1 \\ 0 & 0 & 0 & 9 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 3 & 5 & 7 \\ 0 & 0 & 3 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

are the matrices in row Echelon form.

Similarly we can define the column echelon form of a matrix.

Rank of a matrix:  $\Rightarrow$  The number of linearly independent rows.

Columns of a matrix gives the ranks of the matrix.

$\rightarrow$  If  $A$  is  $m \times n$  matrix then rank of  $A \leq \min\{m, n\}$ .

$\rightarrow$  In other words, the no. of non-zero rows in the row echelon form of a matrix gives the rank of the matrix.

Ex Reduce the following matrices to row Echelon form and find their ranks.

(1)  $A = \begin{bmatrix} 1 & 3 & 5 \\ 2 & -1 & 4 \\ -2 & 8 & 2 \end{bmatrix}$

$R_2 \leftarrow R_2 - 2R_1$

$R_3 \leftarrow R_3 + 2R_1$

$A = \begin{bmatrix} 1 & 3 & 5 \\ 0 & -7 & -6 \\ 0 & 14 & 12 \end{bmatrix} \quad R_3 \leftarrow R_3 + 2R_2 = \begin{bmatrix} 1 & 3 & 5 \\ 0 & -7 & -6 \\ 0 & 0 & 0 \end{bmatrix}$

$\Rightarrow$  # of non-zero rows in row Echelon form is 2

$\Rightarrow$  Rank of  $A = 2$ .

H.W (1)  $A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 1 & 4 & 5 \\ 1 & 5 & 5 & 7 \\ 8 & 1 & 14 & 17 \end{bmatrix}$

(2)  $A = \begin{bmatrix} 3 & 1 & 7 \\ 1 & 2 & 4 \\ 4 & -1 & 7 \\ 2 & 1 & 5 \end{bmatrix}$

→ Examine whether the following set of vectors is L.I.  
or not.

$$(1) (1, 2, 3, 4); (2, 0, 1, -2); (3, 2, 4, 2)$$

Let  $A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 0 & 1 & -2 \\ 3 & 2 & 4 & 2 \end{bmatrix}$

$$R_2 \leftarrow R_2 - 2R_1$$

$$R_3 \leftarrow R_3 - 3R_1$$

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & -4 & -5 & -10 \\ 0 & -4 & -5 & -10 \end{bmatrix} R \leftarrow R_3 - R_2 = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & -4 & -5 & -10 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

⇒ # of non-zero rows in  $A = 2$

$$\Rightarrow \text{Rank}(A) = 2$$

⇒ Given Set of vectors are linearly dependent.

Quadratic forms: Let  $x = (x_1, x_2, \dots, x_n) \in \mathbb{R}^n$  be an arbitrary vector. A real quadratic form is an homogeneous expression of the form

$$Q = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j \quad (1)$$

in which the total power in each term is 2.

We can write (1) as

$$\begin{aligned} Q &= a_{11} x_1^2 + a_{12} x_1 x_2 + \dots + a_{1n} x_1 x_n \\ &\quad + a_{21} x_2 x_1 + a_{22} x_2^2 + \dots + a_{2n} x_2 x_n \\ &\quad \vdots \\ &\quad + a_{n1} x_n x_1 + a_{n2} x_n^2 x_2 + \dots + a_{nn} x_n^2 \\ &= a_{11} x_1^2 + (a_{12} + a_{21}) x_1 x_2 + \dots + (x_1 x_n) (a_{1n} + a_{n1}) \\ &\quad + a_{22} x_2^2 + (a_{23} + a_{32}) x_2 x_3 + \dots + (a_{2n} + a_{n2}) x_2 x_n \\ &\quad + \dots + a_{nn} x_n^2 \\ &= x^T A x \quad (\text{By def' of Matrix multiplication}) \end{aligned}$$

↪ (2)

Now Set  $b_{ij} = \frac{(a_{ij} + a_{ji})}{2}$

$\Rightarrow B = (b_{ij})$  Matrix is Symmetric matrix  
 $(\because b_{ij} = b_{ji})$

So (2) can be written as

$$Q = x^T B x$$

where B is a Symmetric matrix

and  $b_{ij} = \frac{a_{ij} + a_{ji}}{2}$ .

Ques Obtain the Symmetric matrix B for the Quadratic form

$$(1) \quad Q = 2x_1^2 + 3x_1 x_2 + x_2^2$$

$$B = (b_{ij}) \text{ and } b_{ij} = \frac{a_{ij} + a_{ji}}{2}$$

$$\begin{array}{l|l} a_{11} = 2; a_{12} + a_{21} = 3; a_{22} = 1 & \text{Hence } B = \begin{bmatrix} 2 & 3/2 \\ 3/2 & 1 \end{bmatrix} \\ b_{12} = \frac{3}{2} = b_{21} & \end{array}$$

Que

$$Q = x_1^2 + 2x_1x_2 - 4x_1x_3 + 6x_2x_3 - 5x_2^2 + 4x_3^2$$

$$B = \begin{bmatrix} 1 & 1 & -2 \\ 1 & -5 & 3 \\ -2 & 3 & 4 \end{bmatrix}$$

$$\because a_{11} = 1, a_{22} = -5, a_{33} = 4$$

$$a_{12} + a_{21} = 2; a_{13} + a_{31} = -4; a_{23} + a_{32} = 6.$$

Conversely If a Symmetric matrix is given then we can find the Corresponding Quadratic form.

Ex

$$A = \begin{bmatrix} 2 & 3/2 \\ 3/2 & 1 \end{bmatrix}$$

then Quadratic form is  $Q = \mathbf{x}^T A \mathbf{x}$  where  $\mathbf{x} \in \mathbb{R}^2$

$$Q = (x_1, x_2) \begin{pmatrix} 2 & 3/2 \\ 3/2 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$= \left( 2x_1 + \frac{3}{2}x_2, \frac{3}{2}x_1 + x_2 \right) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$= 2x_1^2 + \frac{3}{2}x_1x_2 + \frac{3}{2}x_1x_2 + x_2^2$$

$$Q = 2x_1^2 + 3x_1x_2 + x_2^2$$

Que

Find the Sym. matrix A for the Quadratic forms

$$(1) Q = x_1^2 - 2x_1x_2 + 4x_2x_3 - x_2^2 + x_3^2$$

$$(2) Q = 3x_1^2 + 2x_1x_2 - 4x_1x_3 + 8x_2x_3 + x_3^2$$

Ans (1)

$$\begin{bmatrix} 1 & -1 & 0 \\ -1 & 1 & 2 \\ 0 & 2 & 1 \end{bmatrix}$$

(2)

$$\begin{bmatrix} 3 & 1 & -2 \\ 1 & 1 & 4 \\ -2 & 4 & 0 \end{bmatrix}$$

And Find their Corresponding Quadratic forms (For practice)

Ques Examine whether the following set of vectors is L.I. or L.O.  
Also find the rank of the matrix associated.

- (1)  $\{(2, 3, 6, -3, 4); (4, 2, 12, -3, 6); (4, 10, 12, -9, 10)\}$  Ans: L.D., Rank 2
- (2)  $\{(3, 2, 4); (1, 0, 2); (1, -1, -1)\} \rightarrow$  Ans: L.I., Rank 3
- (3)  $\{(1, 2, 3, 1); (2, 1, -1, 1); (4, 5, 5, 3); (5, 4, 1, 3)\}$  Ans: L.D., Rank 2
- (4)  $\{(2, 2, 0, 2); (4, 1, 4, 1); (3, 0, 4, 0)\}$  Ans: L.D., Rank 2

## Gauss Elimination method:

System of Linear Equations: →

$$\text{Let } a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \quad (1)$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

$$\text{So } Ax = b$$

$$\text{where } A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}_{m \times n}, \quad b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}, \quad x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

(1) is the System of  $m$  equations and  $n$  unknowns.

System (1) is said to be Consistent if it has at least one solution and Inconsistent, if it has no solution.

There are three Possibilities:-

(1) The System (1) has unique solution.

(2) System (1) has no solution.

(3) System (1) has infinite no. of solutions.

Result 1 The non-hom. System of Equation  $Ax=b$  has a solution iff

$\text{Rank}(A) = \text{Rank}(A|b)$  where  $A|b$  is the augmented matrix.

⇒ If  $\text{Rank}(A) \neq \text{Rank}(A|b) \Rightarrow$  (1) has no solution.

→ If  $\text{Rank}(A) = \text{Rank}(A|b) = n$  (no. of unknowns) then  
(1) has unique solution.

→ If  $\text{Rank}(A) = \text{Rank}(A|b) \leftarrow m < n$  then (1) has infinite no. of solutions.

## Gauss Elimination method for non-homogeneous systems

(1) Solve  $2x + y - z = 4$

$$x - y + 2z = -2$$

$$-x + 2y - z = 2$$

Sol:

$$\left[ \begin{array}{ccc|c} 2 & 1 & -1 & 4 \\ 1 & -1 & 2 & -2 \\ -1 & 2 & -1 & 2 \end{array} \right] \quad Ax = b$$

Write the augmented matrix  $[A|b]$  and reduce it to row echelon form by applying elementary row operations.

$$[A|b] = \left[ \begin{array}{ccc|c} 2 & 1 & -1 & 4 \\ 1 & -1 & 2 & -2 \\ -1 & 2 & -1 & 2 \end{array} \right]$$

$$R_2 \leftarrow R_2 - R_1/2$$

$$R_3 \leftarrow R_3 + R_1/2$$

$$= \left[ \begin{array}{ccc|c} 2 & 1 & -1 & 4 \\ 0 & -3/2 & 5/2 & -4 \\ 0 & 5/2 & -3/2 & 4 \end{array} \right]$$

$$R_3 \leftarrow R_3 + \frac{5}{3}R_2$$

$$= \left[ \begin{array}{ccc|c} 2 & 1 & -1 & 4 \\ 0 & -3/2 & 5/2 & -4 \\ 0 & 0 & 8/3 & -8/3 \end{array} \right]$$

$$\text{Hence } \text{Rank}(A) = \text{Rank}(A|b) = 3$$

⇒ System has a unique solution.

And solution is

$$\frac{8}{3}z = -\frac{8}{3} \Rightarrow z = -1$$

$$\frac{-3}{2}y + \frac{5}{2}z = -4 \Rightarrow y = 1$$

$$2x + y - z = 4 \Rightarrow x = 1$$

So  $(x=1, y=1, z=-1)$  is the solution.

(2)

$$2x + z = 3$$

$$x - y + z = 1$$

$$4x - 2y + 3z = 3$$

$$\left[ \begin{array}{ccc|c} 2 & 0 & 1 & x \\ 1 & -1 & 1 & y \\ 4 & -2 & 3 & z \end{array} \right] = \left[ \begin{array}{c} 3 \\ 1 \\ 3 \end{array} \right]$$

The augmented matrix is

$$\left[ \begin{array}{ccc|c} 2 & 0 & 1 & 3 \\ 1 & -1 & 1 & 1 \\ 4 & -2 & 3 & 3 \end{array} \right]$$

$$R_2 \leftarrow R_2 - R_1/2$$

$$R_3 \leftarrow R_3 - 2R_1$$

$$= \left[ \begin{array}{ccc|c} 2 & 0 & 1 & 3 \\ 0 & -1 & 1/2 & -1/2 \\ 0 & -2 & 1 & -3 \end{array} \right]$$

$$R_3 \leftarrow R_3 - 2R_2$$

$$= \left[ \begin{array}{ccc|c} 2 & 0 & 1 & 3 \\ 0 & -1 & 1/2 & -1/2 \\ 0 & 0 & 0 & -2 \end{array} \right]$$

$$\Rightarrow \text{Rank}(A) = 2 \quad \& \quad \text{Rank}(A|b) = 3$$

$\Rightarrow$  System has no solution.

(3)

$$x - y + z = 1$$

$$2x + y - z = 2 \Rightarrow$$

$$5x - 2y + 2z = 5$$

$$\left[ \begin{array}{ccc|c} 1 & -1 & 1 & x \\ 2 & 1 & -1 & y \\ 5 & -2 & 2 & z \end{array} \right] = \left[ \begin{array}{c} 1 \\ 2 \\ 5 \end{array} \right]$$

The augmented form of the matrix is

$$[A|b] = \left[ \begin{array}{ccc|c} 1 & -1 & 1 & 1 \\ 2 & +1 & -1 & 2 \\ 5 & -2 & 2 & 5 \end{array} \right]$$

$$R_2 \leftarrow R_2 - 2R_1$$

$$R_3 \leftarrow R_3 - 5R_1$$

$$= \left[ \begin{array}{ccc|c} 1 & -1 & 1 & 1 \\ 0 & 3 & -3 & 0 \\ 0 & 3 & -3 & 0 \end{array} \right]$$

$$R_3 \leftarrow R_3 - 3R_2$$

$$= \left[ \begin{array}{ccc|c} 1 & -1 & 1 & 1 \\ 0 & 3 & -3 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\Rightarrow \text{Rank}(A) = \text{Rank}(A|b) = 2 < 3$$

$\Rightarrow$  System has Infinite no. of solutions.

$$3y - 3z = 0$$

$$\Rightarrow y = z$$

$$x - y + z = 1$$

$$\Rightarrow x = 1$$

So  $x = 1$ ,  $y = z$  and  $z$  can be chosen arbitrarily.

Ques

$$\text{Solve } 4x - 3y - 9z + 6w = 0$$

$$2x + 3y + 3z + 6w = 6$$

$$4x - 21y - 39z - 6w = -24$$

Ans :- Infinite Sol<sup>n</sup>

Ques

$$\text{Solve } x + 2y - 2z = 1$$

$$2x - 3y + z = 0$$

$$5x + y - 5z = 1$$

$$3x + 14y - 12z = 5$$

Ans:-  $x = 1, y = 1, z = 1$  Unique Sol<sup>n</sup>.

Ques

$$\begin{bmatrix} 2 & -3 & 1 \\ 1 & -1 & 2 \\ 2 & 1 & -3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -2 \\ 3 \\ -2 \end{bmatrix}$$

Ans  $x=1, y=2, z=2$

Ques

$$\begin{bmatrix} 5 & 3 & 14 \\ 0 & 1 & 2 \\ 1 & 1 & 2 \\ 2 & 1 & 6 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \\ 0 \\ 2 \end{bmatrix}$$

Ans  $x=-1, y=-\frac{1}{2}, z=\frac{3}{4}$

Ques

$$\begin{bmatrix} 1 & 1 & 1 & -1 \\ 1 & 1 & 1 & -1 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \\ 2 \\ 0 \end{bmatrix}$$

Ans  $[2-\alpha, 1, \alpha, 1]$ ;  $\alpha$  arbitrary

Ques

$$\begin{bmatrix} -1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 1 \\ 1 & 1 & -1 & 1 \\ 1 & 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left[ \frac{-1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4} \right]$$

### Unit 3

Vector Space  $\Rightarrow$  Let  $V$  be a set of certain objects, which may be vectors, matrices, functions or some other objects. Each object is an element of  $V$  and is called a vector.

Let  $+ : V \times V \rightarrow V$  a binary operation, called vector addition

$\cdot : F \times V \rightarrow V$  an operation, called scalar multiplication.

Then  $(V, +, \cdot)$  is called a vector space if  $V, a, b, c \in V, \alpha, \beta \in F$  the following properties are satisfied.

- (1)  $a+b \in V$
- (2)  $a+b = b+a$
- (3)  $(a+b)+c = a+(b+c)$
- (4)  $a+0 = 0 = 0+a$  where  $0$  is the zero element in  $V$
- (5)  $a+(-a) = 0$

- (6)  $\alpha a \in V$
- (7)  $(\alpha+\beta) \cdot a = \alpha \cdot a + \beta \cdot a$
- (8)  $(\alpha \cdot \beta) \cdot a = \alpha \cdot (\beta \cdot a)$
- (9)  $\alpha \cdot (a+b) = \alpha \cdot a + \alpha \cdot b$
- (10)  $1 \cdot a = a$  where  $1$  is unity element in  $F$ .

Note that  $F$  is the set of real numbers or set of complex numbers, called field of scalars.

$\rightarrow V = \{0\}$  is called a trivial vector space.

Ex (1)  $V = \{\text{Set of real numbers}\}$  is a vector space with usual addition and scalar multiplication over  $F = \mathbb{R}$

(2)  $V = \{\text{Set of all continuous functions i.e. } f: [a, b] \rightarrow \mathbb{R}\}$   
 $V$  is a vector space over  $\mathbb{R}$ .

(3)  $V = \{ \text{Set of polynomials of degree } \leq n \}$   
 is a vector space over  $F = \mathbb{R}$ .

(4)  $V = \{ \text{Set of all } m \times n \text{ matrices} \}$   
 $V$  is a vector space over  $F = \mathbb{R}$ .  
 Here  $0 = \text{Null matrix}$ .

(5) Let  $V = \{ \text{Set of all polynomials of degree } n \}$ .  
 Then  $V$  is not a vector space.

$$\left\{ \begin{array}{l} \therefore \text{let } p_n = a_0 + a_1 x + \dots + a_n x^n \in V \\ q_n = b_0 + b_1 x + \dots + b_n x^n \in V \end{array} \right.$$

$$p_n + q_n = (a_0 + b_0) + (a_1 + b_1)x + \dots + (a_n + b_n)x^n$$

is a polynomial of deg (n+1)

$$\Rightarrow p_n + q_n \notin V.$$

(6)  $V = \{ \text{Set of all polynomials of degree } n \}$   
 for  $a, b \in V$ ,  $a+b = ab$

and usual scalar multiplication.

Then  $V$  is not a vector space.

$$\therefore \text{let } p_n = a_0 + a_1 x + \dots + a_n x^n \in V$$

$$q_n = b_0 + b_1 x + \dots + b_n x^n \in V$$

Then  $p_n \cdot q_n = p_n \cdot q_n$  is a polynomial of degree  
 $2n \Rightarrow p_n + q_n \notin V$

$\Rightarrow V$  is not a vector space.

(7)  $V = \mathbb{R}^2$  i.e. Set of all ordered pairs  $(x, y)$ ,  $x, y \in \mathbb{R}$

Vector addition is defined as

$$(a+b) = (x_1, y_1) + (x_2, y_2) = (2x_1 - 3x_2, y_1 - y_2)$$

$$d \cdot a = d(x_1, y_1) = \left( \frac{dx_1}{3}, \frac{dy_1}{3} \right)$$

Check whether  $V$  is a vector space or not over  $F = \mathbb{R}$ .

Sol:  $a+b \neq b+a$

$\because$  let  $a = (x_1, y_1)$ ,  $b = (x_2, y_2)$

$$\text{Then } a+b = (x_1, y_1) + (x_2, y_2) = (x_1 - 3x_2, y_1 - y_2)$$

$$b+a = (x_2, y_2) + (x_1, y_1) = (2x_1 - 3x_2, y_2 - y_1)$$

Similarly  $(a+b)+c \neq a+(b+c)$



$$\text{Also } 1 \cdot (x_1, y_1) = (x_1, y_1) = \left(\frac{x_1}{3}, \frac{y_1}{3}\right) \neq (x_1, y_1)$$

$\Rightarrow 1 \cdot a \neq a$  where 1 is the unity element in  $\mathbb{R}$ .

$\Rightarrow V$  is not a vector space over  $\mathbb{R}$ .

H.M.

Ques let  $V = \mathbb{R}^2$  i.e. set of all ordered pairs.

let  $a = (x_1, y_1)$ ,  $b = (x_2, y_2) \in V$

$$a+b = (x_1, y_1) + (x_2, y_2) = (x_1 + x_2, y_1 + y_2)$$

$$\text{And } da = d(x_1, y_1) = (dx_1, dy_1)$$

Then show that  $V$  is not a v.s over  $\mathbb{R}$ .

$\rightarrow$  Subspace: let  $(V, +, \cdot)$  be a vector space over field  $F$ .

let  $W$  be a non-empty subset of  $V$ . i.e.  $W \subseteq V$ .

Then  $W$  is called a subspace of  $V$  if  $W$  is a vector space under the vector addition ' $+$ ' and scalar multiplication ' $\cdot$ '.

Two Step Test to check the Subspace:

let  $(V, +, \cdot)$  be a vector space over  $F$

and  $W \neq \emptyset$ ,  $W \subseteq V$

Then  $W$  is subspace of  $V$  if

$$a+b \in W \quad \forall a, b \in W$$

$$\text{And } da \in W \quad \forall d \in F, a \in W$$

One Step Test: let  $(V, +, \cdot)$  be a v.s. over  $F$

and  $W \neq \emptyset$ ,  $W \subseteq V$

Then  $W$  is subspace of  $V$  if

$$da + db \in W \quad \forall d, \alpha, \beta \in F, a, b \in W$$

Ex let  $V = \{(x_1, x_2, \dots, x_n) \in \mathbb{R}^n\}$ ;  $F = \mathbb{R}$

$V$  is a V.S. with usual addition & scalar multiplication.

(1) let  $W = \{(x_1, \dots, x_n) \mid x_1 = 0\} \subseteq V$

Then  $W$  is subspace of  $V$

$\left\{ \because \text{let } a = (0, x_2, \dots, x_n); b = (0, x_2, \dots, x_n) \in W \right.$

Then  $a+b = (0, x_2 + x_2, \dots, x_n) \in W$

and  $\alpha \in F; \alpha a \in W$ .

(2) let  $W = \{(x_1, \dots, x_n) \mid x_i \geq 0\}$

Then  $W$  is not a subspace of  $V$ .

$\left\{ \because \text{let } \alpha = -1 \text{ let } a = (x_1, \dots, x_n) \in W \right.$

Then  $\alpha a = -a = -(x_1, \dots, x_n)$

$= (x_1, -x_2, \dots, -x_n) \notin W$

(3) let  $W = \{(x_1, \dots, x_n) \mid x_2 = x_1 + 1\}$

Then  $W$  is not a subspace of  $V$

$\left\{ \because \text{let } a = (x_1, x_2, \dots, x_n); b = (y_1, y_2, \dots, y_n) \in W \right.$

$\Rightarrow x_2 = x_1 + 1; y_2 = y_1 + 1$

Then  $a+b = (x_1+y_1, x_2+y_2, \dots, x_n+y_n)$

and  $x_2+y_2 = (x_1+1)+(y_1+1)$

$= x_1+y_1+2 \neq (x_1+y_1)+1$

$\Rightarrow W$  is not a subspace.

Ex let  $V = \{a_0 + a_1 x + \dots + a_m x^m \mid \text{polynomials of deg. } \leq m\}$

is a V.S. with usual addition and scalar multiplication

$F = \mathbb{R}$

Then

(1) let  $W = \{\text{polynomials of deg. } \leq m \mid b(0) = 0\}$

Then  $W$  is a Subspace of  $V$

$\left\{ \because \text{let } p(x), q(x) \in W \Rightarrow p(0) = q(0) \right.$

$p(x) + q(x) \in W \text{ as } p(0) + q(0) = 0$

and  $\alpha p(x) \in W \text{ as } \alpha p(0) = 0, \alpha \in F$ .

(2)  $W = \{P(x) \in V \mid P(0) = 1\}$

is not a Subspace

$\therefore$  let  $P(x), Q(x) \in W$

$$\Rightarrow P(0) = Q(0)$$

Then  $P(x) + Q(x) \notin W$  ( $\because P(0) + Q(0) = 2 \neq 1$ )

(3)  $W = \{P(x) \in V \mid \text{Coefficients are Positive}\}$

Then  $W$  is not a Subspace

$\left\{ \because \text{let } P(x) = a_0 + a_1 x + \dots + a_m x^m \in W, a_0, a_1, \dots, a_m > 0. \right.$

$\left. \text{let } \alpha = -1 \in F \right.$

$\text{Then } \alpha P(x) = -a_0 - a_1 x - \dots - a_m x^m \notin W$

HW  $V = \{\text{Set of all } m \times n \text{ real Square matrices}\}$  is a V.S. with usual matrix addition & scalar multiplication.  $F = \mathbb{R}$

(1)  $W = \{\text{Set of all Symmetric matrices}\}$

(2)  $W = \{\text{Set of all upper Triangular matrices}\}$

(3)  $W = \{\text{Set of all } n \times n \text{ matrices having real positive Elements}\}$

Check that  $W$  is a Subspace of  $V$  or not.