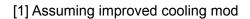
Copy this spreadsheet to customize your analysis!	Speed Constant Max (Kv) Current*		Max voltage	Phase Resistance	Price (qty	Mass	Link	Torque	No-load speed		Power at c	Motor size constant (Km)	Force	Linear Velocity	Linear Acceleration	Time to base speed	Distance to base speed	Base speed kinetic energy	Encoder freq. (base speed)	
(feilds highlighted in blue are inputs)	rpm/V	Α	V	mOhm	USD	g		Nm	RPM	Rad/s	W	Nm/sqrt(W)	N	m/s	m/s^2	ms	mm	J	kHz	
ODrive Robotics D5065 - 270kv	270	65	32	2 39	69	420	https://odriv	1.99	8640	904.78	1801	0.13	208.49	8.64	69.57	124.18	536.47	70.92	294.912	
ODrive Robotics D6374 - 150kv	150	70	48	39	99	890	https://odriv	3.86	5760	603.19	2328	0.23	404.15	5.76	134.87	42.71	123.00	31.52	196.608	
Tarot 4008 330kv	330	25	24	1	32	80	https://www.a	0.63	7920	829.38	520		65.61	7.92	21.89	361.74	1,432.50	59.59	270.336	
Turnigy Aerodrive SK3 - 4250-350kv	350	50	20	)	36	266	https://hobby	1.18	7000	733.04	866		123.72	7.00	41.29	169.55	593.42	46.55	238.9333333	
ACK 5312CP - 330KV	330	50	30	)	41	230	https://hobby	1.25	9900	1,036.73	1299		131.22	9.90	43.79	226.09	1,119.14	93.11	337.92	
Turnigy Aerodrive SK3 - 5065-275kv	275	60	40	)	56	530	https://hobby	1.80	10560	1,105.84	1995		188.95	10.56	63.05	167.47	884.26	105.94	360.448	
KEDA 63-64 190KV	190	50	40	)	49	670	https://hobby	2.18	7296	764.04	1663		227.90	7.30	76.05	95.93	349.97	50.57	249.0368	
Turnigy Aerodrive SK3 - 6374-149kv	149	68	48	3	80	840	https://hobby	3.77	5722	599.16	2261		395.23	5.72	131.89	43.38	124.10	31.10	195.29728	
9235-100KV Turnigy Multistar	100	57	48	3	103	674	https://hobby	4.71	3840	402.12	1896		493.63	3.84	164.73	23.31	44.76	14.01	131.072	
Hoverboard Hub-motor	16	25 [1]	48	3	40	a lot	https://www.e	12.92	614	64.34	831		1,353.16	0.61	451.56	1.36	0.42	0.36	20.97152	
		*Note that to	orque and co	urrent ratings	s are with Extremely	emely good	d forced air co	cooling												
		See Torque o	derating curv	<u>'e</u>																
Parameter	Value												250							
Bus voltage	48	V	5										250							
Max modulation	0.8									•										
Load mass	1.9								.77				200				199			1896
Rotor inertia [2]	1.00E-04	kg m^2	4						•								1663			
Pulley circumference or screw pitch	60	mm/rev							•								1003			
Radius	0.009549296	m/rad											150			4000				
Reflected inertia	1.10		€ 3										§ 0			1299	)			
Peak brake power	1200		Ž				2.18						70			•				
Brake resistor resistance	1.92	ohm	Torque (Nm)				• 1.80						Š 100			866831				
			P 2				•							'		•				
Conversion constants						1.18 <sup>1.25</sup>										520				
I by kv to Nm	8.269933431		1		0:63	• •							500			•				
					0.00															
Encoder																				
Encoder resolution	2048		ا ا										0							
Linear resolution	7.32			)	25		50	75		100				0	25		50	7	5	100
Max speed	15000	RPM					Price (\$)										Price (\$)			
There are more tabs!			5																	
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			Η "	0 200 400 600 800																
						,	Weight (g)													



[2] Note: We should measure inertia of each individual motor. This is an estimate of 5065 size motors.