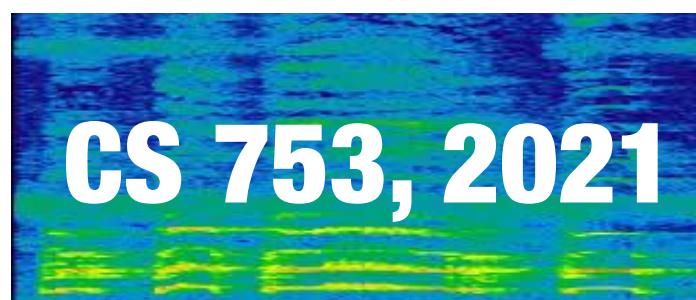


HMMs for Acoustic Modeling

Lecture 1b



Instructor: Preethi Jyothi, IITB

Recap: HMMs

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What are (first-order) HMMs?

Recap: HMMs



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Decoding: Given as input an HMM $\lambda = (A, B)$ and a sequence of observations $O = o_1, o_2, \dots, o_T$, find the most probable sequence of states $Q = q_1 q_2 q_3 \dots q_T$.

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Learning in HMMs

Problem 1 (Likelihood): Given an HMM $\lambda = (A, B)$ and an observation sequence O , determine the likelihood $P(O|\lambda)$.

Problem 2 (Decoding): Given an observation sequence O and an HMM $\lambda = (A, B)$, discover the best hidden state sequence Q .

Problem 3 (Learning): Given an observation sequence O and the set of states in the HMM, learn the HMM parameters A and B .

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EM for general HMMs: Baum-Welch algorithm (1972)

(predates the general formulation of EM (1977))

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Forward-backward or Baum-Welch (EM) algorithm

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What is the EM Algorithm?

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E step: Estimate hidden variables given the observations and current estimates of the model parameters.

M step: Estimating model parameters by maximising the likelihood function using estimates of the hidden data from the E step.

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Observed data: i.i.d samples $x_i, i=1, \dots, N$

Goal: Find $\arg \max_{\theta} \mathcal{L}(\theta)$ where $\mathcal{L}(\theta) = \sum_{i=1}^N \log \Pr(x_i; \theta)$

Hidden data: Denoted by z

$$= \sum_i \log \sum_z \Pr(x_i, z; \theta)$$

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$$Q(\theta, \theta^{\ell-1}) = \sum_{i=1}^N \sum_z \Pr(z|x_i; \theta^{\ell-1}) \log \Pr(x_i, z; \theta)$$

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Estimate θ^ℓ cannot get worse over iterations because for all θ :

$$\mathcal{L}(\theta) - \mathcal{L}(\theta^{\ell-1}) \geq \underbrace{Q(\theta, \theta^{\ell-1}) - Q(\theta^{\ell-1}, \theta^{\ell-1})}_{\text{or stay the same}}$$

The EM algorithm is guaranteed to increase the likelihood at every iteration & hence guaranteed to converge

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EM is guaranteed to converge to a local optimum or saddle points [Wu83]

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$$Q(\theta, \theta^{\ell-1}) = \sum_{i=1}^N \sum_z \Pr(z|x_i; \theta^{\ell-1}) \log \Pr(x_i, z; \theta)$$

Jensen's inequality

$$\log \sum_i \lambda_i x_i \geq \sum_i \lambda_i \log x_i$$

$$\lambda_i \geq 0, \sum_i \lambda_i = 1$$

$$L(\theta) > L(\theta_n) \Rightarrow L(\theta) - L(\theta_n) = \log \sum_z P(x, z|\theta) - \log P(x|\theta_n)$$

Want to maximize this delta

$P(z|x, \theta_n)$ can serve as a λ

$$L(\theta) - L(\theta_n) = \log \sum_z P(x|z, \theta) P(z|\theta) \frac{P(z|x, \theta_n)}{P(z|x, \theta_n)} - \log P(x|\theta_n)$$

$$\geq \sum_z P(z|x, \theta_n) \log \frac{P(x|z, \theta) P(z|\theta)}{P(z|x, \theta_n)} - \log P(x|\theta_n)$$

choose a θ that maximizes $L(\theta) \geq L(\theta_n) + \beta(\theta, \theta_n) \frac{P(z|x, \theta_n)}{P(z|x, \theta_n)}$

$$\theta_{n+1} = \arg \max_{\theta} Q(\theta, \theta_n) = \arg \max_{\theta} \sum_z P(z|x, \theta_n) \log P(x, z|\theta)$$

**How do we use EM for
HMM parameter estimation?**

Forward and Backward Probabilities

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Require two probabilities to compute estimates for the transition and observation probabilities:

1. **Forward probability:** Recall $\alpha_t(j) = P(o_1, o_2 \dots o_t, q_t = j | \lambda)$

2. **Backward probability:** $\beta_t(i) = P(o_{t+1}, o_{t+2} \dots o_T | q_t = i, \lambda)$

Backward probability

1. Initialization:

$$\beta_T(i) = 1, \quad 1 \leq i \leq N$$

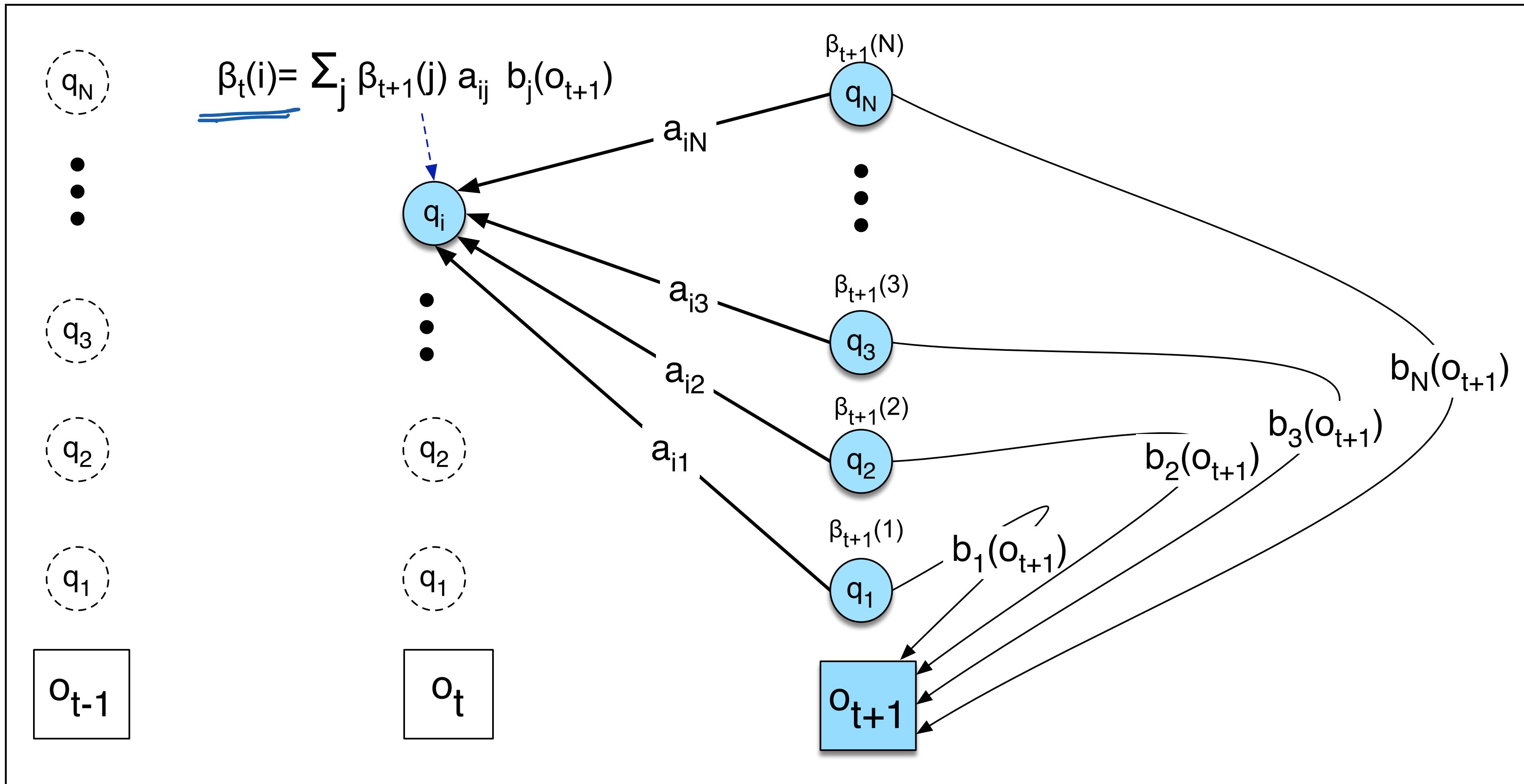
2. Recursion

$$\beta_t(i) = \sum_{j=1}^N a_{ij} b_j(o_{t+1}) \beta_{t+1}(j), \quad 1 \leq i \leq N, 1 \leq t < T$$

3. Termination:

$$P(O|\lambda) = \sum_{j=1}^N \pi_j b_j(o_1) \beta_1(j)$$

Visualising backward probability computation



1. Baum-Welch: Estimating a_{ij}

We need to define $\xi_t(i, j)$ to estimate a_{ij}

where $\xi_t(i, j) = \underline{P}(\underline{q}_t = i, \underline{q}_{t+1} = j | O, \lambda)$

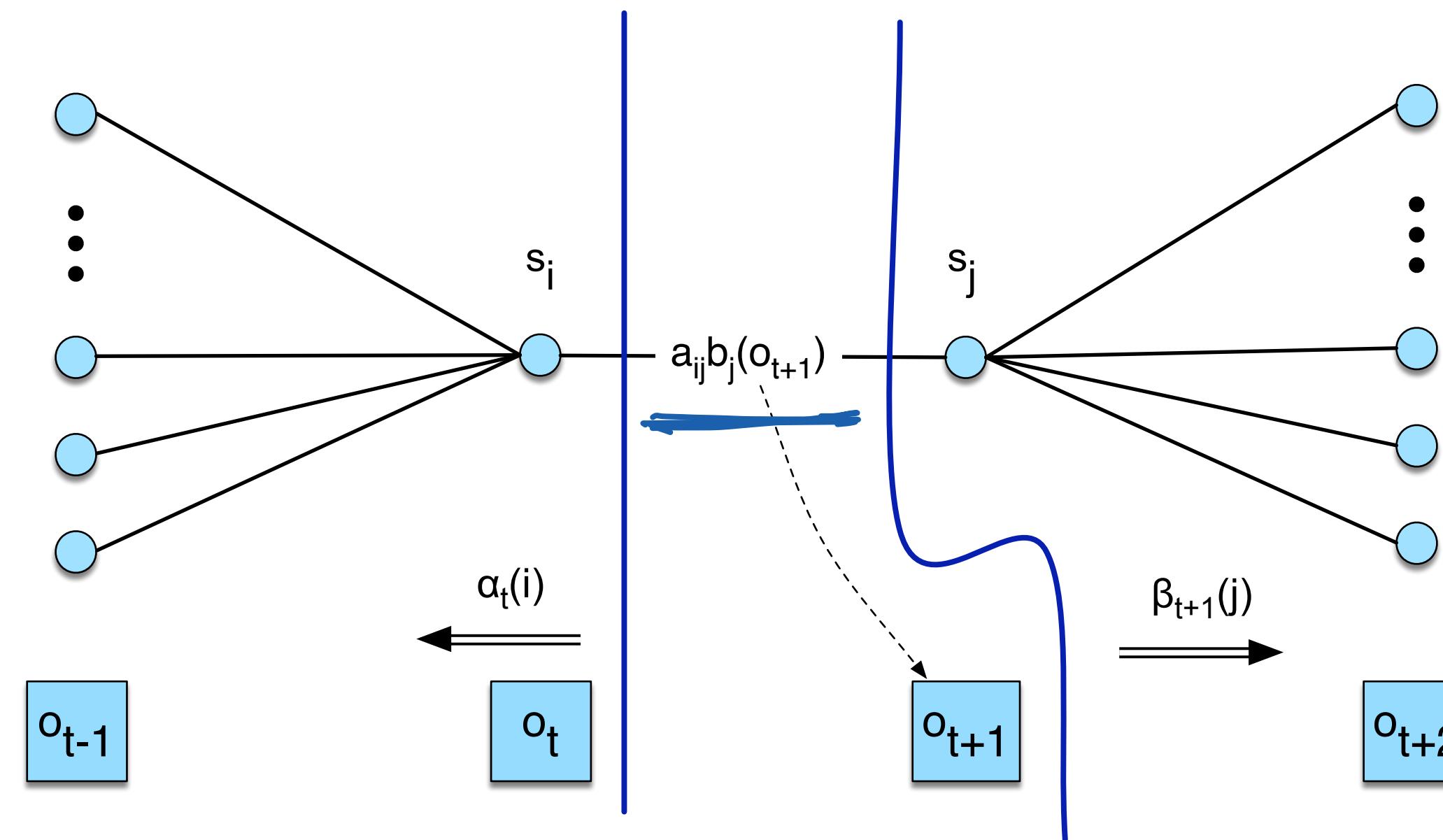
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$$\stackrel{?}{=} \frac{P(q_t=i, q_{t+1}=j, O | \lambda)}{P(O | \lambda)}$$



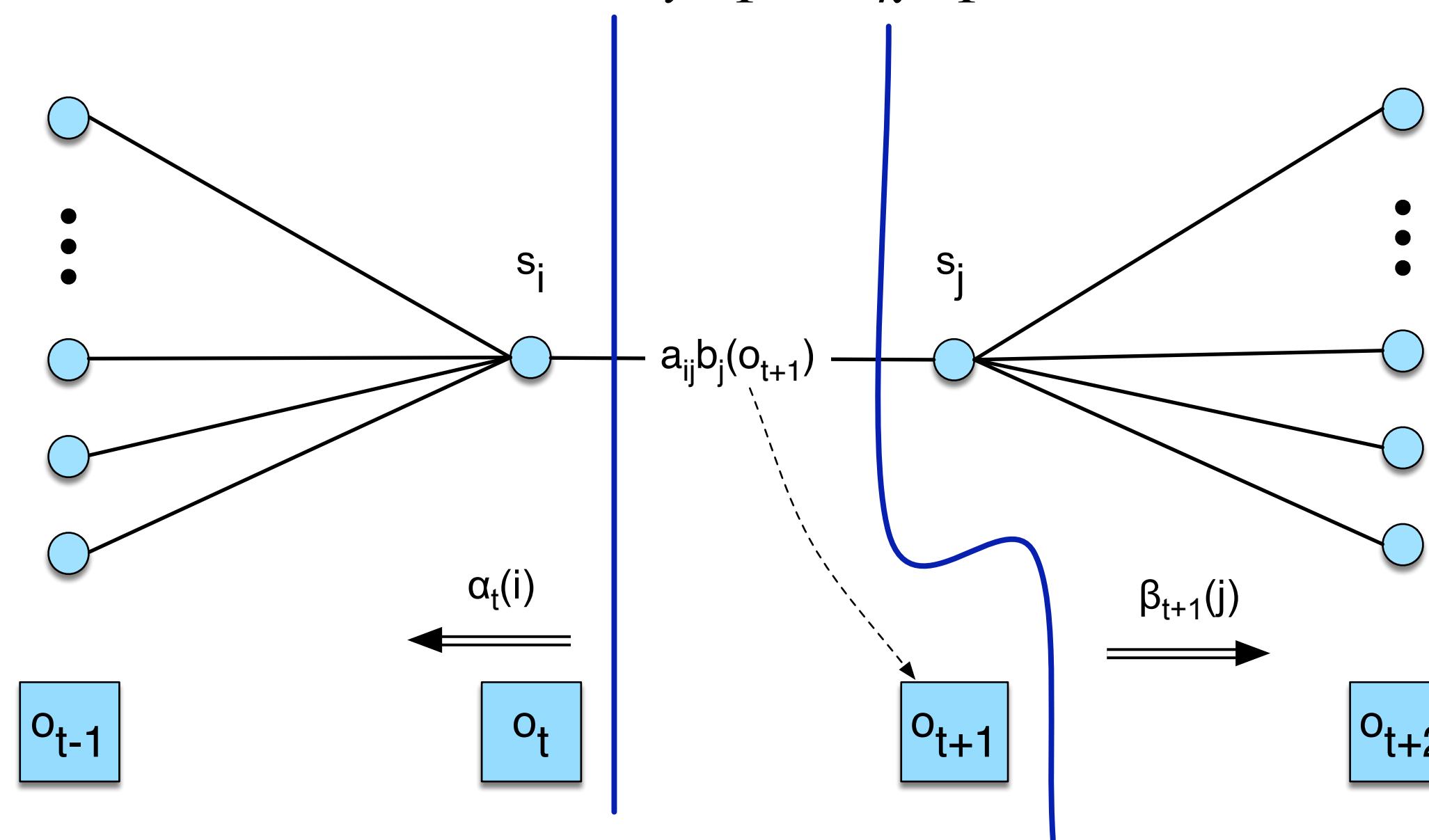
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Then, $\hat{a}_{ij} = \frac{\sum_{t=1}^{T-1} \xi_t(i, j)}{\sum_{t=1}^{T-1} \sum_{k=1}^N \xi_t(i, k)}$



2. Baum-Welch: Estimating $b_j(v_k)$

We need to define $\gamma_t(j)$ to estimate $b_j(v_k)$

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State occupancy
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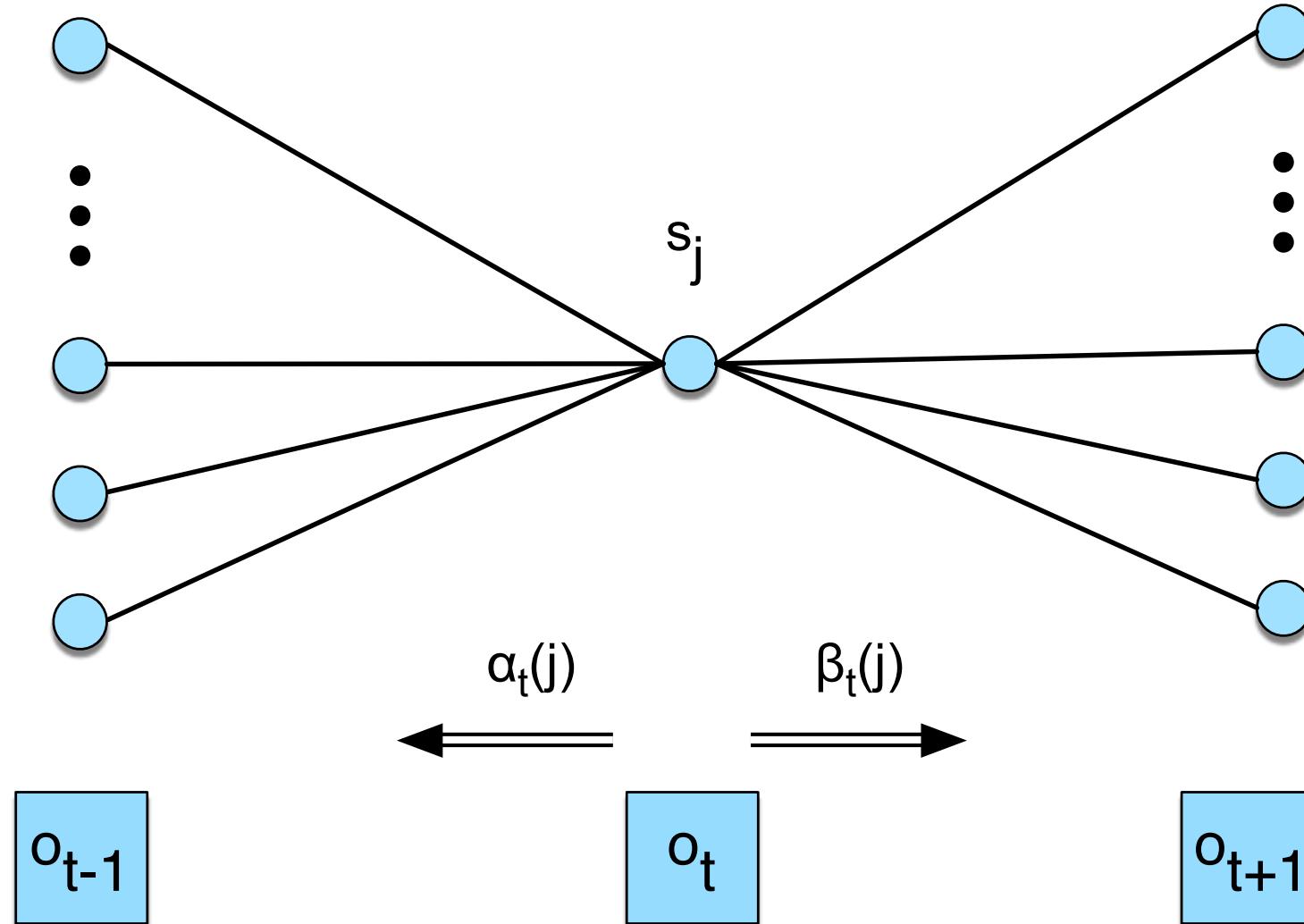
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$P(q_t=j | O, \lambda)$
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 $\sum_j \alpha_t(j)\beta_t(j)$



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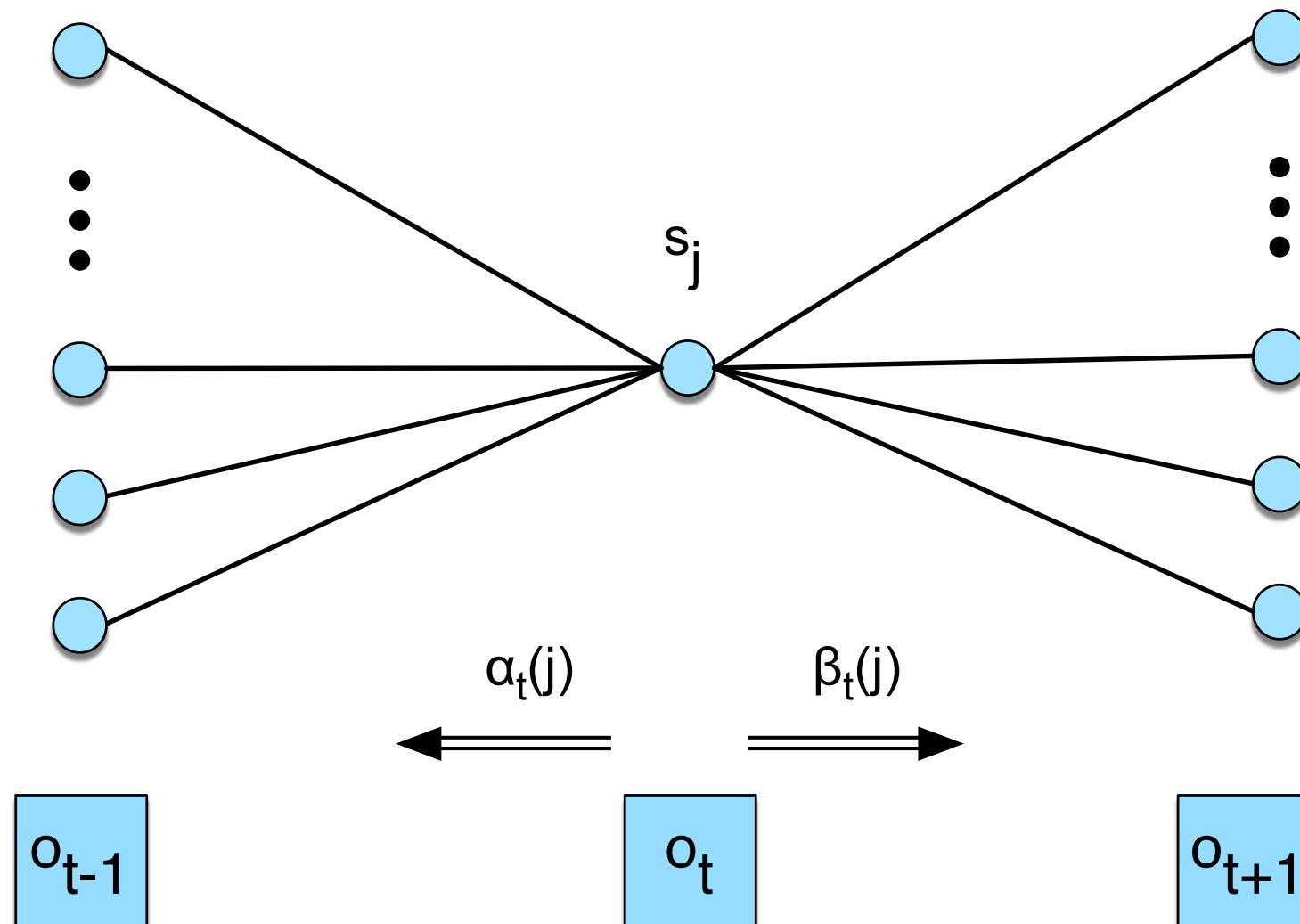
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State occupancy probability

Then, $\hat{b}_j(v_k) = \frac{\sum_{t=1}^T \gamma_t(j)}{\sum_{t=1}^T \gamma_t(j)}$ for discrete outputs



Bringing it all together: Baum-Welch

Estimating HMM parameters iteratively using the EM algorithm.
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Estimating HMM parameters iteratively using the EM algorithm.
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M step: Reestimate HMM parameters, i.e. transition probabilities, observation probabilities, based on the estimates derived in the E step

Baum-Welch algorithm (pseudocode)

function FORWARD-BACKWARD(*observations* of len T , *output vocabulary* V , *hidden state set* Q) **returns** $HMM=(A,B)$

initialize A and B

iterate until convergence

E-step

$$\gamma_t(j) = \frac{\alpha_t(j)\beta_t(j)}{\alpha_T(q_F)} \quad \forall t \text{ and } j$$

$$\xi_t(i,j) = \frac{\alpha_t(i)a_{ij}b_j(o_{t+1})\beta_{t+1}(j)}{\alpha_T(q_F)} \quad \forall t, i, \text{ and } j$$

M-step

$$\sum_{t=1}^{T-1} \xi_t(i,j)$$

$$\hat{a}_{ij} = \frac{\sum_{t=1}^{T-1} \sum_{k=1}^N \xi_t(i,k)}{\sum_{t=1}^{T-1} \sum_{k=1}^N \xi_t(i,k)}$$

$$\sum_{t=1}^T \gamma_t(j)$$

$$\hat{b}_j(v_k) = \frac{\sum_{t=1}^T s.t. O_t=v_k \gamma_t(j)}{\sum_{t=1}^T \gamma_t(j)}$$

return A, B

Baum-Welch Algorithm as EM

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[EM Iteration, E-step]

Compute quantities involved in $Q(\theta, \theta^{\ell-1})$

$$\gamma_{i,t}(j) = \underline{\Pr(z_t = j \mid x_i; \theta^{\ell-1})}$$



$$\xi_{i,t}(j,k) = \underline{\Pr(z_t = j, z_{t+1} = k \mid x_i; \theta^{\ell-1})}$$

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Find θ which maximises $Q(\theta, \theta^{\ell-1})$

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$$A_{j,k} = \frac{\sum_{i=1}^N \sum_{t=1}^{T_i-1} \xi_{i,t}(j, k)}{\sum_{i=1}^N \sum_{t=1}^{T_i-1} \sum_{k'} \xi_{i,t}(j, k')}$$

$$B_{j,v} = \frac{\sum_{i=1}^N \sum_{t:x_{it}=v} \gamma_{i,t}(j)}{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j)}$$

Discrete to continuous outputs

We derived Baum-Welch updates for discrete outputs.

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Use probability density functions to define observation probabilities

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If x were 1D values, HMM observation probabilities: $b_j(x) = \mathcal{N}(x | \mu_j, \sigma_j^2)$
where μ_j is the mean associated with state j and σ_j^2 is its variance

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If $\mathbf{x} \in \mathbb{R}^d$, then we use multivariate Gaussians, $b_j(\mathbf{x}) = \mathcal{N}(\mathbf{x} | \underline{\mu}_j, \underline{\Sigma}_j)$
where Σ_j is the covariance matrix associated with state j

BW for Gaussian Observation Model

Observed data: N sequences, $x_i = (x_{i1}, \dots, x_{iT_i})$, $i=1..N$ where $x_{it} \in \mathbb{R}^d$

Parameters θ : transition matrix A , observation prob. $B = \{(\mu_j, \Sigma_j)\}$ for all j

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A same as with discrete outputs

$$\underline{\mu_j} = \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j) x_{it}}{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j)}$$

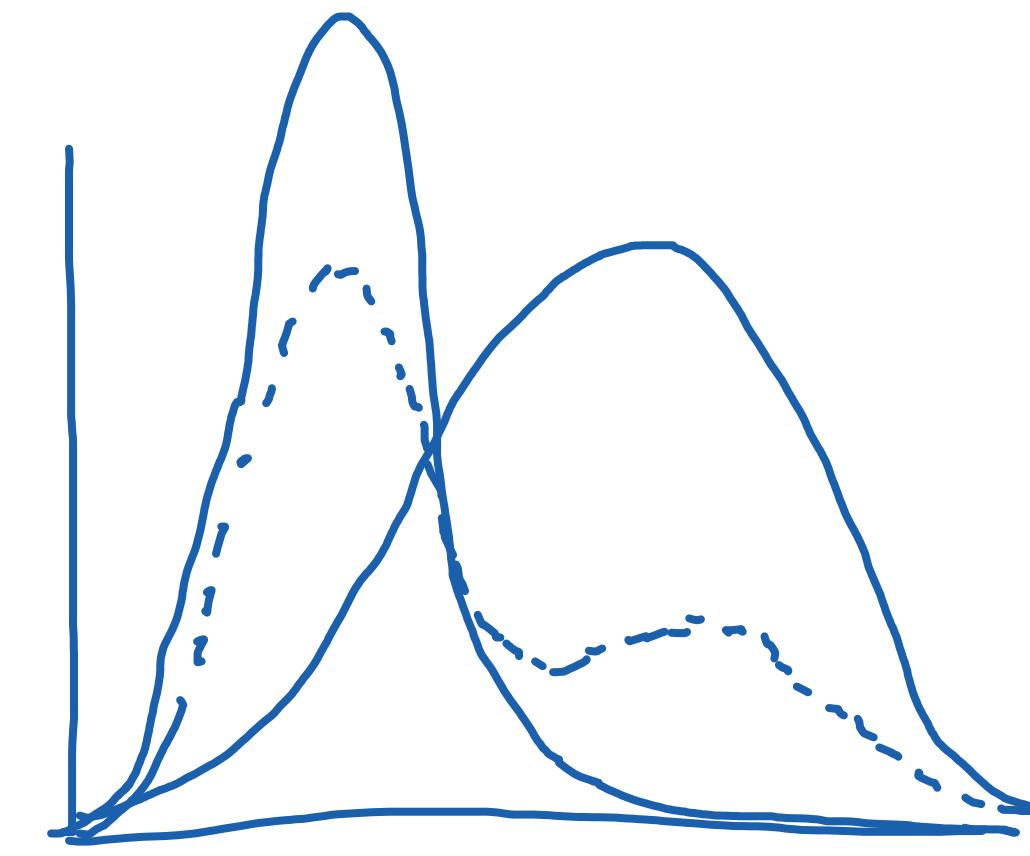
$$\underline{\Sigma_j} = \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \overbrace{\gamma_{i,t}(j)}^{\text{blue bracket}} (x_{it} - \mu_j)(x_{it} - \mu_j)^T}{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j)}$$

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- Assuming that observations associated with a state follow a Gaussian distribution is too simplistic.
- More generally, we use a “mixture of Gaussians” to allow for acoustic vectors associated with a state to be non-Gaussian.
- Instead of $b_j(\mathbf{x}) = \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_j, \Sigma_j)$ in the single Gaussian case, $b_j(\mathbf{x})$ can be an M -component mixture model:

$$\underline{b_j(\mathbf{x})} = \sum_{m=1}^M \underline{c_{jm}} \underline{\mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_{jm}, \Sigma_{jm})}$$

where c_{jm} is the mixing probability for Gaussian component m of state j

$$\sum_{m=1}^M c_{jm} = 1, \quad c_{jm} \geq 0$$

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[EM Iteration, M-step]

Find θ which maximises $Q(\theta, \theta^{\ell-1})$

$$\mu_{jm} = \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j, m) x_{it}}{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j, m)}$$

$$\Sigma_{jm} = \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j, m) (x_{it} - \mu_{jm})(x_{it} - \mu_{jm})^T}{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j, m)}$$

$$c_{jm} = \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j, m)}{\sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{m'=1}^M \gamma_{i,t}(j, m')}$$

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[EM Iteration, M-step]

Find θ which maximises $Q(\theta, \theta^{\ell-1})$

$$\mu_{jm} = \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j, m) x_{it}}{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j, m)}$$

$$\Sigma_{jm} = \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j, m) (x_{it} - \mu_{jm})(x_{it} - \mu_{jm})^T}{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j, m)}$$

$$c_{jm} = \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j, m)}{\sum_{i=1}^N \sum_{t=1}^{T_i} \sum_{m'=1}^M \gamma_{i,t}(j, m')}$$

Prob. of component m
of state j at time t

Baum Welch: In summary

Baum Welch: In summary

[Every EM Iteration]

Compute $\theta = \{ A_{jk}, (\mu_{jm}, \Sigma_{jm}, C_{jm}) \}$ for all j, k, m

Baum Welch: In summary

[Every EM Iteration]

Compute $\theta = \{ A_{jk}, (\mu_{jm}, \Sigma_{jm}, C_{jm}) \}$ for all j, k, m

$$A_{j,k} = \frac{\sum_{i=1}^N \sum_{t=2}^{T_i} \xi_{i,t}(j, k)}{\sum_{i=1}^N \sum_{t=2}^{T_i} \sum_{k'} \xi_{i,t}(j, k')}$$

Baum Welch: In summary

[Every EM Iteration]

Compute $\theta = \{ A_{jk}, (\mu_{jm}, \Sigma_{jm}, c_{jm}) \}$ for all j, k, m

$$A_{j,k} = \frac{\sum_{i=1}^N \sum_{t=2}^{T_i} \xi_{i,t}(j, k)}{\sum_{i=1}^N \sum_{t=2}^{T_i} \sum_{k'} \xi_{i,t}(j, k')}$$

$$\mu_{jm} = \frac{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j, m) x_{it}}{\sum_{i=1}^N \sum_{t=1}^{T_i} \gamma_{i,t}(j, m)}$$

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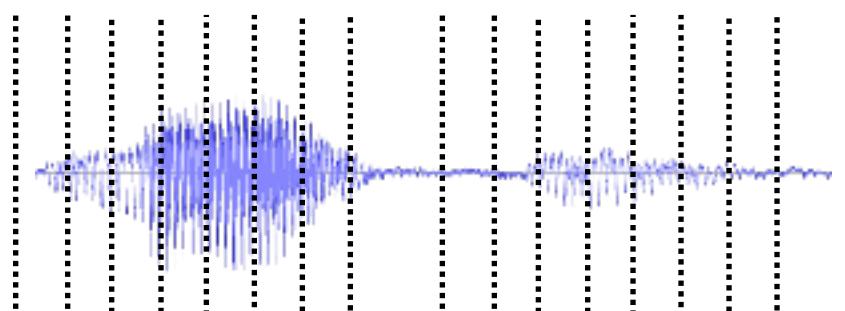
Overall Summary

Training



Overall Summary

Training

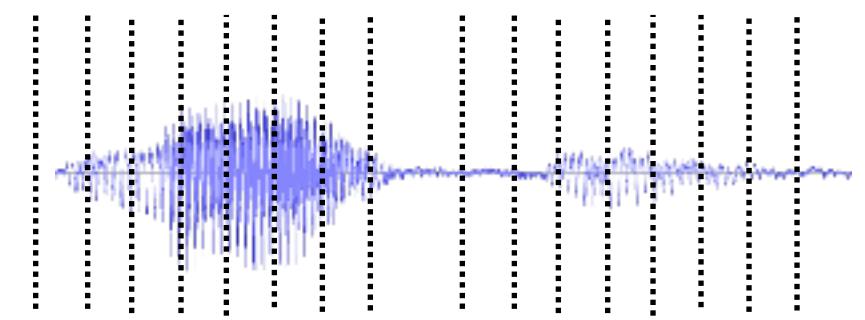


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Overall Summary

Training



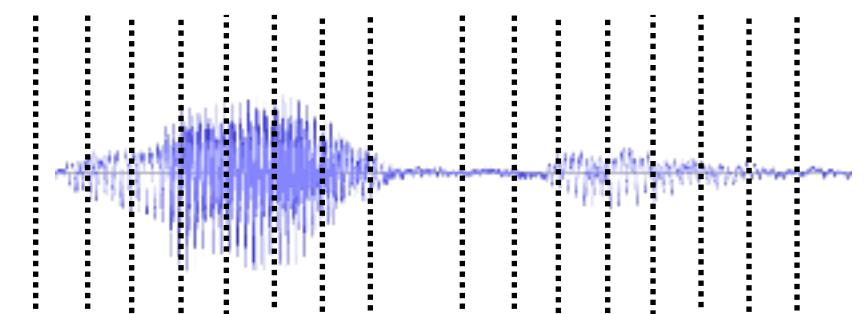
$$\rightarrow O_1^1, \dots, O_{t1}^1$$

...

...

Overall Summary

Training



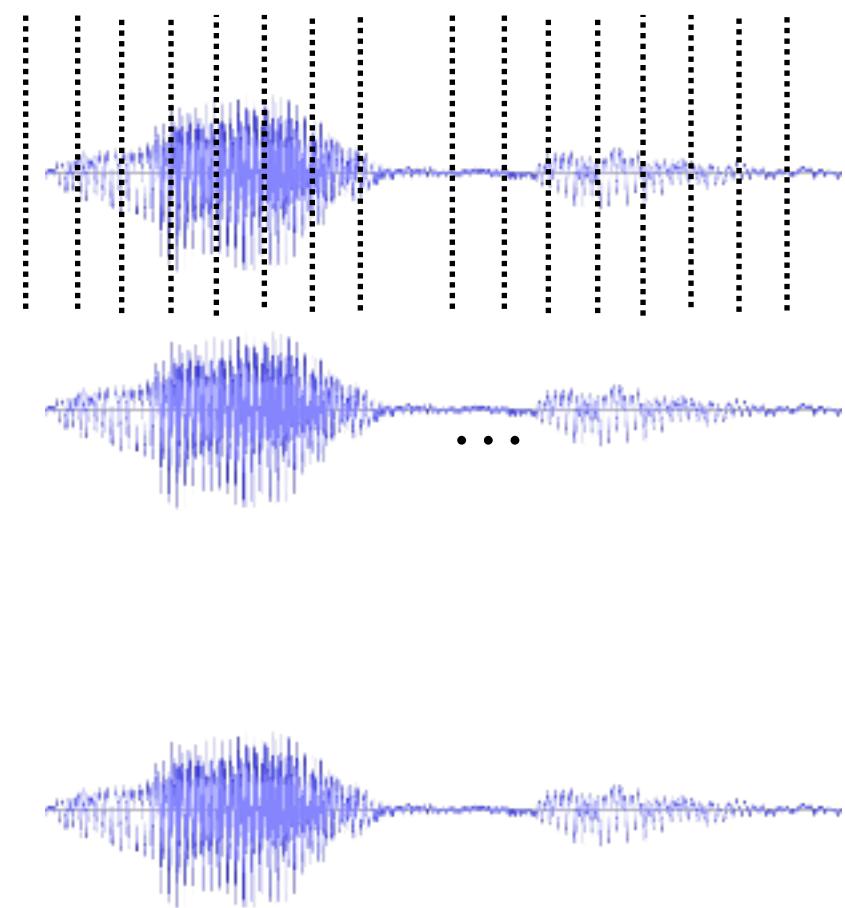
$\rightarrow O_1^1, \dots, O_{t1}^1$ **and** $\mathbf{w}^1 = w_1^1, \dots, w_{\ell 1}^1$

...

...

Overall Summary

Training



$\rightarrow O_1^1, \dots, O_{t1}^1$ **and** $\mathbf{w}^1 = w_1^1, \dots, w_{\ell 1}^1$

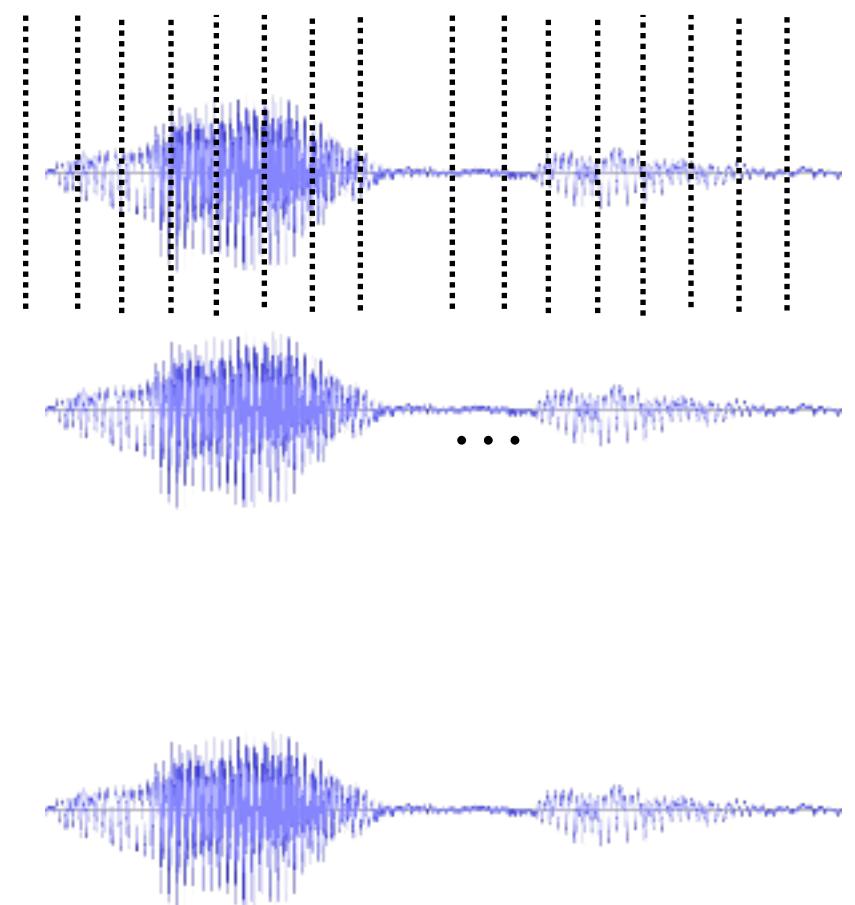
$\dots \rightarrow O_1^2, \dots, O_{t2}^2$ **and** $\mathbf{w}^2 = w_1^2, \dots, w_{\ell 2}^2$

\vdots

$\rightarrow O_1^N, \dots, O_{tN}^N$ **and** $\mathbf{w}^N = w_1^N, \dots, w_{\ell N}^N$

Overall Summary

Training



$\rightarrow O_1^1, \dots, O_{t1}^1 \quad \text{and} \quad \mathbf{w}^1 = w_1^1, \dots, w_{\ell 1}^1$

$\dots \rightarrow O_1^2, \dots, O_{t2}^2 \quad \text{and} \quad \mathbf{w}^2 = w_1^2, \dots, w_{\ell 2}^2$

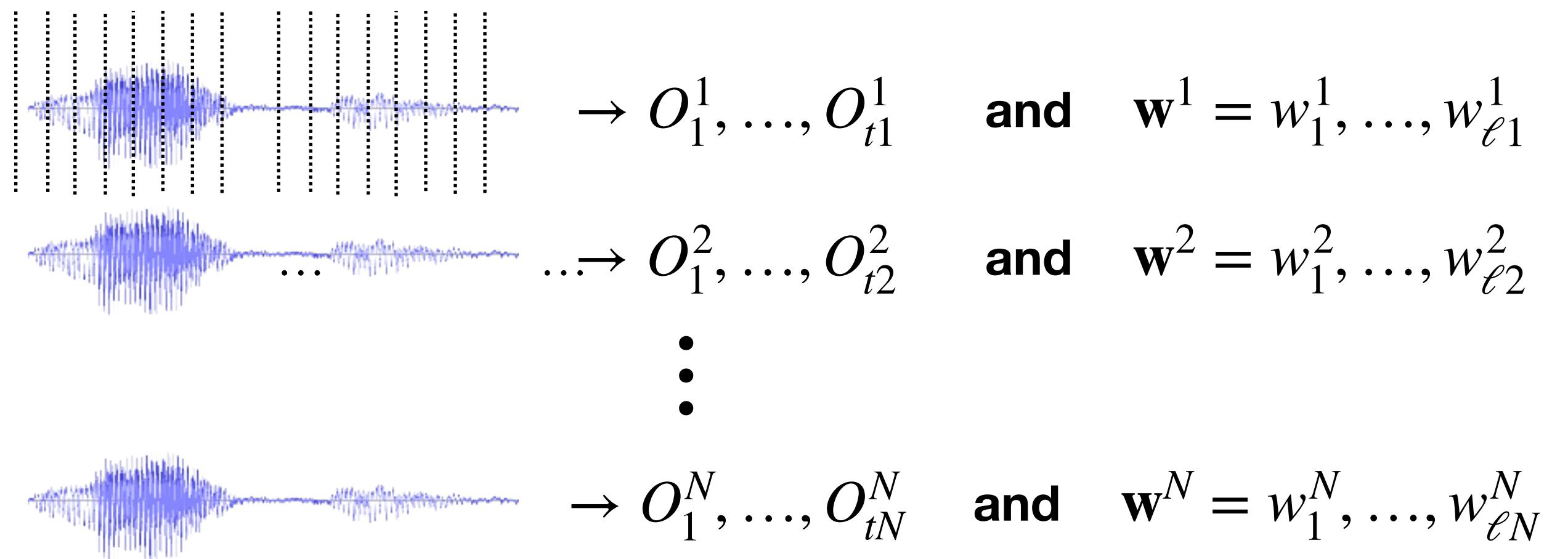
\vdots

$\rightarrow O_1^N, \dots, O_{tN}^N \quad \text{and} \quad \mathbf{w}^N = w_1^N, \dots, w_{\ell N}^N$

Estimate $\theta = \{A_{jk}, (\mu_{jm}, \Sigma_{jm}, C_{jm})\}$ over all phone states. Use Baum-Welch.

Overall Summary

Training

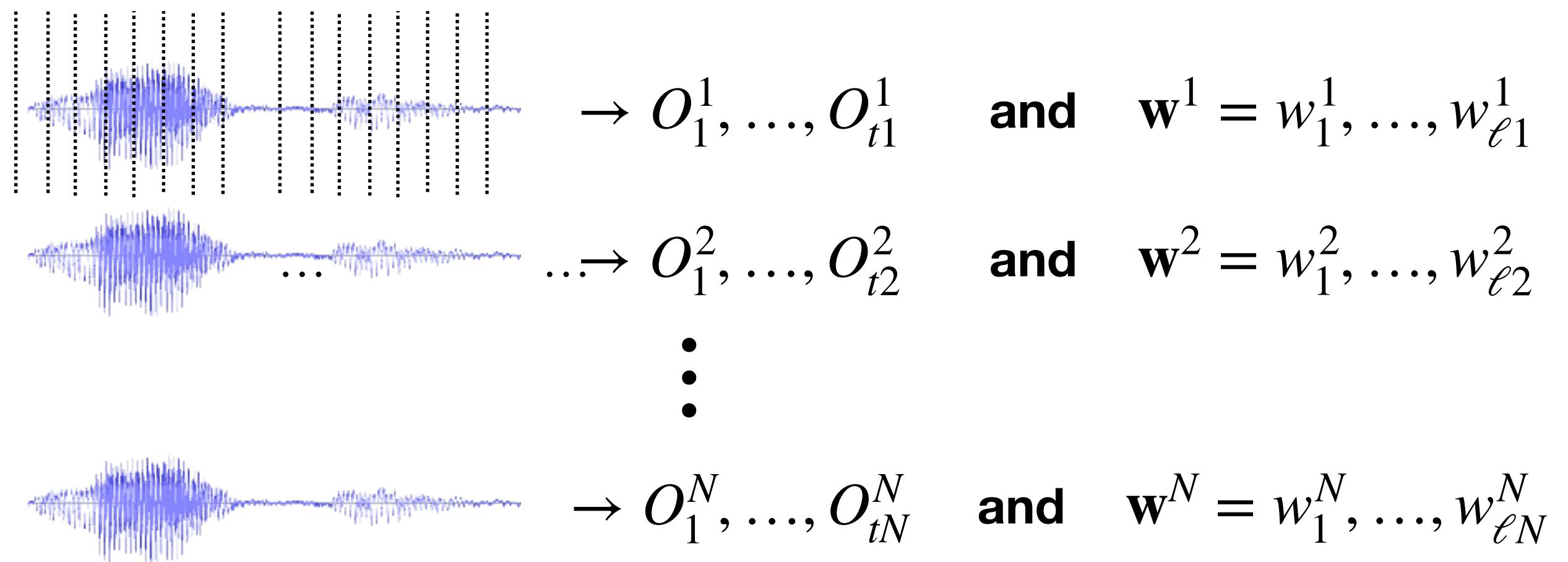


Estimate $\theta = \{A_{jk}, (\mu_{jm}, \Sigma_{jm}, C_{jm})\}$ over all phone states. Use Baum-Welch.

HMM of i th training utterance determined by using a word-to-phone mapping applied to $w_1^i, \dots, w_{\ell i}^i$

Overall Summary

Training



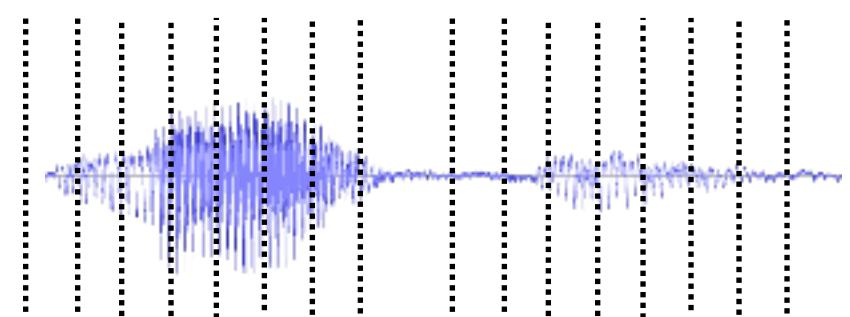
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HMM of i th training utterance determined by using a word-to-phone mapping applied to $w_1^i, \dots, w_{\ell i}^i$

Train LM using $\mathbf{w}^1, \dots, \mathbf{w}^N$

Overall Summary

Training



$$\rightarrow O_1^1, \dots, O_{t1}^1 \quad \text{and} \quad \mathbf{w}^1 = w_1^1, \dots, w_{\ell 1}^1$$

$$\dots \rightarrow O_1^2, \dots, O_{t2}^2 \quad \text{and} \quad \mathbf{w}^2 = w_1^2, \dots, w_{\ell 2}^2$$

⋮

$$\rightarrow O_1^N, \dots, O_{tN}^N \quad \text{and} \quad \mathbf{w}^N = w_1^N, \dots, w_{\ell N}^N$$

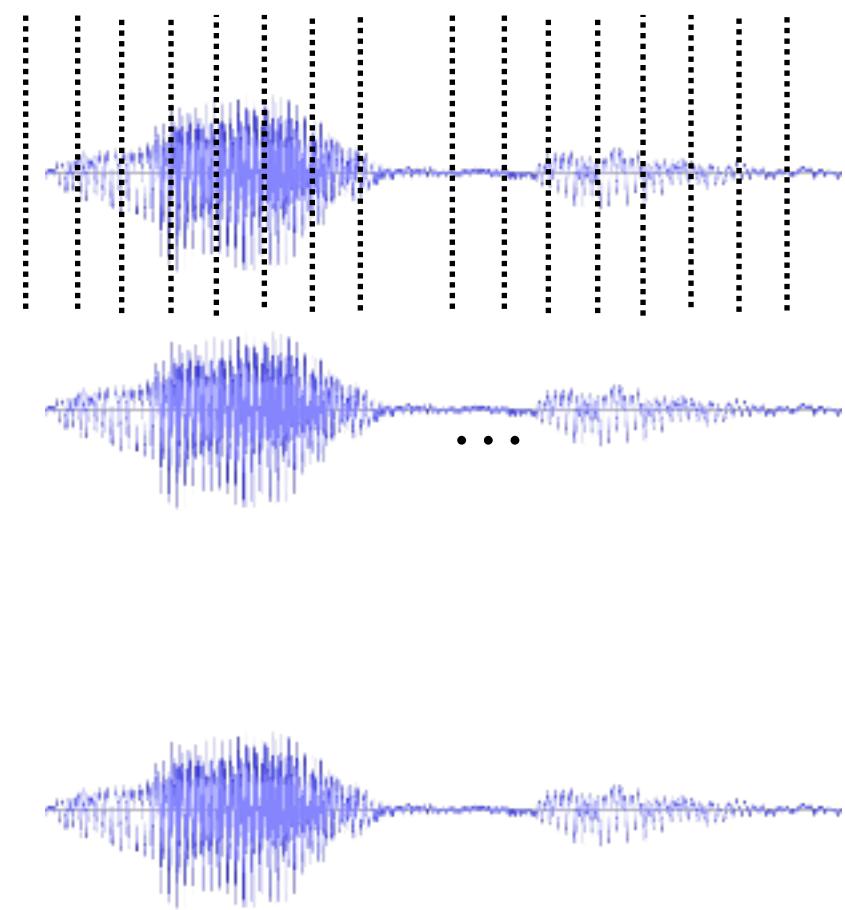
Estimate $\theta = \{A_{jk}, (\mu_{jm}, \Sigma_{jm}, C_{jm})\}$ over all phone states. Use Baum-Welch.

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Overall Summary

Training



$\rightarrow O_1^1, \dots, O_{t1}^1$ and $\mathbf{w}^1 = w_1^1, \dots, w_{\ell 1}^1$
 $\dots \rightarrow O_1^2, \dots, O_{t2}^2$ and $\mathbf{w}^2 = w_1^2, \dots, w_{\ell 2}^2$
 \vdots
 $\rightarrow O_1^N, \dots, O_{tN}^N$ and $\mathbf{w}^N = w_1^N, \dots, w_{\ell N}^N$

Estimate $\theta = \{A_{jk}, (\mu_{jm}, \Sigma_{jm}, C_{jm})\}$ over all phone states. Use Baum-Welch.

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Train LM using $\mathbf{w}^1, \dots, \mathbf{w}^N$

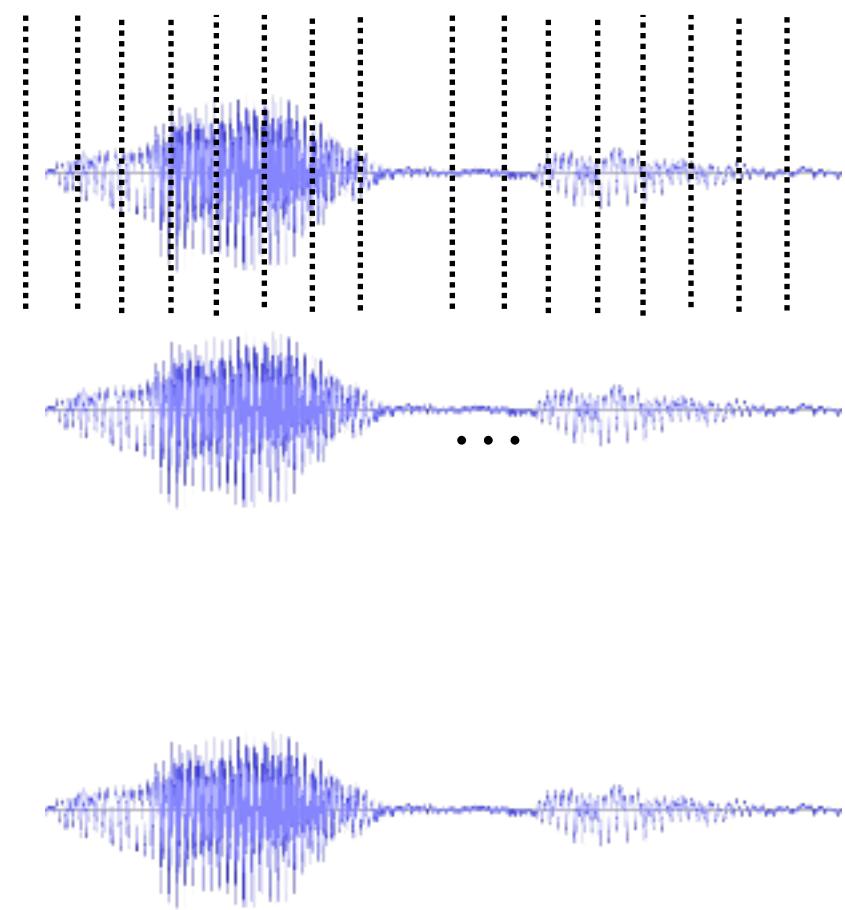
Test



$\mathbf{O} = O_1, \dots, O_T$

Overall Summary

Training



$\rightarrow O_1^1, \dots, O_{t1}^1$ and $\mathbf{w}^1 = w_1^1, \dots, w_{\ell 1}^1$
 $\dots \rightarrow O_1^2, \dots, O_{t2}^2$ and $\mathbf{w}^2 = w_1^2, \dots, w_{\ell 2}^2$
 \vdots
 $\rightarrow O_1^N, \dots, O_{tN}^N$ and $\mathbf{w}^N = w_1^N, \dots, w_{\ell N}^N$

Estimate $\theta = \{A_{jk}, (\mu_{jm}, \Sigma_{jm}, C_{jm})\}$ over all phone states. Use Baum-Welch.

HMM of i th training utterance determined by using a word-to-phone mapping applied to $w_1^i, \dots, w_{\ell i}^i$

Train LM using $\mathbf{w}^1, \dots, \mathbf{w}^N$

Test

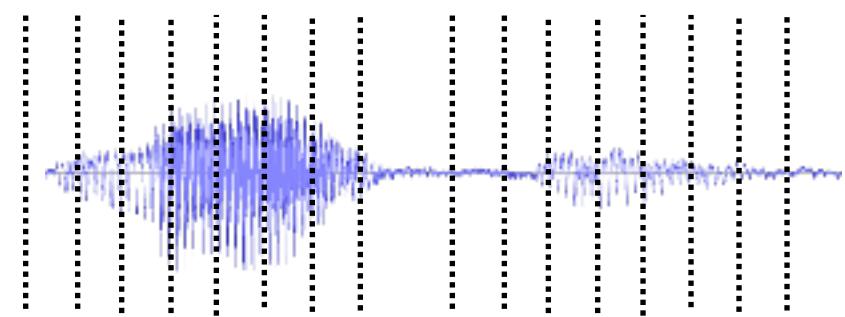


$$\mathbf{O} = O_1, \dots, O_T$$

$$W^* = \arg \max_W P(W | O)$$

Overall Summary

Training



$$\rightarrow O_1^1, \dots, O_{t1}^1 \quad \text{and} \quad \mathbf{w}^1 = w_1^1, \dots, w_{\ell 1}^1$$

$$\dots \rightarrow O_1^2, \dots, O_{t2}^2 \quad \text{and} \quad \mathbf{w}^2 = w_1^2, \dots, w_{\ell 2}^2$$

⋮

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Train LM using $\mathbf{w}^1, \dots, \mathbf{w}^N$

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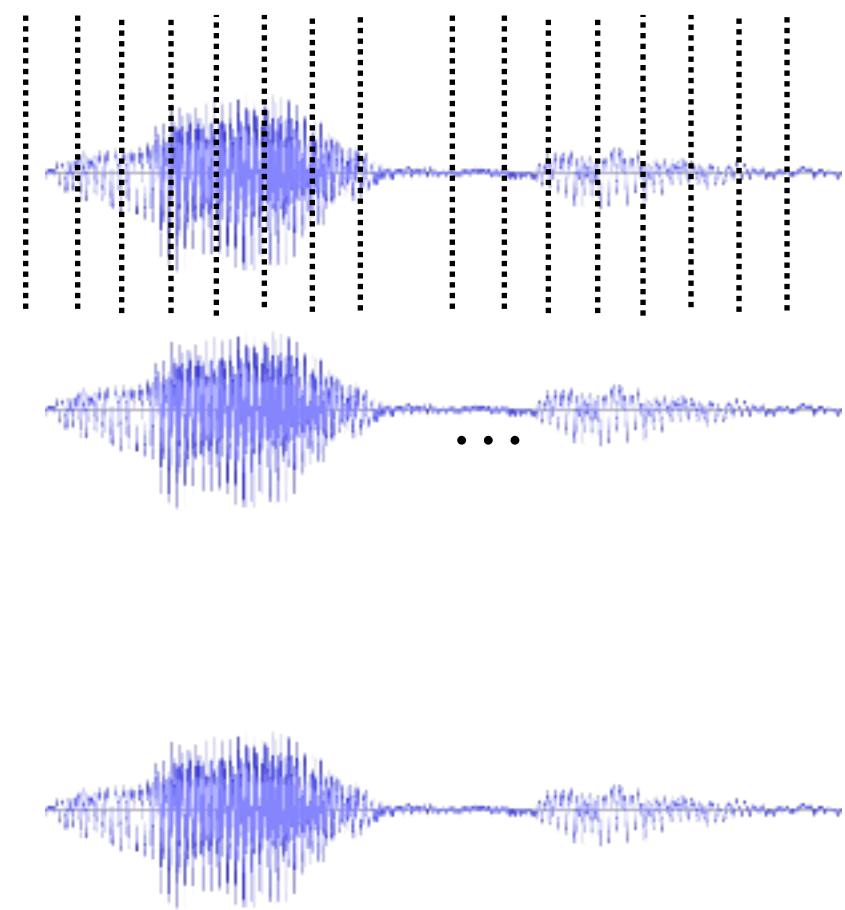
$$\mathbf{O} = O_1, \dots, O_T$$

$$W^* = \arg \max_W P(W | O)$$

Compute using Viterbi algorithm

Overall Summary

Training



$\rightarrow O_1^1, \dots, O_{t1}^1$ and $\mathbf{w}^1 = w_1^1, \dots, w_{\ell 1}^1$
 $\dots \rightarrow O_1^2, \dots, O_{t2}^2$ and $\mathbf{w}^2 = w_1^2, \dots, w_{\ell 2}^2$
 \vdots
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HMM of i th training utterance determined by using a word-to-phone mapping applied to $w_1^i, \dots, w_{\ell i}^i$

Train LM using $\mathbf{w}^1, \dots, \mathbf{w}^N$

Test



$$\mathbf{O} = O_1, \dots, O_T$$

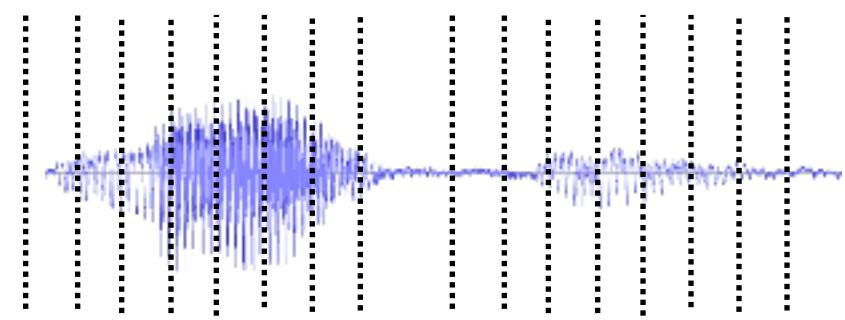
$$W^* = \arg \max_W P(W | O)$$

Compute using Viterbi algorithm

Search all possible state sequences arising from all word sequences most likely to have generated \mathbf{O}

Overall Summary

Training



$$\rightarrow O_1^1, \dots, O_{t1}^1 \quad \text{and} \quad \mathbf{w}^1 = w_1^1, \dots, w_{\ell 1}^1$$

$$\dots \rightarrow O_1^2, \dots, O_{t2}^2 \quad \text{and} \quad \mathbf{w}^2 = w_1^2, \dots, w_{\ell 2}^2$$

⋮

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Train LM using $\mathbf{w}^1, \dots, \mathbf{w}^N$

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$$\mathbf{O} = O_1, \dots, O_T$$

$$W^* = \arg \max_W P(W | O)$$

Compute using Viterbi algorithm

Search all possible state sequences arising from all word sequences most likely to have generated \mathbf{O}

Computationally intractable for continuous speech! Efficient algorithms in later classes.