

Power Amplifiers

Typical PA Performance

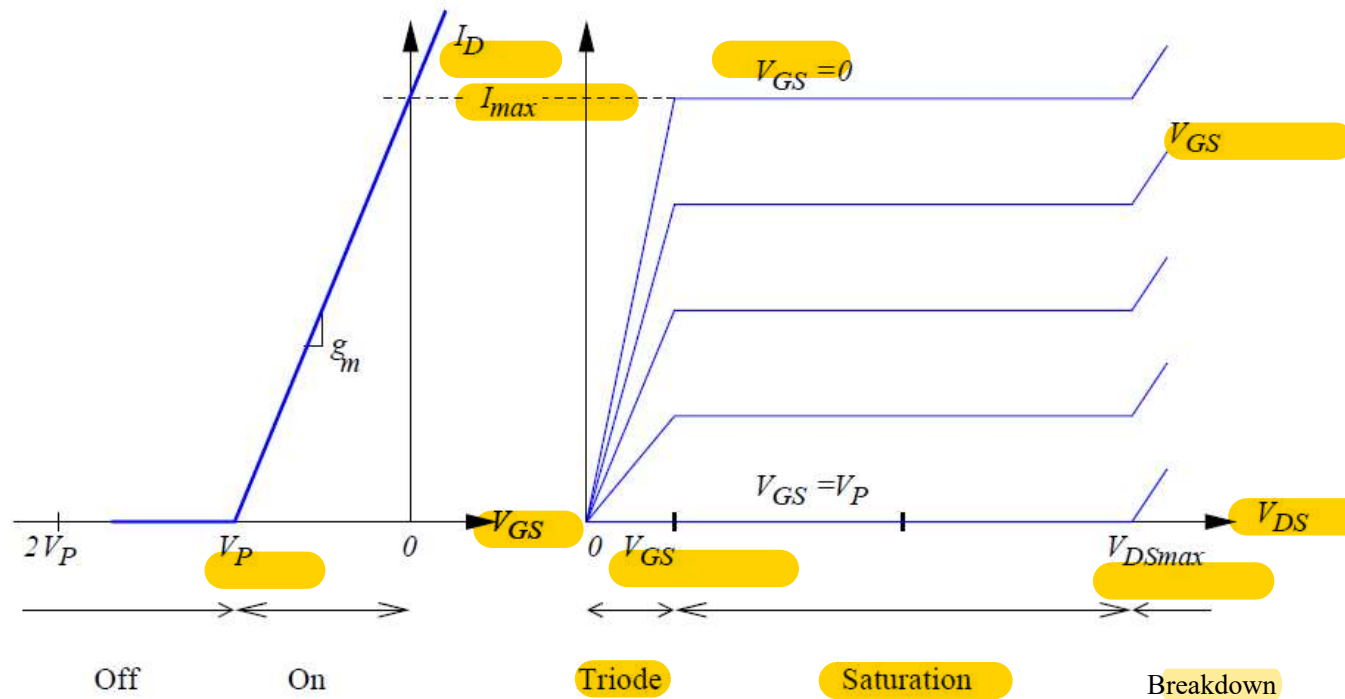
Output Power	20 to 30 dBm (.1 to 1 W)
Efficiency	30 % to 60 %
IMD	- 30 dBc
Supply Voltage	3.8 to 5.8 V
Gain	20 to 30 dB
Output Spurs & Harmonics	- 50 to - 70 dBc
Power Control	On-Off (TDMA) or 1 dB-steps (CDMA)
Output Thermal Noise	< -130 dBm/Hz
Stability Factor	>1

PA efficiency

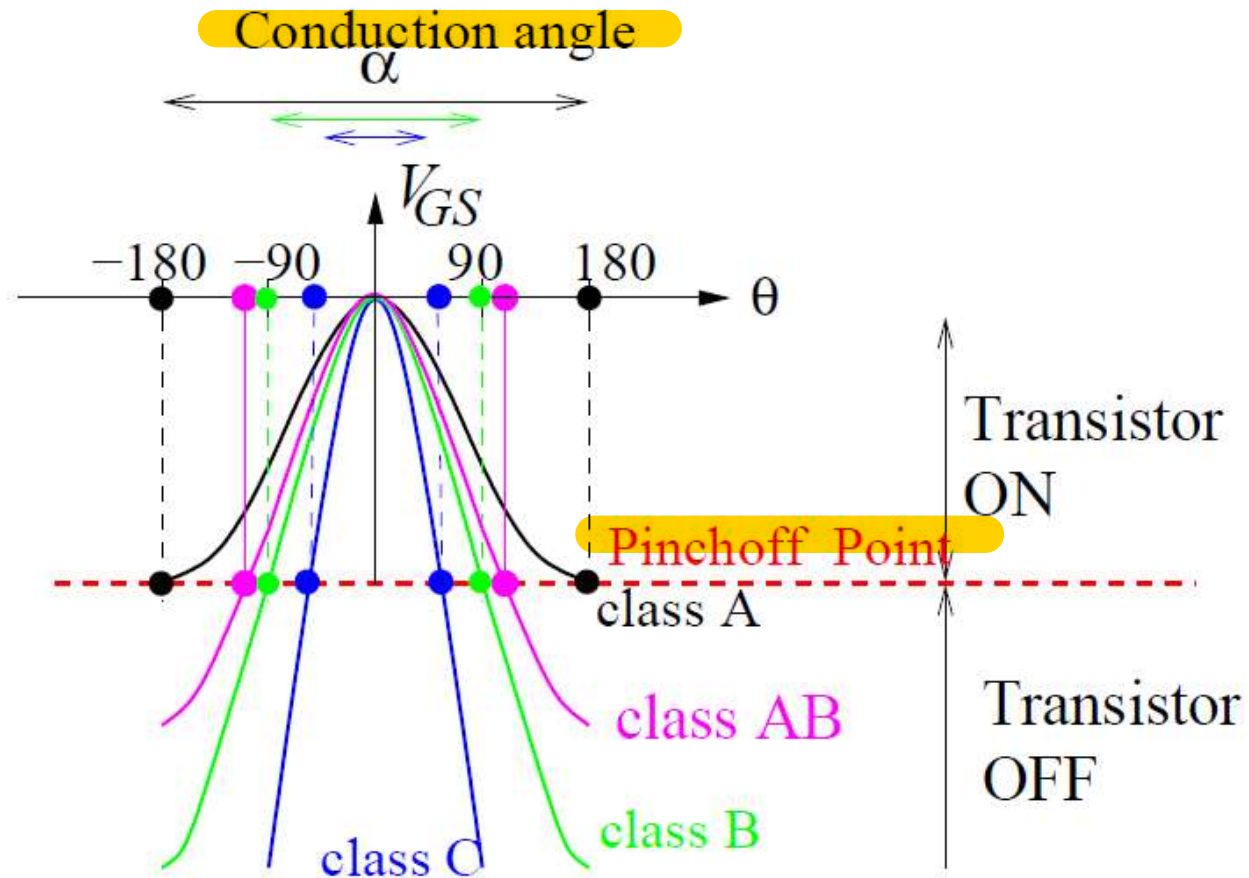
Drain Efficiency, $\eta = \frac{P_{RF}}{P_{DC}}$

Power Added Efficiency, PAE = $\frac{P_{RF} - P_{in}}{P_{DC}}$

Ideal FET Characteristics



Conduction Angle Definition (α)



Class Definition

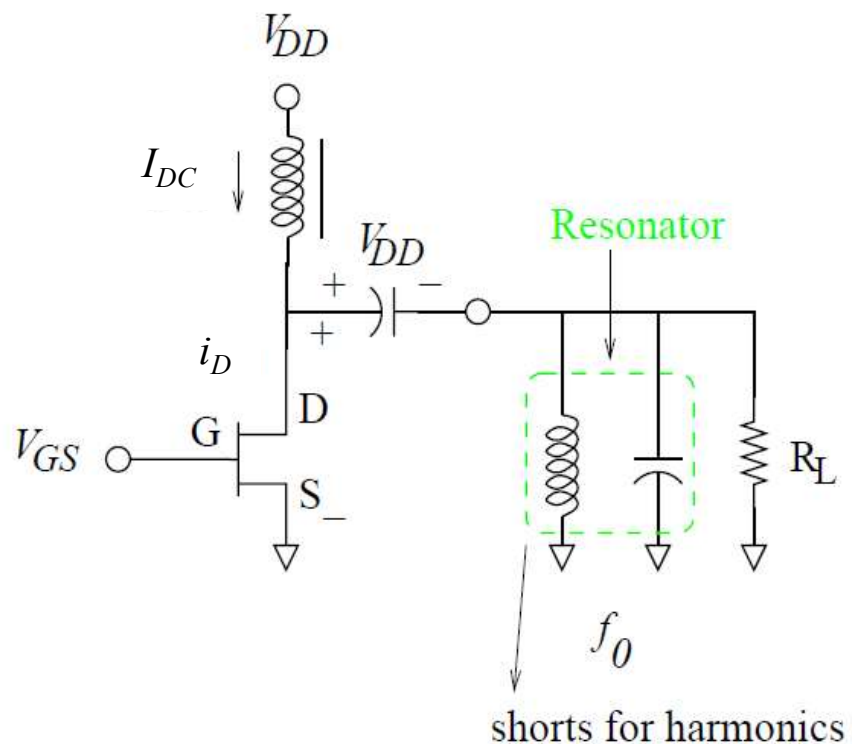
Amplifier classes are defined using the conduction angle:

- Class A: $\alpha = 360^\circ$ (On 100% of the cycle)
- Class AB: $180 < \alpha < 360$ (On 50 - 100% of the cycle)
- Class B: $\alpha = 180^\circ$ (On 50 % of the cycle)
- Class C: $\alpha < 180^\circ$ (On less than 50% of the cycle)

Note:

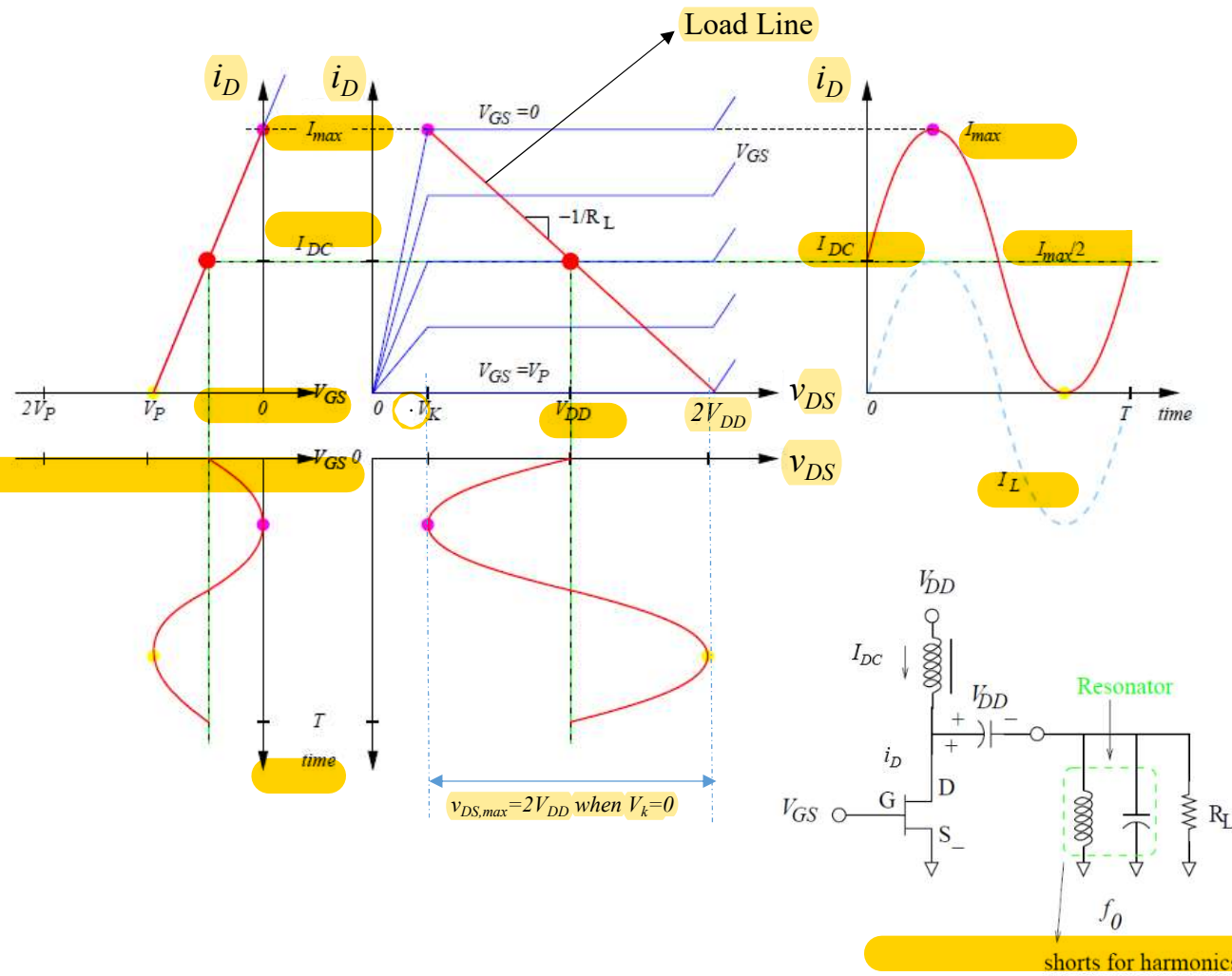
- Low noise amplifiers operate in class A.
- Power amplifiers operate in class A to F

Class A Amplifier



- The RF choke maintains a constant DC current and provides an RF open.
- The power supply voltage V_{DD} appears across the DC block capacitor.
- V_{DS} can swing from 0 to $2V_{DD}$.

Class A Amplifier Operation ($V_K=0$)



$$i_D = I_{DD} + \underbrace{(-i_{pk} \cos(\omega_0 t))}_{I_L} = I_{DD} + \underbrace{(i_{pk} \sin(\omega_0 t))}_{I_L}$$

$$\Rightarrow I_{DC} (\text{dc value of } i_D) = I_{DD}$$

$$I_{DC} = V_{DD} / R_L \Rightarrow I_{DD} = V_{DD} / R_L$$

because V_{DD} appears directly across R_L when $v_{DS} = 0$

$$\text{when } i_D = 0 \Rightarrow |i_{pk}| = I_{DD} = V_{DD} / R_L$$

$$\text{max value of } i_D = I_{max} = 2|i_{pk}| = 2I_{DC}$$

Taking $V_K = 0$,

$$v_{DS} = V_{DD} + i_{pk} R_L \cos(\omega_0 t)$$

$$\Rightarrow v_{DS,max} = 2V_{DD}$$

Further,

$$v_{DS} = 2V_{DD} - R_L i_D = v_{DS,max} - R_L i_D \rightarrow \text{Load line eqn}$$

$$\text{when } i_D = 0, v_{DS} = v_{DS,max}$$

$$\text{when } v_{DS} = 0, i_D = I_{max} \Rightarrow I_{max} = \frac{2V_{DD}}{R_L} = 2I_{DD} = 2I_{DC}$$

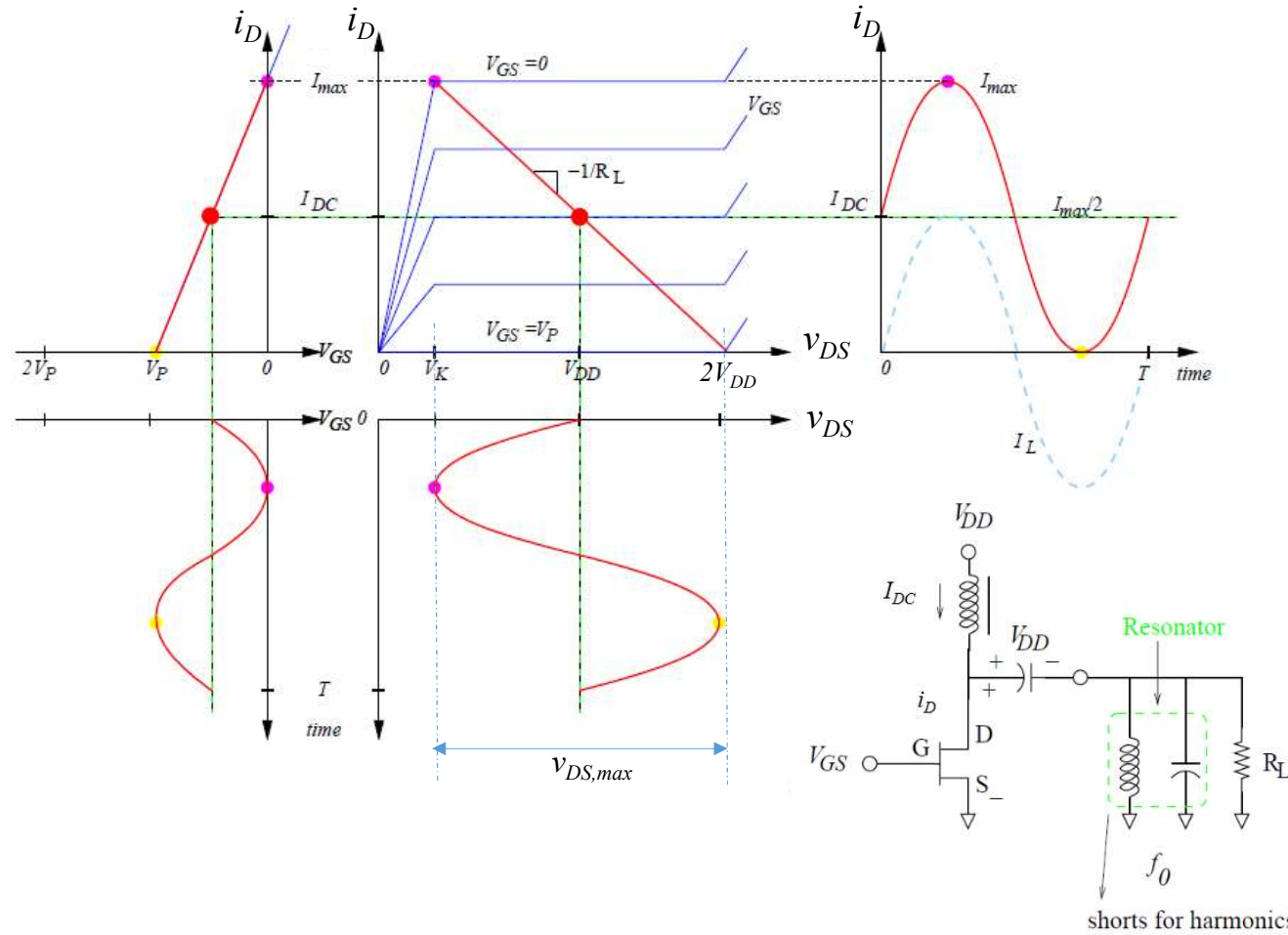
$$P_{rf,max} = \frac{i_{pk}^2 R_L}{2} = \frac{I_{DD}^2 R_L}{2} = \frac{V_{DD}^2}{2R_L},$$

$$P_{DC} = I_{DD} V_{DD} = I_{DD}^2 R_L = \frac{V_{DD}^2}{R_L}$$

$$\text{Drain Efficiency, } \eta = \frac{P_{RF,MAX}}{P_{DC}} = \frac{1}{2} = 50\%$$

assuming V_K is very small

If V_K (Knee Voltage) $\neq 0$ (Class A)



$$V_{RF} = \frac{1}{2}(v_{DS\max} - V_K)$$

The rf voltage swing across D-S is centered at V_{DD}

$$\text{Hence, } V_{DD} = \frac{1}{2}(v_{DS\max} + V_K)$$

$$\Rightarrow v_{DS\max} = 2V_{DD} - V_K$$

amplitude of rf output current, $i_{pk} = I_{DC} = I_{DD}$

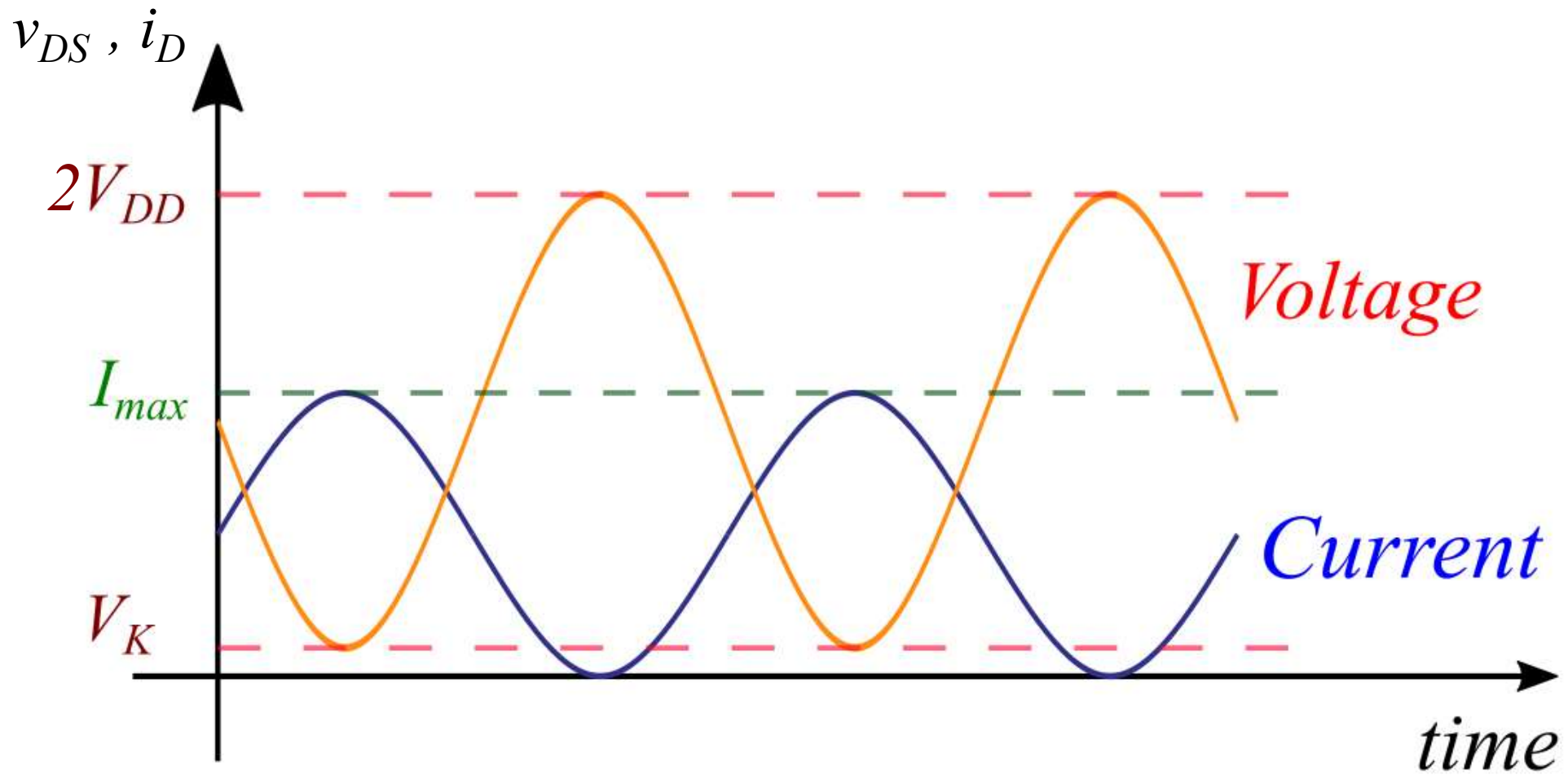
$$P_{RF} = \frac{1}{2}V_{RF}i_{pk} \quad (\text{Assuming swing is between } v_{DS\max} \text{ and } V_K)$$

$$= \frac{1}{4}(v_{DS\max} - V_K)I_{DC}$$

$$P_{DC} = V_{DD}I_{DC}$$

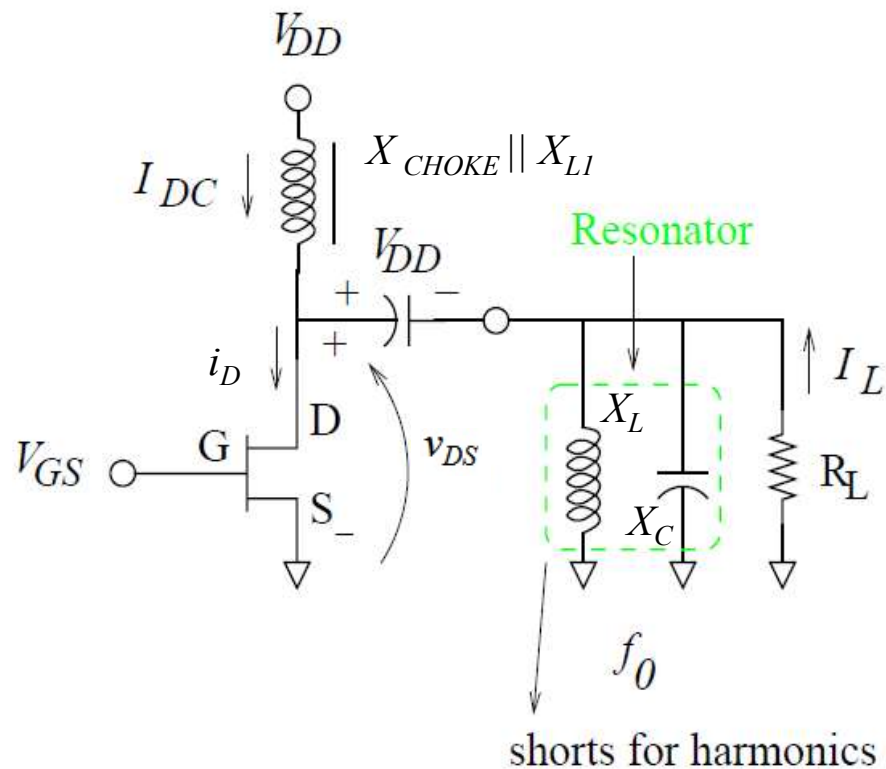
$$\eta = \frac{P_{RF}}{P_{DC}} = \frac{\frac{1}{4}(v_{DS\max} - V_K)I_{DC}}{\frac{1}{2}(v_{DS\max} + V_K)I_{DC}}$$

$$= \frac{1}{2} \frac{v_{DS\max} - V_K}{v_{DS\max} + V_K} = 50\% \text{ when } V_K = 0$$



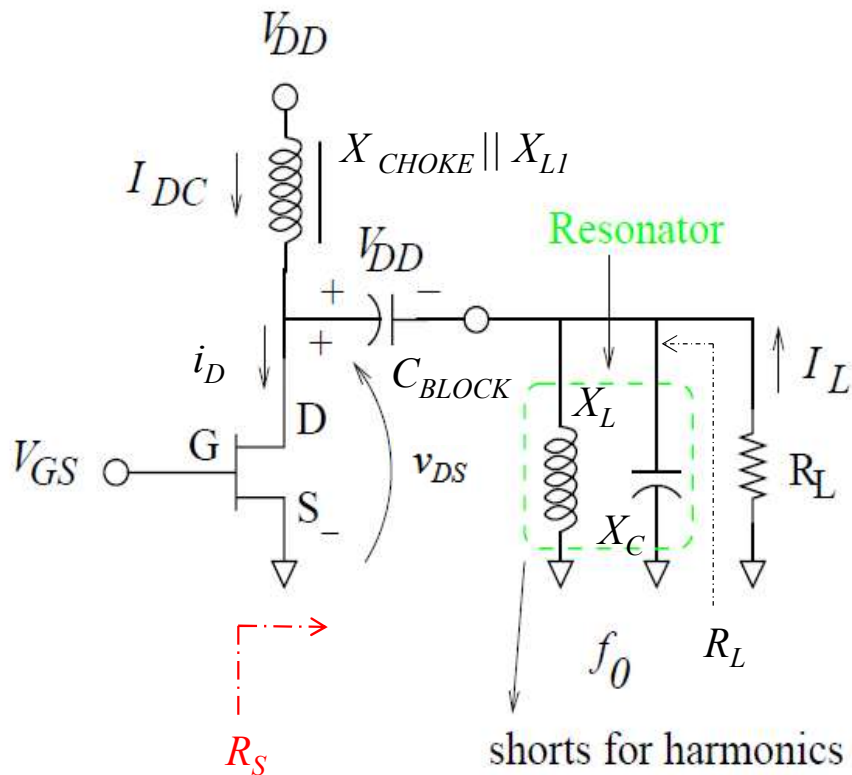
Drain voltage and current for ideal Class A amplifier

Class A amplifier design example



- Required max o/p power, $P_{max} = 1$ watt, $V_{DD} = 3.3$ V.
- $R_L = V_{DD}^2 / 2P_{max} = (3.3)^2 / (2 \times 1) = 5.4$ ohms.
- Peak RF current $i_{pk} = V_{DD} / R_L = 3.3 / 5.4 = 0.611$ mA.
- $I_{DC} = i_{pk} = 0.611$ mA.
- Drain efficiency, $\eta = P_{max} / P_{DC} = 1 / (0.611 \times 3.3) = 49.6 \% < 50\%$.
- Say $f = 1$ GHz. Required $Q = 10$. Hence $2\Delta f = 100$ MHz.
- $Q = \omega C / G \Rightarrow \omega C = (1/50) \times 10$
 $\Rightarrow C = (1/5) \times (1 / (2 \times \pi \times 10^9)) = 31.8$ pF
- $X_L = X_C = 1 / \omega C = 1 / (2 \times \pi \times 10^9 \times 31.8 \times 10^{-12})$
 $\Rightarrow L = X_L / (2 \times \pi \times 10^9) = 0.79$ nH

Class A amplifier design example (..Contd)

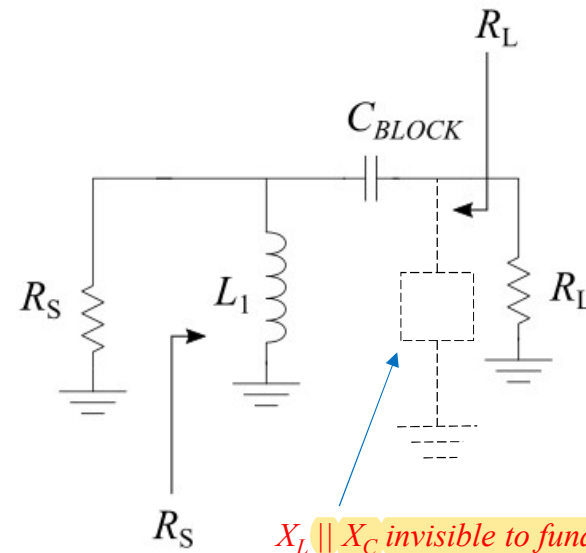


$$X_{CHOKE} = 10R_L = 10 \times 5.4 \text{ ohms} = 54 \text{ ohms} \Rightarrow L_{CHOKE} = 8.6 \text{ nH}$$

$$M \cong \sqrt{R_S/R_L} = \sqrt{50/5.4} = 3.04$$

$$L_1 = R_S / (2 \times \pi \times 10^9 \times M) = 2.6 \text{ nH} \rightarrow \text{combined with } L_{CHOKE}$$

$$C_{BLOCK} = 1 / (2 \times \pi \times 10^9 \times M \times R_L) = 9.7 \text{ pF}$$

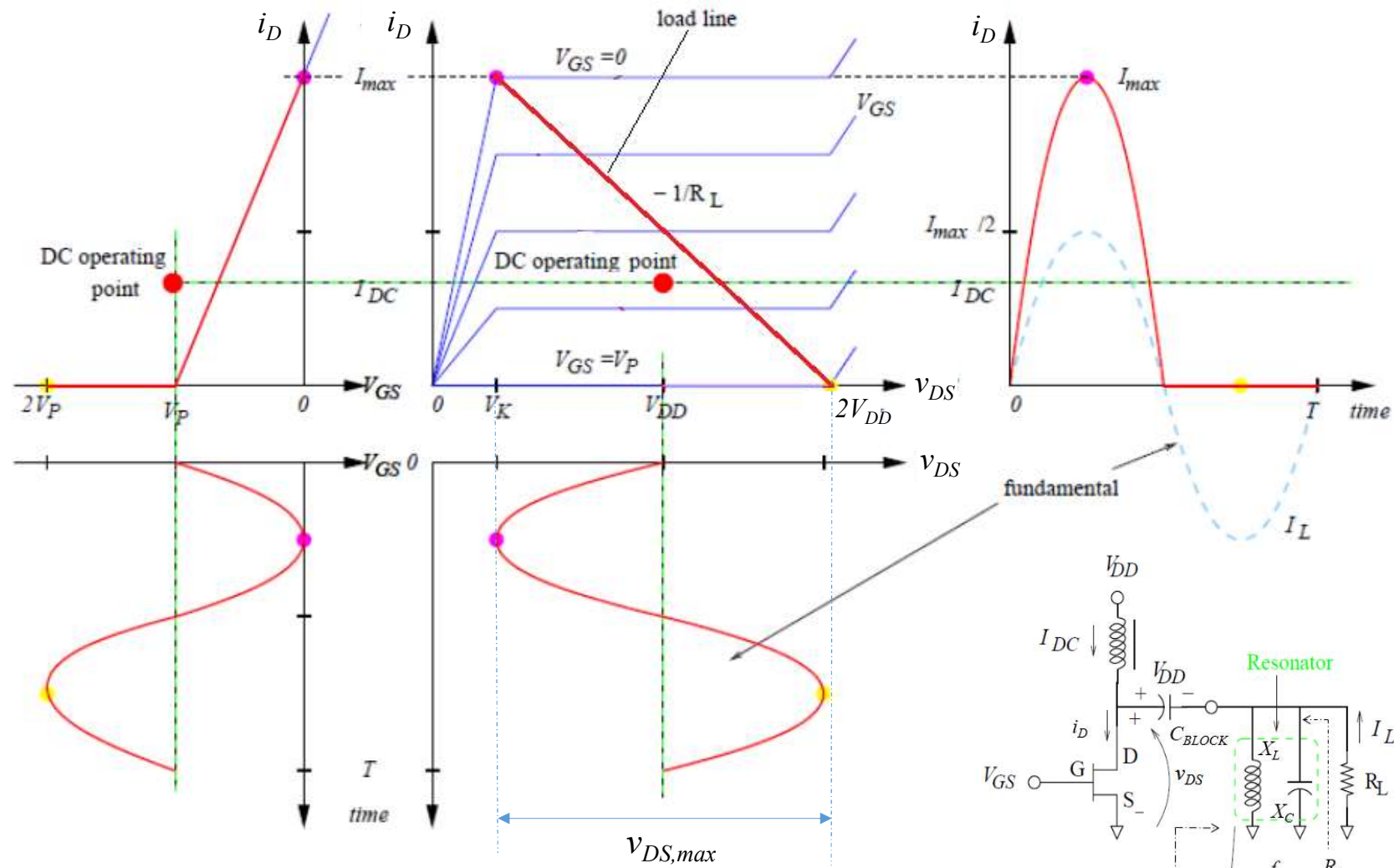


$$X_{L1} \cong R_S/M$$

$$X_{C,BLOCK} \cong M R_L$$

$X_L \parallel X_C$ invisible to fundamental

Class B Amplifiers



Jayanta Mukherjee

Class-B Operation

· Drain current on for half the cycle

$$i_D = \begin{cases} i_{rf} \sin(\omega_0 t) & i_d > 0 \\ 0 & i_d \leq 0 \end{cases}$$

$$i_D(t) = \underbrace{\frac{i_{rf}}{\pi}}_{dc} + \underbrace{\frac{i_{rf}}{2} \sin(2\pi f_0 t)}_{-I_L \text{ (fundamental)}} - \underbrace{\frac{2i_{rf}}{\pi} \sum_{k \geq 1} \frac{\cos(4\pi k f t)}{4k^2 - 1}}_{\text{higher harmonics (sunk by BP filter)}}$$

$$I_{DC} = \frac{i_{rf}}{\pi}$$

$$v_{RF} = -\frac{i_{rf}}{2} R_L \sin(\omega_0 t),$$

$$\text{Max value of } v_{RF, \max} = V_{DD} = v_{DS \max} - (v_{DS \max} + V_K) / 2 = (v_{DS \max} - V_K) / 2$$

$$\Rightarrow v_{DS \max} \approx 2V_{DD} \text{ (Taking } V_K = 0)$$

$$|i_{rf, \max}| = \frac{2v_{RF, \max}}{R_L} = \frac{2V_{DD}}{R_L} = I_{\max}$$

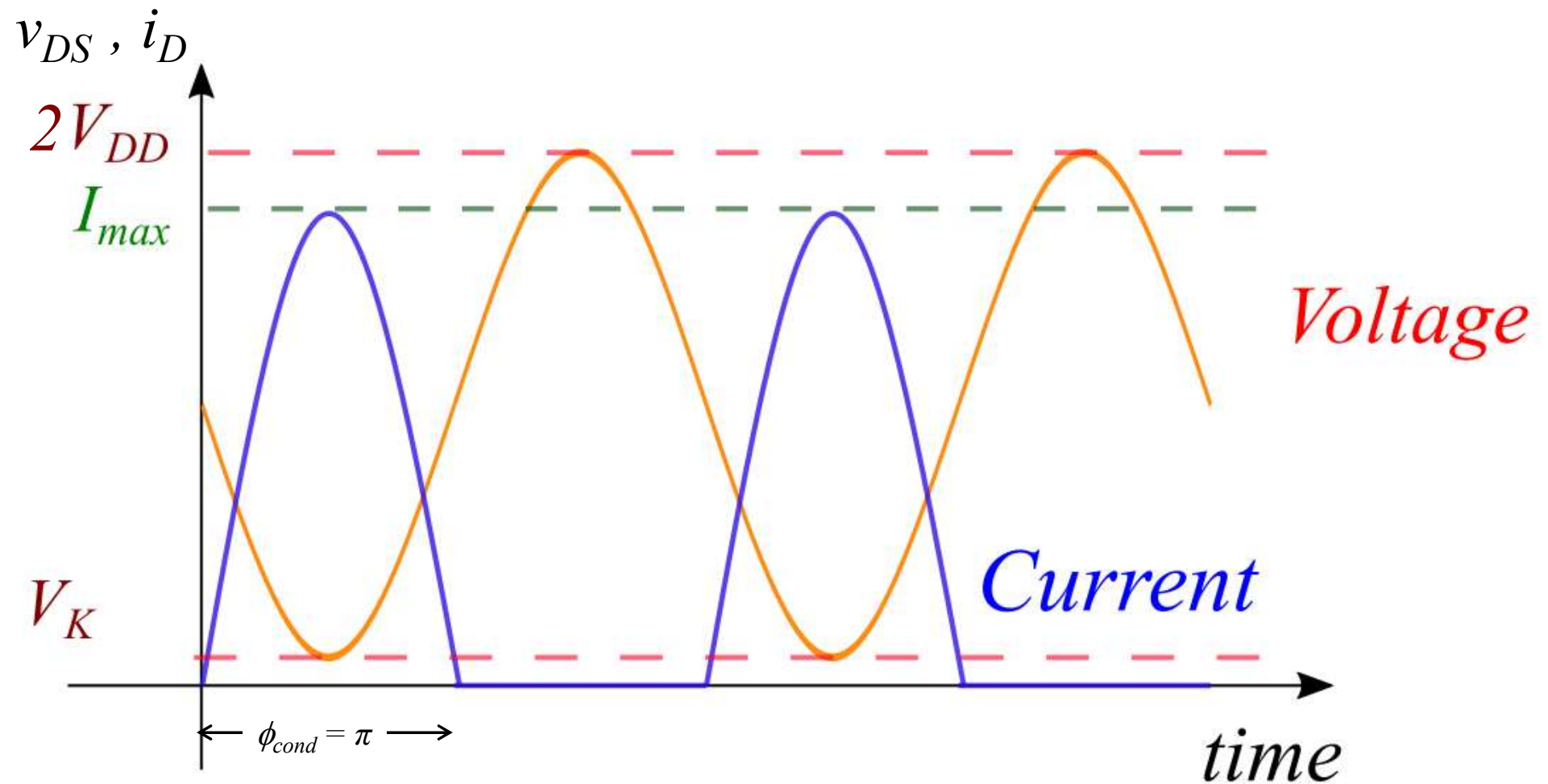
$$P_{RF, \max} = \frac{\left(\frac{i_{rf, \max}}{2} R_L \right)^2}{2R_L} = \frac{V_{DD}^2}{2R_L}$$

· Efficiency

$$P_{RF, \max} = \frac{\left(\frac{i_{rf, \max}}{2} R_L \right)^2}{2R_L} = \frac{V_{DD}^2}{2R_L}$$

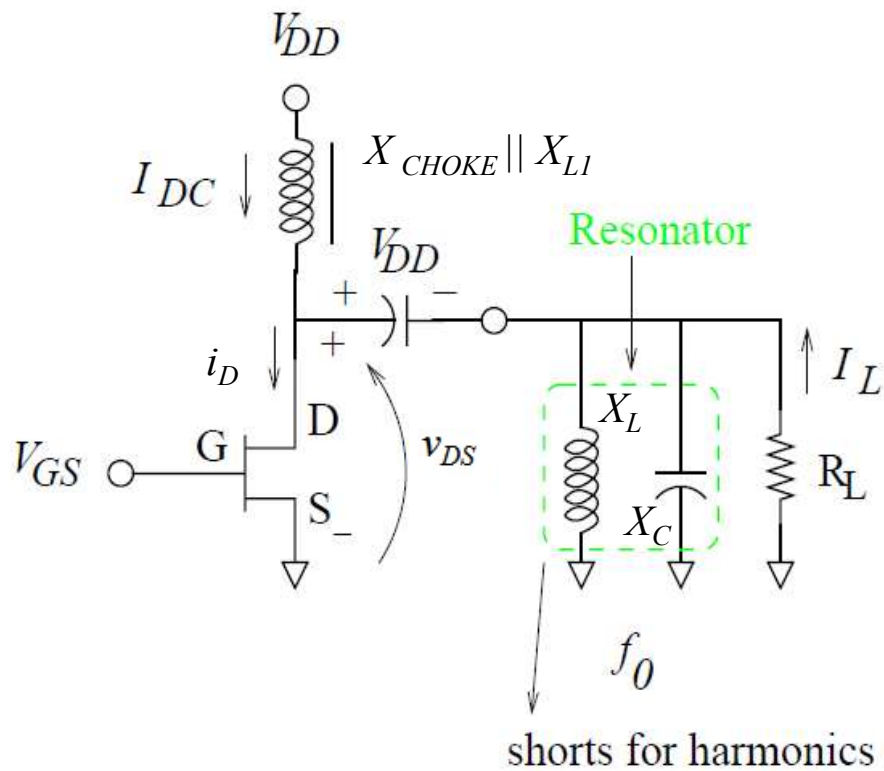
$$P_{DC} = V_{DD} I_{DC} = V_{DD} \cdot \frac{i_{rf}}{\pi} = \frac{2V_{DD}^2}{\pi R_L}$$

$$\text{Drain efficiency, } \eta = \frac{P_{RF, \max}}{P_{DC}} = \frac{\pi}{4} = 78.5\%$$



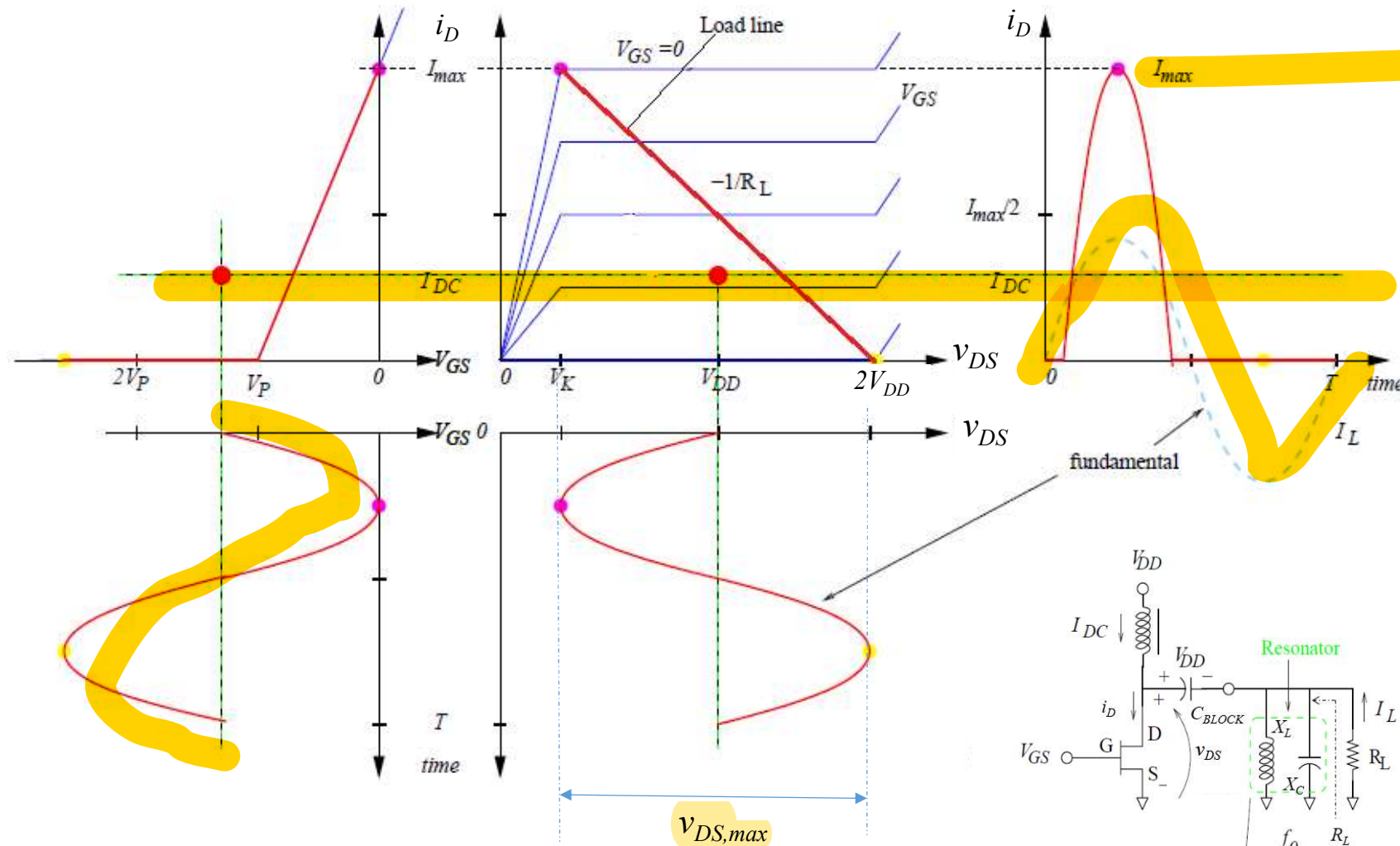
Drain voltage and current for ideal Class B amplifier

Class B amplifier design example



- Required max o/p power, $P_{\max} = 1 \text{ watt} = (1/2)(i_{\text{rf,max}}/2)^2 R_L$,
- $V_{DD} = 3.3 \text{ V}$, $i_{\text{rf,max}} = (2V_{DD}/R_L)$
- $R_L = V_{DD}^2 / 2P_{\max} = (3.3)^2 / (2 \times 1) = 5.4 \text{ ohms}$, $i_{\text{rf,max}} = 1.22 \text{ A}$
- $I_{DC} = i_{\text{rf,max}} / \pi = 0.388 \text{ mA}$.
- Drain efficiency, $\eta = P_{\max} / P_{DC} = 1 / (0.388 \times 3.3) = 78.1 \% > 50\%$.

Class C Amplifier Operation



Jayanta Mukherjee

Class-C Operation

$$i_D = I_{DD} + i_p \cos(\omega_0 t), i_D > 0$$

$$= 0 \text{ otherwise}$$

$$\cos \Phi = -\frac{I_{DD}}{i_p} \Rightarrow I_{DD} = -i_p \cos \Phi, \dots (1)$$

Φ is the value of $\omega_0 t$

when i_D goes to zero.

$$I_{DC} = \frac{1}{2\pi} \int_{-\Phi}^{\Phi} (I_{DD} + i_p \cos \varphi) d\varphi = \frac{1}{2\pi} 2\Phi I_{DD} + \frac{1}{2\pi} [i_p \sin \varphi]_{-\Phi}^{\Phi}$$

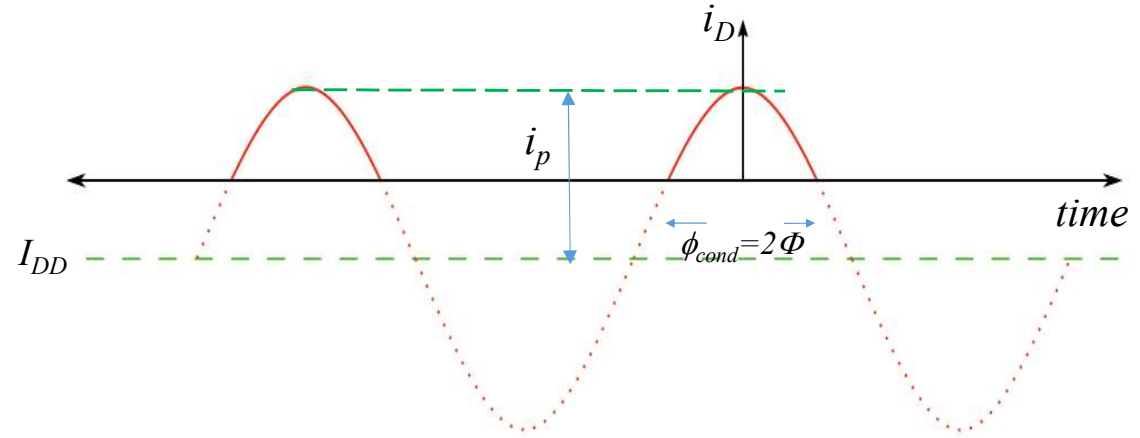
$$\Rightarrow I_{DC} = \frac{i_p}{\pi} [\sin \Phi - \Phi \cos \Phi] = \frac{i_p}{\pi} \left[\sin \frac{\varphi_{cond}}{2} - \frac{\varphi_{cond}}{2} \cos \frac{\varphi_{cond}}{2} \right]$$

Fundamental component

$$i_{fund} = \frac{2}{T} \int_{-T/2}^{T/2} i_D \cos(\omega_0 t) = \frac{1}{\pi} \int_{-\Phi}^{\Phi} (I_{DD} + i_p \cos(\varphi)) \cos(\varphi) d\varphi = \frac{2}{\pi} \int_0^{\Phi} (I_{DD} + i_p \cos(\varphi)) \cos(\varphi) d\varphi$$

$$= \frac{2}{\pi} \left[I_{DD} \sin \varphi + \frac{i_p}{2} (\varphi) + \frac{i_p}{4} (\sin 2\varphi) \right]_0^{\Phi} = \frac{2}{\pi} \left[-i_p \cos \Phi \sin \Phi + \frac{i_p}{2} \Phi + \frac{i_p}{4} (\sin 2\Phi) \right]$$

$$= \frac{i_p}{\pi} \left[\Phi - \frac{1}{2} (\sin 2\Phi) \right] = \frac{i_p}{\pi} \left[\frac{\varphi_{cond}}{2} - \frac{1}{2} (\sin \varphi_{cond}) \right]$$



Class-C Operation

$$v_{rf} = i_{fund} R_L = \frac{R_L i_p}{\pi} \left[\frac{\varphi_{cond}}{2} - \frac{1}{2} (\sin \varphi_{cond}) \right]$$

$$P_{rf} = v_{rf}^2 / (2R_L) = \frac{R_L i_p^2}{2\pi^2} \left[\frac{\varphi_{cond}}{2} - \frac{1}{2} \sin(\varphi_{cond}) \right]^2 = \frac{i_p^2 R_L}{8\pi^2} (\varphi_{cond} - \sin(\varphi_{cond}))^2$$

Maximum value of $v_{rf} = v_{rf,max} = V_{DD} \Rightarrow i_{p,max} = \frac{2\pi V_{DD}}{R_L [\varphi_{cond} - \sin \varphi_{cond}]} = -\frac{I_{DD}}{\cos(\varphi_{cond}/2)}$ (From Eqn (1))

$$\Rightarrow I_{DD} = \frac{2\pi V_{DD} \cos(\varphi_{cond}/2)}{R_L [\sin \varphi_{cond} - \varphi_{cond}]}$$

$$I_{max} = I_{DD} + i_{p,max} = \frac{2\pi V_{DD} \cos(\varphi_{cond}/2)}{R_L [\sin \varphi_{cond} - \varphi_{cond}]} + \frac{2\pi V_{DD}}{R_L [\varphi_{cond} - \sin \varphi_{cond}]} = \frac{2\pi V_{DD} [\cos(\varphi_{cond}/2) - 1]}{R_L [\sin \varphi_{cond} - \varphi_{cond}]} = i_{p,max} [1 - \cos(\varphi_{cond}/2)]$$

Verification:

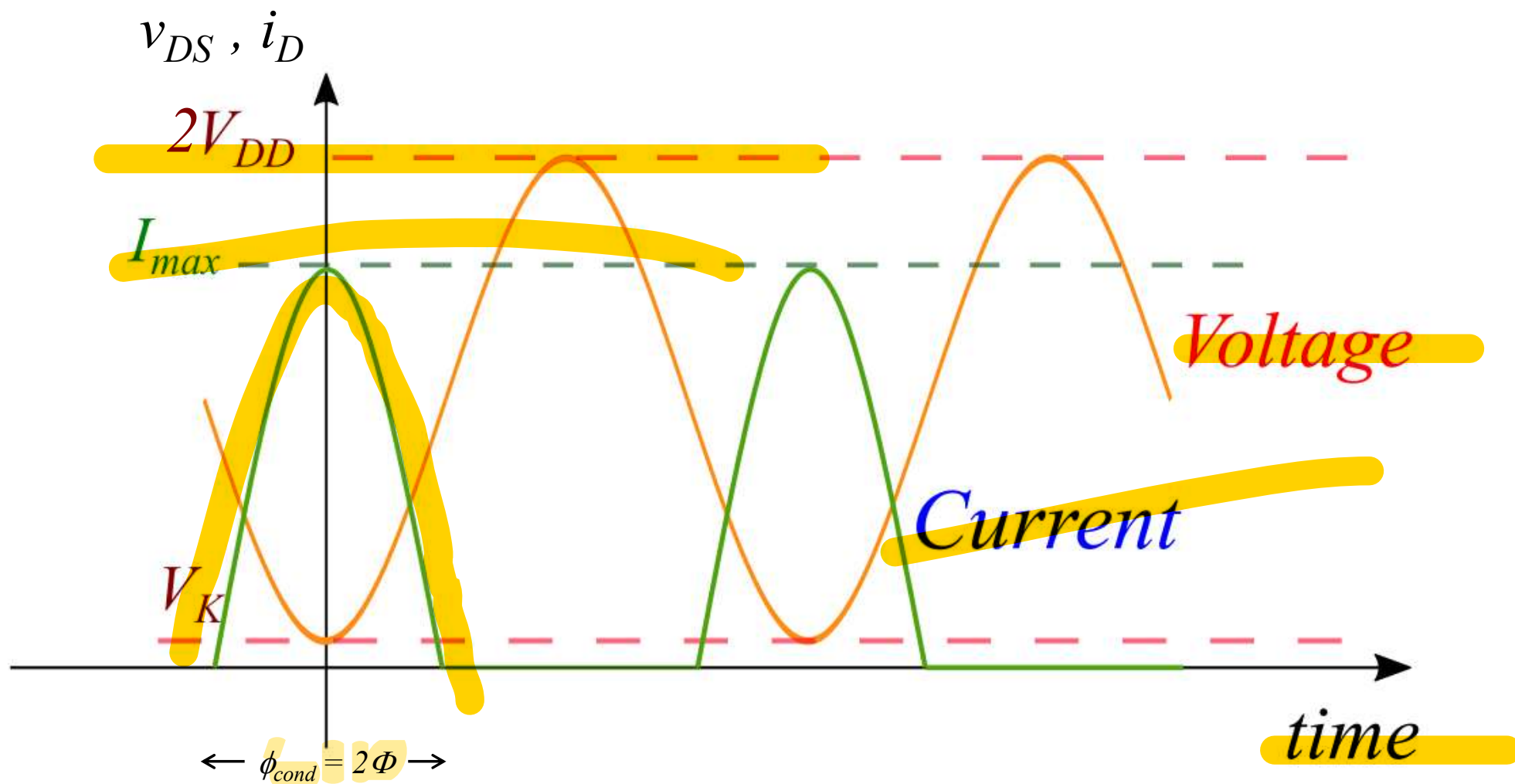
For class A, $\varphi_{cond} = 2\pi$, hence $I_{DD} = V_{DD}/R_L$, For class B, $\varphi_{cond} = \pi$, hence $I_{DD} = 0$

$$I_{max} = I_{DD} + i_{p,max},$$

For class A, $\varphi_{cond} = 2\pi$, hence $I_{max} = I_{DD} + i_{p,max} = 2V_{DD}/R_L$,

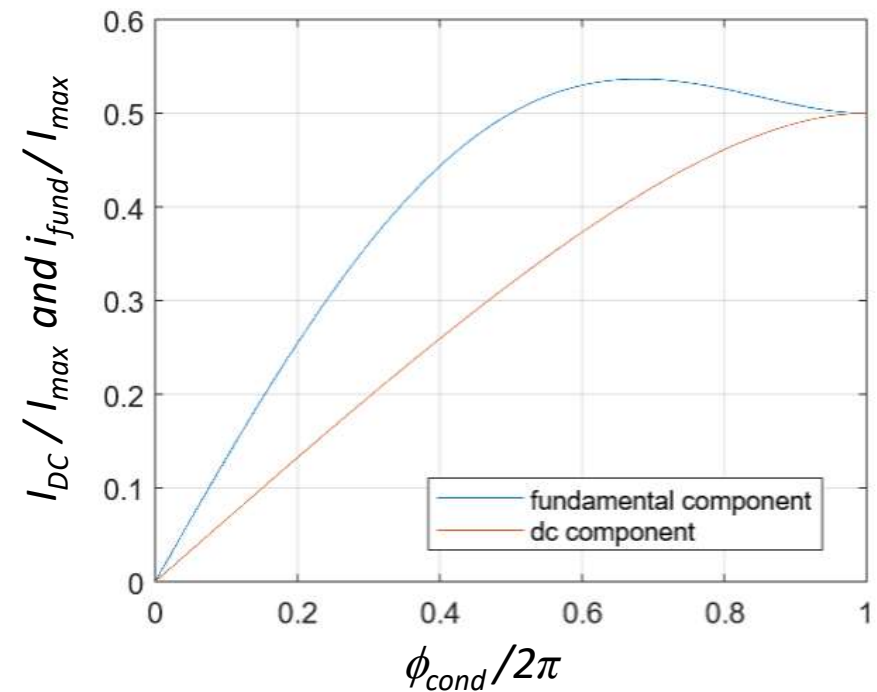
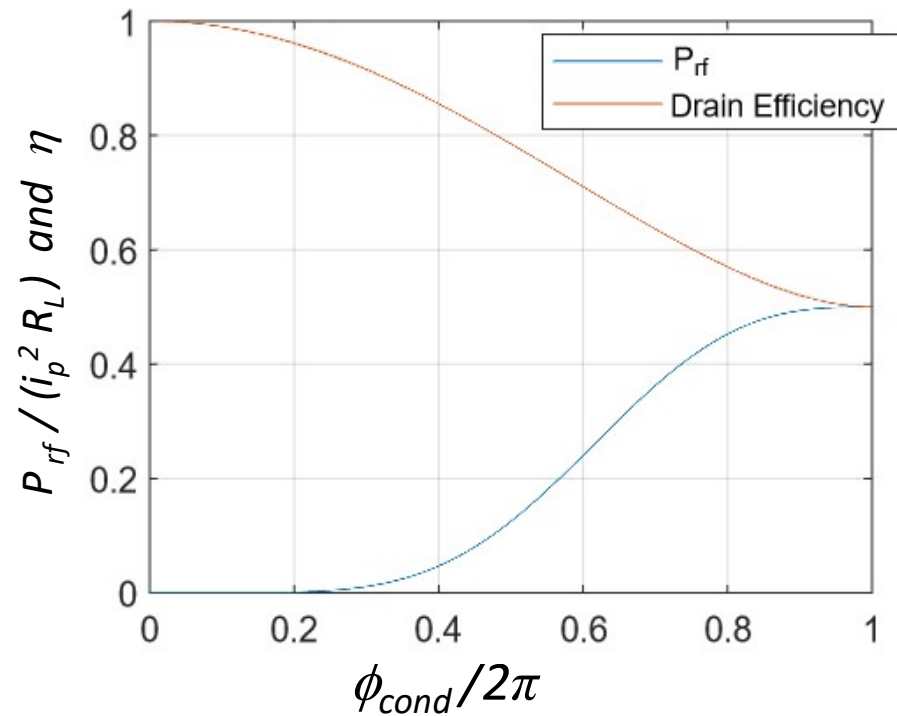
For class B, $\varphi_{cond} = \pi$, hence $I_{max} = I_{DD} + i_{p,max} = 0 + 2V_{DD}/R_L = 2V_{DD}/R_L$

$$\text{Drain Efficiency, } \eta = \frac{P_{rf,max}}{P_{DC}} = \frac{(v_{rf,max})^2 / 2R_L}{V_{DD} I_{DC}} = \frac{(V_{DD}^2) / 2R_L}{V_{DD} \cdot \frac{i_{p,max}}{\pi} \left[\sin \frac{\varphi_{cond}}{2} - \frac{\varphi_{cond}}{2} \cos \frac{\varphi_{cond}}{2} \right]} = \frac{[\varphi_{cond} - \sin \varphi_{cond}]}{2 \left[2 \sin \frac{\varphi_{cond}}{2} - \varphi_{cond} \cos \frac{\varphi_{cond}}{2} \right]}$$



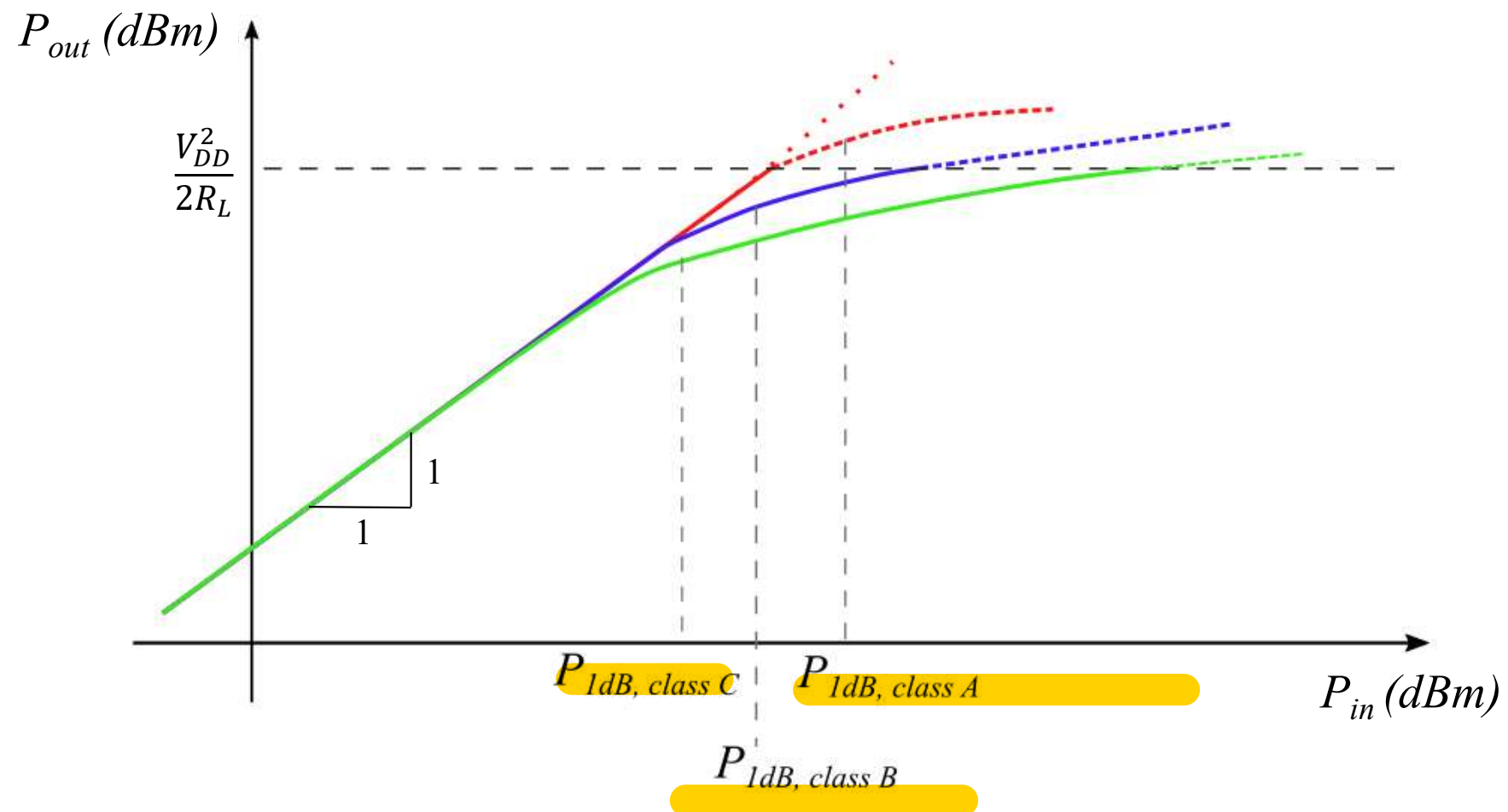
Drain voltage and current for ideal Class C amplifier

Amplifier Efficiency and Harmonics

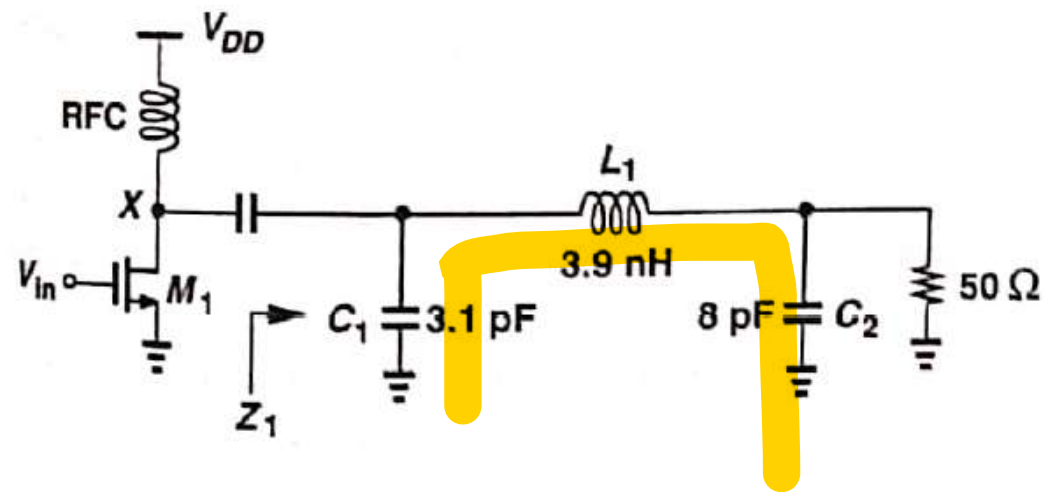


The output power decreases as the power efficiency increases

Linearity

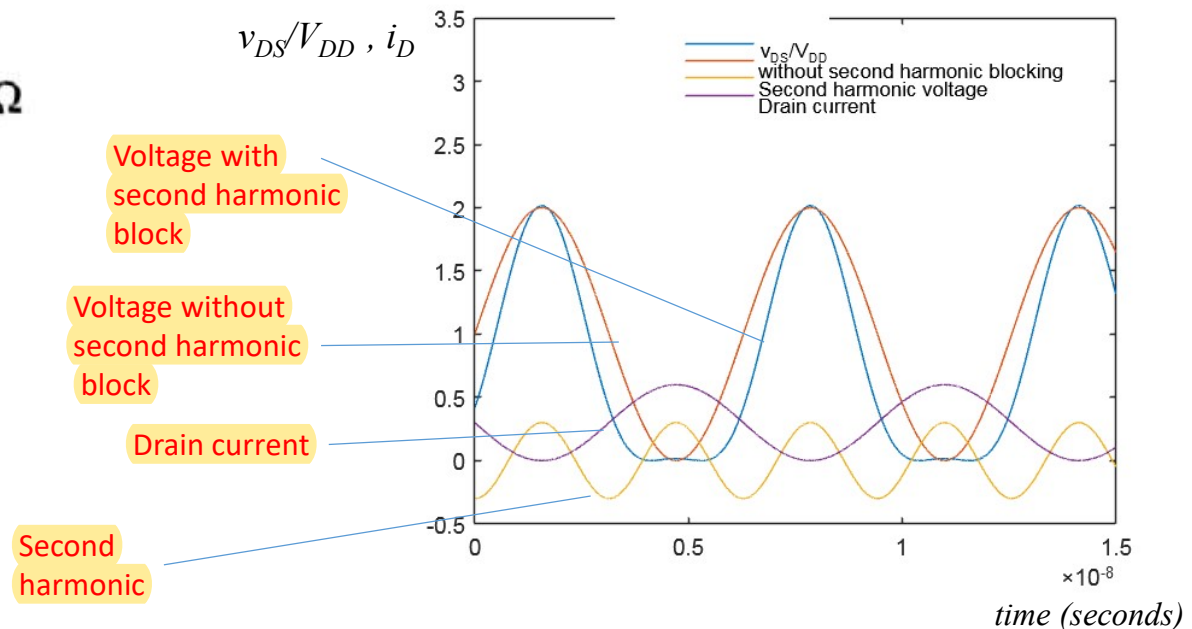
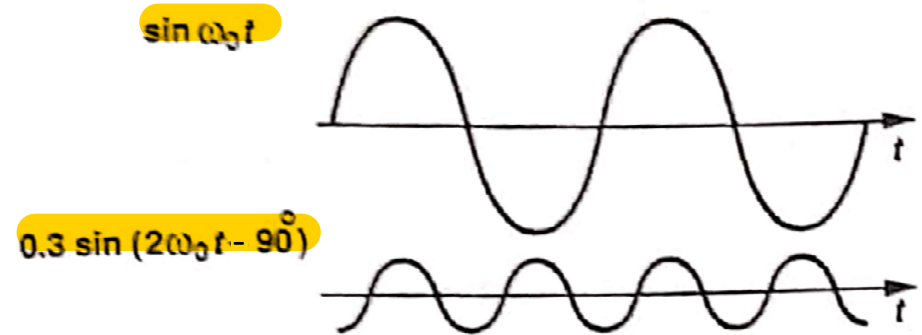


High Efficiency Class A PA



$$Z_1(850 \text{ MHz}) = 9 \text{ ohms}$$

$$Z_1(2 \times 850 \text{ MHz}) = 330 \text{ ohms}$$



Drain voltage and current for high efficiency Class A amplifier

Class E PA – a switching amplifier

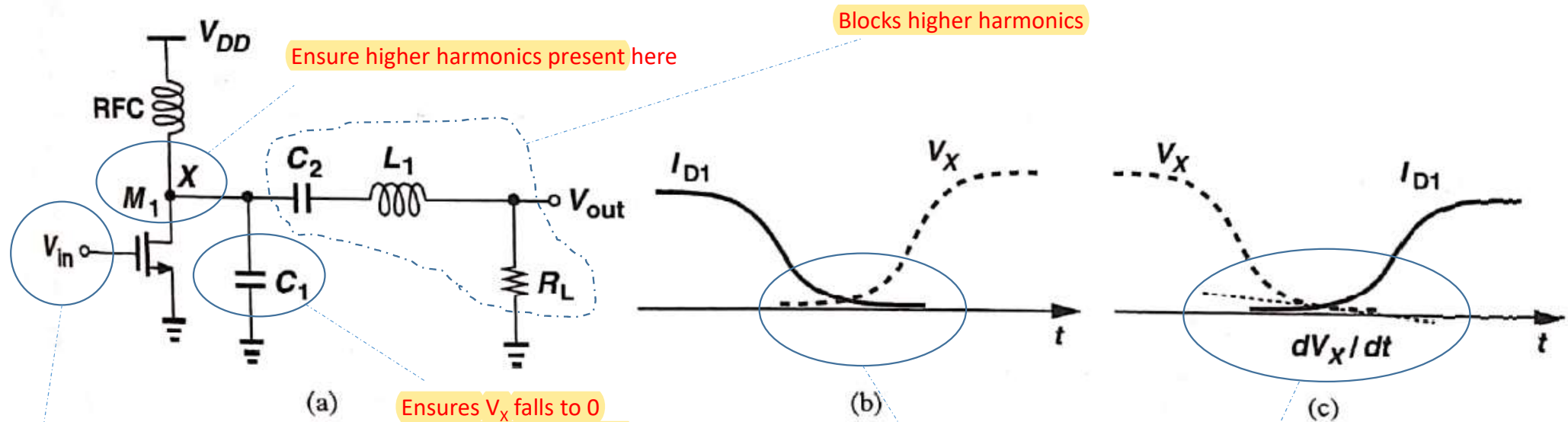


Figure 12.27 (a) Class E stage, (b) condition to ensure minimal overlap between drain current and voltage, (c) condition to ensure low sensitivity to timing errors.

Sharp switching, ideally turned on only when $V_X = 0$ to make ideal efficiency 100 %

I_D should be ideally 0 when $V_X \neq 0$
And slope of voltage vs time curve should be 0 ideally to minimize efficiency variation

Class E Design Equations

$$L_1 = \frac{QR_L}{\omega}, C_1 = \frac{1}{\omega R_L \left(\frac{\pi^2}{4} + 1 \right) \left(\frac{\pi}{2} \right)} \approx \frac{1}{\omega (R_L \cdot 4.447)}$$

$$C_2 \approx C_1 \left(\frac{5.447}{Q} \right) \left(1 + \frac{1.42}{Q - 2.08} \right), \text{ Q is obtained from the desired BW of the LC n/w}$$

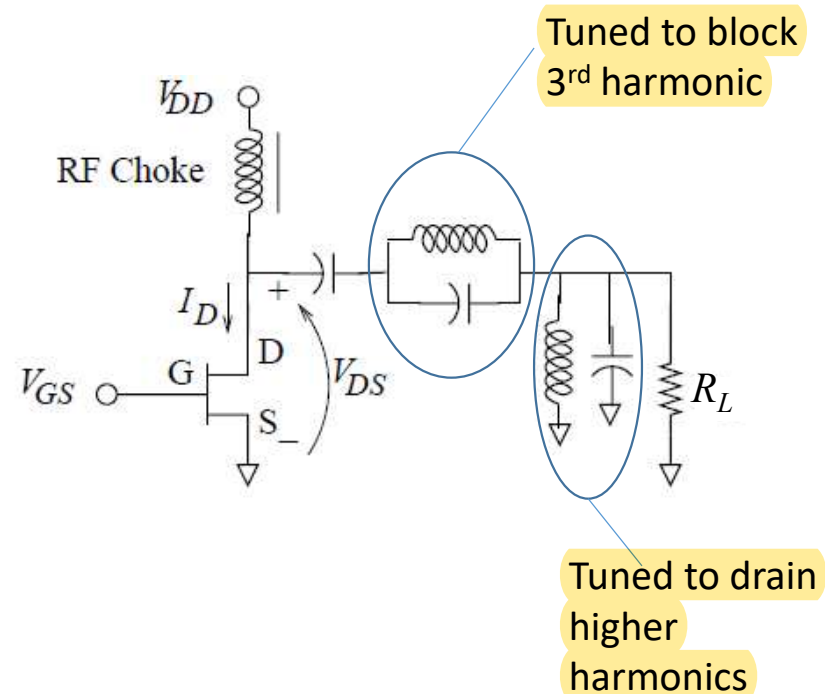
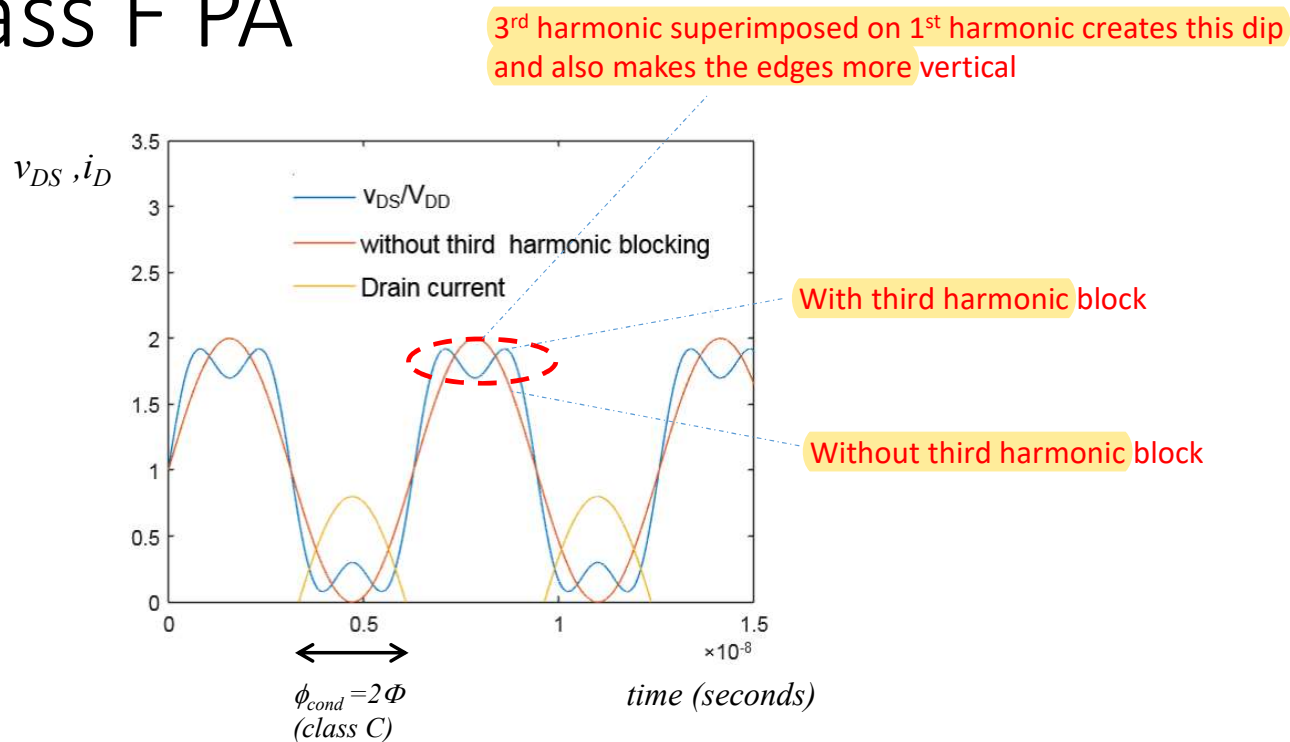
$$P_{\text{rf,max}} = \frac{2}{1 + \pi^2 / 4} \cdot \frac{V_{DD}^2}{R_L} \approx 0.577 \cdot \frac{V_{DD}^2}{R_L}$$

Not easy to find expression for drain current or drain voltage.

Class E shows **poor power o/p capability and** reduced efficiency due to switch turn off losses.

Class E-A new class of high-efficiency tuned single-ended switching power amplifiers, N.O. Sokal; A.D. Sokal, IEEE Journal of Solid-State Circuits Year: 1975 | Volume: 10, Issue: 3

Class F PA

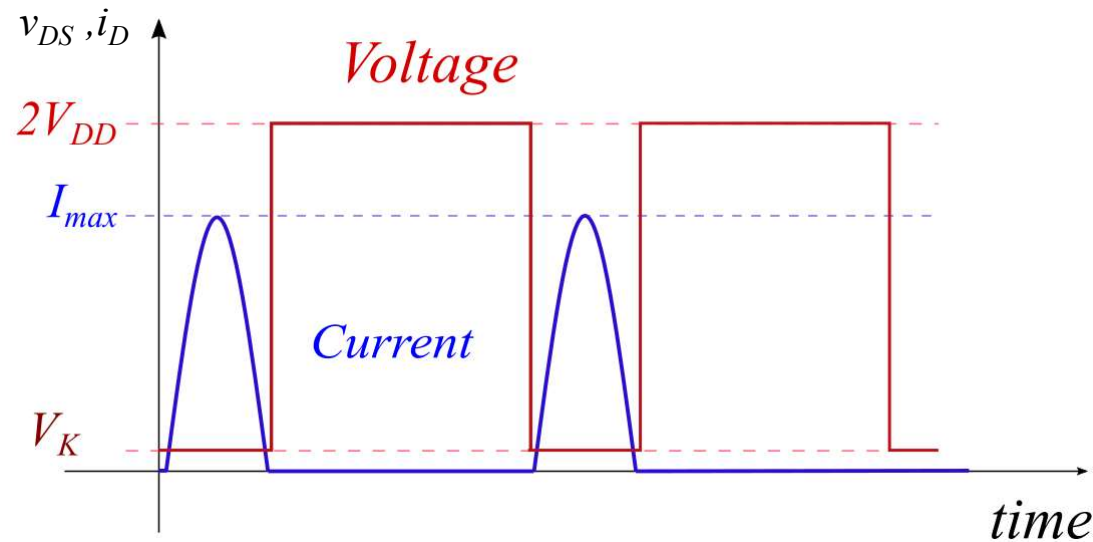


- Drain voltage and current for ideal Class F amplifier.

$$\text{peak to peak voltage of fundamental component of } v_{DS} = \frac{4}{\pi} \cdot 2V_{DD}$$

$$P_{rf, \max} = \left(\frac{4}{\pi} \cdot V_{DD} \right)^2 / 2R_L = 0.81 \frac{V_{DD}^2}{R_L}, \quad i_{fund} = \left(\frac{8}{\pi} \cdot V_{DD} \right) / R_L = 2.54 \frac{V_{DD}}{R_L}$$

Ideal Class F voltage and current



- Ideally the waveform approaches a rectangular wave when all odd harmonics are superimposed.
- Theoretical drain efficiency is 100%.

peak to peak voltage of fundamental component of $v_{DS} = \frac{4}{\pi} \cdot 2V_{DD}$

$$P_{rf,max} = \left(\frac{4}{\pi} \cdot V_{DD} \right)^2 / 2R_L = 0.81 \frac{V_{DD}^2}{R_L}, \quad i_{fund} = \left(\frac{8}{\pi} \cdot V_{DD} \right) / R_L = 2.54 \frac{V_{DD}}{R_L}$$

Inverse class F or F^{-1}

- Dual of class F, i.e. Voltage and current waveforms are interchanged

O/P power comparison between Class A and B PAs

Max o/p power for both class A and B is comparable

$$P_{RF,A} = \frac{V_{DD}^2}{2R} \quad P_{RF,B} = \frac{V_{DD}^2}{2R}$$

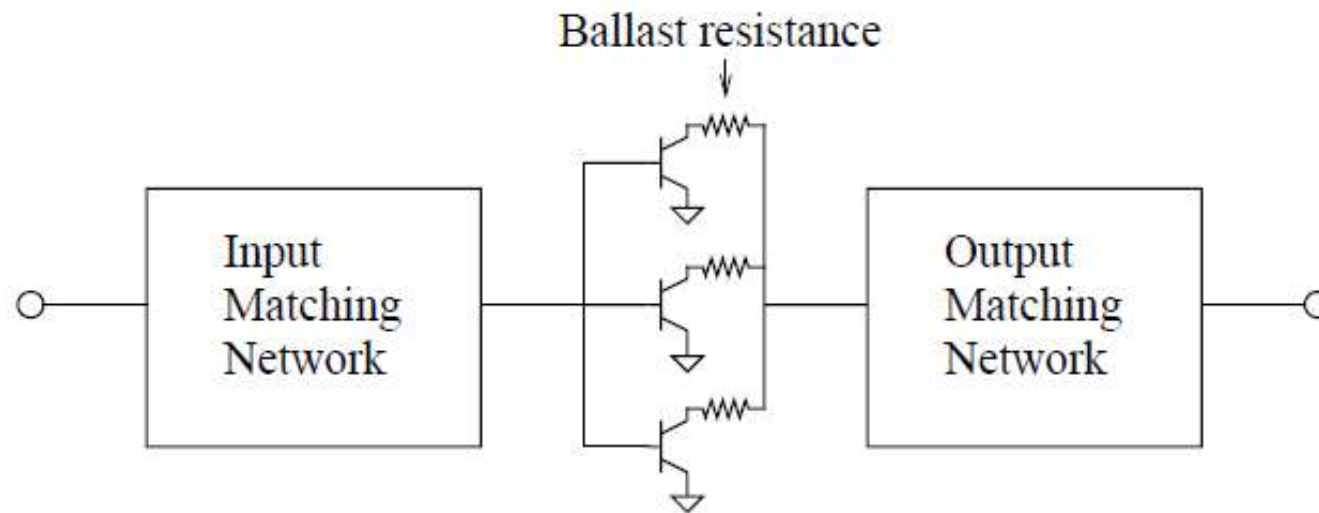
However for same v_{in} the power o/p of class B is lesser

$$P_{RF,class\ B} = \frac{1}{2} \times \left(\underbrace{i_{rf}/2}_{\text{amplitude of first harmonic}} \right)^2 \times R_L = \frac{i_{rf}^2 R_L}{8}$$

$$P_{RF,class\ A} = \frac{1}{2} \times (i_{pk})^2 \times R_L = \frac{i_{pk}^2 R_L}{2}$$

Assuming $i_{rf} = i_{pk} = g_m v_{in}$, for the same v_{in} , power o/p of a class B amplifier is 6 dB lesser than a class A amplifier.

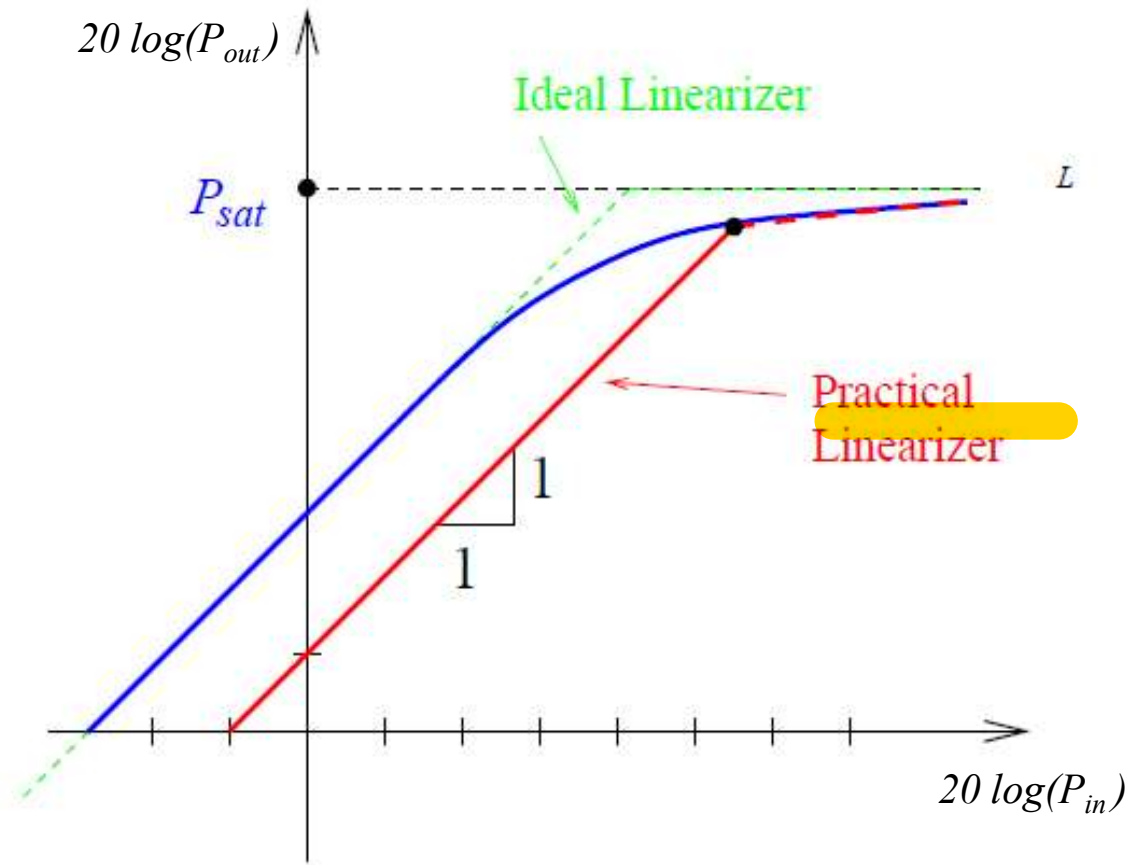
Power Combining



Issues

- Difficult to design: input impedance is very low or very high.
- Load sharing: ballast resistances are needed but reduce the output power.
- Distributed effects: constant delay & corporate tree impedance

Linearization

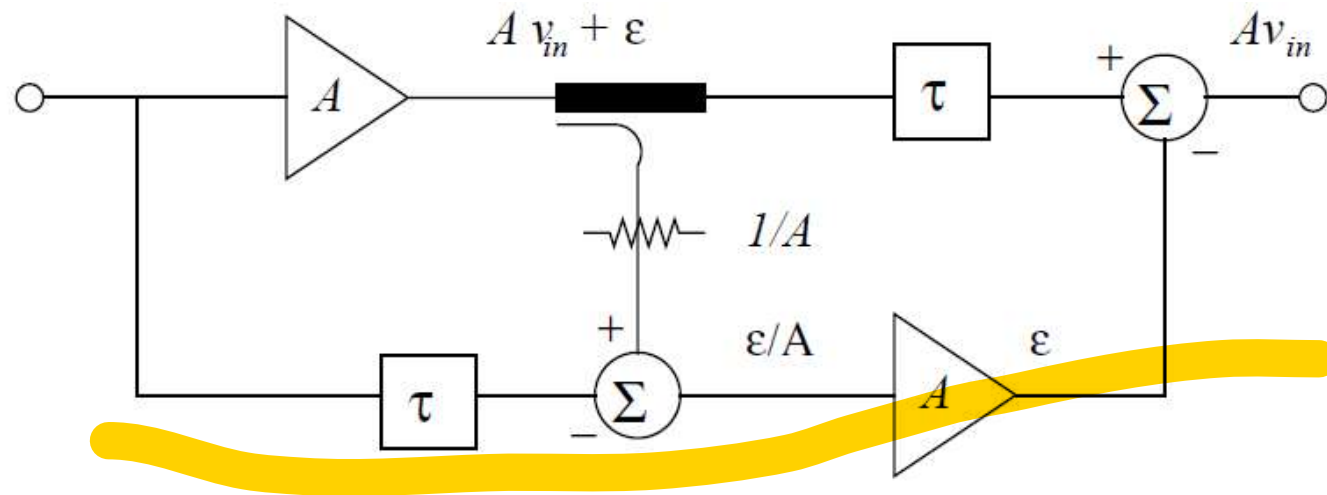


- Power saturation is the same
- Some degradation in gain typical
- Improved IMD3 and ACPR

Various Methods Potentially Applicable

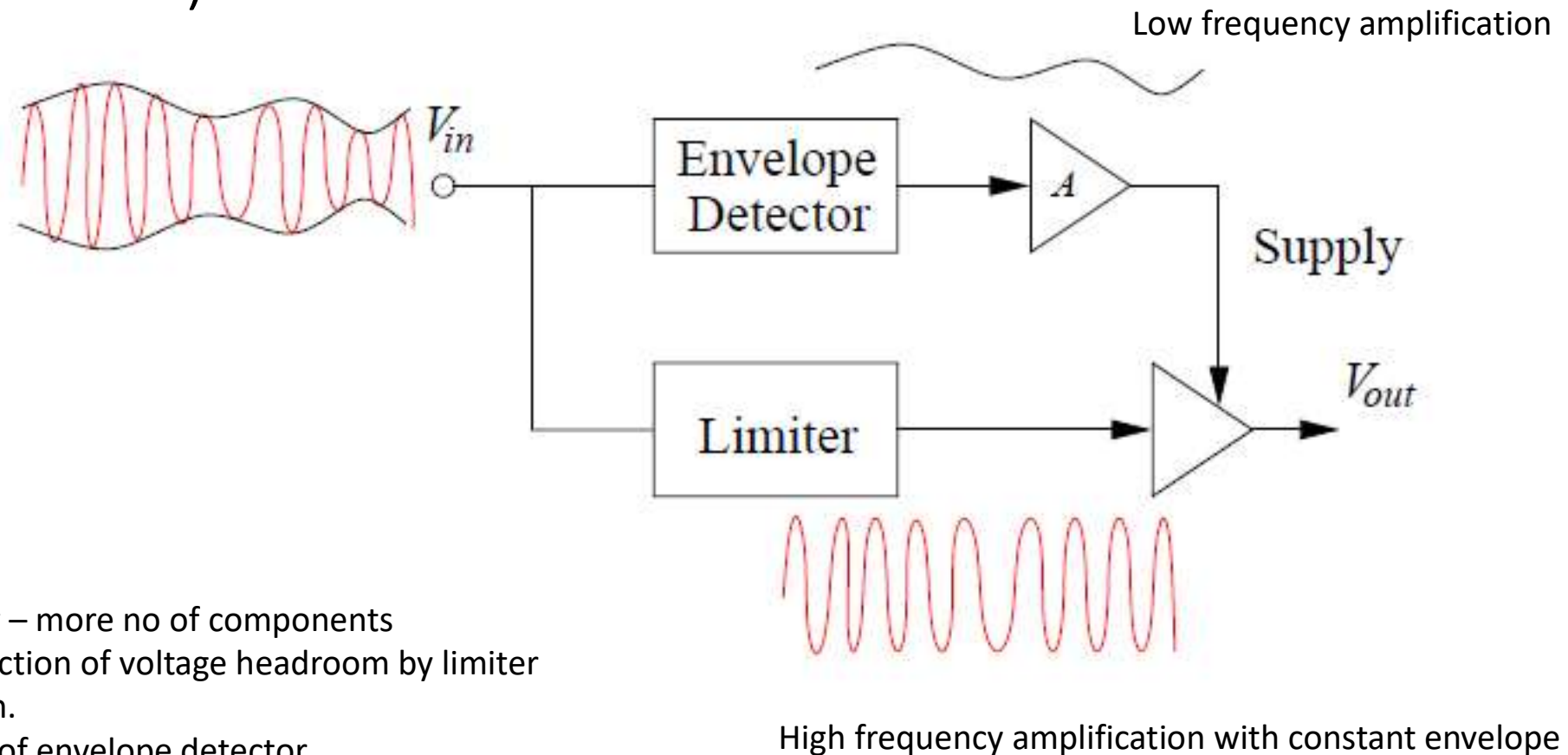
- Feedforward
- Predistortion
- Envelope Elimination and Restoration or Polar Modulation
- LINC (linear amplification with non-linear components): a non-constant envelope v_{in} is expressed in terms of constant envelope signals v_1 and v_2 such that: $v_{in} = v_1(t) + v_2(t)$
- Doherty

Feed Forward Linearization



Broadband but complex (2 loops) , expensive and inefficient (since 2 PAs used)

Envelope Elimination and Restoration (or Polar Modulation)



Issues

1. Efficiency – more no of components and reduction of voltage headroom by limiter
2. Mismatch.
3. Linearity of envelope detector.
4. Bandwidth of limiter

Predistortion Linearization

Consider an incoming signal

$$x = A \cos(\omega t + \varphi) = I \cos(\omega t) - Q \sin(\omega t)$$

$$\text{with, } I = A \cos \varphi \text{ and } Q = A \sin \varphi$$

The action of the predistorter is to modify the phase and amplitude of the input signal to compensate for the in-band AM-AM and AM-PM distortion introduced by the PA.

The output of the predistorter is then,

$$y = A B \cos(\omega t + \varphi + \psi) = \left[\underbrace{I \times B \cos \psi - Q \times B \sin \psi}_{I'} \cos(\omega t) + \left[\underbrace{-B \times I \sin \psi - B \times Q \cos \psi}_{Q'} \sin(\omega t) \right] \right]$$

where one can easily verify that I' and Q' are given by:

$$\begin{bmatrix} I' \\ Q' \end{bmatrix} = \begin{bmatrix} B \cos \psi & -B \sin \psi \\ -B \sin \psi & -B \cos \psi \end{bmatrix} \begin{bmatrix} I \\ Q \end{bmatrix} = \begin{bmatrix} \alpha & -\beta \\ -\beta & -\alpha \end{bmatrix} \begin{bmatrix} I \\ Q \end{bmatrix}$$

with $\alpha = B \cos \psi$ and $\beta = B \sin \psi$.

So, say we pre-distort I & Q as follows,

$$\begin{bmatrix} I'' \\ Q'' \end{bmatrix} = \begin{bmatrix} \alpha & -\beta \\ -\beta & -\alpha \end{bmatrix}^{-1} \begin{bmatrix} I \\ Q \end{bmatrix}, \text{ then } I' \text{ and } Q' \text{ become,}$$

$$\begin{bmatrix} I' \\ Q' \end{bmatrix} = \begin{bmatrix} \alpha & -\beta \\ -\beta & -\alpha \end{bmatrix} \begin{bmatrix} I'' \\ Q'' \end{bmatrix} = \begin{bmatrix} \alpha & -\beta \\ -\beta & -\alpha \end{bmatrix} \begin{bmatrix} \alpha & -\beta \\ -\beta & -\alpha \end{bmatrix}^{-1} \begin{bmatrix} I \\ Q \end{bmatrix} = \begin{bmatrix} I \\ Q \end{bmatrix}$$

α and β need to be estimated continuously

Digital Implementation of Predistortion

