

# cme241 - Assignment 3

Frederic Ladouceur

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## 1 Question 1

$$V^{\pi_D}(s) = Q^{\pi_D}(s, \pi_D(s)) \quad (1)$$

$$Q^{\pi_D}(s, a) = R(s, a) + \gamma \sum_{s' \in N} P(s, \pi_D(s), s') V^{\pi_D}(s') \quad (2)$$

$$V^{\pi_D}(s) = R(s, \pi_D(s)) + \gamma \sum_{s' \in N} P(s, \pi_D(s), s') V^{\pi_D}(s') \quad (3)$$

$$Q^{\pi_D}(s, a) = R(s, a) + \gamma \sum_{s' \in N} P(s, \pi_D(s), s') Q^{\pi_D}(s', \pi_D(s')) \quad (4)$$

The four equations above represents the 4 MDP Bellman equations for a deterministic policy. Equation 1 represents  $V^{\pi_D}$  in terms of  $Q^{\pi_D}$ , Equation 2 represents  $Q^{\pi_D}$  in terms of  $V^{\pi_D}$ , Equation 3 represents  $V^{\pi_D}$  in terms of  $V^{\pi_D}$ , and Equation 4 represents  $Q^{\pi_D}$  in terms of  $Q^{\pi_D}$ .

## 2 Question 2

The MDP State-Value Function Bellman Optimality Equation is:

$$V^*(s) = \max_{a \in A} \{R(s, a) + \gamma \sum_{s' \in N} P(s, a, s') V^*(s')\} \quad (5)$$

From the values given in the problem statement, the equation becomes:

$$V^*(s) = \max_{a \in A} \{(1-a)(1+2a) + 1/2(aV^*(s+1) + (1-a)V^*(s))\} \quad (6)$$

Since the optimal value function doesn't depend on the value of s, i.e.  $V^*(s) = V^*(s')$  for all  $s, s' \in S$ , we have:

$$V^*(s) = \max_{a \in A} \{(1-a)(1+2a) + 1/2(aV^*(s) + (1-a)V^*(s))\} \quad (7)$$

$$V^*(s) = 2 \max_{a \in A} \{(1-a)(1+2a)\} \quad (8)$$

$$V^*(s) = 9/4 \quad (9)$$

We also have:

$$\pi^*(s) = \operatorname{argmax}_{a \in A} \{(1-a)(1+2a)\} = 1/4 \quad (10)$$