Olalekan Ogunmolu

Education

- 2019 **PhD in Electrical Engineering**, *University of Texas at Dallas*, Richardson, TX, United States.
- 2012 Master of Science in Engineering in Control Systems, The University of Sheffield, UK.

Publications

Azar Sadeghnejad Barkousaraie, **Olalekan Ogunmolu**, Steve Jiang, and Dan Nguyen. A Fast Deep Learning Approach for Beam Orientation Selection Using Supervised Learning with Column Generation on IMRT Prostate Cancer Patients. Under review at *Medical Physics (An AAPM Journal)*, May 2019.

Olalekan Ogunmolu, Michael Folkerts, Dan Nguyen, Nicholas Gans, and Steve Jiang. Deep BOO: Automating Beam Orientation Selection in Intensity Modulated Radiation Therapy. *Algorithmic Foundations of Robotics XIII, International Workshop (WAFR)*, Mérida, Mexico. December 2018.

Olalekan Ogunmolu, Nicholas Gans, and Tyler Summers. Minimax Iterative Dynamic Game: Application to Nonlinear Robot Control Tasks. *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Madrid, Spain. October 2018. DOI: 10.1109/IROS.2018.8594037

Olalekan Ogunmolu, Adwait Kulkarn, Yonas Tadesse, Xuejun Gu, Steve Jiang, and Nick Gans. Soft-NeuroAdapt: A 3-DOF Neuro-Adaptive Pose Correction System For Frameless and Maskless Cancer Radiotherapy. *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Vancouver, BC, Canada. September 2017. DOI: 10.1109/IROS.2017.8206211.

Olalekan Ogunmolu, Nicholas Gans, and Tyler Summers. Robust Zero-Sum Deep Reinforcement Learning. *arxiv PrePrints, arxiv ID:1710.00491*, Oct 2017.

Olalekan Ogunmolu, Xuejun Gu, Steve Jiang, and Nicholas Gans. Nonlinear Systems Identification Using Deep Dynamic Neural Networks. *arxiv PrePrints, arxiv ID:1610.01439*, Oct 2016.

Olalekan Ogunmolu, Xuejun Gu, Steve Jiang, and Nick Gans. Vision-based control of a soft-robot for Maskless Cancer Radiotherapy. *IEEE Conference on Automation Science and Engineering (CASE)*, Fort-Worth, Texas, August 2016. DOI: 10.1109/CoASE.2016.7743378.

Olalekan Ogunmolu, Xuejun Gu, Steve Jiang, and Nick Gans. A Real-Time Soft-Robotic Patient Positioning System for Maskless Head-and-Neck Cancer Radiotherapy. *IEEE Conference on Automation Science and Engineering (CASE)*, Gothenburg, Sweden, August 2015. DOI: 10.1109/CoASE.2015.7294318.

Azar Sadeghnejad Barkousaraie, **Olalekan Ogunmolu**, Steve Jiang, and Dan Nguyen. Using supervised learning and guided Monte Carlo tree search for beam orientation optimization in radiation therapy. Under review at *International Conference on Medical Image Computing and Computer Assisted Intervention*, XXII (MICCAI), Shenzhen, China. October 2019.

Azar Sadeghnejad Barkousaraie, **Olalekan Ogunmolu**, Steve Jiang, and Dan Nguyen. Deep Learning Neural Network for Beam Orientation Optimization. To appear in *International Conference on the use of Computers in Radiation Therapy XVI (ICCR)*, Montreal, CA. June 2019.

Olalekan Ogunmolu, Dan Nguyen, Xun Jia, Weiguo Lu, Nick Gans, and Steve Jiang. Automating Beam Orientation Optimization for IMRT Treatment Planning: A Deep Reinforcement Learning Approach. 60th Annual Meeting of the American Association of Physicists in Medicine, Nashville, TN (AAPM). July 2018.

Yara Almubarak, Joshi Aniket, **Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, Nicholas Gans, and Yonas Tadesse, Design and Development of Soft Robots for Head and Neck Cancer Radiotherapy. *SPIE: Smart Structures + Nondestructive Evaluation*, Denver, CO, U.S.A. March 2018.

Invited Talks

Stanford Robotic Radiotherapy: Automating Position Correction in Intensity-Modulated Radiation University Therapy. Department of Energy Resources Engineering, Stanford University, Stanford, CA, USA. November 2018.

Open Soft-Robotic Position Correction Mechanisms in Intensity-Modulated Radiation Therapy.

Robotics Open Robotics Foundation, Mountain View, CA, USA. January 2019.

UChicago Robotic Radiotherapy: Automating Position Correction in Intensity-Modulated Radiation Therapy. Department of Radiation and Cellular Oncology, The University of Chicago, Chicago, IL, USA. November 2018.

ATR CNS Minimax Iterative Dynamic Game. Department of Brain Robot Interface, Computational Labs Neuroscience Labs, ATR, Osaka, Japan. August 2018.

UTSW, A 3-DOF Neuro-Adaptive Patient Pose Correcting System For Frameless and Maskless Cancer Dallas, TX Radiotherapy, *Physics Research Seminar Series, Radiation Oncology Department, UT Southwestern Medical Center,* Dallas, TX, USA. March 2017.

IEEE Towards automated accurate patient positioning in maskless cancer radiotherapy. *IEEE* Arlington, TX. *Computational Intelligence Society*, UT Arlington, TX, USA. December 2015.

Awards and honors

Tivaras ana nonors		
• President's Teaching Excellence Award for Teaching	g Assistants N	Iominated Feb. 2017
o IEEE RAS Travel Award		August 2016
 Ericsson Graduate Fellowship 		2015 - 2016
 Jonsson Scholarship 		2014 - 2015
 Achievement Award, University of Florida, (Declin Mech & Aerospace Engineering Dept. 	ed)	Fall 2014
o PTDF Overseas Scholarship Award [Nigeria]	\sim 1.7% acceptance	ce, 2011 - 2012
o Federal Government (of Nigeria) Scholarship,	~3.6% acceptan	ce, 2002
 Ondo State (Nigeria) Scholarship 	\sim 10% acceptanc	e, 2004