

# Olalekan Ogunmolu

Robotics | Control Systems | ML

*Rerum Cognoscere Causas: To know the causes of things.*

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☎ omitted intentionally

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## Education

- 2014–Present **PhD in Electrical and Computer Engineering**, *University of Texas at Dallas*, Richardson, United States.  
Advisers: Nick Gans (UTD) and Steve Jiang (UT Southwestern Medical Center)  
• Design and prototype of a medical soft robot for automated patient positioning in Intensity Modulated Radiation Therapy (IMRT)  
• Beam Angle Optimization in IMRT.
- 2011–2012 **Master of Science in Engineering in Control Systems**, *The University of Sheffield*, Sheffield, United Kingdom.  
Advisor: Tony J. Dodd. Thesis: “Autonomous Navigation of a Rotorcraft Unmanned Aerial Vehicle using Machine Vision.”
- 2000–2005 **Bachelor Of Science in Physics & Electronics**, *Adekunle Ajasin University*, Akungba, Nigeria.  
[Senior thesis](#) advised by Ademola Amusa (MS, Columbia University, PhD UIUC). | Dissertation Grade: 85%  $\equiv$  A+ | Graduated Magna Cum Laude.

## Publications

### Journals

**Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, Nicholas Gans. [Nonlinear Systems Identification Using Deep Dynamic Neural Networks](#). Under review at *Physical Review Applied*, American Physical Society, Submitted September 2018.

**Olalekan Ogunmolu**. [Deep BOO: Automating Beam Orientation Selection in Intensity Modulated Radiation Therapy](#). To appear in *Springer Proceedings in Advanced Robotics* (SPAR), 2018.

### Conferences

**Olalekan Ogunmolu**. [Deep BOO: Automating Beam Orientation Selection in Intensity Modulated Radiation Therapy](#). To appear at *The 13th International Workshop on the Algorithmic Foundations of Robotics* (WAFR), Mérida, Mexico. December 2018.

**Olalekan Ogunmolu**, Nicholas Gans, Tyler Summers. [Minimax Iterative Dynamic Game: Application to Nonlinear Robot Control Tasks](#). To appear at: *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Madrid, Spain. October 2018.

**Olalekan Ogunmolu**, Dan Nguyen, Xun Jia, Weiguo Lu, Nick Gans, and Steve Jiang. [Automating Beam Orientation Optimization for IMRT Treatment Planning: A Deep Reinforcement Learning Approach](#). Selected for Oral Presentation at the John R. Cameron Young Investigators Symposium – 60th Annual Meeting of the American Association of Physicists in Medicine, Nashville, TN (AAPM). July 2018.

Yara Almubarak, Joshi Aniket, **Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, Nicholas Gans, and Yonas Tadesse, [Design and Development of Soft Robots for Head and Neck Cancer Radiotherapy](#). *SPIE: Smart Structures + Nondestructive Evaluation*, Denver, CO, U.S.A. March 2018.

**Olalekan Ogunmolu**, Adwait Kulkarni, Yonas Tadesse, Xuejun Gu, Steve Jiang, and Nick Gans. [Soft-NeuroAdapt: A 3-DOF Neuro-Adaptive Pose Correction System For Frameless and Maskless Cancer Radiotherapy](#). *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Vancouver, BC, Canada. September 2017. DOI: 10.1109/IROS.2017.8206211.

**Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, and Nick Gans. [Vision-based control of a soft-robot for Maskless Cancer Radiotherapy](#). *IEEE Conference on Automation Science and Engineering (CASE)*, Fort-Worth, Texas, August 2016. DOI: 10.1109/CoASE.2016.7743378.

**Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, and Nick Gans. [A Real-Time Soft-Robotic Patient Positioning System for Maskless Head-and-Neck Cancer Radiotherapy](#). *IEEE Conference on Automation Science and Engineering (CASE)*, Gothenburg, Sweden, August 2015. DOI: 10.1109/CoASE.2015.7294318.

**Olalekan Ogunmolu**, [Autonomous Navigation of a Rotor-craft unmanned aerial vehicle using machine vision](#). .

MS Thesis, August. 2011. Advisor: Tony J. Dodd, University of Sheffield, England.

**Olalekan Ogunmolu**, [Single Fractional Parentage Coefficients in the sd-Shell Nuclei](#) .

BS Thesis, Nov. 2004. Advisor: Ademola Amusa, Adekunle Ajasin University, Nigeria.

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## Abstracts:

**Olalekan Ogunmolu**, Nicholas Gans, Tyler Summers. [Minimax Iterative Dynamic Game: Application to Nonlinear Robot Control Tasks](#). *IEEE International Conference on Robotics and Automation, Machine Learning for Planning and Control Workshop Extended Abstract (ICRA 2018)*, Madrid, Spain. October 2018.

**Olalekan Ogunmolu**, Nicholas Gans, Tyler Summers [Minimax Iterative Dynamic Game: Application to Nonlinear Robot Control Tasks](#)., *IEEE International Conference on Robotics and Automation, Late Breaking Result Abstract* Brisbane, Australia, May 2018.

Yara Almubarak, Joshi Aniket, **Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, Nicholas Gans, and Yonas Tadesse, [Design and Development of Soft Robots for Head and Neck Cancer Radiotherapy](#). *SPIE: Smart Structures + Nondestructive Evaluation*, Denver, CO, U.S.A. March 2018.

Tyler Summers, **Olalekan Ogunmolu**, Nicholas Gans. [Robustness Margins and Robust Guided Policy Search for Deep Reinforcement Learning](#)". *IROS 2017 Abstract Only Track*, Vancouver, BC, Canada. September 2017.

**Olalekan Ogunmolu**, Nick Gans, Steve Jiang, Xuejun Gu. [An Image-Guided Soft Robotic Patient Positioning System for Maskless Head-And-Neck Cancer Radiotherapy: A Proof-of-Concept Study](#). *American Association of Physicists in Medicine (AAPM) Annual Meeting*, Anaheim, CA, USA. July 2015.

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## Tech Reports:

**Olalekan Ogunmolu**, Nicholas Gans, Tyler Summers. [Robust Zero-Sum Deep Reinforcement Learning](#). *arxiv PrePrints*, *arxiv ID:1710.00491*, Oct 2017.

**Olalekan Ogunmolu**. [Review of "Continuous Finite-Time Stabilization of Translational and Rotational Double Integrators"](#). *arxiv PrePrints*, *arxiv ID: 1612.01607v2*, May 2015.

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## Research Interests

Optimal/Adaptive Control • System Identification • Dynamic Programming • Game Theory • Deep/Reinforcement Learning

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## Experience

### Research:

Summer '18 **Research Intern**, [Preferred Networks](#), Otemachi, Chiyoda-ku, Tokyo, Japan.

*Research Intern within the Robotics Team. Worked on stable learning of complex robot motion-planning/manipulation tasks.*

Implemented Khansari-Zadeh's CLF-DM on the Tokyo Robotics 7-DoF Arm. Proposed a DP approach for better complex robot trajectory imitation.

- Fall '17 - **Visiting Research Student**, Medical Artificial Intelligence and Automation Laboratory, Division of Medical Physics and Engineering, Radiation Oncology Department, UT Southwestern Medical Center.  
 Present *Research Assistant for Dr. Steve Jiang, Barbara Crittenden Professor of Cancer Research, UTSW Department of Radiation Oncology.*  
 Developed a multidisciplinary approach (spanning Deep learning, optimal control, dynamic programming, and game theory) in order to solve the classic beam orientation optimization (BOO) problem.
- Summer - **Research Assistant**, Dr. Tyler Summers, Mechanical Engineering, UT Dallas.  
 Fall '17 *Dynamic Programming, Decision Theoretic Control, Machine/Reinforcement Learning.*  
 Developed a conservative controller for mitigating the lack of robustness in multi-stage decision policies.
- Fall '14 - **Research Assistant**, Dr. Nick Gans, Electrical Engineering, University of Texas at Dallas.  
 Now *Control Systems, Systems Identification, State Estimation and Computer Vision.*  
 Conceived the prototypical testbed, procured hardware, integrated components to simulate soft robot compensating systems for patients in intensity modulated radiotherapy.
- Summer '16 **Hardware Integration Intern**, Amazon Robotics LLC.  
*SLAM, Software and Hardware Integration.*  
 Helped integrate the hardware and software for the P3-DX robot used as a recreational robot in the Amazon Robotics office.
- Spring '16 **Hardware Integration Intern**, Advanced Robotics Lab, Amazon Robotics LLC.  
*Computer Vision, Hardware Integration.*  
 Wrote the codebase for the line scanners used in tracking objects in amazon warehouse assembly lines.
- Teaching:**
- Fall '14 - '16 **Teaching Assistant, Introduction to Robotics**, University of Texas at Dallas.  
 Guided students during laboratories in programming the Robai Cyton 300R2 Robot and graded homeworks.
- Spring '15 **Teaching Assistant, Linear Systems (M.S. Class)**, University of Texas at Dallas.  
 Responsible for helping Masters students with linear control theory applications; graded homeworks and midterms.
- Spring '14 **Instructor, Analysis and Design of Digital Systems**, Adekunle Ajasin University.  
 Developed course modules, sole instructor for sophomore students, graded homeworks, designed and graded exams.
- Summer '14 **Instructor, Digital Logic Design**, Adekunle Ajasin University.  
 Co-developed course modules, joint-instructor for junior students, graded homeworks, designed and graded exams.
- Miscellaneous:**
- 2009–2011 **Warehouse Manager, Apapa Plant**, Coca-Cola Hellenic Bottling Company Plc, Lagos.
- 2007–2008 **Banking Assistant**, First Bank of Nigeria Plc, Lagos.
- 2005–2007 **System Engineer**, DMT Technologies Limited, KD, Nigeria.

## Invited Talks

### Presentations:

- ATR CNS **Minimax Iterative Dynamic Game.**  
 Labs Department of Brain Robot Interface, Computational Neuroscience Labs, ATR, Osaka, Japan. August 2018.
- Preferred **Neural Networks and Adaptive Control.**  
 Networks Preferred Networks Tech. Talk, Chiyoda-ku, Tokyo. Japan. August 2018.
- Google **SoftNeuroAdapt: A 3-DoF Neuro-Adaptive Healthcare System.**  
 Work presented by Nick Gans, Google Robotics, Mountain View, CA. USA. September 2017.
- EFSC'17, **Soft Robotic Modules as Position Correcting Mechanisms in Cancer RT.**  
 Vancouver **3rd Entrepreneurship Forum & Start-up Competition, EFSC'17**, Vancouver, BC, Canada. September 2017.

UTSW, Dallas, TX [A 3-DOF Neuro-Adaptive Patient Pose Correcting System For Frameless and Maskless Cancer Radiotherapy](#),  
*Physics Research Seminar Series, Radiation Oncology Department, UT Southwestern Medical Center, Dallas, TX, USA. March 2017.*

IEEE Arlington, TX [Towards automated accurate patient positioning in maskless cancer radiotherapy](#).  
*IEEE Computational Intelligence Society, UT Arlington, TX, USA. December 2015.*

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## Poster Presentations:

ICRA '18 **Minimax Iterative Dynamic Game: Application to Nonlinear Robot Control Tasks.**,  
*IEEE International Conference on Robotics and Automation* Brisbane, Australia, May 2018.

NIPS '17 **An iterative dynamic game for robust deep reinforcement learning**,  
*Neural Information Processing Systems* Long Beach, CA, December 2017.

IROS '17 **Robustness Margins and Robust Guided Policy Search for Deep Reinforcement Learning**,  
*International Conference on Intelligent Robots and Systems* Vancouver, BC, Canada. September 2017.

Texas Systems Day **A 3-DOF Neuro-Adaptive Pose Correction System For Frameless and Maskless Cancer Radiotherapy**,  
*Texas Systems Day, Texas A & M University, College Station, TX, USA. March 2017.*

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## Awards and honors

- IEEE RAS/IROS Travel Award August 2018
- Finalist at the [3rd Entrepreneurship Forum and Startup Competition](#) August 2017  
Sponsored by IEEE Robotics and Automation Society, KUKA AG, and Univ. Hamburg
- [NSF Doctoral Consortium Award](#) August 2017
- **Mary and Richard Templeton Graduate Fellowship** August 2017
- **ROSCon Scholarship** (Open Software for Robotics Foundation) July 2017
- **President's Teaching Excellence Award** for Teaching Assistants Nom. Feb. 2017
- **Golden Key International Honour Society** Inducted Dec. 2016
- IEEE RAS/ISAM Travel Award August 2016
- **Ericsson Graduate Fellowship** 2015 - 2016
- **Jonsson Scholarship** 2014 - 2015
- **Achievement Award, University of Florida** (*Declined*) Fall 2014
- **PTDF Overseas Scholarship Award, £25,500+ for one year.** (~1.7% acceptance) 2011
- **Federal Government (of Nigeria) Scholarship** (~3.6% acceptance) 2002
- **Ondo State (Nigeria) Scholarship** (~10% acceptance) 2004

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## Relevant Coursework

Convex Optimization  
Nonlinear systems  
Optimization theory and practice  
Signal Processing and Estimation  
Intelligent Systems  
Robotics and Multisensor Systems

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## Select services and leadership

[Journals/conferences peer reviewing activities](#)

2018 **Reviewer**, *Institute of Physics: Measurement Science and Technology (Journal)*.

2018 **Reviewer**, *IEEE International Conference on Intelligent Robots and Systems (IROS) 2018*.

2018 **Reviewer**, *Neural Computing and Applications (Journal)*, Neuro-Adaptive Control.

- 2017 **Reviewer**, *IEEE International Conference on Robotics and Automation (ICRA) 2018*.
- 2017 **Reviewer**, *American Control Conference (ACC)*, Reinforcement Learning Track.
- 2017 **Reviewer**, *International Federation of Automatic Control World Congress (IFAC)*, Switched Systems Track.
- 2017 **Open Reviewer**, *35th International Conference on Machine Learning (ICML)*, [OptNet: Differentiable Optimization as a Layer in Neural Networks](#).

### Miscellaneous

- 2017 **Invited Contributor**, *IEEE/RSJ International Conference on Robots and Intelligent Systems (IROS)*, Abstract Only Track, Vancouver, BC, Canada.
- 2017 – Now **Member**, **IEEE Robotics and Automation Society**.
- 2016–Now **Member**, *IEEE Boston*, Greater Boston, USA.
- 2015 – 2016 **Science instructor**, *IEEE Dallas Shoulder of Giants Workshops*, Dallas, TX.  
Participant at IEEE Dallas Young Professionals community outreaches in promoting STEM education and awareness in the Dallas/Fort-Worth Metroplex.
- 2015 **Summer Science Program**, *University of Texas at Dallas*, Richardson, TX.  
Trained high-school kids in basic robots control and programming with the Berkeley Snap! kit and arduino.
- 2012 **Workshop participant**, *ILA Berlin Airshow*, Berlin, Germany.  
Selected by Cassidian (an EADS company) for the *Aerospace Systems Engineering* workshop.
- 2012 **Workshop participant**, *Farnborough International Airshow*, NE Hampshire, England.  
Selected by Airbus (an EADS company) among participants at the *UAV and Fighter Aircraft* workshop.

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## Mentoring

### Undergraduate mentoring:

- Summer 2017 Rachael Thompson. Plano High School Student. Currently an undergrad at MIT's CSAIL. Class of 2017.
- 2016 - Now Alex Tomkovich. Computer Engineering Junior.
- Spring 2015 Grant Carr. Computer Engineering Junior.

### Masters mentoring:

- 2016 – 2017 Adwait Kulkarn. Mechanical Engineering Masters student (Currently at Drov Technologies, MN).
- 2015 Ajith Venkateswaran. Computer Engineering Masters student (Currently Senior Robotics Software Engineer, Samsung Research, America).

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## Computing

**Programming** C++, Python, Lua, MATLAB, LabVIEW.

**Libraries** Point Cloud Library, OpenCV, Torch7, Eigen, Docker, PyTorch, OpenAI Gym, MuJoCo, Numpy, SciPy, Scikit-Learn, C++11/14 standards.

**OS** Ubuntu, Debian, Windows.

**OSRF** ROS hydro, indigo, jade, kinetic, and melodic distros.

**Web** HTML, Markdown, socket.io, node.js, and express.js.

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## Select OpenSource Projects

- Lyapunov-Learner** Python Implementation of "Learning Control Lyapunov Functions for Dynamical Systems". (Available at <https://github.com/lakehanne/LyapunovLearner>)
- Awesome-NeuroControl** A curated list of neural applications in control theory and practice. (Available at <https://github.com/lakehanne/awesome-neurocontrol>)
- PCL** Fix for segfault in our-cvfh algorithm in the point-cloud library. (Available at [PR 1827](#))

- GPS** Catkinized version of Levine et. al's guided policy search algorithm in ROS Indigo (Available at <https://github.com/lakehanne/gps>). Dockerized version available at [gps-docker](#).
- Keyence** Minimal source code for retrieving profile map from the keyence LJV-7000 series line scanners. (Available at <https://github.com/lakehanne/keyence>)
- RBN** Recurrent Batch Normalization of Neural Networks in Torch7. (Available at <https://github.com/element-research/rnn>)
- DICE** Sørensen-Dice coefficients in Torch7. (Available at <https://github.com/lakehanne/nn>).
- FARNNs** Training of multilayer networks, simple recurrent neural networks, long short-term memory cells (with peep-hole connections), fast LSTMS, and recurrent batch normalized FastLSTMs to model the relationship between Borel measurable sets. (Available at <https://github.com/lakehanne/FARNN>)

## Languages

English	Reads, writes, and speaks fluently	<i>Lived in Nigeria, United Kingdom and United States.</i>
Japanese	Basic proficiency	<i>Lived in Japan for 3 months.</i>
Yoruba	Reads, writes, and speaks fluently.	<i>Native Nigerian Language. Spoken at home.</i>
German	Basic proficiency	

Last updated: September 05, 2018