

# Olalekan Ogunmolu

Robotics | Control Systems | AI

*Rerum Cognoscere Causas: To know the causes of things.*

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☎ omitted intentionally

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## Education

- 2014–Present **PhD in Electrical and Computer Engineering**, *University of Texas at Dallas*, Richardson, United States.  
Advisers: Nick Gans (UTD) and Steve Jiang (*UT Southwestern Medical Center*) | Design and prototype of a medical soft robot for automated patient positioning in Intensity Modulated Radiation Therapy (IMRT) | Beam Angle Optimization in IMRT.
- 2011–2012 **Master of Science in Engineering in Control Systems**, *The University of Sheffield*, Sheffield, United Kingdom.  
Advisor: Tony J. Dodd. Thesis: “[Autonomous Navigation of a Rotorcraft Unmanned Aerial Vehicle using Machine Vision](#).”
- 2000–2005 **Bachelor Of Science in Physics & Electronics**, *Adekunle Ajasin University*, Akungba, Nigeria.  
[Senior thesis](#) advised by Ademola Amusa (MS, *Columbia University*, PhD UIUC). | Dissertation Grade: 85%  $\equiv$  A+ | Graduated Magna Cum Laude.

## Research Interests

Optimal/Adaptive Control • System Identification • Dynamic Programming • Deep Learning • Reinforcement Learning

## Publications

Peer-Reviewed:

**Olalekan Ogunmolu**. [Deep BOO: Automating Beam Orientation Selection in Intensity Modulated Radiation Therapy. Part I: Methodologies](#). Under review at: *The 13th International Workshop on the Algorithmic Foundations of Robotics (WAFR)*, Mérida, Mexico. December 2018.

**Olalekan Ogunmolu**. [Deep BOO: Automating Beam Orientation Selection in Intensity Modulated Radiation Therapy. Part II: Initial Results](#). Under review at: *The 13th International Workshop on the Algorithmic Foundations of Robotics (WAFR)*, Mérida, Mexico. December 2018.

**Olalekan Ogunmolu**, Nicholas Gans, Tyler Summers. [Minimax Iterative Dynamic Game: Application to Nonlinear Robot Control Tasks](#). To appear in: *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Madrid, Spain. October 2018.

**Olalekan Ogunmolu**, Dan Nguyen, Xun Jia, Weiguo Lu, Nick Gans, and Steve Jiang. [Automating Beam Orientation Optimization for IMRT Treatment Planning: A Deep Reinforcement Learning Approach](#). To appear at *60th Annual Meeting of the American Association of Physicists in Medicine*, Nashville, TN (AAPM). June 2018.

Yara Almubarak, Joshi Aniket, **Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, Nicholas Gans, and Yonas Tadesse, [Design and Development of Soft Robots for Head and Neck Cancer Radiotherapy](#). *SPIE: Smart Structures + Nondestructive Evaluation*, Denver, CO, U.S.A. March 2018.

**Olalekan Ogunmolu**, Adwait Kulkarni, Yonas Tadesse, Xuejun Gu, Steve Jiang, and Nick Gans. [Soft-NeuroAdapt: A 3-DOF Neuro-Adaptive Pose Correction System For Frameless and Maskless Cancer Radiotherapy](#). *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Vancouver, BC, Canada. September 2017.

**Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, and Nick Gans. [Vision-based control of a soft-robot for Maskless Cancer Radiotherapy](#). *IEEE Conference on Automation Science and Engineering (CASE)*, Fort-Worth, Texas, August 2016. DOI: 10.1109/CoASE.2016.7743378

**Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, and Nick Gans. [A Real-Time Soft-Robotic Patient Positioning System for Maskless Head-and-Neck Cancer Radiotherapy](#). *IEEE Conference on Automation Science and Engineering (CASE)*, Gothenburg, Sweden, August 2015. DOI: 10.1109/CoASE.2015.7294318

**Olalekan Ogunmolu**, [Autonomous Navigation of a Rotor-craft unmanned aerial vehicle using machine vision](#). .

MS Thesis, August. 2011. Advisor: Tony J. Dodd, University of Sheffield, England.

**Olalekan Ogunmolu**, [Single Fractional Parentage Coefficients in the sd-Shell Nuclei](#) .

BS Thesis, Nov. 2004. Advisor: Ademola Amusa, Adekunle Ajasin University, Nigeria.

### Journals Under Preprparation:

**Olalekan Ogunmolu**, Michael Folkerts, Dan Nguyen, Nicholas Gans, Steve Jiang. [Deep BOO: End-to-End Training of Beam Angle Selection Policies for Intensity Modulated Radiation Therapy](#). *Clinical Trials*. IEEE Transactions on Neural Systems and Rehabilitation Engineering. 2018.

**Olalekan Ogunmolu**, Ayaka Kume, Jethro Tan. [A stable Lyapunov approach for designing deep policies for complex robot motion tasks](#). *Robotics and Automation Letters/International Conference on Robotics and Automation (ICRA/RA-L)*. 2018.

**Olalekan Ogunmolu**, Nick Gans, Steve Jiang. [A Neural Network Adaptive Controller for Position Correction in IMRT](#). *Transactions on Robotics (T-RO)* 2018.

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### Abstracts:

**Olalekan Ogunmolu**, Nicholas Gans, Tyler Summers. [Minimax Iterative Dynamic Game: Application to Nonlinear Robot Control Tasks](#). *IEEE International Conference on Robotics and Automation, Machine Learning for Planning and Control Workshop Extended Abstract (ICRA 2018)*, Madrid, Spain. October 2018.

**Olalekan Ogunmolu**, Nicholas Gans, Tyler Summers [Minimax Iterative Dynamic Game: Application to Nonlinear Robot Control Tasks](#)., *IEEE International Conference on Robotics and Automation, Late Breaking Result Abstract* Brisbane, Australia, May 2018.

Yara Almubarak, Joshi Aniket, **Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, Nicholas Gans, and Yonas Tadesse, [Design and Development of Soft Robots for Head and Neck Cancer Radiotherapy](#). *SPIE: Smart Structures + Nondestructive Evaluation*, Denver, CO, U.S.A. March 2018.

Tyler Summers, **Olalekan Ogunmolu**, Nicholas Gans. [Robustness Margins and Robust Guided Policy Search for Deep Reinforcement Learning](#)". *IROS 2017 Abstract Only Track*, Vancouver, BC, Canada. September 2017.

**Olalekan Ogunmolu**, Nick Gans, Steve Jiang, Xuejun Gu. [An Image-Guided Soft Robotic Patient Positioning System for Maskless Head-And-Neck Cancer Radiotherapy: A Proof-of-Concept Study](#). *American Association of Physicists in Medicine (AAPM) Annual Meeting*, Anaheim, CA, USA. July 2015.

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### Tech Reports:

**Olalekan Ogunmolu**, Nicholas Gans, Tyler Summers. [Robust Zero-Sum Deep Reinforcement Learning](#). *arxiv PrePrints*, *arxiv ID:1710.00491*, Oct 2017.

**Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, Nicholas Gans. [Nonlinear Systems Identification Using Deep Dynamic Neural Networks](#)". *arxiv PrePrints*, *arxiv ID:1610.01439*, Oct 2016.

**Olalekan Ogunmolu**. [Review of "Continuous Finite-Time Stabilization of Translational and Rotational Double Integrators"](#). *arxiv PrePrints*, *arxiv ID: 1612.01607v2*, May 2015.

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## Invited Talks

### Presentations:

- Google [SoftNeuroAdapt: A 3-DoF Neuro-Adaptive Healthcare System.](#)  
*Work presented by Nick Gans, Google Robotics, Mountain View, CA. USA. September 2017.*
- EFSC'17, Soft Robotic Modules as Position Correcting Mechanisms in Cancer RT.  
Vancouver [3rd Entrepreneurship Forum & Start-up Competition, EFSC'17](#), Vancouver, BC, Canada.  
September 2017.
- UTSW, [A 3-DOF Neuro-Adaptive Patient Pose Correcting System For Frameless and Maskless Cancer Radiotherapy,](#)  
Dallas, TX *Physics Research Seminar Series, Radiation Oncology Department, UT Southwestern Medical Center, Dallas, TX, USA. March 2017.*
- IEEE [Towards automated accurate patient positioning in maskless cancer radiotherapy.](#)  
Arlington, TX *IEEE Computational Intelligence Society, UT Arlington, TX, USA. December 2015.*

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## Poster Presentations:

- ICRA '18 **Minimax Iterative Dynamic Game: Application to Nonlinear Robot Control Tasks.,**  
*IEEE International Conference on Robotics and Automation Brisbane, Australia, May 2018.*
- NIPS '17 **An iterative dynamic game for robust deep reinforcement learning,**  
*Neural Information Processing Systems Long Beach, CA, December 2017.*
- IROS '17 **Robustness Margins and Robust Guided Policy Search for Deep Reinforcement Learning,**  
*International Conference on Intelligent Robots and Systems Vancouver, BC, Canada. September 2017.*
- Texas **A 3-DOF Neuro-Adaptive Pose Correction System For Frameless and Maskless Cancer Radiotherapy,**  
Systems Day *Texas Systems Day, Texas A & M University, College Station, TX, USA. March 2017.*

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## Awards and honors

- Finalist at the [3rd Entrepreneurship Forum and Startup Competition](#) August 2017  
Sponsored by IEEE Robotics and Automation Society, KUKA AG, and Univ. Hamburg
- [NSF Doctoral Consortium Award](#) August 2017
- **Mary and Richard Templeton Graduate Fellowship (UTD)** August 2017
- **ROSCon Scholarship** (Open Software for Robotics Foundation) July 2017
- **President's Teaching Excellence Award** for Teaching Assistants (UTD) Nom. Feb. 2017
- **Golden Key International Honour Society** Inducted Dec. 2016
- **IEEE RAS/ISAM Travel Award** August 2016
- **Ericsson Graduate Fellowship** 2015 - 2016
- **Jonsson Scholarship** 2014 - 2015
- **Achievement Award, University of Florida** (*Declined*) Fall 2014
- **PTDF Overseas Scholarship Award, £25,500+ for one year.** (~1.7% acceptance) 2011
- **Federal Government (of Nigeria) Scholarship** (~3.6% acceptance) 2002
- **Ondo State (Nigeria) Scholarship** (~10% acceptance) 2004

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## Journals/conferences peer reviewing activities

- 2018 **Reviewer**, *Institute of Physics: Measurement Science and Technology (Journal).*
- 2018 **Reviewer**, *IEEE International Conference on Intelligent Robots and Systems (IROS) 2018.*
- 2018 **Reviewer**, *Neural Computing and Applications (Journal), Neuro-Adaptive Control.*
- 2017 **Reviewer**, *IEEE International Conference on Robotics and Automation (ICRA) 2018.*
- 2017 **Reviewer**, *American Control Conference (ACC), Reinforcement Learning Track.*

- 2017 **Reviewer**, *International Federation of Automatic Control World Congress (IFAC)*, Switched Systems Track.
- 2017 **Open Reviewer**, *35th International Conference on Machine Learning (ICML)*, [OptNet: Differentiable Optimization as a Layer in Neural Networks](#).

## Select services and leadership

- 2017 **Invited Contributor**, *IEEE/RSJ International Conference on Robots and Intelligent Systems (IROS)*, Abstract Only Track, Vancouver, BC, Canada.
- 2017 – Now **Member**, **IEEE Robotics and Automation Society**.
- 2016–Now **Member**, *IEEE Boston*, Greater Boston, USA.
- 2015 – 2016 **Science instructor**, *IEEE Dallas Shoulder of Giants Workshops*, Dallas, TX.  
Participant at IEEE Dallas Young Professionals community outreaches in promoting STEM education and awareness in the Dallas/Fort-Worth Metroplex.
- 2015 **Summer Science Program**, *University of Texas at Dallas*, Richardson, TX.  
Trained high-school kids in basic robots control and programming with the Berkeley Snap! kit and arduino.
- 2012 **Workshop participant**, *ILA Berlin Airshow*, Berlin, Germany.  
Selected by Cassidian (an EADS company) for the *Aerospace Systems Engineering* workshop.
- 2012 **Workshop participant**, *Farnborough International Airshow*, NE Hampshire, England.  
Selected by Airbus (an EADS company) among participants at the *UAV and Fighter Aircraft* workshop.

## Experience

### Research:

- Summer 18 **Research Intern**, Preferred Networks, Tokyo, Japan.  
*Research Intern within the Robotics Team. Working on stable learning of complex robot motion-planning/manipulation tasks.*
- Fall 17 - **Visiting Research Student**, Medical Artificial Intelligence and Automation Laboratory,  
Present Division of Medical Physics and Engineering, Radiation Oncology Department, UT Southwestern Medical Center.  
*Research Assistant for Dr. Steve Jiang, Barbara Crittenden Professor of Cancer Research, UTSW Department of Radiation Oncology*
- Summer - **Research Assistant**, Dr. Tyler Summers, Mechanical Engineering, UT Dallas.  
Fall '17 Dynamic Programming, Decision Theoretic Control, Machine/Reinforcement Learning.
- Fall '14 - **Research Assistant**, Dr. Nick Gans, Electrical Engineering, University of Texas at Dallas.  
Now Control Systems, Systems Identification, State Estimation and Computer Vision.
- Summer '16 **Hardware Integration Intern**, Amazon Robotics LLC.  
SLAM, Software and Hardware Integration.
- Spring '16 **Hardware Integration Intern**, Advanced Robotics Lab, Amazon Robotics LLC.  
Computer Vision, Hardware Integration.

### Teaching:

- Fall '14 - '16 **Teaching Assistant, Introduction to Robotics**, *University of Texas at Dallas*.  
Guided students during laboratories in programming the Robai Cyton 300R2 Robot and graded homeworks.
- Spring '15 **Teaching Assistant, Linear Systems (M.S. Class)**, *University of Texas at Dallas*.  
Responsible for helping Masters students with linear control theory applications; graded homeworks and midterms.
- Spring '14 **Instructor, Analysis and Design of Digital Systems**, *Adekunle Ajasin University*.  
Developed course modules, sole instructor for sophomore students, graded homeworks, designed and graded exams.
- Summer '14 **Instructor, Digital Logic Design**, *Adekunle Ajasin University*.  
Co-developed course modules, joint-instructor for junior students, graded homeworks, designed and graded exams.

## Miscellaneous:

- 2009–2011 **Warehouse Manager, Apapa Plant**, *Coca-Cola Hellenic Bottling Company Plc*, Lagos.  
2007–2008 **Banking Assistant**, *First Bank of Nigeria Plc*, Lagos.  
2005–2007 **System Engineer**, *DMT Technologies Limited*, KD, Nigeria.

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## Mentoring

### Undergraduate mentoring:

- Summer 2017 Rachael Thompson. MIT Freshman 2017.  
2016 - Now Alex Tomkovich. Computer Engineering Junior.  
Spring 2015 Grant Carr. Computer Engineering Junior.

### Masters mentoring:

- 2016 – 2017 Adwait Kulkarn. Mechanical Engineering Masters student (Currently at Drov Technologies, MN).  
2015 Ajith Venkateswaran. Computer Engineering Masters student (Currently Senior Robotics Software Engineer, Samsung Research, America).

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## Computing

**Programming** C++, Python, Lua, MATLAB, LabVIEW.

**Libraries** Point Cloud Library, OpenCV, Torch7, Eigen, Docker, PyTorch, OpenAI Gym, MuJoCo, Numpy, SciPy, Scikit-Learn, C++11/14 standards.

**OS** Ubuntu, Debian, Windows.

**OSRF** ROS hydro, indigo, jade, and kinetic distros. Xacro, urdfs, pr2 robot packages, gazebo, urdfdom-py, ros-control, message filters, eigen, tf, tf2, hector-quadrator, kdl, slam-gmapping, rviz, rqt, amcl, orocos, controller-manager, geometry-msgs, rosaria, ros-arnl, sensor-msgs, nav stack. Familiar with Staubli TX-90 and ur10 robot packages.

**Web** HTML, Markdown, socket.io, node.js, and express.js.

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## Select OpenSource Projects

**Lyapunov-Learner** Python Implementation of "Learning Control Lyapunov Functions for Dynamical Systems". (Available at <https://github.com/lakehanne/LyapunovLearner>)

**Awesome-NeuroControl** A curated list of neural applications in control theory and practice. (Available at <https://github.com/lakehanne/awesome-neurocontrol>)

**PCL** Fix for segfault in our-cvfh algorithm in the point-cloud library. (Available at [PR 1827](#))

**GPS** Catkinized version of Levine et. al's guided policy search algorithm in ROS Indigo (Available at <https://github.com/lakehanne/gps>). Dockerized version available at [gps-docker](#).

**Keyence** Minimal source code for retrieving profile map from the keyence LJV-7000 series line scanners. (Available at <https://github.com/lakehanne/keyence>)

**RBN** Recurrent Batch Normalization of Neural Networks in Torch7. (Available at <https://github.com/element-research/rnn>)

**DICE** Sørensen-Dice coefficients in Torch7. (Available at <https://github.com/lakehanne/nn>).

**FARNNs** Training of multilayer networks, simple recurrent neural networks, long short-term memory cells (with peep-hole connections), fast LSTMS, and recurrent batch normalized FastLSTMs to model the relationship between Borel measurable sets. (Available at <https://github.com/lakehanne/FARNN>)

**An all-convolutional network** Source codes for my entry in the Kaggle 2016 data science competition in identifying and segmenting ultrasound images of the human neck. Codes available upon request.