K-Nearest Neighbor (KNN) Algorithm for Machine Learning

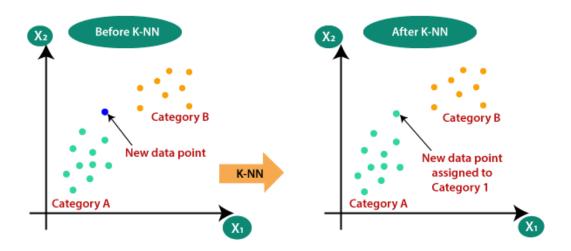
- K-Nearest Neighbor is one of the simplest Machine Learning algorithms based on Supervised Learning technique.
- K-NN algorithm assumes the similarity between the new case/data and available cases and put the new case into the category that is most similar to the available categories.
- K-NN algorithm stores all the available data and classifies a new data point based on the similarity. This means when new data appears then it can be easily classified into a well suite category by using K- NN algorithm.
- K-NN algorithm can be used for Regression as well as for Classification but mostly it is used for the Classification problems.
- o K-NN is a **non-parametric algorithm**, which means it does not make any assumption on underlying data.
- It is also called a lazy learner algorithm because it does not learn from the training set immediately instead it stores the dataset and at the time of classification, it performs an action on the dataset.
- KNN algorithm at the training phase just stores the dataset and when it gets new data,
 then it classifies that data into a category that is much similar to the new data.
- Example: Suppose, we have an image of a creature that looks similar to cat and dog, but we want to know either it is a cat or dog. So for this identification, we can use the KNN algorithm, as it works on a similarity measure. Our KNN model will find the similar features of the new data set to the cats and dogs images and based on the most similar features it will put it in either cat or dog category.

KNN Classifier



Why do we need a K-NN Algorithm?

Suppose there are two categories, i.e., Category A and Category B, and we have a new data point x1, so this data point will lie in which of these categories. To solve this type of problem, we need a K-NN algorithm. With the help of K-NN, we can easily identify the category or class of a particular dataset. Consider the below diagram:



How does K-NN work?

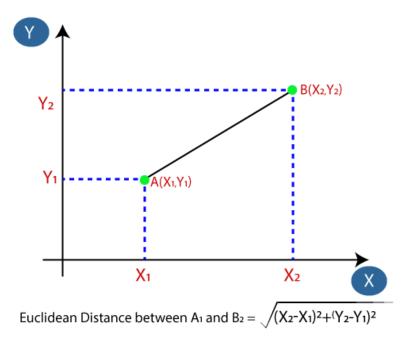
The K-NN working can be explained on the basis of the below algorithm:

- Step-1: Select the number K of the neighbors
- Step-2: Calculate the Euclidean distance of K number of neighbors
- Step-3: Take the K nearest neighbors as per the calculated Euclidean distance.
- o **Step-4:** Among these k neighbors, count the number of the data points in each category.
- **Step-5:** Assign the new data points to that category for which the number of the neighbor is maximum.
- Step-6: Our model is ready.

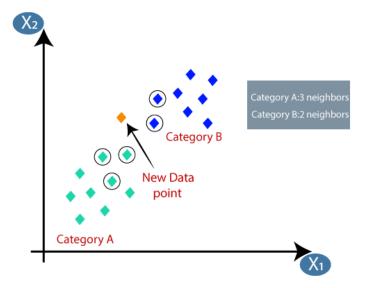
Suppose we have a new data point and we need to put it in the required category. Consider the below image:



- o Firstly, we will choose the number of neighbors, so we will choose the k=5.
- Next, we will calculate the Euclidean distance between the data points. The Euclidean
 distance is the distance between two points, which we have already studied in
 geometry. It can be calculated as:



By calculating the Euclidean distance we got the nearest neighbors, as three nearest neighbors in category A and two nearest neighbors in category B. Consider the below image:



 As we can see the 3 nearest neighbors are from category A, hence this new data point must belong to category A.

How to select the value of K in the K-NN Algorithm?

Below are some points to remember while selecting the value of K in the K-NN algorithm:

- There is no particular way to determine the best value for "K", so we need to try some values to find the best out of them. The most preferred value for K is 5.
- A very low value for K such as K=1 or K=2, can be noisy and lead to the effects of outliers in the model.
- Large values for K are good, but it may find some difficulties.

Advantages of KNN Algorithm:

- It is simple to implement.
- It is robust to the noisy training data
- o It can be more effective if the training data is large.

Disadvantages of KNN Algorithm:

- o Always needs to determine the value of K which may be complex some time.
- The computation cost is high because of calculating the distance between the data points for all the training samples.

Naïve Bayes Classifier Algorithm

- Naïve Bayes algorithm is a supervised learning algorithm, which is based on Bayes theorem and used for solving classification problems.
- o It is mainly used in *text classification* that includes a high-dimensional training dataset.
- Naïve Bayes Classifier is one of the simple and most effective Classification algorithms which helps in building the fast machine learning models that can make quick predictions.
- It is a probabilistic classifier, which means it predicts on the basis of the probability of an object.
- Some popular examples of Naïve Bayes Algorithm are spam filtration, Sentimental analysis, and classifying articles.

Why is it called Naïve Bayes?

The Naïve Bayes algorithm is comprised of two words Naïve and Bayes, Which can be described as:

- Naïve: It is called Naïve because it assumes that the occurrence of a certain feature is independent of the occurrence of other features. Such as if the fruit is identified on the bases of color, shape, and taste, then red, spherical, and sweet fruit is recognized as an apple. Hence each feature individually contributes to identify that it is an apple without depending on each other.
- Bayes: It is called Bayes because it depends on the principle of Bayes' Theorem.

Bayes' Theorem:

- Bayes' theorem is also known as Bayes' Rule or Bayes' law, which is used to determine the probability of a hypothesis with prior knowledge. It depends on the conditional probability.
- The formula for Bayes' theorem is given as:

$$P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B)}$$

Where,

P(A|B) is **Posterior probability**: Probability of hypothesis A on the observed event B.

P(B|A) is Likelihood probability: Probability of the evidence given that the probability of a hypothesis is true.

P(A) is **Prior Probability**: Probability of hypothesis before observing the evidence.

P(B) is Marginal Probability: Probability of Evidence.

Working of Naïve Bayes' Classifier:

Working of Naïve Bayes' Classifier can be understood with the help of the below example:

Suppose we have a dataset of **weather conditions** and corresponding target variable "**Play**". So using this dataset we need to decide that whether we should play or not on a particular day according to the weather conditions. So to solve this problem, we need to follow the below steps:

- 1. Convert the given dataset into frequency tables.
- 2. Generate Likelihood table by finding the probabilities of given features.
- 3. Now, use Bayes theorem to calculate the posterior probability.

Problem: If the weather is sunny, then the Player should play or not?

Solution: To solve this, first consider the below dataset:

S.No.	Outlook	Play
0	Rainy	Yes
1	Sunny	Yes
2	Overcast	Yes
3	Overcast	Yes
4	Sunny	No
5	Rainy	Yes
6	Sunny	Yes
7	Overcast	Yes
8	Rainy	No
9	Sunny	No
10	Sunny	Yes
11	Rainy	No
12	Overcast	Yes
13	Overcast	Yes

Frequency table for the Weather Conditions:

Weather	Yes	No
Overcast	5	0
Rainy	2	2
Sunny	3	2
Total	10	5

Likelihood table weather condition:

Weather	No	Yes	
Overcast	0	5	5/14= 0.35
Rainy	2	2	4/14=0.29
Sunny	2	3	5/14=0.35
All	4/14=0.29	10/14=0.71	

Applying Bayes theorem:

P(Yes|Sunny)=P(Sunny|Yes)*P(Yes)/P(Sunny)

P(Sunny|Yes)= 3/10= 0.3

P(Sunny) = 0.35

P(Yes)=0.71

So P(Yes|Sunny) = 0.3*0.71/0.35= **0.60**

P(No|Sunny)= P(Sunny|No)*P(No)/P(Sunny)

P(Sunny|NO)= 2/4=0.5

P(No) = 0.29

P(Sunny)= 0.35

So P(No|Sunny) = 0.5*0.29/0.35 = 0.41

So as we can see from the above calculation that P(Yes|Sunny)>P(No|Sunny)

Hence on a Sunny day, Player can play the game.

Advantages of Naïve Bayes Classifier:

- o Naïve Bayes is one of the fast and easy ML algorithms to predict a class of datasets.
- o It can be used for Binary as well as Multi-class Classifications.

- It performs well in Multi-class predictions as compared to the other Algorithms.
- o It is the most popular choice for **text classification problems**.

Disadvantages of Naïve Bayes Classifier:

 Naive Bayes assumes that all features are independent or unrelated, so it cannot learn the relationship between features.

Applications of Naïve Bayes Classifier:

- It is used for Credit Scoring.
- It is used in medical data classification.
- It can be used in real-time predictions because Naïve Bayes Classifier is an eager learner.
- It is used in Text classification such as Spam filtering and Sentiment analysis.

Types of Naïve Bayes Model:

There are three types of Naive Bayes Model, which are given below:

- Gaussian: The Gaussian model assumes that features follow a normal distribution. This
 means if predictors take continuous values instead of discrete, then the model assumes
 that these values are sampled from the Gaussian distribution.
- Multinomial: The Multinomial Naïve Bayes classifier is used when the data is multinomial distributed. It is primarily used for document classification problems, it means a particular document belongs to which category such as Sports, Politics, education,
 - The classifier uses the frequency of words for the predictors.
- Bernoulli: The Bernoulli classifier works similar to the Multinomial classifier, but the predictor variables are the independent Booleans variables. Such as if a particular word is present or not in a document. This model is also famous for document classification tasks.

ML | Linear Regression

Linear regression is a type of <u>supervised machine learning</u> algorithm that computes the linear relationship between the dependent variable and one or more independent features by fitting a linear equation to observed data.

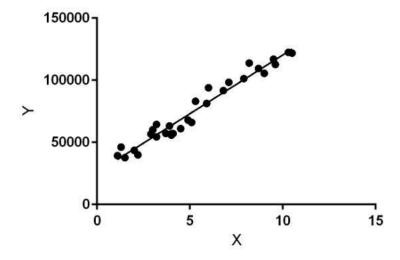
When there is only one independent feature, it is known as <u>Simple Linear Regression</u>, and when there are more than one feature, it is known as <u>Multiple Linear Regression</u>.

Similarly, when there is only one dependent variable, it is considered <u>Univariate Linear Regression</u>, while when there are more than one dependent variables, it is known as <u>Multivariate Regression</u>.

Why Linear Regression is Important?

The interpretability of linear regression is a notable strength. The model's equation provides clear coefficients that elucidate the impact of each independent variable on the dependent variable, facilitating a deeper understanding of the underlying dynamics. Its simplicity is a virtue, as linear regression is transparent, easy to implement, and serves as a foundational concept for more complex algorithms.

Linear regression is not merely a predictive tool; it forms the basis for various advanced models. Techniques like regularization and support vector machines draw inspiration from linear regression, expanding its utility. Additionally, linear regression is a cornerstone in assumption testing, enabling researchers to validate key assumptions about the data.



Types of Linear Regression

There are two main types of linear regression:

Simple Linear Regression (Univariate)

This is the simplest form of linear regression, and it involves only one independent variable and one dependent variable. The equation for simple linear regression is:

$$y = \beta_0 + \beta_1 X$$

where:

- Y is the dependent variable
- X is the independent variable
- B0 is the intercept
- β1 is the slope

Multiple Linear Regression (Multivariate)

This involves more than one independent variable and one dependent variable. The equation for multiple linear regression is:

$$y = \beta_0 + \beta_1 X 1 + \beta_2 X 2 + \dots + \beta_n X n$$

where:

- Y is the dependent variable
- X1, X2, ..., Xn are the independent variables
- β0 is the intercept
- β1, β2, ..., βn are the slopes

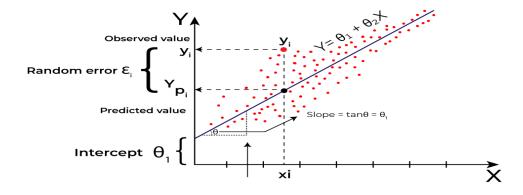
The goal of the algorithm is to find the best Fit Line equation that can predict the values based on the independent variables.

In regression set of records are present with X and Y values and these values are used to learn a function so if you want to predict Y from an unknown X this learned function can be used. In regression we have to find the value of Y, So, a function is required that predicts continuous Y in the case of regression given X as independent features.

What is the best Fit Line?

Our primary objective while using linear regression is to locate the best-fit line, which implies that the error between the predicted and actual values should be kept to a minimum. There will be the least error in the best-fit line.

The best Fit Line equation provides a straight line that represents the relationship between the dependent and independent variables. The slope of the line indicates how much the dependent variable changes for a unit change in the independent variable(s).



Here Y is called a dependent or target variable and X is called an independent variable also known as the predictor of Y. There are many types of functions or modules that can be used

for regression. A linear function is the simplest type of function. Here, X may be a single feature or multiple features representing the problem.

Linear regression performs the task to predict a dependent variable value (y) based on a given independent variable (x)). Hence, the name is Linear Regression. In the figure above, X (input) is the work experience and Y (output) is the salary of a person. The regression line is the best-fit line for our model.

We utilize the cost function to compute the best values in order to get the best fit line since different values for weights or the coefficient of lines result in different regression lines.

Hypothesis function in Linear Regression

As we have assumed earlier that our independent feature is the experience i.e X and the respective salary Y is the dependent variable. Let's assume there is a linear relationship between X and Y then the salary can be predicted using:

$$\hat{Y} = \theta_1 + \theta_2 X$$
OR
 $\hat{y}_i = \theta_1 + \theta_2 x_i$

- yi∈Y(i=1,2,···,n) are labels to data (Supervised learning)
- xieX(i=1,2,···,n) are the input independent training data (univariate one input variable(parameter))
- yi^∈Y^(i=1,2,···,n) are the predicted values.

The model gets the best regression fit line by finding the best $\theta 1$ and $\theta 2$ values.

- **θ1**: intercept
- θ2: coefficient of x

Once we find the best $\theta 1$ and $\theta 2$ values, we get the best-fit line. So when we are finally using our model for prediction, it will predict the value of y for the input value of x.

How to update $\theta 1$ and $\theta 2$ values to get the best-fit line?

To achieve the best-fit regression line, the model aims to predict the target value Y $^{\circ}$ such that the error difference between the predicted value Y $^{\circ}$ and the true value Y is minimum. So, it is very important to update the $\theta 1$ and $\theta 2$ values, to reach the best value that minimizes the error between the predicted y value (pred) and the true y value (y).

$$minimize \frac{1}{n} \sum_{i=1}^{n} (\hat{y}_i - y_i)^2$$

Cost function for Linear Regression

The <u>cost function</u> or the <u>loss function</u> is nothing but the error or difference between the predicted value Y^ and the true value Y.

In Linear Regression, the **Mean Squared Error (MSE)** cost function is employed, which calculates the average of the squared errors between the predicted values y¹ and the actual values yi. The purpose is to determine the optimal values for the intercept $\theta 1\theta 1$ and the coefficient of the input feature $\theta 2\theta 2$ providing the best-fit line for the given data points. The linear equation expressing this relationship is y¹ = $\theta 1 + \theta 2x$ i

MSE function can be calculated as:

Cost function
$$(J) = \frac{1}{n} \sum_{i=1}^{n} (\hat{y}_i - y_i)^2$$

Utilizing the MSE function, the iterative process of gradient descent is applied to update the values of $\0$ 2. This ensures that the MSE value converges to the global minima, signifying the most accurate fit of the linear regression line to the dataset.

This process involves continuously adjusting the parameters \(\theta_1\) and \(\theta_2\) based on the gradients calculated from the MSE. The final result is a linear regression line that minimizes the overall squared differences between the predicted and actual values, providing an optimal representation of the underlying relationship in the data.

Gradient Descent for Linear Regression

A linear regression model can be trained using the optimization algorithm gradient descent by iteratively modifying the model's parameters to reduce the mean squared error (MSE) of the model on a training dataset. To update $\theta 1$ and $\theta 2$ values in order to reduce the Cost function (minimizing RMSE value) and achieve the best-fit line the model uses Gradient Descent. The idea is to start with random $\theta 1$ and $\theta 2$ values and then iteratively update the values, reaching minimum cost.

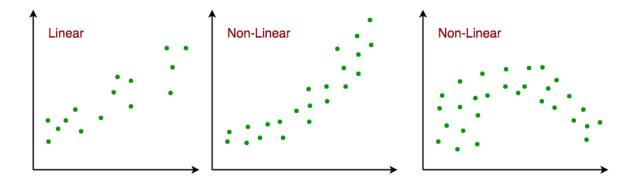
A gradient is nothing but a derivative that defines the effects on outputs of the function with a little bit of variation in inputs.

Finding the coefficients of a linear equation that best fits the training data is the objective of linear regression. By moving in the direction of the Mean Squared Error negative gradient with respect to the coefficients, the coefficients can be changed. And the respective intercept and coefficient of X will be if α is the learning rate.

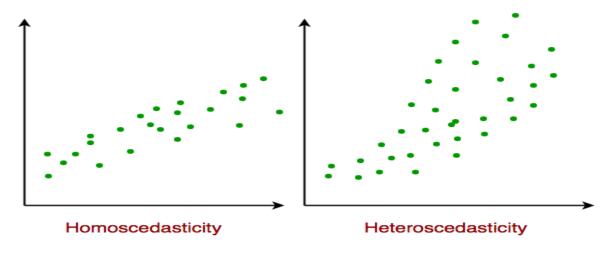
Assumptions of Simple (Univariate) Linear Regression

Linear regression is a powerful tool for understanding and predicting the behavior of a variable, however, it needs to meet a few conditions in order to be accurate and dependable solutions.

1. **Linearity**: The independent and dependent variables have a linear relationship with one another. This implies that changes in the dependent variable follow those in the independent variable(s) in a linear fashion. This means that there should be a straight line that can be drawn through the data points. If the relationship is not linear, then linear regression will not be an accurate model.



- 2. **Independence**: The observations in the dataset are independent of each other. This means that the value of the dependent variable for one observation does not depend on the value of the dependent variable for another observation. If the observations are not independent, then linear regression will not be an accurate model.
- 3. **Homoscedasticity**: Across all levels of the independent variable(s), the variance of the errors is constant. This indicates that the amount of the independent variable(s) has no impact on the variance of the errors. If the variance of the residuals is not constant, then linear regression will not be an accurate model.



4. **Normality**: The residuals should be normally distributed. This means that the residuals should follow a bell-shaped curve. If the residuals are not normally distributed, then linear regression will not be an accurate model.

Assumptions of Multiple (Multivariate) Linear Regression

For Multiple Linear Regression, all four of the assumptions from Simple Linear Regression apply. In addition to this, below are few more:

1. **No multicollinearity**: There is no high correlation between the independent variables. This indicates that there is little or no correlation between the independent variables.

Multicollinearity occurs when two or more independent variables are highly correlated with each other, which can make it difficult to determine the individual effect of each variable on the dependent variable. If there is multicollinearity, then multiple linear regressions will not be an accurate model.

- 2. **Additivity:** The model assumes that the effect of changes in a predictor variable on the response variable is consistent regardless of the values of the other variables. This assumption implies that there is no interaction between variables in their effects on the dependent variable.
- 3. **Feature Selection:** In multiple linear regression, it is essential to carefully select the independent variables that will be included in the model. Including irrelevant or redundant variables may lead to overfitting and complicate the interpretation of the model.
- 4. **Overfitting:** Overfitting occurs when the model fits the training data too closely, capturing noise or random fluctuations that do not represent the true underlying relationship between variables. This can lead to poor generalization performance on new, unseen data.

Multicollinearity

<u>Multicollinearity</u> is a statistical phenomenon that occurs when two or more independent variables in a multiple regression model are highly correlated, making it difficult to assess the individual effects of each variable on the dependent variable.

Detecting Multicollinearity includes two techniques:

- Correlation Matrix: Examining the correlation matrix among the independent variables is a common way to detect multicollinearity. High correlations (close to 1 or -1) indicate potential multicollinearity.
- VIF (Variance Inflation Factor): VIF is a measure that quantifies how much the variance of an estimated regression coefficient increases if your predictors are correlated. A high VIF (typically above 10) suggests multicollinearity.

Evaluation Metrics for Linear Regression

A variety of <u>evaluation measures</u> can be used to determine the strength of any linear regression model. These assessment metrics often give an indication of how well the model is producing the observed outputs.

The most common measurements are:

Mean Square Error (MSE)

<u>Mean Squared Error (MSE)</u> is an evaluation metric that calculates the average of the squared differences between the actual and predicted values for all the data points. The difference is squared to ensure that negative and positive differences don't cancel each other out.

$$MSE = \frac{1}{n} \sum_{i=1}^{n} (y_i - \widehat{y_i})^2$$

Here,

- n is the number of data points.
- yi is the actual or observed value for the ith data point.
- yi^yi is the predicted value for the ith data point.

MSE is a way to quantify the accuracy of a model's predictions. MSE is sensitive to outliers as large errors contribute significantly to the overall score.

Mean Absolute Error (MAE)

<u>Mean Absolute Error</u> is an evaluation metric used to calculate the accuracy of a regression model. MAE measures the average absolute difference between the predicted values and actual values.

Mathematically, MAE is expressed as:

$$MAE = \frac{1}{n} \sum_{i=1}^{n} |Y_i - \widehat{Y}_i|$$

Here,

- n is the number of observations
- Yi represents the actual values.
- Yi^Yi represents the predicted values

Lower MAE value indicates better model performance. It is not sensitive to the outliers as we consider absolute differences.

Root Mean Squared Error (RMSE)

The square root of the residuals' variance is the <u>Root Mean Squared Error</u>. It describes how well the observed data points match the expected values, or the model's absolute fit to the data.

In mathematical notation, it can be expressed as:

$$RMSE = \sqrt{\frac{RSS}{n}} = \sqrt{\frac{\sum_{i=2}^{n}(y_{i}^{actual} - y_{i}^{predicted})^{2}}{n}}$$

Rather than dividing the entire number of data points in the model by the number of degrees of freedom, one must divide the sum of the squared residuals to obtain an unbiased estimate. Then, this figure is referred to as the Residual Standard Error (RSE).

In mathematical notation, it can be expressed as:

$$RMSE = \sqrt{\frac{RSS}{n}} = \sqrt{\frac{\sum_{i=2}^{n} (y_i^{actual} - y_i^{predicted})^2}{(n-2)}}$$

RSME is not as good of a metric as R-squared. Root Mean Squared Error can fluctuate when the units of the variables vary since its value is dependent on the variables' units (it is not a normalized measure).

Coefficient of Determination (R-squared)

R-Squared is a statistic that indicates how much variation the developed model can explain or capture. It is always in the range of 0 to 1. In general, the better the model matches the data, the greater the R-squared number. In mathematical notation, it can be expressed as:

$$R^2 = 1 - (\frac{RSS}{TSS})$$

• <u>Residual sum of Squares</u> (RSS): The sum of squares of the residual for each data point in the plot or data is known as the residual sum of squares, or RSS. It is a measurement of the difference between the output that was observed and what was anticipated.

$$RSS = \sum_{i=2}^{n} (y_i - b_0 - b_1 x_i)^2$$

• **Total Sum of Squares (TSS):** The sum of the data points' errors from the answer variable's mean is known as the total sum of squares, or TSS.

$$TSS = \sum (y - \overline{y_i})^2$$

R squared metric is a measure of the proportion of variance in the dependent variable that is explained the independent variables in the model.

Adjusted R-Squared Error

Adjusted R2 measures the proportion of variance in the dependent variable that is explained by independent variables in a regression model. <u>Adjusted R-square</u> accounts the number of predictors in the model and penalizes the model for including irrelevant predictors that don't contribute significantly to explain the variance in the dependent variables.

Mathematically, adjusted R2 is expressed as:

$$Adjusted R^2 = 1 - (\frac{(1-R^2).(n-1)}{n-k-1})$$

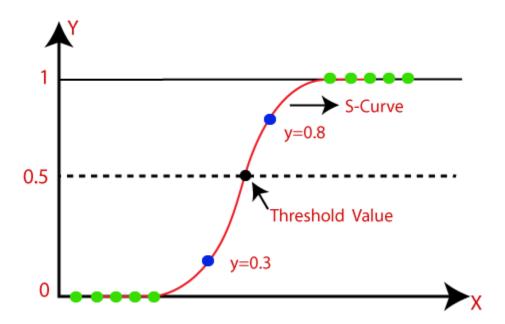
Here,

- n is the number of observations
- k is the number of predictors in the model
- R2 is coeeficient of determination

Adjusted R-square helps to prevent overfitting. It penalizes the model with additional predictors that do not contribute significantly to explain the variance in the dependent variable.

Logistic Regression in Machine Learning

- Logistic regression is one of the most popular Machine Learning algorithms, which comes under the Supervised Learning technique. It is used for predicting the categorical dependent variable using a given set of independent variables.
- Logistic regression predicts the output of a categorical dependent variable. Therefore the outcome must be a categorical or discrete value. It can be either Yes or No, 0 or 1, true or False, etc. but instead of giving the exact value as 0 and 1, it gives the probabilistic values which lie between 0 and 1.
- Logistic Regression is much similar to the Linear Regression except that how they are used. Linear Regression is used for solving Regression problems, whereas Logistic regression is used for solving the classification problems.
- o In Logistic regression, instead of fitting a regression line, we fit an "S" shaped logistic function, which predicts two maximum values (0 or 1).
- The curve from the logistic function indicates the likelihood of something such as whether the cells are cancerous or not, a mouse is obese or not based on its weight, etc.
- Logistic Regression is a significant machine learning algorithm because it has the ability to provide probabilities and classify new data using continuous and discrete datasets.
- Logistic Regression can be used to classify the observations using different types of data and can easily determine the most effective variables used for the classification. The below image is showing the logistic function:



Logistic Function (Sigmoid Function):

- The sigmoid function is a mathematical function used to map the predicted values to probabilities.
- o It maps any real value into another value within a range of 0 and 1.
- The value of the logistic regression must be between 0 and 1, which cannot go beyond this limit, so it forms a curve like the "S" form. The S-form curve is called the Sigmoid function or the logistic function.
- o In logistic regression, we use the concept of the threshold value, which defines the probability of either 0 or 1. Such as values above the threshold value tends to 1, and a value below the threshold values tends to 0.

Assumptions for Logistic Regression:

- The dependent variable must be categorical in nature.
- The independent variable should not have multi-collinearity.

Logistic Regression Equation:

The Logistic regression equation can be obtained from the Linear Regression equation. The mathematical steps to get Logistic Regression equations are given below:

We know the equation of the straight line can be written as:

$$y = b_0 + b_1 x_1 + b_2 x_2 + b_3 x_3 + \dots + b_n x_n$$

 In Logistic Regression y can be between 0 and 1 only, so for this let's divide the above equation by (1-y):

$$\frac{y}{1-y}$$
; 0 for y= 0, and infinity for y=1

 But we need range between -[infinity] to +[infinity], then take logarithm of the equation it will become:

$$log\left[\frac{y}{1-y}\right] = b_0 + b_1x_1 + b_2x_2 + b_3x_3 + \dots + b_nx_n$$

The above equation is the final equation for Logistic Regression.

Type of Logistic Regression:

On the basis of the categories, Logistic Regression can be classified into three types:

- o **Binomial:** In binomial Logistic regression, there can be only two possible types of the dependent variables, such as 0 or 1, Pass or Fail, etc.
- Multinomial: In multinomial Logistic regression, there can be 3 or more possible unordered types of the dependent variable, such as "cat", "dogs", or "sheep"
- o **Ordinal:** In ordinal Logistic regression, there can be 3 or more possible ordered types of dependent variables, such as "low", "Medium", or "High".

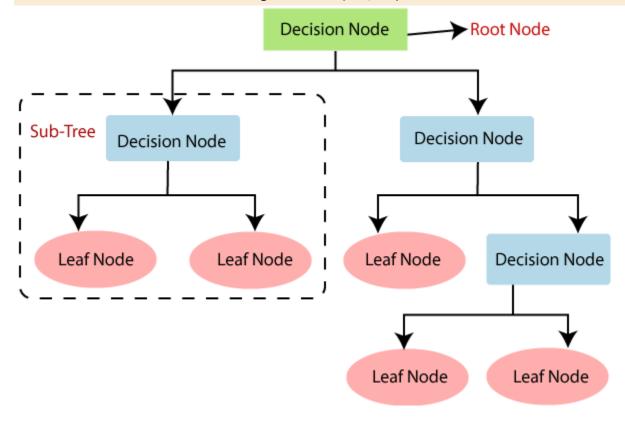
Difference between Linear Regression and Logistic Regression:

Linear Regression	Logistic Regression
Linear regression is used to predict the continuous dependent variable using a given set of independent variables.	Logistic Regression is used to predict the categorical dependent variable using a given set of independent variables.
Linear Regression is used for solving Regression problem.	Logistic regression is used for solving Classification problems.
In Linear regression, we predict the value of continuous variables.	In logistic Regression, we predict the values of categorical variables.
In linear regression, we find the best fit line, by which we can easily predict the output.	In Logistic Regression, we find the S-curve by which we can classify the samples.
Least square estimation method is used for estimation of accuracy.	Maximum likelihood estimation method is used for estimation of accuracy.
The output for Linear Regression must be a continuous value, such as price, age, etc.	The output of Logistic Regression must be a Categorical value such as 0 or 1, Yes or No, etc.
In Linear regression, it is required that relationship between dependent variable and independent variable must be linear.	In Logistic regression, it is not required to have the linear relationship between the dependent and independent variable.
In linear regression, there may be collinearity between the independent variables.	In logistic regression, there should not be collinearity between the independent variable.

Decision Tree Algorithm

- Decision Tree is a Supervised learning technique that can be used for both classification and Regression problems, but mostly it is preferred for solving Classification problems. It is a tree-structured classifier, where internal nodes represent the features of a dataset, branches represent the decision rules and each leaf node represents the outcome.
- o In a Decision tree, there are two nodes, which are the Decision Node and Leaf Node. Decision nodes are used to make any decision and have multiple branches, whereas Leaf nodes are the output of those decisions and do not contain any further branches.
- o The decisions or the test are performed on the basis of features of the given dataset.
- It is a graphical representation for getting all the possible solutions to a problem/decision based on given conditions.
- It is called a decision tree because, similar to a tree, it starts with the root node, which expands on further branches and constructs a tree-like structure.
- In order to build a tree, we use the CART algorithm, which stands for Classification and Regression Tree algorithm.
- A decision tree simply asks a question, and based on the answer (Yes/No), it further split the tree into subtrees.
- o Below diagram explains the general structure of a decision tree:

Note: A decision tree can contain categorical data (YES/NO) as well as numeric data.



Why use Decision Trees?

There are various algorithms in Machine learning, so choosing the best algorithm for the given dataset and problem is the main point to remember while creating a machine learning model. Below are the two reasons for using the Decision tree:

- Decision Trees usually mimic human thinking ability while making a decision, so it is easy to understand.
- The logic behind the decision tree can be easily understood because it shows a tree-like structure.

Decision Tree Terminologies

Root Node: Root node is from where the decision tree starts. It represents the entire dataset, which further gets divided into two or more homogeneous sets.

Leaf Node: Leaf nodes are the final output node, and the tree cannot be segregated further after getting a leaf node.

Splitting: Splitting is the process of dividing the decision node/root node into sub-nodes according to the given conditions.

Branch/Sub Tree: A tree formed by splitting the tree.

Pruning: Pruning is the process of removing the unwanted branches from the tree.

Parent/Child node: The root node of the tree is called the parent node, and other nodes are called the child nodes.

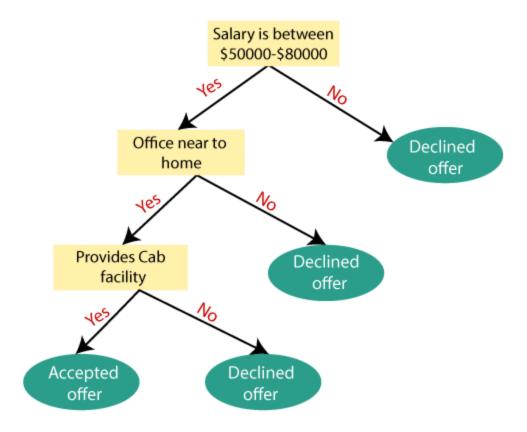
How does the Decision Tree algorithm Work?

In a decision tree, for predicting the class of the given dataset, the algorithm starts from the root node of the tree. This algorithm compares the values of root attribute with the record (real dataset) attribute and, based on the comparison, follows the branch and jumps to the next node.

For the next node, the algorithm again compares the attribute value with the other sub-nodes and move further. It continues the process until it reaches the leaf node of the tree. The complete process can be better understood using the below algorithm:

- Step-1: Begin the tree with the root node, says S, which contains the complete dataset.
- Step-2: Find the best attribute in the dataset using Attribute Selection Measure (ASM).
- Step-3: Divide the S into subsets that contains possible values for the best attributes.
- o **Step-4:** Generate the decision tree node, which contains the best attribute.
- Step-5: Recursively make new decision trees using the subsets of the dataset created in step -3. Continue this process until a stage is reached where you cannot further classify the nodes and called the final node as a leaf node.

Example: Suppose there is a candidate who has a job offer and wants to decide whether he should accept the offer or Not. So, to solve this problem, the decision tree starts with the root node (Salary attribute by ASM). The root node splits further into the next decision node (distance from the office) and one leaf node based on the corresponding labels. The next decision node further gets split into one decision node (Cab facility) and one leaf node. Finally, the decision node splits into two leaf nodes (Accepted offers and Declined offer). Consider the below diagram:



Attribute Selection Measures

While implementing a Decision tree, the main issue arises that how to select the best attribute for the root node and for sub-nodes. So, to solve such problems there is a technique which is called as **Attribute selection measure or ASM.** By this measurement, we can easily select the best attribute for the nodes of the tree. There are two popular techniques for ASM, which are:

- Information Gain
- o Gini Index

1. Information Gain:

- Information gain is the measurement of changes in entropy after the segmentation of a dataset based on an attribute.
- o It calculates how much information a feature provides us about a class.
- According to the value of information gain, we split the node and build the decision tree.
- A decision tree algorithm always tries to maximize the value of information gain, and a node/attribute having the highest information gain is split first. It can be calculated using the below formula:
- 1. Information Gain= Entropy(S)- [(Weighted Avg) *Entropy(each feature)

Entropy: Entropy is a metric to measure the impurity in a given attribute. It specifies randomness in data. Entropy can be calculated as:

Entropy(s)= -P(yes)log2 P(yes)- P(no) log2 P(no) Where,

- S= Total number of samples
- P(yes)= probability of yes
- o P(no)= probability of no

2. Gini Index:

- Gini index is a measure of impurity or purity used while creating a decision tree in the CART(Classification and Regression Tree) algorithm.
- An attribute with the low Gini index should be preferred as compared to the high Gini index.
- It only creates binary splits, and the CART algorithm uses the Gini index to create binary splits.
- Gini index can be calculated using the below formula:

Gini Index= 1- $\sum_{j} P_{j}^{2}$

Pruning: Getting an Optimal Decision tree

Pruning is a process of deleting the unnecessary nodes from a tree in order to get the optimal decision tree.

A too-large tree increases the risk of overfitting, and a small tree may not capture all the important features of the dataset. Therefore, a technique that decreases the size of the learning tree without reducing accuracy is known as Pruning. There are mainly two types of tree **pruning** technology used:

- Cost Complexity Pruning
- Reduced Error Pruning.

Advantages of the Decision Tree

- o It is simple to understand as it follows the same process which a human follow while making any decision in real-life.
- It can be very useful for solving decision-related problems.
- o It helps to think about all the possible outcomes for a problem.
- There is less requirement of data cleaning compared to other algorithms.

Disadvantages of the Decision Tree

- The decision tree contains lots of layers, which makes it complex.
- It may have an overfitting issue, which can be resolved using the Random Forest algorithm.
- For more class labels, the computational complexity of the decision tree may increase.

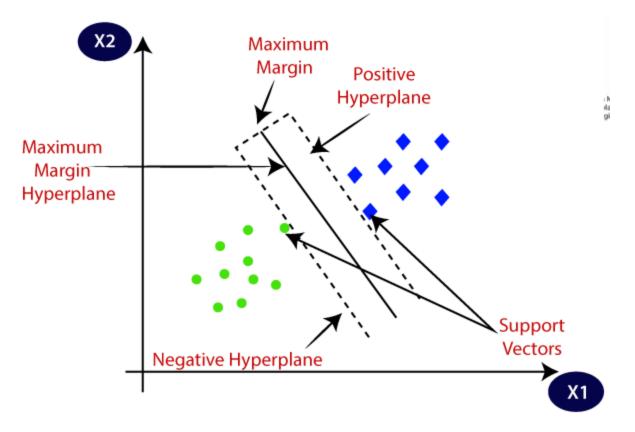
Support Vector Machine Algorithm

Support Vector Machine (SVM) is a supervised machine learning algorithm used for both classification and regression. Though we say regression problems as well its best suited for classification. The objective of SVM algorithm is to find a hyperplane in an N-dimensional space that distinctly classifies the data points. The dimension of the hyperplane depends upon the number of features. If the number of input features is two, then the hyperplane is just a line. If the number of input features is three, then the hyperplane becomes a 2-D plane. It becomes difficult to imagine when the number of features exceeds three.

The goal of the SVM algorithm is to create the best line or decision boundary that can segregate n-dimensional space into classes so that we can easily put the new data point in the correct category in the future. This best decision boundary is called a hyperplane.

SVM chooses the extreme points/vectors that help in creating the hyperplane. These extreme cases are called as support vectors, and hence algorithm is termed as Support Vector Machine.

Consider the below diagram in which there are two different categories that are classified using a decision boundary or hyperplane:



Types of SVM

SVM can be of two types:

- Linear SVM: Linear SVM is used for linearly separable data, which means if a dataset can be classified into two classes by using a single straight line, then such data is termed as linearly separable data, and classifier is used called as Linear SVM classifier.
- Non-linear SVM: Non-Linear SVM is used for non-linearly separated data, which means
 if a dataset cannot be classified by using a straight line, then such data is termed as nonlinear data and classifier used is called as Non-linear SVM classifier.

Hyperplane and Support Vectors in the SVM algorithm:

Hyperplane: There can be multiple lines/decision boundaries to segregate the classes in n-dimensional space, but we need to find out the best decision boundary that helps to classify the data points. This best boundary is known as the hyperplane of SVM.

The dimensions of the hyperplane depend on the features present in the dataset, which means if there are 2 features (as shown in image), then hyperplane will be a straight line. And if there are 3 features, then hyperplane will be a 2-dimension plane.

We always create a hyperplane that has a maximum margin, which means the maximum distance between the data points.

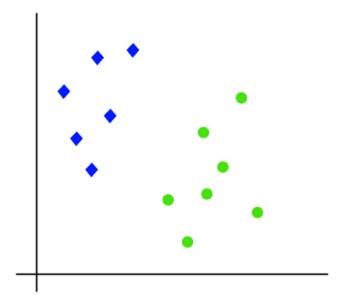
Support Vectors:

The data points or vectors that are the closest to the hyperplane and which affect the position of the hyperplane are termed as Support Vector. Since these vectors support the hyperplane, hence called a Support vector.

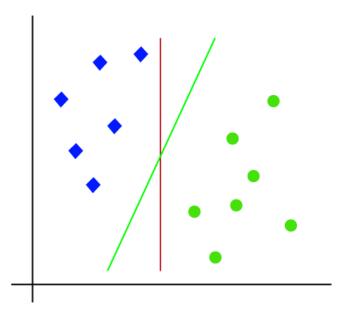
How does SVM works?

Linear SVM:

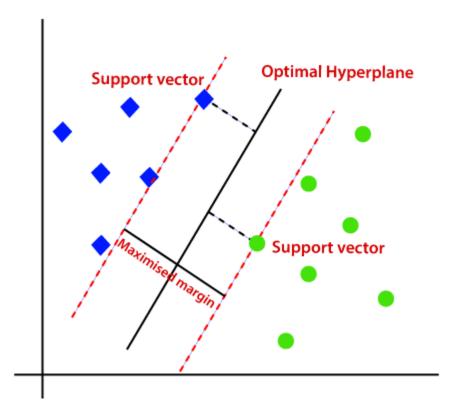
The working of the SVM algorithm can be understood by using an example. Suppose we have a dataset that has two tags (green and blue), and the dataset has two features x1 and x2. We want a classifier that can classify the pair(x1, x2) of coordinates in either green or blue. Consider the below image:



So as it is 2-d space so by just using a straight line, we can easily separate these two classes. But there can be multiple lines that can separate these classes. Consider the below image:

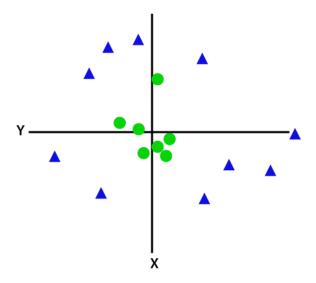


Hence, the SVM algorithm helps to find the best line or decision boundary; this best boundary or region is called as a **hyperplane**. SVM algorithm finds the closest point of the lines from both the classes. These points are called support vectors. The distance between the vectors and the hyperplane is called as **margin**. And the goal of SVM is to maximize this margin. The **hyperplane** with maximum margin is called the **optimal hyperplane**.



Non-Linear SVM:

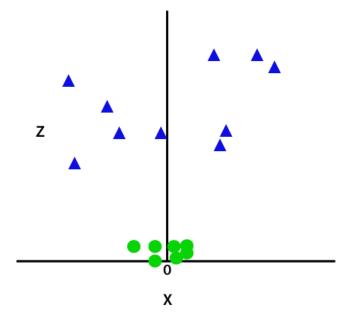
If data is linearly arranged, then we can separate it by using a straight line, but for non-linear data, we cannot draw a single straight line. Consider the below image:



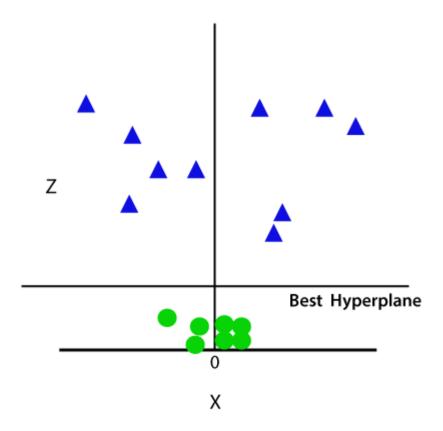
So to separate these data points, we need to add one more dimension. For linear data, we have used two dimensions x and y, so for non-linear data, we will add a third dimension z. It can be calculated as:

$$z=x^{2}+y^{2}$$

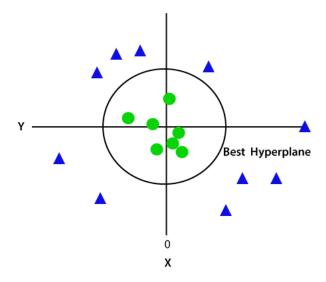
By adding the third dimension, the sample space will become as below image:



So now, SVM will divide the datasets into classes in the following way. Consider the below image:



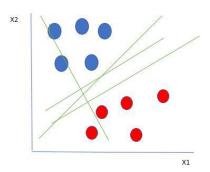
Since we are in 3-d Space, hence it is looking like a plane parallel to the x-axis. If we convert it in 2d space with z=1, then it will become as:



Hence we get a circumference of radius 1 in case of non-linear data.

Example

Let's consider two independent variables x1, x2 and one dependent variable which is either a blue circle or a red circle.

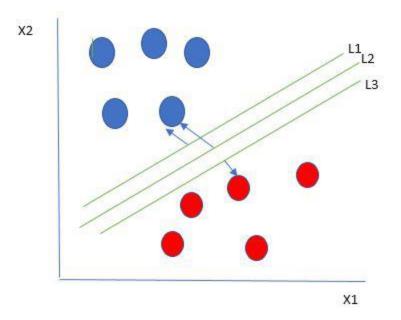


Linearly Separable Data points

From the figure above its very clear that there are multiple lines (our hyperplane here is a line because we are considering only two input features x1, x2) that segregates our data points or does a classification between red and blue circles. So how do we choose the best line or in general the best hyperplane that segregates our data points.

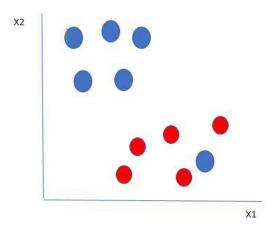
Selecting the best hyper-plane:

One reasonable choice as the best hyperplane is the one that represents the largest separation or margin between the two classes.

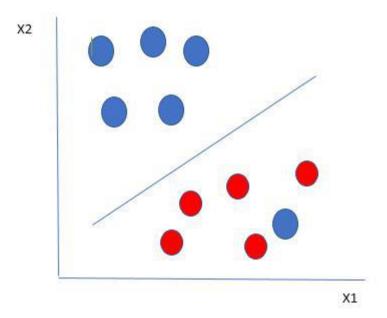


So we choose the hyperplane whose distance from it to the nearest data point on each side is maximized. If such a hyperplane exists it is known as the maximum-margin hyperplane/hard margin. So from the above figure, we choose L2.

Let's consider a scenario like shown below

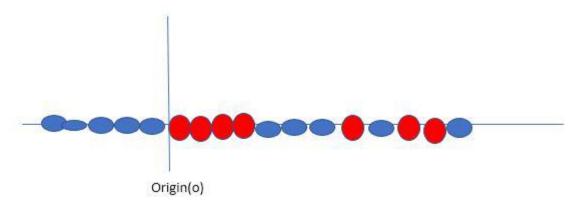


Here we have one blue ball in the boundary of the red ball. So how does SVM classify the data? It's simple! The blue ball in the boundary of red ones is an outlier of blue balls. The SVM algorithm has the characteristics to ignore the outlier and finds the best hyperplane that maximizes the margin. SVM is robust to outliers.

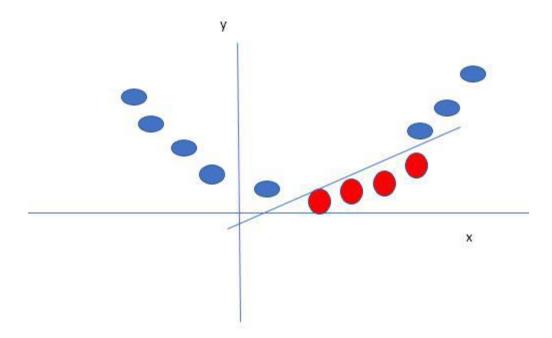


So in this type of data points what SVM does is, it finds maximum margin as done with previous data sets along with that it adds a penalty each time a point crosses the margin. So the margins in these type of cases are called soft margin.

Till now, we were talking about linearly separable data(the group of blue balls and red balls are separable by a straight line/linear line). What to do if data are not linearly separable?



Say, our data is like shown in the figure above.SVM solves this by creating a new variable using a kernel. We call a point x_i on the line and we create a new variable y_i as a function of distance from origin o.so if we plot this we get something like as shown below



In this case, the new variable y is created as a function of distance from the origin. A non-linear function that creates a new variable is referred to as kernel.

SVM Kernel:

The SVM kernel is a function that takes low dimensional input space and transforms it into higher-dimensional space, ie it converts non separable problem to separable problem. It is mostly useful in non-linear separation problems. Simply put the kernel, it does some extremely complex data transformations then finds out the process to separate the data based on the labels or outputs defined.

Advantages of SVM:

Effective in high dimensional cases

- Its memory efficient as it uses a subset of training points in the decision function called support vectors
- Different kernel functions can be specified for the decision functions and its possible to specify custom kernels

Multiclass classification

In <u>machine learning</u> and <u>statistical classification</u>, **multiclass classification** or **multinomial classification** is the problem of classifying instances into one of three or more classes (classifying instances into one of two classes is called binary classification).

While many classification algorithms (notably <u>multinomial logistic regression</u>) naturally permit the use of more than two classes, some are by nature <u>binary</u> algorithms; these can, however, be turned into multinomial classifiers by a variety of strategies.

Multiclass classification should not be confused with <u>multi-label classification</u>, where multiple labels are to be predicted for each instance.

The existing multi-class classification techniques can be categorized into (i) transformation to binary (ii) extension from binary and (iii) hierarchical classification.

Transformation to binary

This section discusses strategies for reducing the problem of multiclass classification to multiple binary classification problems. It can be categorized into *one vs rest* and *one vs one*. The techniques developed based on reducing the multi-class problem into multiple binary problems can also be called problem transformation techniques.

One-vs.-rest

One-vs.-rest (OvR or one-vs.-all, OvA or one-against-all, OAA) strategy involves training a single classifier per class, with the samples of that class as positive samples and all other samples as negatives. This strategy requires the base classifiers to produce a real-valued confidence score for its decision, rather than just a class label; discrete class labels alone can lead to ambiguities, where multiple classes are predicted for a single sample.

One-vs.-one

n the *one-vs.-one* (OvO) reduction, one trains K(K-1) / 2 binary classifiers for a K-way multiclass problem; each receives the samples of a pair of classes from the original training set, and must learn to distinguish these two classes. At prediction time, a voting scheme is applied: all K(K-1) / 2 classifiers are applied to an unseen sample and the class that got the highest number of "+1" predictions gets predicted by the combined classifier.

Like OvR, OvO suffers from ambiguities in that some regions of its input space may receive the same number of votes.

We have heard about classification and regression techniques in <u>machine learning</u>. We know that these two techniques work on different algorithms for discrete and continuous data respectively. In this article, we will learn more about classification. If we dig deeper into

classification, we deal with two types of target variables, binary class, and multi-class target variables.

Binary, as the name suggests, has two categories in the dependent column. Multiclass refers to columns with more than two categories in it.

You will get answers to all the questions that might cross your mind while reading this article, such as:

- 1. What is multiclass classification?
- 2. Which classifiers do we use in multiclass classification?
- 3. How and when do we use these classifiers?
- 4. Is multiclass and multi-label classification similar?

What is multiclass classification?

Classification means categorizing data and forming groups based on the similarities. In a dataset, the independent variables or features play a vital role in classifying our data. When we talk about multiclass classification, we have more than two classes in our dependent or target variable, as can be seen in Fig.1:

Species	PetalWidthCm	PetalLengthCm	SepalWidthCm	SepalLengthCm
Iris-virginica	2.3	5.9	3.2	6.8
Iris-virginica	2.3	5.1	3.1	6.9
Iris-setosa	0.2	1.4	3.0	4.9
Iris-versicolor	1.5	4.5	3.0	5.6
Iris-setosa	0.2	1.6	3.1	4.8
Iris-virginica	2.4	5.1	2.8	5.8
Iris-virginica	2.5	6.1	3.6	7.2
Iris-setosa	0.3	1.4	3.5	5.1
Iris-setosa	0.2	1.6	3.2	4.7
Iris-versicolor	1.4	4.4	3.0	6.6

Fig.1: Iris dataset having three categories

The above picture is taken from the Iris dataset which depicts that the target variable has three categories i.e., Virginica, setosa, and Versicolor, which are three species of Iris plant. We might use this dataset later, as an example of a conceptual understanding of multiclass classification.

Which classifiers do we use in multiclass classification? When do we use them?

We use many algorithms such as Naïve Bayes, <u>Decision trees</u>, SVM, Random forest classifier, KNN, and <u>logistic regression</u> for classification. But we might learn about only a few of them here because our motive is to understand multiclass classification. So, using a few algorithms we will try to cover almost all the relevant concepts related to multiclass classification.