

COLLEGE OF ENGINEERING



ECE 599 / CS 519 - SPRING 2015

Failure Detector Properties ...

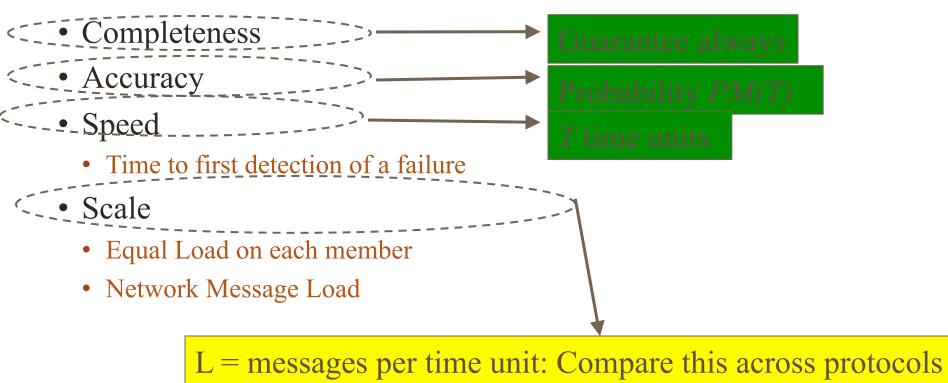
- Completeness
- Accuracy
- Speed
 - Time to first detection of a failure
- Scale
 - Equal Load on each member
 - Network Message Load

...Are application-defined Requirements

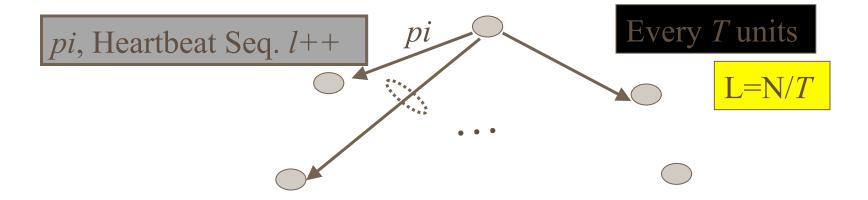
- Completeness
 Accuracy
 Speed

 Guarantee always
 Probability PM(T)
 Time units
 - Time to first detection of a failure
- Scale
 - Equal Load on each member
 - Network Message Load

...Are application-defined Requirements



All-to-All Heartbeating

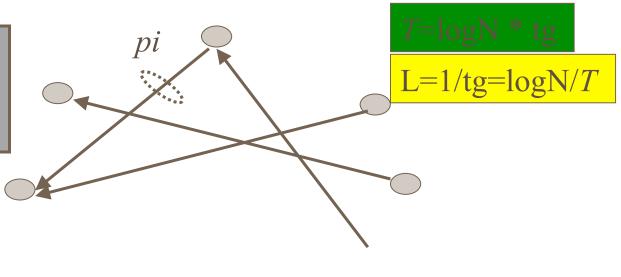


Gossip-style Heartbeating

Array of Heartbeat Seq. *l* for member subset

Every tg units

=gossip period,
send O(N) gossip
message



What's the Best/Optimal we can do?

- Worst case load L* per member in the group (messages per time unit)
 - as a function of T, PM(T), N
 - Independent Message Loss probability p_{ml}

$$L^* = \frac{\log(PM(T))}{\log(p_{ml})} \cdot \frac{1}{T}$$

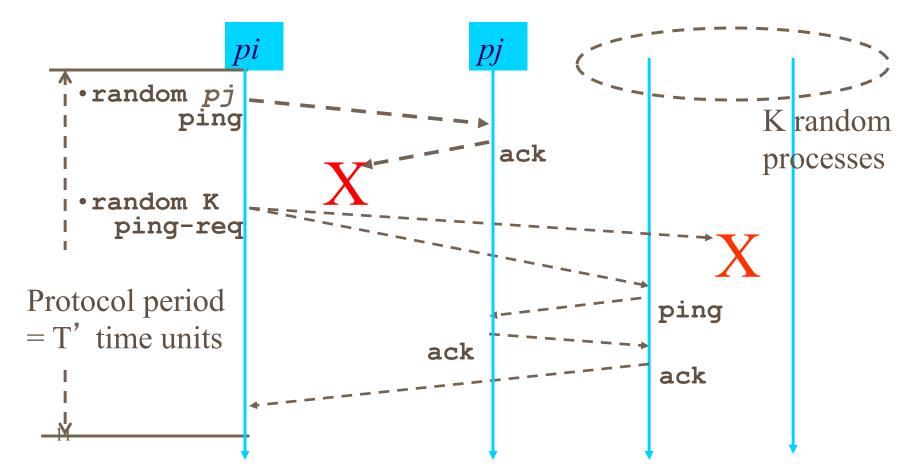
Heartbeating

- Optimal L is independent of N (!)
- All-to-all and gossip-based: sub-optimal
 - L=O(N/T)
 - try to achieve simultaneous detection at *all* processes
 - fail to distinguish Failure Detection and Dissemination components
 - ⇒Key:
 - Separate the two components
 - Use a non heartbeat-based Failure Detection Component

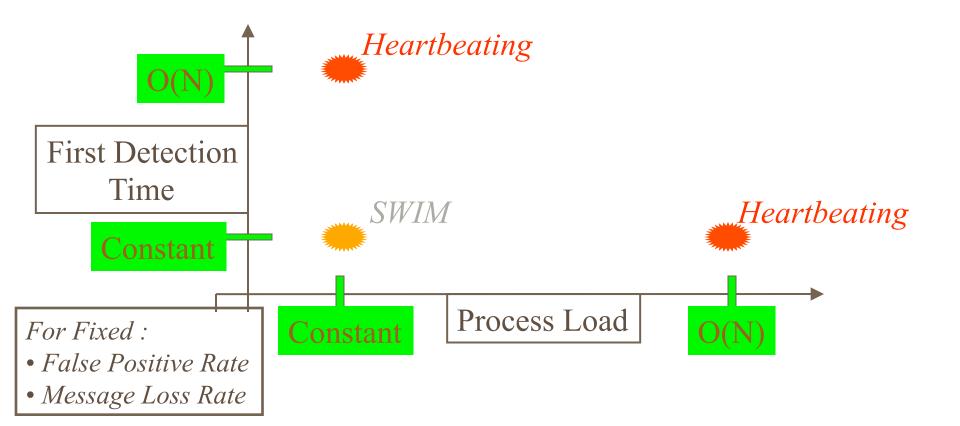
Next

• Is there a better failure detector?

SWIM Failure Detector Protocol



SWIM versus Heartbeating



SWIM Failure Detector

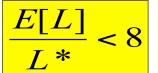
Parameter	SWIM
First Detection Time	• Expected $\left[\frac{e}{e-1}\right]$ periods • Constant (independent of group size)
Process Load	• Constant per period • < 8 L* for 15% loss
False Positive Rate	Tunable (via K)Falls exponentially as load is scaled
Completeness	 Deterministic time-bounded Within O(log(N)) periods w.h.p.

Accuracy, Load

PM(T) is exponential in -K. Also depends on pml (and pf)

See paper

$$\frac{L}{L^*} < 28$$



for up to 15 % loss rates

Detection Time

Prob. of being pinged in T'=
$$1 - (1 - \frac{1}{N})^{N-1} = 1 - e^{-1}$$

$$E[T] = T' \cdot \frac{e}{e-1}$$

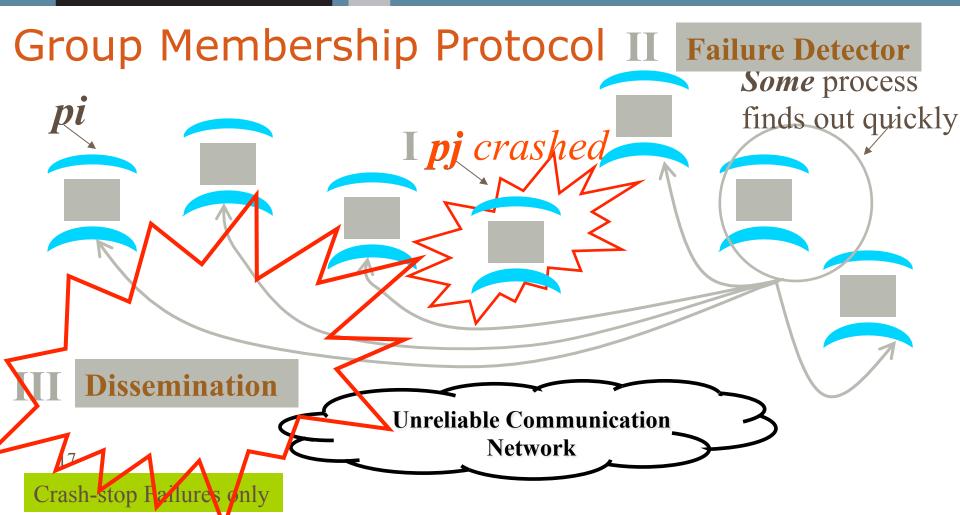
Completeness: Any alive member detects failure

- Eventually
- By using a trick: within worst case O(N) protocol periods

Next

• How do failure detectors fit into the big picture of a group membership protocol?

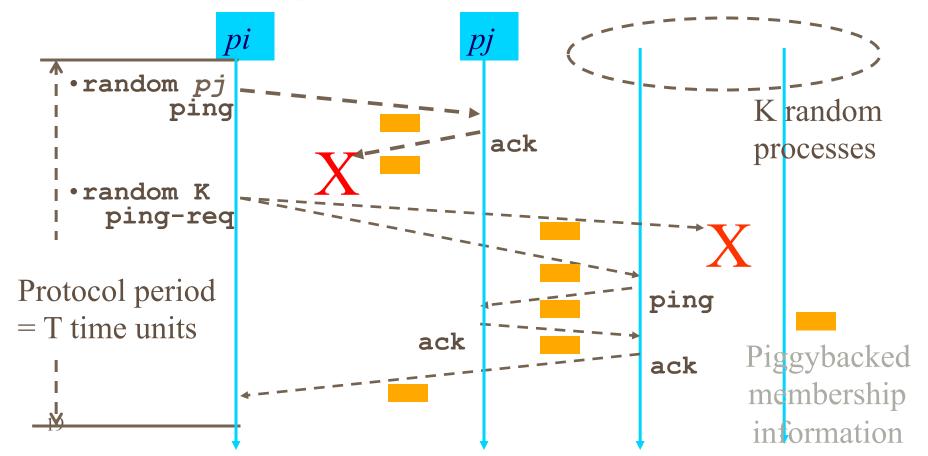
• What are the missing blocks?



Dissemination Options

- Multicast (Hardware / IP)
 - unreliable
 - multiple simultaneous multicasts
- Point-to-point (TCP / UDP)
 - expensive
- Zero extra messages: Piggyback on Failure Detector messages
 - Infection-style Dissemination

Infection-style Dissemination



Infection-style Dissemination

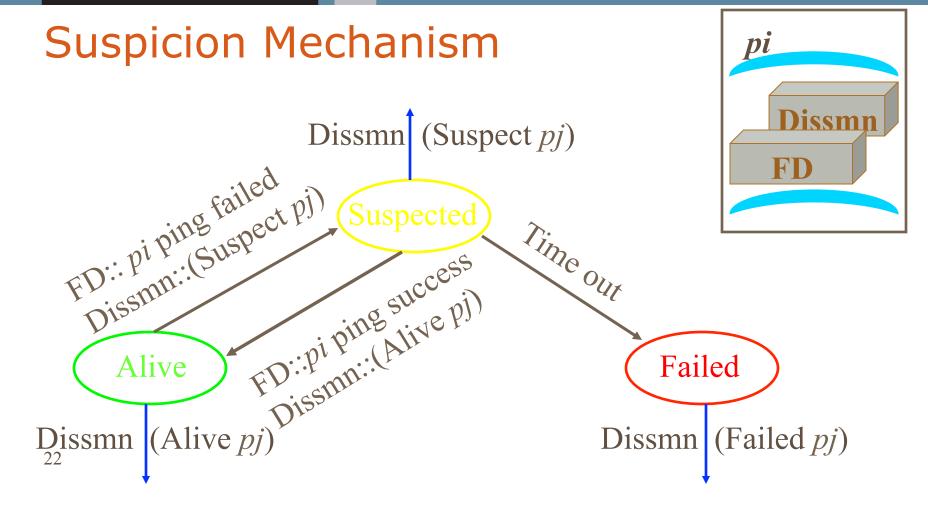
- Epidemic/Gossip style dissemination
 - After $\lambda . \log(N)$ protocol periods, $N^{-(2\lambda-2)}$ processes would not have heard about an update
- Maintain a buffer of recently joined/evicted processes
 - Piggyback from this buffer
 - Prefer recent updates
- Buffer elements are garbage collected after a while
 - After $\lambda . \log(N)$ protocol periods, i.e., once they've propagated through the system; this defines weak consistency

Suspicion Mechanism

- False detections, due to
 - Perturbed processes
 - Packet losses, e.g., from congestion

• Indirect pinging may not solve the problem

• Key: *suspect* a process before *declaring* it as failed in the group



Suspicion Mechanism

- Distinguish multiple suspicions of a process
 - Per-process incarnation number
 - *Inc* # for *pi* can be incremented only by *pi*
 - e.g., when it receives a (Suspect, *pi*) message
 - Somewhat similar to DSDV

- Higher inc# notifications over-ride lower inc#'s
- Within an inc#: (Suspect inc #) > (Alive, inc #)
- (Failed, inc #) overrides everything else

Wrap Up

- Failures the norm, not the exception in datacenters
- Every distributed system uses a failure detector
- Many distributed systems use a membership service
- Ring failure detection underlies
 - IBM SP2 and many other similar clusters/machines
- Gossip-style failure detection underlies
 - Amazon EC2/S3 (rumored!)