VIP Refresher: Linear Algebra

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Matrix notations

□ **Vector** – We note $x \in \mathbb{R}^n$ a vector with n entries, where $x_i \in \mathbb{R}$ is the i^{th} entry:

$$x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n$$

□ Matrix – We note $A \in \mathbb{R}^{m \times n}$ a matrix with n rows and m, where $a_{i,j} \in \mathbb{R}$ is the entry located in the i^{th} row and j^{th} column:

$$A = \begin{pmatrix} a_{1,1} & \cdots & a_{1,n} \\ \vdots & & \vdots \\ a_{m,1} & \cdots & a_{m,n} \end{pmatrix} \in \mathbb{R}^{m \times n}$$

Remark: the vector x defined above can be viewed as a $n \times 1$ matrix and is more particularly called a column-vector.

□ Matrix-vector multiplication – The product of matrix $A \in \mathbb{R}^{m \times n}$ and vector $x \in \mathbb{R}^n$ is a vector of size \mathbb{R}^n , such that:

$$Ax = \begin{pmatrix} \sum_{j=1}^{n} a_{1,j} x_j \\ \vdots \\ \sum_{j=1}^{n} a_{m,j} x_j \end{pmatrix} \in \mathbb{R}^m$$

□ System of equations – The system of equations

$$\begin{cases} y_1 &= a_{1,1}x_1 + a_{1,2}x_2 + \ldots + a_{1,n}x_n \\ y_2 &= a_{2,1}x_1 + a_{2,2}x_2 + \ldots + a_{2,n}x_n \\ \vdots \\ y_m &= a_{m,1}x_1 + a_{m,2}x_2 + \ldots + a_{m,n}x_n \end{cases}$$

can be rewritten in matrix form y = Ax with $y \in \mathbb{R}^m, A \in \mathbb{R}^{m \times n}$ and $x \in \mathbb{R}^n$.

Determinant

□ Definition – The determinant of a square matrix $A \in \mathbb{R}^{n \times n}$, noted |A| or $\det(A)$ is expressed recursively in terms of $A_{\backslash i,\backslash j}$, which is the matrix A without its i^{th} row and j^{th} column, as follows:

$$\det(A) = |A| = \sum_{j=1}^{n} (-1)^{i+j} a_{i,j} |A_{\langle i, \backslash j |}|$$

Remark: A is invertible if and only if $|A| \neq 0$. Also, |AB| = |A||B| and $|A^T| = |A|$.

 \Box Characteristic equation – The characteristic equation of a linear system of n equations represented by A is given by:

$$\det(A - \lambda I) = 0$$

For n = 2, this equation can be written as:

$$\lambda^2 - (a_{11} + a_{22})\lambda + (a_{11}a_{22} - a_{12}a_{21}) = 0$$

□ Eigenvector, eigenvalue – The roots λ of the characteristic equation are the eigenvalues of A. The solutions \vec{v} of the equation $A\vec{v} = \lambda I$ are called the eigenvectors associated with the eigenvalue λ .

☐ Computing the determinant in particular cases – We have the following cases:

– For a 2 × 2 matrix – The determinant of a given matrix $A \in \mathbb{R}^{2 \times 2} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ can be computed as follows:

$$\det(A) = ad - bc$$

– For a 3×3 matrix – The determinant of a given matrix $A\in\mathbb{R}^{3\times 3}=\begin{pmatrix}a&b&c\\d&e&f\\g&h&i\end{pmatrix}$ can be computed as follows:

$$det(A) = a(ei - fh) - b(di - fg) + c(dh - eg)$$

Partial fractions

□ Concept – A fraction $\frac{P(x)}{Q(x)}$ with P and Q polynomial functions of x and $\deg(P) < \deg(Q)$ can be decomposed into partial fractions by distinguishing the types of roots that are in the factorized form of Q(x), as detailed in the table below:

I	Factor of $Q(x)$	Type of root	Associated partial fraction
	$(x-a)^n$	Real root of multiplicity $n \geqslant 1$	$\frac{A_1}{x-a} + \dots + \frac{A_n}{(x-a)^n}$
($(ax^2 + bx + c)^n$	Complex roots of multiplicity $n \geqslant 1$	$\frac{A_1x + B_1}{ax^2 + bx + c} + \dots + \frac{A_nx + B_n}{(ax^2 + bx + c)^n}$