Open Session

General workflow

1) Given a dataset

$$D = \begin{bmatrix} 1 & 0 & 3 & 2 & -5 \\ 2 & -1 & -5 & 4 & 3 \end{bmatrix}$$

Five different data-points in \mathbb{R}^2 .

- n = 5, d = 2
- 2) Centering the dataset

$$\boldsymbol{\mu} = \frac{1}{5} \sum_{i=1}^{5} \mathbf{x}_i = \frac{1}{5} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} + \begin{bmatrix} 0 \\ -1 \end{bmatrix} + \begin{bmatrix} 3 \\ -5 \end{bmatrix} + \begin{bmatrix} 2 \\ 4 \end{bmatrix} + \begin{bmatrix} -5 \\ 3 \end{bmatrix} \right\} = \frac{1}{5} \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 0.2 \\ 0.6 \end{bmatrix}$$

$$\mathbf{X} = \begin{bmatrix} 0.8 & -0.2 & 2.8 & 1.8 & -5.2 \\ 1.4 & -1.6 & -5.6 & 3.4 & 2.4 \end{bmatrix}$$

3) Covariance matrix

$$\mathbf{C} = \frac{1}{5} \cdot \sum_{i=1}^{5} \mathbf{x}_{i} \mathbf{x}_{i}^{T} = \begin{bmatrix} 0.8 \\ 1.4 \end{bmatrix} \begin{bmatrix} 0.8 & 1.4 \end{bmatrix} = \begin{bmatrix} 0.8 \times 0.8 & 0.8 \times 1.4 \\ 1.4 \times 0.8 & 1.4 \times 1.4 \end{bmatrix} + \dots$$

$$= \begin{bmatrix} 7.76 & -4.12 \\ -4.12 & 10.64 \end{bmatrix}$$

Checks:

Symmetric

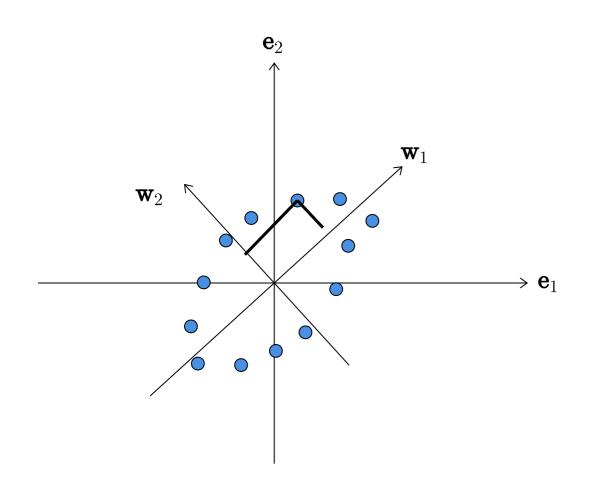
- *d* × *d*
- 4) Find the principal components \rightarrow eigenvectors of C

$$\lambda_1 = 13.56, \ \lambda_2 = 4.84$$

$$\mathbf{w}_1 = \begin{bmatrix} -0.58\\0.82 \end{bmatrix}, \ \mathbf{w}_2 = \begin{bmatrix} -0.82\\-0.58 \end{bmatrix}$$

Checks:

- Orthogonality
- Unit norm
- Eigenvector-eigenvalue
- 5) Select the value of \boldsymbol{k}



$$\mathbf{X} = \begin{bmatrix} | & & | \\ \mathbf{x}_1 & \cdots & \mathbf{x}_n \\ | & | \end{bmatrix}$$
 $\mathbf{C} = \frac{1}{n} \mathbf{X} \mathbf{X}^T$

$$\mathbf{C} = \frac{1}{n} \mathbf{X} \mathbf{X}^T$$

$$\mathbf{C} = \mathbf{Q} \mathbf{D} \mathbf{Q}^T$$

$$\mathbf{Y} = \mathbf{Q}^T \mathbf{X}$$

$$\mathbf{Q} = \left[egin{array}{ccc} ert & ert \ \mathbf{w}_1 & \mathbf{w}_2 \ ert & ert \end{array}
ight]$$

$$\mathbf{Q}^T\mathbf{Q} = \mathbf{I}$$

$$\mathbf{Y} = \mathbf{Q}^{T} \mathbf{X}$$

$$= \begin{bmatrix} -\mathbf{w}_{1}^{T} & - \end{bmatrix} \begin{bmatrix} \mathbf{x}_{1} & \cdots & \mathbf{x}_{n} \\ \mathbf{x}_{1} & \cdots & \mathbf{x}_{n} \end{bmatrix}$$

$$= \begin{bmatrix} \mathbf{w}_{1}^{T} \mathbf{x}_{1} & \cdots & \mathbf{w}_{1}^{T} \mathbf{x}_{n} \\ \mathbf{w}_{2}^{T} \mathbf{x}_{1} & \cdots & \mathbf{w}_{2}^{T} \mathbf{x}_{n} \end{bmatrix}$$

$$\mathbf{x}_{i} = (\mathbf{x}_{i}^{T} \mathbf{w}_{1}) \mathbf{w}_{1} + (\mathbf{x}_{i}^{T} \mathbf{w}_{2}) \mathbf{w}_{2}$$

$$\mathbf{x}_i = \left(\mathbf{x}_i^T \mathbf{w}_1\right) \mathbf{w}_1 + \left(\mathbf{x}_i^T \mathbf{w}_2\right) \mathbf{w}_2$$