

PCA

MLT

Karthik Thiagarajan

Learning Representations

"Learning from data"

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Documentary

- Collect Data
 - Interview people
 - * 50 people
 - * 10 hourss

Learning Representations

"Learning from data"

Documentary

- Collect Data
 - Interview people
 - * 50 people
 - * 10 hourss
- Create documentary
 - 2 hours

Learning Representations

"Learning from data"

Documentary

- Collect Data
 - Interview people
 - * 50 people
 - * 10 hourss
- Create documentary
 - 2 hours
 - Editing

Learning Representations

"Learning from data"

Documentary

- Collect Data
 - Interview people
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 - * 10 hourss
- Create documentary
 - 2 hours
 - Editing
 - * choose people
 - * choose key moments
 - * weave it into a narrative
 - * capture all important dimensions
 - * "essence"

Learning Representations

"Learning from data"

Documentary

- Collect Data
 - Interview people
 - * 50 people
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Themes

- Compression
- Representation
- Reconstruction

Learning Representations

"Learning from data"

Documentary

- Collect Data
 - Interview people
 - * 50 people
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$$\{\mathbf{x}_1, \dots, \mathbf{x}_n\} \xrightarrow[\text{editing}]{\text{PCA}} \{\mathbf{x}_1^{(r)}, \dots, \mathbf{x}_n^{(r)}\}$$

Themes

- Compression
- Representation
- Reconstruction

Good Representations

$$\{\mathbf{x}_1, \dots, \mathbf{x}_n\} \rightarrow \{\mathbf{x}_1^{(r)}, \dots, \mathbf{x}_n^{(r)}\}$$

Good Representations

$$\{\mathbf{x}_1, \dots, \mathbf{x}_n\} \rightarrow \{\mathbf{x}_1^{(r)}, \dots, \mathbf{x}_n^{(r)}\}$$

$$\frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{x}_i^{(r)}\|^2$$

Good Representations

$$\{\mathbf{x}_1, \dots, \mathbf{x}_n\} \rightarrow \{\mathbf{x}_1^{(r)}, \dots, \mathbf{x}_n^{(r)}\}$$

$$\min_{\{\mathbf{x}_i^{(r)}\}_{i=1}^n} \frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{x}_i^{(r)}\|^2$$

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Good Representations

$$\{\mathbf{x}_1, \dots, \mathbf{x}_n\} \rightarrow \{\mathbf{x}_1^{(r)}, \dots, \mathbf{x}_n^{(r)}\}$$

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$$\frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{x}_i^{(r)}\|^2$$

$$\mathbf{x}_i^{(r)} = \mathbf{x}_i$$

Good Representations

$$\{\mathbf{x}_1, \dots, \mathbf{x}_n\} \rightarrow \{\mathbf{x}_1^{(r)}, \dots, \mathbf{x}_n^{(r)}\}$$

$$\min_{\{\mathbf{x}_i^{(r)}\}_{i=1}^n} \frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{x}_i^{(r)}\|^2$$

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$$\mathbf{x}_i^{(r)} = \mathbf{x}_i$$

Constraint: Compression

Good Representations

"Freedom without discipline is chaos"

$$\{\mathbf{x}_1, \dots, \mathbf{x}_n\} \rightarrow \{\mathbf{x}_1^{(r)}, \dots, \mathbf{x}_n^{(r)}\}$$

$$\min_{\{\mathbf{x}_i^{(r)}\}_{i=1}^n} \frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{x}_i^{(r)}\|^2$$

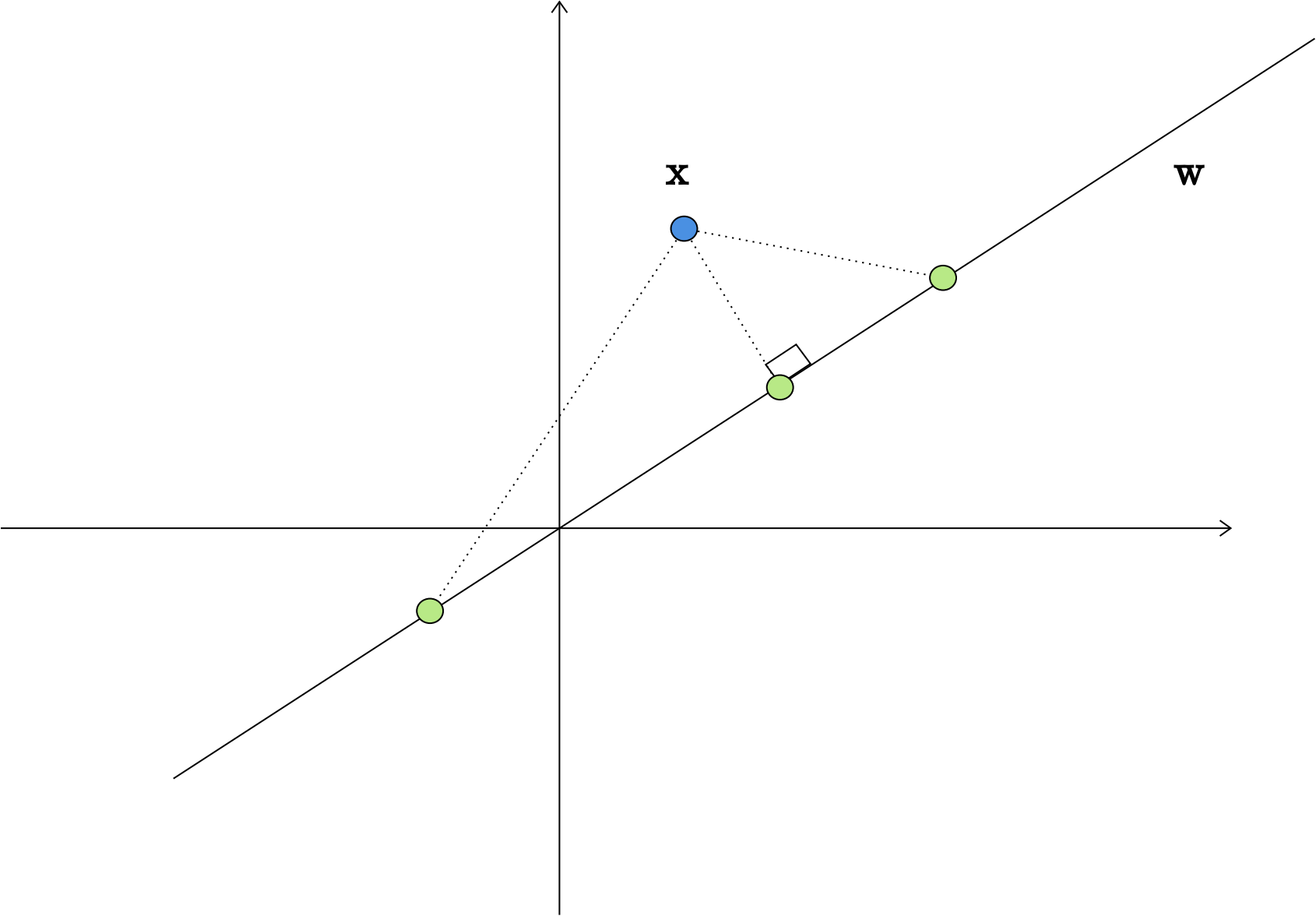
$$\frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{x}_i^{(r)}\|^2$$

$$\mathbf{x}_i^{(r)} = \mathbf{x}_i$$

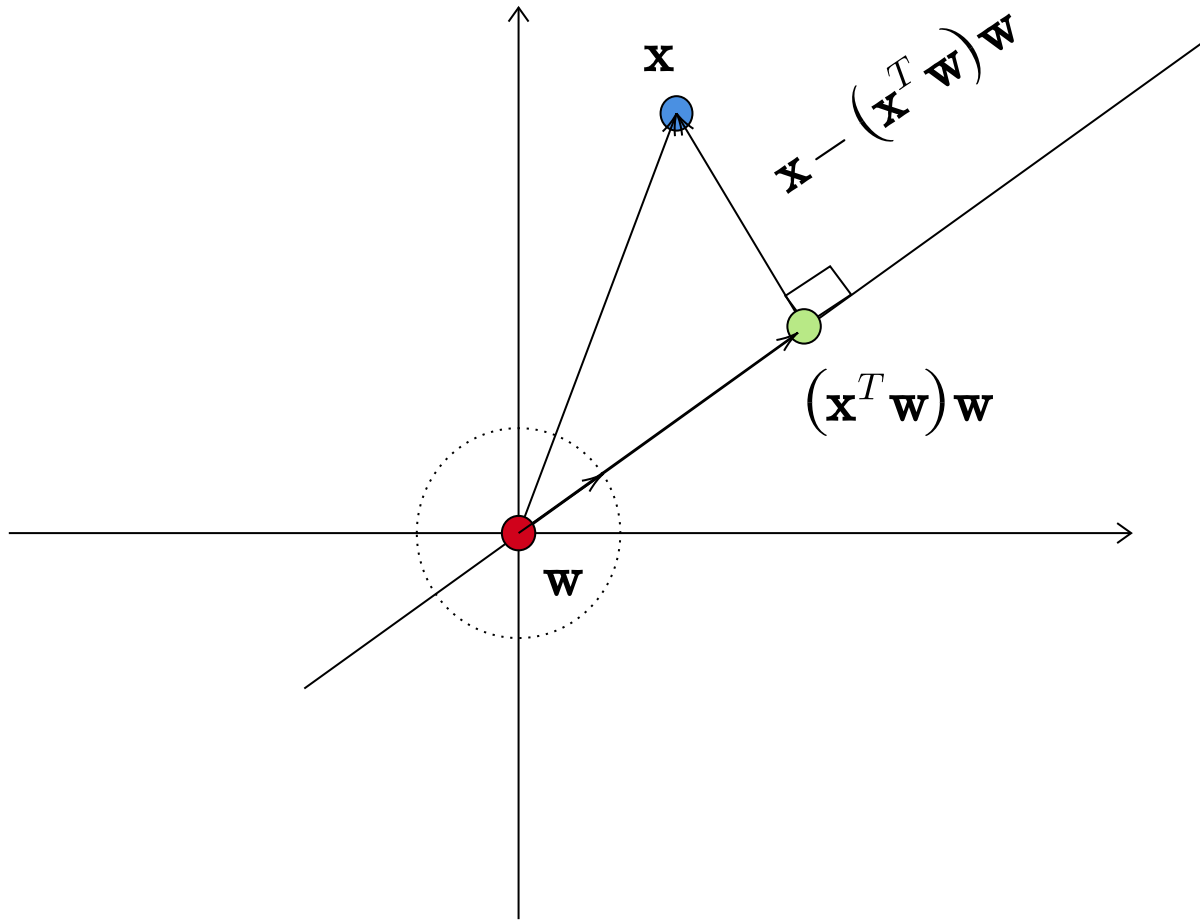
Constraint: Compression

$$\mathbf{x}_i^{(r)} = \alpha_i \mathbf{w}$$

Best Proxy



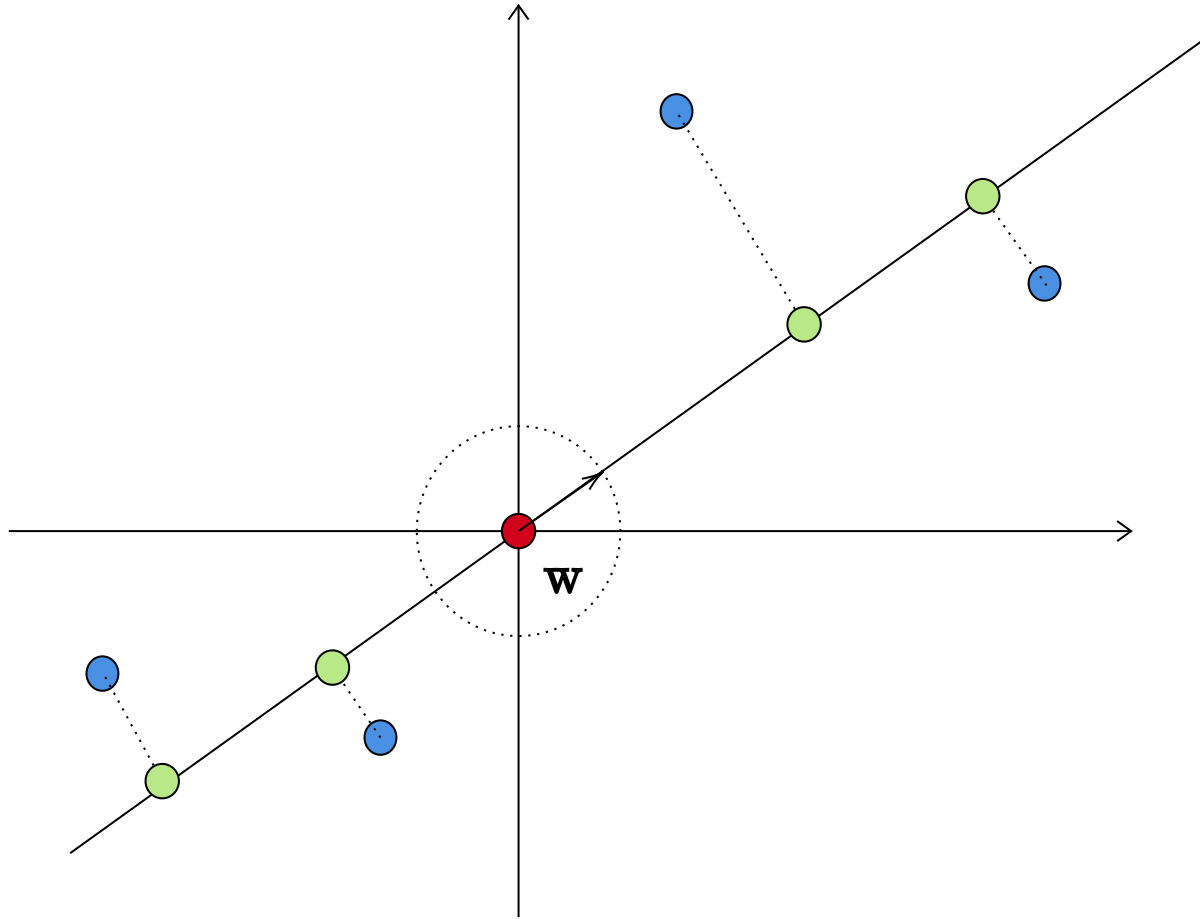
Best Proxy



$$\|\mathbf{w}\| = 1$$

$$\|\mathbf{x} - (\mathbf{x}^T \mathbf{w}) \mathbf{w}\|^2$$

Average Error

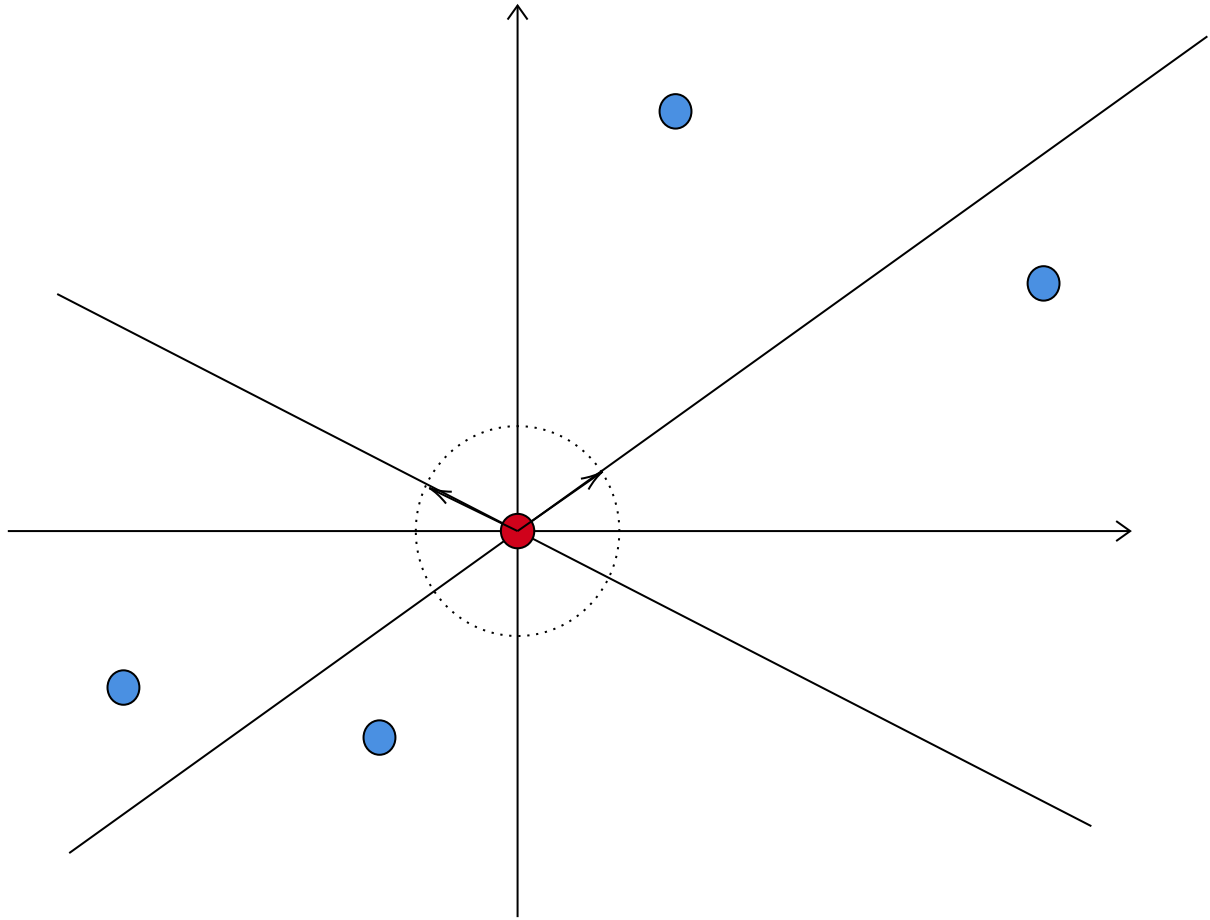


$$||\mathbf{w}'|| = 1$$

Average Error

$$\frac{1}{n} \cdot \sum_{i=1}^n ||\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}') \mathbf{w}'||^2$$

Error Minimization



$$\|\mathbf{w}\| = 1$$

$$\min_{\mathbf{w}, \|\mathbf{w}\|=1} \frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}\|^2$$

Error Minimization (algebra)

$$\min_{\mathbf{w}, \|\mathbf{w}\|=1} \frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}\|^2$$

$$\|\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}\|^2 =$$

Error Minimization (algebra)

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$$\|\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}\|^2 = \left(\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w} \right)^T \left(\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w} \right)$$

$$\|\mathbf{v}\|^2 = \mathbf{v}^T \mathbf{v}$$

Error Minimization (algebra)

$$\min_{\mathbf{w}, \|\mathbf{w}\|=1} \quad \frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}\|^2$$

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$$= \mathbf{x}_i^T \mathbf{x}_i - \left(\mathbf{x}_i^T \mathbf{w} \right) \left(\mathbf{x}_i^T \mathbf{w} \right) - \left(\mathbf{x}_i^T \mathbf{w} \right) \left(\mathbf{w}^T \mathbf{x}_i \right) + \left(\mathbf{x}_i^T \mathbf{w} \right)^2 \left(\mathbf{w}^T \mathbf{w} \right)$$

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$$= \mathbf{x}_i^T \mathbf{x}_i - \left(\mathbf{x}_i^T \mathbf{w} \right)^2$$

$$\|\mathbf{v}\|^2 = \mathbf{v}^T \mathbf{v}$$

$$\mathbf{x}_i^T \mathbf{w} = \mathbf{w}^T \mathbf{x}_i$$

$$\mathbf{w}^T \mathbf{w} = 1$$

Error Minimization (algebra)

$$\min_{\mathbf{w}, \|\mathbf{w}\|=1} \quad \frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}\|^2$$

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Error Minimization (algebra)

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Journey from min to max

$$\min_{\mathbf{w}, ||\mathbf{w}||=1} \quad \frac{1}{n} \cdot \sum_{i=1}^n ||\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}||^2$$

Journey from min to max

$$\min_{\mathbf{w}, ||\mathbf{w}||=1} \frac{1}{n} \cdot \sum_{i=1}^n ||\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}||^2 \equiv \min_{\mathbf{w}, ||\mathbf{w}||=1} \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i^T \mathbf{x}_i - \left(\mathbf{x}_i^T \mathbf{w} \right)^2$$

Journey from min to max

$$\begin{aligned} \min_{\mathbf{w}, \|\mathbf{w}\|=1} \quad & \frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}\|^2 \quad \equiv \quad \min_{\mathbf{w}, \|\mathbf{w}\|=1} \quad \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i^T \mathbf{x}_i - \left(\mathbf{x}_i^T \mathbf{w}\right)^2 \\ & \equiv \quad \min_{\mathbf{w}, \|\mathbf{w}\|=1} \quad \frac{1}{n} \cdot \sum_{i=1}^n - \left(\mathbf{x}_i^T \mathbf{w}\right)^2 \end{aligned}$$

Journey from min to max

$$\begin{aligned} \min_{\mathbf{w}, \|\mathbf{w}\|=1} \quad & \frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}\|^2 \quad \equiv \quad \min_{\mathbf{w}, \|\mathbf{w}\|=1} \quad \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i^T \mathbf{x}_i - \left(\mathbf{x}_i^T \mathbf{w}\right)^2 \\ & \equiv \quad \min_{\mathbf{w}, \|\mathbf{w}\|=1} \quad \frac{1}{n} \cdot \sum_{i=1}^n - \left(\mathbf{x}_i^T \mathbf{w}\right)^2 \\ & \equiv \quad \max_{\mathbf{w}, \|\mathbf{w}\|=1} \quad \frac{1}{n} \cdot \sum_{i=1}^n \left(\mathbf{x}_i^T \mathbf{w}\right)^2 \end{aligned}$$

Journey from min to max

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Journey from min to max

$$\begin{aligned} \min_{\mathbf{w}, \|\mathbf{w}\|=1} \quad & \frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}\|^2 \quad \equiv \quad \min_{\mathbf{w}, \|\mathbf{w}\|=1} \quad \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i^T \mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w})^2 \\ & \equiv \quad \min_{\mathbf{w}, \|\mathbf{w}\|=1} \quad \frac{1}{n} \cdot \sum_{i=1}^n - (\mathbf{x}_i^T \mathbf{w})^2 \\ & \equiv \quad \max_{\mathbf{w}, \|\mathbf{w}\|=1} \quad \frac{1}{n} \cdot \sum_{i=1}^n (\mathbf{x}_i^T \mathbf{w})^2 \\ & \equiv \quad \max_{\mathbf{w}, \|\mathbf{w}\|=1} \quad \frac{1}{n} \cdot \sum_{i=1}^n (\mathbf{w}^T \mathbf{x}_i) (\mathbf{x}_i^T \mathbf{w}) \\ & \equiv \quad \max_{\mathbf{w}, \|\mathbf{w}\|=1} \quad \mathbf{w}^T \left[\frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^T \right] \mathbf{w} \end{aligned}$$

Journey from min to max

$$\min_{\mathbf{w}, \|\mathbf{w}\|=1} \frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}\|^2 \equiv \min_{\mathbf{w}, \|\mathbf{w}\|=1} \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i^T \mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w})^2$$

$$\equiv \min_{\mathbf{w}, \|\mathbf{w}\|=1} \frac{1}{n} \cdot \sum_{i=1}^n - (\mathbf{x}_i^T \mathbf{w})^2$$

$$\equiv \max_{\mathbf{w}, \|\mathbf{w}\|=1} \frac{1}{n} \cdot \sum_{i=1}^n (\mathbf{x}_i^T \mathbf{w})^2$$

$$\equiv \max_{\mathbf{w}, \|\mathbf{w}\|=1} \frac{1}{n} \cdot \sum_{i=1}^n (\mathbf{w}^T \mathbf{x}_i) (\mathbf{x}_i^T \mathbf{w})$$

$$\equiv \max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \left[\frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^T \right] \mathbf{w}$$

$$\equiv \boxed{\max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \mathbf{C} \mathbf{w}}$$

Covariance Matrix
(Centered Dataset)

$$\mathbf{C} = \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^T$$

Optimization Problem

$$\max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \mathbf{C} \mathbf{w}$$

$$\arg \max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \mathbf{C} \mathbf{w}$$

Optimization Problem

$$\max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \mathbf{C} \mathbf{w} = \lambda_1$$

$$\arg \max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \mathbf{C} \mathbf{w} = \mathbf{w}_1$$

Optimization Problem

$$\max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \mathbf{C} \mathbf{w} = \lambda_1$$

$$\arg \max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \mathbf{C} \mathbf{w} = \mathbf{w}_1$$

$$\mathbf{C} = \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^T$$

$$\lambda_1 \geq \dots \geq \lambda_d \geq 0$$

$$\mathbf{w}_1, \dots, \mathbf{w}_d$$

Optimization Problem

$$\max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \mathbf{C} \mathbf{w} = \lambda_1$$

$$\arg \max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \mathbf{C} \mathbf{w} = \mathbf{w}_1$$

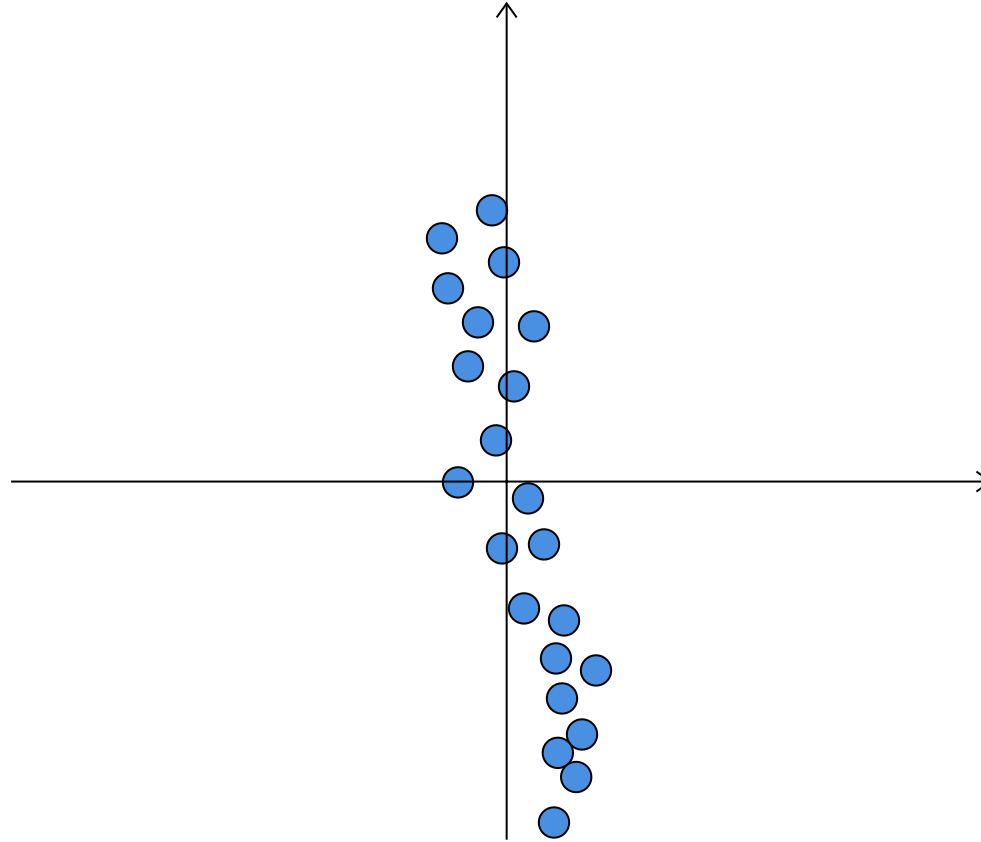
$$\mathbf{C} = \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^T$$

$$\lambda_1 \geq \dots \geq \lambda_d \geq 0$$

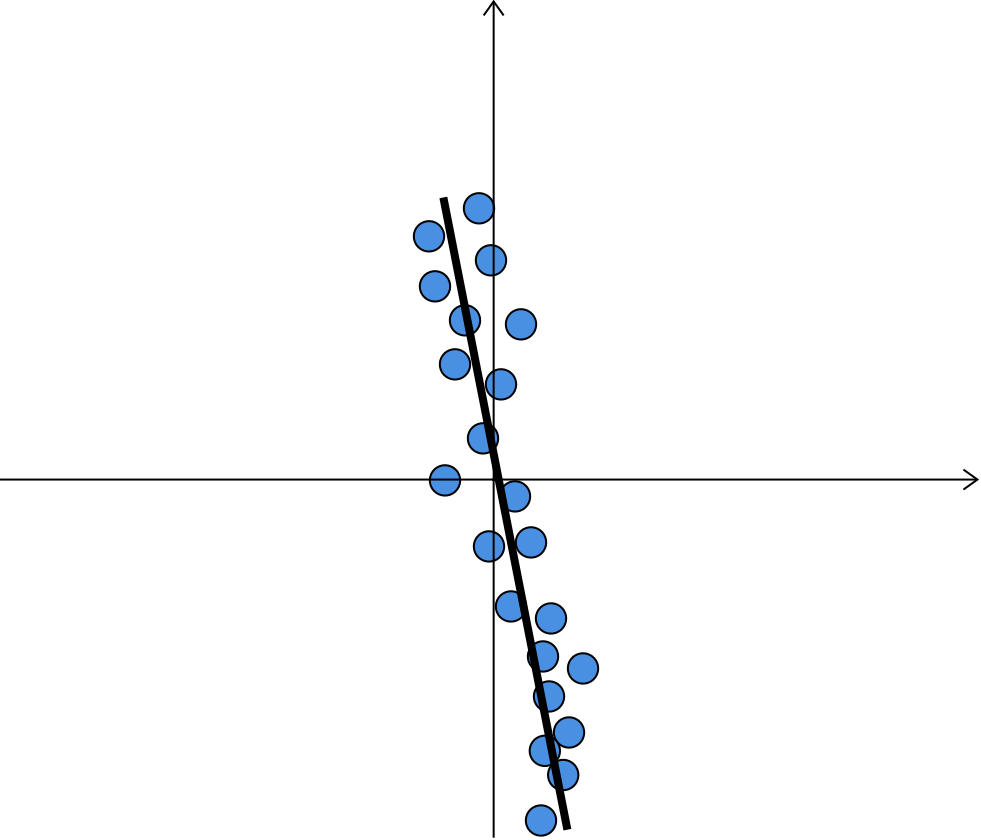
$$\mathbf{w}_1, \dots, \mathbf{w}_d$$

The direction that minimizes the reconstruction error is the eigenvector corresponding to the largest eigenvalue of the covariance matrix.

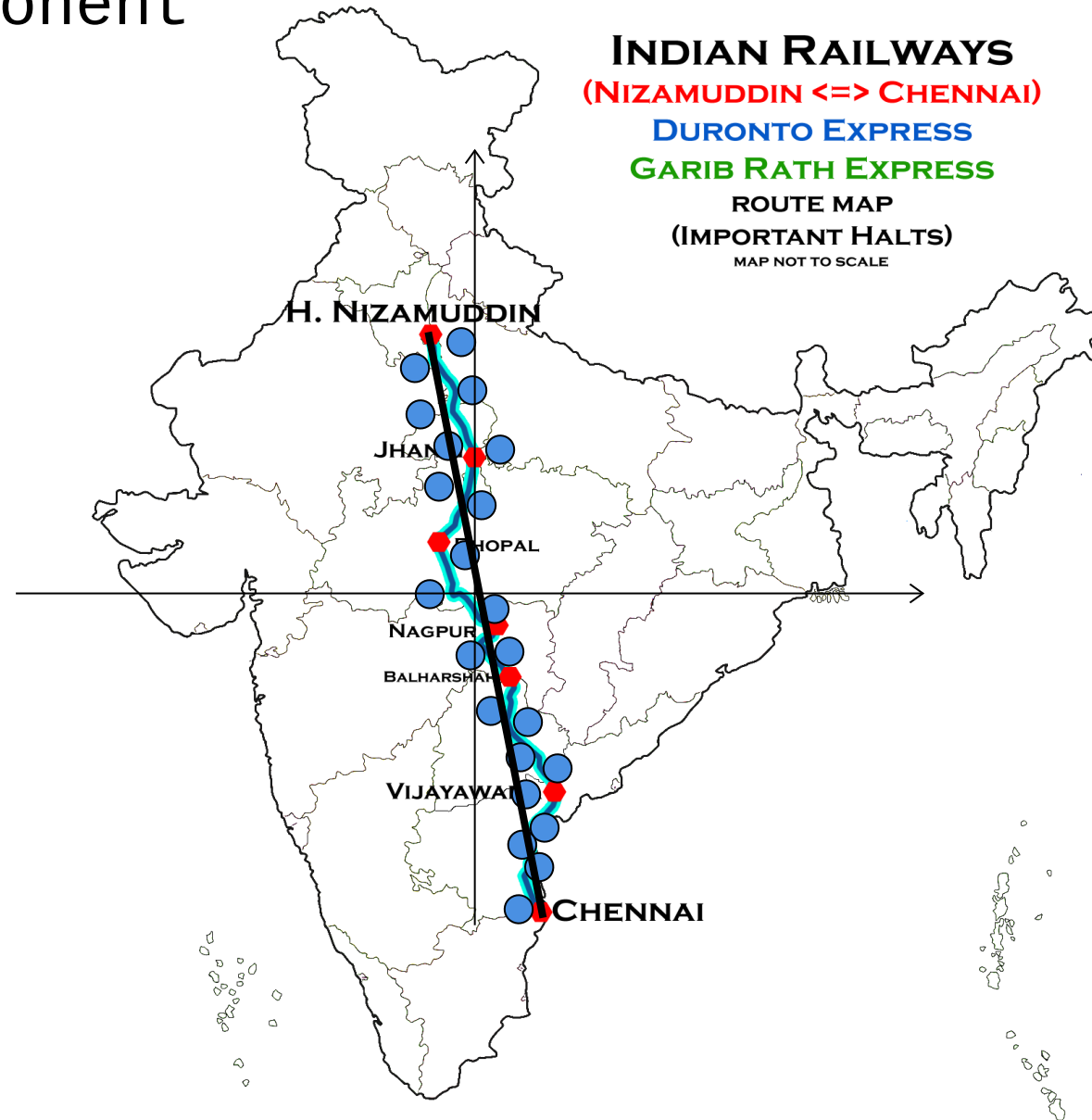
First Principal Component



First Principal Component

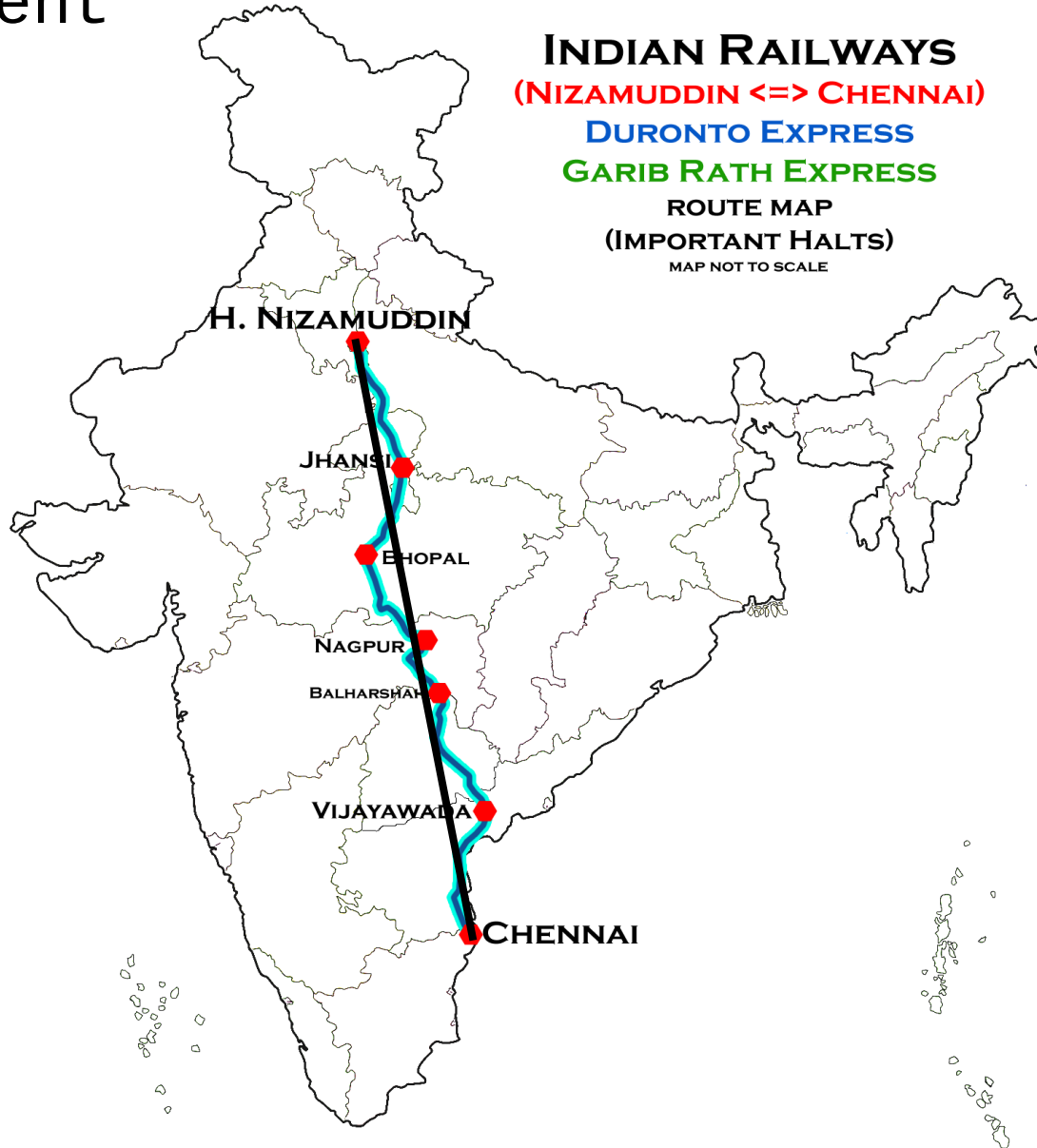


First Principal Component



[Image Credits](#)

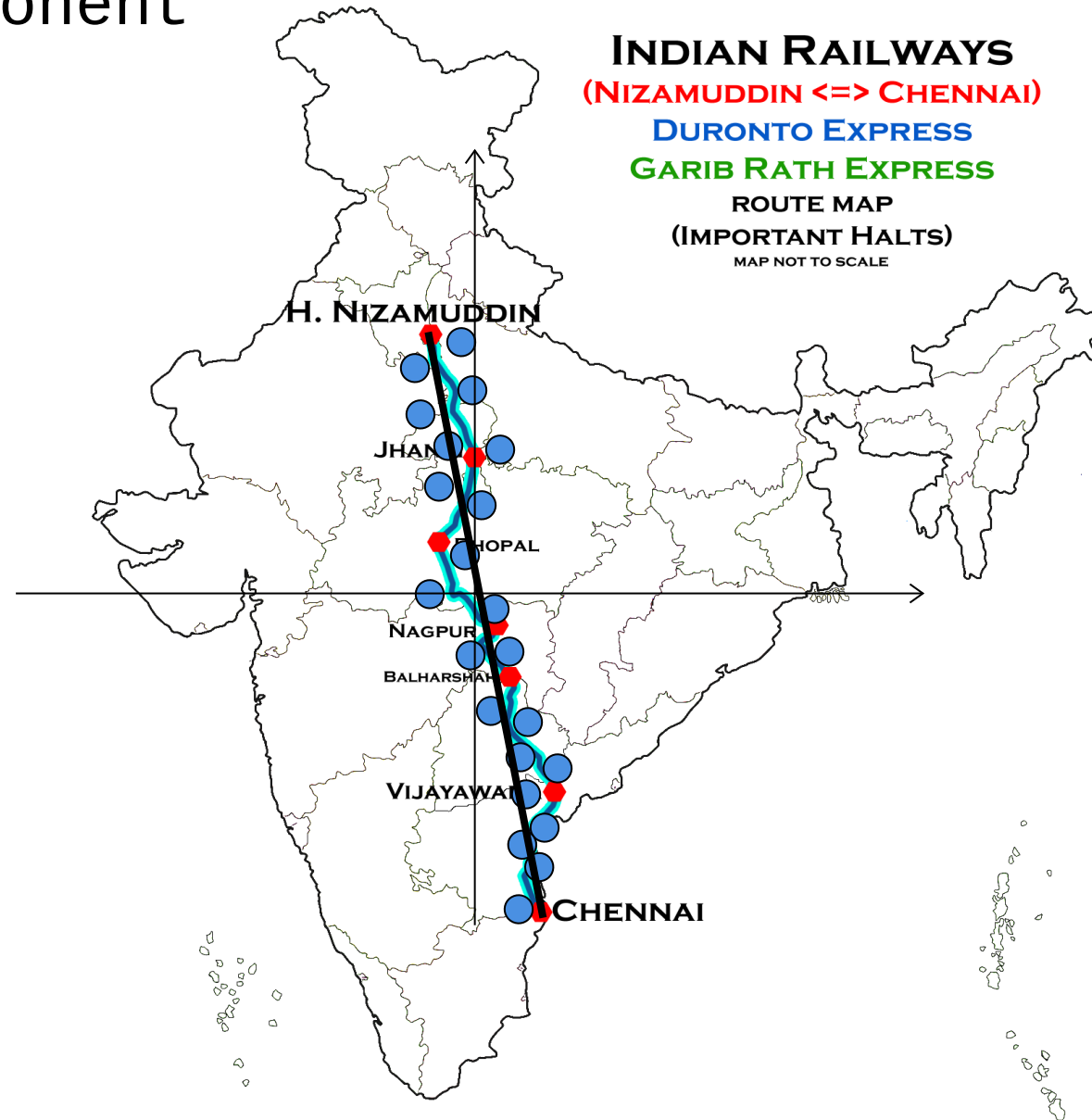
First Principal Component



[Image Credits](#)

First Principal Component

Chennai-Delhi Garib Rath

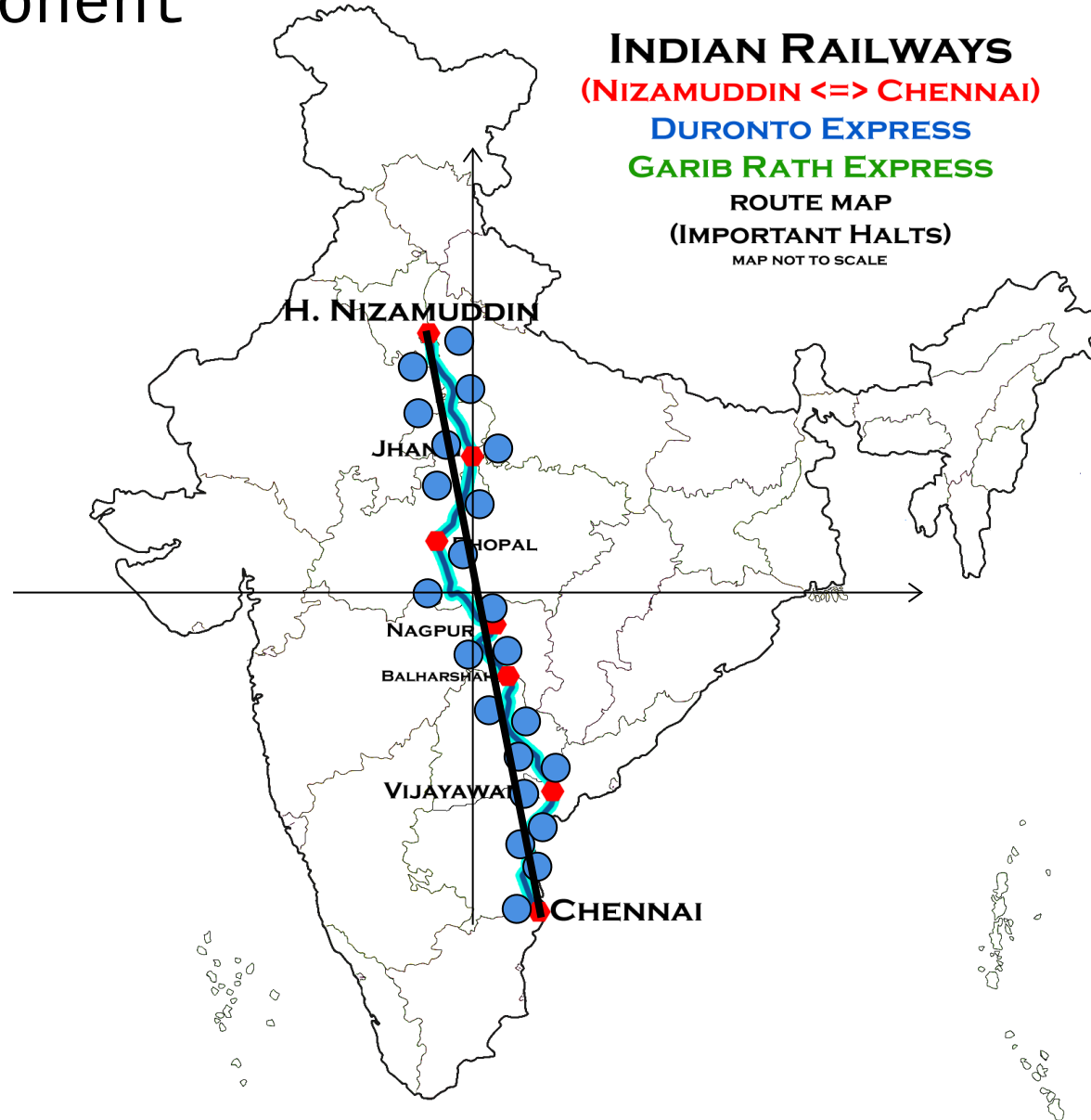


[Image Credits](#)

First Principal Component

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- Data
 - matrix
 - abstract

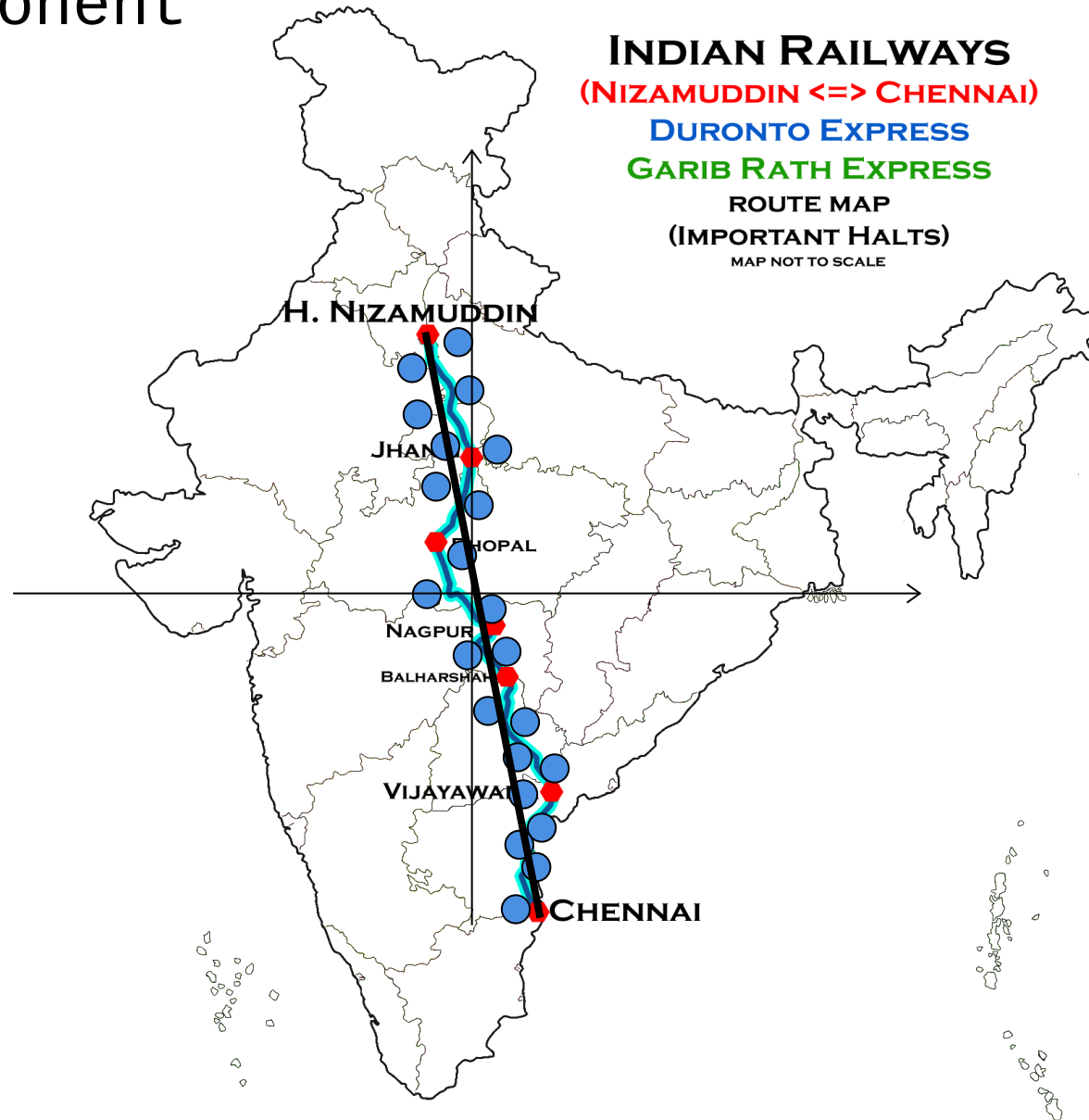


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First Principal Component

Chennai-Delhi Garib Rath

- Data
 - matrix
 - abstract
- **Algorithm**
 - general
 - powerful

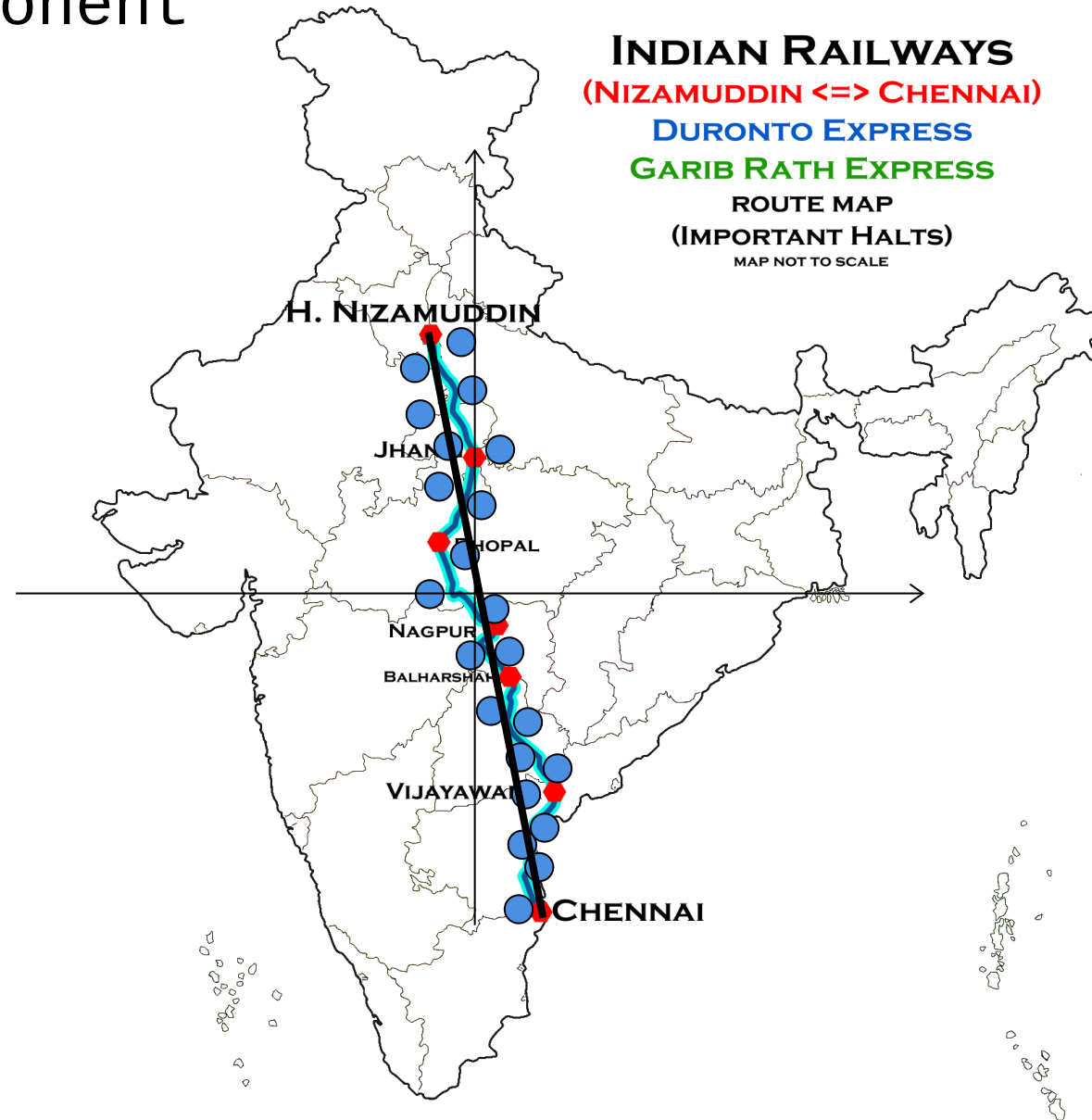


[Image Credits](#)

First Principal Component

Chennai-Delhi Garib Rath

- Data
 - matrix
 - abstract
- **Algorithm**
 - general
 - powerful
- Domain knowledge



[Image Credits](#)

Variance

Variance



$$\sigma_1^2$$



Variance

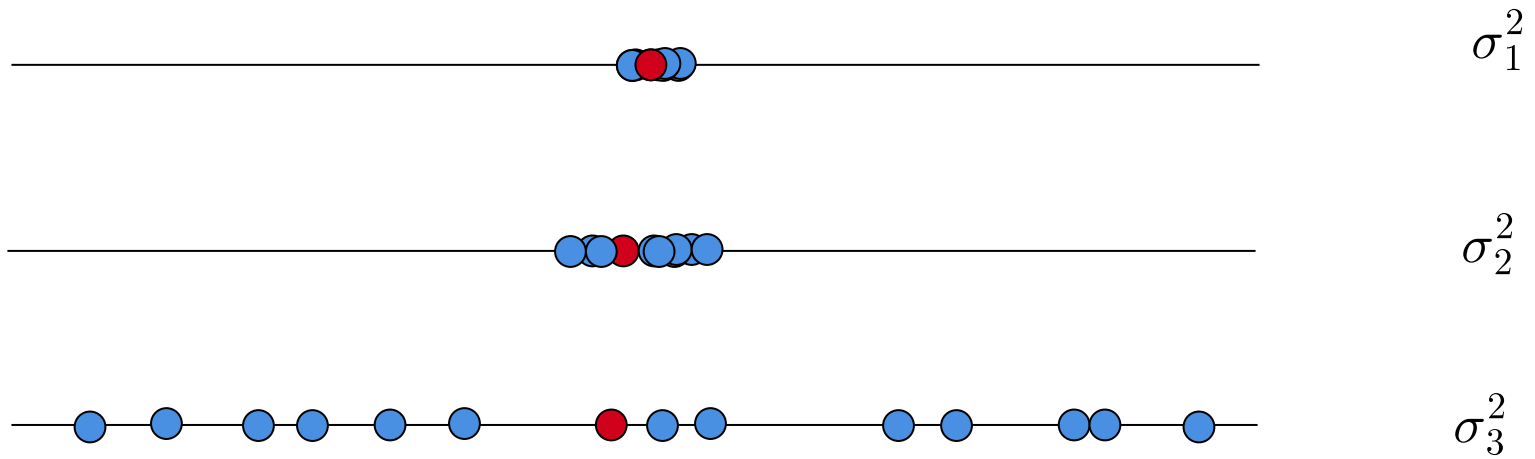


$$\sigma_1^2$$



$$\sigma_2^2$$

Variance



Variance



$$\sigma_1^2$$

$$\sigma_1^2 < \sigma_2^2 < \sigma_3^2$$

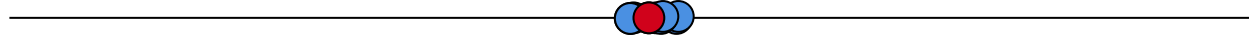


$$\sigma_2^2$$



$$\sigma_3^2$$

Variance



$$\sigma_1^2$$

$$\sigma_1^2 < \sigma_2^2 < \sigma_3^2$$



$$\sigma_2^2$$



$$\sigma_3^2$$

- Temperature
- Weight

Variance



$$\sigma_1^2$$



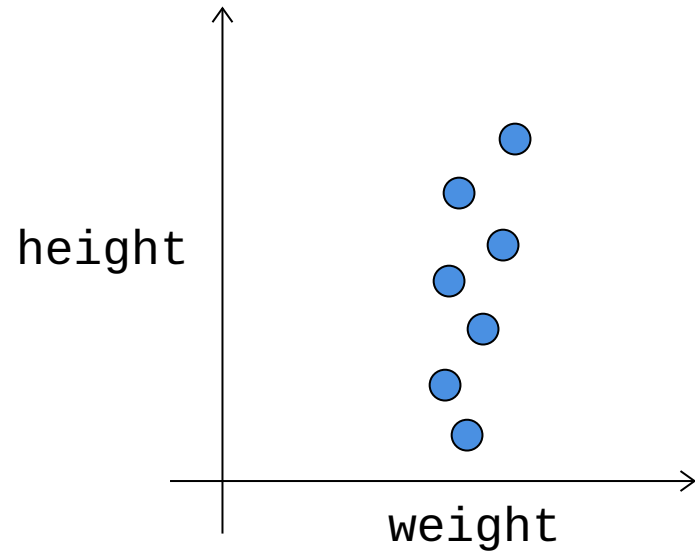
$$\sigma_2^2$$



$$\sigma_3^2$$

$$\sigma_1^2 < \sigma_2^2 < \sigma_3^2$$

- Temperature
- Weight



Variance



$$\sigma_1^2$$



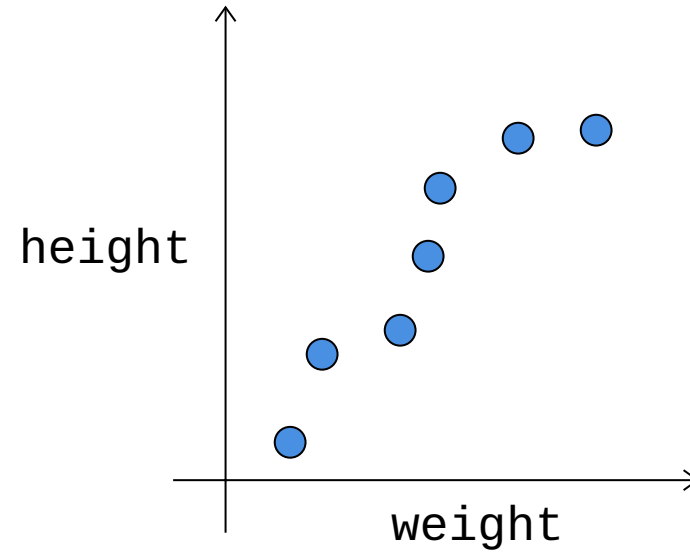
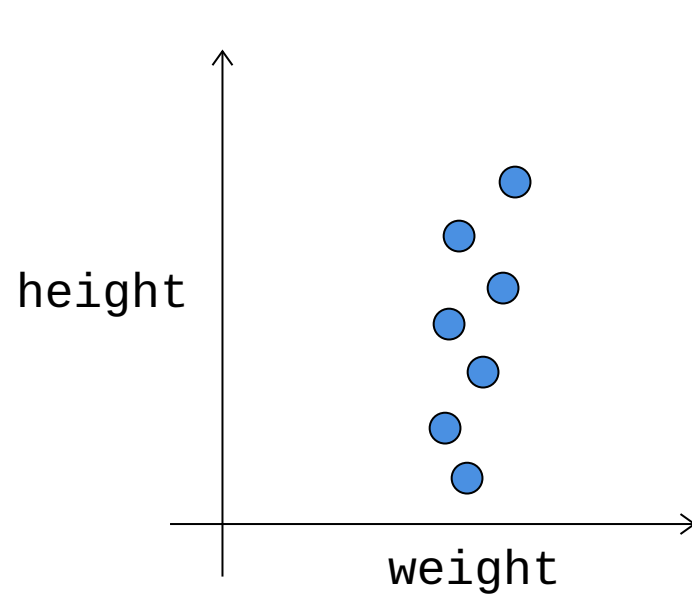
$$\sigma_2^2$$



$$\sigma_3^2$$

$$\sigma_1^2 < \sigma_2^2 < \sigma_3^2$$

- Temperature
- Weight



Variance



σ_1^2



σ_2^2

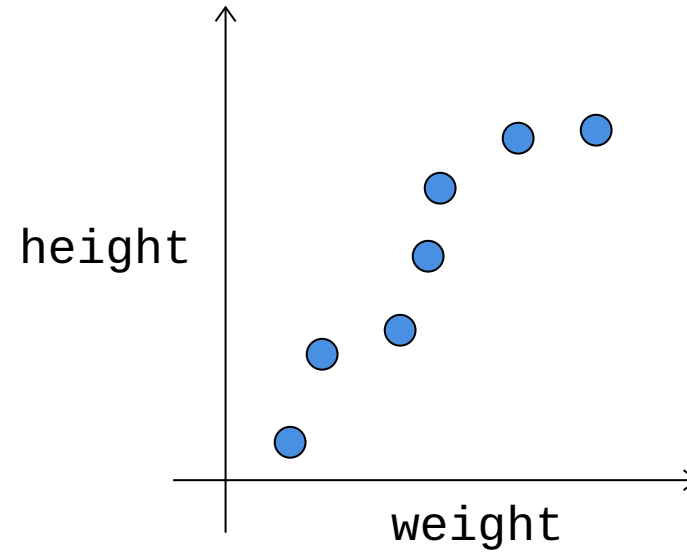
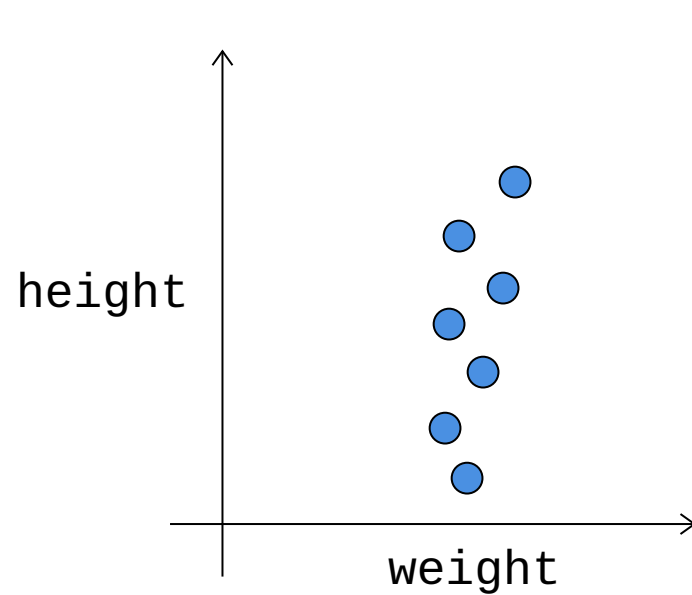


σ_3^2

$$\sigma_1^2 < \sigma_2^2 < \sigma_3^2$$

- Temperature
- Weight

- Variance
- Information
- Explanatory power



Variance



$$\sigma_1^2$$

$$\sigma_1^2 < \sigma_2^2 < \sigma_3^2$$



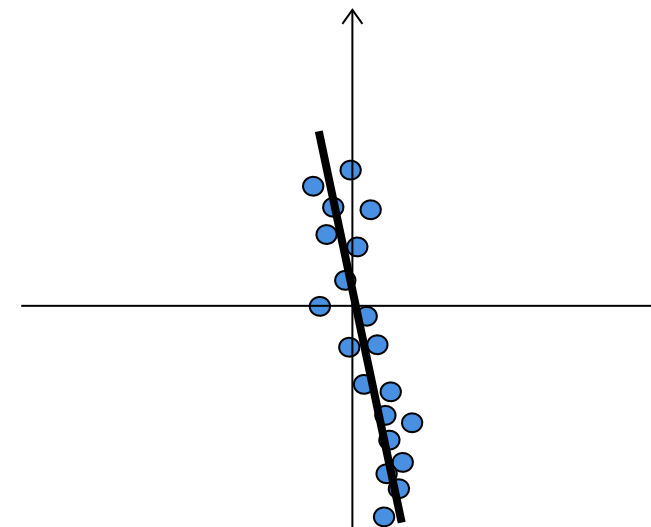
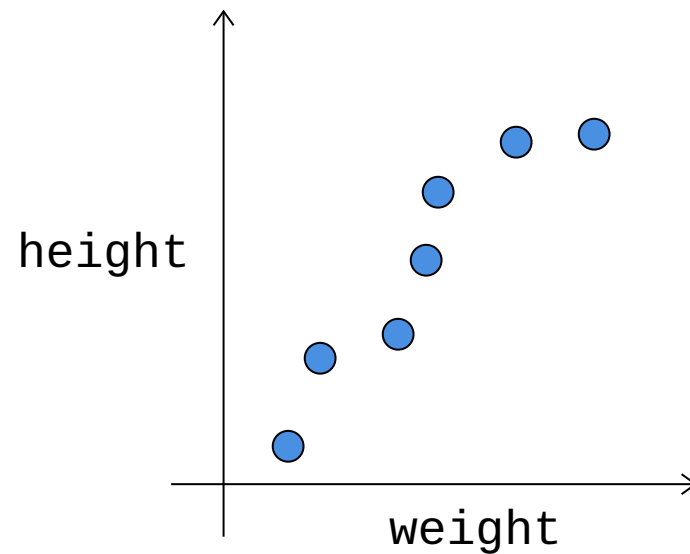
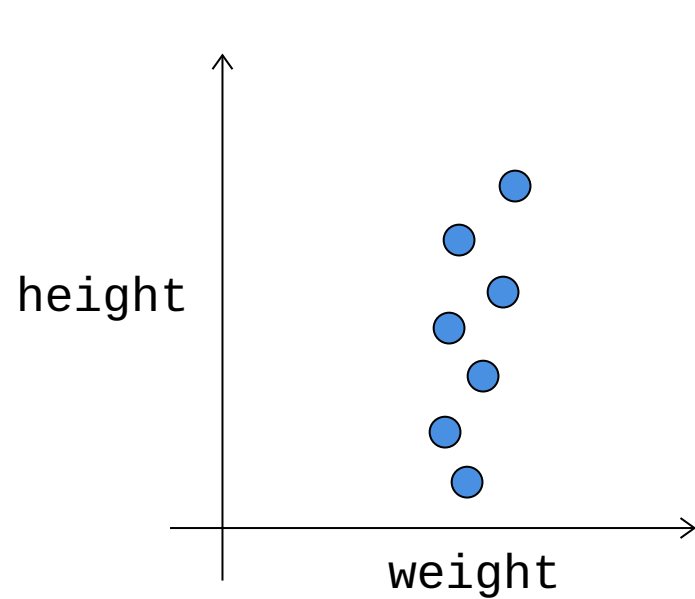
$$\sigma_2^2$$

- Temperature
- Weight



$$\sigma_3^2$$

- Variance
- Information
- Explanatory power



Variance Maximization

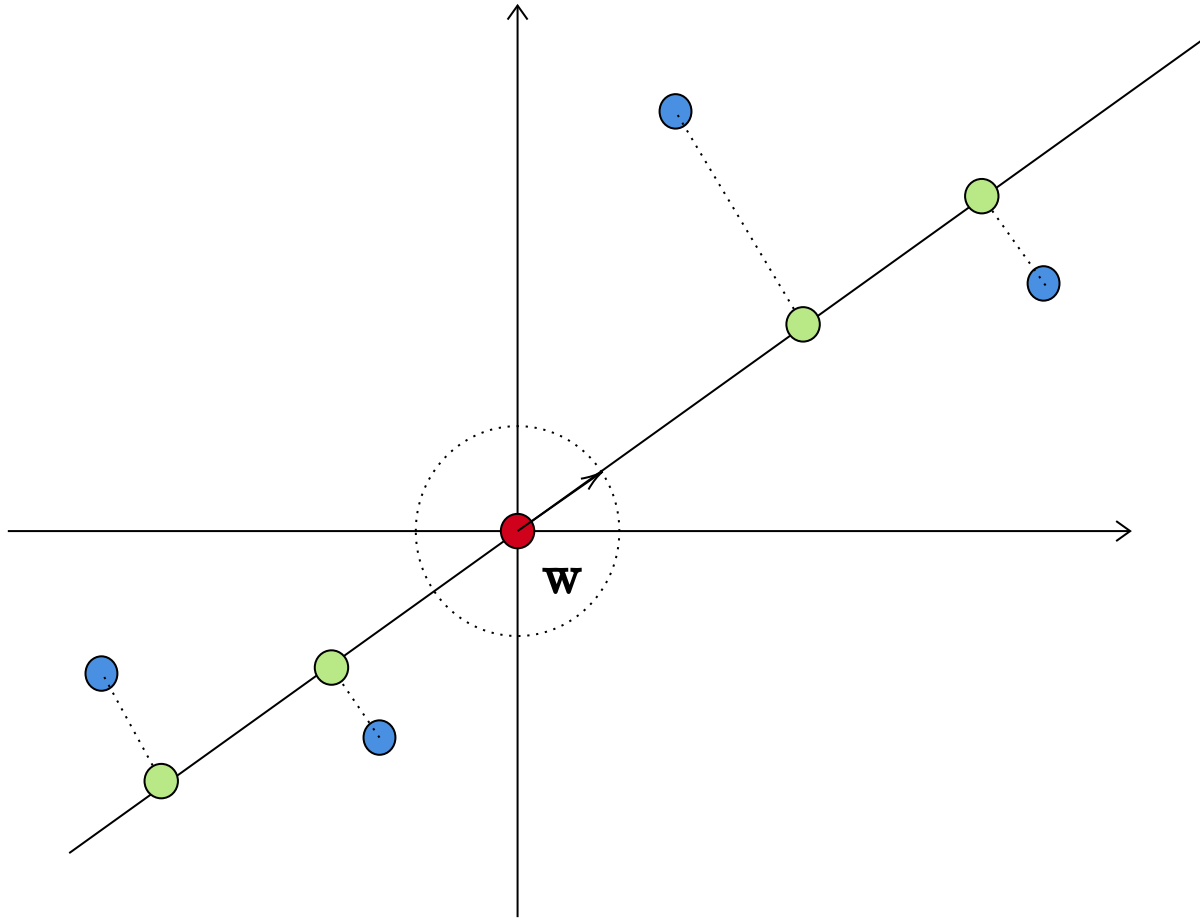
$$D = \{\mathbf{x}_1, \cdots, \mathbf{x}_n\}$$

$$\boldsymbol{\mu} = \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i = \mathbf{0}$$

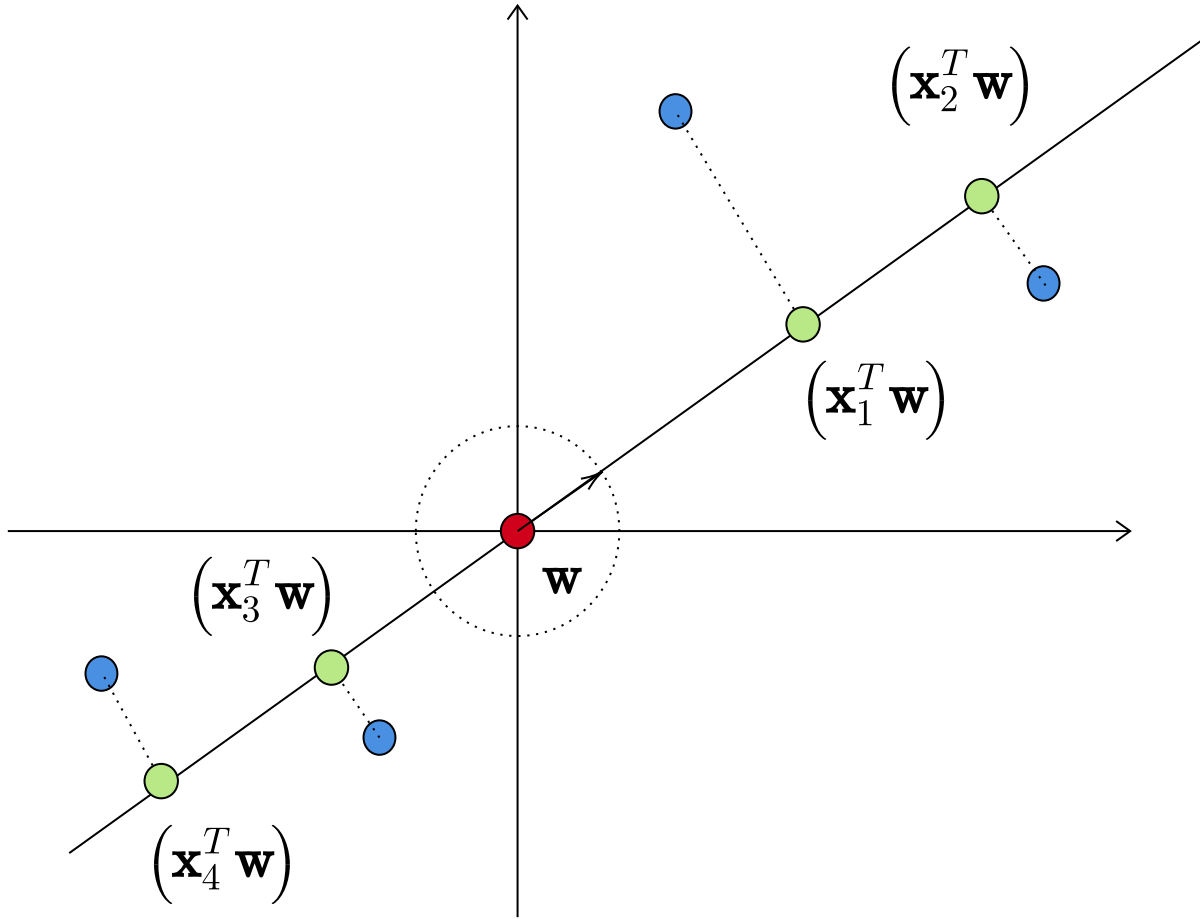
Variance Maximization

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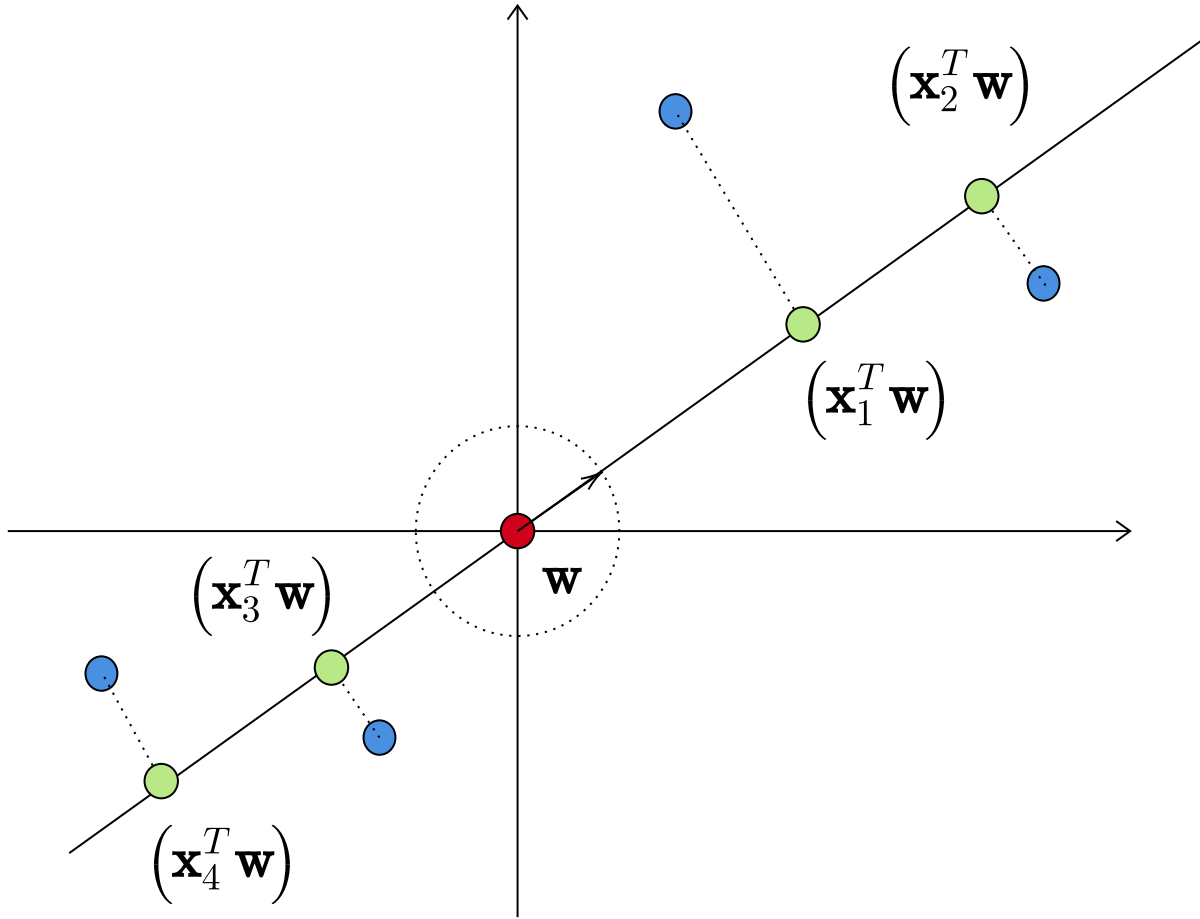
Variance Maximization



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Variance Maximization

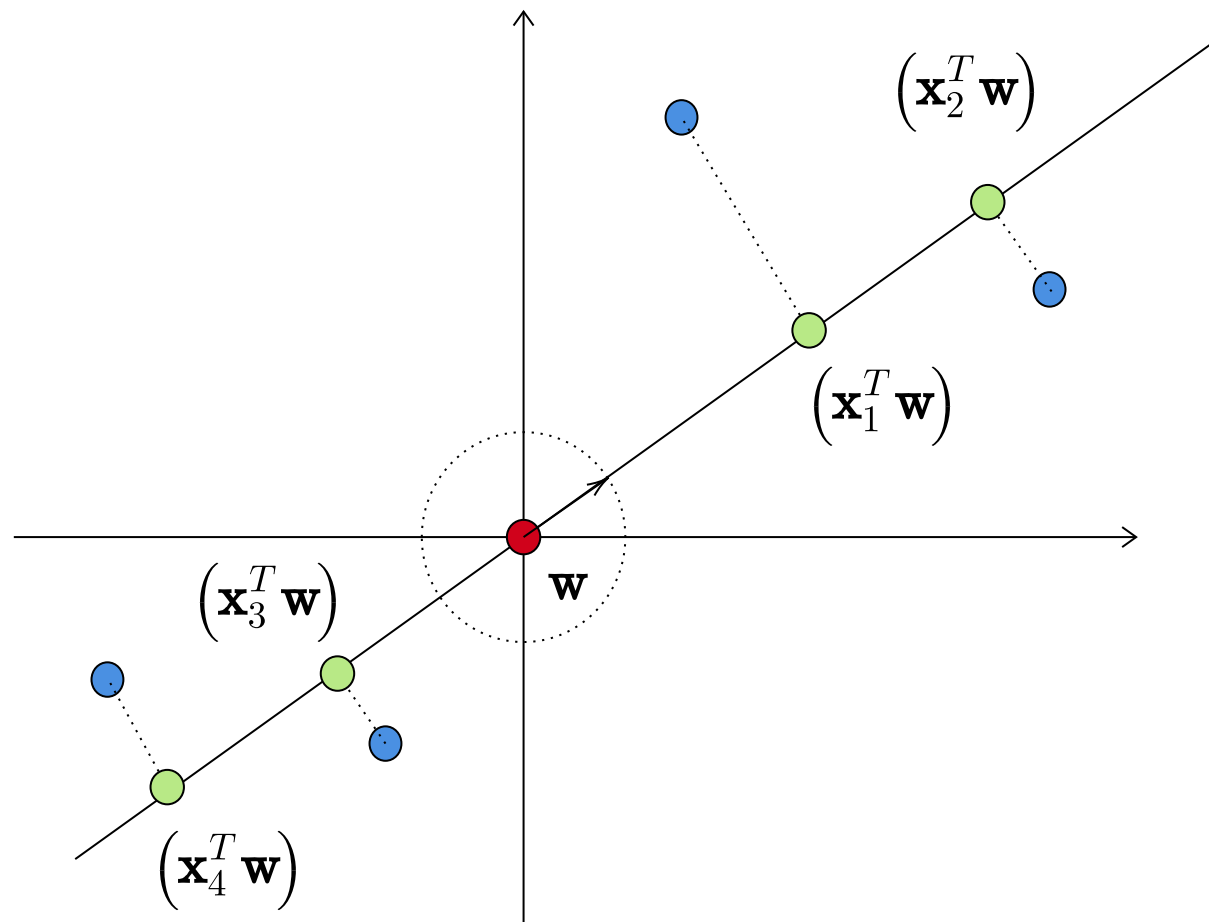


$$D = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$$

$$\mu = \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i = \mathbf{0}$$

$$\text{var}(D, \mathbf{w}) =$$

Variance Maximization

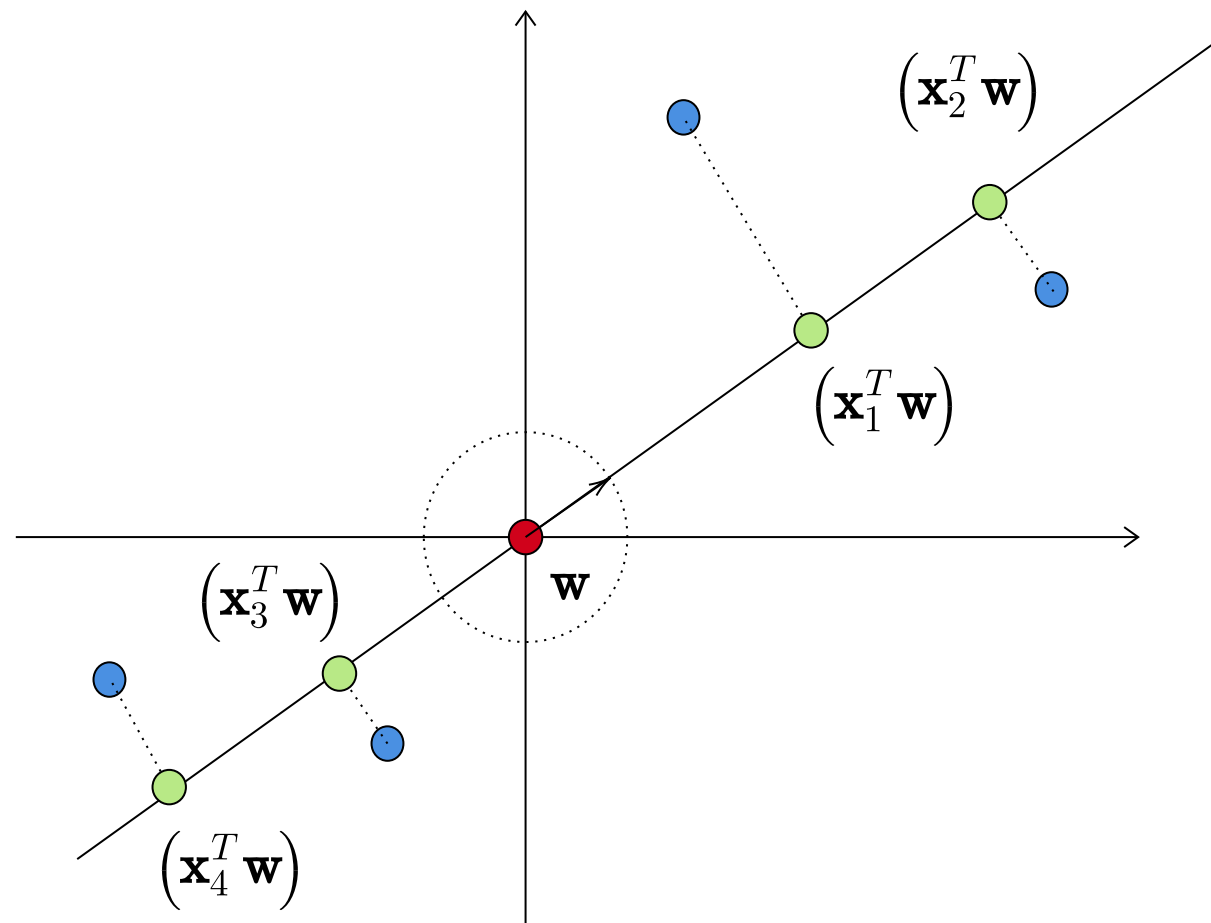


$$D = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$$

$$\mu = \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i = \mathbf{0}$$

$$\text{var}(D, \mathbf{w}) = \frac{1}{n} \cdot \sum_{i=1}^n (\mathbf{x}_i^T \mathbf{w})^2$$

Variance Maximization

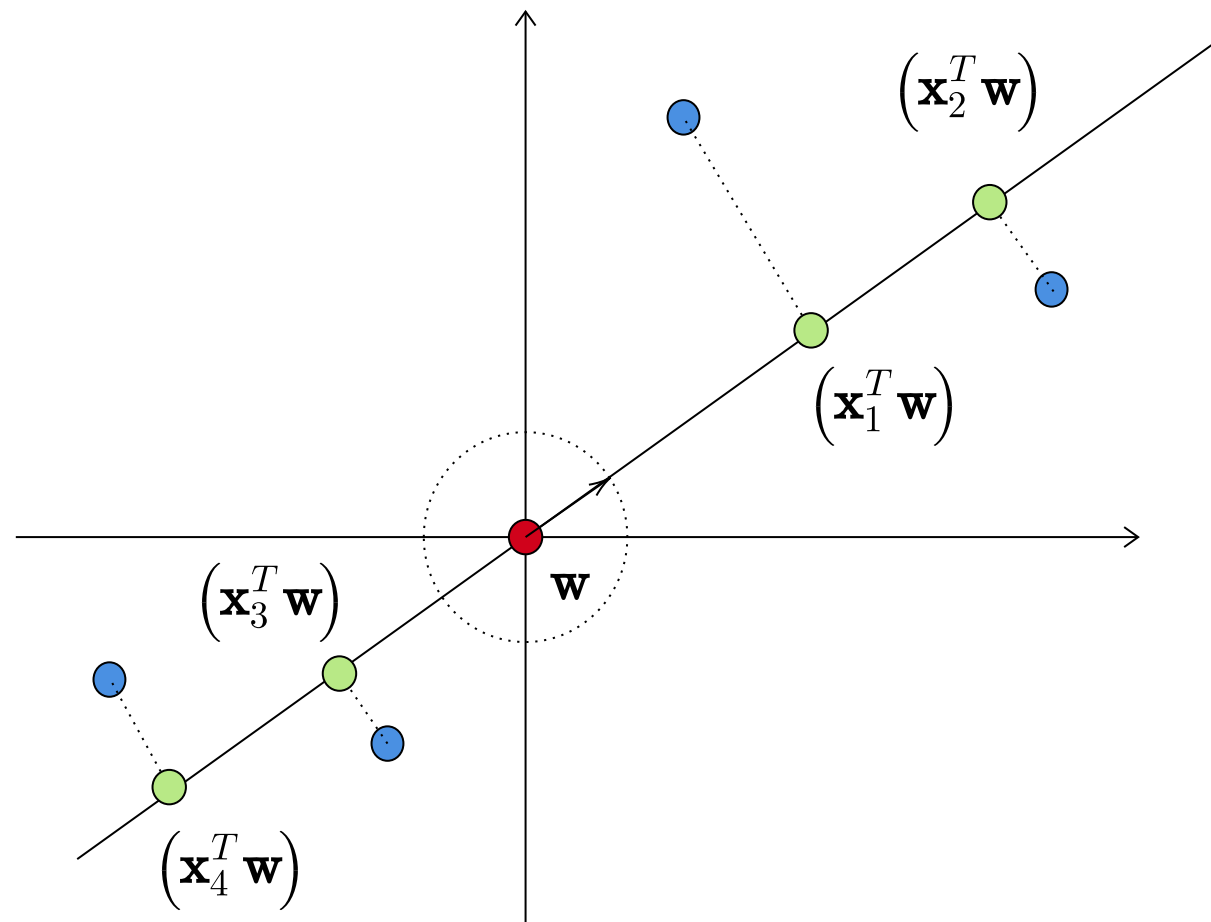


$$D = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$$

$$\boldsymbol{\mu} = \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i = \mathbf{0}$$

$$\begin{aligned} \text{var}(D, \mathbf{w}) &= \frac{1}{n} \cdot \sum_{i=1}^n (\mathbf{x}_i^T \mathbf{w})^2 \\ &= \mathbf{w}^T \left[\frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^T \right] \mathbf{w} \end{aligned}$$

Variance Maximization

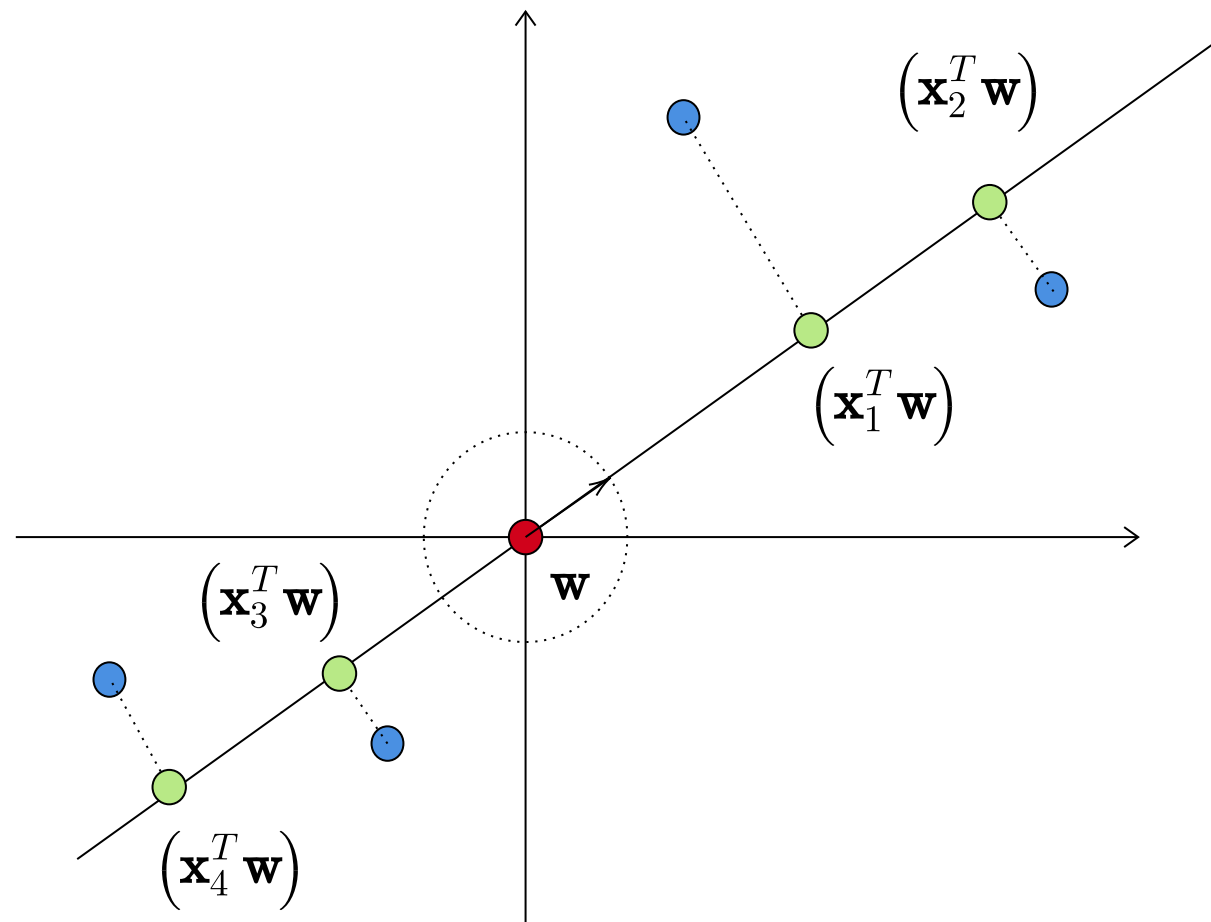


$$D = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$$

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$$\begin{aligned} \text{var}(D, \mathbf{w}) &= \frac{1}{n} \cdot \sum_{i=1}^n (\mathbf{x}_i^T \mathbf{w})^2 \\ &= \mathbf{w}^T \left[\frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^T \right] \mathbf{w} \\ &= \mathbf{w}^T \mathbf{C} \mathbf{w} \end{aligned}$$

Variance Maximization



$$D = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$$

$$\mu = \frac{1}{n} \cdot \sum_{i=1}^n \mathbf{x}_i = \mathbf{0}$$

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$$\max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \mathbf{C} \mathbf{w} = \lambda_1$$

$$\arg \max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \mathbf{C} \mathbf{w} = \mathbf{w}_1$$

Summary

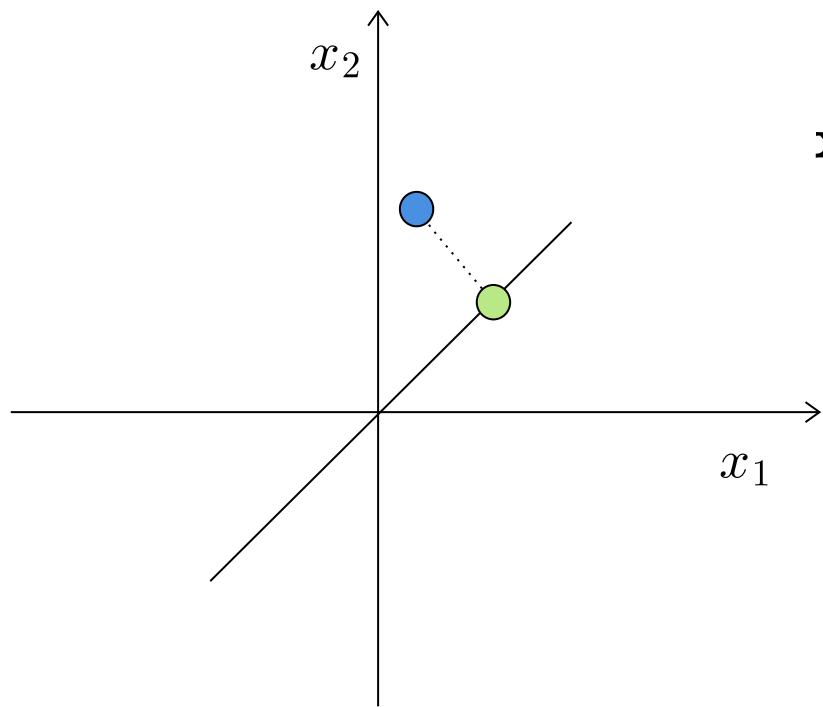
Error minimization $\overset{\mathbf{w}_1}{\equiv}$ Variance Maximization
PC

Summary

Error minimization \equiv Variance Maximization

\mathbf{w}_1

PC

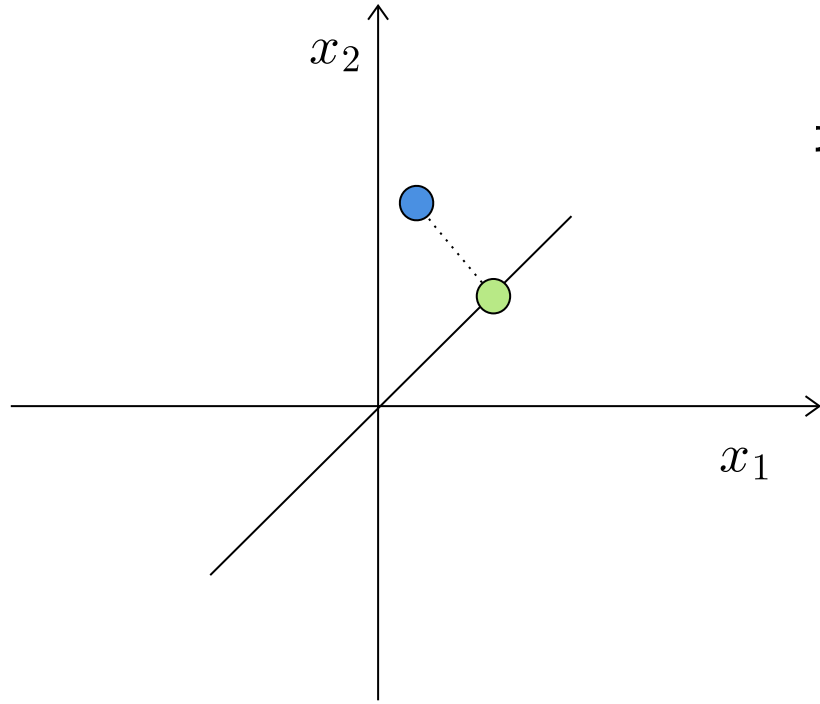


$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_d \end{bmatrix}$$

Summary

Error minimization \equiv Variance Maximization

PC



$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_d \end{bmatrix}$$

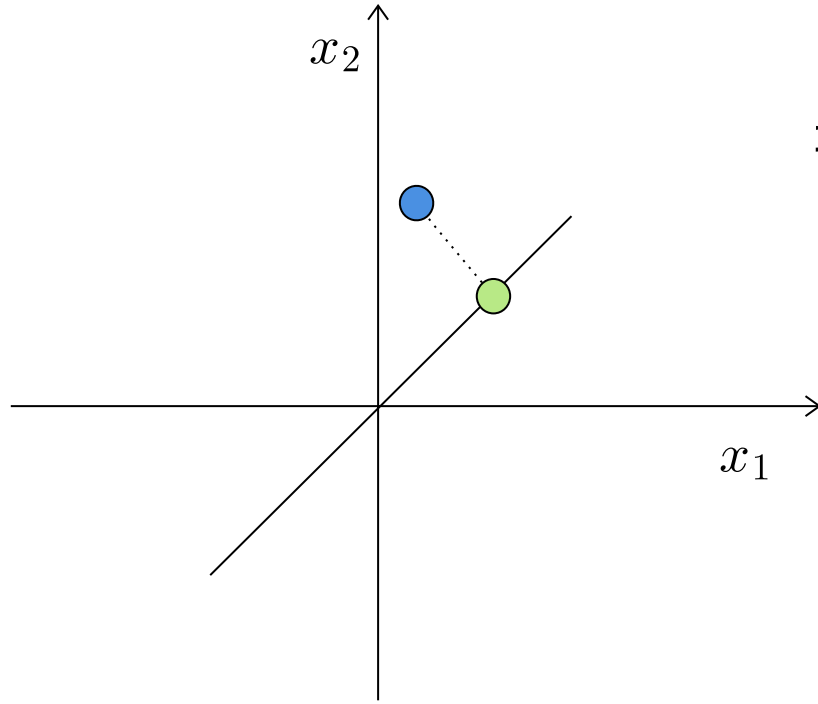
$$\mathbf{x}^T \mathbf{w}_1 = \begin{bmatrix} x_1 & \cdots & x_d \end{bmatrix} \begin{bmatrix} w_{11} \\ \vdots \\ w_{d1} \end{bmatrix}$$

Summary

Error minimization \equiv Variance Maximization

\mathbf{w}_1

PC



$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_d \end{bmatrix}$$

$$\begin{aligned} \mathbf{x}^T \mathbf{w}_1 &= \begin{bmatrix} x_1 & \cdots & x_d \end{bmatrix} \begin{bmatrix} w_{11} \\ \vdots \\ w_{d1} \end{bmatrix} \\ &= \boxed{w_{11}} x_1 + \cdots + \boxed{w_{i1}} x_i + \cdots + \boxed{w_{d1}} x_d \end{aligned}$$

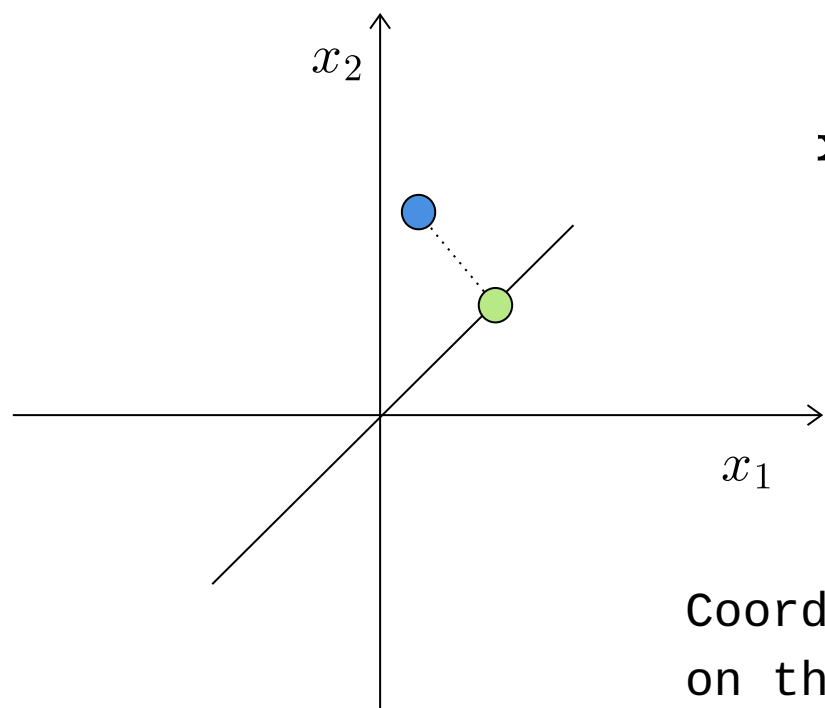
Summary

Note that the first PC is \mathbf{w}_1 , a vector. In this slide, we look at how the d features get transformed when they are projected onto a PC.

Error minimization \equiv Variance Maximization

\mathbf{w}_1

PC



$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_d \end{bmatrix}$$

$$\mathbf{x}^T \mathbf{w}_1 = \begin{bmatrix} x_1 & \cdots & x_d \end{bmatrix} \begin{bmatrix} w_{11} \\ \vdots \\ w_{d1} \end{bmatrix}$$

$$= \boxed{w_{11}} x_1 + \cdots + \boxed{w_{i1}} x_i + \cdots + \boxed{w_{d1}} x_d$$

Coordinate of \mathbf{x}
on the first PC.

PC (coordinate view)

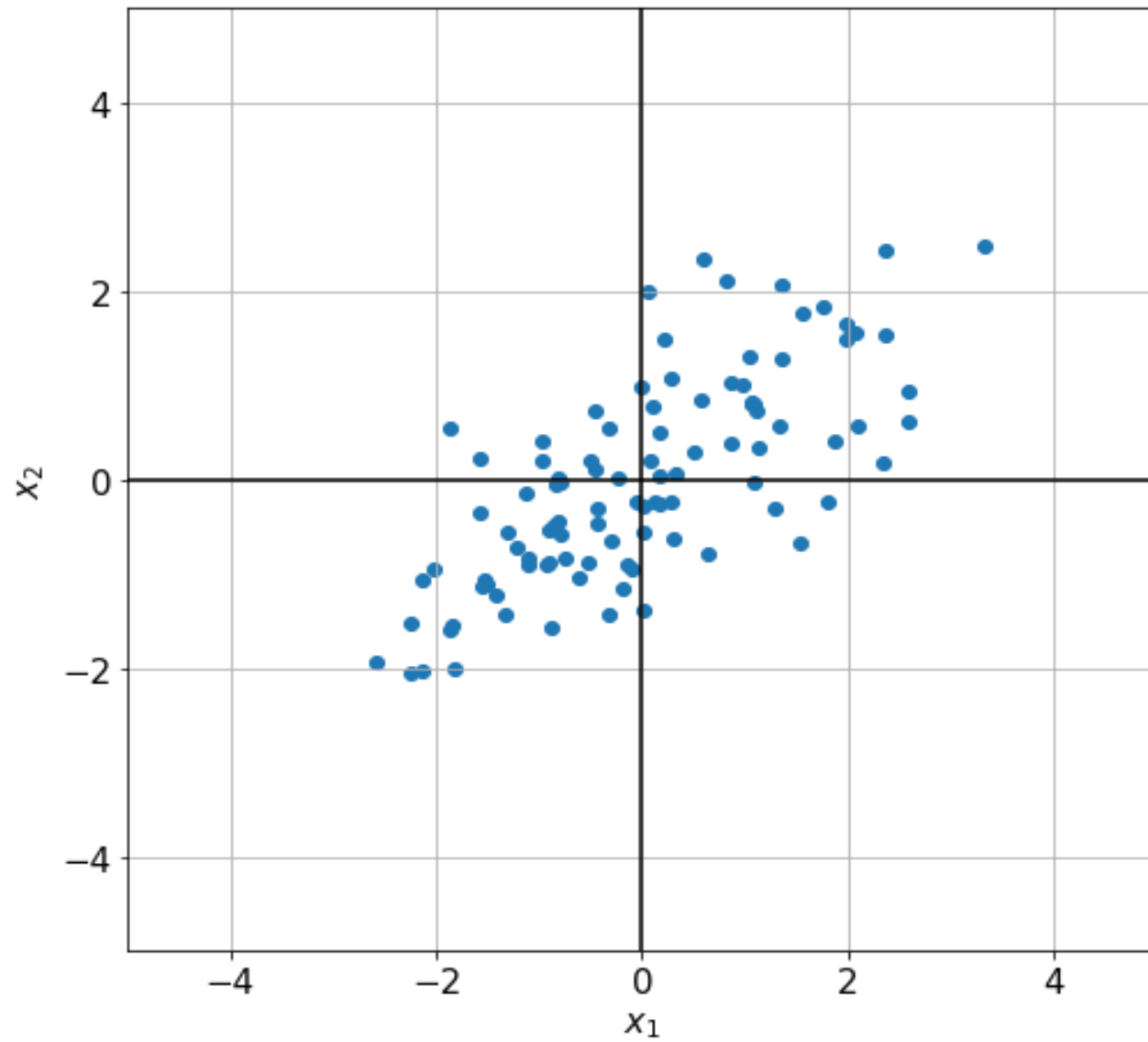
- Each PC specifies a new coordinate
- Linear combination of features
- Recall change of basis

Demo

$$n = 100$$

$$d = 2$$

Demo



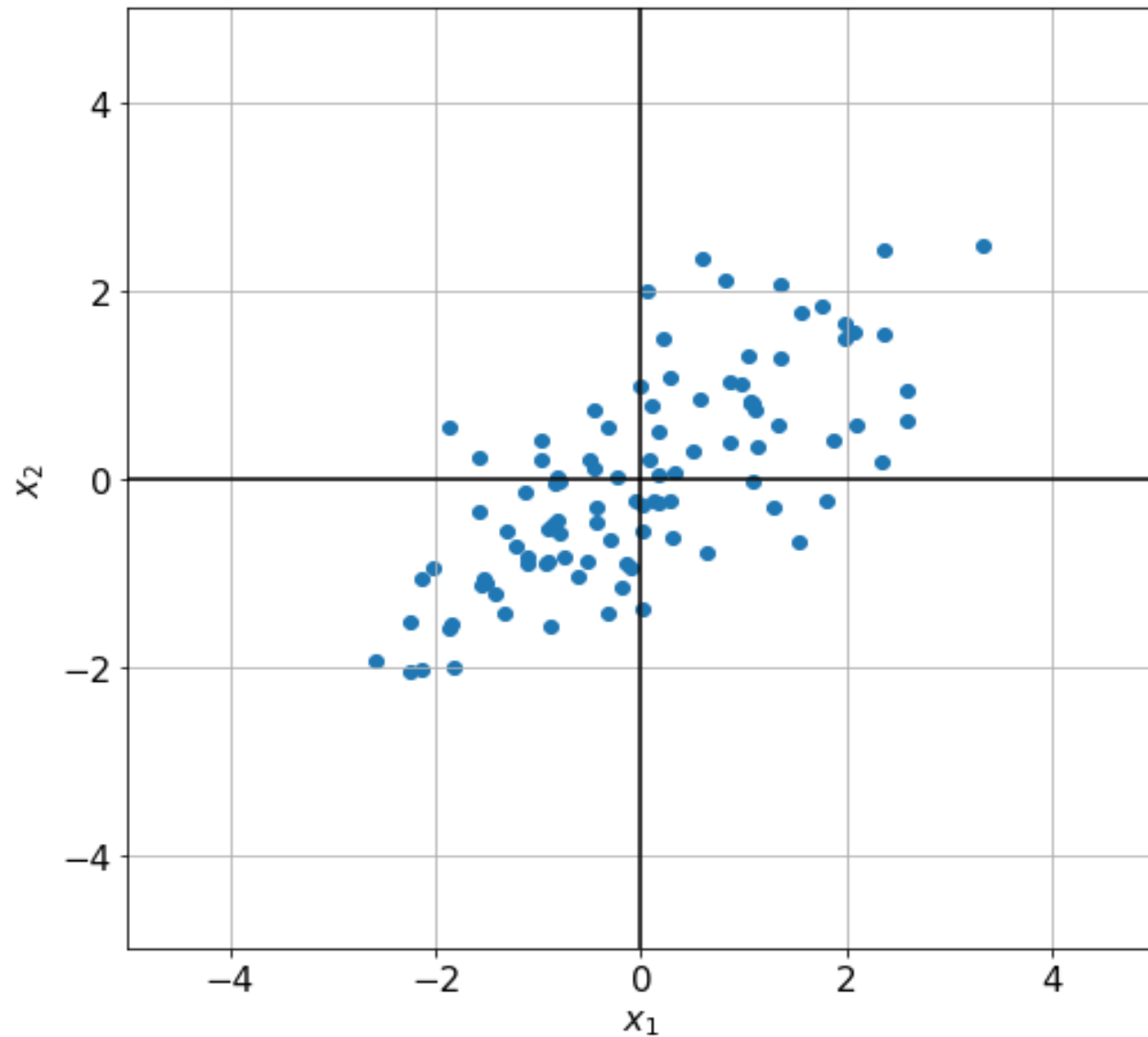
$$n = 100$$

$$d = 2$$

Demo

$$\mathbf{x} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{aligned} \mathbf{xx}^T &= \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \end{aligned}$$



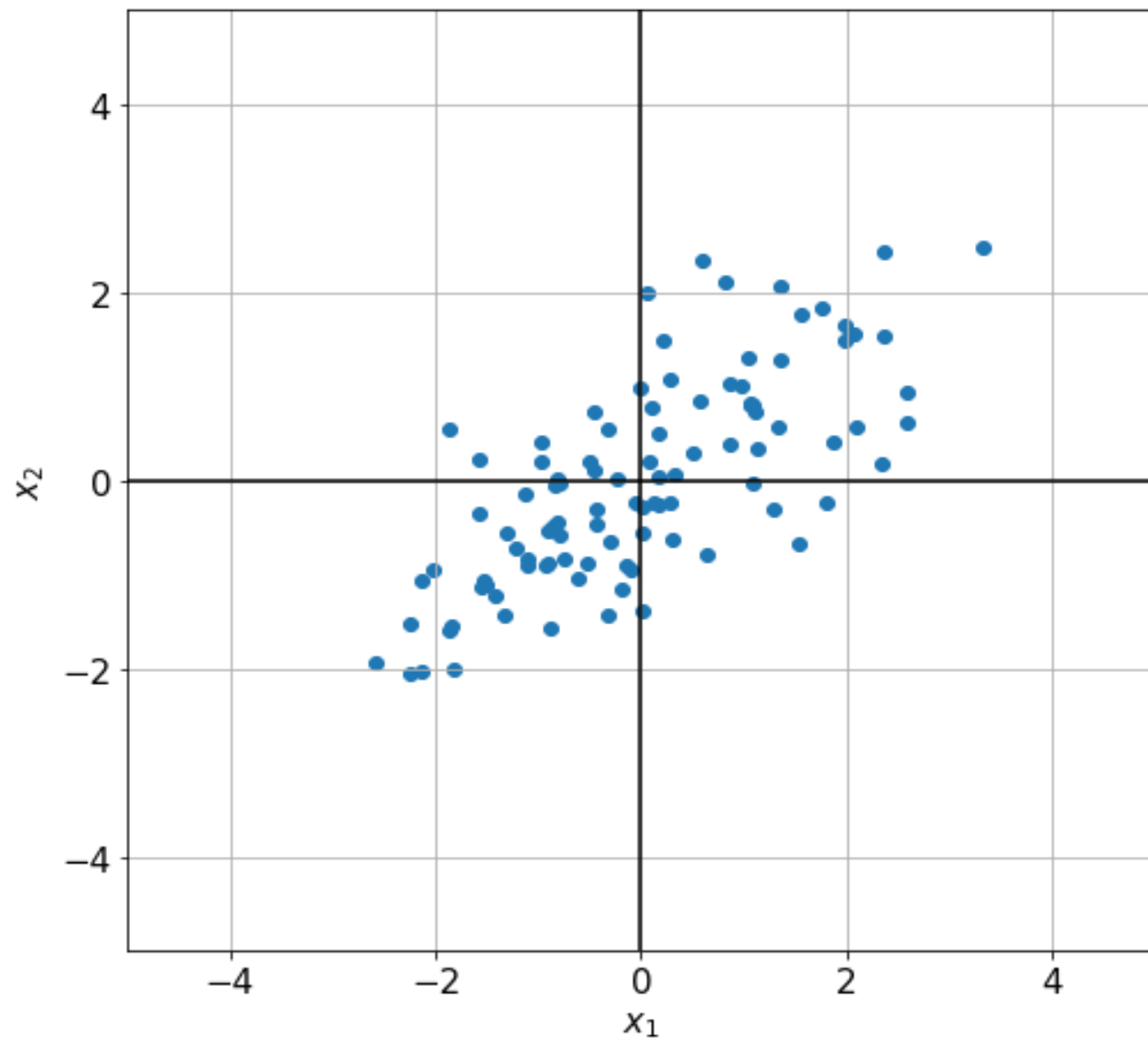
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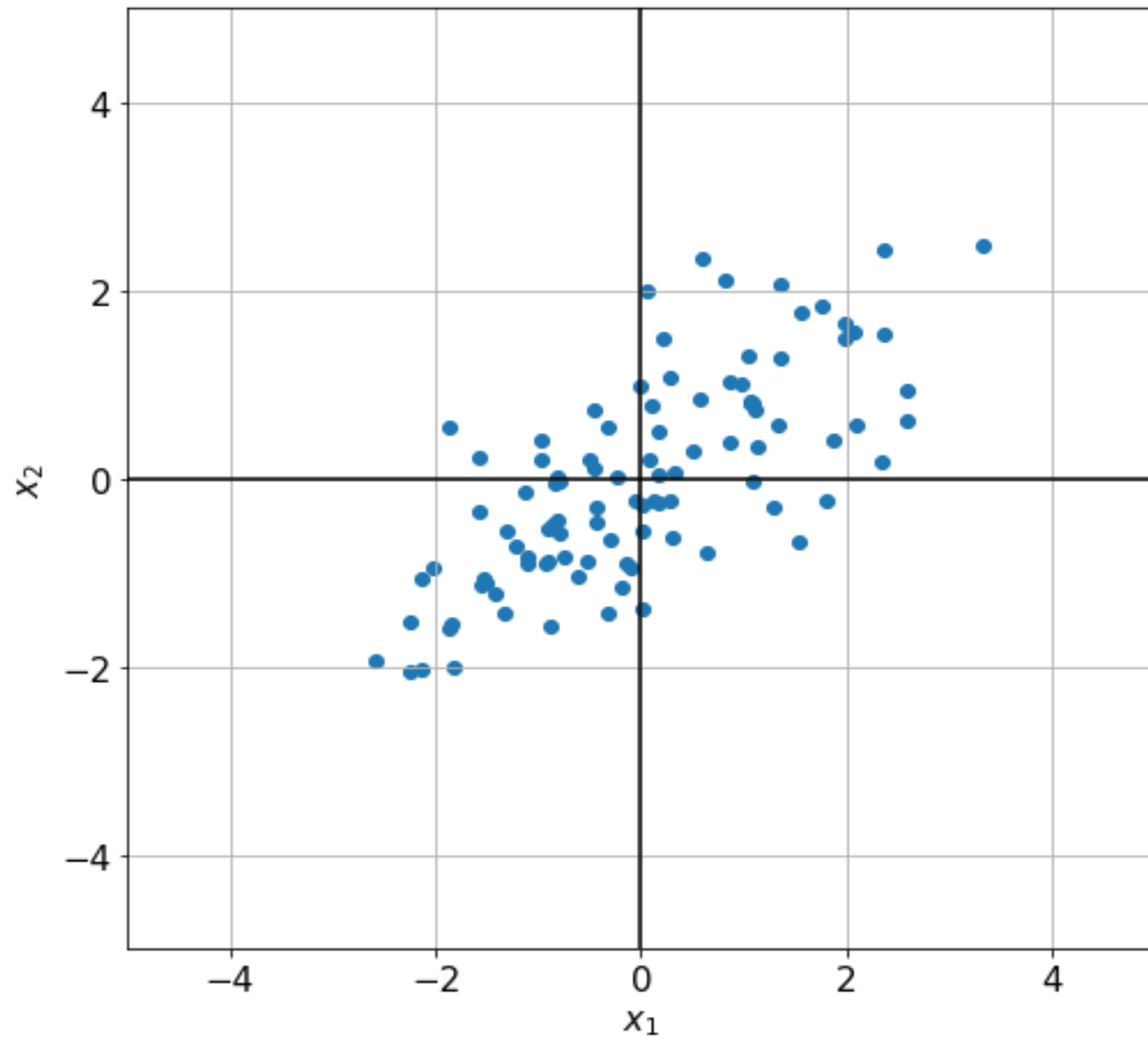
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$$n = 100$$

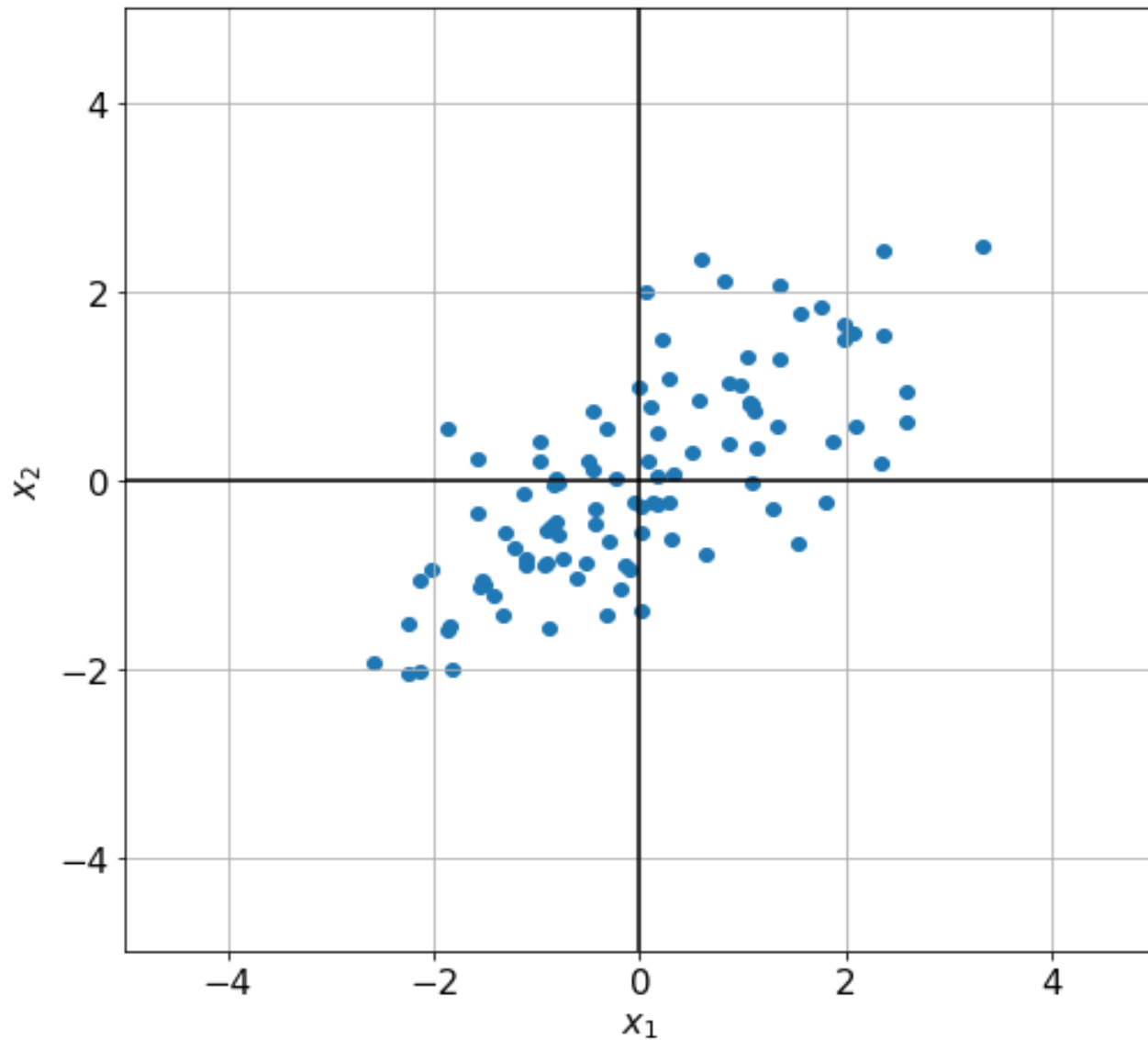
$$d = 2$$

$$\mathbf{C} = \begin{bmatrix} 1.70 & 1.03 \\ 1.03 & 1.17 \end{bmatrix}$$

Demo

$$\mathbf{x} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{aligned} \mathbf{xx}^T &= \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \end{aligned}$$



$$n = 100$$

$$d = 2$$

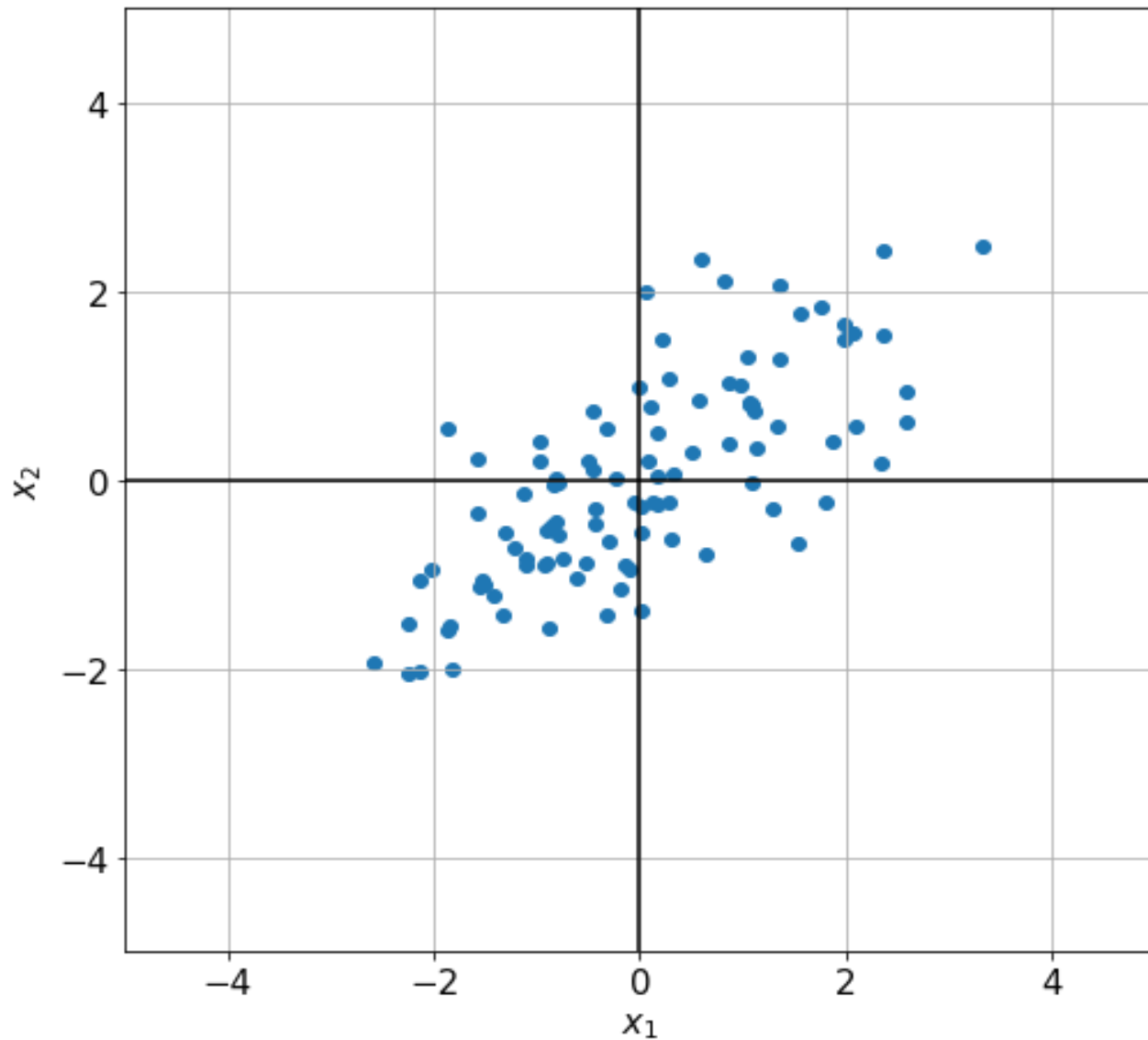
$$\mathbf{C} = \begin{bmatrix} 1.70 & 1.03 \\ 1.03 & 1.17 \end{bmatrix}$$

$$(\lambda_1, \mathbf{w}_1) = \text{Solver}(\mathbf{C})$$

Demo

$$\mathbf{x} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{aligned} \mathbf{xx}^T &= \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \end{aligned}$$



$$n = 100$$

$$d = 2$$

$$\mathbf{C} = \begin{bmatrix} 1.70 & 1.03 \\ 1.03 & 1.17 \end{bmatrix}$$

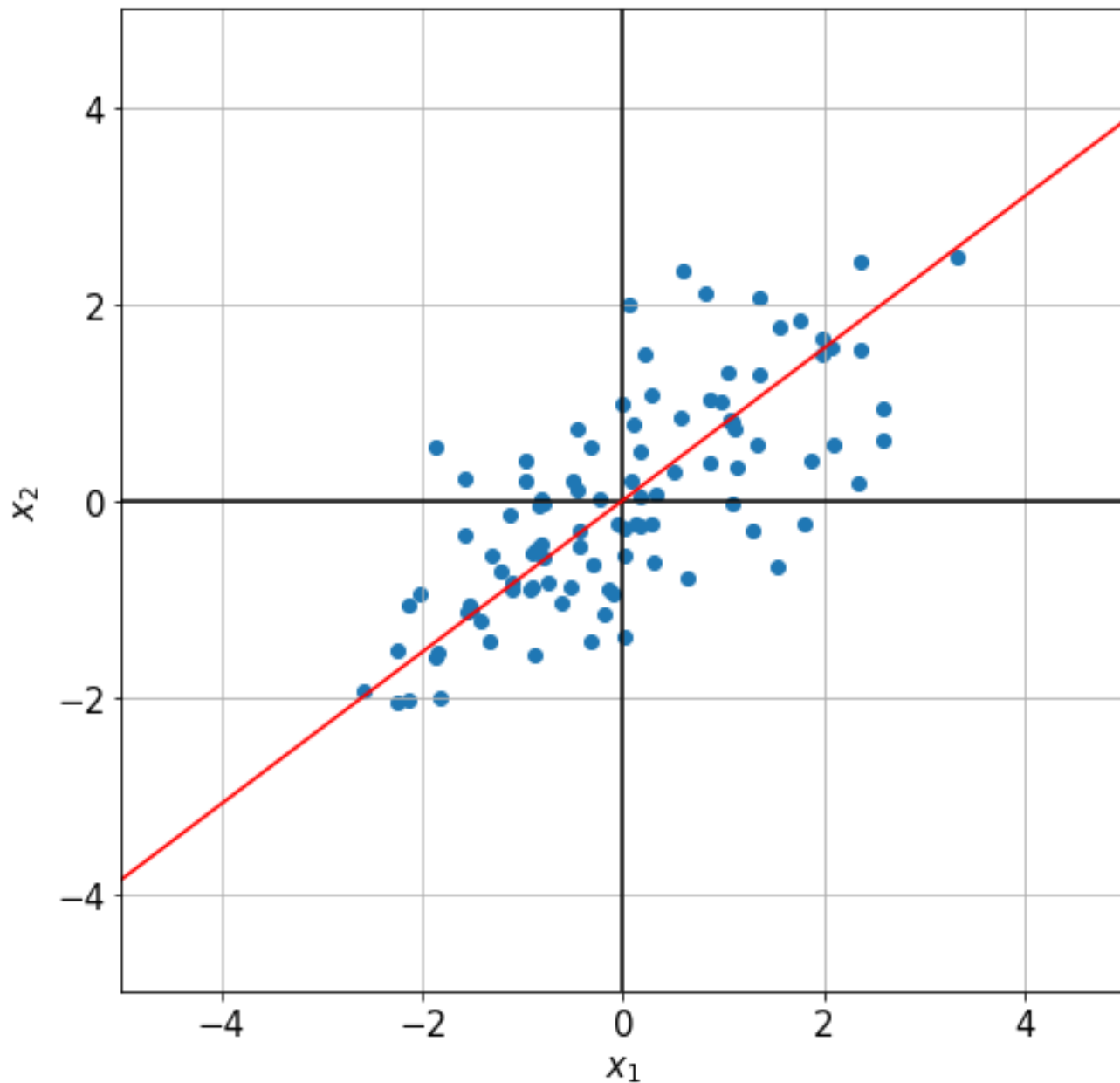
$$(\lambda_1, \mathbf{w}_1) = \text{Solver}(\mathbf{C})$$

$$\lambda_1 = 2.5 \quad \mathbf{w}_1 = - \begin{bmatrix} 0.79 \\ 0.61 \end{bmatrix}$$

Demo

$$\mathbf{x} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{aligned} \mathbf{xx}^T &= \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \end{aligned}$$



$$n = 100$$

$$d = 2$$

$$\mathbf{C} = \begin{bmatrix} 1.70 & 1.03 \\ 1.03 & 1.17 \end{bmatrix}$$

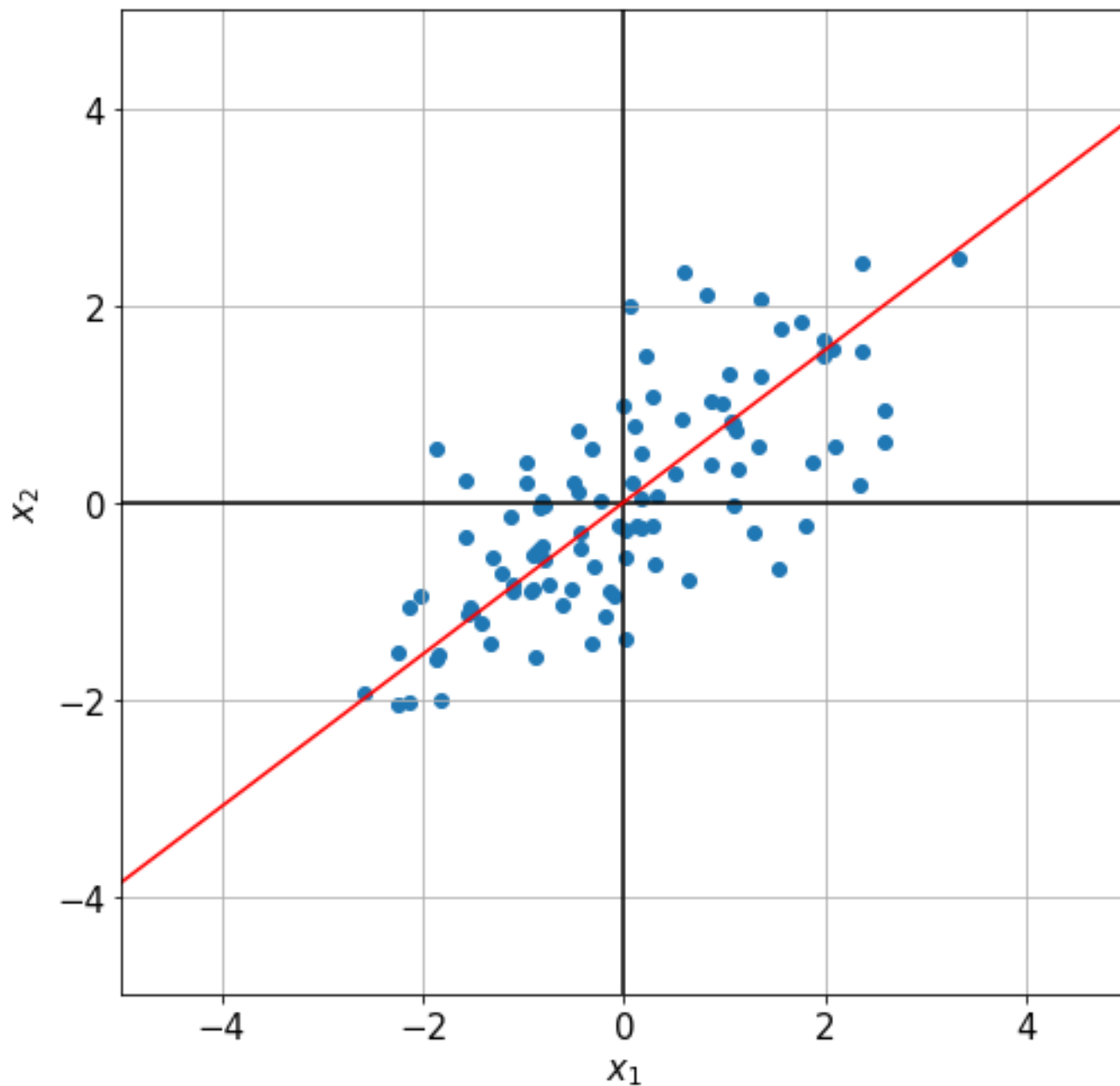
$$(\lambda_1, \mathbf{w}_1) = \text{Solver}(\mathbf{C})$$

$$\lambda_1 = 2.5 \quad \mathbf{w}_1 = - \begin{bmatrix} 0.79 \\ 0.61 \end{bmatrix}$$

Demo

$$\mathbf{x} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{aligned} \mathbf{xx}^T &= \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \end{aligned}$$



$$n = 100 \quad d = 2$$

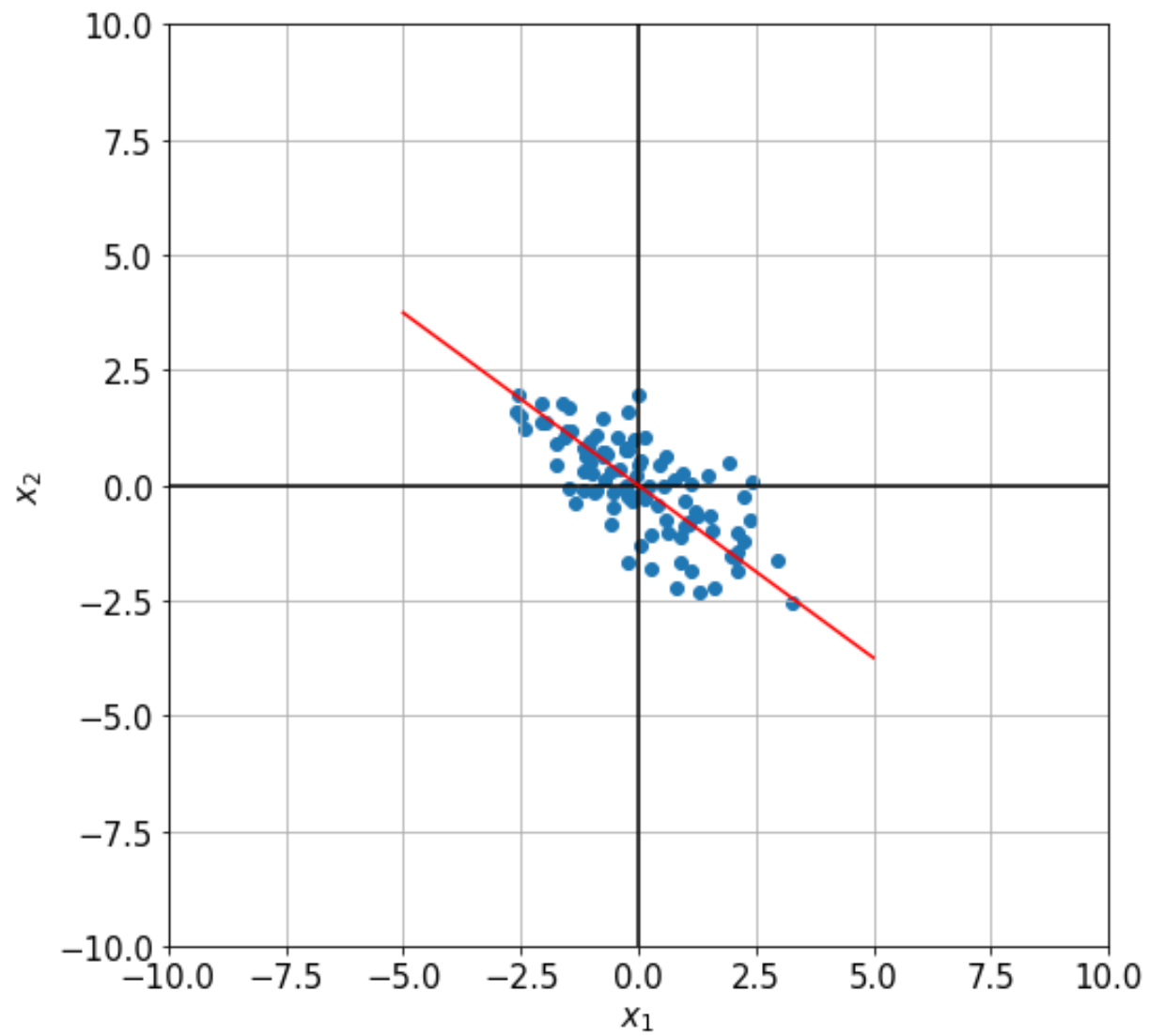
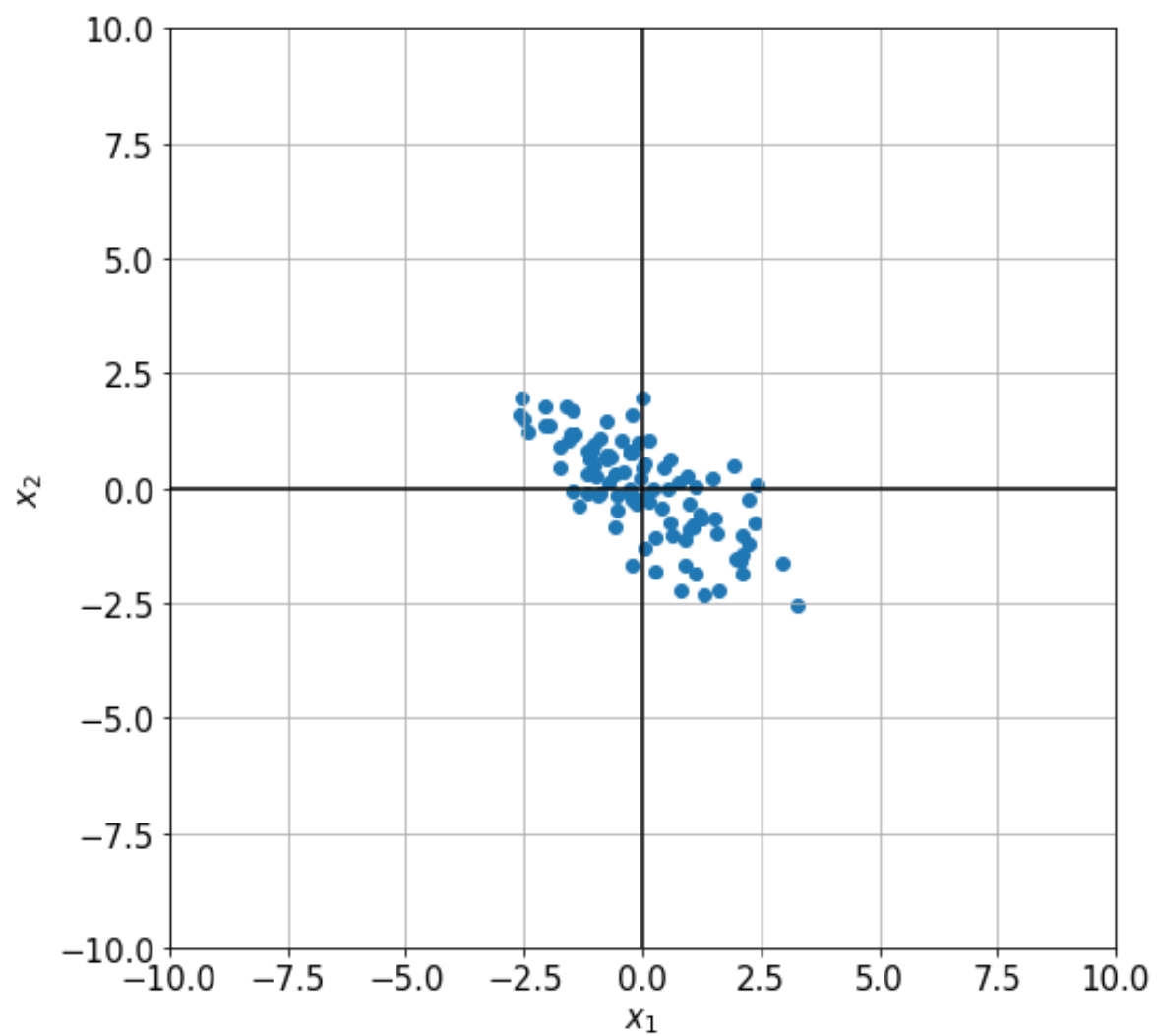
$$\mathbf{C} = \begin{bmatrix} 1.70 & 1.03 \\ 1.03 & 1.17 \end{bmatrix}$$

$$(\lambda_1, \mathbf{w}_1) = \text{Solver}(\mathbf{C})$$

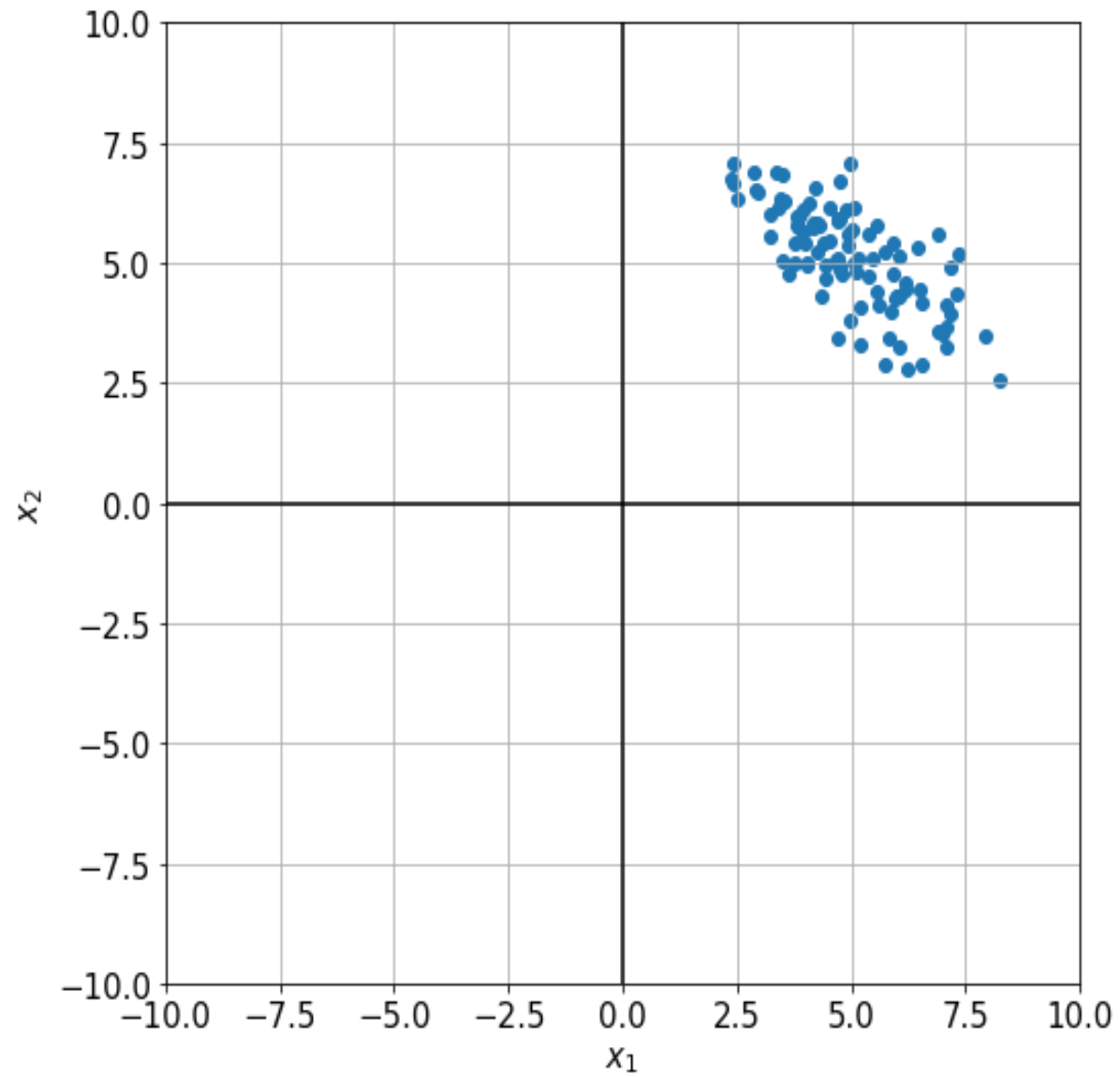
$$\lambda_1 = 2.5 \quad \mathbf{w}_1 = - \begin{bmatrix} 0.79 \\ 0.61 \end{bmatrix}$$

$$w_1 := (-0.79)x_1 + (-0.61)x_2$$

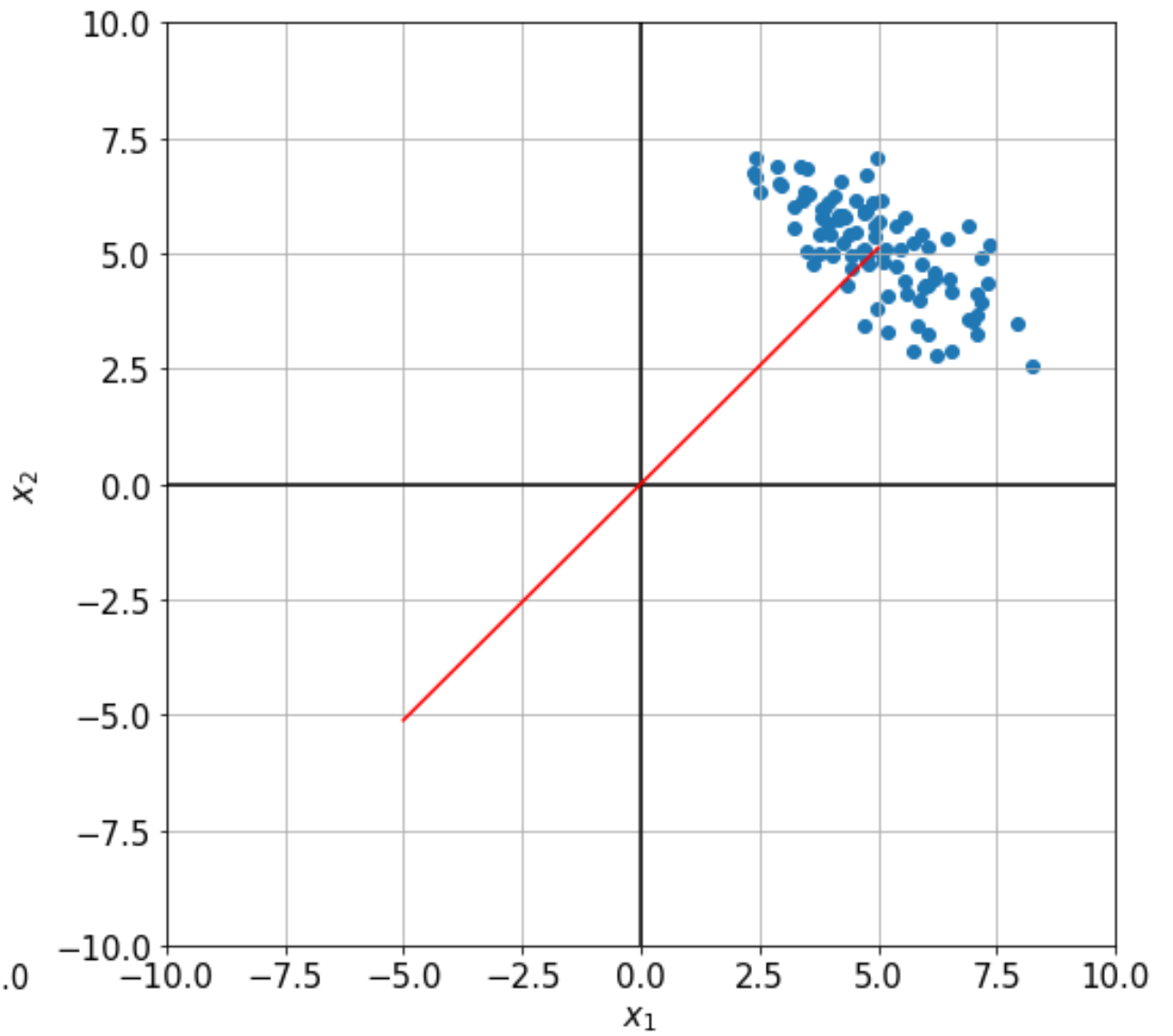
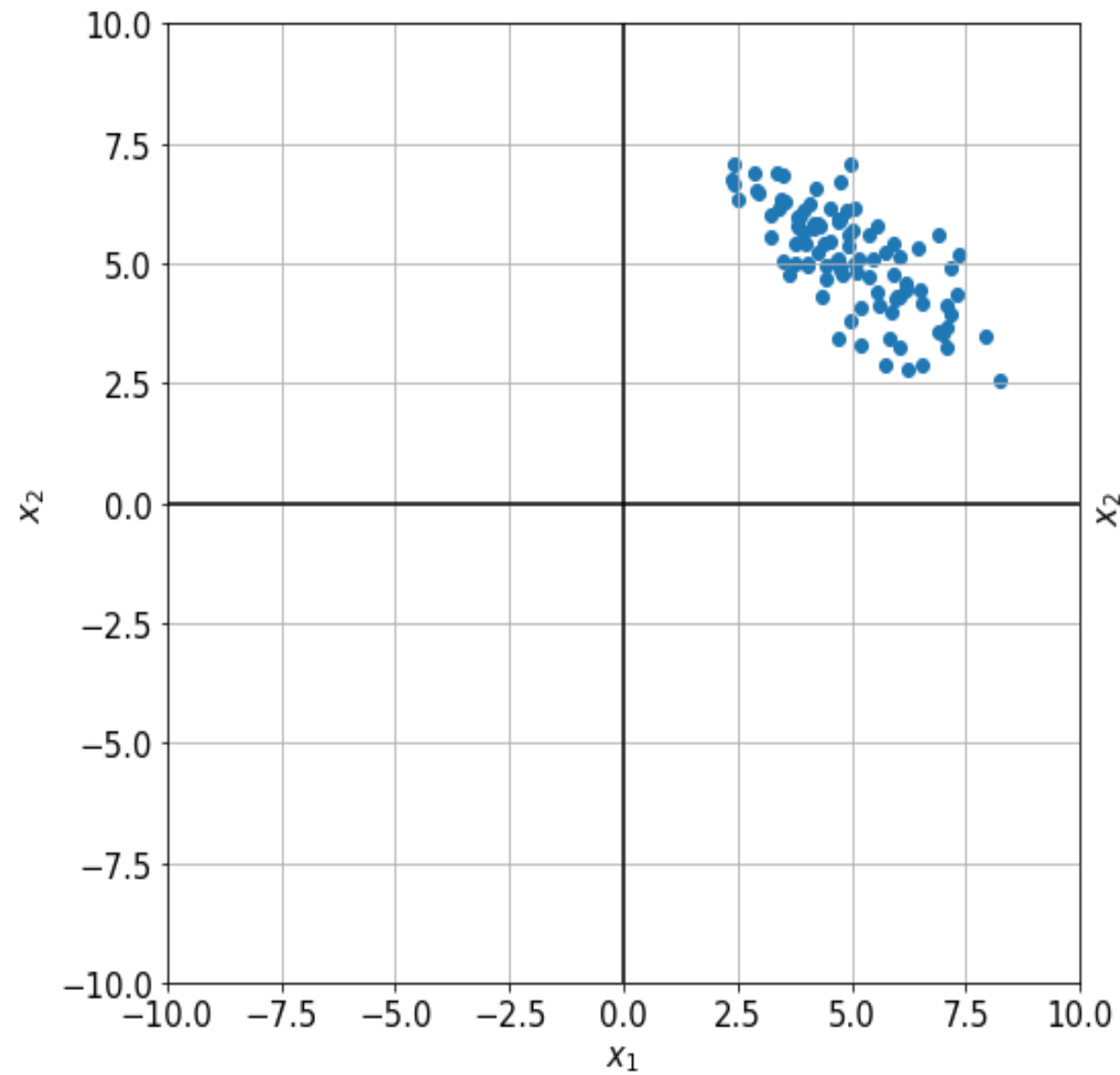
Centering



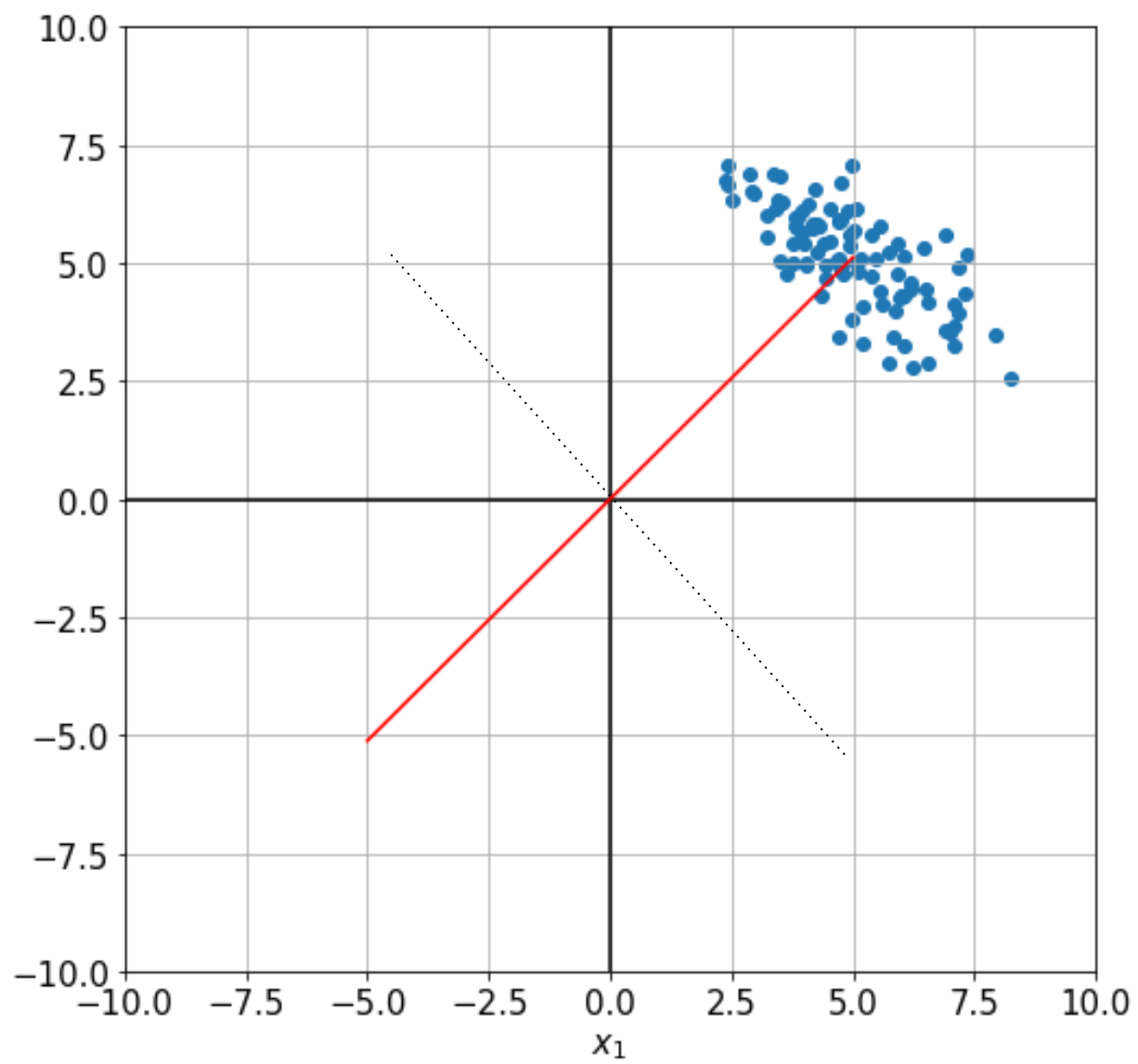
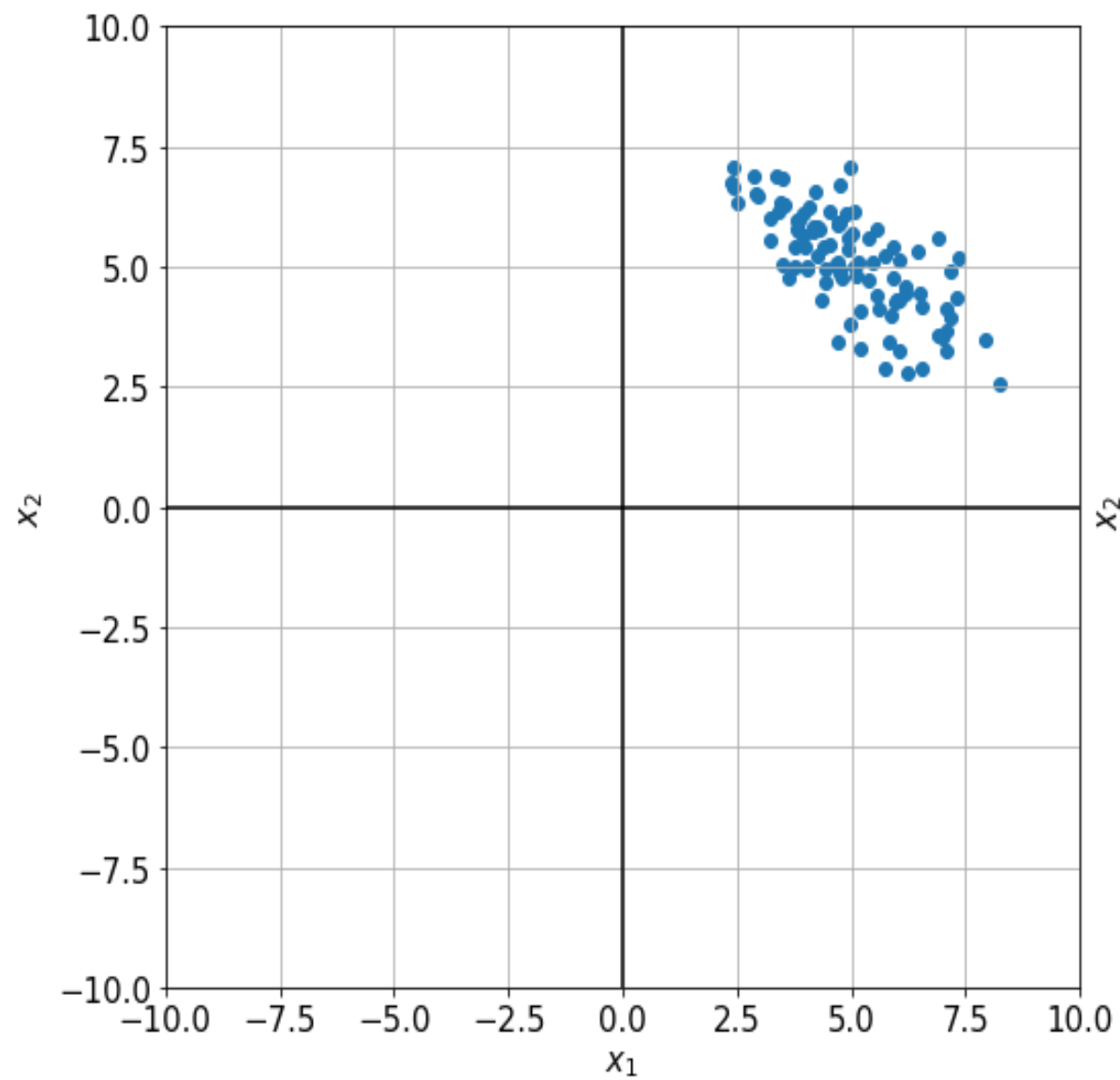
Centering



Centering



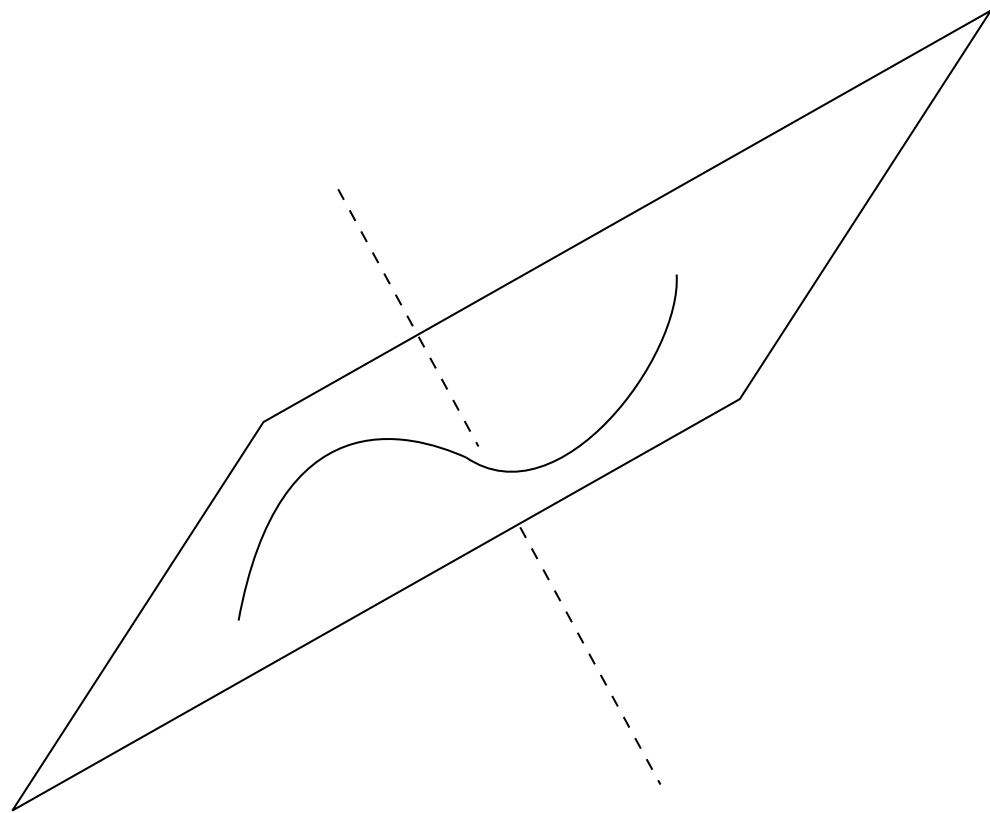
Centering



Other Directions

$$n = 100$$

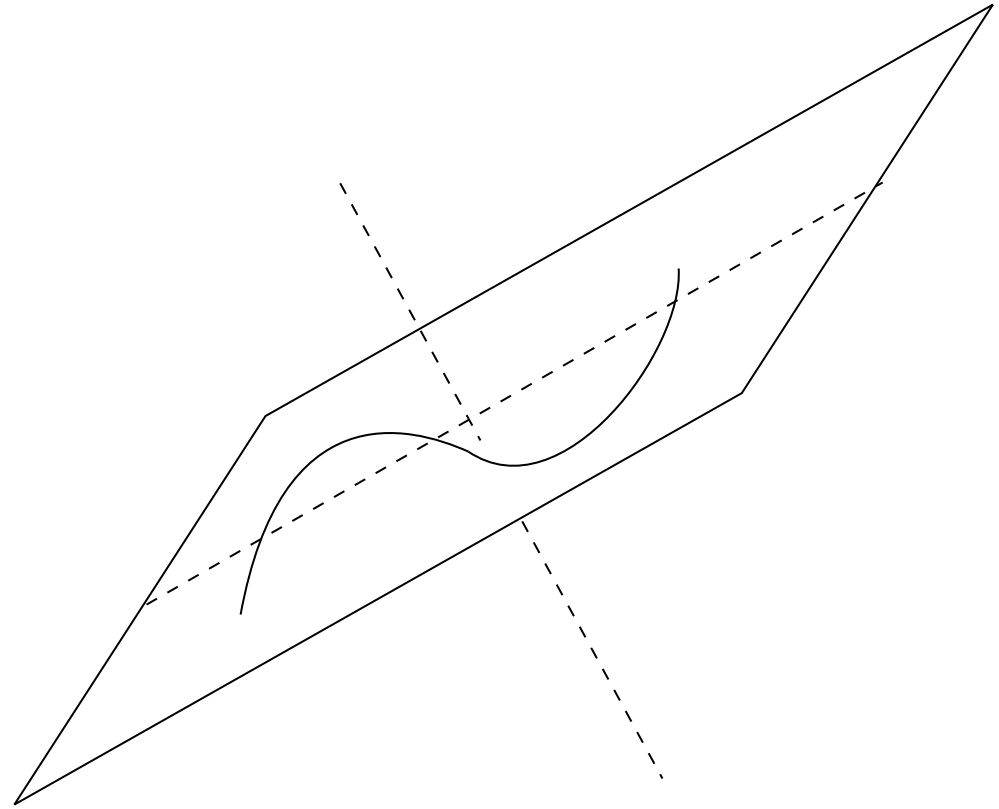
$$x_1, x_2, x_3$$



Other Directions

$$n = 100$$

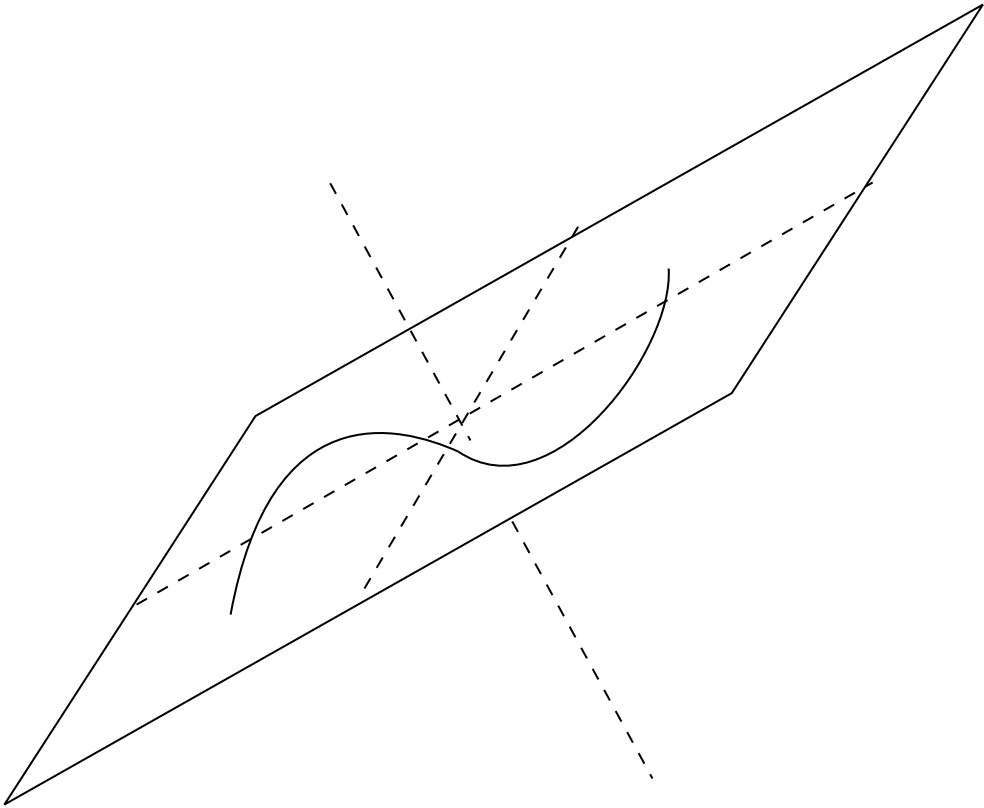
$$x_1, x_2, x_3$$



Other Directions

$n = 100$

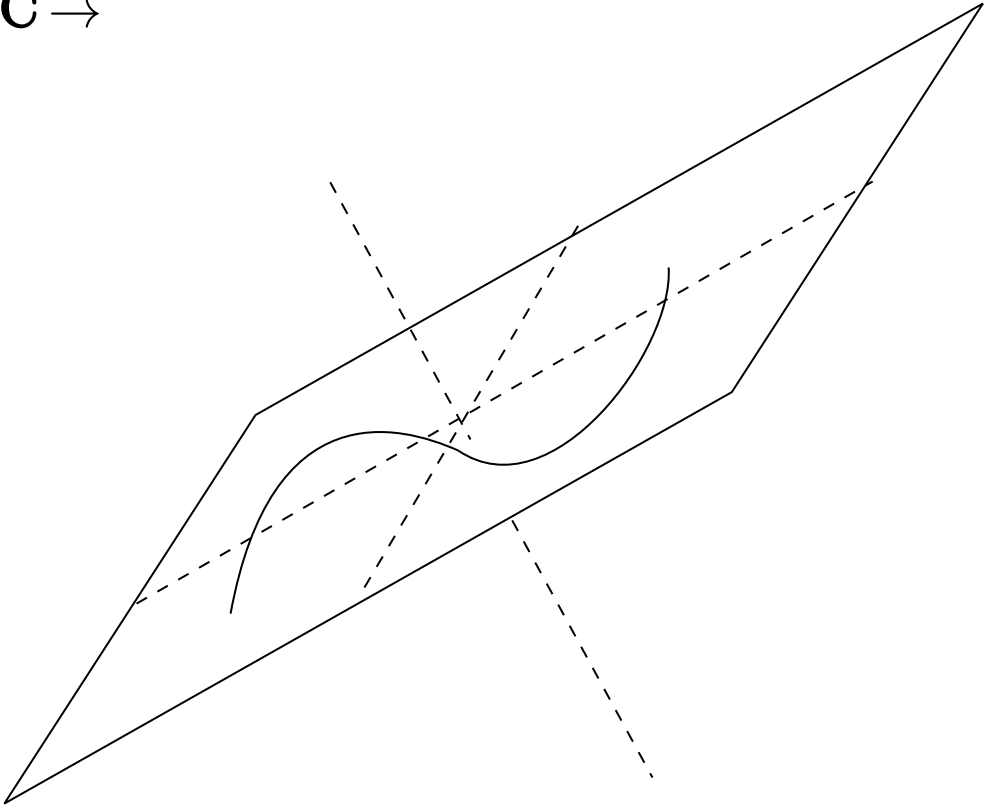
x_1, x_2, x_3



Other Directions

$n = 100$ $\mathbf{C} \rightarrow$

x_1, x_2, x_3

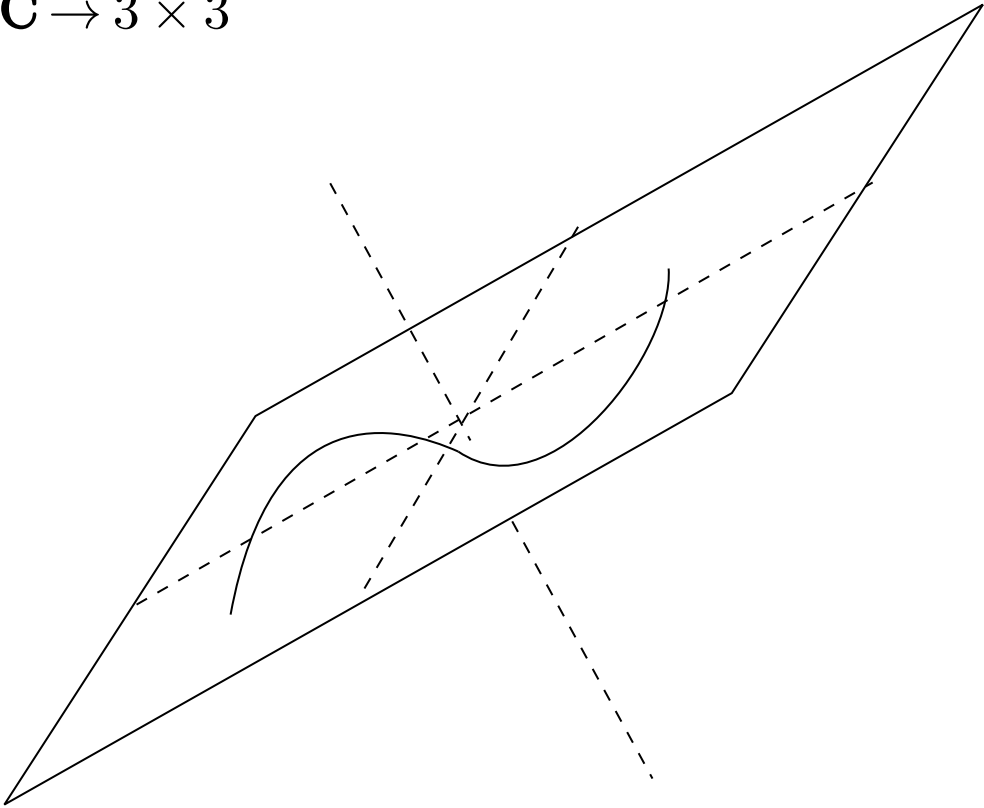


Other Directions

$n = 100$

$\mathbf{C} \rightarrow 3 \times 3$

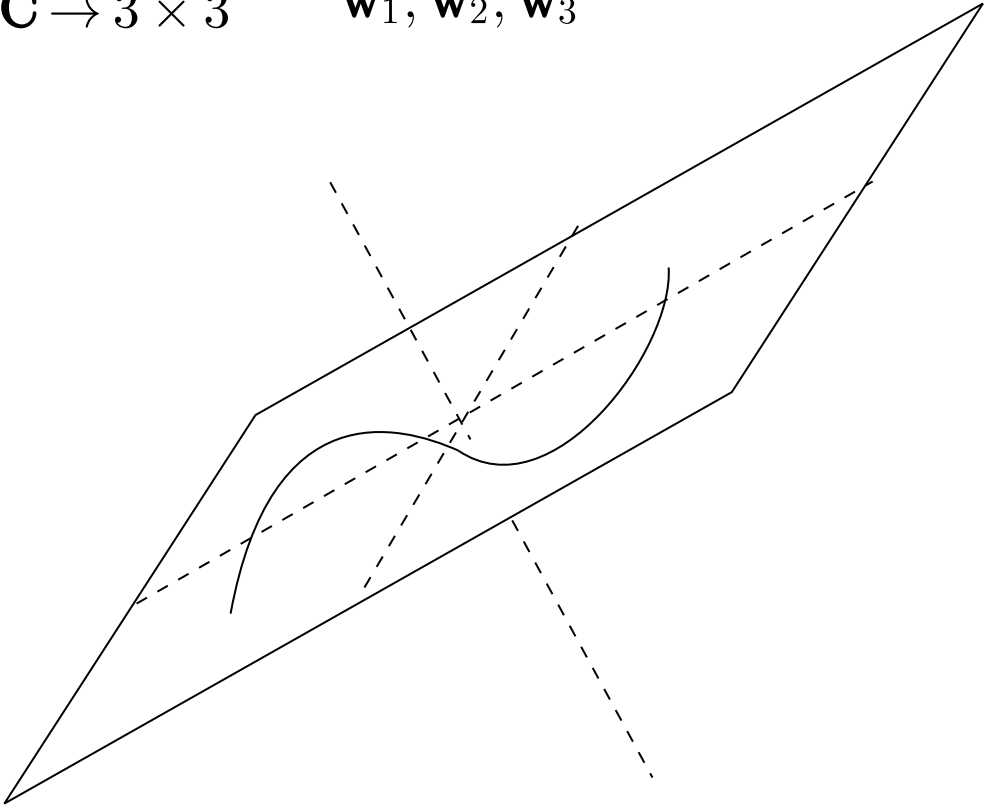
x_1, x_2, x_3



Other Directions

$n = 100$ $\mathbf{C} \rightarrow 3 \times 3$ $\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3$

x_1, x_2, x_3



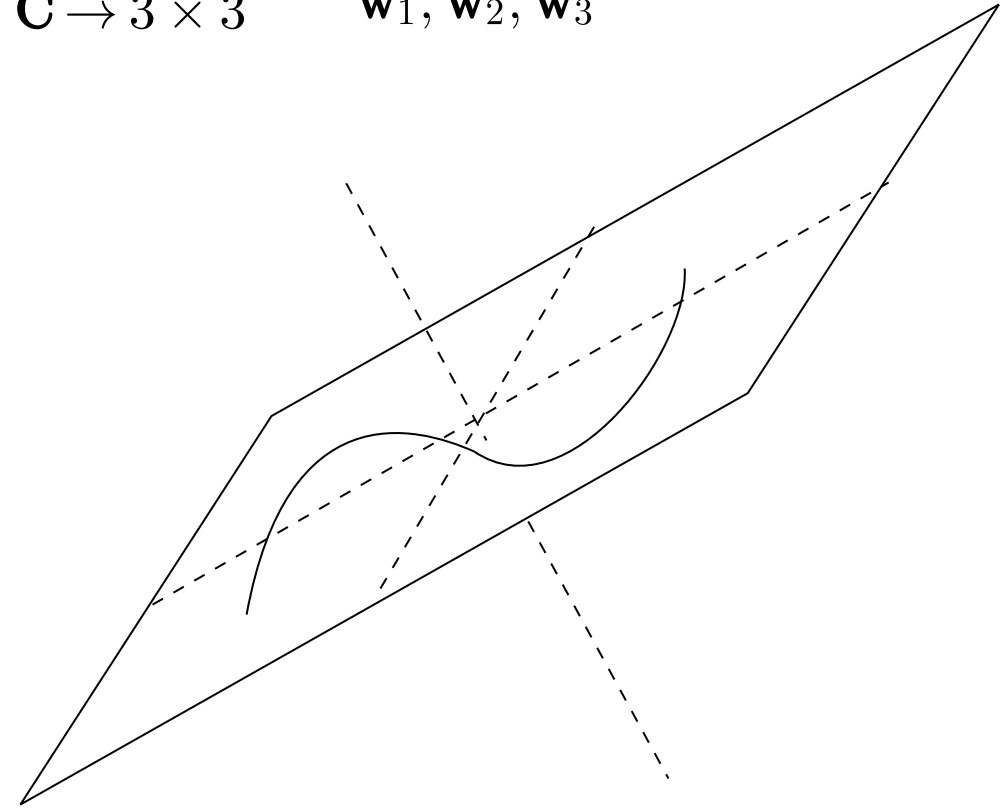
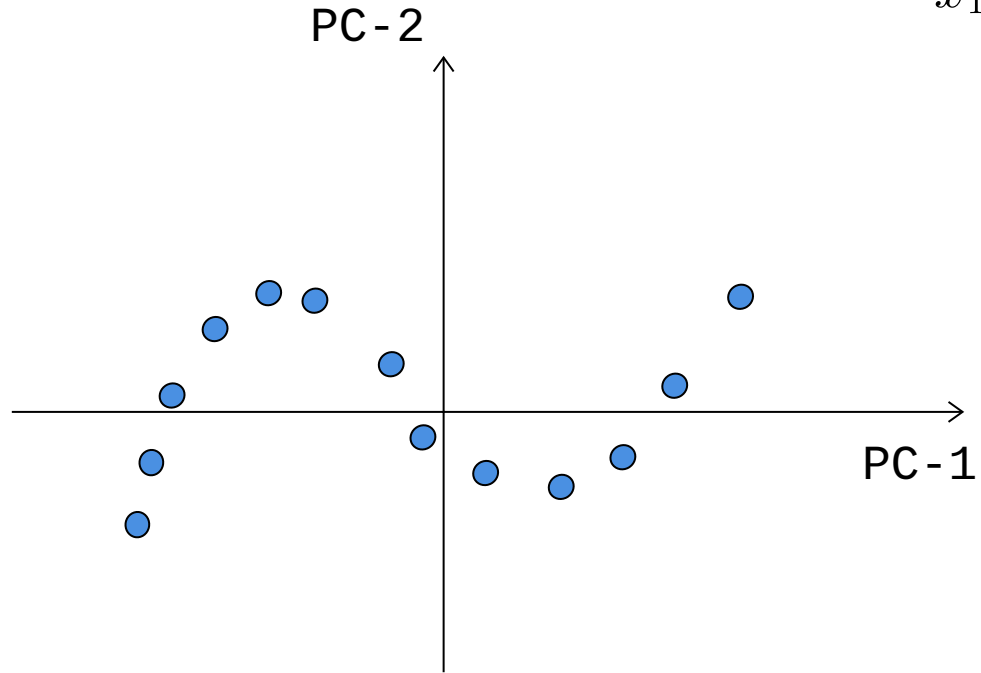
Other Directions

$$n = 100$$

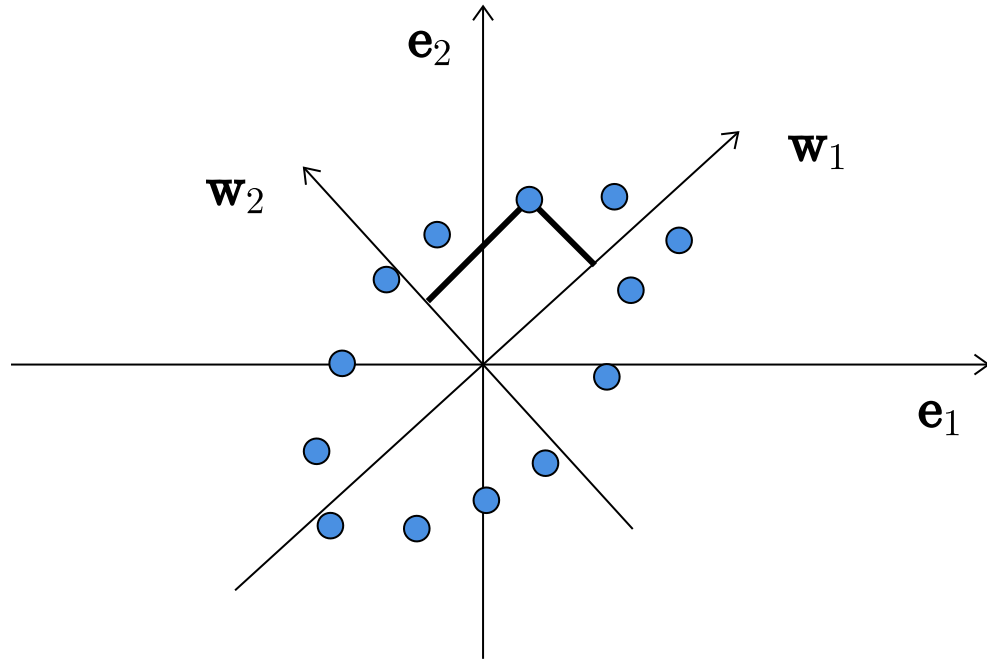
$$\mathbf{C} \rightarrow 3 \times 3$$

$$\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3$$

$$x_1, x_2, x_3$$



Some more aspects



$$\mathbf{Y} = \mathbf{Q}^T \mathbf{X}$$

$$= \begin{bmatrix} - & \mathbf{w}_1^T & - \\ - & \mathbf{w}_2^T & - \end{bmatrix} \begin{bmatrix} | & & | \\ \mathbf{x}_1 & \cdots & \mathbf{x}_n \\ | & & | \end{bmatrix}$$

$$= \begin{bmatrix} \mathbf{w}_1^T \mathbf{x}_1 & \cdots & \mathbf{w}_1^T \mathbf{x}_n \\ \mathbf{w}_2^T \mathbf{x}_1 & \cdots & \mathbf{w}_2^T \mathbf{x}_n \end{bmatrix}$$

$$\mathbf{X} = \begin{bmatrix} | & & | \\ \mathbf{x}_1 & \cdots & \mathbf{x}_n \\ | & & | \end{bmatrix}$$

$$\mathbf{C} = \frac{1}{n} \mathbf{X} \mathbf{X}^T$$

$$\mathbf{C} = \mathbf{Q} \mathbf{D} \mathbf{Q}^T$$

(spectral theorem)

$$\mathbf{Q} = \begin{bmatrix} | & | \\ \mathbf{w}_1 & \mathbf{w}_2 \\ | & | \end{bmatrix}$$

$$\mathbf{Q}^T \mathbf{Q} = \mathbf{I}$$

$$\mathbf{x}_i = (\mathbf{x}_i^T \mathbf{w}_1) \mathbf{w}_1 + (\mathbf{x}_i^T \mathbf{w}_2) \mathbf{w}_2$$

$$\mathbf{Y} = \mathbf{Q}^T \mathbf{X}$$

(rotation)

$$\mathbf{C}' = \frac{1}{n} \mathbf{Y} \mathbf{Y}^T$$

$$= \frac{1}{n} (\mathbf{Q}^T \mathbf{X}) (\mathbf{X}^T \mathbf{Q})$$

$$= \mathbf{Q}^T \mathbf{C} \mathbf{Q}$$

$$= \mathbf{D}$$

$$= \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

\mathbf{C}' : Covariance matrix
in the new basis
is diagonal
(decorrelated)

PCA

Dataset

$$D = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}, \mathbf{x}_i \in \mathbb{R}^d$$

Reconstruction error for direction \mathbf{w}

$$\frac{1}{n} \cdot \sum_{i=1}^n \|\mathbf{x}_i - (\mathbf{x}_i^T \mathbf{w}) \mathbf{w}\|^2$$

Covariance Matrix

- $\mathbf{C} = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^T$, centered
- $(\lambda_k, \mathbf{w}_k)$ is an eigenpair of \mathbf{C}
- $\lambda_1 \geq \dots \geq \lambda_d \geq 0$

Minimize reconstruction error
(OR) Maximize variance

$$\max_{\mathbf{w}, \|\mathbf{w}\|=1} \mathbf{w}^T \mathbf{C} \mathbf{w}$$

Principal components

- $\mathbf{w}_1, \dots, \mathbf{w}_d$
- $\mathbf{w}_i^T \mathbf{w}_j = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases}$
- \mathbf{w}_k is the k^{th} eigenvector of \mathbf{C}

Projection of \mathbf{x} along k^{th} p.c.
 $(\mathbf{x}^T \mathbf{w}_k) \mathbf{w}_k$

Reconstruction of \mathbf{x} using top- K p.c, $K \leq d$

$$\sum_{k=1}^K (\mathbf{x}^T \mathbf{w}_k) \mathbf{w}_k$$

Variance of D along k^{th} p.c.

$$\lambda_k = \mathbf{w}_k^T \mathbf{C} \mathbf{w}_k$$

Choice of K

$$\frac{\sum_{k=1}^K \lambda_k}{\sum_{k=1}^d \lambda_k} \geq 0.95$$

Credits and References

- Professor Arun Rajkumar
 - The content in almost all of these slides has been borrowed from professor Arun's [videos](#) and slides.
 - The notation is also derived from there. The only difference is in the tool and method of presentation.
- [mathcha.io](#) is the tool used to prepare these slides.
- The example concerning the train journey and particle motion in 3d was inspired by this [tutorial](#).
- The example concerning non-centered dataset was derived from this [stackexchange post](#).