

# Finite Volume Methods for Hydrodynamics

**Rony Keppens**

*Centre for Plasma-Astrophysics, K.U.Leuven (Belgium)*



*& FOM-Institute for Plasma Physics 'Rijnhuizen'  
& Astronomical Institute, Utrecht University*



**Solaire postgraduate school**, Bochum march 3-14 2008

# Finite Volume Methods for hydrodynamics

## Overview

- **Linear hyperbolic systems and nonlinear scalar equations:** Riemann problem, Burgers equation, shocks and rarefactions. Explicit time integration, CFL condition, TVD concept and TVDLF method.
- **Finite Volume discretization:** integral versus differential form, from 1D to multi-D.
- **Euler equations:** gas dynamics in 1D, solution of the Riemann problem. TVDLF simulations.
- **Roe solver for Euler equations:** characteristic based shock-capturing schemes. Comparison with TVDLF.

## Linear Hyperbolic Systems

- constant coefficient linear system

$$\vec{q}_t + A\vec{q}_x = 0$$

$\Rightarrow$  with  $\vec{q}(x, t) \in \mathbb{R}^m$  and matrix  $A \in \mathbb{R}^{m \times m}$

- **hyperbolic** when  $A$  is diagonalizable with real eigenvalues
  - $\Rightarrow$  **strictly hyperbolic** when distinct
  - $\Rightarrow m$  right eigenvectors +  $m$  real eigenvalues

$$A\vec{r}_p = \lambda_p\vec{r}_p \text{ with } p : 1, \dots, m$$

- write as

$$[A] [\vec{r}_1 \mid \vec{r}_2 \mid \dots \mid \vec{r}_m] = [\vec{r}_1 \mid \vec{r}_2 \mid \dots \mid \vec{r}_m] \begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \dots & \\ & & & \lambda_m \end{bmatrix}$$

$\Rightarrow$  or shorthand  $A R = R \Lambda$  with diagonal matrix  $\Lambda$

$\Rightarrow$  **matrix  $R$  with right eigenvectors as columns**

- The solution to system  $\vec{q}_t + A \vec{q}_x = 0$  is equivalent to:

$\Rightarrow$  pre-multiply with  $R^{-1}$  or:

$$(R^{-1} \vec{q})_t + R^{-1} (R \Lambda R^{-1}) \vec{q}_x = 0$$

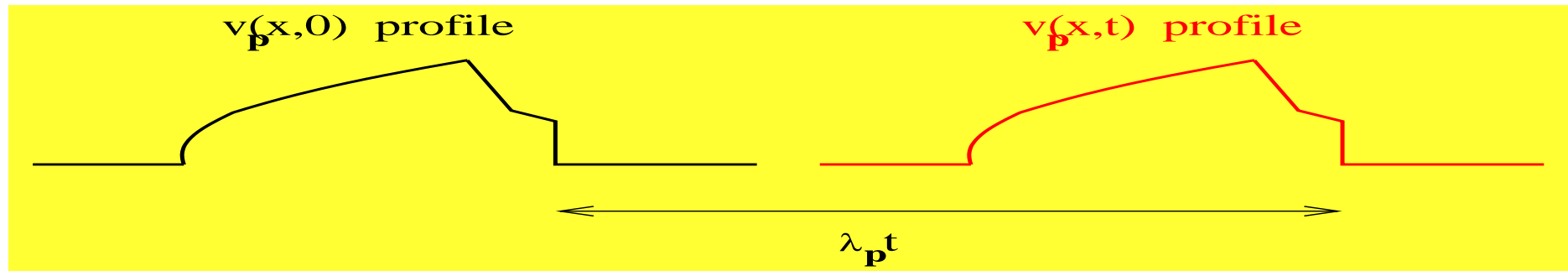
$\Rightarrow$  redefine  $\vec{v} \equiv R^{-1} \vec{q}$  to get

$$\vec{v}_t + \Lambda \vec{v}_x = 0$$

$\Rightarrow$   $m$  independent constant coefficient linear advection equations!

- Each advection equation has trivial analytic solution:

$$v_p(x, t) = v_p(x - \lambda_p t, 0)$$



⇒ **analytic solution to the full linear hyperbolic system is**

$$\Rightarrow \vec{q}(x, t) = \sum_{p=1}^m v_p(x - \lambda_p t, 0) \vec{r}_p$$

⇒ **depends on initial data at  $m$  discrete points**

⇒ superposition of  $m$  waves, advected independently without distortion

- nomenclature:  $\vec{v}$  are ‘characteristic variables’

⇒ curves  $x = x_o + \lambda_p t$  are “p-characteristics”

## The Riemann problem for a linear hyperbolic system

- Riemann Problem for linear hyperbolic system:

$$\Rightarrow \text{initial data } \vec{q}(x, 0) = \begin{cases} \vec{q}_l & x < 0 \\ \vec{q}_r & x > 0 \end{cases}$$

$\Rightarrow$  **decompose initial data in terms of right eigenvectors as**

$$\vec{q}_l = \sum_{p=1}^m \alpha_p \vec{r}_p$$

$$\vec{q}_r = \sum_{p=1}^m \beta_p \vec{r}_p$$

- then at  $t = 0$ , characteristic variables are  $v_p(x, 0) = \begin{cases} \alpha_p & x < 0 \\ \beta_p & x > 0 \end{cases}$

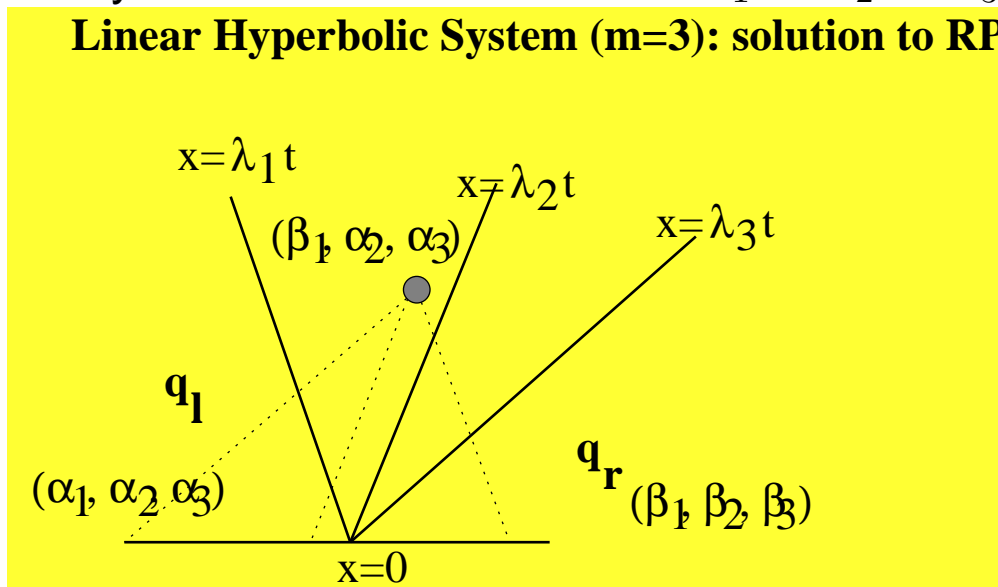
$$\Rightarrow \text{hence } v_p(x, t) = \begin{cases} \alpha_p & \text{if } x - \lambda_p t < 0 \\ \beta_p & \text{if } x - \lambda_p t > 0 \end{cases}$$

- the solution to the Riemann problem for linear hyperbolic system is then:

$$\vec{q}(x, t) = \sum_{\text{all } p \text{ where } x - \lambda_p t < 0} \alpha_p \vec{r}_p + \sum_{\text{all } p \text{ where } x - \lambda_p t > 0} \beta_p \vec{r}_p$$

$\Rightarrow$  graphically illustrated for  $m = 3$  with  $\lambda_1 < \lambda_2 < \lambda_3$

**Linear Hyperbolic System (m=3): solution to RP**



- constant states separated by discontinuities**

$\Rightarrow$  traveling at characteristic speeds

$\Rightarrow$  Note: jumps are eigenvectors of matrix  $A$

## Scalar nonlinear conservation law

- nonlinear scalar conservation law for  $u(x, t)$  written as

$$u_t + (f(u))_x = 0$$

- **inviscid Burgers equation** for  $f(u) = u^2/2$

⇒ quasi-linear form (assuming differentiability):

$$u_t + u u_x = 0$$

⇒ characteristic speed from Jacobian, i.e. derivative,  $f_u = u \equiv f'(u)$

⇒ similar to **linear advection equation**  $u_t + v u_x = 0$  (fixed  $v$ ), which has trivial solution:  $u(x, 0)$  advected with speed  $v$



- **Nonlinearity** in inviscid Burgers  $u_t + u u_x = 0$

⇒ advection with local speed  $u$

- Consider  $t = 0$  triangular pulse (width  $2x_0$ , height  $h_0$ ) given by

$$u(x, 0) = \begin{cases} u_0 & x \leq -x_0 \\ u_0 + h_0 \frac{x_0 + x}{x_0} & -x_0 < x \leq 0 \\ u_0 + h_0 \frac{x_0 - x}{x_0} & 0 < x \leq x_0 \\ u_0 & x > x_0 \end{cases}$$

⇒ **wave steepening and shock formation** expected!

- tip of triangle experiences fastest rightward advection

⇒ conserving total area underneath triangle, front edge steepens.

- discontinuity forms at time  $t_s = x_0/h_0$

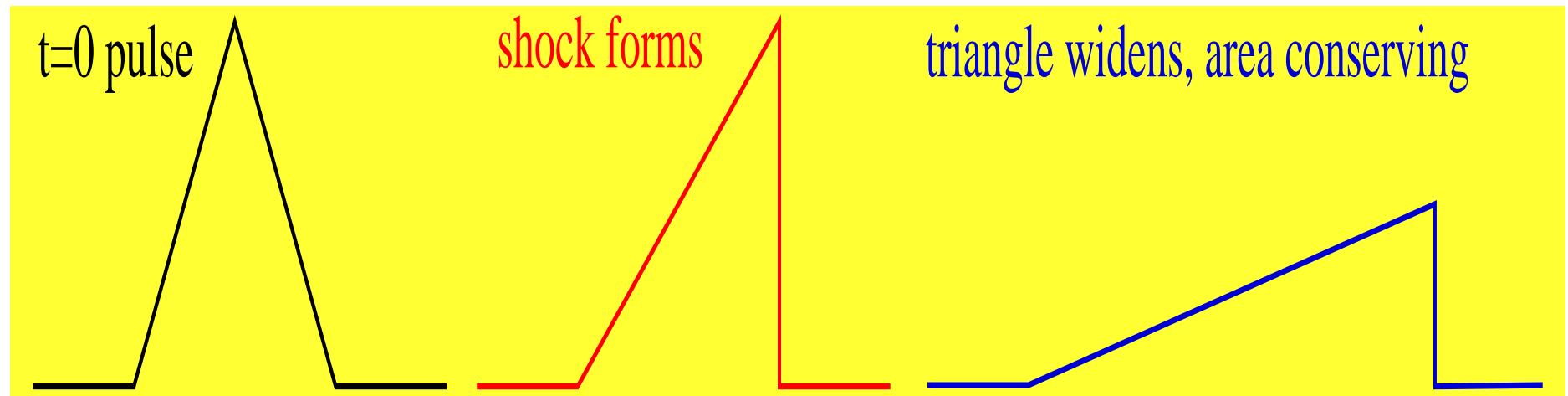
⇒ tip of triangle catches up rightmost point of front edge

⇒ **discrete equivalent of conservation law across discontinuity**

⇒ **Rankine-Hugoniot relation** for left  $u_l$  and right  $u_r$  values

$$f(u_l) - f(u_r) = s(u_l - u_r)$$

- for inviscid Burgers case, find shock speed  $s = (u_l + u_r)/2$
- fully analytic solution to triangular pulse problem
  - $\Rightarrow$  after shock forms, base of triangle widens due to the speed difference between left edge traveling with  $u_0$ , and shocked right edge traveling at speed  $s(t)$ . In accord with conservation, the height of the triangle must therefore decrease in time.



$\Rightarrow$  **Assignment: try different numerical schemes to simulate this evolution**

## The Riemann problem for Burgers

- specific initial condition separating 2 constant states
- Riemann problem for scalar conservation law

$$u = u_l \text{ for } x \leq 0$$

$$u = u_r \text{ for } x > 0$$

- Rankine-Hugoniot states

$$f(u_l) - f(u_r) = s(u_l - u_r)$$

⇒ symmetric in arguments  $u_l$  and  $u_r$

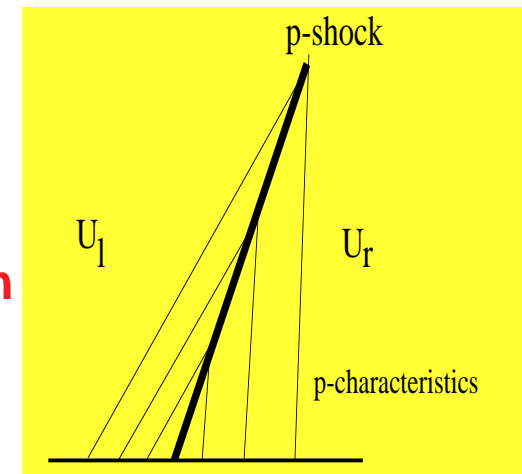
- For inviscid Burgers: only shock expected for  $u_l > u_r$

⇒ extra condition for admissible shock: **Lax entropy condition**

$$f'(u_l) > s > f'(u_r)$$

⇒ **shock speed between characteristic speeds of 2 states**

⇒ characteristics 'go into the shock'



- **Rarefaction** waves for Burgers equation

⇒ when  $u_l < u_r$  expect right state 'runs away' from left

⇒ try '**centered simple wave**'  $u(\xi) = u(x/t)$

⇒ conservation law translates into

$$f'(u) \frac{du}{d\xi} = \xi \frac{du}{d\xi}$$

⇒ rarefaction wave: for Burgers:

$$u(x, t) = u(x/t) = \begin{cases} u_l & x < u_l t \\ x/t & u_l t < x < u_r t \\ u_r & x > u_r t \end{cases}$$

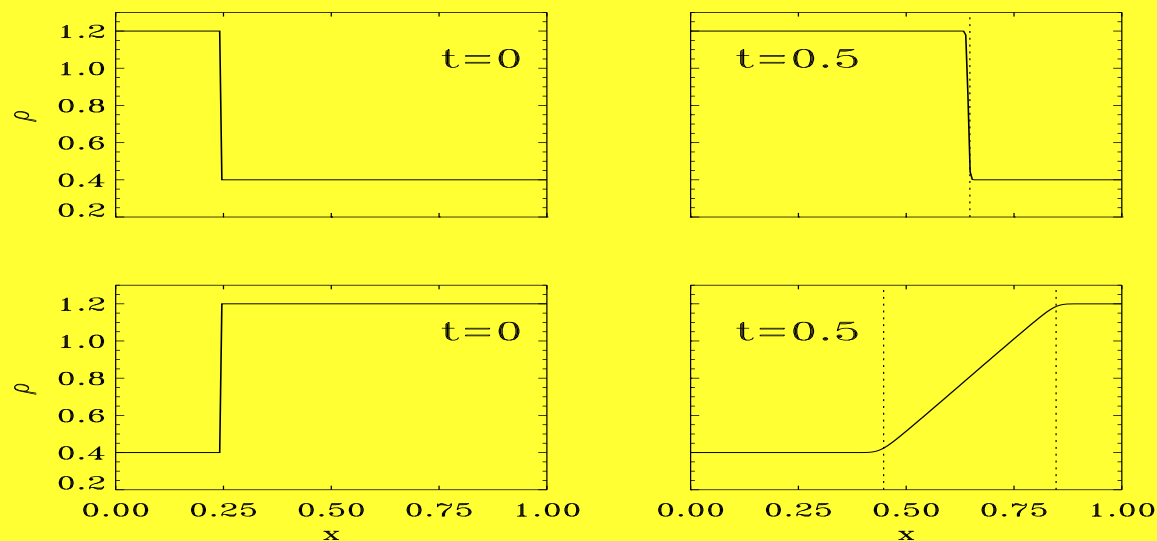
⇒  $u$  decreases (density: medium gets rarefied) when signal passes

- Riemann problem for inviscid Burgers has two cases:**

$\Rightarrow \rho_l > \rho_r$ : shock traveling at speed  $s = \frac{\rho_l + \rho_r}{2}$

$\Rightarrow \rho_l < \rho_r$ : rarefaction wave  $\rho(x, t) = \rho(x/t) = \begin{cases} \rho_l & x < \rho_l t \\ x/t & \rho_l t < x < \rho_r t \\ \rho_r & x > \rho_r t \end{cases}$

$\Rightarrow$  Numerically with TVDLF scheme (see later):



## Numerical methods for nonlinear conservation law

- introduce spatial  $x_i = i\Delta x$  and temporal  $t^n = n\Delta t$  steps  
⇒ try **explicit** scheme on Burgers, directly discretize  $u_t + u u_x = 0$  to

$$u_i^{n+1} - u_i^n + \frac{\Delta t}{\Delta x} u_i^n (u_i^n - u_{i-1}^n) = 0$$

⇒ initial data  $[1, 1, 1, 0, 0, 0]$  remains solution to this scheme

⇒ **WRONG !!!!!** should be traveling shock at speed  $s = 0.5$

- reason: above scheme non-conservative (but ok for continuous data!)

⇒ **conservative scheme** is of form

$$\mathbf{U}_i^{n+1} = \mathbf{U}_i^n - \frac{\Delta t}{\Delta x} [\mathbf{F}_{i+1/2} - \mathbf{F}_{i-1/2}]$$

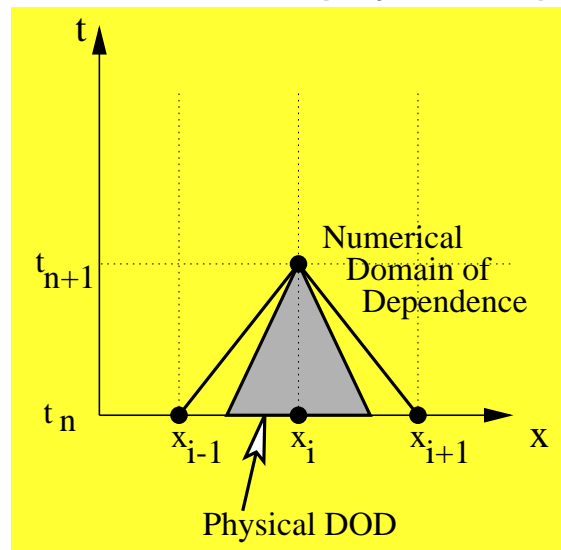
⇒ numerical fluxes  $\mathbf{F}_{i+1/2}$ : time-average fluxes over cell edges  $x_i + \frac{1}{2}\Delta x \equiv x_{i+\frac{1}{2}}$

## Explicit time integration

- calculate fluxes (and sources) from known time level  $t^n$
- Explicit:  $\Delta t$  restricted by Courant, Friedrichs, Lewy condition  
*domain of dependence of discretization must include PDE domain of dependence*

$\Rightarrow \Delta t \leq$  crossing time of cells by fastest wave

$\Rightarrow \Delta t \leq \Delta x / c^{\max}$  with maximal physical speed  $c^{\max}$



## Lax-Friedrichs and Max-Cormack methods

- Better explicit discretization: **first order** Lax-Friedrichs

$$u_i^{n+1} = \frac{u_{i+1}^n + u_{i-1}^n}{2} - \frac{\Delta t}{2\Delta x} (f_{i+1}^n - f_{i-1}^n)$$

⇒ scheme is **conditionally stable**: restriction by CFL condition

$$\left| \frac{\Delta t}{\Delta x} f'(u_i) \right| \leq 1$$

⇒ conservative scheme, identify numerical flux as

$$F_{i+1/2}^{\text{LF}} = \frac{1}{2} \left\{ f_{i+1} + f_i - \frac{\Delta x}{\Delta t} [u_{i+1} - u_i] \right\}$$

- first order accuracy: local truncation error  $\propto \Delta t$



- another, multilevel method: **two-step MacCormack method:**

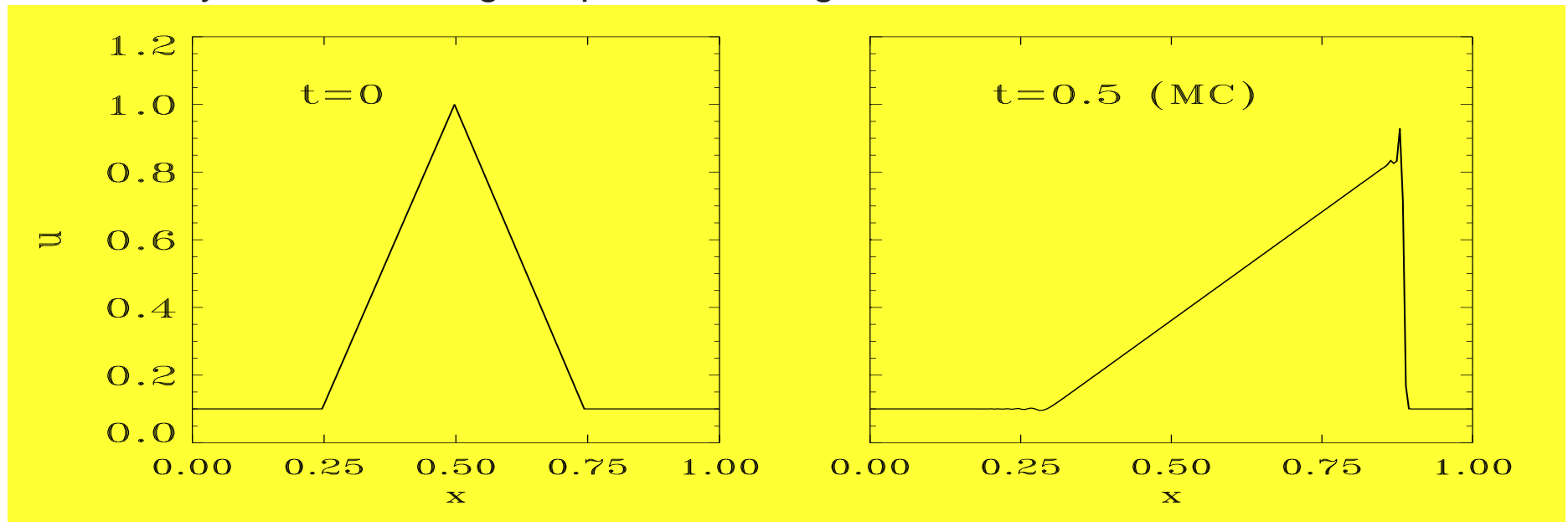
‘predictor’: 
$$u_i^* = u_i^n - \frac{\Delta t}{\Delta x} (f_{i+1}^n - f_i^n)$$

‘corrector’: 
$$u_i^{n+1} = \frac{1}{2}(u_i^n + u_i^*) - \frac{1}{2} \frac{\Delta t}{\Delta x} (f_i^* - f_{i-1}^*)$$

⇒ step size in predictor now  $\Delta t$

⇒ second order accurate: local truncation error  $\propto \Delta t^2$

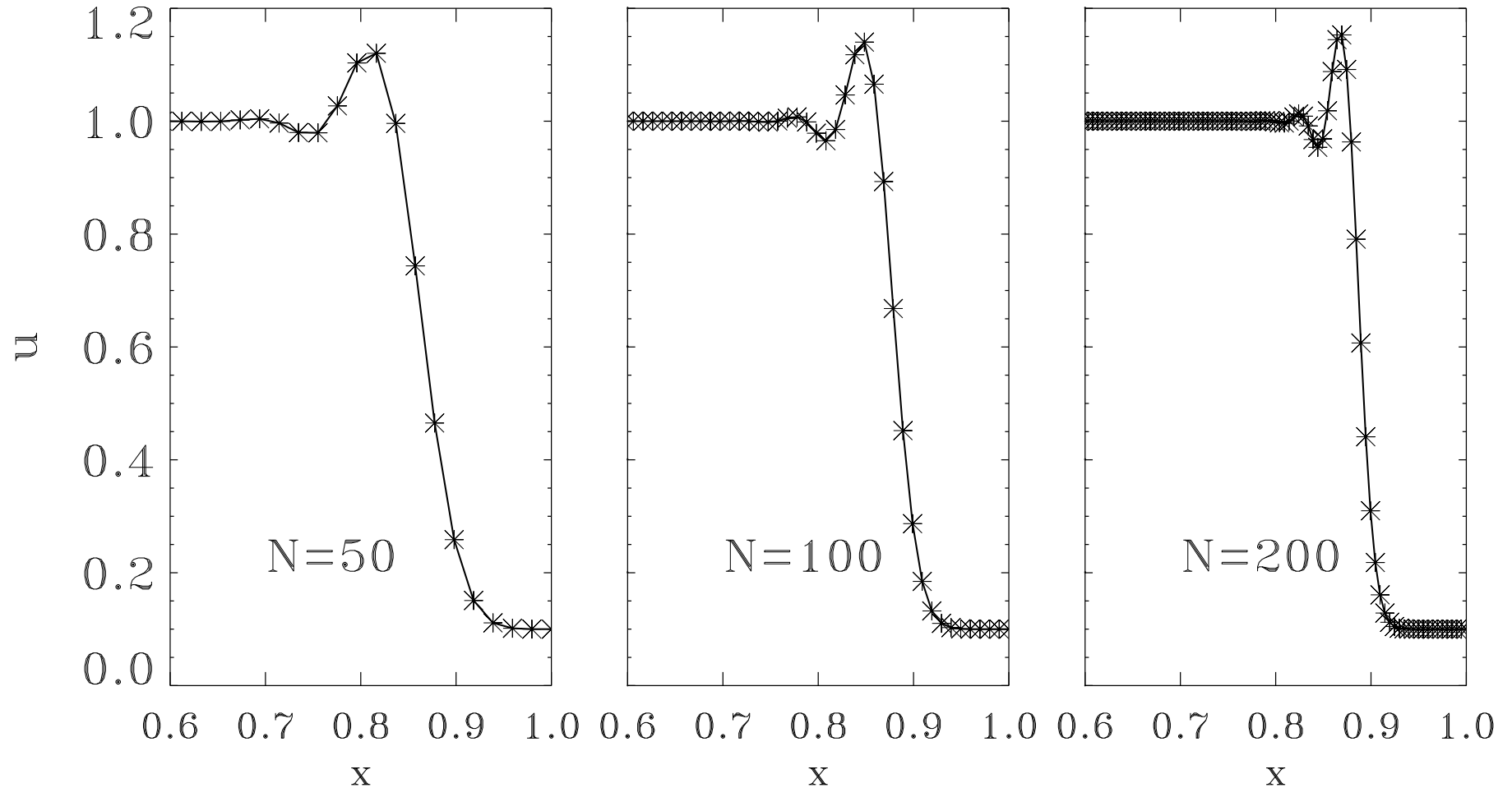
- Numerically simulate triangular pulse for Burgers



⇒ in agreement with theory, except for the ‘wiggles’

- MacCormack method: **dispersive**

⇒ manifests **Gibbs phenomenon**: for linear advection of discontinuity



⇒ **non-monotonicity preserving**: monotone  $u(x, 0)$  develops extrema

## Total Variation Diminishing concept

- **total variation** of function  $u(x)$  on domain  $[0, 1]$  defined as

$$TV(u) \equiv \int_0^1 \left| \frac{du}{dx} \right| dx$$

$\Rightarrow$  total variation of numerical approximation of  $u$

$$TV(u^n) = \sum_{i=0}^N |u_{i+1}^n - u_i^n|$$

- scheme is **total variation diminishing** (TVD) in time if

$$TV(u^{n+1}) \leq TV(u^n) \quad \forall n$$

$\Rightarrow$  solution scalar conservation law has TVD property  $\forall t_2 > t_1$

$$TV(u(x, t_2)) \leq TV(u(x, t_1))$$

- **a TVD scheme is clearly monotonicity preserving!**

⇒ a new local extremum would raise TV

- Harten: any scheme written in general form

$$u_i^{n+1} = u_i^n + A_{i+1/2} \underbrace{(u_{i+1}^n - u_i^n)}_{\Delta u_{i+1/2}^n} - B_{i-1/2} \underbrace{(u_i^n - u_{i-1}^n)}_{\Delta u_{i-1/2}^n}$$

⇒ is TVD when coefficients  $A_{i+1/2}$  and  $B_{i-1/2}$  obey

$$A_{i+1/2} \geq 0$$

$$B_{i-1/2} \geq 0$$

$$0 \leq A_{i+1/2} + B_{i+1/2} \leq 1$$

- **first order Lax-Friedrichs scheme is TVD**, since rewrites as

$$u_i^{n+1} = u_i^n + \frac{1}{2} \left( 1 - \frac{\Delta t}{\Delta x} \frac{f_{i+1}^n - f_i^n}{\Delta u_{i+\frac{1}{2}}^n} \right) \Delta u_{i+\frac{1}{2}}^n - \frac{1}{2} \left( 1 + \frac{\Delta t}{\Delta x} \frac{f_i^n - f_{i-1}^n}{\Delta u_{i-\frac{1}{2}}^n} \right) \Delta u_{i-\frac{1}{2}}^n$$

⇒ TVD requirements translate to CFL condition

$$\left| \frac{\Delta t}{\Delta x} \frac{f_{i+1}^n - f_i^n}{u_{i+1}^n - u_i^n} \right| \leq 1$$

⇒ **generalize Lax-Friedrichs scheme to second order, keep TVD property**

## TVDLF scheme

- Recall: numerical flux for first-order Lax-Friedrichs is

$$F_{i+1/2}^{\text{LF}} = \frac{1}{2} \left\{ f_{i+1} + f_i - \frac{\Delta x}{\Delta t} [u_{i+1} - u_i] \right\}$$

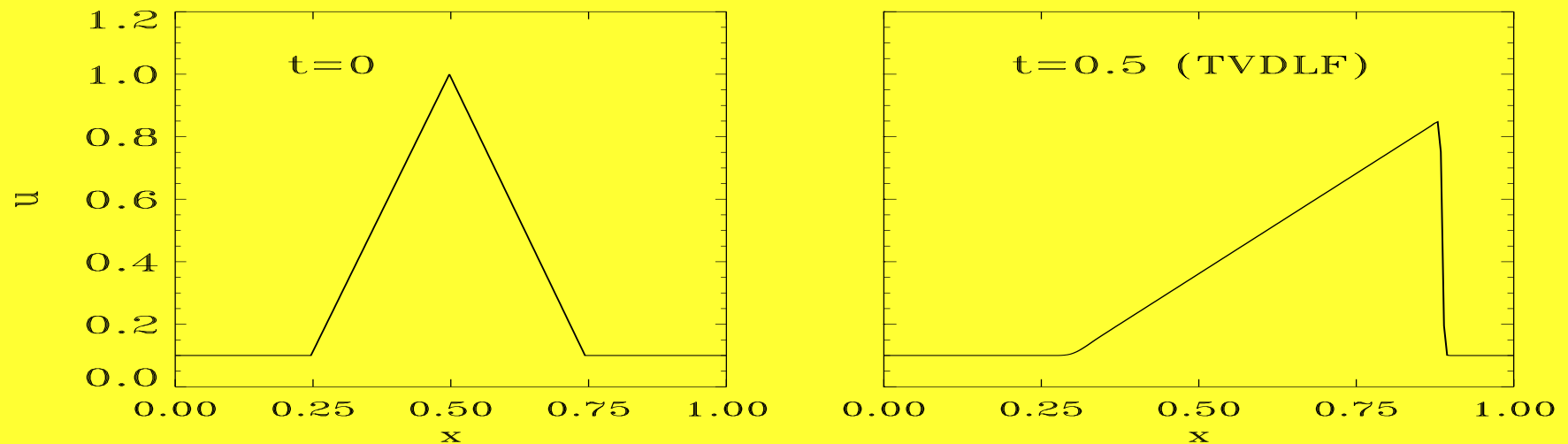
⇒ can improve scheme by changing to **Local Lax-Friedrichs** flux

$$F_{i+1/2}^{\text{LLF}} = \frac{1}{2} \left\{ f_{i+1} + f_i - |\alpha_{i+\frac{1}{2}}| [u_{i+1} - u_i] \right\}$$

⇒  $\alpha_{i+1/2} = \frac{f_{i+1}^n - f_i^n}{u_{i+1}^n - u_i^n}$ , proxy for local characteristic speed  $f'(u)$

⇒ still in accord with TVD, if CFL condition satisfied

- turn into **second order accurate TVDLF scheme** by
  - ⇒ use predictor-corrector approach (raise temporal accuracy)
  - ⇒ use some form of linear interpolation in space (but keep TVD!)
- **Numerically simulate triangular pulse for Burgers**



- ⇒ Riemann problem for  $u_l > u_r$
- ⇒ Riemann problem for  $u_l < u_r$

## TVDLF scheme

- Robust, **general scheme to ANY hyperbolic system, ensures TVD (for scalar)**

⇒ Predictor-corrector approach for temporal advance

$$\mathbf{U}^{n+1/2} = \mathbf{U}^n + \frac{\Delta t}{2} [-\nabla \cdot \mathbf{F}(\mathbf{U}^n) + \mathbf{S}(\mathbf{U}^n)]$$

$$\mathbf{U}^{n+1} = \mathbf{U}^n + \Delta t \left[ -\nabla \cdot \mathbf{F}(\mathbf{U}^{n+1/2}) + \mathbf{S}(\mathbf{U}^{n+1/2}) \right]$$

⇒ CFL condition links  $\Delta t$  with  $\Delta x$  (explicit scheme)

- **slope limited linear reconstruction** and flux expression

$$\mathbf{F}_{i+\frac{1}{2}} = \frac{1}{2} \left\{ \mathbf{F}(\mathbf{U}_{i+\frac{1}{2}}^L) + \mathbf{F}(\mathbf{U}_{i+\frac{1}{2}}^R) - \left| c^{\max} \left( \frac{\mathbf{U}_{i+\frac{1}{2}}^L + \mathbf{U}_{i+\frac{1}{2}}^R}{2} \right) \right| \left[ \mathbf{U}_{i+\frac{1}{2}}^R - \mathbf{U}_{i+\frac{1}{2}}^L \right] \right\}$$

⇒ scalar  $c^{\max}$  denotes maximal physical propagation speed

⇒ for 1D HD  $c^{\max}$  is  $|v_x|$  plus sound speed, for MHD  $c^{\max} = |v_x| + c_f$



## Integral form of conservation law

- consider cell  $[x_1, x_2]$  and quantity  $u(x, t)$  within cell

$\Rightarrow$  flux over cell edge  $f(u)$  changes total mass from  $t_1$  to  $t_2$  by

$$\int_{x_1}^{x_2} u(x, t_2) dx = \int_{x_1}^{x_2} u(x, t_1) dx + \int_{t_1}^{t_2} f(x_1, t) dt - \int_{t_1}^{t_2} f(x_2, t) dt$$

$\Rightarrow$  integral form of scalar conservation law

$$u_t + (f(u))_x = 0$$

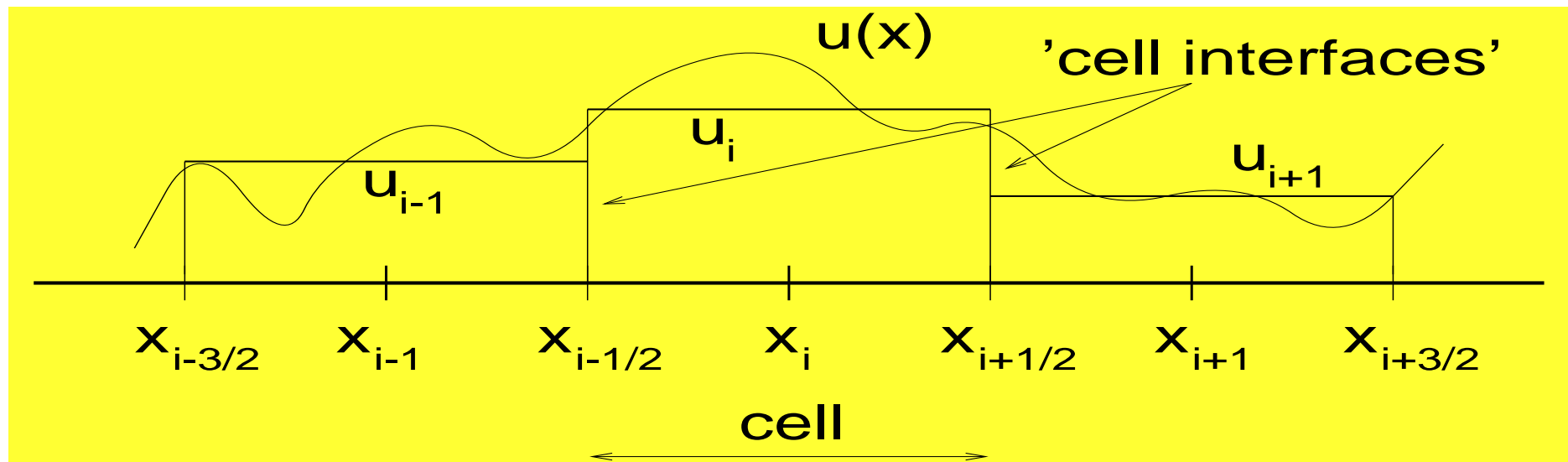
- integral form more general: allows for discontinuous solutions**

$\Rightarrow$  differential form assumes differentiable functions

- **Finite Volume** method in 1D for system of conservation laws

⇒ interpret  $U_i$  as average value of  $U(x, t)$  in  $[x_{i-1/2}, x_{i+1/2}]$ :

$$U_i(t) \equiv \frac{1}{\Delta x_i} \int_{x_{i-1/2}}^{x_{i+1/2}} U(x, t) dx ,$$



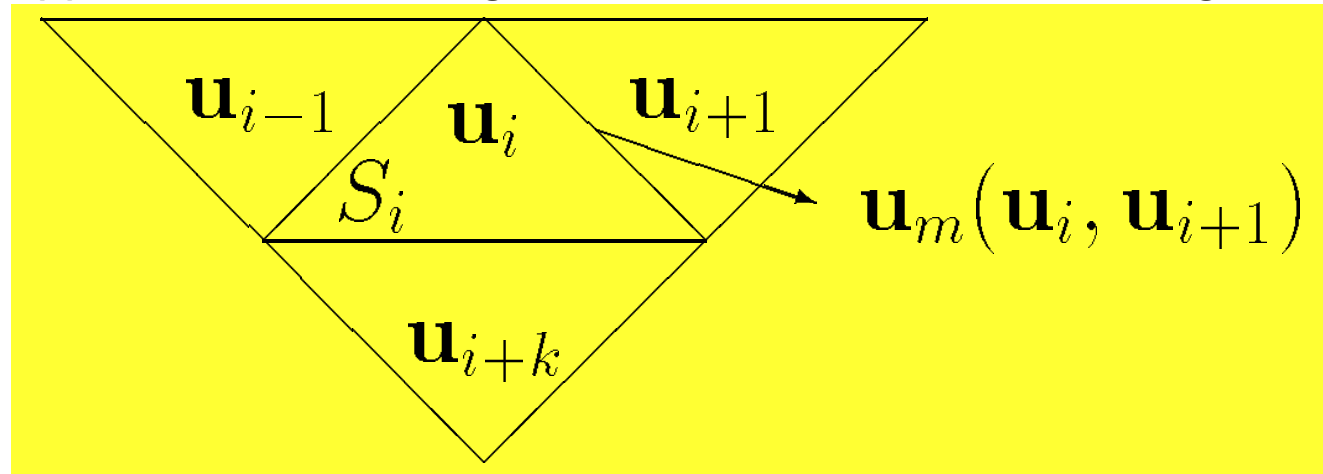
⇒ update volume averages by

$$\frac{dU_i}{dt} + \frac{1}{\Delta x_i} (F_{i+1/2} - F_{i-1/2}) = 0 .$$

⇒ discretized equation is integral law, weak solutions obey conservation

## Finite Volume on unstructured grids

- Finite volume approach: natural on general 2D and 3D unstructured grids



- multidimensional set of conservation laws

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F} = 0$$

$\Rightarrow$  in 3D, the  $\nabla \cdot \mathbf{F}$  with three Cartesian coordinate axes

$$\nabla \cdot \mathbf{F} = \frac{\partial \mathbf{F}_x}{\partial x} + \frac{\partial \mathbf{F}_y}{\partial y} + \frac{\partial \mathbf{F}_z}{\partial z}$$

- discretize space in control volumes  $V_i$

$\Rightarrow$  bounding surfaces  $\partial V_i$ , unit normal  $\mathbf{n} = (n_x, n_y, n_z)$

$$\begin{aligned} \frac{d \int_{V_i} \mathbf{U}(\mathbf{x}, t) d\mathbf{x}}{dt} &= - \int_{\partial V_i} \mathbf{F} \cdot \mathbf{n} dS \\ &= - \int_{\partial V_i} (\mathbf{F}_x n_x + \mathbf{F}_y n_y + \mathbf{F}_z n_z) dS \end{aligned}$$

$\Rightarrow$  introduce ( $8 \times 8$  for MHD) matrix  $T(\mathbf{n})$  which rotates vector quantities to local orthogonal coordinate system  $\mathbf{n}, \mathbf{t}, \mathbf{s} \equiv \mathbf{n} \times \mathbf{t}$ , where latter are tangential unit vectors within  $\partial V_i$

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & \sin \theta \cos \varphi & \sin \theta \sin \varphi & \cos \theta & 0 & 0 & 0 & 0 & 0 \\ 0 & \cos \theta \cos \varphi & \cos \theta \sin \varphi & -\sin \theta & 0 & 0 & 0 & 0 & 0 \\ 0 & -\sin \varphi & \cos \varphi & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & \sin \theta \cos \varphi & \sin \theta \sin \varphi & \cos \theta & 0 \\ 0 & 0 & 0 & 0 & 0 & \cos \theta \cos \varphi & \cos \theta \sin \varphi & -\sin \theta & 0 \\ 0 & 0 & 0 & 0 & 0 & -\sin \varphi & \cos \varphi & 0 & 0 \end{pmatrix}.$$

- HD and MHD equations must be unchanged under rotation

$$\mathbf{F}_x n_x + \mathbf{F}_y n_y + \mathbf{F}_z n_z = T^{-1}(\mathbf{n}) \mathbf{F}_x (T(\mathbf{n}) \mathbf{U})$$

⇒ obtain essentially 1D problem in direction normal to volume boundary

$$\frac{d \int_{V_i} \mathbf{U}(\mathbf{x}, t) d\mathbf{x}}{dt} = - \int_{\partial V_i} T^{-1}(\mathbf{n}) \mathbf{F}_x (T(\mathbf{n}) \mathbf{U}) dS$$

- control volumes with multiple, flat surface segments

⇒ integral over boundary into discrete sum over its sides

⇒ **only information of grid: volumes  $V_i$ , and geometry of cells: number of bounding surface segments, their surface area and their normal directions.**

## The Euler equations

- conservation laws for 1D dynamics of compressible gas

$$\begin{cases} \rho_t + (\rho v)_x = 0 \\ m_t + (m v + p)_x = 0 \\ e_t + (e v + p v)_x = 0 \end{cases}$$

- vector of conserved quantities  $U = \begin{pmatrix} \rho \\ m \\ e \end{pmatrix}$

$\Rightarrow$  total energy density related to pressure by

$$e = \underbrace{\frac{\rho v^2}{2}}_{\text{kinetic}} + \underbrace{\frac{p}{\gamma - 1}}_{\text{thermal energy}}$$

$\Rightarrow$  ratio of specific heats  $\gamma$

- internal energy considerations
  - $\Rightarrow$  specific ( $\equiv$  per unit mass) internal energy  $e_i^s$
  - $\Rightarrow \rho e_i^s = p/(\gamma - 1)$
- for ideal gas: temperature defined as  $p = \mathcal{R}\rho T$  with gas constant  $\mathcal{R}$ 
  - $\Rightarrow e_i^s(T) = \frac{\mathcal{R}T}{\gamma-1} = \frac{(c_p - c_v)T}{\frac{c_p}{c_v} - 1} = c_v T$
  - $\Rightarrow c_v$  specific heat at constant volume
- generally  $\gamma = \frac{\alpha+2}{\alpha}$ , where  $\alpha$  is the total number of degrees of freedom over which internal energy can be distributed
  - $\Rightarrow$  for molecules: translational, rotational, vibrational
  - $\Rightarrow$  monoatomic gas: only 3 translational DOF  $\rightarrow \gamma = 5/3$

- deduce equation for ‘entropy’  $s = p\rho^{-\gamma}$

$$\frac{\partial s}{\partial t} + v \frac{\partial s}{\partial x} = 0$$

$\Rightarrow$  since  $v(x, t)$ : Not in conservation form!

$\Rightarrow$  like advection equation

$\Rightarrow$   $s$  **constant along characteristics**  $\frac{dx}{dt} = v$ : **Riemann Invariant**

- equivalent to the ‘characteristic’ equation

$\Rightarrow$  along  $\frac{dx}{dt} = v$ , find

$$dp - c_s^2 d\rho = 0$$

$\Rightarrow$  with  $dp = p_t dt + p_x dx$  and  $c_s^2 = \gamma p / \rho$



- write system as  $U_t + (F(U))_x = 0$  with flux vector

$$F = \begin{pmatrix} m \\ \frac{m^2}{\rho} \frac{3-\gamma}{2} + (\gamma-1)e \\ \frac{em}{\rho} \gamma - \frac{\gamma-1}{2} \frac{m^3}{\rho^2} \end{pmatrix}$$

$\Rightarrow$  **Flux Jacobian** becomes

$$\frac{\partial F}{\partial U} = \begin{pmatrix} 0 & 1 & 0 \\ \frac{m^2}{\rho^2} \frac{\gamma-3}{2} & \frac{m}{\rho} (3-\gamma) & \gamma-1 \\ -\gamma \frac{em}{\rho^2} + (\gamma-1) \frac{m^3}{\rho^3} & \frac{e\gamma}{\rho} + (1-\gamma) \frac{3}{2} \frac{m^2}{\rho^2} & \frac{m\gamma}{\rho} \end{pmatrix}$$

$\Rightarrow$  **3 eigenvalues/right eigenvectors**

- eigenvalue  $\lambda_1 = \frac{m}{\rho} - \sqrt{\frac{\gamma p}{\rho}} = v - c_s$   
 $\Rightarrow$  eigenvector  $\vec{r}_1 = \begin{pmatrix} 1 \\ v - c_s \\ \frac{v^2}{2} - v c_s + \frac{c_s^2}{\gamma - 1} \end{pmatrix}$
- eigenvalue  $\lambda_2 = \frac{m}{\rho} = v$   
 $\Rightarrow$  eigenvector  $\vec{r}_2 = \begin{pmatrix} 1 \\ v \\ \frac{v^2}{2} \end{pmatrix}$
- eigenvalue  $\lambda_3 = \frac{m}{\rho} + \sqrt{\frac{\gamma p}{\rho}} = v + c_s$   
 $\Rightarrow$  eigenvector  $\vec{r}_3 = \begin{pmatrix} 1 \\ v + c_s \\ \frac{v^2}{2} + v c_s + \frac{c_s^2}{\gamma - 1} \end{pmatrix}$

- Rankine-Hugoniot relations for Euler system

$$F(U_l) - F(U_r) = s(U_l - U_r)$$

$$\Rightarrow \begin{cases} m_l - m_r = s(\rho_l - \rho_r) \\ \left[ \frac{m_l^2}{\rho_l} \frac{3-\gamma}{2} + (\gamma-1)e_l \right] - \left[ \frac{m_r^2}{\rho_r} \frac{3-\gamma}{2} + (\gamma-1)e_r \right] = s(m_l - m_r) \\ \left[ \frac{e_l m_l}{\rho_l} \gamma - \frac{\gamma-1}{2} \frac{m_l^3}{\rho_l^2} \right] - \left[ \frac{e_r m_r}{\rho_r} \gamma - \frac{\gamma-1}{2} \frac{m_r^3}{\rho_r^2} \right] = s(e_l - e_r) \end{cases}$$

$\Rightarrow$  for given right state: 3 equations for 4 unknowns  $s, U_l$

- verify that **Contact Discontinuity obeys RH**

$\Rightarrow s = v, v_l = v_r = v, p_l = p_r = p$  while  $\rho_l \neq \rho_r$

$\Rightarrow$  '2-wave' for eigenvalue  $\lambda_2 = v$  has (generalized Riemann) invariants  $v$  and  $p$

- **general solution to Riemann Problem:**

⇒ given two states  $U_l$  and  $U_r$

⇒ find intermediate state  $U_{mr}$  connected to  $U_r$  by a ‘3-wave’

⇒ which is such that its velocity and pressure

$$U_{mr} = \underbrace{\begin{pmatrix} \rho_{mr} \\ m_{mr} \\ e_{mr} \end{pmatrix}}_{\text{conservative}} \equiv \underbrace{\begin{pmatrix} \rho_{mr} \\ v_* \\ p_* \end{pmatrix}}_{\text{primitive}}$$

match the velocity and pressure of intermediate state

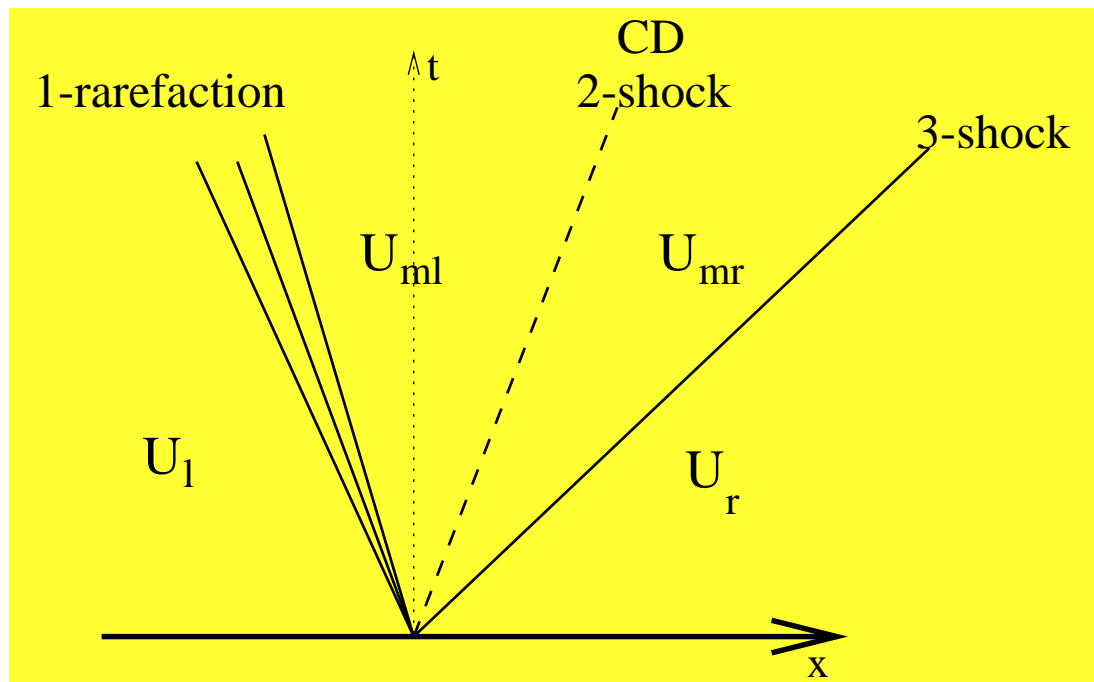
$$U_{ml} = \begin{pmatrix} \rho_{ml} \\ v_* \\ p_* \end{pmatrix}$$

connected to  $U_l$  by a ‘1-wave’

⇒ the states  $U_{ml}$  and  $U_{mr}$  can be connected by a ‘2-shock’ (contact discontinuity)

- note: counts ok:

$\Rightarrow$  6 equations for 6 unknowns  $(s_1, \rho_{ml}, v_*, p_*)$  and  $(s_3, \rho_{mr}, v_*, p_*)$



$\Rightarrow$  again **only entropy-satisfying shocks allowed**

- ingredients to solve RP:  $L - R_1$  or  $S_1 - M_l - CD - M_r - R_3$  or  $S_3 - R$

- Euler system in terms of **primitive** variables

$$\begin{pmatrix} \rho \\ v \\ p \end{pmatrix}_t + \begin{pmatrix} v & \rho & 0 \\ 0 & v & \frac{1}{\rho} \\ 0 & \gamma p & v \end{pmatrix} \begin{pmatrix} \rho \\ v \\ p \end{pmatrix}_x = 0$$

$\Rightarrow$  possible to deduce

$$v_t + (v \pm c) v_x \pm \frac{1}{\sqrt{\gamma p \rho}} (p_t + (v \pm c) p_x) = 0$$

- since  $\frac{2c}{\gamma-1} = \frac{2}{\gamma-1} \sqrt{\frac{\gamma p}{\rho}}$  and under constant  $s = p\rho^{-\gamma}$

$\Rightarrow$  can be rewritten to

$$\left(v \pm \frac{2c}{\gamma-1}\right)_t + (v \pm c) \left(v \pm \frac{2c}{\gamma-1}\right)_x = 0$$

- found (generalized) Riemann Invariants

$\Rightarrow$  **for '1-wave'  $v - c$ : invariants are  $s$  and  $v + \frac{2c}{\gamma-1}$**

$\Rightarrow$  **for '2-wave'  $v$ : invariants are  $v$  and  $p$**

$\Rightarrow$  **for '3-wave'  $v + c$ : invariants are  $s$  and  $v - \frac{2c}{\gamma-1}$**

- can be written as **'characteristic' equations**
  - $\Rightarrow dp - \rho c dv = 0$  along  $\frac{dx}{dt} = v - c$
  - $\Rightarrow dp - c^2 d\rho = 0$  along  $\frac{dx}{dt} = v$
  - $\Rightarrow dp + \rho c dv = 0$  along  $\frac{dx}{dt} = v + c$
  - $\Rightarrow$  could be used to solve IVP in  $(x, t)$  space



- back to Rankine-Hugoniot relations for Euler system

$$F(U_l) - F(U_r) = s (U_l - U_r)$$

⇒ **consider again stationary shock**  $s = 0 \rightarrow m_l = m_r$

⇒ two remaining equations result in

$$\frac{v_l^2}{2} + \frac{c_l^2}{\gamma - 1} = \frac{v_r^2}{2} + \frac{c_r^2}{\gamma - 1} = \frac{\gamma + 1}{2(\gamma - 1)} c_*^2$$

⇒ last equality for sonic point where  $v_* = c_*$

⇒ again leads to  $c_*^2 = v_l v_r$  **Prandtl Meyer relation**

⇒ stationary shock separates super- from subsonic state (w.r.t.  $c_*$ )!

- further analysis of stationary shock introduces  $M_l = \frac{v_l}{c_l}$

$$\frac{v_l}{v_r} = \frac{(\gamma + 1)M_l^2}{(\gamma - 1)M_l^2 + 2}$$

$\Rightarrow$  and since  $m_l = m_r$  we get for the density ratio

$$\frac{\rho_l}{\rho_r} = \frac{(\gamma - 1)M_l^2 + 2}{(\gamma + 1)M_l^2}$$

$\Rightarrow$  pressure ratio can be shown to obey

$$\frac{p_l}{p_r} = \frac{\gamma + 1}{1 - \gamma + 2\gamma M_l^2}$$

$\Rightarrow$  **for stationary shock: all jumps depend on  $\gamma$  and  $M_l$  only**

- moving shock: Galilean transformation
  - $\Rightarrow$  leaves all thermodynamic quantities unchanged
  - $\Rightarrow$  change to parameters  $\alpha = \frac{\gamma+1}{\gamma-1}$  and  $P = \frac{p_l}{p_r}$
  - $\Rightarrow$  stationary shock obeys

$$\frac{v_l}{v_r} = \frac{\alpha + P}{\alpha P + 1} = \frac{\rho_r}{\rho_l}$$

- $\Rightarrow$  three parameters for a moving shock:  $\alpha$ ,  $P$ , shock speed  $s$  give

$$\frac{v_l - s}{v_r - s} = \frac{\alpha + P}{\alpha P + 1} = \frac{\rho_r}{\rho_l}$$

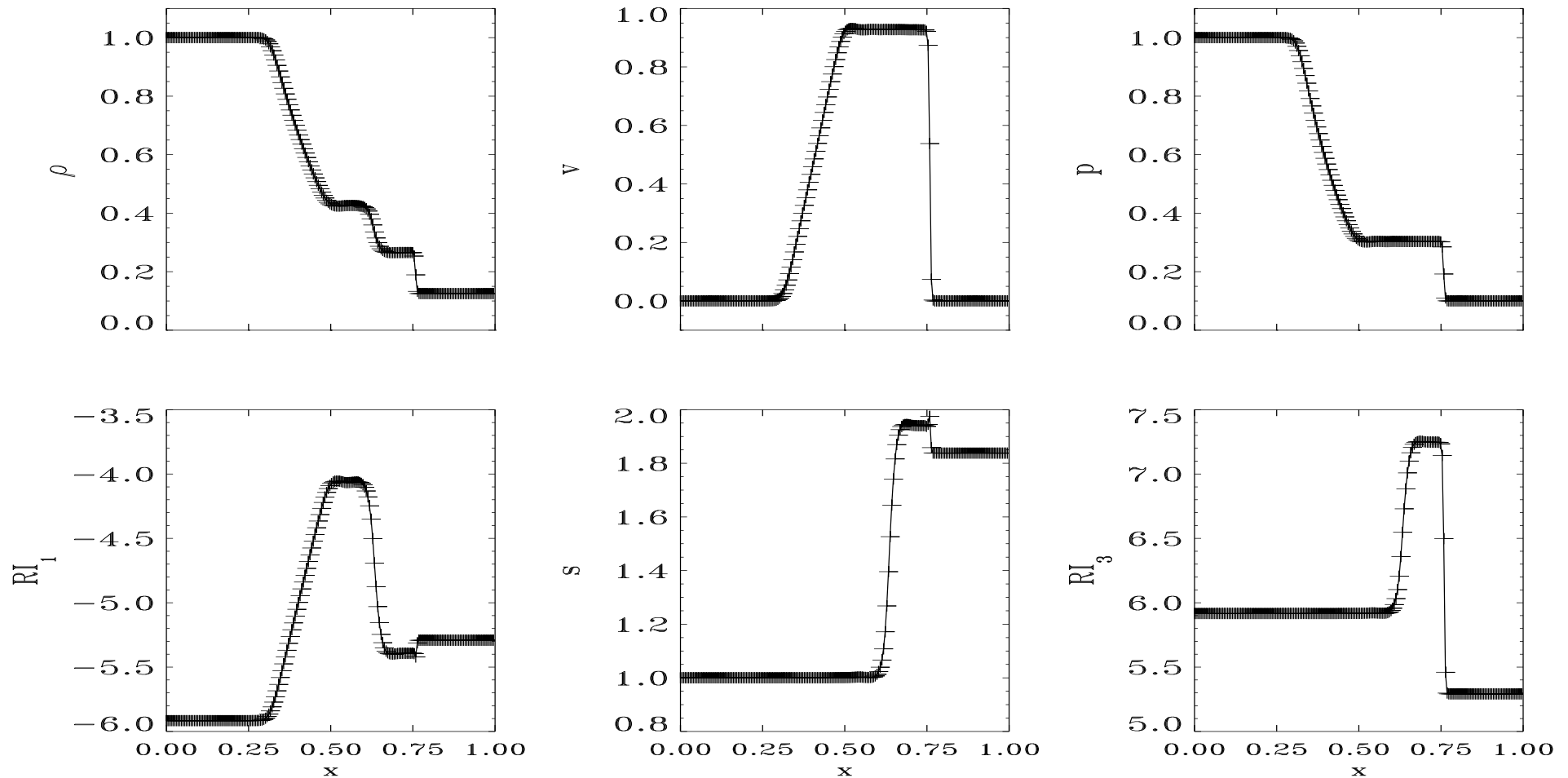
- $\Rightarrow$  while also

$$(s - v_l)^2 = c_l^2 \left[ 1 + \frac{\gamma + 1}{2\gamma} \left( \frac{p_r}{p_l} - 1 \right) \right]$$

## Numerical tests

- Perform series of Riemann Problem calculations for 1D Euler
  - ⇒ always use **2nd order accurate, conservative, TVDLF discretization**
  - ⇒ TVDLF is 'Total Variation Diminishing Lax-Friedrichs' scheme
  - ⇒ monotonicity preserving, but diffusive especially at CD
  - ⇒ 200 grid points on  $[0, 1]$ ,  $\gamma = 1.4$
  - ⇒ BCs:  $\partial x = 0$
- Start with **classical 'Sod' problem**
  - ⇒  $U_l = (\rho_l, v_l, p_l) = (1, 0, 1)$  and  $U_r = (0.125, 0, 0.1)$
  - ⇒ **'shock tube problem': diaphragm separates 2 gases at rest**

- Sod problem at  $t = 0.15$

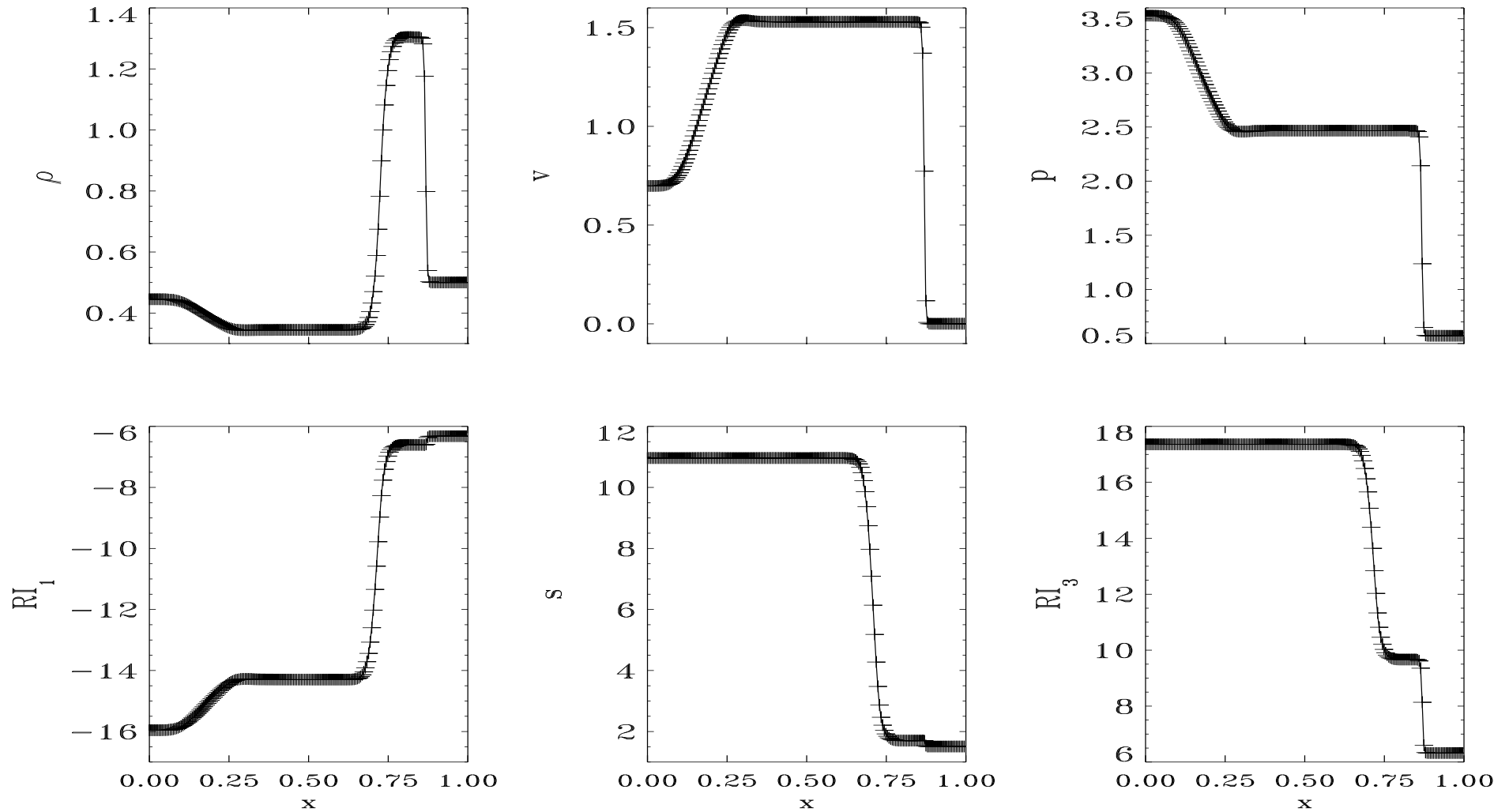


$\Rightarrow$  note  $R_1$  where Riemann Invariants  $s$  and  $v + 2c/(\gamma - 1)$  are constant

$\Rightarrow$  CD spread over many cells

- test case from Lax: initial rightwardly moving left state, till  $t = 0.15$

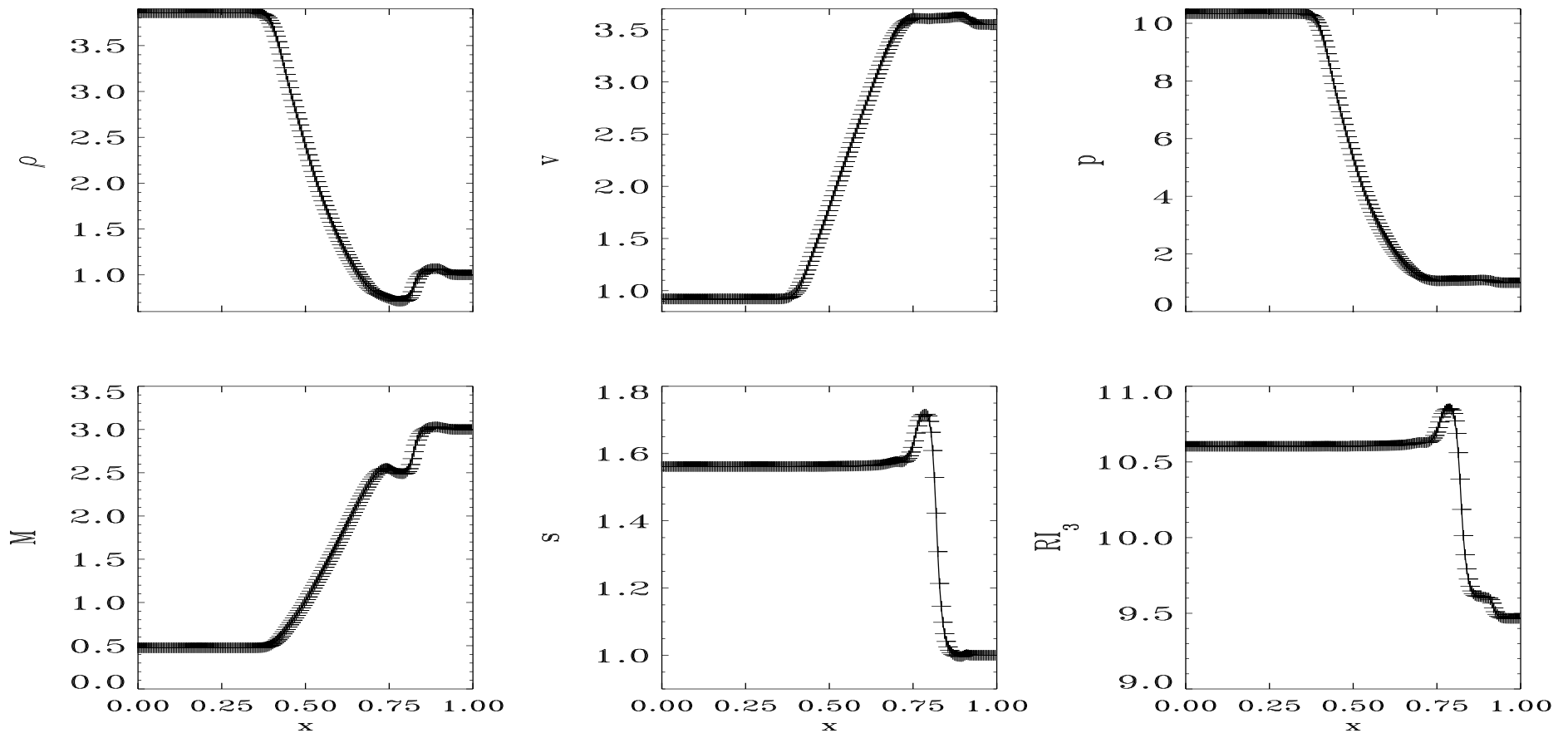
$$\Rightarrow U_l = (\rho_l, v_l, p_l) = (0.445, 0.698, 3.528) \text{ and } U_r = (0.5, 0, 0.571)$$



- Sod and Lax test case: remain subsonic  $M = v/c_s < 1$

⇒ **Arora & Roe Mach 3 test case** considers

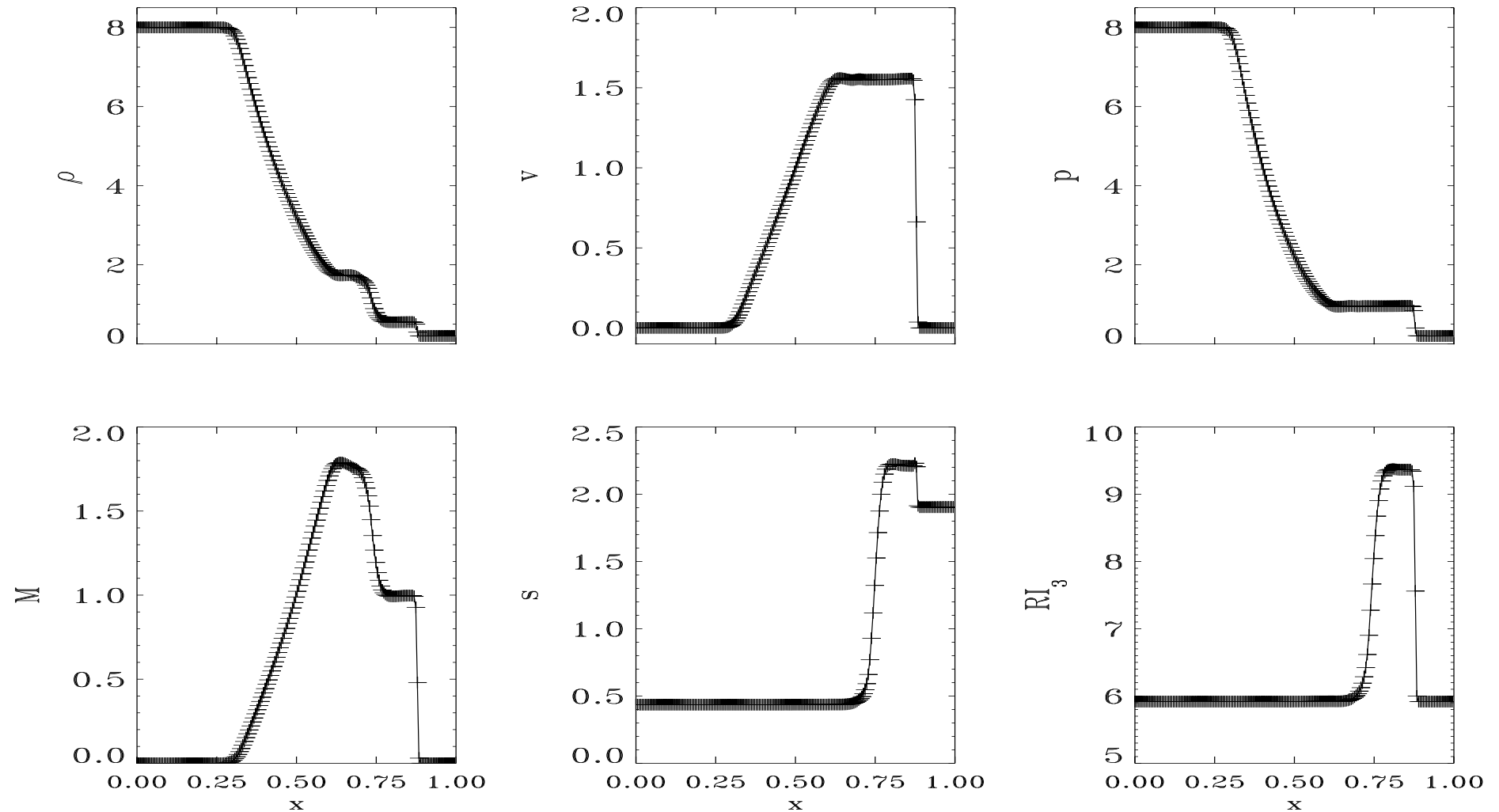
⇒  $U_l = (\rho_l, v_l, p_l) = (3.857, 0.92, 10.333)$  and  $U_r = (1, 3.55, 1)$



⇒ solution at  $t = 0.09$

- supersonic shock tube problem at time  $t = 0.1562$

$$\Rightarrow U_l = (\rho_l, v_l, p_l) = (8, 0, 8) \text{ and } U_r = (0.2, 0, 0.2)$$

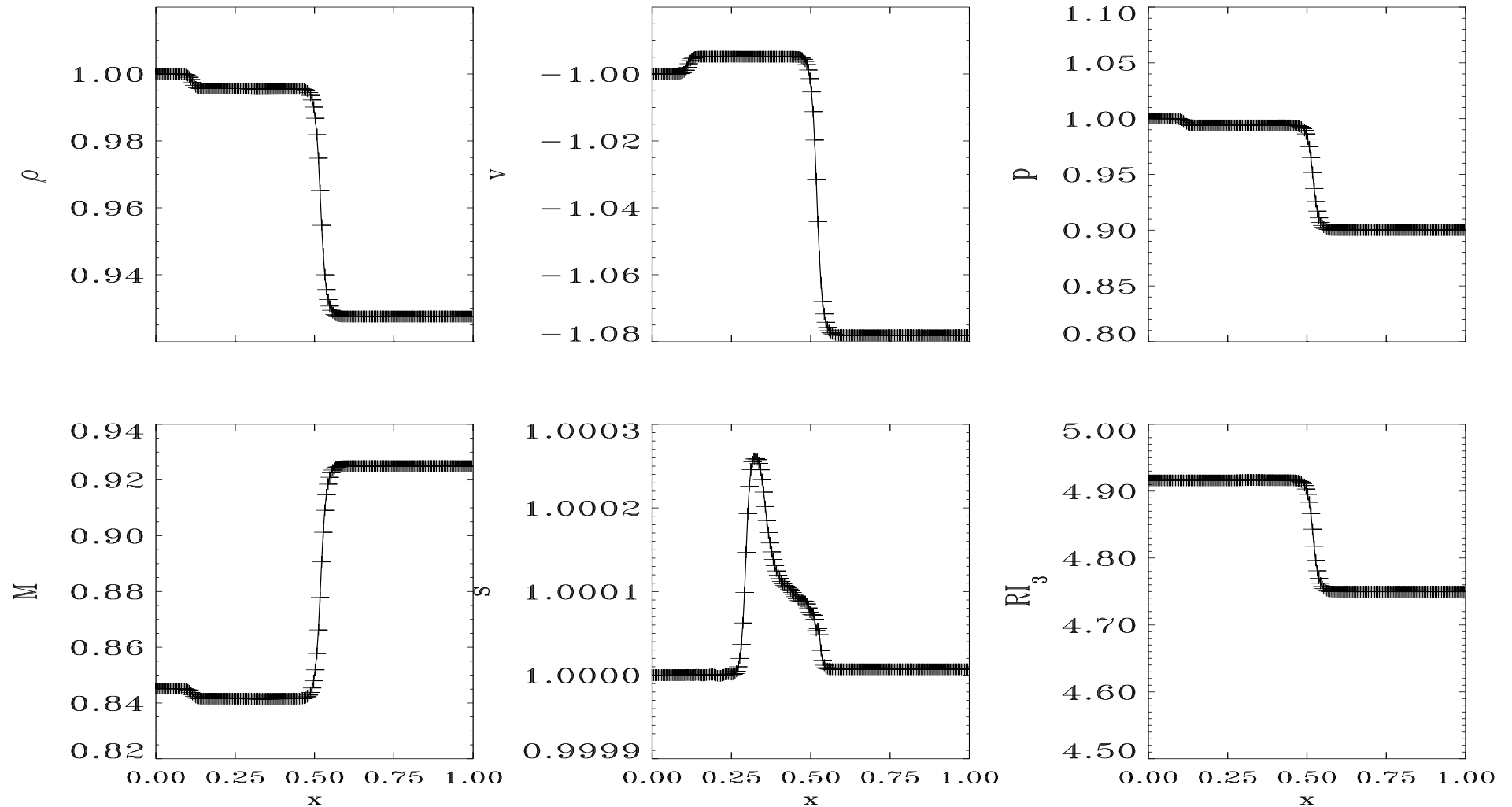


$\Rightarrow$  better behaviour at contact than in Mach 3 case



- case of a slowly moving very weak shock, show  $t = 0.175$

$$\Rightarrow U_l = (\rho_l, v_l, p_l) = (1, -1, 1) \text{ and } U_r = (0.9275, -1.0781, 0.9)$$

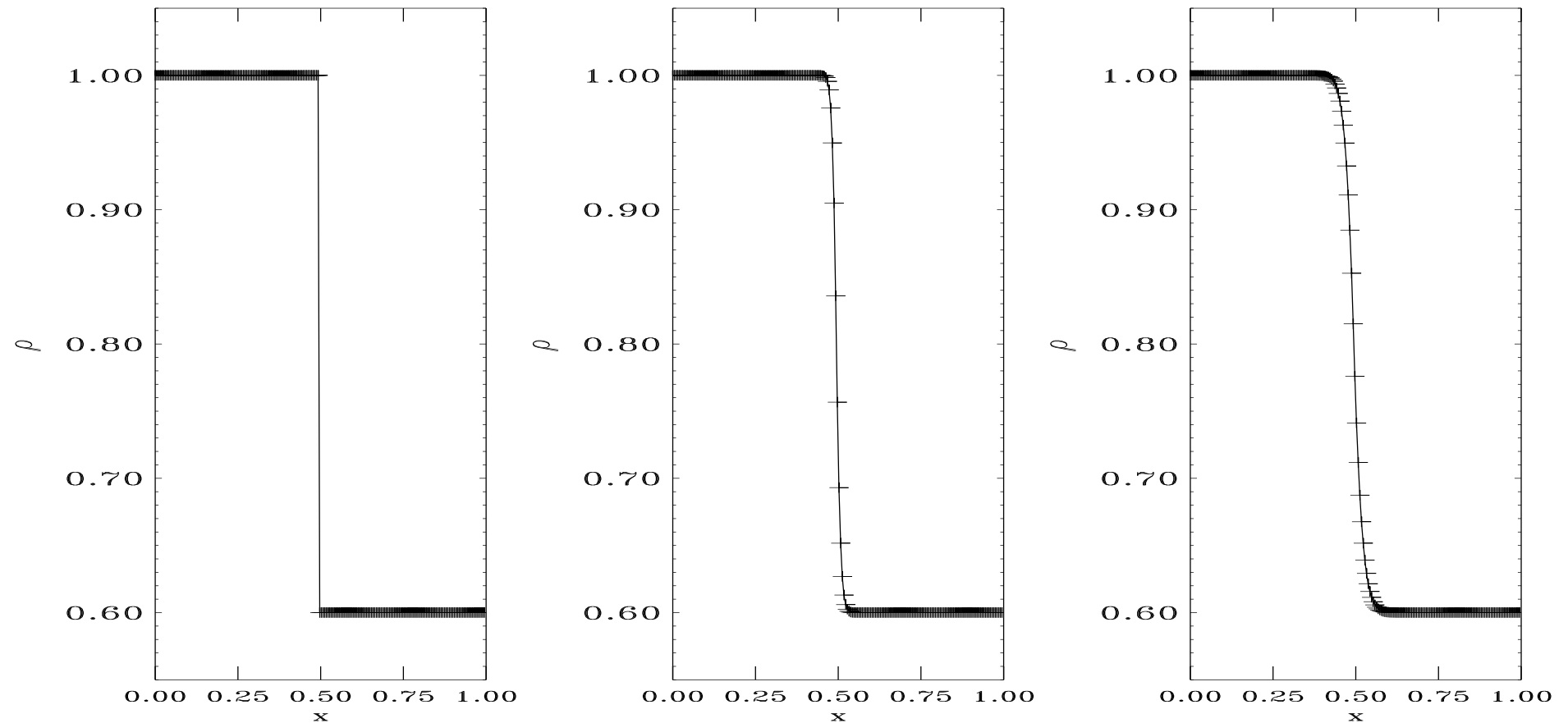


$\Rightarrow$  leftward rarefaction and rightward shock: (too) many cells in shock!

- stationary contact discontinuity

$$\Rightarrow U_l = (\rho_l, v_l, p_l) = (1, 0, 0.5) \text{ and } U_r = (0.6, 0, 0.5)$$

$\Rightarrow t = 0$  and  $t = 0.1$  and  $t = 1$  solution



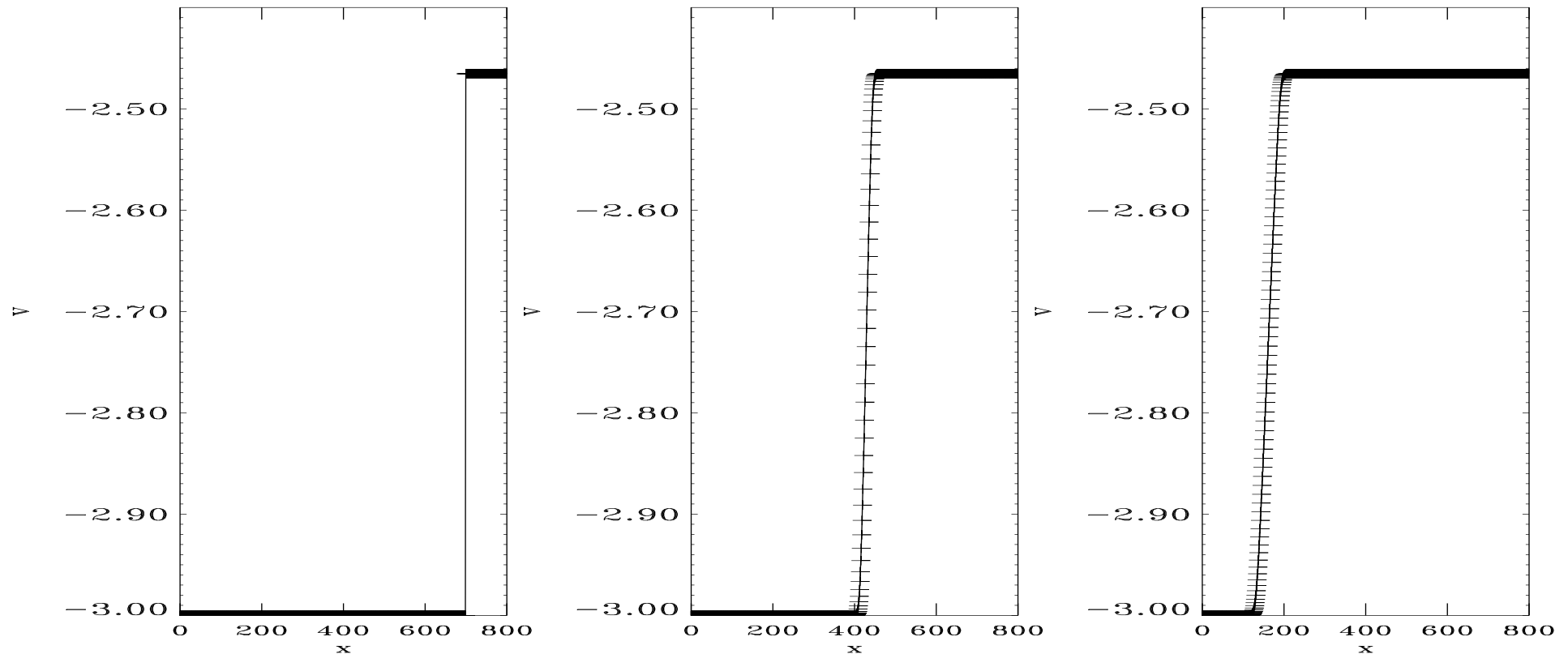
$\Rightarrow$  diffusion obvious: increasingly (too) many cells in CD!

- recognizing a rarefaction wave

⇒ 800 cells from  $[0, 800]$  with  $\gamma = 5/3$

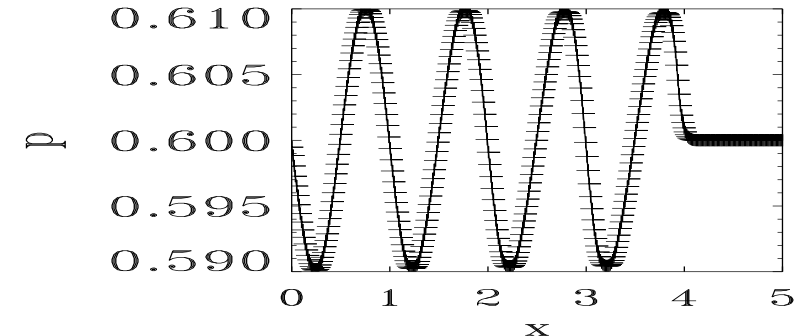
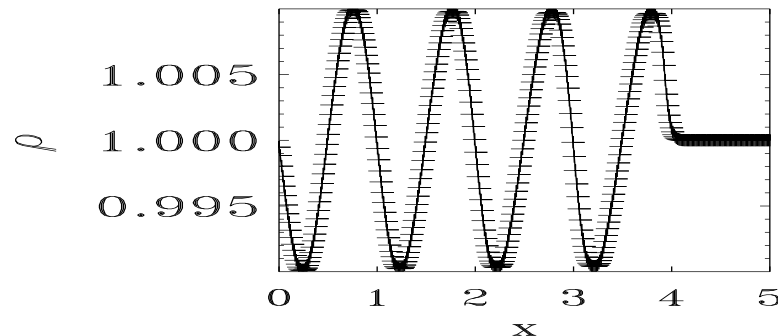
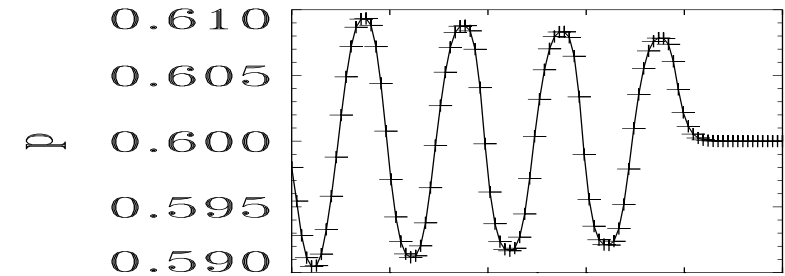
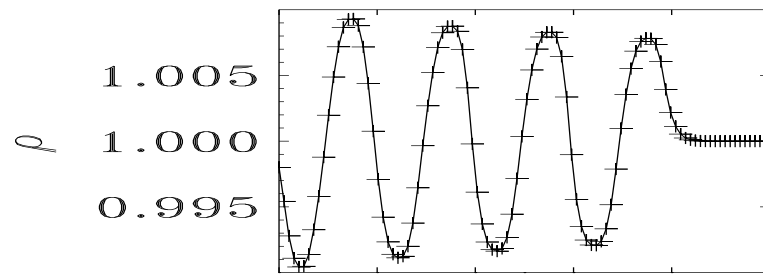
⇒  $U_l = (\rho_l, v_l, p_l) = (1, -3, 10)$  and  $U_r = (0.87469, -2.46537, 8)$

⇒  $t = 0$  and  $t = 40$  and  $t = 80$  solution, plot  $v$



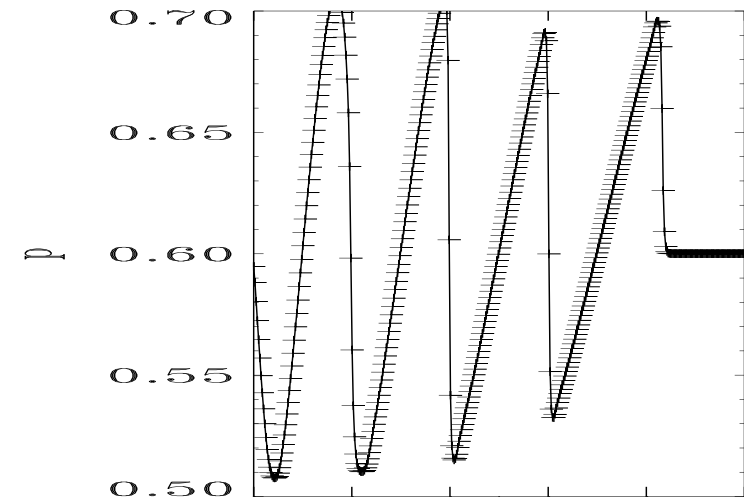
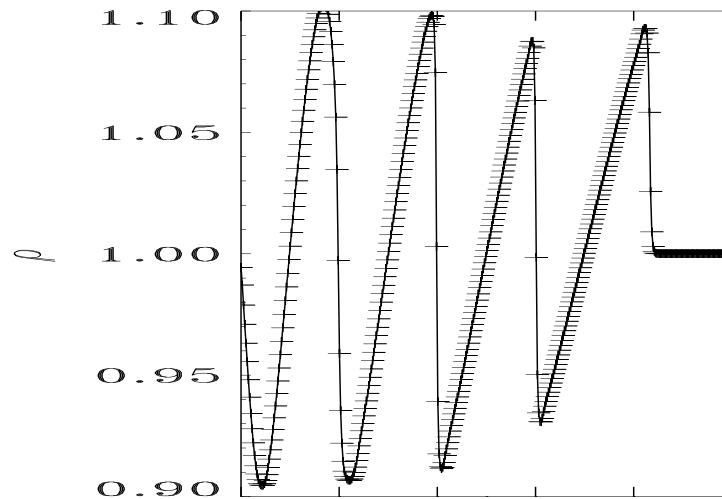
⇒ two states with same entropy: rarefaction emerges

- Linear sound waves: time dependent driver  $v = A \sin(2\pi t/P)$  at  $x = 0$ 
  - $\Rightarrow$  density  $\rho(t = 0) = 1$ ,  $v(t = 0) = 0$ ,  $p(t = 0) = 0.6$  with  $\gamma = 5/3$
  - $\Rightarrow A = 0.02$  with  $P = 1$  generates sound waves (amplitude 0.01)
  - $\Rightarrow$  compare TVDLF for 100 versus 400 cells at  $t = 4$



$\Rightarrow$  to follow linear dynamics: need high resolution to battle diffusion!

- sound wave steepening and shock formation: take amplitude  $A = 0.2$



⇒ nonlinear shock formation well captured

- Caution to use these methods for pure linear wave processes
  - ⇒ high resolution prerequisite
  - ⇒ separate true physical diffusion from numerical effects
  - ⇒ note that 10 % variations already imply nonlinear effects!

## Approximate Riemann solver based methods

- modern high resolution, shock-capturing schemes for Euler
  - ⇒ capitalize on known solution of the Riemann problem
  - ⇒ originally developed by Godunov
- always use conservative scheme of form

$$\frac{dU_i}{dt} + \frac{1}{\Delta x} (F_{i+1/2} - F_{i-1/2}) = 0$$

- ⇒ cell values  $U_i$  change through fluxes across cell edges
- ⇒ edge-centered numerical flux  $F_{i+1/2}(U_{i-p}, U_{i-p+1}, \dots, U_{i+q})$

## The Godunov scheme

- values  $U_i^n$  for time  $t = t_n$ 
  - $\Rightarrow$  consider piecewise constant values in cells
  - $\Rightarrow$  serve as initial condition to solve  $U_t + (F(U))_x = 0$  for  $t > t_n$
  - $\Rightarrow$  restrict timestep to  $\Delta t_{n+1} < \frac{\Delta x}{2 \max|\lambda|}$
  - $\Rightarrow$  with  $\lambda$  eigenvalue of flux Jacobian  $F_U$
  - $\Rightarrow$  then exact solution given by solving RP at cell interfaces
  - $\Rightarrow$  restriction on timestep ensures no wave interaction within  $\Delta t_{n+1}$
- Godunov scheme
  - $\Rightarrow$  denote exact RP solution for state  $U_i^n$  and  $U_{i+1}^n$  as  $\hat{U} \left( \frac{x-x_{i+1/2}}{t}, U_i^n, U_{i+1}^n \right)$
  - $\Rightarrow$  numerical flux
$$F_{i+1/2}(U_i, U_{i+1}) = F(\hat{U}(0, U_i^n, U_{i+1}^n))$$
  - $\Rightarrow$  need an exact Riemann solver

## The Roe solver

- due to piecewise constant representation
  - ⇒ Godunov scheme 1st order accurate
- exact solution to RP is complicated
  - ⇒ scheme is not exact due to piecewise constant representation
  - ⇒ might as well solve RP in approximate fashion
- schemes exploiting **approximate Riemann solver**
  - ⇒ use linearization of the nonlinear problem
  - ⇒ recall: exact solution for linear hyperbolic system known



## Roe-type approximate Riemann solver

- general procedure to solve system  $\mathbf{U}_t + (\mathbf{F}(\mathbf{U}))_x = 0$ 
  - $\Rightarrow$  local Riemann problem from left and right interface values  $\mathbf{U}_l$  and  $\mathbf{U}_r$ .
  - $\Rightarrow$  instead of exact nonlinear solution, solve a linear Riemann problem

$$\mathbf{U}_t + (\mathbf{G}(\mathbf{U}))_x = 0$$

$\Rightarrow \mathbf{G}(\mathbf{U}) = \mathbf{F}(\mathbf{U}_r) + A(\mathbf{U} - \mathbf{U}_r)$  includes constant matrix  $A = A(\mathbf{U}_l, \mathbf{U}_r)$

$\Rightarrow$  matrix must satisfy conditions

1.  $\mathbf{F}(\mathbf{U}_l) - \mathbf{F}(\mathbf{U}_r) = A(\mathbf{U}_l, \mathbf{U}_r) (\mathbf{U}_l - \mathbf{U}_r)$ ,
2.  $A(\mathbf{U}_l, \mathbf{U}_r) \rightarrow \mathbf{F}_{\mathbf{U}}(\mathbf{U}_r)$  as  $\mathbf{U}_l \rightarrow \mathbf{U}_r$ ,
3.  $A(\mathbf{U}_l, \mathbf{U}_r)$  has only real eigenvalues,
4.  $A(\mathbf{U}_l, \mathbf{U}_r)$  has a complete system of eigenvectors.

$\Rightarrow$  exact solution obtained when initial states obey Rankine-Hugoniot relations

$\Rightarrow$  consistency and solvability of the linear Riemann problem.

- if Roe matrix  $A$  found, Roe scheme uses the numerical flux

$$\mathbf{F}_{i+1/2}(\mathbf{U}_i, \mathbf{U}_{i+1}) = \mathbf{F}(\mathbf{U}_i) + A_{i+1/2} (\hat{\mathbf{U}} - \mathbf{U}_i)$$

$\Rightarrow \hat{\mathbf{U}} = \hat{\mathbf{U}}(0, \mathbf{U}_i, \mathbf{U}_{i+1})$  is exact solution of linear Riemann problem

- Latter solution easy: when  $A_{i+1/2} \vec{r}^p = \lambda_p \vec{r}^p$  write

$$\mathbf{U}_{i+1} - \mathbf{U}_i = \sum \alpha_p \vec{r}^p$$

$\Rightarrow$  can show that the solution along the  $(x, t)$  ray  $(x - x_{i+\frac{1}{2}})/t = 0$

$$\hat{\mathbf{U}} = \frac{\mathbf{U}_i + \mathbf{U}_{i+1}}{2} + \frac{1}{2} \left[ \sum_{\lambda_p < 0} - \sum_{\lambda_p > 0} \right] \alpha_p \vec{r}^p$$

- fill in for Roe flux, use first Roe condition to get

$$\mathbf{F}_{i+1/2} = \frac{1}{2} (\mathbf{F}(\mathbf{U}_i) + \mathbf{F}(\mathbf{U}_{i+1})) - \frac{1}{2} \sum |\lambda_p| \alpha_p \vec{r}^p$$

$\Rightarrow$  **‘upwinding’: characteristic speeds and wave directionality taken into account**

- **Needed: Roe matrix  $A$ , its eigenvalues  $\lambda_p$ , its right eigenvectors  $\vec{r}^p$ , and the wave strengths  $\alpha_p$**

$\Rightarrow$  when left eigenvectors  $\vec{l}^p$  given, wave strengths

$$\alpha_p = \vec{l}^p \cdot (\mathbf{U}_{i+1} - \mathbf{U}_i)$$

- In practice: use for  $A$  the Flux Jacobian  $\mathbf{F}_U$ , evaluated in average state, e.g. arithmetic average of  $\mathbf{U}_l$  and  $\mathbf{U}_r$

$\Rightarrow$  then not all Roe conditions fulfilled though

$\Rightarrow$  all ingredients known: eigenvalues (characteristic speeds), eigenvectors from  $R$ , left eigenvectors from  $R^{-1}$

- Note: wave strengths can also be computed from primitive jumps

$$\alpha_p = \vec{l}^p \cdot (\mathbf{V}_{i+1} - \mathbf{V}_i)$$

$\Rightarrow$  left eigenvectors  $\vec{l}^p$  are found from rows of

$$\mathbf{R}^{-1} = R^{-1} \mathbf{U}_V$$

$\Rightarrow$  where transformation matrix relates primitive with conservative formulation

$$d\mathbf{U} = \mathbf{U}_V d\mathbf{V}$$

- solver completely determined once matrix  $A_{i+1/2}$  that satisfies the Roe conditions is constructed

$$\Rightarrow \text{recall that } U = \begin{pmatrix} \rho \\ m \\ e \end{pmatrix} \text{ and } F = \begin{pmatrix} m \\ \frac{m^2}{\rho} \frac{3-\gamma}{2} + (\gamma-1)e \\ \frac{em}{\rho} \gamma - \frac{\gamma-1}{2} \frac{m^3}{\rho^2} \end{pmatrix} = \begin{pmatrix} \rho v \\ \rho v^2 + p \\ v(e+p) \end{pmatrix}$$

$$\Rightarrow \text{introduce vector } Z = \begin{pmatrix} \sqrt{\rho} \\ \sqrt{\rho} v \\ (e+p)/\sqrt{\rho} \end{pmatrix}$$

$\Rightarrow$  find that

$$U = \begin{pmatrix} z_1 z_1 \\ z_1 z_2 \\ \frac{1}{\gamma} z_1 z_3 + \frac{\gamma-1}{2\gamma} z_2 z_2 \end{pmatrix}$$

$\Rightarrow$  and similarly

$$F = \begin{pmatrix} z_1 z_2 \\ \frac{\gamma+1}{2\gamma} z_2 z_2 + \frac{\gamma-1}{\gamma} z_1 z_3 \\ z_2 z_3 \end{pmatrix}$$

$\Rightarrow$  both  $U$  and  $F$  are quadratic functions of elements of  $Z$

- define difference  $\delta a = a_{i+1} - a_i$ 
  - $\Rightarrow$  verify existence of matrices  $B$  and  $C$  such that
  - $\Rightarrow \delta U = B\delta Z$  and  $\delta F = C\delta Z$
  - $\Rightarrow$  matrices  $B$  and  $C$  have elements linear in  $\bar{z} = \frac{1}{2}(z_i + z_{i+1})$
- matrix  $A_{i+1/2} \equiv C B^{-1}$  then satisfies
  - $\Rightarrow A_{i+1/2}\delta U = \delta F$
  - $\Rightarrow$  **first Roe condition**

- define so-called **Roe-averages** as

$$\bar{v} \equiv \frac{\sqrt{\rho_i} v_i + \sqrt{\rho_{i+1}} v_{i+1}}{\sqrt{\rho_i} + \sqrt{\rho_{i+1}}}$$

$$\bar{h} \equiv \frac{\sqrt{\rho_i} h_i + \sqrt{\rho_{i+1}} h_{i+1}}{\sqrt{\rho_i} + \sqrt{\rho_{i+1}}}$$

⇒ latter uses the total specific enthalpy  $h = \frac{e+p}{\rho}$

⇒ can write matrix  $A_{i+1/2}$  as

$$A_{i+1/2} = \begin{pmatrix} 0 & 1 & 0 \\ \frac{\gamma-3}{2} \bar{v}^2 & (3-\gamma) \bar{v} & \gamma-1 \\ \frac{\gamma-1}{2} \bar{v}^3 - \bar{v} \bar{h} & \bar{h} - (\gamma-1) \bar{v}^2 & \gamma \bar{v} \end{pmatrix}$$

⇒ by inspection, this is equal to  $F_U(\bar{U})$

⇒ **flux Jacobian evaluated at Roe averaged state  $\bar{U}$**

⇒ thus satisfies all other Roe conditions

- can be shown that matrix satisfying all Roe conditions is unique

- all ingredients for Roe flux now known

$\Rightarrow$  eigenvalues  $\lambda_1 = \bar{v} - \bar{c}$ ,  $\lambda_2 = \bar{v}$ ,  $\lambda_3 = \bar{v} + \bar{c}$

$\Rightarrow$  uses sound speed from  $\bar{c}^2 = (\gamma - 1) \left( \bar{h} - \frac{\bar{v}^2}{2} \right)$

$\Rightarrow$  recall eigenvectors  $\vec{r}_1 = \begin{pmatrix} 1 \\ \bar{v} - \bar{c} \\ \bar{h} - \bar{v}\bar{c} \end{pmatrix}$   $\vec{r}_2 = \begin{pmatrix} 1 \\ \bar{v} \\ \frac{\bar{v}^2}{2} \end{pmatrix}$   $\vec{r}_3 = \begin{pmatrix} 1 \\ \bar{v} + \bar{c} \\ \bar{h} + \bar{v}\bar{c} \end{pmatrix}$

$\Rightarrow$  coefficients  $\alpha_p = \vec{r}^p \cdot (U_{i+1} - U_i)$

$\Rightarrow$  with orthogonal left eigenvectors  $\vec{l}^p$  from  $\vec{l}^p \cdot \vec{r}_q = \delta_q^p$  given by

$$\vec{l}^1 = \left( \frac{\bar{v}}{4\bar{c}}(2 + (\gamma - 1)\frac{\bar{v}}{\bar{c}}), -\frac{1}{2\bar{c}}(1 + (\gamma - 1)\frac{\bar{v}}{\bar{c}}), \frac{\gamma - 1}{2} \frac{1}{\bar{c}^2} \right)$$

$$\vec{l}^2 = \left( 1 - \frac{\gamma - 1}{2} \frac{\bar{v}^2}{\bar{c}^2}, (\gamma - 1)\frac{\bar{v}}{\bar{c}^2}, -(\gamma - 1)\frac{1}{\bar{c}^2} \right)$$

$$\vec{l}^3 = \left( -\frac{\bar{v}}{4\bar{c}}(2 - (\gamma - 1)\frac{\bar{v}}{\bar{c}}), \frac{1}{2\bar{c}}(1 - (\gamma - 1)\frac{\bar{v}}{\bar{c}}), \frac{\gamma - 1}{2} \frac{1}{\bar{c}^2} \right)$$

- coefficients  $\alpha_p$  expressed in primitive variable differences

$$\alpha_1 = \frac{1}{2\bar{c}^2} (\Delta p - \bar{c}\bar{\rho}\Delta v)$$

$$\alpha_2 = \Delta\rho - \frac{1}{\bar{c}^2}\Delta p$$

$$\alpha_3 = \frac{1}{2\bar{c}^2} (\Delta p + \bar{c}\bar{\rho}\Delta v)$$

$\Rightarrow$  with  $\bar{\rho} = \sqrt{\rho_i\rho_{i+1}}$

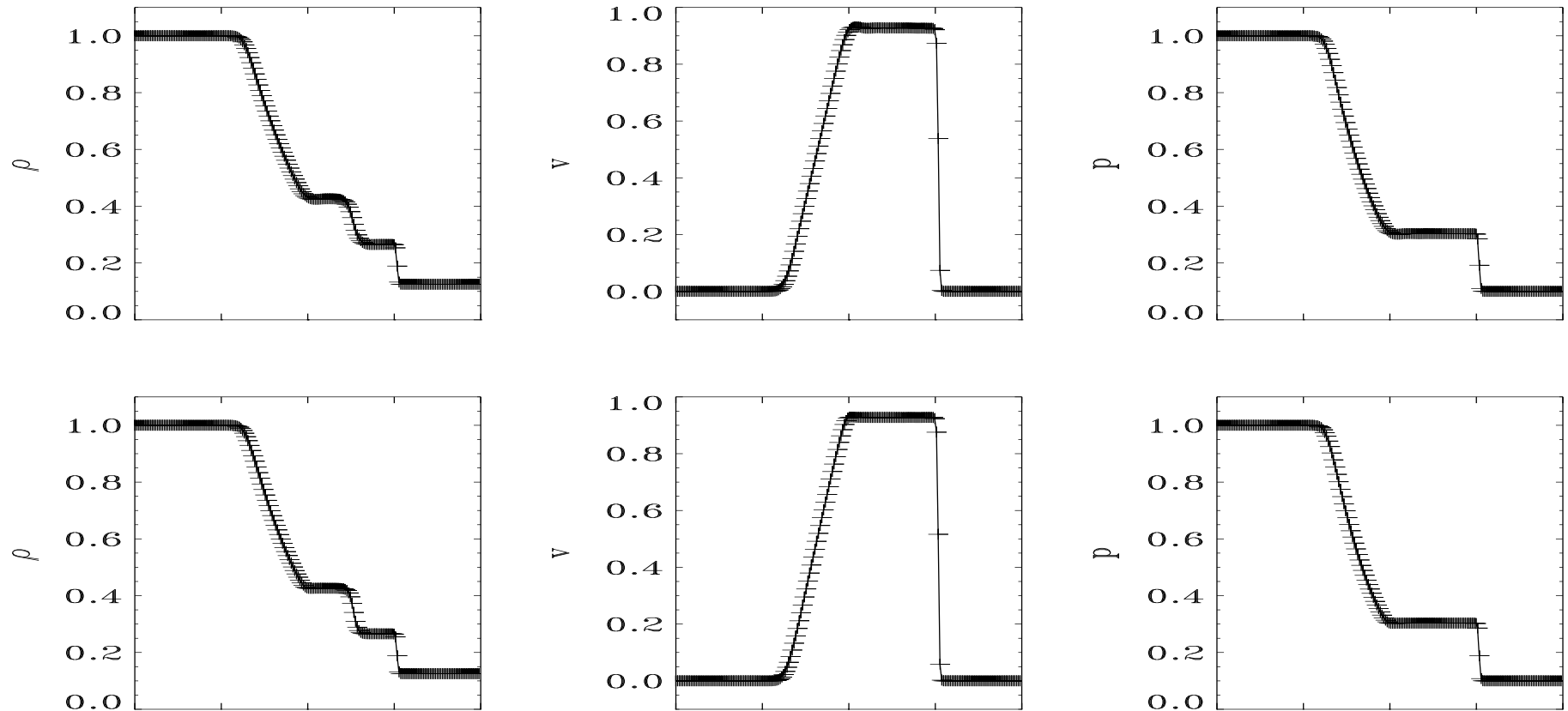
$\Rightarrow$  correspondence with characteristic equations



## Numerical tests

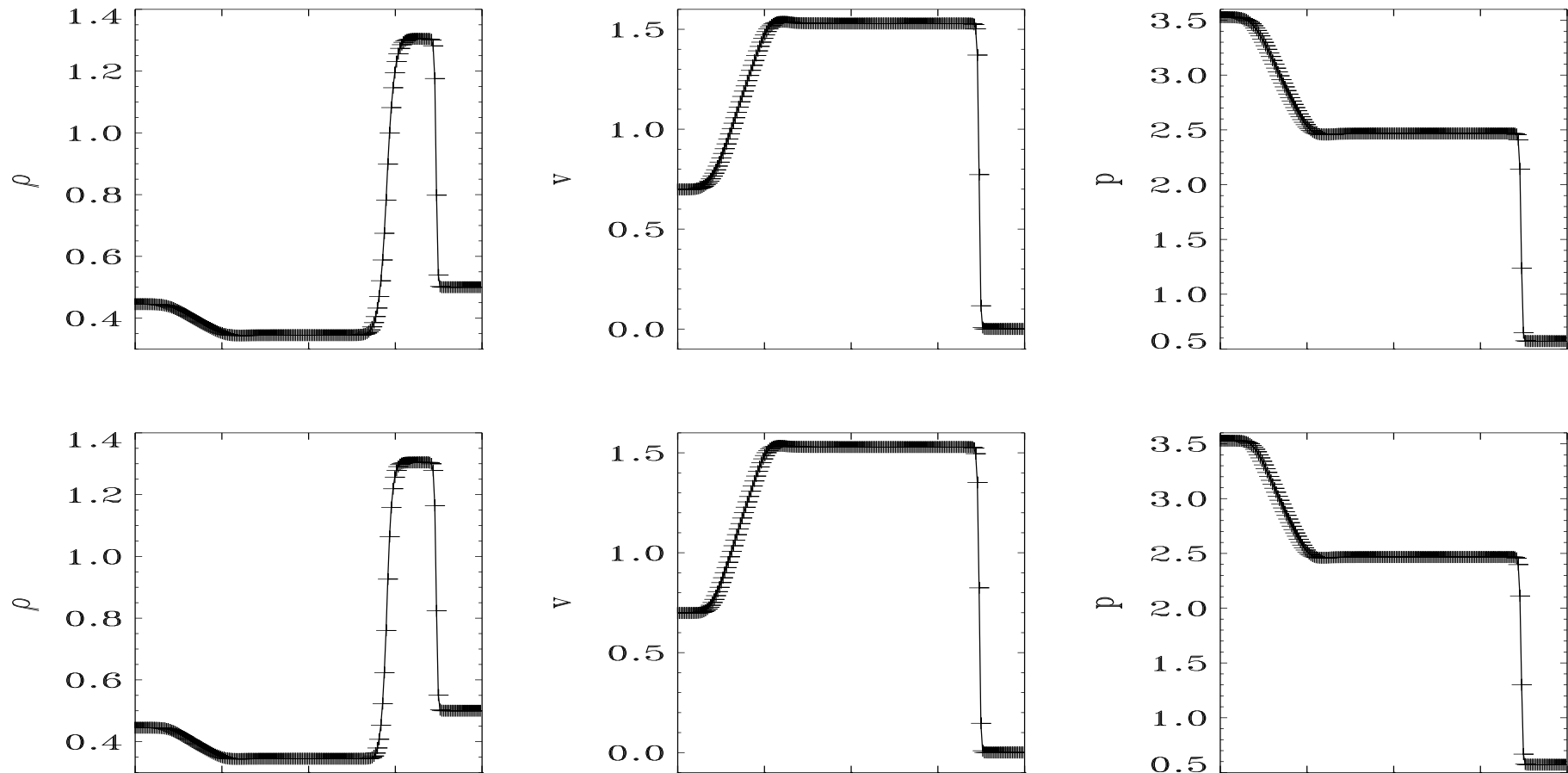
- Perform series of Riemann Problem calculations for 1D Euler
  - ⇒ **compare 2nd order conservative TVDLF with Roe-based TVD**
  - ⇒ 200 grid points on  $[0, 1]$ ,  $\gamma = 1.4$  and BCs:  $\partial x = 0$
- Start with classical 'Sod' problem
  - ⇒  $U_l = (\rho_l, v_l, p_l) = (1, 0, 1)$  and  $U_r = (0.125, 0, 0.1)$
  - ⇒ 'shock tube problem': diaphragm separates 2 gases at rest

- Sod shock tube  $t = 0.15$ : compare TVDLF (top) with Roe (bottom)



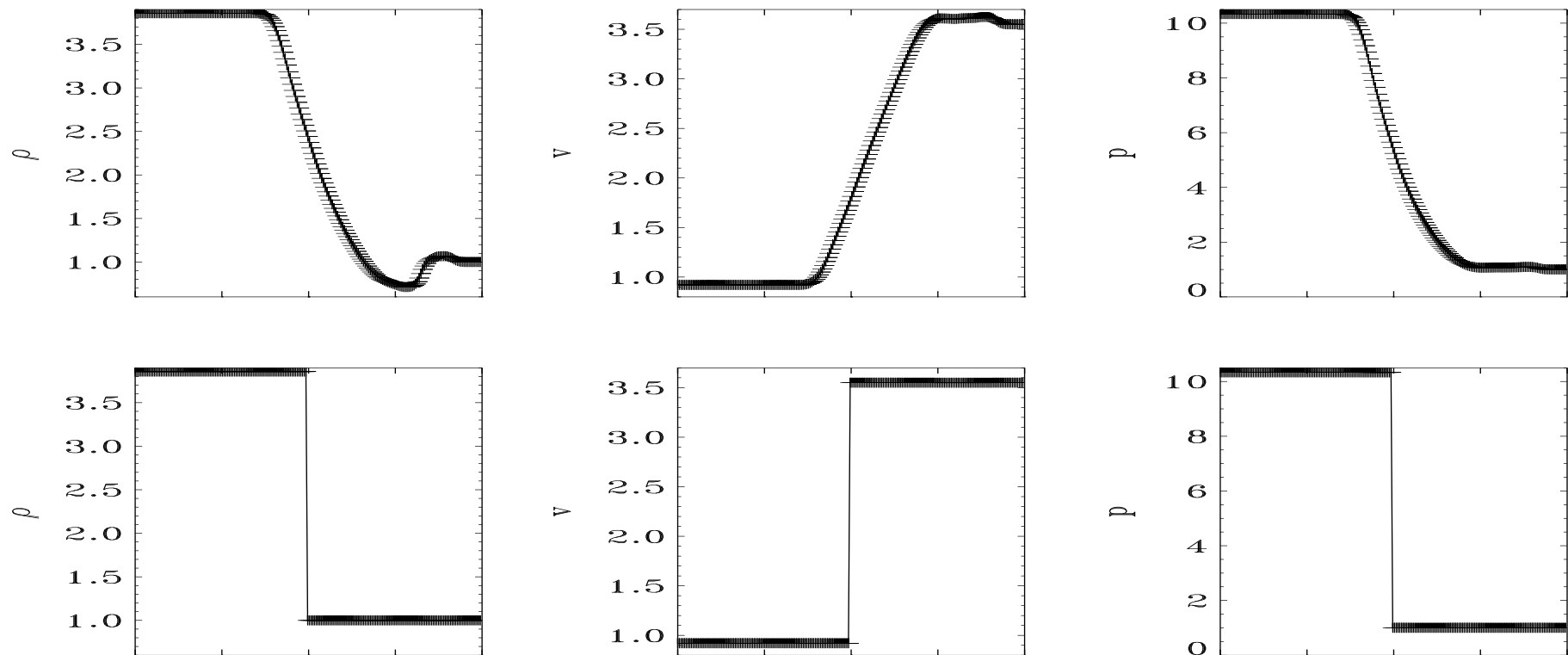
$\Rightarrow$  Roe: slight improvement for CD

- Lax test case, TVDLF (top) versus TVD (bottom)



$\Rightarrow$  slight improvement for CD

- Arora & Roe Mach 3 test case considers  
 $\Rightarrow U_l = (\rho_l, v_l, p_l) = (3.857, 0.92, 10.333)$  and  $U_r = (1, 3.55, 1)$
- Mach 3 test at  $t = 0.09$ , TVDLF (top) versus Roe (bottom)



$\Rightarrow$  Roe gives completely wrong solution!!!!

- Erroneous Mach 3 result due to presence of  $M = 1$  point

⇒  $R_1$ -rarefaction (expansion fan) goes transonic

⇒ eigenvalue  $\lambda_1 = \bar{v} - \bar{c} = 0$  at sonic point

⇒ what if simultaneously  $\alpha_2 = \alpha_3 = 0$ ?

⇒ Roe flux reduces to central discretization

$$F_{i+1/2} = \frac{1}{2} (F(U_i) + F(U_{i+1}))$$

⇒ discontinuities are insufficiently smeared out

⇒ entropy-violating solution may occur (must increase through shock)

- **‘sonic entropy fix’ for Roe scheme**

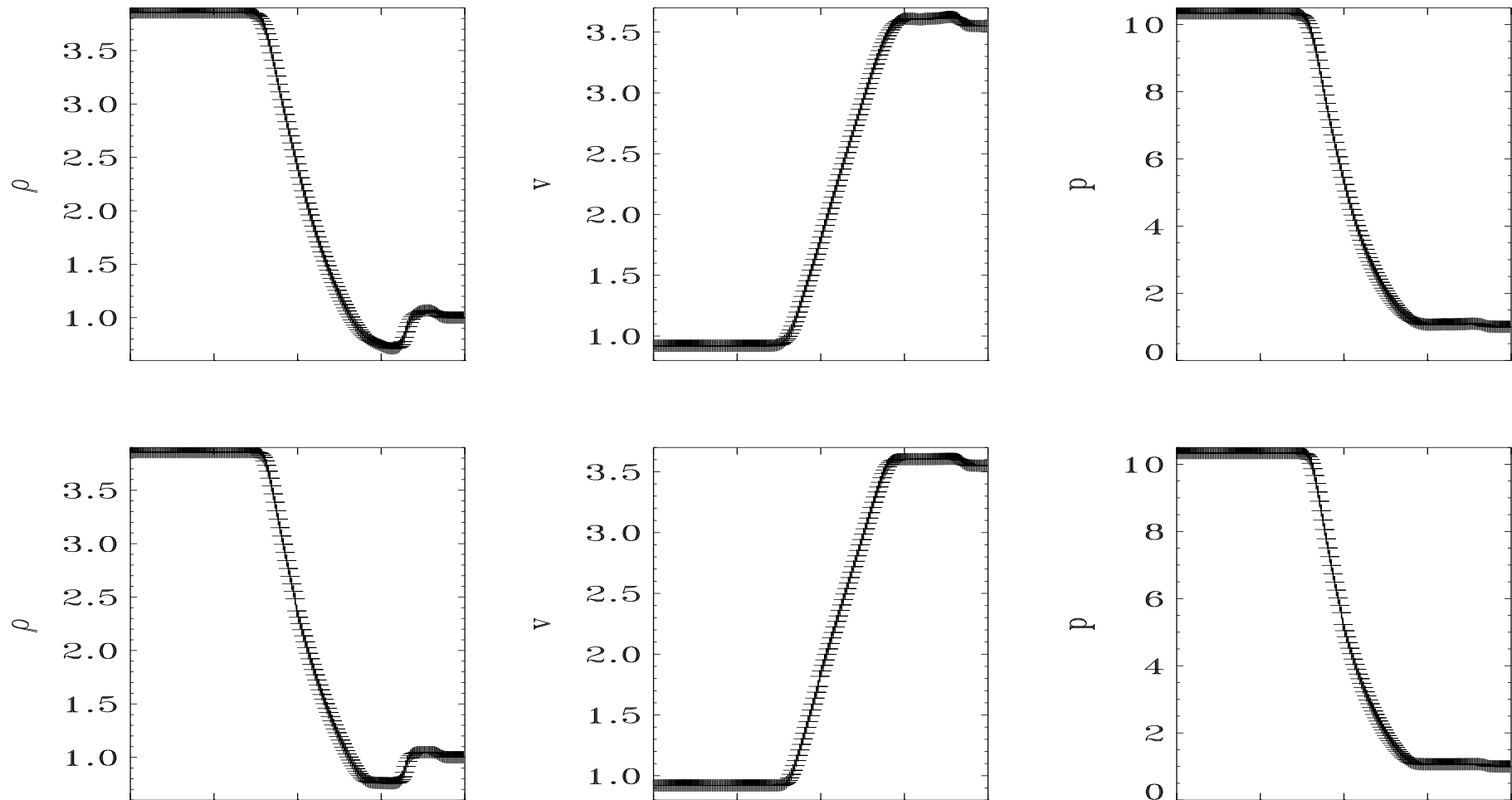
⇒ replace eigenvalues  $\lambda_1$  and  $\lambda_3$  in the vicinity of zero

⇒ if  $|\lambda_1| < \epsilon$  or  $|\lambda_3| < \epsilon$

$$\lambda_p \rightarrow \frac{1}{2} \left( \frac{\lambda_p^2}{\epsilon} + \epsilon \right)$$

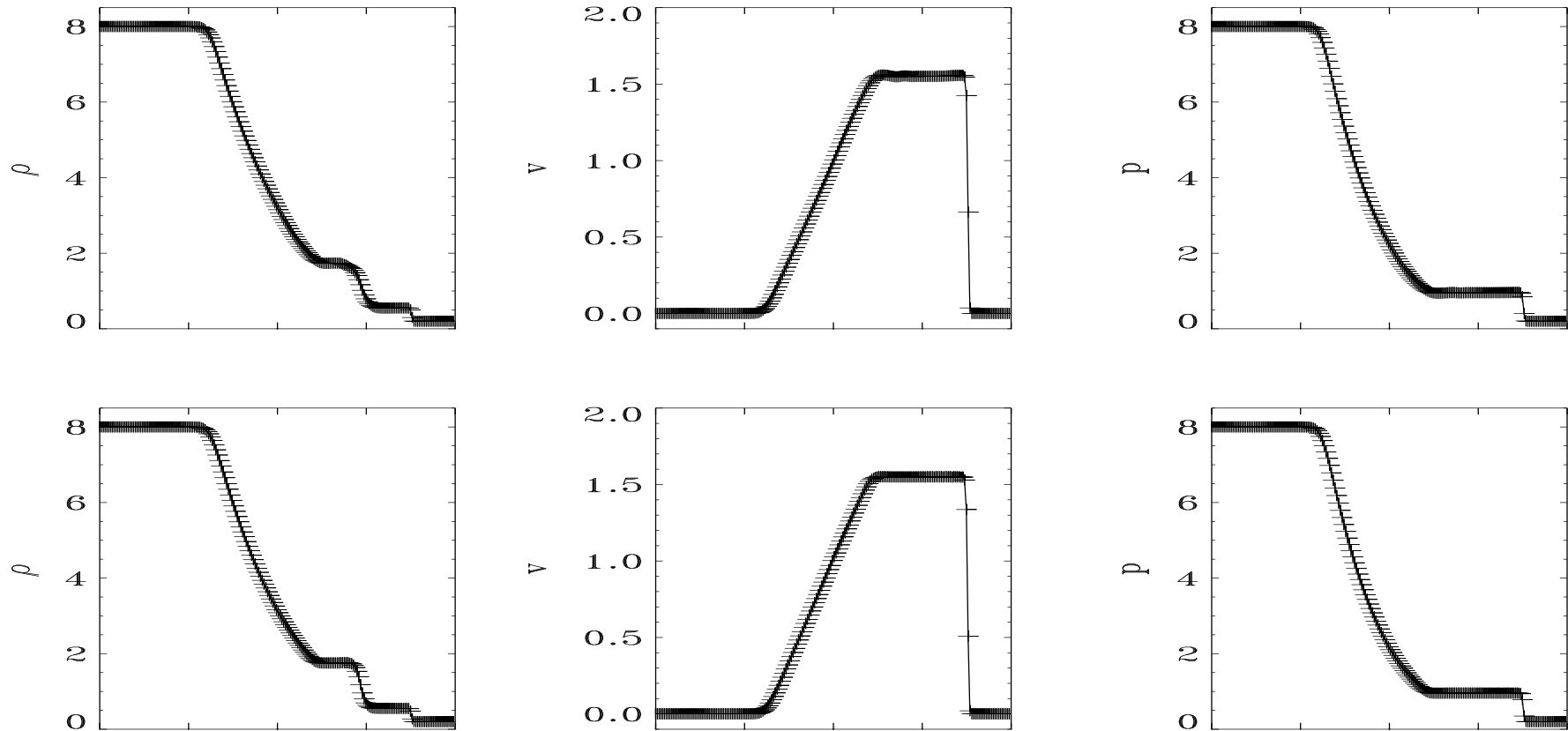
⇒ with  $\epsilon$  a small value, at play where  $|v| \simeq c$

- Repeat Mach 3 with entropy fix:



⇒ Roe: (bottom) improvement over TVDLF (top)

- supersonic shock tube test:

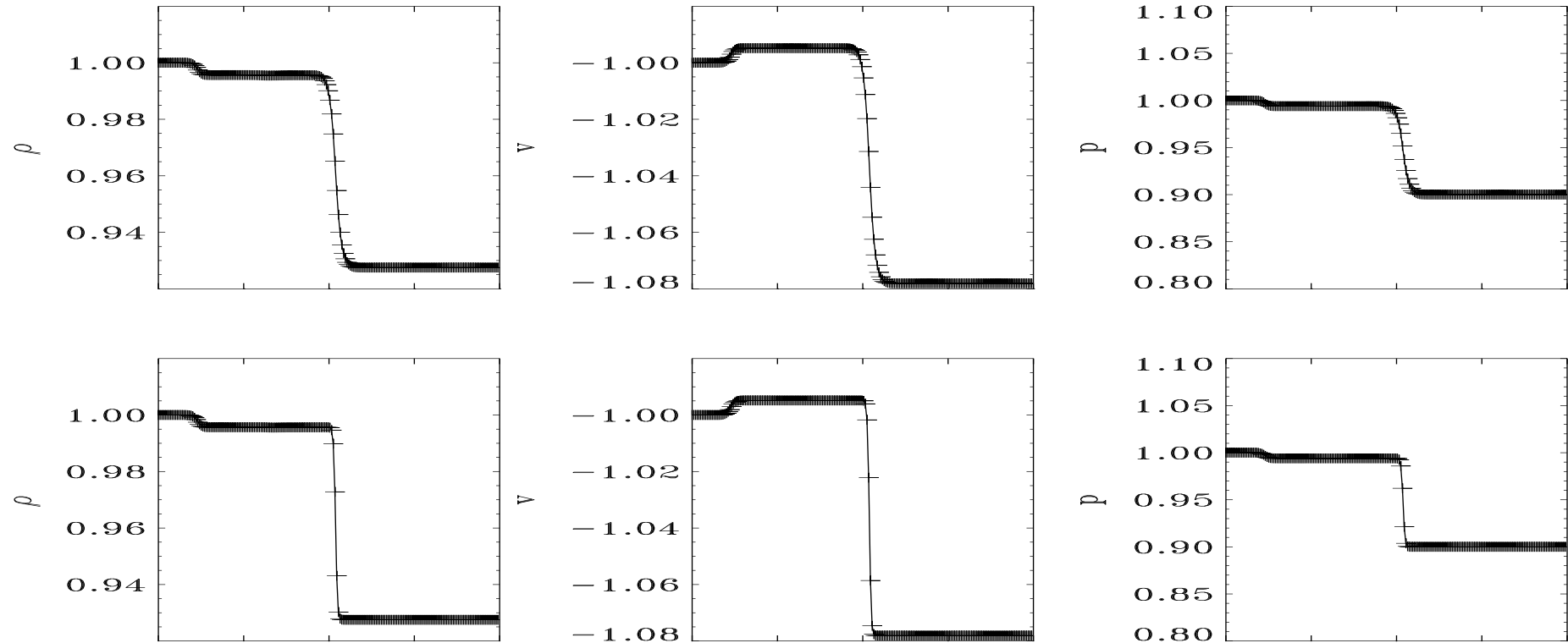


$\Rightarrow$  improvement over TVDLF, better at CD

- case of a slowly moving very weak shock, show  $t = 0.175$

$$\Rightarrow U_l = (\rho_l, v_l, p_l) = (1, -1, 1) \text{ and } U_r = (0.9275, -1.0781, 0.9)$$

$\Rightarrow$  leftward rarefaction and rightward shock



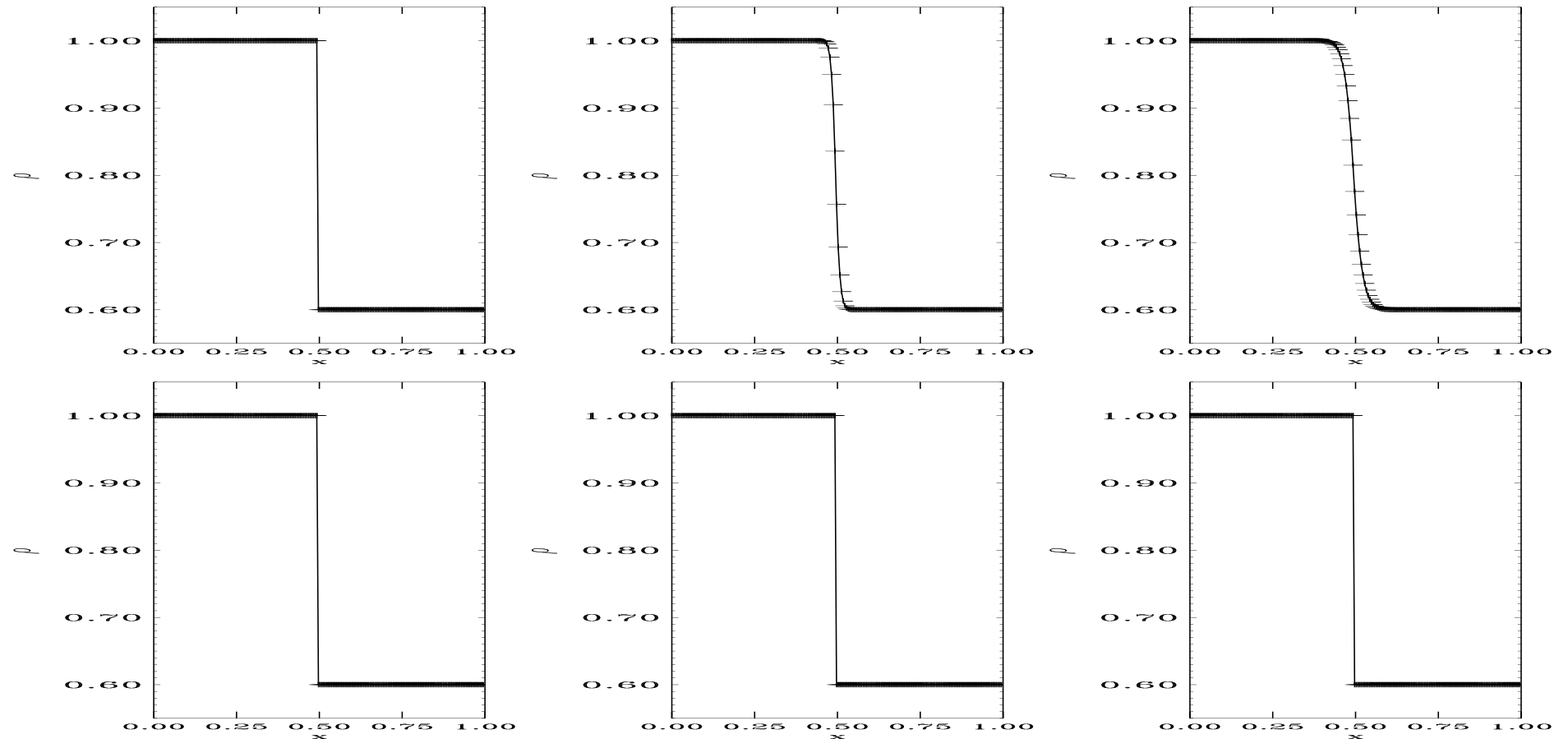
$\Rightarrow$  Roe (bottom) much better than TVDLF (top: many cells in shock)!



- stationary contact discontinuity :

$$\Rightarrow U_l = (\rho_l, v_l, p_l) = (1, 0, 0.5) \text{ and } U_r = (0.6, 0, 0.5)$$

$\Rightarrow t = 0$  and  $t = 0.1$  and  $t = 1$  solution



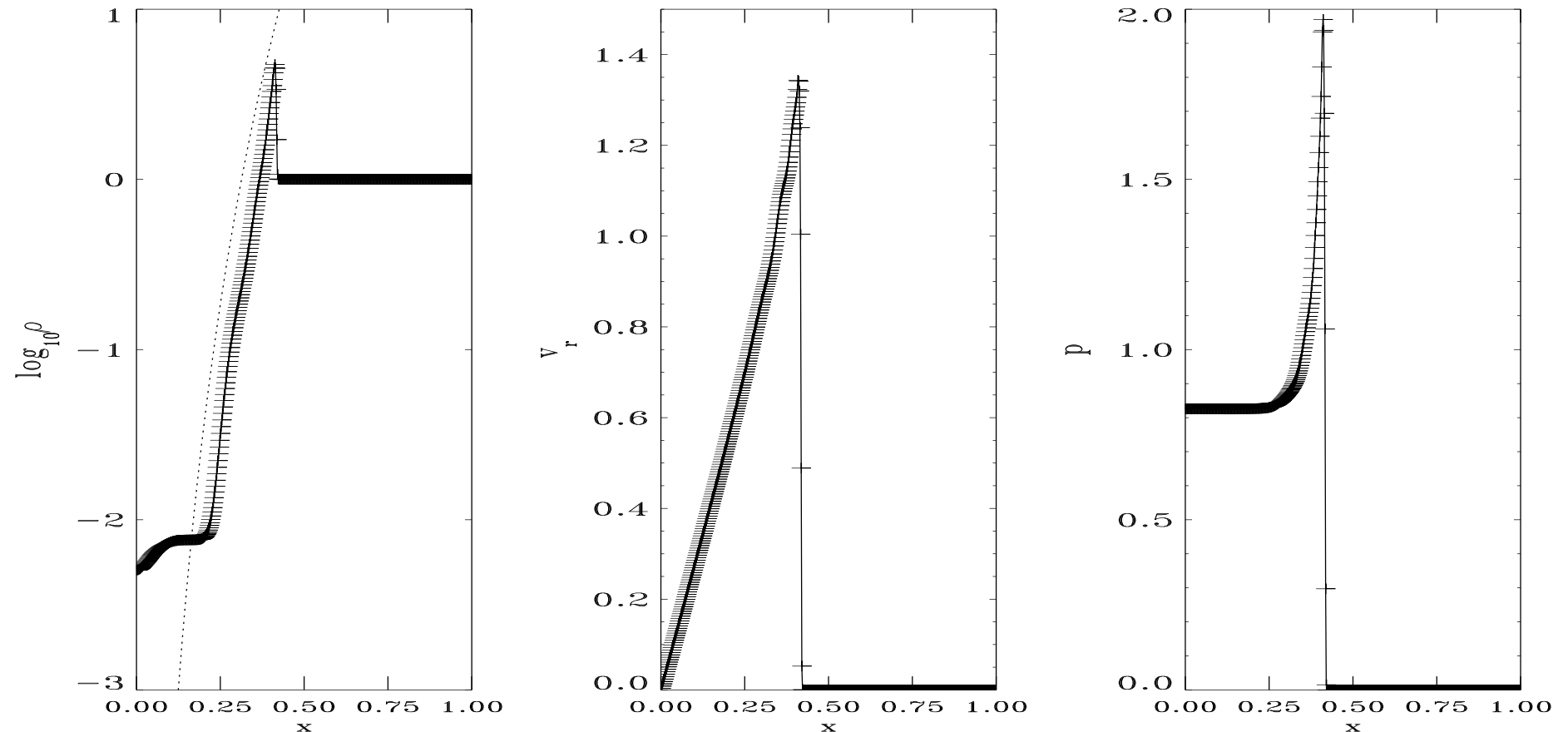
$\Rightarrow$  **Roe (bottom): CD recognized as steady solution, no diffusion!!!**

- summarizing
  - ⇒ non-trivial calculation of Roe flux (more involved than TVDLF)
  - ⇒ need for entropy fix for transonic expansion fans
  - ⇒ better representation of CD, especially stationary CD
  - ⇒ ok with slowly traveling weak shocks
- note: conclusions for 2nd order variants of TVDLF and Roe-based TVD
  - ⇒ both heavily used in multi-D HD simulations

## Sedov blast wave

- astrophysical application: ‘supernova’ explosion or ‘blast wave’
  - ⇒ modeled as 1D Euler Riemann Problem in spherical symmetry
- initial conditions  $v_r = 0$ ,  $\rho = 1$ , and  $\gamma = 1.4$ 
  - ⇒ extreme  $p$  jump  $p_{exp} = 763.944$  for  $r \in [0, 0.05]$  and  $p_{ext} = 10^{-5}$
  - ⇒ take 512 grid points on  $r = [0, 1]$  run till time  $t = 0.1$  with TVD

- good agreement with analytical result



- $\Rightarrow p$  goes to constant value at center
- $\Rightarrow v_r$  goes to linear profile in  $r/R(t)$  with  $R(t)$  shock position
- $\Rightarrow$  density goes to profile  $(r/R(t))^{3/(\gamma-1)}$  (overplotted)