

SEENIVASAN LALITHKUMAR

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EDUCATION

Doctor of Philosophy (PhD), Biomedical Engineering

2019 – Ongoing
National University of Singapore, Singapore
• AI-assisted scene understanding in robotic surgery.

B.Eng. (Hons) Electrical Engineering

2016 – 2019
National University of Singapore, Singapore
• Design Centric Programme
• CAP: 3.94 / 5.0
• Student Exchange Programme at Tampere University of Technology, Finland.

Diploma in Mechatronics

2010 – 2013
Temasek Polytechnic, Singapore
• Diploma with Merit
• GPA: 3.91 / 4.0
• Diploma plus in Life Sciences Fundamentals

Secondary School Examination 2010

2000 – 2010
Vel's Vidyashram, India
• CGPA: 9.2/10

PUBLICATIONS

Key Highlights

- Seenivasan, L., Mitharan, S., Islam, M., & Ren, H. (2022). Global-reasoned multi-task learning model for surgical scene understanding. *IEEE Robotics and Automation Letters*.
- Islam, M., Seenivasan, L., Ren, H., & Glocker, B. (2021). Class-distribution-aware calibration for long-tailed visual recognition. *UDL Workshop, International Conference on Machine Learning*.
- Islam, M., Seenivasan, L., Ming, L. C., & Ren, H. (2020). Learning and reasoning with the graph structure representation in robotic surgery. In *International conference on medical image computing and computer-assisted intervention* (pp. 627–636). Springer.
- Xu, M., Seenivasan, L., Yeo, L. L. L., & Ren, H. (2020). Stent deployment detection using radio frequency-based sensor and convolutional neural networks. *Advanced Intelligent Systems*, 2(10), 2000092.
- Ren, H., Chen, C. X., Cai, C., Ramachandra, K., & Lalithkumar, S. (2017). Pilot study and design conceptualization for a slim single-port surgical manipulator with spring backbones and catheter-size channels. In *2017 IEEE International Conference on Information and Automation (ICIA)* (pp. 499–504). IEEE.

LIFE PHILOSOPHY

“Follow your passion and it’s no longer work”

AWARDS

National University of Singapore

- Outstanding Undergraduate Researcher Prize AY2017/2018
- FoE 32nd INNOVATION & RESEARCH AWARD (2018)

Temasek Polytechnic

- Singapore Manufacturing Federation Metal, Machinery & Engineering Industry Group Project Prize 2013
- Commendation Award for Major Project 2013
- CCA Merit Award in Leadership 2013
- Director's List Award 2013
- Director's List Award 2012

National Service, Singapore Police Force

- Commander's Outstanding Performance Award 2015
- Sword Of Merit, Police Officer Cadet Course 2014

SKILLS

Python PyTorch OpenCV

C / C++ Gazebo simulator

Robot Operating System (ROS)

LabVIEW Verilog

microcontroller programming

CAD Design Sheet metal design

Mechanical Prototyping

LANGUAGES

English
Tamil



👥 Collaborations

- Huaultmé, A., Harada, K., Nguyen, Q.-M., Park, B., Hong, S., Choi, M.-K., ... Dou, Q., et al. (2022). Peg transfer workflow recognition challenge report: Does multi-modal data improve recognition? *arXiv preprint arXiv:2202.05821*.
- Nwoye, C. I., Alapatt, D., Yu, T., Vardazaryan, A., Xia, F., Zhao, Z., ... Wang, H., et al. (2022). Choelectriplet2021: A benchmark challenge for surgical action triplet recognition. *arXiv preprint arXiv:2204.04746*.
- Lal, R., Swaminathan, R., Seenivasan, L., Qiu, L., & Ren, H. (2021). Scoopnet: 6dof pose estimation pipeline for origami-inspired worm robots. In *2021 IEEE International Conference on Development and Learning (ICDL)* (pp. 1–6). IEEE.
- Seenivasan, L., Bai, F., Ji, M., Gu, X., Tse, Z. T. H., & Ren, H. (2020). Shape tracking of flexible morphing matters from depth images. *IEEE Sensors Journal*, 21(6), 8234–8244.

EXPERIENCE

Research Engineer

National University of Singapore

📅 Dec 2020 – Ongoing 📍 Singapore

- Manage and lead projects with research interns

Engineering Manager

Aitech Robotics And Automation Pte Ltd

📅 Aug 2019 – Jul 2020 📍 Singapore

- Technical adviser
- Lead and manage the R&D department
- Design overall system architecture

Software Engineer (Part-time)

Aitech Robotics And Automation Pte Ltd

📅 Jun 2016 – Jul 2019 📍 Singapore

Associate Engineer

Aitech Robotics And Automation Pte Ltd

📅 Jan 2016 – Jun 2016 📍 Singapore

- Member of the R&D department
- Develop robotic solutions in the Robot Operating System (ROS)
- Develop autonomous navigation stack (robot localization, navigation and obstacle avoidance)

Temp Technical Support Officer

Temasek Polytechnic

📅 Oct 2013 – Jan 2014 📍 Singapore

- Involved in a research project in developing an indoor micro-aerial vehicle with autonomous navigation features without the aid of GPS

Lab Assistant (Part-time)

Temasek Polytechnic

📅 Oct 2011 – Sep 2013 📍 Singapore

- Assist and support lecturers in teaching the students

NATIONAL SERVICE



Assistant Superintendent of Police Reservist

📅 2021 – ongoing 👤 Singapore Police Force



Inspector Reservist

📅 2016 – 2021 👤 Singapore Police Force



National Service Inspector Active

📅 2014 – 2016 👤 Singapore Police Force

LEADERSHIP

Vice-Captain, Touch Rugby

📅 2018 – 2019 🏠 NUS Raffles Hall

Captain, Touch Rugby

📅 2017 – 2018 🏠 NUS Raffles Hall

Quartermaster, Temasek Polytechnic International Students Group

📅 2012 – 2013 🏠 Temasek Polytechnic

Member, Scouts

📅 2007 – 2009 🏠 Vel's Vidyashram

CO-CURRICULAR

Touch Rugby

📅 2016 – 2019 🏠 NUS Raffles Hall

Softball

📅 2016 – 2019 🏠 NUS Raffles Hall

Board of Photography

📅 2017 – 2018 🏠 NUS Raffles Hall

Temasek Polytechnic International Students Group

📅 2010 – 2013 🏠 Temasek Polytechnic

PERSONAL INTEREST

