SEENIVASAN LALITHKUMAR



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EDUCATION

Doctor of Philosophy (PhD), Biomedical Engineering

- **2019** Ongoing
- National University of Singapore, Singapore
- Al-assisted scene understanding in robotic surgery.

B.Eng. (Hons) Electrical Engineering

- **2016 2019**
- National University of Singapore, Singapore
- Design Centric Programme
- CAP: 3.94 / 5.0
- Student Exchange Programme at Tampere University of Technology, Finland

Diploma in Mechatronics

- **2010 2013**
- ▼ Temasek Polytechnic, Singapore
- Diploma with Merit and Diploma plus in Life Sciences Fundamentals

PUBLICATIONS

Key Highlights

- Seenivasan, L., Islam, M., Krishna, A. K., & Ren, H. (2022). Surgicalvqa: Visual question answering in surgical scenes using transformer. In International conference on medical image computing and computer-assisted intervention (pp. 33-43). Springer.
- Seenivasan, L., Islam, M., Ng, C.-F., Lim, C. M., & Ren, H. (2022). Biomimetic incremental domain generalization with a graph network for surgical scene understanding. Biomimetics, 7(2), 68.
- Seenivasan, L., Islam, M., Xu, M., Lim, C. M., & Ren, H. (2022). Task-aware asynchronous multi-task model with class incremental contrastive learning for surgical scene understanding. (Accepted in IJCARs), arXiv preprint arXiv:2211.15327.
- Seenivasan, L., Mitheran, S., Islam, M., & Ren, H. (2022). Globalreasoned multi-task learning model for surgical scene understanding. IEEE Robotics and Automation Letters.
- Islam, M., Seenivasan, L., Ren, H., & Glocker, B. (2021). Classdistribution-aware calibration for long-tailed visual recognition. UDL Workshop, International Conference on Machine Learning.
- Islam, M., Seenivasan, L., Ming, L. C., & Ren, H. (2020). Learning and reasoning with the graph structure representation in robotic surgery. In International conference on medical image computing and computer-assisted intervention (pp. 627-636). Springer.
- Xu, M., Seenivasan, L., Yeo, L. L. L., & Ren, H. (2020). Stent deployment detection using radio frequency-based sensor and convolutional neural networks. Advanced Intelligent Systems, 2(10), 2000092.

LIFE PHILOSOPHY

"Follow your passion and it's no longer work"

AWARDS

National University of Singapore

- Outstanding Undergraduate Researcher Prize AY2017/2018
- FoE 32nd INNOVATION & RESEARCH AWARD (2018)

Temasek Polytechnic

- Singapore Manufacturing Federation Metal, Machinery & Engineering Industry Group Project Prize 2013
- Commendation Award for Major Project 2013
- CCA Merit Award in Leadership 2013
- Director's List Award 2013
- Director's List Award 2012

National Service, Singapore Police

- Commander's Outstanding Performance Award
- Sword Of Merit, Police Officer Cadet Course 2014

CITATION METRICS

Citations: 47

H-index: 4

i10-index: 1 (As of Jan 2023)

SKILLS

Pvthon PvTorch OpenCV

Gazebo simulator

ROS

LabVIEW

C / C++

Verilog

microcontroller programming

CAD Design

Mechanical Prototyping

LANGUAGES

English Tamil



• Ren, H., Chen, C. X., Cai, C., Ramachandra, K., & Lalithkumar, S. (2017). Pilot study and design conceptualization for a slim single-port surgical manipulator with spring backbones and cathetersize channels. In 2017 ieee international conference on information and automation (icia) (pp. 499-504). IEEE.

Collaborations

- Huaulmé, A., Harada, K., Nguyen, Q.-M., Park, B., Hong, S., Choi, M.-K., ... Dou, Q., et al. (2022). Peg transfer workflow recognition challenge report: Does multi-modal data improve recognition? arXiv preprint arXiv:2202.05821.
- Nwoye, C. I., Alapatt, D., Yu, T., Vardazaryan, A., Xia, F., Zhao, Z., ... Wang, H., et al. (2022). Cholectriplet2021: A benchmark challenge for surgical action triplet recognition. arXiv preprint arXiv:2204.04746.
- Pang, W., Islam, M., Mitheran, S., Seenivasan, L., Xu, M., & Ren, H. (2022). Rethinking feature extraction: Gradient-based localized feature extraction for end-to-end surgical downstream tasks. IEEE Robotics and Automation Letters, 7(4), 12623–12630.
- Lal, R., Swaminathan, R., Seenivasan, L., Qiu, L., & Ren, H. (2021). Scoopnet: 6dof pose estimation pipeline for origami-inspired worm robots. In 2021 ieee international conference on development and learning (icdl) (pp. 1–6). IEEE.
- Seenivasan, L., Bai, F., Ji, M., Gu, X., Tse, Z. T. H., & Ren, H. (2020). Shape tracking of flexible morphing matters from depth images. IEEE Sensors Journal, 21(6), 8234-8244.

EXPERIENCE

Research Engineer **National University of Singapore**

- Dec 2020 Ongoing
- Singapore
- Manage and lead projects with research interns

Engineering Manager

Aitech Robotics And Automation Pte Ltd

- **Aug** 2019 Jul 2020
- Singapore
- Lead and manage the R&D department
- Technical adviser & Design overall system architecture

Software Engineer (Part-time), R&D Department Aitech Robotics And Automation Pte Ltd

- **J**un 2016 Jul 2019

Associate Engineer, R&D Department Aitech Robotics And Automation Pte Ltd

- **a** Jan 2016 Jun 2016
- Singapore
- Develop robotic solutions in the Robot Operating System (ROS)
- Develop autonomous navigation stack (robot localization, navigation and obstacle avoidance)

Temp Technical Support Officer Temasek Polytechnic

- iii Oct 2013 Jan 2014
- Singapore
- Involved in a research project in developing an indoor micro-aerial vehicle with autonomous navigation features without the aid of GPS

NATIONAL SERVICE

Assistant Superintendent of Police Reservist

📋 2021 – ongoing 🛮 🚢 Singapore Police Force

Inspector Reservist

2016 - 2021

Singapore Police Force

National Service Inspector

Active

2014 - 2016

Singapore Police Force

LEADERSHIP

Vice-Captain, Touch Rugby

2018 - 2019

Captain, Touch Rugby

2017 - 2018

1 NUS Raffles Hall

Quartermaster, Temasek Polytechnic International Students Group

2012 - 2013

Member, Scouts

2007 - 2009

1 Vel's Vidyashram

CO-CURRICULAR

Touch Rugby

2016 - 2019

Softball

= 2016 - 2019

1 NUS Raffles Hall

Board of Photography

2017 - 2018

nus Raffles Hall

Temasek Polytechnic International Students Group

2010 - 2013

1 Temasek Polytechnic

PERSONAL INTEREST

