```
#include <iostream>
#include <vector>
#include <queue>
#include <omp.h>
using namespace std;
class Graph {
  int V; // Number of vertices
  // Adjacency list representation of graph
  vector<vector<int>> adj;
public:
  Graph(int V) : V(V), adj(V) \{\}
  // Add an edge to the graph
  void addEdge(int u, int v) {
     adj[u].push back(v);
    adj[v].push_back(u); // Assuming undirected graph
  }
  // Parallel Breadth First Search
  void parallelBFS(int start) {
    vector<bool> visited(V, false);
     queue<int> q;
    #pragma omp parallel
       #pragma omp single
         q.push(start);
         visited[start] = true;
       while (!q.empty()) {
          int u;
         #pragma omp critical
            u = q.front();
            q.pop();
```

```
#pragma omp for
          for (int v : adj[u]) {
            if (!visited[v]) {
               #pragma omp critical
                 q.push(v);
                 visited[v] = true;
          #pragma omp barrier
          #pragma omp master
            cout << u << " ";
  // Parallel Depth First Search
  void parallelDFS(int start) {
     vector<bool> visited(V, false);
     #pragma omp parallel
       parallelDFSUtil(start, visited);
private:
  // DFS utility function
  void parallelDFSUtil(int u, vector<bool>& visited) {
     if (visited[u]) return;
     visited[u] = true;
     cout << u << " "; // Process the current node
     #pragma omp for
     for (int v : adj[u]) {
       parallelDFSUtil(v, visited);
};
```

```
int main() {
    Graph g(6);
    g.addEdge(0, 1);
    g.addEdge(0, 2);
    g.addEdge(1, 3);
    g.addEdge(1, 4);
    g.addEdge(2, 5);

    cout << "Parallel BFS starting from node 0:" << endl;
    g.parallelBFS(0);
    cout << endl;

    cout << "Parallel DFS starting from node 0:" << endl;
    g.parallelDFS(0);
    cout << endl;

    return 0;
}</pre>
```