

```

1  program two_body_problem
2      implicit none
3      real::G,Ma,Mb,gravconst,t,tmax,dt      !Constants
4      real::xa,xb,ya,yb                      !positions
5      real::vxa,vxb,vya,vyb                  !velocities
6      real::rx,ry,modr3,fx,fy
7
8      open(1,file="body1.dat");    open(2,file="body2.dat")
9
10     G = 1; Ma = 1; Mb = 1; gravconst = G*Ma*Mb
11     tmax = 2.5; dt = 0.001; t = 0
12     !particle a's initial position and velocity
13     xa = 0.5; ya = 0.0;      vxa = 0; vya = 0.5
14
15     !particle b's initial position and velocity
16     xb = -0.5; yb = 0.0;      vxb = 0.0; vyb = -0.5
17
18     do while(t <= tmax)
19         rx = xa - xb;  ry = ya - yb
20         modr3 = (rx**2.0 + ry**2.0)**1.5
21
22         fx = -gravconst*rx/modr3;  fy = -gravconst*ry/modr3
23
24         vxa = vxa + fx*dt/Ma;  vya = vya + fy*dt/Ma
25         vxb = vxb - fx*dt/Mb;  vyb = vyb - fy*dt/Mb
26
27         xa = xa + vxa*dt;  ya = ya + vya*dt
28         xb = xb + vxb*dt;  yb = yb + vyb*dt
29
30         t = t + dt
31
32         write(1,*)xa,ya;    write(2,*)xb,yb
33
34     enddo
35
36 end program

```