# Line Search Algorithm for Optimization

- Mathe 3 (CES)
- WS20
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```
    using PlutoUI, Calculus, Gadfly, LinearAlgebra
```

# **Define Objective**

$$f(x) = x^2$$

```
f = #1 (generic function with 1 method)
  f = (x -> x[1]^2)
```

#### Line Search

```
1. Given x^{(0)} 2. For k+0,1,2,\ldots do 1. Update: x^{(k+1)}=x^{(k)}+lpha_k d^{(k)} 3. End
```

line\_search (generic function with 1 method)

## **Check Line Search**

Observe that different step sizes change the result!

```
(0, Any[1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0])

• line_search(f, 1, (x->1), (x->-sign(x)), 10)

(1, Any[1, -1, 1, -1, 1, -1, 1, -1, 1])

• line_search(f, 1, (x->2), (x->-sign(x)), 10)
```

#### **Gradient Descent**

ullet Is basically line search with  $d^{(k)} = - 
abla f(x^{(k)})$ 

hessian (generic function with 9 methods)

```
begin
# some notation
∇ = derivative
∇² = hessian
end
```

gradient\_descent (generic function with 1 method)

```
    function gradient_descent(f, x0, α, kmax)
    return line_search(f, x0, α, (x->-∇(f, x)), kmax)
    end
```

#### **Check Gradient Descent**

```
(2.03704e-10, Any[1, 0.8, 0.64, 0.512, 0.4096, 0.32768, 0.262144, 0.209715, 0.167

• gradient_descent(f, 1, (x->0.1), 100)

(2.03704e-10, Any[1, -0.8, 0.64, -0.512, 0.4096, -0.32768, 0.262144, -0.209715, 0

• gradient_descent(f, 1, (x->0.9), 100) # slower, oscillating but converging
```

## Newton's Method for Optimization

ullet Is line search with  $d^{(k)} = - \left[ 
abla^2 f(x^{(k)}) 
ight]^{-1} 
abla f(x^{(k)})$ 

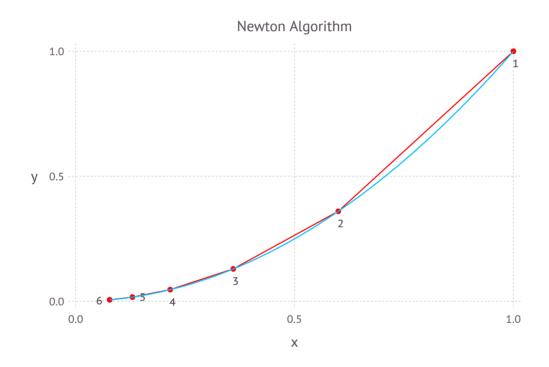
```
newton (generic function with 1 method)
```

```
    function newton(f, x0, α, kmax)
    return line_search(f, x0, α, (x->-inv(∇²(f, x))*∇(f, x)), kmax)
    end
```

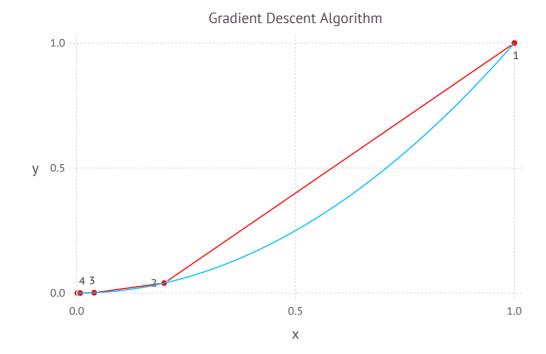
### **Check Newton's Method**

```
(1.05879e-22, Any[1.0, -7.28306e-7, 1.05879e-22, 1.05879
```

#### Visualize Results



```
begin
    res_n = newton(f, 1., (x->0.4), 5)
Gadfly.plot(
Guide.title("Newton Algorithm"),
layer(f, minimum(res_n[2]), maximum(res_n[2])),
layer(x=res_n[2], y=f.(res_n[2]), label=string.(1:length(res_n[2])),
Geom.point, Geom.path, Geom.label, Theme(default_color=color("red")))
end
end
```



## **Two-Dimensional Optimization**

## **Define Objective**

$$g(x,y) = x^2 + y^2$$

```
g = \#23 (generic function with 1 method)
g = (x->x[1]^2+x[2]^2)
```

#### **Check Methods**

both work

```
res_gd_2d =

(Float64[4.18545e-22, 4.18545e-22], Any[Float64[1.0, 1.0], Float64[0.2, 0.2], Float

• res_gd_2d = gradient_descent(g, [1.,1.], (x->0.4), 100)
```

```
res_n_2d =
   (Float64[2.33348e-22, 3.04878e-22], Any[Float64[1.0, 1.0], Float64[0.6, 0.6], Float
   res_n_2d = newton(g, [1.,1.], (x->0.4), 100)

Float64[2.33348e-22, 3.04878e-22]
   res_n_2d[2][end]
```

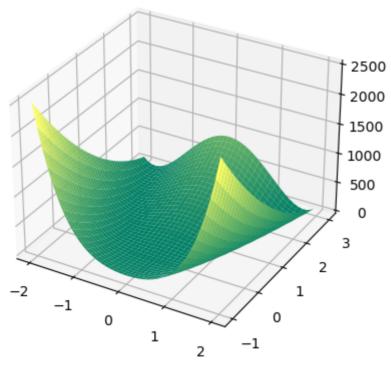
#### true

```
• norm(res_n_2d[2][end] - [0,0]) < eps(Float64) # is converged to machine-precision?</pre>
```

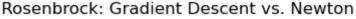
## Test Gradient Descent vs Newton for 2D Rosenbrock

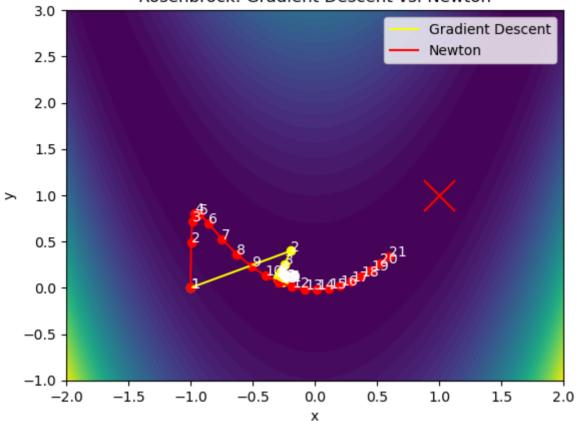
```
    begin
    ENV["MPLBACKEND"]="Agg"
    using PyPlot
    end
```

#### Rosenbrock Function



```
    X=collect(-2:\Delta:2)
    Y=collect(-1:\Delta:3)
    ff = (x->x[1]^2+x[2]^2)
    F=[h([X[j],Y[i]]) for i=1:length(X), j=1:length(Y)]
    clf()
    surf(X, Y, F, cmap=:summer)
    PyPlot.title("Rosenbrock Function")
    gcf()
end
```





```
begin
     # Rosenbrock function with x* = [a,a^2], f(x*)=0
     a = 1
     b = 100
     h = (x \rightarrow (a-x[1])^2 + b*(x[2]-x[1]^2)^2)
     x0 = [-1.,0.]
     # Gradient Descent
     res_gd_2d_rb = gradient_descent(h, x0, (x->0.002), 20)
res_gd_2d_rb_x = [res_gd_2d_rb[2][i][1] for i=1:length(res_gd_2d_rb[2])]
res_gd_2d_rb_y = [res_gd_2d_rb[2][i][2] for i=1:length(res_gd_2d_rb[2])]
     # Newton
     res_n_2d_rb = newton(h, x0, (x->0.5), 20)
res_n_2d_rb_x = [res_n_2d_rb[2][i][1] for i=1:length(res_n_2d_rb[2])]
res_n_2d_rb_y = [res_n_2d_rb[2][i][2] for i=1:length(res_n_2d_rb[2])]
     clf()
     \Delta = 0.1
     X=collect(-2:\Delta:2)
     Y=collect(-1:\Delta:3)
     F=[h([X[j],Y[i]]) for i=1:length(X), j=1:length(Y)]
     contourf(X,Y,F, levels=50)
     PyPlot.title("Rosenbrock: Gradient Descent vs. Newton")
     # res_gd_2d_rb
     PyPlot.plot(res_gd_2d_rb_x, res_gd_2d_rb_y, color="yellow")
     scatter(res_gd_2d_rb_x, res_gd_2d_rb_y, color="yellow")
     for i=1:length(res_gd_2d_rb_x)
          annotate(string(i), [res_gd_2d_rb_x[i], res_gd_2d_rb_y[i]], color="w",
zorder=2)
     end
     # res_n_2d_rb
     PyPlot.plot(res_n_2d_rb_x, res_n_2d_rb_y, color="red")
     scatter(res_n_2d_rb_x, res_n_2d_rb_y, color="red")
     for i=1:length(res_n_2d_rb_x)
```

```
annotate(string(i), [res_n_2d_rb_x[i], res_n_2d_rb_y[i]], color="w",
zorder=2)
end

legend(["Gradient Descent", "Newton"])

xlabel("x")
ylabel("y")

# Mark minimum
scatter(a, a^2, color="r", s=500, zorder=3, marker="x")

gcf()
end
```