

## Riemann surfaces

A complex analytic manifold  $X$  of dimension one is called a Riemann surface. If  $X$  is non-compact one refers to an open Riemann surface, while  $X$  is a closed Riemann surface if it is compact. The study of open, respectively closed Riemann surface leads to different results. When  $X$  is closed the maximum principle for analytic functions entails that the space  $\mathcal{O}(X)$  of globally defined holomorphic functions is reduced to constant function. For an open Riemann surface  $X$  the situation is quite different. For example, let  $\{p_\nu\}$  be a discrete sequence of points on  $X$  and  $\{k_\nu\}$  a sequence of positive integers then there exists  $f \in \mathcal{O}(X)$  which is zero-free outside the  $p$ -points, and for every  $\nu$  it has a zero of order  $k_\nu$  at  $p_\nu$ . Moreover the Cousin problem has a solution for every pair of open sets  $U, V$  whose union is equal to  $X$ . It means that for every  $\phi \in \mathcal{O}(U \cap V)$  there exist  $a \in \mathcal{O}(U)$  and  $b \in \mathcal{O}(V)$  such that the restriction of  $a - b$  to  $U \cap V$  is equal to  $\phi$ . When  $X$  is a compact Riemann surface the obstruction to solutions of the Cousin problem for a pair of open sets  $U, V$  whose union is  $X$  turns out to be described by a  $g$ -dimensional complex vector space where  $g$  is the genus of  $X$ . We treat the compact case in § x while open Riemann surfaces are studied in § xx. Closed Riemann surfaces arise via algebraic equations. Namely, let  $\mathbf{C}[x, y]$  be the polynomial ring of two variables with complex coefficients. To each irreducible polynomial  $p(x, y)$  we get the algebraic curve in  $\mathbf{C}^2$  defined by  $\{p = 0\}$  and let us denote it by  $S$ . Assume that  $p$  is monic with respect to  $y$ , i.e.

$$p(x, y) = y^m + q_{m-1}(x)y^{m-1} + \dots + q_0(x)$$

where no special assumption is imposed on the  $q$ -polynomials except for the condition that  $p(x, y)$  is an irreducible polynomial. General residue calculus - which actually is valid for algebraic hypersurfaces in  $\mathbf{C}^n$  for every  $n \geq 2$  asserts that there exists a  $\bar{\partial}$ -closed current of bi-degree  $(1, 0)$  define for test-forms  $\psi^{0,1}$  in the 4-dimensional space attached to  $\mathbf{C}^2$  and defined by

$$\psi^{0,1} \mapsto \int_S \frac{dx}{P'_y} \wedge \psi^{0,1}$$

Above  $S$  is an algebraic curve in  $\mathbf{C}^2$  and we remark that the  $\bar{\partial}$ -closed current excises in general, i.e. even when  $S$  contains singular points. However, via a classical local contraction due to Puiseux there exists normalization of  $S$  which yields a non-singular curve  $\hat{S}$  and a map  $\rho: \hat{S} \rightarrow S$ . Passing to the proalgebraic closure one can also construct local charts in the sense of Puiseux and in this way arrive at a closed Riemann surface  $X$  for this one has a map  $\rho: X \rightarrow \hat{S}$  which in many cases is a homeomorphism but in certain examples it appears that for a finite set of points in  $S$  the inverse image  $\rho^{-1}(s)$  is a finite set in  $X$ . However, in all cases the current  $(*)$  yields via a pull-back to  $X$  a  $\bar{\partial}$ -closed differential form which therefore is called a holomorphic form. The whole space of holomorphic 1-forms on  $X$  is denoted by  $\Omega(X)$ . We shall learn that it is a finite dimensional complex vector space whose dimension is equal to the genus of  $X$ . To find a basis for  $\Omega(X)$  one must study under what conditions the special holomorphic 1-form extends to be holomorphic at points in  $X$  which belong to  $\rho^{-1}(\partial S)$ . Here one encounters typical calculations during the study of closed Riemann surfaces.

**An example.** Consider the case

$$p(x, y) = y^2 - q(x)$$

where  $q(x)$  is a polynomial on  $x$  only and of some odd degree  $2m + 1$  with  $m \geq 1$ . Here we shall learn that  $y$  extends to a meromorphic function on  $X$  with a pole of order  $2m + 1$  at the point at infinity, while  $x$  has a pole of order 2. From this it follows that the meromorphic differential  $dx$  has a pole of order 3 at infinity and at the same time  $y^{-1}$  has a zero of order  $2m + 1$ . It follows that  $\frac{dx}{y}$  remains holomorphic at the point at infinity. If  $m \geq 2$  one gets more holomorphic 1-forms on  $X$  using

$$\omega_\nu = x^\nu \cdot \frac{dx}{y}$$

where the condition is that

$$2\nu \leq 2m + 1 - 3 \implies \nu \leq m - 1$$

From this it follows that the  $g = m$ . Consider s an example the case  $m = 2$  and we the polynomials  $q(x)$  of the form

$$q(x) = \prod (x - \alpha_\nu)$$

where  $\alpha_1, \dots, \alpha_5$  are distinct complex numbers. So to every such  $q$ -polynomial we arrive at a closed Riemann surface of genus two. with we denote by  $X(\alpha_1, \dots, \alpha_5)$  Now one enuoviuner a typical modality problem, i.e decide when a pair of such closed Riemann surfaces are isomorphic. We shall find that the answer is highly non-trivial.