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Study of Models for
Runtime Remote Attestations

Submitted by

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Declaration of Authorship

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"By (the Token of) Time (through the ages), Verily Man is in loss, Except such as have Faith, and do righteous deeds, and (join together) in the mutual teaching of Truth, and of Patience and Constancy."

The Quran - The Epoch

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Abstract

ISTD (MSSD)

Master of Science in Security by Design

Study of Models for
Runtime Remote Attestations

by Jon Kartago LAMIDA

Runtime remote attestation enable attesting application to ensure there is no control flow attack that alter the intended behavior of the program. Prior to the ScaRR [18] , remote attestation was only feasible for embedded system and there was no scalable solution for complex programs. This thesis present the implementation of ScaRR offline measurement using LLVM and analyze the performance of the computation.

Flavio leave the abstract as last point ◁

Acknowledgements

The acknowledgments and the people to thank go here, don't forget to include your project advisor...

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This thesis is dedicated to my family

Chapter 1

Introduction

1.1 Motivation

This research are trying to answer these questions.

- How to implement offline program analysis for the ScaRR novel model for remote attestation?

- How is the performance of the analyzer?

- How is the performance comparison against some other attestation scheme such as C-Flat?

1.2 Related Works

In this section we present related work in model for remote attestation. Specifically we discuss how different attestation scheme encode the offline program representations.

C-Flat [1] is the first remote attestation scheme to detect runtime control flow attack for embedded systems. C-Flat are generating offline measurement by traversing all possible path of program from start node to the termination node. In each node, C-Flat hashes the node ID and the hash of previous node. In the first node, since there is no previous hash, we pass 0. This creates hash chains which is stored as offline measurement database.

Lo-Fat[8] is improving C-Flat by using hardware support for control flow attestation. Lo-Fat offline program analysis is still inheriting C-Flat approach.

Atrium [20] is remote attestation scheme that can provide resiliency against physical memory attack where adversaries can exploit the property of Time of Check Time of Use (TOCTOU) during attestation. In this paper author are describing memory bank attack where adversary can control instruction fetches to benign memory area when attestation is running and direct the fetch to the malicious area otherwise.

The offline measurement are calculated slightly different compared with C-Flat and Lo-Fat. In Atrium, the verifier perform one-time pre-processing to generate CFG of the program and computes cryptographic hash measurement over the instructions and addresses of basic blocks. C-Flat are only hash the node ID. While this approach can mitigate the TOCTOU attack, the offline measurement generation still grow exponentially as the complexity of the program grow.

LiteHax [7] is hardware assisted remote attestation scheme that allow verifier to detect these different attacks:
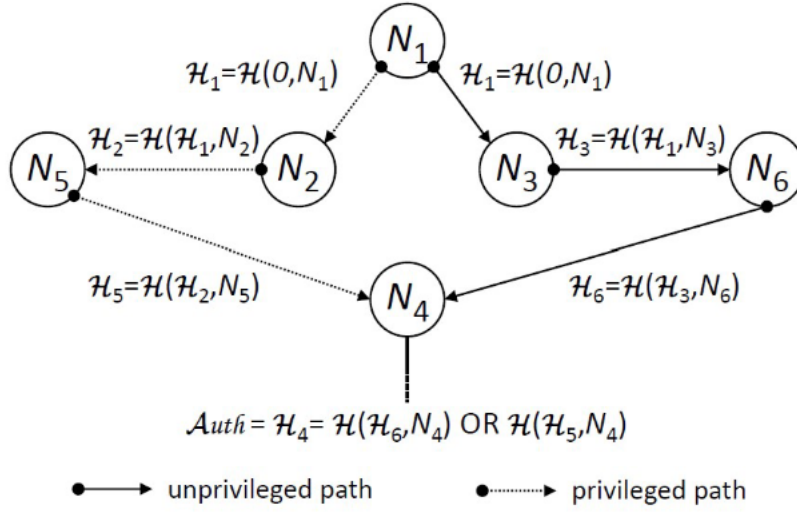
FIGURE 1.1: C-Flat
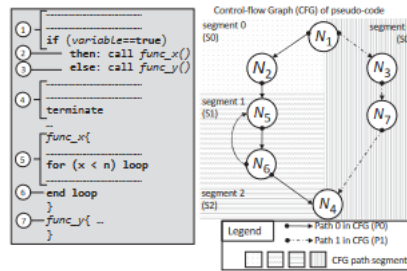
FIGURE 1.2: Atrium

- control-data attack such as code injection or code reuse attack like ROP

- non-control-data attack

- data-only attack such us DOP which do not affect control flow

Different with the previous remote attestation scheme, the offline measurement phase of LiteHax are only generates program CFG without calculating any hash over all control flow and data flow events. However, in the online prover-side verification time, prover are still computing hash and sending it as report to the verifier. Verifier runs symbolic execution and incremental forward data-flow analysis without doing any lookup to offline measurement database.

Diat [2] is remote attestation scheme that can attest data integrity and control-flow of autonomous systems. To improve efficiency of attestation, the program attested must be decomposed into small interacting modules. Data-flow monitoring is to be setup between critical modules. Control path attestation is being done against novel execution path representation using multiset has (MSH) function [5]. The use of MSH makes some execution order of the program lost.
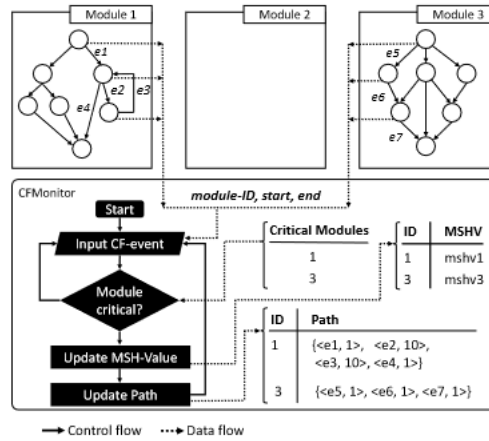
FIGURE 1.3: Diat

OAT [16] is remote attestation scheme to attest operation integrity of embedded device. OAT defines two type of measurements for control flow attestation: a trace (for recording branches and jumps) and a hash (for encoding returns). These two measurements are encoded as $H = Hash(H \bigoplus RetAddr)$ which called as attestation blob.

During verification, verifier reconstruct paths from the attestation blob. The control flow violation is identified when CFI check against an address is failed or mismatched between hash and trace.

Although OAT does not encounter the combinatorial hash explosion in C-Flat, there is a verification overhead since verifier needs to reconstruct the attestation blob. TODO compare the overhead with ScaRR.
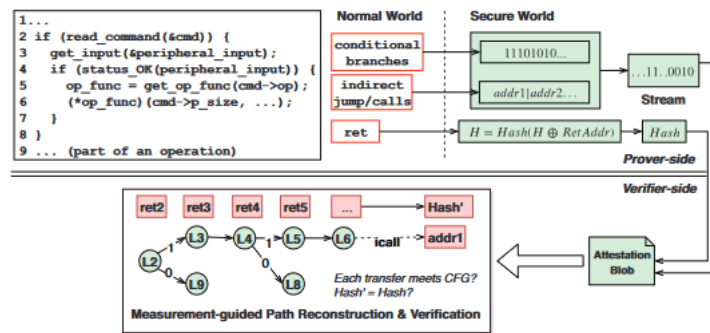
FIGURE 1.4: OAT

Chapter 2

Scope

2.1 Implementation

This thesis is implementing the ScaRR Control Flow Model as LLVM passes using LLVM 13.0.0.

2.2 Analysis

We analyzed the control-flow model extracted against different programs with various size and complexities. In this thesis, we are only analyzing program written in C. However, since the LLVM pass is running control from graph extraction against the intermediate representation, we should get consistent result on any programming language that compiles to IR.

Chapter 3

Background

In this chapter, we present some backgrounds on control-flow attack and remote attestation to detect attacks. The chapter ends with an overview of LLVM that relevant to the research.

3.1 Control Flow Attack

Control-flow attack happens when adversaries make a program to perform action of their choice without statically modify the program binary but alter the runtime properties of the program. The adversary intention can be to execute malicious operations or to leak secret information. Many of this runtime software security attacks are occured due to memory corruption bug in software written in low-level languages like C and C++ [17].

Once memory corruption is triggered, there are different exploit types which adversary can use to perform the attack. Some of the relevant exploits are control-flow hijack [15, 14] and data only attack [4, 3].

Control-flow hijack can be classified further into code injection attack and code reuse attack such as return oriented programming [13]. Code injection attack will inject code in the program which will execute action prepared by the attacker. Code injection attack is already mitigated by solution like non-executable stack (NX), Data Execution Prevention and $W \bigoplus R$ [19]. Code reuse attack will execute malicous action without injecting any codes, hence can't be detected by previously mentioned defenses mechanism. As example, return-oriented program chains together short instruction sequences already present in a program's address space, each of which ends in a `return` instruction. Unfortunately, ROP can not be mitigated by $W \bigoplus R$ [13].

Memory error attacks and defenses have been always a continuous battle which unfortunately has not shown that it is over. In 2016, Abera et al proposed to use remote attestation to detect control flow attack [1]. That paper opened many researches in this area which we briefly presented in 1.

3.2 Remote Attestation

In this thesis we explore the use of remote attestation in detecting control-flow attack. Remote attestation is the activity of making a claim about properties of a remote target by supplying evidence to an appraiser over a network [6]. The ubiquitous deployment of IoT and different applications in the cloud require robust remote attestation method

to ensure detection when the application is attacked. Remote attestation scope was only covering static attestation of the application binary. However, in the recent years there have been more sophisticated attack that can alter the behavior of application so that static attestation does not suffice.

In remote attestation, there are two roles involved, a trusted prover and a verifier. A prover is the one that must prove that the software has not been compromised. Verifier checks prover to ask the current state of runtime of the program. Alternatively, prover also can just update verifier periodically without being asked. The verifier compares the response from prover with the local database which has been generated before. If any of measurement mismatches, it means the has been violation due to an adversary's attack.

This research mainly focuses on offline measurement data generation for remote attestation which is used by verifier to validate the control flow graph. We use LLVM in implementing the offline program analyzer.

3.3   LLVM

LLVM is compiler framework that was developed by Chris Lattner which provides portable program representation and different tooling. LLVM supports the implementation of different frontend, backend and middle optimizer for various programming languages [9].

3.3.1   Intermediate Representation

LLVM intermediate representation (IR) provides high-level information about programs to support sophisticated analysis and transformations. However, the representation is low-level enough to represent arbitrary programs and to allow extensive optimization. As an example, consider a simple C program in listing 1.

The IR of the program can be seen in listing 2. The text representation below, is just one of form of IR. Beside this readable instruction representation, LLVM IR also can be represented as byte code and in memory representation. In the IR, each line contains LLVM instructions. Instructions are grouped in basic blocks: container for instructions that execute sequentially. This arrangement, makes application control flow graph (CFG) to be explicit in the IR. The details of LLVM IR is available in the Language Reference [10].

LLVM optimizer — which includes Analyzer and Transformer — are working on IR. In this thesis we are using this analyzer and transformer in building the Offline Program Analyzer.

3.3.2   LLVM Pass

LLVM are applying transformations — which may include some analysis pipelines — and optimizations on tools called `opt`. `opt` is taking LLVM IR (either as text, bytecode or in memory) as input and then do transformations, analysis and optimizations on it. Transformation and optimization alters the LLVM structure. Analysis gets information from the structure, which usually to be used by one or more transformations. Different transformations, optimizations and analyses are performed as pipelines of LLVM

```c
#include <stdio.h>

char *get_input()
{
    int rnd = rand() % 2;
    printf("get_input");
    return rnd == 1 ? "auth" : "error";
}

char *get_privileged_info()
{
    printf("get_privileged_info");
    return "you are privileged!";
}

char *get_unprivileged_info()
{
    printf("get_unprivileged_info");
    return "Invalid!";
}

void print_output(char *result)
{
    printf("%s", result);
}

void my_terminate()
{
    printf("Exiting...");
}

int main()
{
    char *access = get_input();
    char *result = "";
    if (strcmp(access, "auth") == 0)
    {
        result = get_privileged_info();
    }
    else
    {
        result = get_unprivileged_info();
    }
    print_output(result);
    my_terminate();
}
```

LISTING 1: Simple C Program

```
1   ; ModuleID = 'simple-loop-no-ext.c'
2   source_filename = "simple-loop-no-ext.c"
3   target datalayout = "e-m:e-p270:32:32-p271:32:32-p272:64:64-i64:..." ; truncated
4   target triple = "x86_64-pc-linux-gnu"
5
6   ; Function Attrs: noinline nounwind uwtable
7   define dso_local i32 @main() #0 {
8   entry:
9     %retval = alloca i32, align 4
10    %i = alloca i32, align 4
11    store i32 0, i32* %retval, align 4
12    store i32 0, i32* %i, align 4
13    br label %for.cond
14
15  for.cond:                                         ; preds = %for.inc, %entry
16    %0 = load i32, i32* %i, align 4
17    %cmp = icmp slt i32 %0, 10
18    br i1 %cmp, label %for.body, label %for.end
19
20  for.body:                                         ; preds = %for.cond
21    br label %for.inc
22
23  for.inc:                                          ; preds = %for.body
24    %1 = load i32, i32* %i, align 4
25    %inc = add nsw i32 %1, 1
26    store i32 %inc, i32* %i, align 4
27    br label %for.cond
28
29  for.end:                                          ; preds = %for.cond
30    %2 = load i32, i32* %retval, align 4
31    ret i32 %2
32  }
33
34  attributes #0 = { noinline nounwind uwtable ... } ; truncated ...
35
36  !llvm.module.flags = !{!0}
37  !llvm.ident = !{!1}
38
39  !0 = !{i32 1, !"wchar_size", i32 4}
40  !1 = !{!"clang version 10.0.0-4ubuntu1 "}
```

LISTING 2: LLVM IR The Sample C Program

entry:
 %retval = alloca i32, align 4
 %i = alloca i32, align 4
 store i32 0, i32* %retval, align 4
 store i32 0, i32* %i, align 4
 br label %for.cond

for.cond:
 %0 = load i32, i32* %i, align 4
 %cmp = icmp slt i32 %0, 10
 br i1 %cmp, label %for.body, label %for.end

| T | F |

for.body:
 br label %for.inc

for.end:
 %2 = load i32, i32* %retval, align 4
 ret i32 %2

for.inc:
 %1 = load i32, i32* %i, align 4
 %inc = add nsw i32 %1, 1
 store i32 %inc, i32* %i, align 4
 br label %for.cond
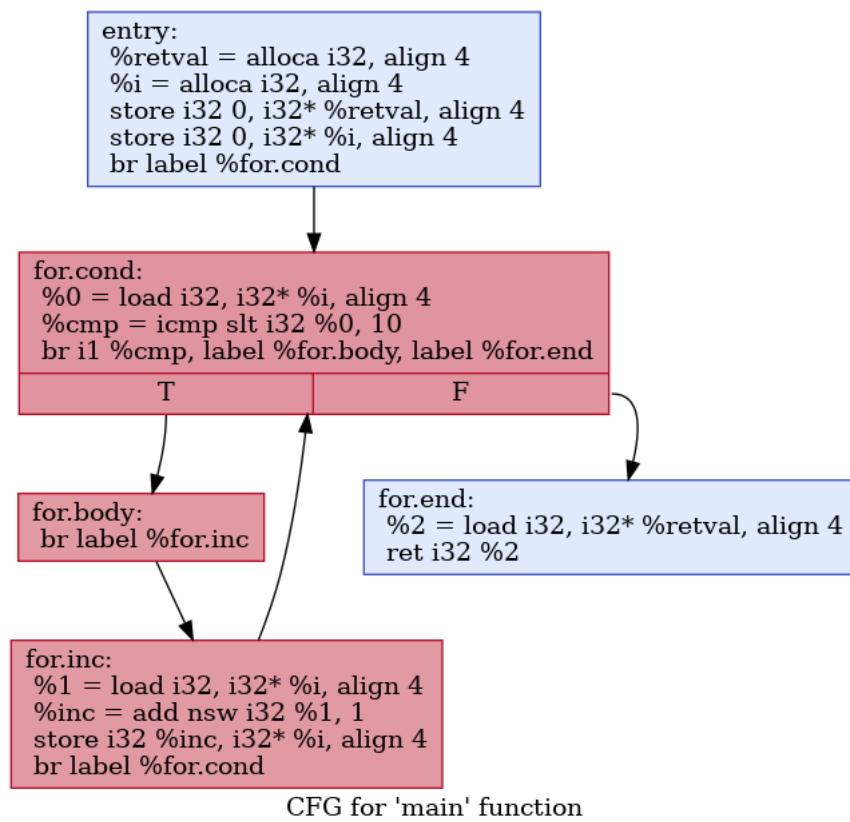
CFG for 'main' function

FIGURE 3.1: CFG for Simple C Program

passes. LLVM pass can run per function, module or loop. LLVM function pass is executed once for every function in the program. LLVM module pass is executed once for every module. LLVM loop pass runs a time for each loop.
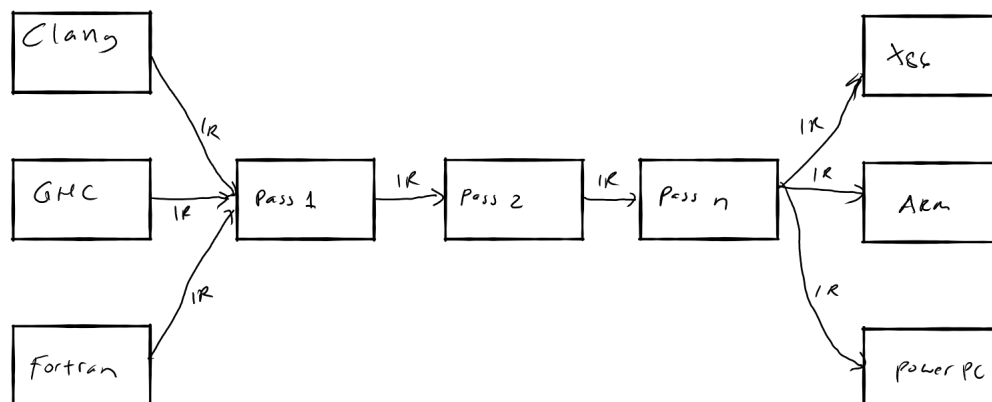

FIGURE 3.2: LLVM Pass (This is image will be replaced with the proper one)

In LLVM there are two ways of implementing Pass. First is using legacy approach and the latest one is using new pass manager approach. The approach different in structuring the code the implement the pass and also the way we use the pass. In the legacy approach, we need to inherit from either `ModulePass`, `FunctionPass` or `LoopPass` and override `runOnXXX` method (xxx is either Function, Module or Loop). In the newer approach we have to inherit CRTP mix-in `PassInfoMixin<PassT>` and override the run method.

The way we use the pass, in legacy approach we need to provide the pass name as literal argument to `opt`. See the example in listing 3. In the new pass manager, we are putting the pass name after '–passes' argument in comma separated list (listing 4). The pass is executed in order.

```
opt --dot-cfg file.ll
```

LISTING 3: Running Legacy LLVM Pass

```
opt –passes=scarr-cp-marker,scarr-loa-collector file.ll
```

LISTING 4: Running LLVM New Pass

3.3.3   LLVM API

In writing LLVM pass, we use LLVM API. In this section we present relevant component that is required in implementing LLVM Pass for the Offline Program Analyzer.

LLVM API is leveraging many C++ features and libraries such as template and STL. The API also provides many ready to use data structure which is not available in the STL. A more broad discussion on the important element of the API is available in the Programmers Manual [12]. Complete API documentation can be referred at the doxygen page [11].

Module

Module is the top level container for all other IR objects. Module contains list of global variables, functions, symbol tables and other various data about target characteristics. Module can be a single translation unit of a program (source file) or can be multiple translation unit combined by linker.

In LLVM pass, we can get access to module by implementing a Module pass or by parsing IR using parseIR or parseIRFile from IRReader.h. Once we get a handler to a module, getting a functions within module is as simple as passing module to a loop, since module provides iterator that return list of function in the module (see listing 5).

```cpp
#include <llvm/IR/LLVMContext.h>
#include <llvm/IR/Module.h>
#include <llvm/IRReader/IRReader.h>
#include <llvm/Support/SourceMgr.h>

int main()
{
    LLVMContext ctx;
    SMDiagnostic Err;
    auto module = parseIRFile("ir-file.ll", Err, ctx);
    for (auto &function : *module)
    {
        // do thing with function
    }
}
```

LISTING 5: LLVM Module API

Function

Function in LLVM represents function in the source program. A function contains list of zero or more BasicBlocks. There is one entry BasicBlock and can be multiple exit BasicBlocks. We can get handler to a function either by getting the iterator from a module instance or by implement a Function Pass. By using optimization, syntax hint or using an inliner pass, a function can be inlined. In this thesis, we are using *inliner-wrapper* pass to inline most function before feeding the IR into the ScaRR passes.

Basic Block

Basic Block represents single entry and single exit section of the code. The single exit can be one of terminator instruction — branches, return, unwind and invoke. We can get handle to a basic block from function. Refer to listing 6 to see how to get the basic block.

```
1        for (auto &function: *module) {
2            for (auto &basicBlok: function) {
3                // do thing with Basic Block
4            }
5        }
```

LISTING 6: LLVM Basic Block API

Graph Traversal

Since LLVM CFG is already structured as a graph, the basic block can be traversed using different ready to use graph traversal algorithm. LLVM offers some common graph traversal algorithms such as breadth first search and depth first search. The algorithms can be used immediately on basic blocks and functions. If there is a need to traverse a custom structure, the algorithms just require the new structure to implement *GraphWriter* interface.

3.3.4   Tools

We are implementing the algorithms using different tools. We are highlighting some of those in this section so that everyone interested can replicate the step.

clang

`clang` is one of the frontend provided by LLVM. It can compiles C, C++ and Objective C. `clang` command line arguments are compatible with widely use gcc compiler. The main use of `clang` in this research is to compile source files into LLVM IR text files. Listing 7 shows how to compile a C program into LLVM IR.

```
clang -S -emit-llvm source.c
```

LISTING 7: Compiling C to LLVM IR

We can pass optimization level from 0 (no-optimization) to 3 (most optimal, can make code run faster but larger in size) when compiling the source code.

By default, clang strips out value names and do some optimization when generating LLVM IR. We can use this flag to disable optimization and get readable value names that can help when troubleshooting and exploring the generated IR. Listing 8

shows how to compile to IR without any optimization and to preserve the function and variable names.

```
clang -S -emit-llvm -Xclang -disable-O0-optnone \
-fno-discard-value-names source.c
```

LISTING 8: Compiling C to LLVM IR without Optimization

opt

`opt` is LLVM optimizer and analyzer that can be invoked from command line. We are using `opt` to execute the offline program analyzer which marks basic block checkpoints and calculate list of action which can be used as information to detect control flow violation during remote attestation.

cmake

`cmake` is a build file generator which is have an important role in large project like LLVM. Although the deep understanding of `cmake` is not required in implementing LLVM pass, but we need to know at least how to build the pass after the implementation so that we can run it.

LLVM can be downloaded using git. See Listing 9. This thesis is implemented on LLVM 13.0.0.

```
git clone https://github.com/llvm/llvm-project
```

LISTING 9: Cloning LLVM Source Code

Once it is downloaded we can go to the LLVM directory and generate the build files. `cmake` supports several build tools such as make and ninja. Refer to listing 10.

```
1    cd llvm-project/llvm
2    mkdir build
3    cd build
4    cmake -G Ninja ../ # generate build file for Ninja
5    ninja opt # build only opt
```

LISTING 10: Building LLVM

With all background discussion in this chapter we should be ready to discuss the methodology in Chapter 4.

Chapter 4

Methodology

In this chapter we present the methodology of the research. First we present the threat model. After that, we show the overview of the implementation of the ScaRR algorithm to extract checkpoint and list of action. The section about ScaRR control-flow model will follow. The last two section is the detail on LLVM implementation to get checkpoints and list of actions from codes. Checkpoints and list of actions are collected to build offline measurement database that is used for the remote attestation.

4.1 Threat Model

The threat model in this research from ScaRR threat model [18]. There are two parties: attacker and prover. The attacker has aim to hijact the application control flow by using various memory attacks described in Chapter 3. However, we do not consider physical attack and data-oriented attack which does not alter program CFG. The prover uses kernel as trusted anchor and has common memory corruption attack mitigations such as $W \bigoplus R$ and ASLR.

4.2 Overview of The Offline Measurement

The goal of the offline measurement is to get the information to be used in the remote attestation. In this research we implement ScaRR Control-flow model [18] which we also elaborate in the Section 4.3. These are the steps that we do in getting the offline measurements:

1. Flattenning the CFG

2. Marking the Checkpoints

3. Finding the List of Actions

4.2.1 Flattenning the CFG

Consider the program in listing 11. The CFG is shown in the figure 4.1. The first step of the offline measurement is to flatten the CFG to get all the basic block list. We can flatten the CFG into basic block with one out of some graph traversal algorithm in LLVM. The CFG in figure 4.1 contains these following basic blocks:
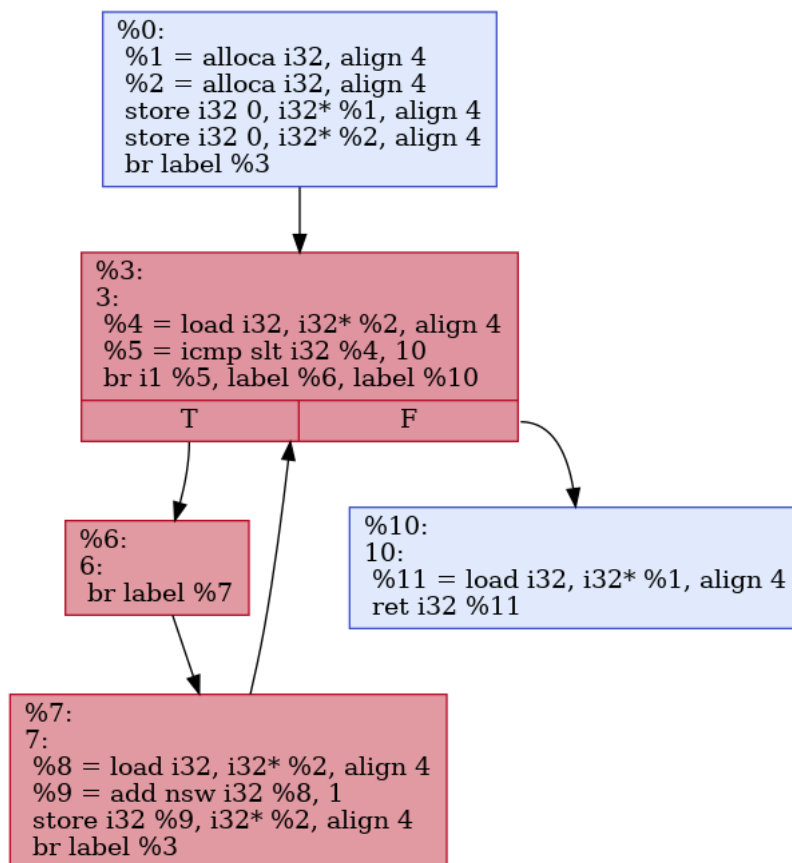
```
int main() {
    for (int i = 0; i < 10; i++) {
        // do nothing
    }
}
```

LISTING 11: Simple Loop

- Basic Block %0

- Basic Block %3

- Basic Block %6

- Basic Block %7

- Basic Block %10

CFG for 'main' function

FIGURE 4.1: Simple Loop CFG

4.2.2 Marking the Checkpoints

After we flatten CFG into basic block, we will check each of basic block to find different kind of checkpoints. The marked checkpoints from the CFG in Figure 4.1 can be seen in Figure 4.2.
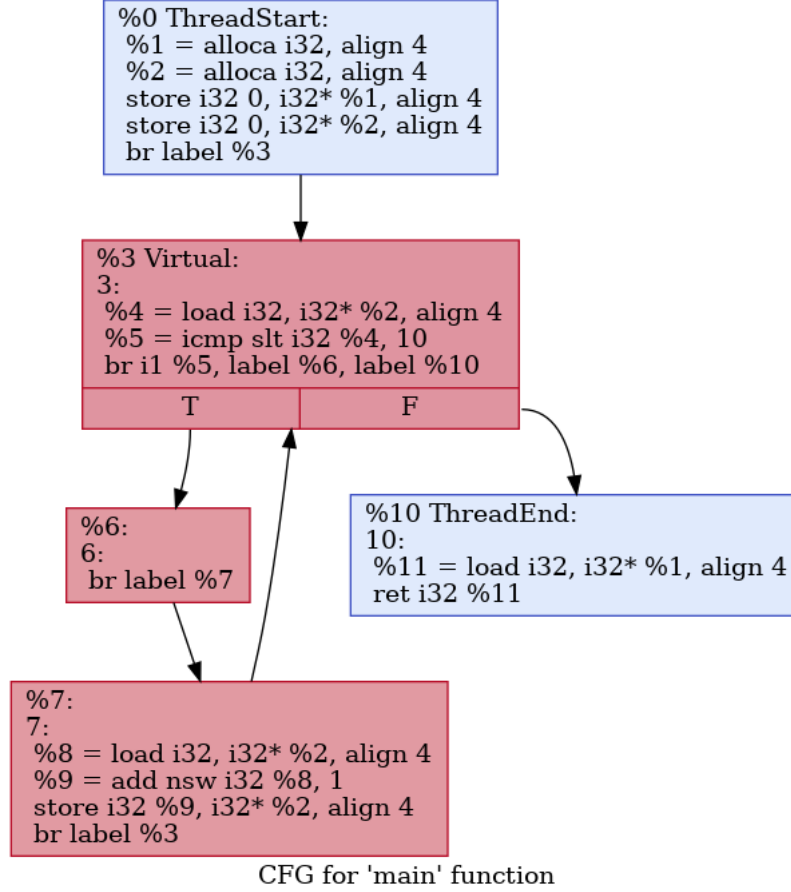

CFG for 'main' function

FIGURE 4.2: Loop CFG

4.2.3 Finding the List of Actions

The step of finding LoA is traversing path between two checkpoints and add significant basic block that traverse the path between the two checkpoints. The detail of this step is explained in the next sections.

4.3 ScaRR Control-Flow Model

ScaRR [18] are taking lesson learned from many former runtime remote attestation scheme to build model that can perform in a scalable way and can perform remote attestation on complex system. ScaRR control-flow model consists of two main components, checkpoint and list of action.

As many previous runtime attestation scheme, ScaRR models and validates the attestation based on program's control flow graph. We need to run one-time measurement computation to extract checkpoints and list of actions of the program.

4.3.1 Checkpoints

Checkpoint is basic block of the program that delimit execution path of the program. ScaRR defines these different checkpoint types:

- Thread Beginning: demarcating the start of program/thread

- Thread End: demarcating the end of program/thread

- Exit Point: representing exit point from application such as system call or out of translation unit function/library call

- Virtual-Checkpoint: managing cases for loop or recursion

In a program there should be at least Thread Beginning and Thread End checkpoints. Later depends on the structure of the program different checkpoint is marked in the program CFG.

4.3.2 List of Actions

List of actions (LoA) are edges (marked by two checkpoints) that direct one checkpoint to the next one. In program execution path, we only consider edges that identify the unique execution path.

LoA is defined through the following notation:

$$[(BBL_{s1}, BBL_{d1}), ..., (BBL_{sn}, BBL_{dn})]$$

Consider again the CFG in the Figure 4.2. The LoA between node 3 (Checkpoint Virtual) and node 10 (checkpoint ThreadEnd) is $[(BBL_3, BBL_{10})]$. However, the LoA between node 0 and node 3 is $[]$ (empty set).

4.4 ScaRR LLVM Pass

ScaRR offline measurement is represented as the following key-value pair.

$$(cp_A, cp_B, H(LoA)) \Rightarrow [(BBL_{s1}, BBL_{d1}), ..., (BBL_{sn}, BBL_{dn})]$$

As described in the section 4.3.1, checkpoint is a special basic block that delimit path between execution path in a CFG. cp_A is the start delimiter of the path. cp_B is the end of delimiter. LoA — list of action — is list of significant basic block pairs which define edges

ScaRR extractor traverses the graph in two passes. The first pass is find whether the basic block is a checkpoint (section 4.5). The second pass traverses the graph and mark List of Action between every two checkpoint (section 4.6).

4.5 ScaRR Checkpoint Marker

The logic of checkpoint marker is to traverse the whole control flow graph at least once. For each basic block, we have to check whether the basic block can be considered as any of checkpoint type mentioned above. To allow marking additional information about ScaRR checkpoint, we are modifying the BasicBlock class to add checkpoint instance variable as shown in listing 12.

```cpp
class BasicBlock ... {
private:
// add checkpoint field
    Checkpoint cp;

public:
    // setter and accessor
void setCheckpoint(Checkpoint);
Checkpoint getCheckpoint() const;
...
}
```

LISTING 12: Add Checkpoint Instance Variable to BasicBlock class.

The algorithm to mark the checkpoint is first we iterate all basic block in main function. First we mark the first basic block with no predecessor as ThreadStart checkpoint and basic block with no successor and ThreadEnd checkpoint.

To identify ExitPoint checkpoint, for each basic block then we iterate each instruction to find whether any instruction in the basic block is a 'call' instruction and has no body defined in this translation unit. Please refer to Listing 13.

```cpp
for (auto &basicBlock: Function) {
    for (auto &instruction : basicBlock) {
        if (isa<CallInst>(i)) {
        auto *call = &cast<CallBase>(i);
        if (call != nullptr && call->getCalledFunction()->empty()) {
            // this basicBlock is ExitPoint
            basicBlock.setCheckpoint(Checkpoint::ExitPoint);
        }
    }
}
```

LISTING 13: Finding ExitPoint Checkpoint

To mark Virtual checkpoint, we need to find loop header basic block. Although there is no direct API to check whether a basic block is a loop header, LLVM provide it in LoopInfoBase API. See Listing 14

```
1          void findVirtualCheckpoint(DominatorTree &DT, Function &F) {
2              DT.recalculate(F);
3              // generate the LoopInfoBase for the current function
4              LoopInfoBase<BasicBlock, Loop>* KLoop = new LoopInfoBase<BasicBlock, Loop>();
5              KLoop->releaseMemory();
6              KLoop->analyze(DT);
7              for (auto &bb : F) {
8                  // Since the BasicBlock would have been inlined, just traverse from main functio
9                  if (F.getName() == "main") {
10                 auto loop = KLoop->getLoopFor(&bb);
11                 if (loop != nullptr) {
12                     // found VirtualCheckpoint
13                             loop->getHeader()->setCheckpoint(Checkpoint::Virtual);
14                 }
15                 }
16             }
17         }
```

LISTING 14: Getting Virtual Checkpoint

4.6 ScaRR LoA Collector

The algorithm of getting LoA between two checkpoints is little bit more complex. First, we iterate all the basic block and if the basic block is a checkpoint we mark this is cpA. Next, we recursively traverse the successor of cpA until we find another checkpoint cpB. It is possible for $cpA = cpB$. If there is no branch between the two checkpoint, the LoA is an empty set. If there is a branch, the first LoA is always be cpA and the second LoA is always be the first basic block after the branch — which can be cpB or just non checkpoint basic block. Interested readers can refer to the implementation of this pass to see the detail.

4.6.1 Running The Pass

To mark the list of Checkpoints, we can invoke LLVM `opt` as shown in listing 15.

```
opt -passes=scarr-cp-marker <file>.ll
```

LISTING 15: Mark Checkpoint in BasicBlock

We can see the basic blocks output that has been marked with checkpoint using LLVM dot-cfg pass.

The commands in listing 16 generates different dot files per function. We can use xdot command line from graphiz to see the graph.

To mark the list of actions between checkpoints, we can invoke LLVM `opt` as shown in Listing 17

```
opt -passes=scarr-cp-marker,dot-cfg <file>.ll
```

LISTING 16: Print Checkpoints in CFG dot file

```
opt -passes=scarr-cp-marker,scarr-loa-collector <file>.ll
```

LISTING 17: Get List of Actions

Note that we have to run scarr-cp-marker before scarr-loa-collector.
The result and its interpretation are discussed in the next chapter.

Chapter 5

Results

In this research we used the offline measurement generator in getting the measurement across different programs. We calculated the ScaRR control flow information from each of the program.

5.1 ScaRR Control Flow Result

5.2 Complexity Analysis

5.3 Case Study

Chapter 6

Discussion and Future Works

TBD

Chapter 7

Conclusion

In this thesis we implemented ScaRR control flow model extractor that can be used to build offline measurement database. We We presented the design and the implementation of the tool as two different LLVM passes.

Appendix A

Appendix Title Here

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