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1  /*-----
2  Name Lamin Jammeh
3  Class: EE417 Summer 2024
4  Lesson 07 HW Question 2
5  Group: Ron Kalin/ Lamin Jammeh
6  Project Description: Controller module sends control command to the Datapath to shift
7  the value 1 left or right in an input data
8  -----*/
9
10 /*-----up/down counter controller-----*/
11 module Controller (
12     input clk,
13     input reset,
14     input done,
15     output reg shift_left,
16     output reg shift_right,
17     output reg load
18 );
19
20 reg [1:0] state, next_state;
21
22 parameter IDLE = 2'b00;
23 parameter LOAD = 2'b01;
24 parameter SHIFT = 2'b10;
25 parameter DONE = 2'b11;
26
27 // State transition logic
28 always @ (posedge clk or posedge reset) begin
29     if (reset)
30         state <= IDLE;
31     else
32         state <= next_state;
33 end
34
35 // Next state logic
36 always @ (*) begin
37     case (state)
38         IDLE: next_state = LOAD;
39         LOAD: next_state = SHIFT;
40         SHIFT: next_state = done ? DONE : SHIFT; //keep shifting if Done is false
41         DONE: next_state = IDLE;
42         default: next_state = IDLE;
43     endcase
44 end
45
46 // Output logic
47 always @ (*) begin
48     shift_left = 0; // Default direction
49     shift_right = 0;
50     load = 0;
51     case (state)
52         IDLE: begin
53             load = 1;
54         end
55         LOAD: begin
56             shift_left = 1;
57         end
58         SHIFT: begin
59             if (shift_left)
60                 begin
61                     shift_left = 1;
62                     shift_right = 0;
63                 end
64             else begin
65                 shift_left = 0;
66                 shift_right = 1;
67             end
68         end
69         DONE: begin

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70 // No control signals
71 end
72 endcase
73 end
74
75 endmodule
```