

**Pr.10.2** This simple problem illustrates that a line integral in general depends not only on the endpoints, but also on the shape of the path. The commands are as in Pr.10.1.

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```

> FC3 := subs(x = r3[1], y = r3[2], z = r3[3], F3);
FC3 := F3

> F3 := [2·z, 7·x, -3·y];
F3 := [2·z, 7·x, -3·y]

> r3 := [cos(t), sin(t), 2·t];
r3 := [cos(t), sin(t), 2·t]

> FC3 := subs(x = r3[1], y = r3[2], z = r3[3], F3);
FC3 := [4·t, 7·cos(t), -3·sin(t)]

> rprime3 := VectorCalculus[diff](r3, t);
rprime3 := [-sin(t), cos(t), 2]

> with(LinearAlgebra):
> integrand3 := DotProduct(FC3, rprime3);
integrand3 := -4 sin(t) t + 7 cos(t) cos(t) - 6 sin(t)

>
> int(integrand3, t = 0 .. 2·π)
15 π

```

**Pr.10.4** The vanishing of the curl of  $\mathbf{F} = [ze^x, 2y, e^x]$  shows path independence. Find a potential by integration. Maple will not give “constants” of integration (functions in the present case), but this is not essential; simply integrate the three functions in the form (the components of  $\mathbf{F}$ ) with respect to  $x, y, z$ , respectively, and find out whether you can find a common expression  $f$  for all three results such that  $\mathbf{F} = \text{grad } f$ . Then calculate  $f(a, b, c) - f(0, 0, 0)$ .

```

> with(LinearAlgebra):
> VectorCalculus[SetCoordinates]('cartesian' [x, y, z]):
> F := VectorCalculus[VectorField](<z*exp(x) 2*y exp(x)>);
F := (ze^x) e_x + 2y e_y + (e^x) e_z

> VectorCalculus[Curl](F);
# Resp. 0 e_z

> int(F[1], x);
# Resp. ze^x

> int(F[2], y);
# Resp. y^2

> int(F[3], z);
# Resp. ze^x

Noting that the last expression is the same as the first,  $\mathbf{F} = \text{grad } f$  can be obtained from

> f := int(F[1], x) + int(F[2], y);
# Resp. f := ze^x + y^2

> answer := subs(x = a, y = b, z = c, f) - subs(x = 0, y = 0, z = 0, f);
answer := ce^a + b^2

```

**Pr.10.10** Type the given representation of  $S$  and keep in mind that  $\mathbf{r} = [x, y, z]$ .

```
> r := <a*cos(v)*cos(u)  b*cos(v)*sin(u)  c*sin(v)>;
      r := [ a*cos(v)*cos(u)  b*cos(v)*sin(u)  c*sin(v) ]
```

Observe that you can combine the first two components by using  $\cos^2 u + \sin^2 u = 1$ , namely,

```
> E1 := r[1]^2/a^2 + r[2]^2/b^2;
      E1 := cos(v)^2*cos(u)^2 + cos(v)^2*sin(u)^2
> E2 := simplify(E1);
      # Resp. E2 := cos(v)^2
```

From this you see that by adding the square of the third component divided by  $c^2$  you obtain

```
> E := E1 + r[3]^2/c^2;
      E := cos(v)^2*cos(u)^2 + cos(v)^2*sin(u)^2 + sin(v)^2
> simplify(E);
      # Resp. 1
```

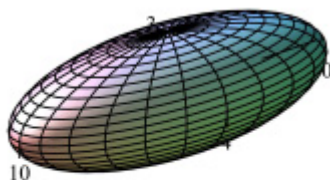
Because  $\mathbf{r}[1]$ ,  $\mathbf{r}[2]$ ,  $\mathbf{r}[3]$  equal  $x, y, z$ , respectively, your result is  $x^2/a^2 + y^2/b^2 + z^2/c^2 = 1$ . This procedure is typical; the transition from one type of representation to another usually requires some trials.

A normal vector  $\mathbf{N}$  is obtained from the given representation by differentiating and taking the cross product,

```
> ru := VectorCalculus[diff](r, u);
      ru := -a*cos(v)*sin(u)*e_x + (b*cos(v)*cos(u))*e_y
> rv := VectorCalculus[diff](r, v);
      rv := -a*sin(v)*cos(u)*e_x - b*sin(v)*sin(u)*e_y + (c*cos(v))*e_z
> with(LinearAlgebra):
> N := CrossProduct(ru, rv);
      N := [ b*cos(v)^2*cos(u)*c  a*cos(v)^2*sin(u)*c  a*cos(v)*sin(u)^2*b*sin(v)
             + b*cos(v)*cos(u)^2*a*sin(v) ]
> N := simplify(%);
      N := [ b*cos(v)^2*cos(u)*c  a*cos(v)^2*sin(u)*c  a*cos(v)*b*sin(v) ]
```

For plotting, type the following. You can turn the ellipsoid by clicking anywhere on the figure and then dragging.

```
> R := subs(a = 10, b = 4, c = 3, r);
      R := [ 10*cos(v)*cos(u)  4*cos(v)*sin(u)  3*sin(v) ]
> plot3d(R, u = 0..2*Pi, v = -Pi/2..Pi/2, axes = NORMAL,
          orientation = [45, 70], scaling = constrained);
```



**Example 10.10.** Ellipsoid

**Pr.10.16** The plane  $x + y + z = 1$  gives the upper portion of the surface, and  $x + y = 1$  its intersection with the  $xy$ -plane  $z = 0$ . Hence  $z = 1 - x - y$  and  $y = 1 - x$ , respectively. These are the upper limits of integration over  $z$  and  $y$ , respectively. Finally, integrate over  $x$  from 0 to 1.

```
[ > with(LinearAlgebra): VectorCalculus[SetCoordinates]('cartesian'[x,y,z]):
[ > F := <3*x  z^3*y^5  y^3*x^4>;          # Resp. F := [ 3x  z^3y^5  y^3x^4 ]
[ > Div := VectorCalculus[Divergence](VectorCalculus[VectorField](F));
[                               Div := 3 + 5z^3y^4
[ > int(int(int(Div, z = 0..1 - x - y), y = 0..1 - x), x = 0..1);
[                               2521
[                               5040
```