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# DEEP LEARNING ON ABSTRACT SIMPLICIAL COMPLEXES

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# Introduction

Most of the deep learning techniques used today are based on models which learn a partition of the set of smooth functions defined on euclidean domains into human friendly equivalence classes...

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# Chapter 1

## Preliminaries on topology

Given a point cloud in some  $\mathbb{R}^n$  sampled from some meaningful subspace and the order of magnitude of the noise acting on the sample one can construct a suitable set in  $\mathbb{R}^n$ , i.e. a *geometric simplicial complex*, homotopy equivalent to the sampled set, therefore recovering some topological information about the set that was lost in the sampling. Although this approach provides simplicial complexes with the topology inherited from the metric space it hides the power of simplicial complexes to describe those networks and interactions which would happily live beside that topology, to make this distinction clear enough we will treat geometric simplicial complexes as a realization of more abstract objects called *abstract simplicial complexes*.

Geometric simplicial complexes are algebraic objects that can in general be constructed from a point cloud in some  $\mathbb{R}^n$  in a way that preserves the topological information (e.g. the homotopy) of the ideal space sampled by the cloud. Although this approach provides simplicial complexes with the topology inherited from the metric space it hides the power of simplicial complexes to describe those networks and interactions which would happily live beside that topology, to make this distinction clear enough we will treat geometric simplicial complexes as a realization of more abstract objects called abstract simplicial complexes.

### Simplicial complexes

In this section we shall define simplicial complexes, which, as abstract as they might look, can be used to model interactions among individuals, traffic and road networks, as well as shapes, and to approximate functions on some compact manifold.

**Definition 1.1.** Let  $\mathcal{V}$  be a finite set we define an *abstract simplicial complex*  $\mathcal{A}$  to be

$$\mathcal{A} := \{\sigma \subset \mathcal{V} : \tau \subset \sigma \Rightarrow \tau \in \mathcal{A}\}$$

where  $\sigma$  are called *abstract simplexes* of  $\mathcal{A}$ .

One calls  $\mathcal{V}$  the *vertex set* of  $\mathcal{A}$  and denotes it by  $Vert(\mathcal{A})$ ; since the vertex set is finite we expect every abstract simplex to be also finite, therefore we might use the notation  $\sigma = \{v_i\}_{i \in I_\sigma}$ , which so far we consider invariant under arbitrary permutations on the finite index set  $I_\sigma$ .

**Definition 1.2.** Let  $\mathcal{A}$  be an abstract simplicial complex we define its *dimension* to be

$$\dim \mathcal{A} := \max_{\sigma \in \mathcal{A}} (|\sigma| - 1),$$

where by  $|\sigma|$  we denote the cardinality of  $\sigma$ .

One calls an abstract simplex of dimension  $p$  an *abstract  $p$ -simplex*, according to our definition the empty set is a  $(-1)$ -simplex. A *graph* is a one dimensional abstract simplicial complex.

**Definition 1.3.** Let  $\mathcal{A}, \mathcal{B}$  be abstract simplicial complexes, then a *simplicial map*  $\phi : \mathcal{A} \rightarrow \mathcal{B}$  is a function such that whenever  $\sigma = \{v_i\}_{i \in I_\sigma} \in \mathcal{A}$ , then  $\phi(\{v_i\}_{i \in I_\sigma}) = \{\phi(v_i)\}_{i \in I_\sigma} \in \mathcal{B}$ , where  $\phi(v_i) \in \text{Vert}(\mathcal{B}) \forall i \in I_\sigma$ .

Although the vertex to vertex mapping is a quite selective condition on the function we did not prevent it from cramming abstract simplexes into lower dimensional ones.

**Theorem 1.4.** All abstract simplicial complexes and simplicial maps are a category  $\mathfrak{A}$  whose identities are called isomorphisms.

Although abstract simplicial complex can be used to model any kind of vertex interaction they lack of a topology, we wish therefore to define some structures in a euclidean space that can be related unequivocally (i.e. via a functor) to abstract simplicial complexes. We shall call those geometric simplicial complexes to avoid misunderstandings.

**Definition 1.5.** Let  $I$  be a finite set of indexes, we define the *convex envelope* of the points  $\{x_i\}_{i \in I} \subset \mathbb{R}^n$  to be

$$\langle x_i \rangle_{i \in I} := \{a = \sum_{i \in I} \lambda_i x_i : \lambda_i \in \mathbb{R}, \lambda_i > 0, \sum_{i \in I} \lambda_i = 1\},$$

which is the smallest convex set containing  $\{x_i\}_{i \in I}$ .

**Definition 1.6.** Let  $\{x_i\}_{i \in I} \subset \mathbb{R}^n$  we define the points  $\{x_i\}_{i \in I}$  to be *affinely independent* if and only if

$$\sum_{i \in I} \lambda_i x_i = \sum_{i \in I} \mu_i x_i \Rightarrow \lambda_i = \mu_i \forall i \in I,$$

where  $\sum_{i \in I} \lambda_i = \sum_{i \in I} \mu_i = 1$ .

**Definition 1.7.** We define a *geometric p-simplex* to be a convex envelop  $\langle x_i \rangle_{i \in I}$  where  $\{x_i\}_{i \in I} \subset \mathbb{R}^n$  are affinely independent and  $|I| = p + 1$ .

**Definition 1.8.** Let  $\sigma$  be a geometric p-simplex, we say that another t-simplex  $\tau$  is a *face* of  $\sigma$  or equivalently that  $\sigma$  is a *coface* of  $\tau$ , by our notation  $\tau \leq \sigma$ , if and only if  $\tau \subset \sigma$ , where  $t \leq p$ .

**Definition 1.9.** We define a *geometric simplicial complex*  $\mathcal{G}$  to be a collection of geometric simplexes such that

- (i)  $\tau \leq \sigma \in \mathcal{G} \Rightarrow \tau \in \mathcal{G}$ ,
- (ii)  $\sigma, \tau \in \mathcal{G} \Rightarrow \sigma \cap \tau \in \mathcal{G}$ .

**Definition 1.10.** *Geometric realization of an abstract simplicial complex*

Let  $\mathcal{K}$  be a geometric simplicial complex, and let  $\text{Vert}(\mathcal{K}) := \{\sigma \in \mathcal{K} : \dim(\sigma) = 0\}$ , we call the abstract simplicial complex  $\mathcal{A} := \{\{x_i\}_{i \in I} \subset \text{Vert}(\mathcal{K}) : \langle x_i \rangle_{i \in I} \in \mathcal{K}\}$  a vertex scheme for  $\mathcal{K}$  or equivalently we might say that  $\mathcal{K}$  is a geometric realization of  $\mathcal{A}$ .

**Theorem 1.11.** Let  $\mathcal{A}$  be a d-dimentional abstract simplicial complex, it admits a geometric realization in  $\mathbb{R}^{2d+1}$ .

Kuratowski theorem proves the prevuois statement to be also sharp.

# Forms and integration on abstract simplicial complexes

## Definition 1.12. Linear space of simplicial p-chains

Let  $\mathcal{A}$  be an abstract simplicial complex, and let  $\mathcal{A}_p := \{\sigma \in \mathcal{A} : \dim(\sigma) = p\}$ , we define the linear space  $C_p = C_p(\mathcal{A})$  of simplicial p-chain on  $\mathcal{A}$  to be

$$C_p = \left\{ \sum_{\sigma \in \mathcal{A}_p} \lambda^\sigma \sigma, \quad \lambda^\sigma \in \mathbb{Z}_2 \right\},$$

where the formal operations of the linear space are given by the definition itself.  
(Possible extension from  $\mathbb{Z}_2$  to  $\mathbb{R}$ , naming  $C_p$  by the dual notation  $\Lambda_p$ )

The set  $\mathcal{A}^p$  is a canonical base of p-simplexes for  $C_p$ .

## Definition 1.13. Boundary operator on $C_{p+1}$

Let  $\sigma$  be an element of the canonical base of  $C_{p+1}$  we define  $\partial : C_{p+1} \rightarrow C_p$  such that

$$\partial \sigma = \sum_{i=0}^{p+1} (-1)^i \sigma_i,$$

where if  $\sigma = \{x_0, \dots, x_{p+1}\} \in C_{p+1}$  we define  $\sigma_i := \{x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_{p+1}\} \in C_p$ .  
Furthermore we extend this operator linearly on the whole space  $C_{p+1}$

$$\partial \left( \sum_{\sigma \in \mathcal{A}_p} \lambda^\sigma \sigma \right) = \sum_{\sigma \in \mathcal{A}_p} \lambda^\sigma \partial \sigma.$$

**Lemma 1.14.** *Let  $\sigma \in \mathcal{A}_{p+2}$ ,  $p \geq 0$  then  $\partial^2 \sigma = 0$ .*

*Proof.* We have

$$\begin{aligned} (\partial^2 \sigma)_x &= \sum_{i=0}^{p+2} (-1)^i (\partial \sigma)_i \\ &= \sum_{i=0}^{p+2} (-1)^i \left[ \sum_{j=0}^{i-1} (-1)^j \sigma_{ij} + \sum_{j=i+1}^{p+2} (-1)^{j-1} \sigma_{ij} \right] \\ &= \sum_{i=0}^{p+2} \sum_{j=0}^{i-1} (-1)^{i+j} \sigma_{ij} - \sum_{i=0}^{p+2} \sum_{j=i+1}^{p+2} (-1)^{i+j} \sigma_{ij} = 0. \end{aligned}$$

□

## Definition 1.15. p-forms on abstract simplicial complexes

Let  $\mathcal{A}$  be an abstract simplicial complex we define the linear space of p-forms  $\Lambda^p = \Lambda^p(\mathcal{A})$  to be

$$\Lambda^p := \{\omega : C_p \rightarrow \mathbb{R}\}, \text{ such that}$$

$$\omega \left( \sum_{\sigma \in \mathcal{A}_p} \lambda^\sigma \sigma \right) = \sum_{\sigma \in \mathcal{A}_p} \lambda^\sigma \omega(\sigma) \quad \forall \omega \in \Lambda^p, \lambda_\sigma \in \mathbb{Z}_2,$$

with linear space operations defined as

$$\begin{aligned} + : \Lambda^p \times \Lambda^p &\rightarrow \Lambda^p & (\omega + \eta)(\sigma) &= \omega(\sigma) + \eta(\sigma) \quad \sigma \in C_p, \omega, \eta \in \Lambda^p, \\ \cdot : \mathbb{R} \times \Lambda^p &\rightarrow \Lambda^p & (\lambda \omega)(\sigma) &= \lambda \omega(\sigma) \quad \sigma \in C_p, \omega \in \Lambda^p, \lambda \in \mathbb{R}. \end{aligned}$$

**Proposition 1.16.** *A canonical base of elementary forms for  $\Lambda^p$  is*

$$\{\sigma^* \in \Lambda^p : \sigma \in \mathcal{A}_p, \sigma^*(\tau) = \delta_{\sigma\tau} \quad \tau \in \mathcal{A}_p\},$$

*therefore giving us an expression for every other  $p$ -form*

$$\omega = \sum_{\sigma \in \mathcal{A}_p} \omega_\sigma \sigma^*, \quad \omega_\sigma \in \mathbb{R}.$$

**Definition 1.17. Exterior derivative of a  $p$ -form**

Let  $\omega \in \Lambda^p$  we define  $d : \Lambda^p \rightarrow \Lambda^{p+1}$  on its coordinates to be

$$(d\omega)_\sigma = \sum_{i=0}^{p+2} (-1)^i \omega_{\sigma_i}.$$

**Lemma 1.18.** *Let  $\omega \in \Lambda^p$ ,  $p \geq 0$  then  $d^2\omega = 0$ .*

*Proof.* We have for  $\sigma \in \mathcal{A}_{p+2}$

$$\begin{aligned} (d^2\omega)_\sigma &= \sum_{i=0}^{p+2} (-1)^i (d\omega)_{\sigma_i} \\ &= \sum_{i=0}^{p+2} (-1)^i \left[ \sum_{j=0}^{i-1} (-1)^j \omega_{\sigma_{ij}} + \sum_{j=i+1}^{p+2} (-1)^{j-1} \omega_{\sigma_{ij}} \right] \\ &= \sum_{i=0}^{p+2} \sum_{j=0}^{i-1} (-1)^{i+j} \omega_{\sigma_{ij}} - \sum_{i=0}^{p+2} \sum_{j=i+1}^{p+2} (-1)^{i+j} \omega_{\sigma_{ij}} = 0. \end{aligned}$$

□

**Definition 1.19. Integration of  $p$ -forms on  $p$ -chains**

Let  $\omega \in \Lambda^p$  and  $\tau \in C_p$  we define the integral of  $\omega$  on  $\tau$  to be a bilinear form  $\Lambda^p \times C_p \rightarrow \mathbb{R}$

$$(\omega, \tau)_p := \sum_{\sigma \in \mathcal{A}_p} \omega_\sigma \tau^\sigma,$$

where  $\omega = \sum_{\sigma \in \mathcal{A}_p} \omega_\sigma \sigma^*$  and  $\tau = \sum_{\sigma \in \mathcal{A}_p} \tau^\sigma \sigma$ .

(This might be extended by adding a non trivial permutation invariant measure on  $\mathcal{A}_p$ )

**Theorem 1.20.** *Let  $\omega = \sum_{\sigma \in \mathcal{A}_p} \omega_\sigma \sigma^*$  and  $\tau = \sum_{\sigma \in \mathcal{A}_{p+1}} \tau^\sigma \sigma$  the following identity holds*

$$(d\omega, \tau)_{p+1} = (\omega, \partial\tau)_p,$$

*i.e. the operators  $d : \Lambda^p \rightarrow \Lambda^{p+1}$  and  $\partial : C_{p+1} \rightarrow C_p$  are dual.*

*Proof.* We have

$$(d\omega, \tau)_{p+1} = \sum_{\sigma \in \mathcal{A}_{p+1}} \tau^\sigma (d\omega, \sigma)_{p+1} \quad , \quad (d\omega, \sigma)_{p+1} = (d\omega)_\sigma = \sum_{i=0}^{p+1} (-1)^i \omega_{\sigma_i},$$

while

$$(\omega, \partial\tau)_p = \sum_{\sigma \in \mathcal{A}_{p+1}} \tau^\sigma (\omega, \partial\sigma)_p \quad , \quad (\omega, \partial\sigma)_p = \left( \omega, \sum_{i=0}^{p+1} (-1)^i \sigma_i \right)_p = \sum_{i=0}^{p+1} (-1)^i \omega_{\sigma_i} \quad .$$

□

This theorem can be seen as the generalized Stokes' theorem on abstract simplicial complexes.

## The Laplace Operator