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GEOMETRIC DEEP LEARNING

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Abstract in italiano...

Abstract in english...

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1 Introduction

1.1 Simplicial complexes

Definition 1.1.1. Abstract simplicial complex (finite)

Let \mathcal{F} be a family of sets we then define an abstract simplicial complex \mathcal{A} to be

$$\mathcal{A} := \{\sigma = \{A_i\}_{i \in I_\sigma} \subset \mathcal{F} : \tau \subset \sigma \Rightarrow \tau \in \mathcal{A}\}$$

where I_σ is a finite set of indexes, we shall call σ abstract simplexes of \mathcal{A} .

Definition 1.1.2. Dimension of an abstract simplicial complex

Let \mathcal{A} be an abstract simplicial complex we define its dimension to be

$$\dim \mathcal{A} := \max_{\sigma \in \mathcal{A}} \dim(\sigma),$$

where $\dim(\sigma) := |\sigma| - 1$.

Definition 1.1.3. Abstract graph

An abstract graph \mathcal{G} is a 1-dimensional abstract simplicial complex whose vertexes and edges are respectively

$$\begin{aligned}\mathcal{V} &:= \{\sigma \in \mathcal{G} : \dim(\sigma) = 0\} \text{ and} \\ \mathcal{E} &:= \{\sigma \in \mathcal{G} : \dim(\sigma) = 1\}.\end{aligned}$$

In Definition 1.1.1. we tacitly assumed the definition of the abstract simplex σ invariant with respect to permutations of the indexes I_σ , this assumption establishes the difference between directed and undirected graphs.

Definition 1.1.4. Convex envelop of points in \mathbb{R}^n

Let I be a finite set of indexes, we define the convex envelope of $\{x_i\}_{i \in I} \subset \mathbb{R}^n$ to be

$$\langle x_i \rangle_{i \in I} := \{a = \sum_{i \in I} \lambda_i x_i : \lambda_i \in \mathbb{R}, \lambda_i > 0, \sum_{i \in I} \lambda_i = 1\},$$

which is the smallest convex set containing $\{x_i\}_{i \in I}$.

Definition 1.1.5. Affine independency of points in \mathbb{R}^n

Let $\{x_i\}_{i \in I} \subset \mathbb{R}^n$ we define $\{x_i\}_{i \in I}$ to be affinely independent if and only if

$$\sum_{i \in I} \lambda_i x_i = \sum_{i \in I} \mu_i x_i \quad \Rightarrow \quad \lambda_i = \mu_i \quad \forall i \in I,$$

where $\sum_{i \in I} \lambda_i = \sum_{i \in I} \mu_i = 1$.

Definition 1.1.6. Geometric k -simplexes

We define a geometric k -simplex to be a convex envelop $\langle x_i \rangle_{i \in I}$ where $\{x_i\}_{i \in I} \subset \mathbb{R}^n$ are affinely independent and $|I| = k + 1$.

Definition 1.1.7. Faces and cofaces of geometric k -simplexes

Let σ be a geometric k -simplex, we say that another t -simplex τ is a face of σ or equivalently that σ is a coface of τ , by our notation $\tau \leq \sigma$, if and only if $\tau \subset \sigma$, where $t \leq k$.

Definition 1.1.8. Geometric Simplicial Complex

We define a geometric simplicial complex \mathcal{K} to be a collection of geometric simplexes such that

- (i) $\tau \leq \sigma \in \mathcal{K} \Rightarrow \tau \in \mathcal{K}$,
- (ii) $\sigma, \tau \in \mathcal{K} \Rightarrow \sigma \cup \tau \in \mathcal{K}$.

Definition 1.1.9. Geometric realization of an abstract simplicial complex

Let \mathcal{K} be a geometric simplicial complex, and let $\text{Vert}(\mathcal{K}) := \{\sigma \in \mathcal{K} : \dim(\sigma) = 0\}$, we call the abstract simplicial complex $\mathcal{A} := \{\{x_i\}_{i \in I} \subset \text{Vert}(\mathcal{K}) : \langle x_i \rangle_{i \in I} \in \mathcal{K}\}$ a vertex scheme for \mathcal{K} or equivalently we might say that \mathcal{K} is a geometric realization of \mathcal{A} .

Theorem 1.1.1. Let \mathcal{A} be a d -dimensional abstract simplicial complex, it admits a geometric realization in \mathbb{R}^{2d+1} .

Kuratowski theorem proves the previous statement to be also sharp.

1.2 Forms on abstract simplicial complexes**Definition 1.2.1. p -forms on abstract simplicial complexes**

Let \mathcal{A} be an abstract simplicial complex we define the linear space of p -forms $\Lambda^p = \Lambda^p(\mathcal{A})$ to be

$$\begin{aligned}\Lambda^p &:= \{\omega : \text{Vert}(\mathcal{A})^{p+1} \rightarrow \mathbb{R}\}, \\ + : \Lambda^p \times \Lambda^p &\rightarrow \Lambda^p \\ (\omega + \eta)(x) &= \omega(x) + \eta(x) \quad x \in \text{Vert}(\mathcal{A})^{p+1}, \quad \omega, \eta \in \Lambda^p, \\ \cdot : \mathbb{R} \times \Lambda^p &\rightarrow \Lambda^p \\ (\lambda\omega)(x) &= \lambda\omega(x) \quad x \in \text{Vert}(\mathcal{A})^{p+1}, \quad \omega \in \Lambda^p, \quad \lambda \in \mathbb{R},\end{aligned}$$

where $\dim(\Lambda^p) = |\text{Vert}(\mathcal{A})|^{p+1}$.

Although this definition seems to stand apart from the concept of simplicial complex we might notice that if we take the subset $\{x \in \text{Vert}(\mathcal{A})^{p+1} : \{x\} \in \mathcal{A}\}$ as the domain of our forms we are defining p -forms on p -simplexes of \mathcal{A} . For a lighter notation we shall define $\mathcal{V} := \text{Vert}(\mathcal{A})$.

Proposition 1.2.1. A canonical base of elementary forms for Λ^p is

$$\{e^x \in \Lambda^p : x \in \mathcal{V}^{p+1}, \quad e^x(y) = \delta_{xy} \quad y \in \mathcal{V}^{p+1}\},$$

therefore giving us an expression for every other p -form

$$\omega = \sum_{x \in \mathcal{V}^{p+1}} \omega_x e^x, \quad \omega_x \in \mathbb{R}.$$

This basis, according to the restriction $\{x \in \text{Vert}(\mathcal{A})^{p+1} : \{x\} \in \mathcal{A}\}$, is the dual basis of the basis of the linear space of simplicial p -chains.

Definition 1.2.2. Exterior derivative of a p -form

Let $\omega \in \Lambda^p$ we define $d : \Lambda^p \rightarrow \Lambda^{p+1}$ such that

$$(d\omega)_x = \sum_{i=0}^{p+1} (-1)^i \omega_{\hat{x}_i},$$

where if $x = (x_0, \dots, x_{p+1}) \in \mathcal{V}^{p+1}$ we define $\hat{x}_i := (x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_{p+1}) \in \mathcal{V}^p$.

Lemma 1.2.1. Let $\omega \in \Lambda^p$, $p \geq 0$ then $d^2\omega = 0$.

$$(d^2\omega)_x = \sum_{i=0}^{p+2} (-1)^i (d\omega)_{\hat{x}_i}$$

Proof. We have for $x \in \Lambda^{p+2}$

$$= \sum_{i=0}^{p+2} (-1)^i \sum_{j=0}^{i-1} (-1)^j \omega_{\hat{x}_{ij}} + \sum_{j=i+1}^{p+2} (-1)^{j-1} \omega_{\hat{x}_{ij}}$$

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