

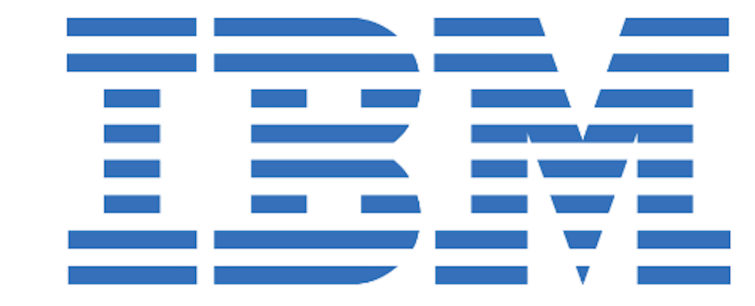
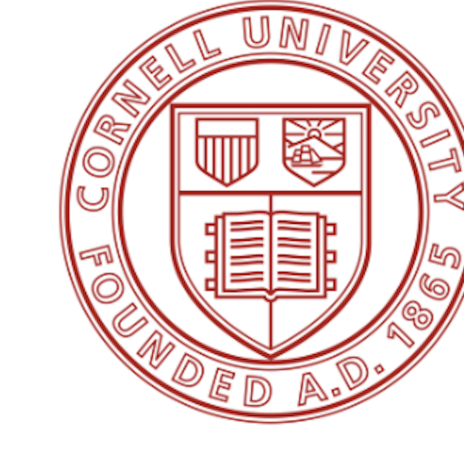
Nesterov Accelerated Shuffling Gradient Method for Convex Optimization

Trang H. Tran¹ · Katya Scheinberg¹ · Lam M. Nguyen²

¹ Cornell University, School of Operations Research and Information Engineering ² IBM Research, Thomas J. Watson Research Center

* Correspondence to Lam M. Nguyen, LamNguyen.MLTD@ibm.com.

ICML | 2022



Problem Statement

We consider the following **finite-sum minimization**:

$$\min_{w \in \mathbb{R}^d} \left\{ F(w) := \frac{1}{n} \sum_{i=1}^n f(w; i) \right\}, \quad (1)$$

where $f(\cdot; i) : \mathbb{R}^d \rightarrow \mathbb{R}$ is a **Lipschitz smooth function** for $i \in [n] := \{1, \dots, n\}$, and F is **convex**. Assume that we have access to the first order oracle of $f(\cdot; i)$. Below are some common sampling schemes:

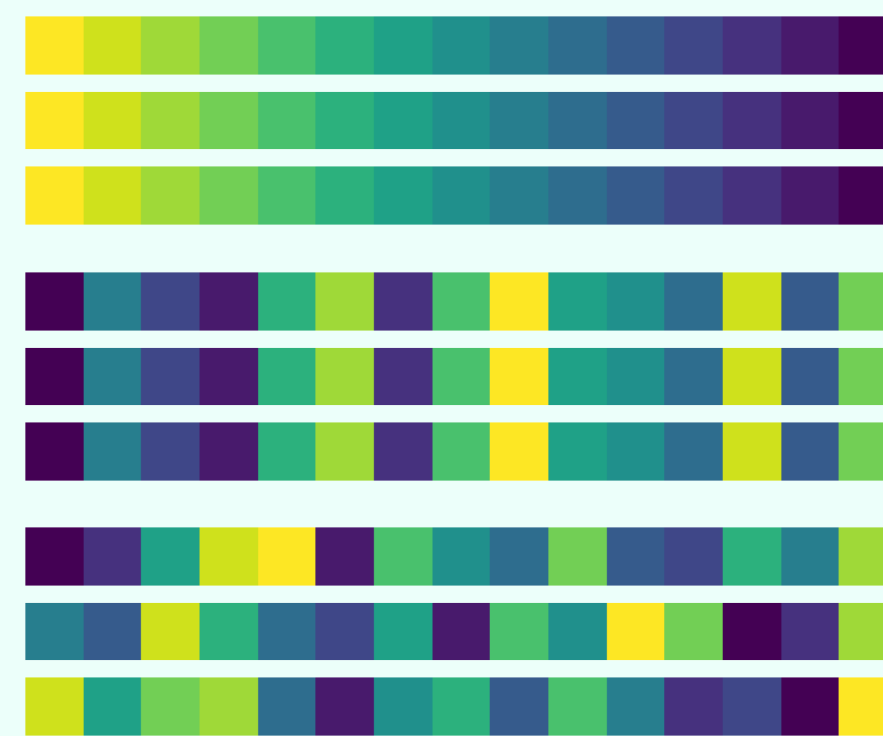
Regular (Standard) Scheme: Uniformly at random: at each iteration i_t of epoch t , sample an index uniformly at random from $[n]$.

Shuffling Schemes:

Incremental Gradient: use a fixed permutation $\{1, \dots, n\}$ for all epochs.

Shuffle Once: random shuffle one permutation and use it for all epochs.

Random Reshuffling: random shuffle a new permutation at every epoch.



Nesterov Accelerated Shuffling Gradient

Algorithm 1: Nesterov Accelerated Shuffling Gradient (NASG) Method

- 1: **Initialization:** Choose an initial point $\tilde{x}_0, \tilde{y}_0 \in \mathbb{R}^d$.
- 2: **for** $t = 1, 2, \dots, T$ **do**
- 3: Set $y_0^{(t)} := \tilde{y}_{t-1}$;
- 4: Generate any permutation $\pi^{(t)}$ of $[n]$ (either deterministic or random);
- 5: **for** $i = 1, \dots, n$ **do**
- 6: Update $y_i^{(t)} := y_{i-1}^{(t)} - \eta_i^{(t)} \nabla f(y_{i-1}^{(t)}; \pi^{(t)}(i))$;
- 7: **end for**
- 8: Set $\tilde{x}_t := y_n^{(t)}$;
- 9: Update $\tilde{y}_t := \tilde{x}_t + \gamma_t(\tilde{x}_t - \tilde{x}_{t-1})$;
- 10: **end for**

Comparison with deterministic NAG:

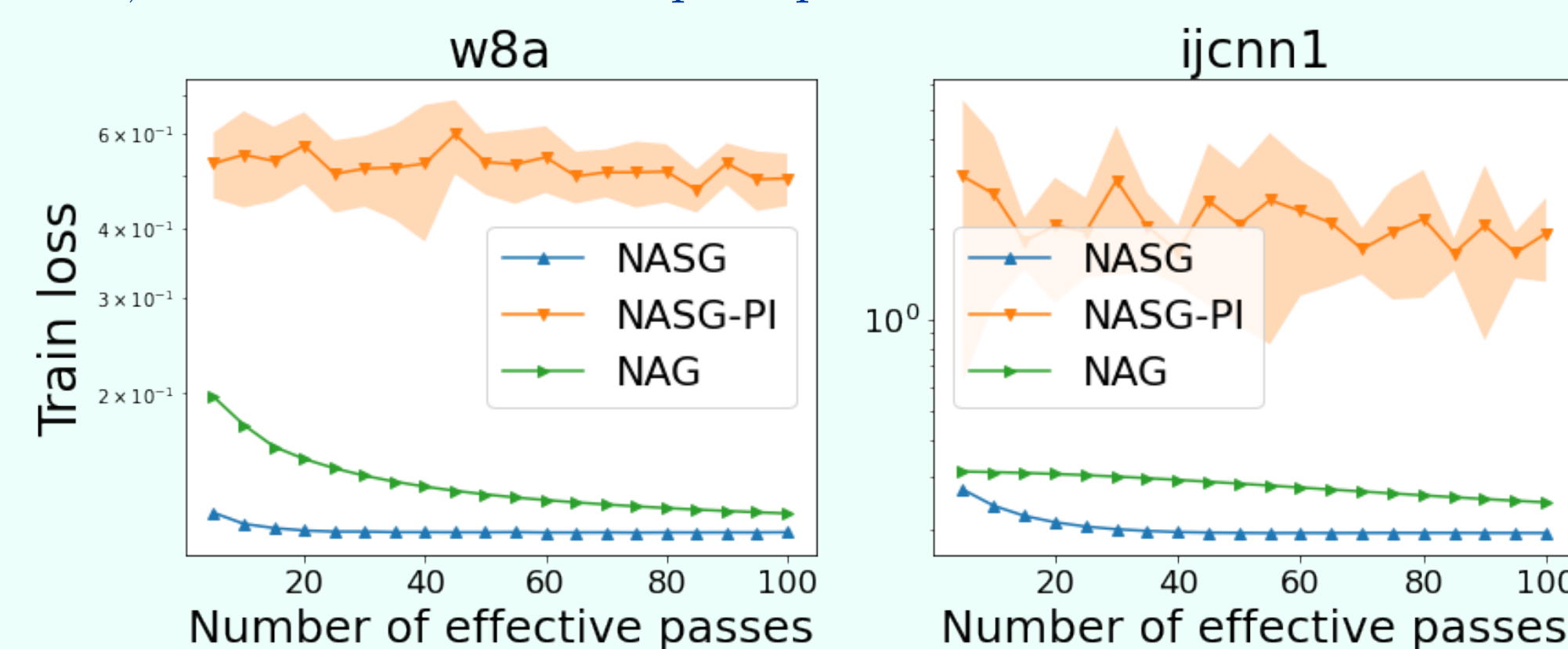
• Inner loop of deterministic NAG

- 1: **for** $i = 1, \dots, n$ **do**
- 2: Update $y_i^{(t)} := y_{i-1}^{(t)} - \eta_i^{(t)} \nabla f(y_{i-1}^{(t)}; \pi^{(t)}(i))$; \leftarrow fixed point
- 3: **end for**

• Inner loop of stochastic NASG

- 1: **for** $i = 1, \dots, n$ **do**
- 2: Update $y_i^{(t)} := y_{i-1}^{(t)} - \eta_i^{(t)} \nabla f(y_{i-1}^{(t)}; \pi^{(t)}(i))$; \leftarrow moving continuously
- 3: **end for**

Our binary classification experiments for **w8a** and **ijcnn1** datasets show our motivation. NASG-PI is the stochastic version that applies Nesterov momentum per iteration, while our method is per epoch.



Assumptions

Problem (1) satisfies:

(a) (**Bounded below and convexity for F**) We assume the existence of a minimizer for F , and F is convex.

(b) (**L -smoothness**) $f(\cdot; i)$ is L -smooth for all $i \in [n]$: , i.e., there exists $L > 0$:

$$\forall w, w' \in \text{dom}(F) \quad \|\nabla f(w; i) - \nabla f(w'; i)\| \leq L\|w - w'\|. \quad (2)$$

We let x_* be any minimizer of F and consider the variance of F at x_* :

$$\sigma_*^2 := \frac{1}{n} \sum_{i=1}^n \|\nabla f(x_*; i)\|^2 \in [0, +\infty). \quad (3)$$

In addition, we assume either (c1) or (c2):

(c1) (**Individual convexity**) $f(\cdot; i)$ is convex for all $i \in [n]$.

(c2) (**Generalized bounded variance**) There exist two finite constants $\Theta, \sigma \geq 0$:

$$\forall w \in \text{dom}(F) : \frac{1}{n} \sum_{i=1}^n \|\nabla f(w; i) - \nabla F(w)\|^2 \leq \Theta \|\nabla F(w)\|^2 + \sigma^2. \quad (4)$$

Main results

Theorem 1 - Unified Schemes (Informal)

We assume Assumption (a) and (b) with either (c1) or (c2) is satisfied. Let $\Delta := \|\tilde{x}_0 - x_*\|^2$ with the initial point \tilde{x}_0 and the minimizer x_* . With an appropriate choice of the learning rate, $F(\tilde{x}_T) - F(x_*)$ is upper bounded by

$$\begin{aligned} &\text{either } \mathcal{O}\left(\frac{\sigma_*^2/L + L\Delta}{T}\right), \text{ for individual convexity (c1)} \\ &\text{or } \mathcal{O}\left(\frac{\sigma^2/(\Theta L) + L\Theta^{1/3}\Delta}{T}\right), \text{ for generalized bounded variance (c2)} \end{aligned}$$

The convergence rate of NASG is better than the current state-of-the-art rate in term of T for convex problems with general shuffling-type strategies [1, 3].

Theorem 2 - Randomized Schemes (Informal)

Suppose that Assumption (a), (b) and (c1) hold. Let $\Delta := \|\tilde{x}_0 - x_*\|^2$ with the initial point \tilde{x}_0 and the minimizer x_* . With an appropriate choice of the learning rate and **randomized shuffling schemes**, we have

$$\mathbb{E}[F(\tilde{x}_T) - F(x_*)] \leq \mathcal{O}\left(\frac{\sigma_*^2/L}{nT} + \frac{L\Delta}{T}\right)$$

This rate has a factor of n improved, and is better than the corresponding rate for randomized schemes in the literature for convex problems [1, 3]. In the table below, we show **the complexity to reach an ϵ -accurate solution x** that satisfies $F(x) - F(x_*) \leq \epsilon$ (or $\mathbb{E}[F(x) - F(x_*)] \leq \epsilon$ in random case).

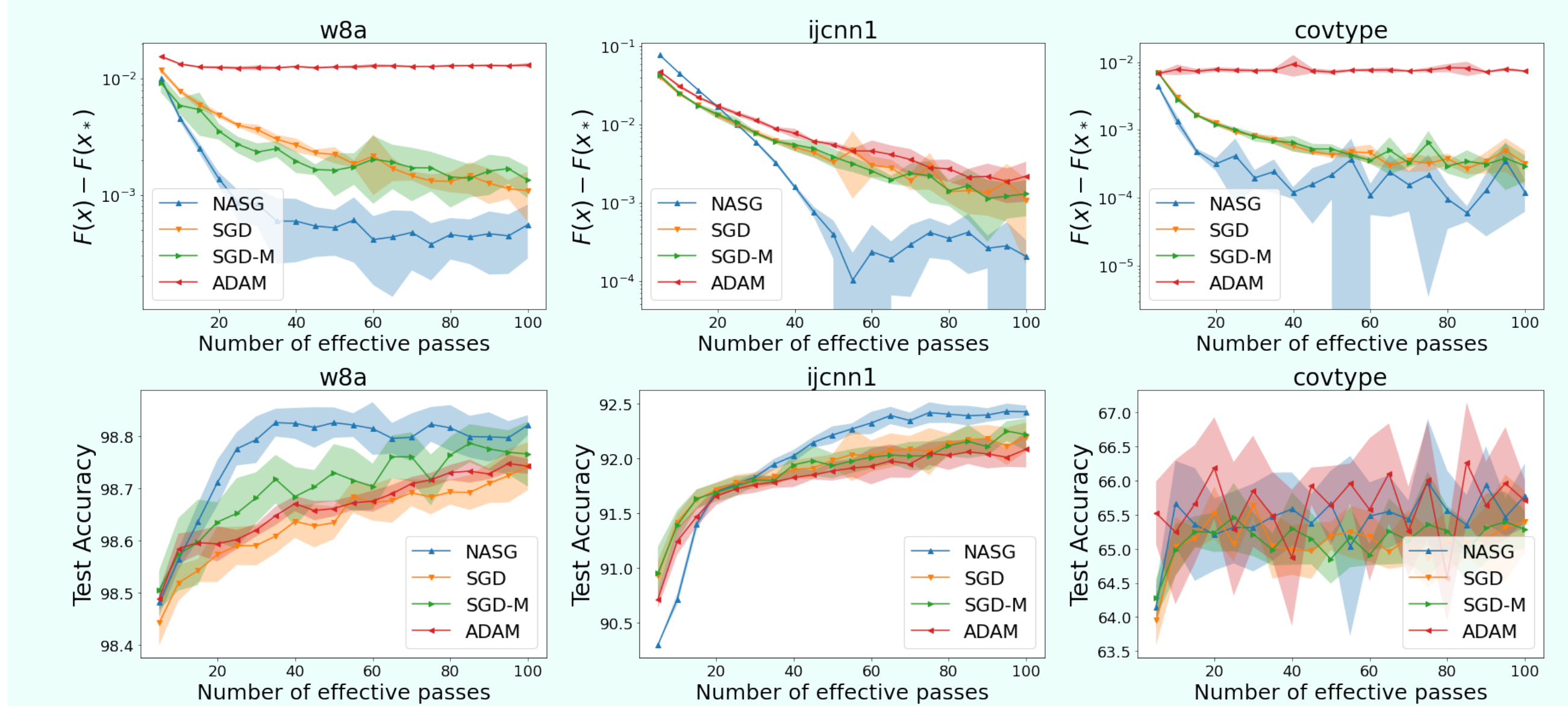
| Algorithms | Complexity | References |
|-----------------------------|--|------------|
| Standard SGD ⁽¹⁾ | $\mathcal{O}\left(\frac{\Delta_0^2 + G^2}{\epsilon^2}\right)$ (1) | [2, 4] |
| SGD - Unified Schemes | $\mathcal{O}\left(\frac{nL\Delta}{\epsilon} + \frac{n\sqrt{L}\sigma_*\Delta}{\epsilon^{3/2}}\right)$ | [1, 3] |
| SGD - Randomized Schemes | $\mathcal{O}\left(\frac{nL\Delta}{\epsilon} + \frac{\sqrt{nL}\sigma_*\Delta}{\epsilon^{3/2}}\right)$ | [1, 3] |
| NASG - Unified Schemes | $\mathcal{O}\left(\frac{nL\Delta}{\epsilon} + \frac{n\sigma_*^2}{L\epsilon}\right)$ | Theorem 1 |
| NASG - Randomized Schemes | $\mathcal{O}\left(\frac{nL\Delta}{\epsilon} + \frac{\sigma_*^2}{L\epsilon}\right)$ | Theorem 2 |

⁽¹⁾ Standard results for SGD often use bounded domain that $\|x - x_*\|^2 \leq \Delta_0$ for each iterate x and/or bounded gradient that $\mathbb{E}[\|\nabla f(x; i)\|] \leq G^2$.

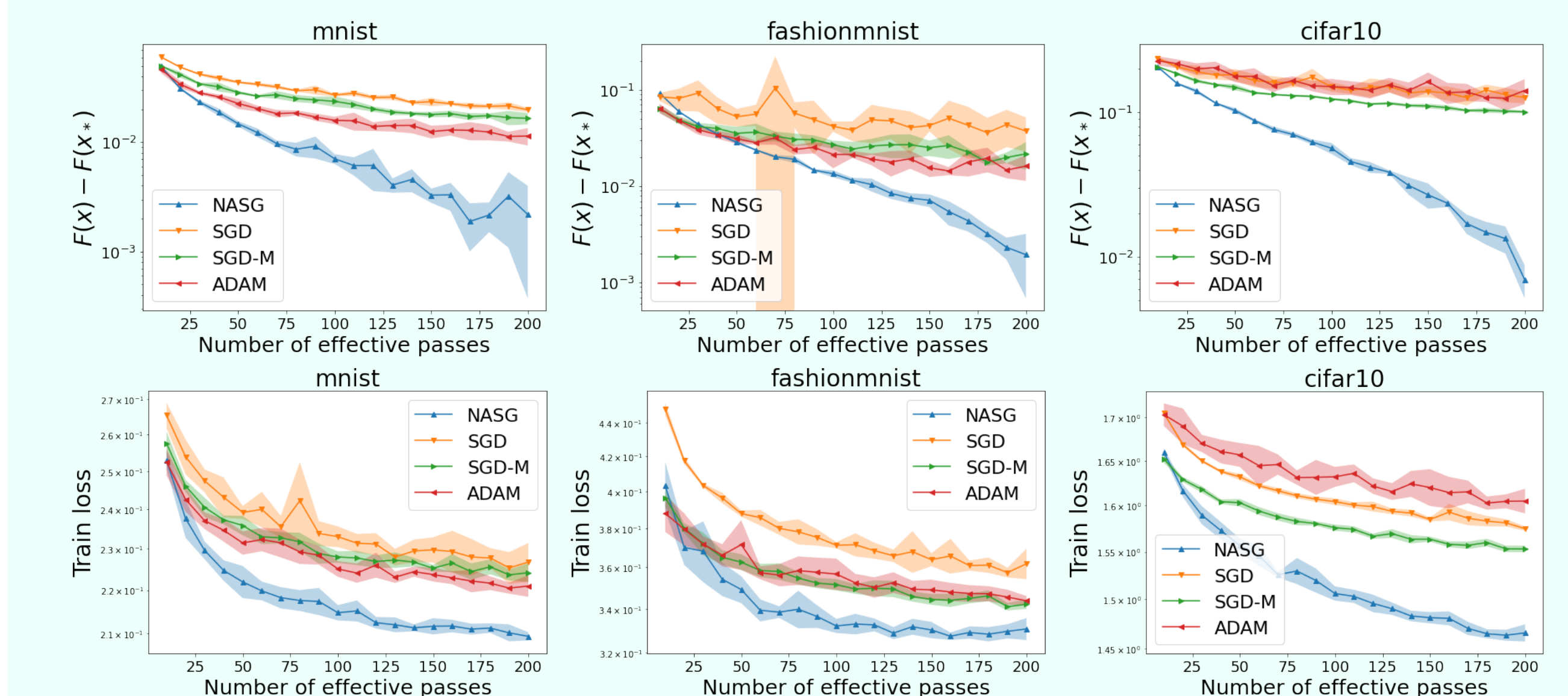
Experiments

We test **NASG method with SGD algorithm, SGD with momentum and ADAM**. Our tests have shown encouraging results for NASG.

(Convex Binary Classification). For the first experiment, we choose a binary classification problem. Below, we show comparisons of **loss residual $F(x) - F(x_*)$** (top) and **test accuracy** (bottom) produced by first-order methods for **w8a**, **ijcnn1** and **covtype** datasets, respectively.



(Convex and Non-convex Image Classification). We test four methods for the second problem: training a neural network to classify images. Our figure below compares the **loss residual $F(x) - F(x_*)$** (convex setting, top) and **train loss $F(x)$** (non-convex setting, bottom) produced by first-order methods for **MNIST**, **Fashion-MNIST** and **CIFAR-10**, respectively.



Key References

- [1] Mishchenko, K., Khaled Ragab Bayoumi, A., and Richtárik P. Random reshuffling: Simple analysis with vast improvements. *Advances in Neural Information Processing Systems*, 33, 2020.
- [2] Nemirovski, A., Juditsky, A., Lan, G., and Shapiro, A. Robust stochastic approximation approach to stochastic programming. *SIAM J. on Optimization*, 19(4):1574–1609, 2009.
- [3] Nguyen, L. M., Tran-Dinh, Q., Phan, D. T., Nguyen, P. H., and van Dijk, M. A unified convergence analysis for shuffling-type gradient methods. *Journal of Machine Learning Research*, 22(207):1–44.
- [4] Shamir, O. and Zhang, T. Stochastic gradient descent for non-smooth optimization: Convergence results and optimal averaging schemes. *Proceedings of the 30th International Conference on Machine Learning, PMLR*.
- [5] Tran, T. H., Nguyen, L. M., and Tran-Dinh, Q. SMG: A shuffling gradient-based method with momentum. *Proceedings of the 38th International Conference on Machine Learning, PMLR*.