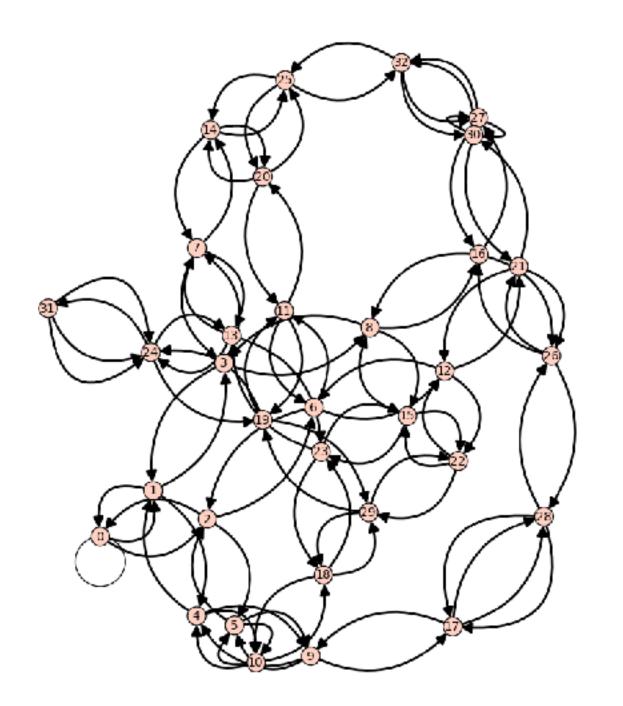
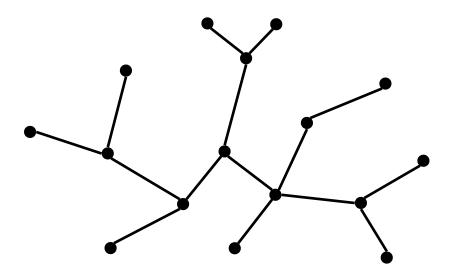
Minimum Spanning Trees

Recitation 13 CS 2112 Fall 2018



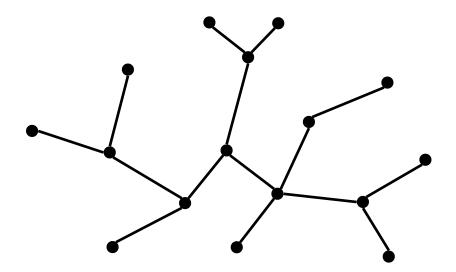
Undirected Trees

• An undirected graph is a *tree* if there is exactly one simple path between any pair of nodes



Undirected Trees

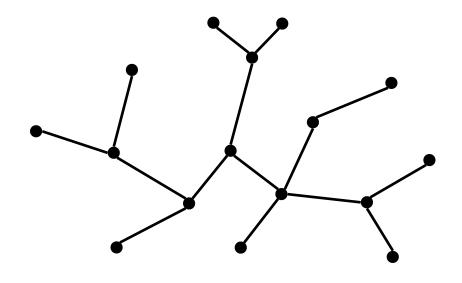
• Equivalently: an undirected graph is a *tree* if it is connected (there is a path between any pair of nodes) and acyclic



Facts About Trees

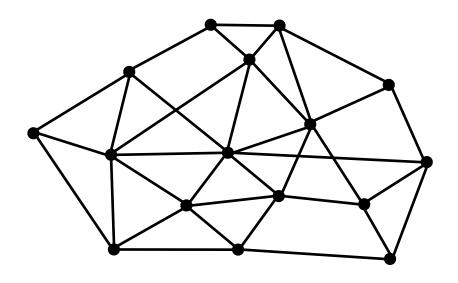
- 1. |E| = |V| 1
- 2. connected
- 3. no cycles

Any two of these properties imply the third, and imply that the graph is a tree



Spanning Trees

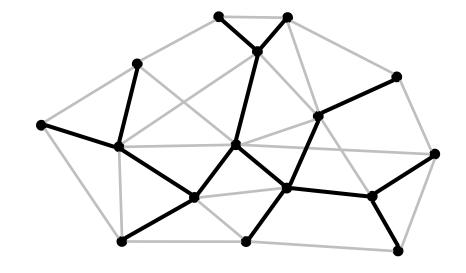
A spanning tree of a connected undirected graph (V, E) is a subgraph (V, E') that is a tree



Spanning Trees

A spanning tree of a connected undirected graph (V, E) is a subgraph (V, E') that is a tree

- Same set of vertices V
- E' ⊆ E
- (V, E') is a tree

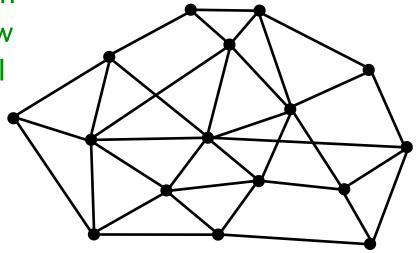


A subtractive method

• Start with the whole graph - it is connected

If there is a cycle, pick an edge on the cycle, throw it out – the graph is still connected (why?)

Repeat until no more cycles

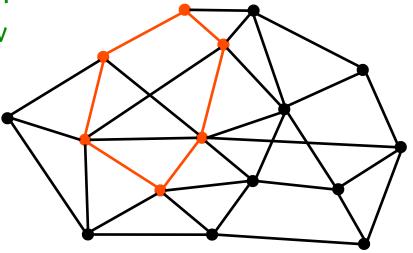


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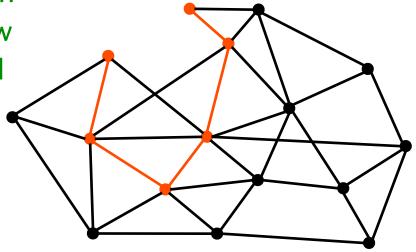


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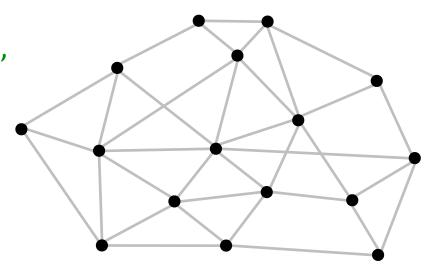
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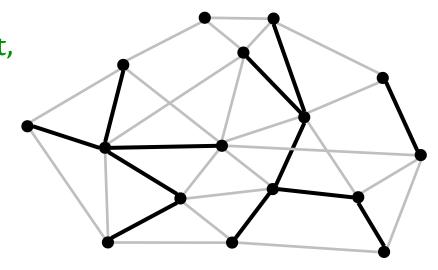
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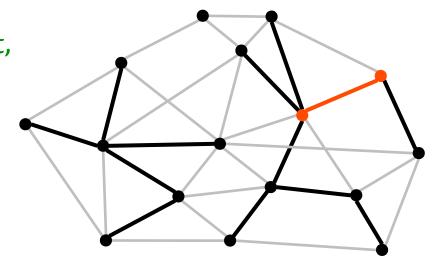
- Start with no edges there are no cycles
- If more than one connected component, insert an edge between them – still no cycles (why?)
- Repeat until only one component



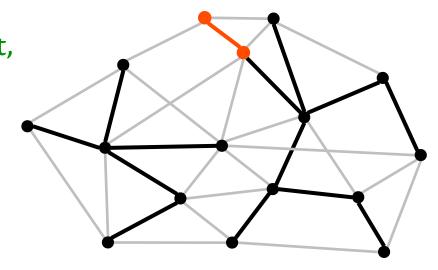
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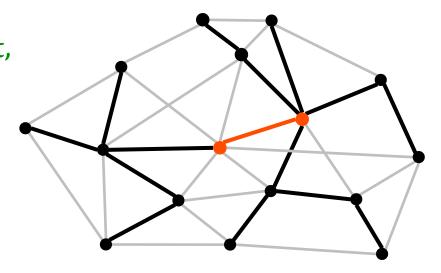
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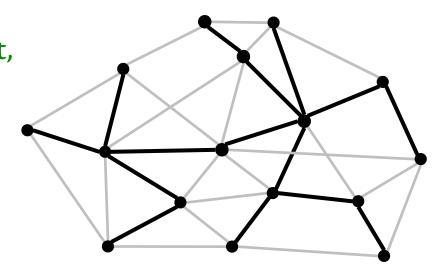
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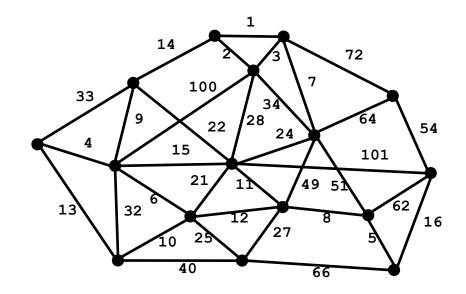
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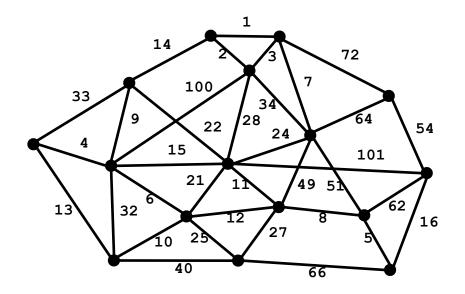


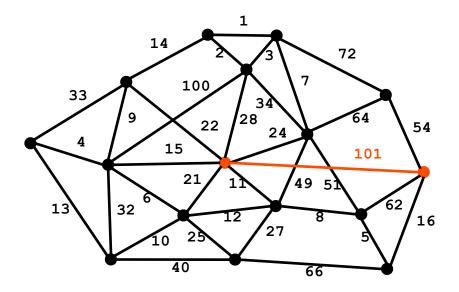
Minimum Spanning Trees

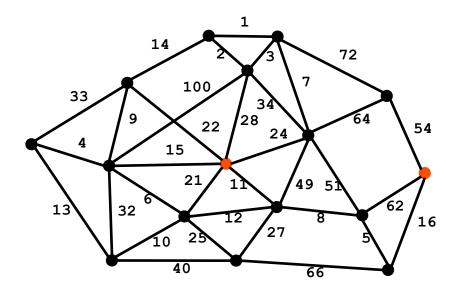
• Suppose edges are weighted, and we want a spanning tree of *minimum cost* (sum of edge weights)

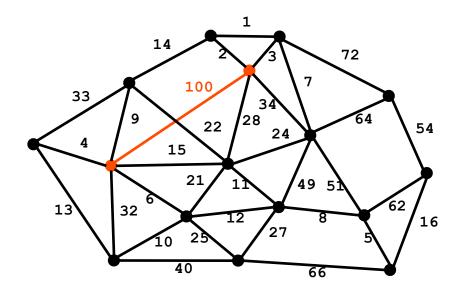
 Useful in network routing & other applications

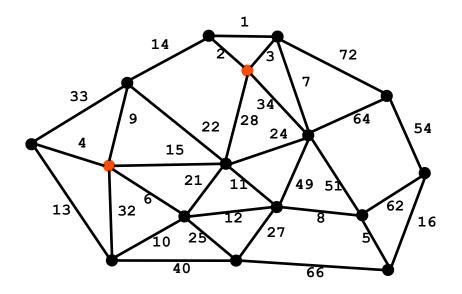


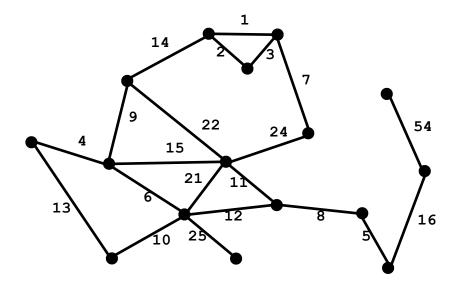


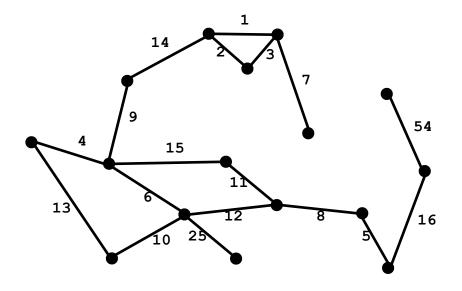


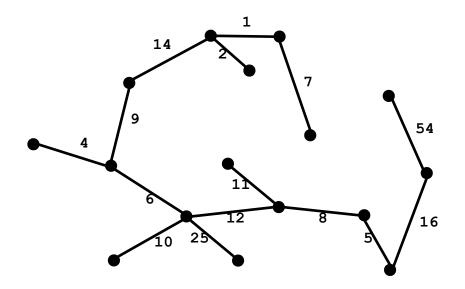




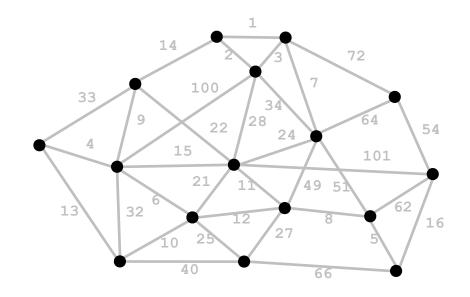




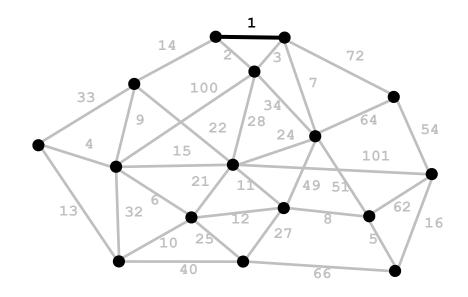




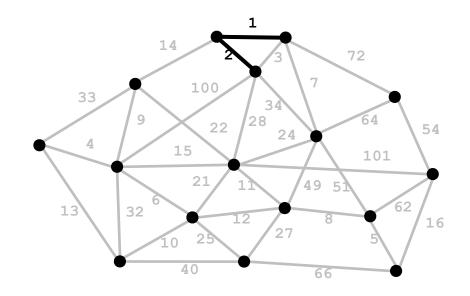
B. Find a min weight edge – if it forms a cycle with edges already taken, throw it out, otherwise keep it



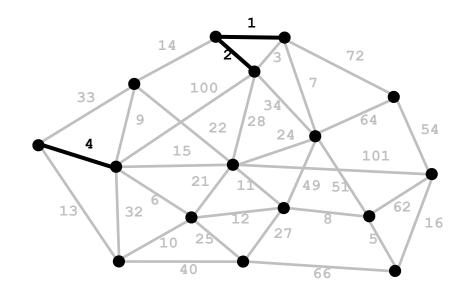
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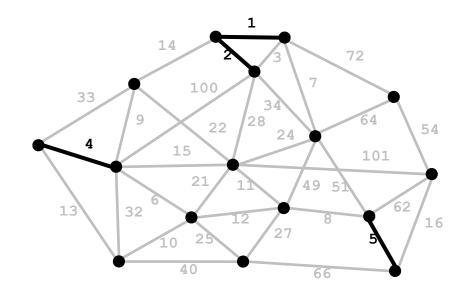
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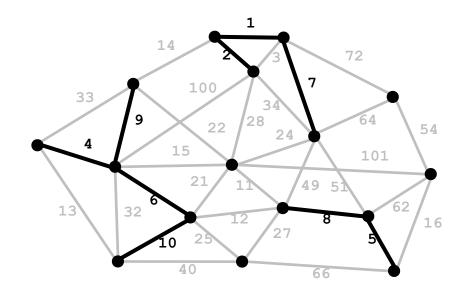
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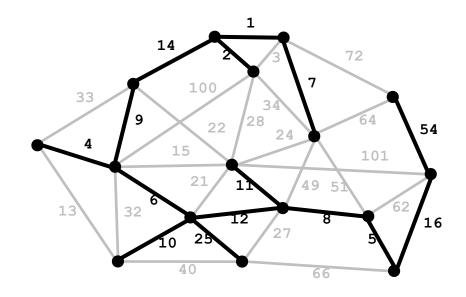
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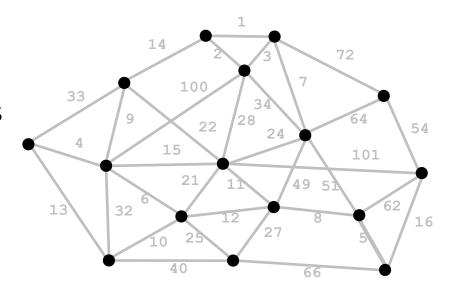
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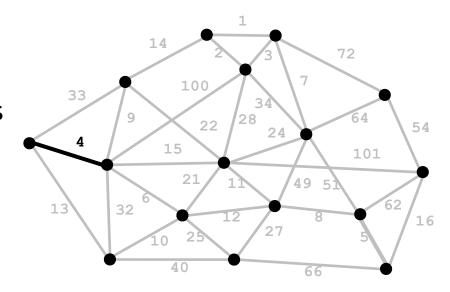
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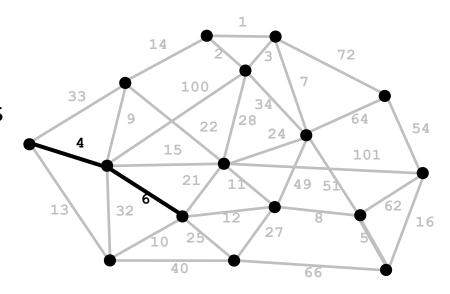
C. Start with any vertex, add min weight edge extending that connected component that does not form a cycle



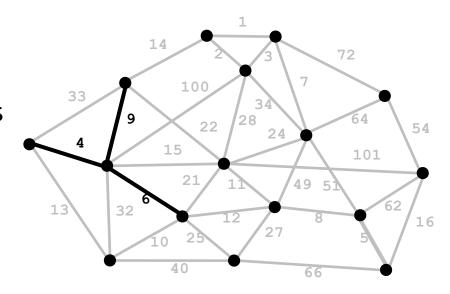
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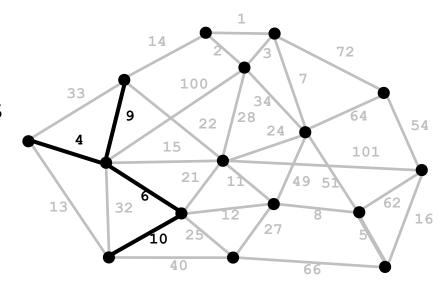
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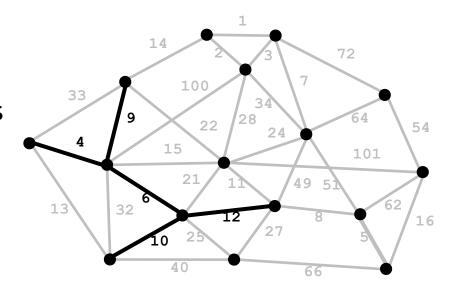


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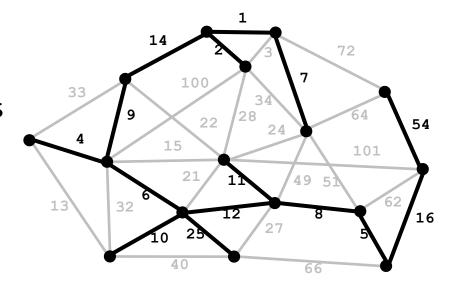
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Prim's algorithm (reminiscent of Dijkstra's algorithm)

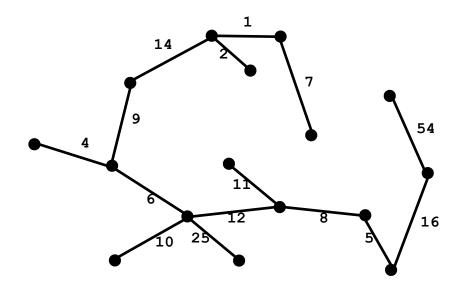


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Prim's algorithm (reminiscent of Dijkstra's algorithm)



All 3 greedy algorithms give the same minimum spanning tree (assuming distinct edge weights)



Prim's Algorithm (pseudo-code)

```
prim(s) {
    D[s] = 0;
    for (v != s) D[v] = ∞;
    while (some vertices are unmarked) {
        u = unmarked vertex with smallest D;
        mark u;
        for (each v adj to u) {
            D[v] = min(D[v], w(u,v));
        }
    }
}
```

- O(n²) for adj matrix
 - While-loop is executed n times
 - For-loop takes O(n) time

- O(m + n log n) for adj list
 - Use a PQ
 - Regular PQ produces time O(n + m log m)
 - Can improve to O(m + n log n) using a fancier heap

- These are examples of Greedy Algorithms
- The Greedy Strategy is an algorithm design technique
 - Like Divide & Conquer
- Greedy algorithms are used to solve optimization problems
 - The goal is to find the best solution
- Works when the problem has the greedy-choice property
 - A global optimum can be reached by making locally optimum choices

- Example: the Change Making Problem:
 Given an amount of money, find the
 smallest number of coins to make that
 amount
- Solution: Use a Greedy Algorithm
 - Give as many large coins as you can
- This greedy strategy produces the optimum number of coins for the US coin system
- Different money system ⇒ greedy strategy may fail
 - Example: old UK system

Similar Code Structures

```
while (some vertices unmarked) {
   u = best of unmarked vertices;
   mark u;
   for (each v adj to u) {
      update v;
   }
}
```

BFS

- best: next in queue
- update: D[w] = D[v]+1
- Dijkstra
 - best: next in PQ
 - update: D[w] =
 min D[w], D[v]+c(v,w)
- Prim
 - best: next in PQ
 - update: D[w] =
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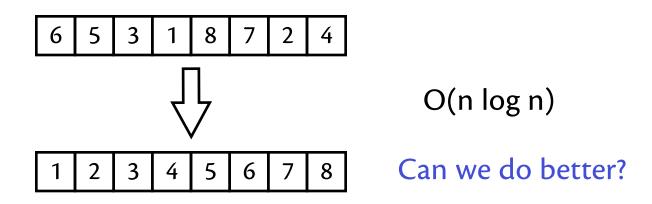
Selection algorithms

6 5 3 1 8 7 2 4

- Find largest?
- Find smallest?
- Find kth smallest?

Quickselect

Find the kth smallest element of an array



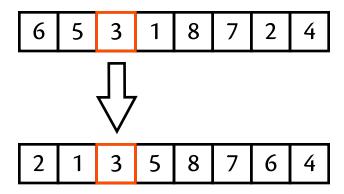
Pick (N-k)th element

Quickselect

```
function select(list, left, right, k)
      if left = right // return if the list has one element
          return list[left]
      // select pivotIndex between left and right
      pivotNewIndex := partition(list, left, right,
 pivotIndex)
      pivotDist := pivotNewIndex - left + 1
      // The pivot is in its final sorted position,
      // so pivotDist reflects its 1-based position
  // if list were sorted
      if pivotDist = k
          return list[pivotNewIndex]
      else if k < pivotDist</pre>
          return select(list, left, pivotNewIndex - 1, k)
      else
          return select(list, pivotNewIndex + 1, right,
                        k - pivotDist)
```

Quickselect





3 is in it's sorted place, so if k=3 we are done

otherwise, only need 1 recursive call.

Quickselect running time

- O(n) on average, but worst case O(n²)
- Worst case happens with bad pivots
 - Min or max of the elements means we select all elements as pivots

• IDEA: ensure O(n) performance by consistently choosing good pivots

Selection in O(n)

- Best pivot is *median* of elements since it will partition the elements equally
- Median-of-medians algorithm
 - -Divide list into (n/5) groups of five
 - -Find median of each group (n/5 medians)
 - -Then find median these medians
 - -Choose this value as the pivot.

Pivot

- Pivot is less than half of the medians
 - -n/10 elements
- Each median is less than 2 elements from its group of 5
- So, the pivot is less than 3(n/10) elements
- Similarly, pivot is greater 3(n/10) elements
- Somewhere between 30/70 and a 70/30 split.
 - -Ensures O(n)!