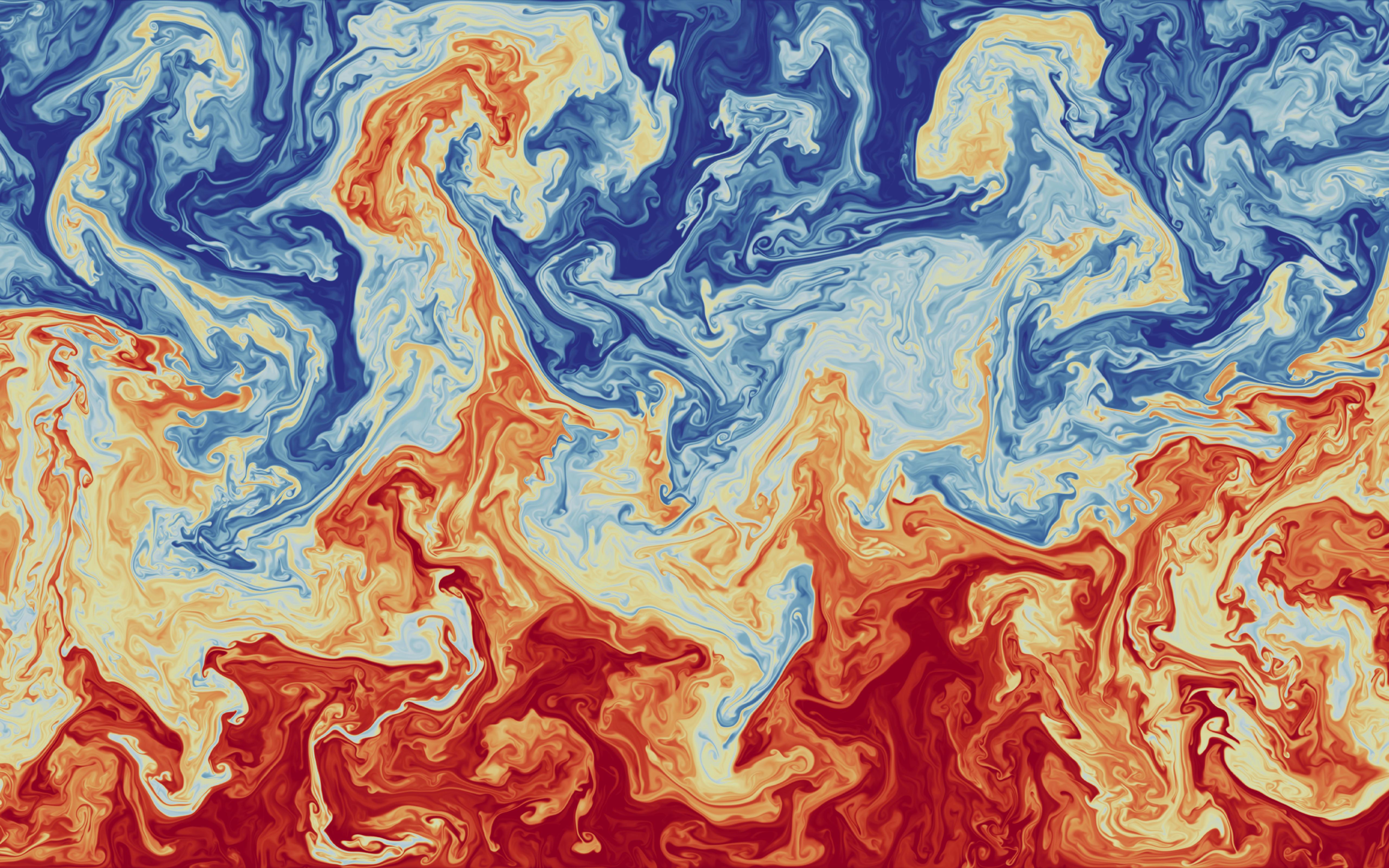
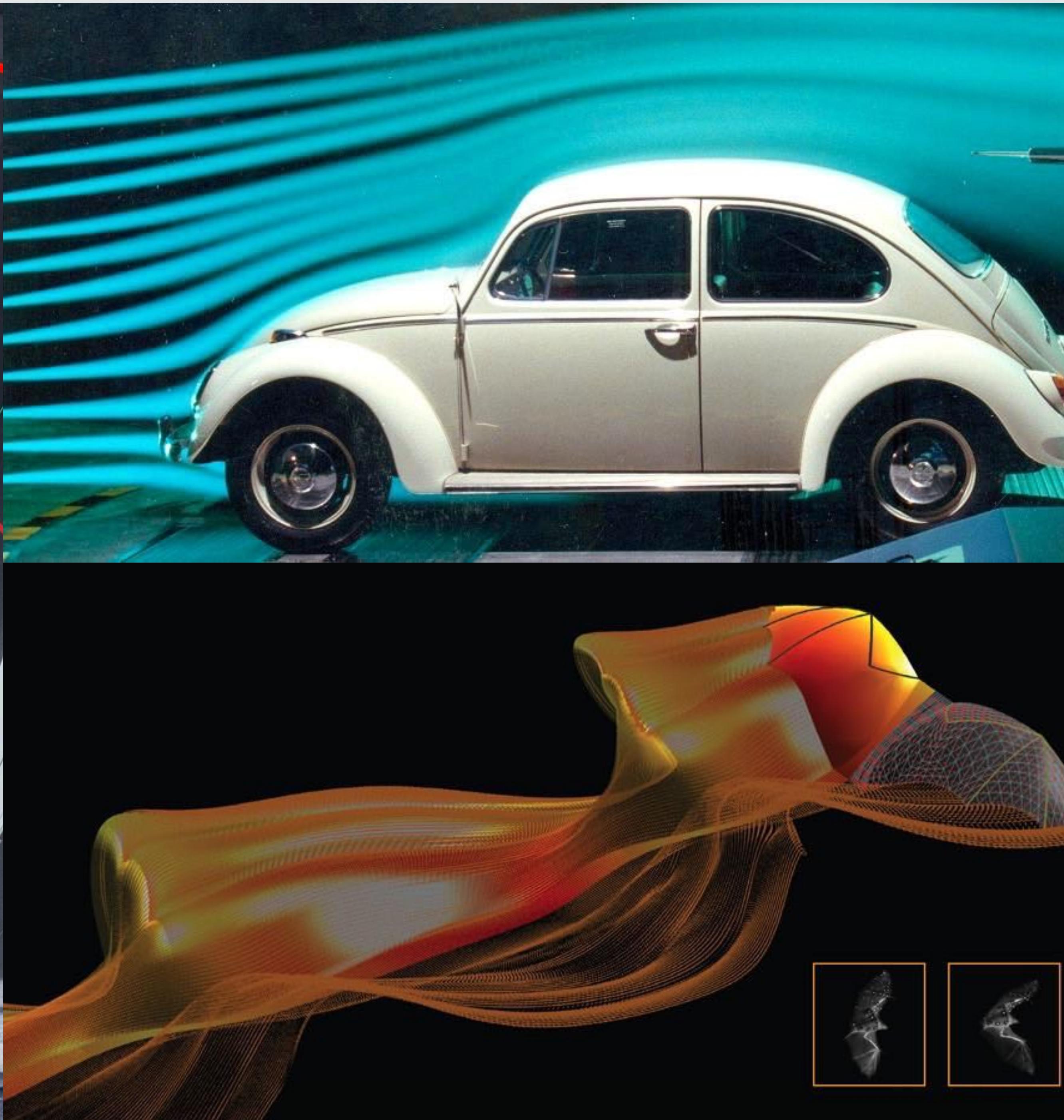


Introduction to Spectral Methods & Dedalus

Keaton Burns
BPM Summer School 2023



PDEs across science & engineering



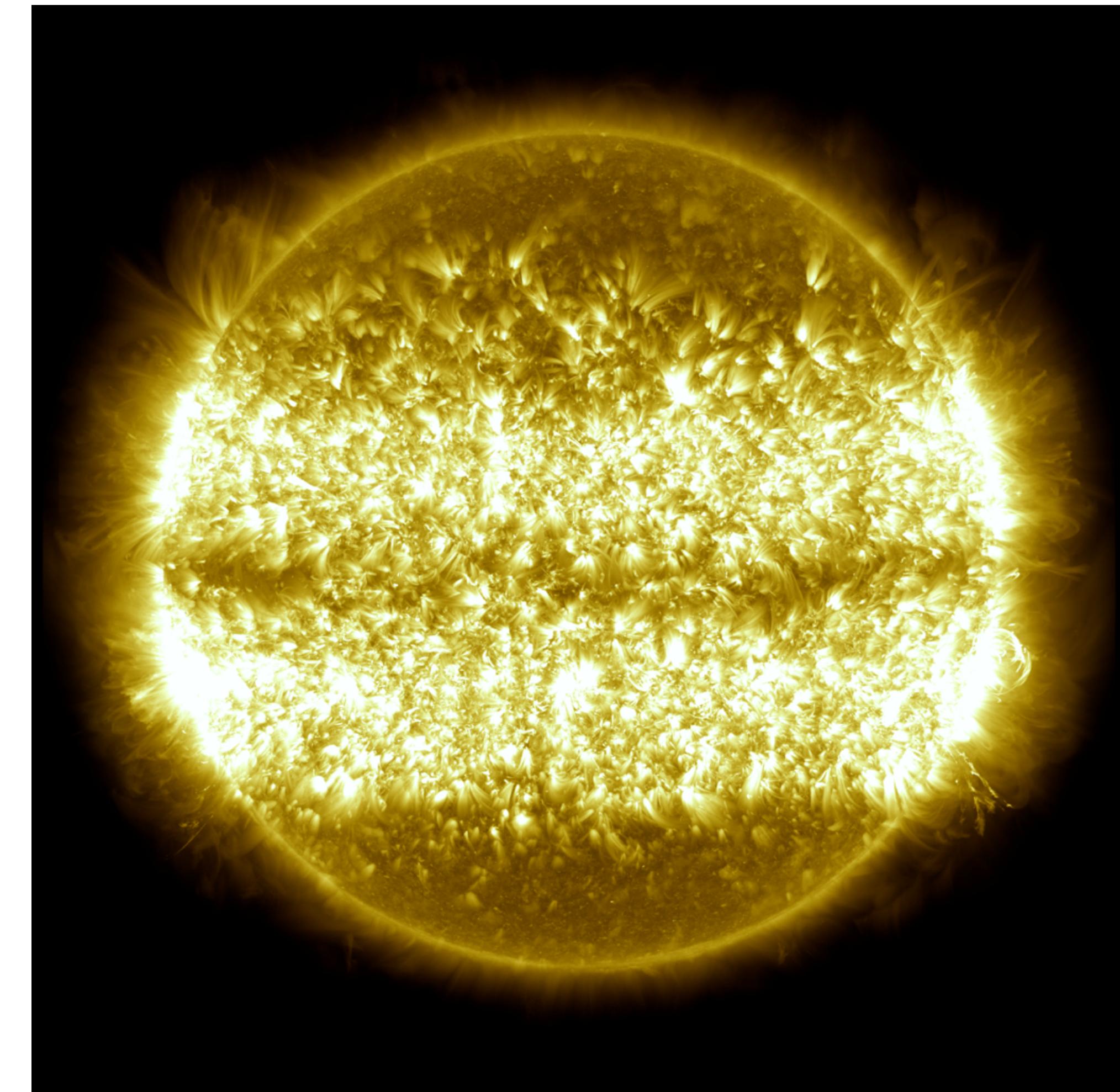
PDEs across science & engineering

Belousov–Zhabotinsky reaction



(Stephen Morris)

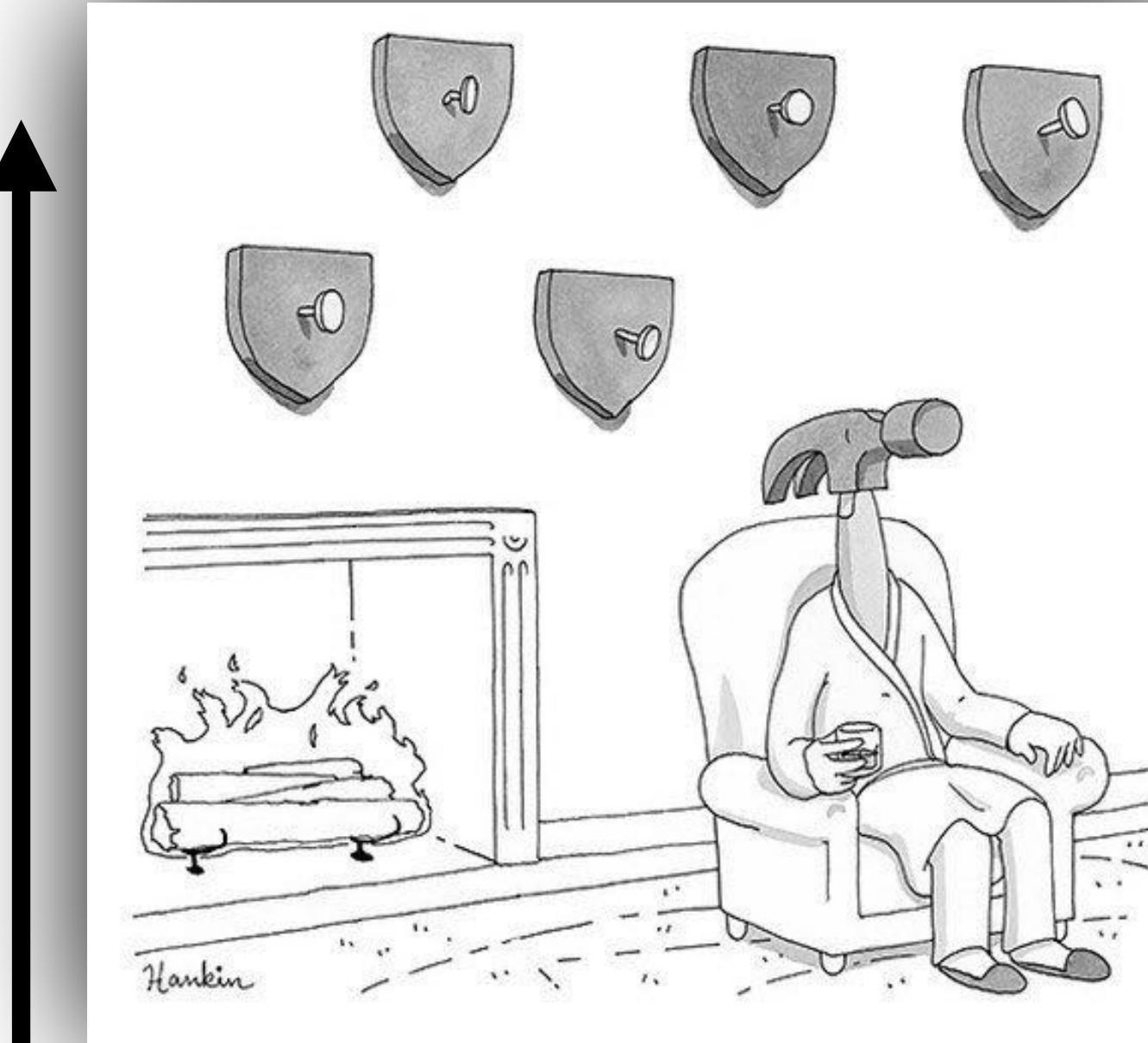
Solar convection



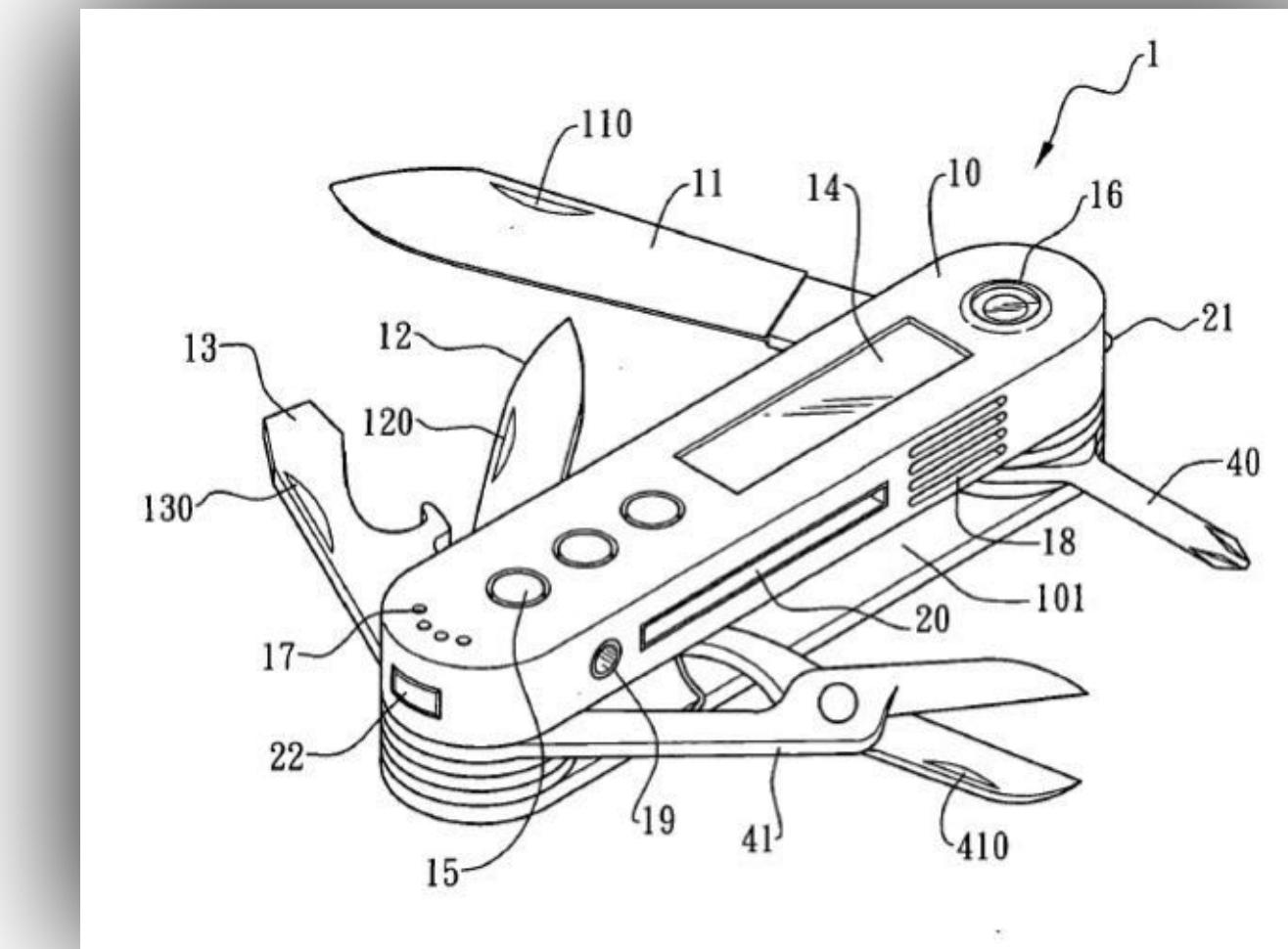
(NASA/SDO)

Challenge: high-order & flexible methods at scale

Performance
&
Scalability

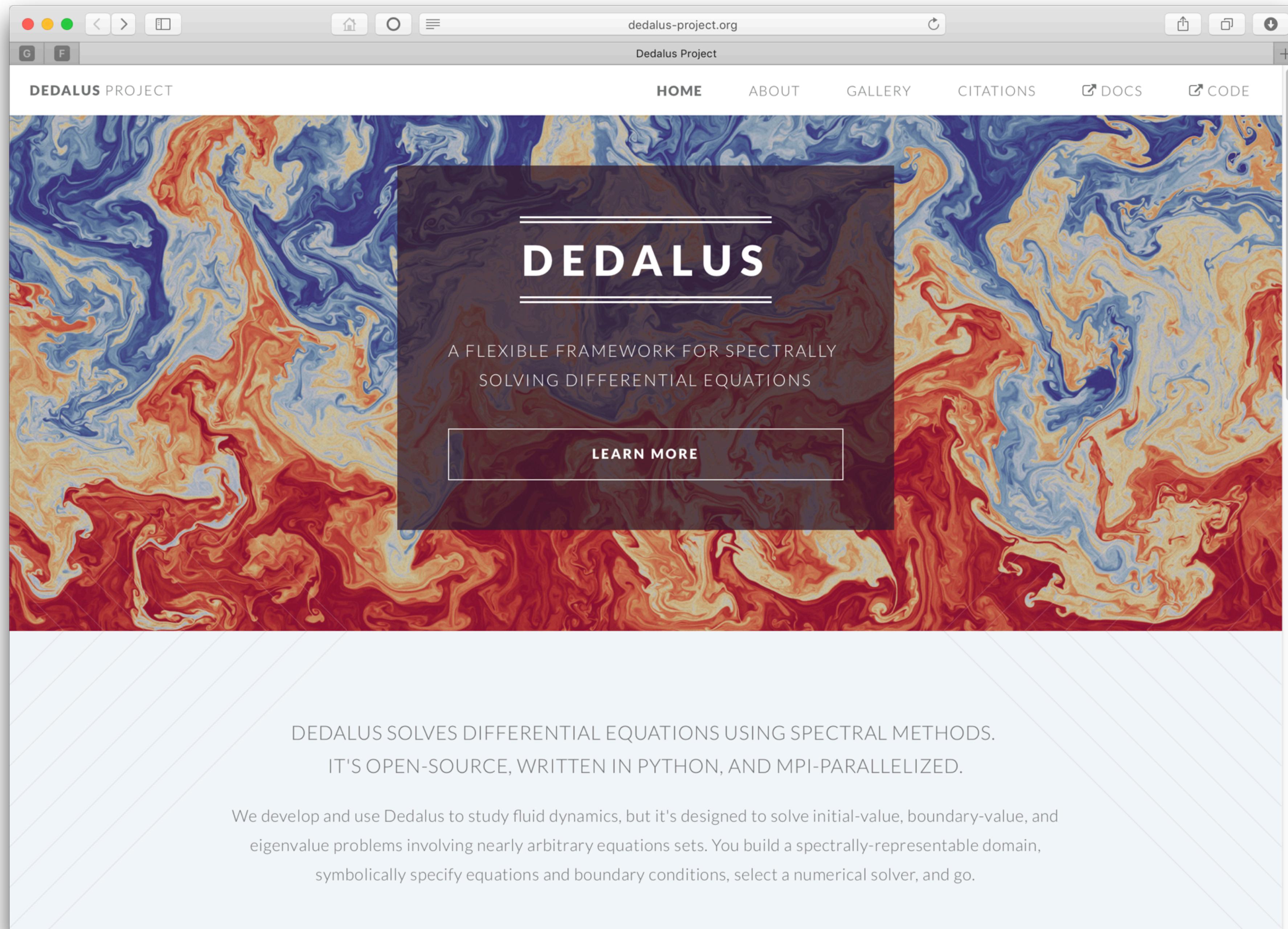


?



Accuracy & Flexibility

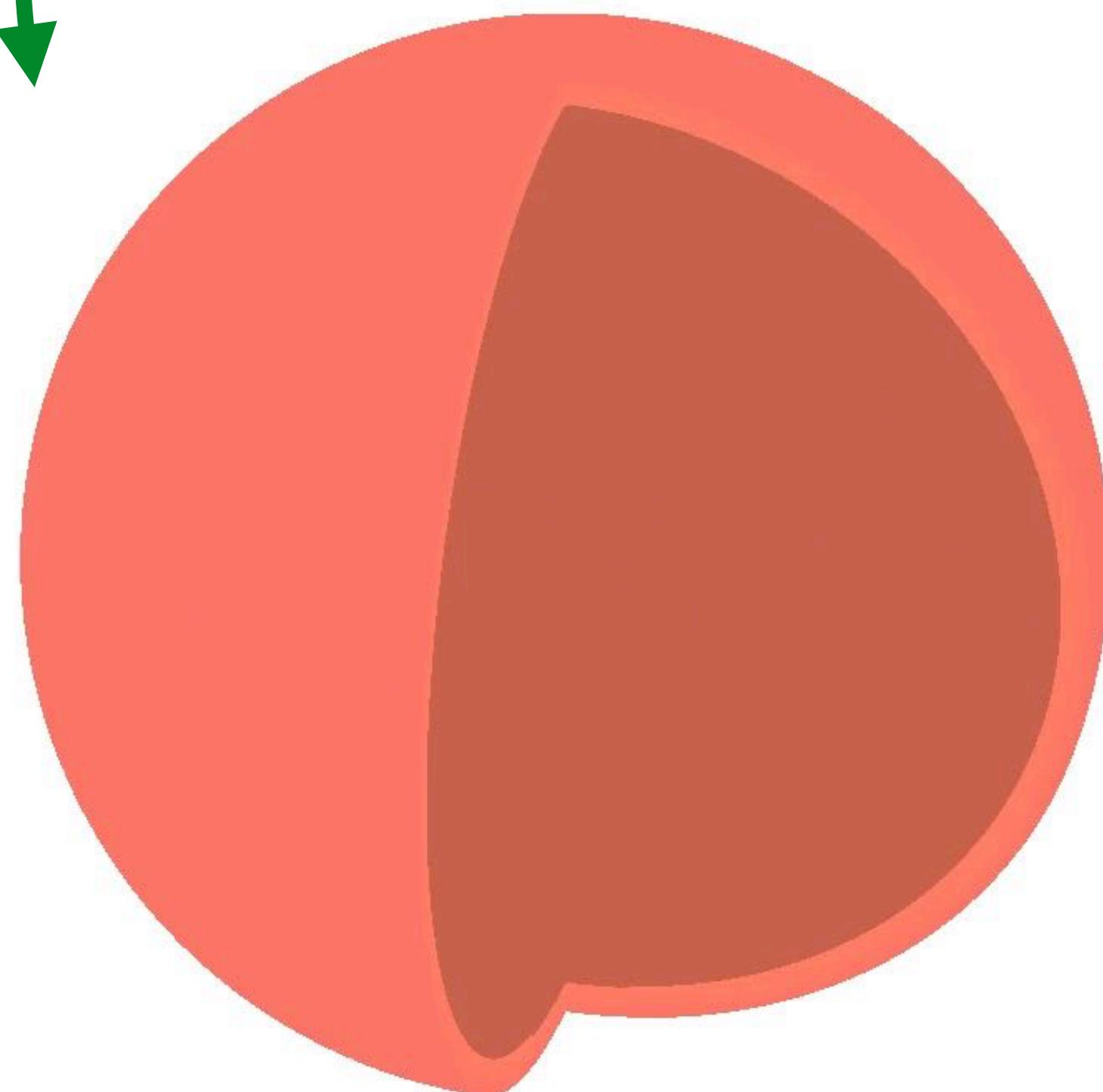
Dedalus Project



Dedalus Project

```
problem.add_equation("div(u) = 0")
problem.add_equation("dt(u) - v*Lap(u) + grad(p) + b*g = - u@grad(u)")
problem.add_equation("dt(b) - K*Lap(b) = - u@grad(b)")
```

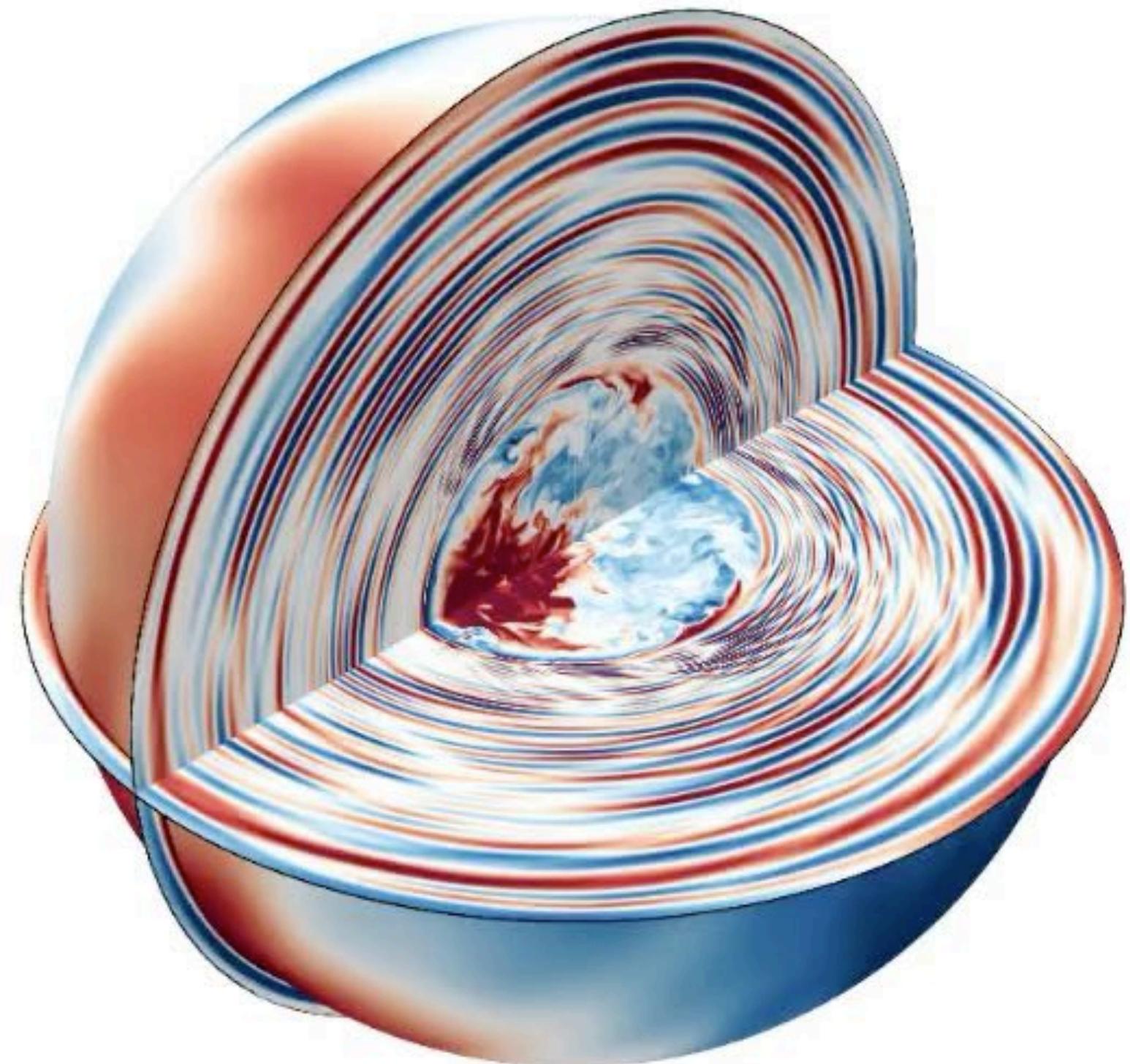
Rapid solver development
Spiral-defect chaos



Flexible equations
NLS quantum graphs



High performance
Turbulent wave excitation



Global Spectral Methods

Global spectral discretizations

Expand over “**trial**” functions:

$$u(x) = \sum_{n=0}^N u_n \phi_n(x)$$

Project equations against “**test**” functions:

$$\mathcal{L}u(x) = f(x)$$

$$\langle \psi_i | \mathcal{L}u \rangle = \langle \psi_i | f \rangle$$

$$\sum_j \langle \psi_i | \mathcal{L}\phi_j \rangle u_j = \langle \psi_i | f \rangle$$

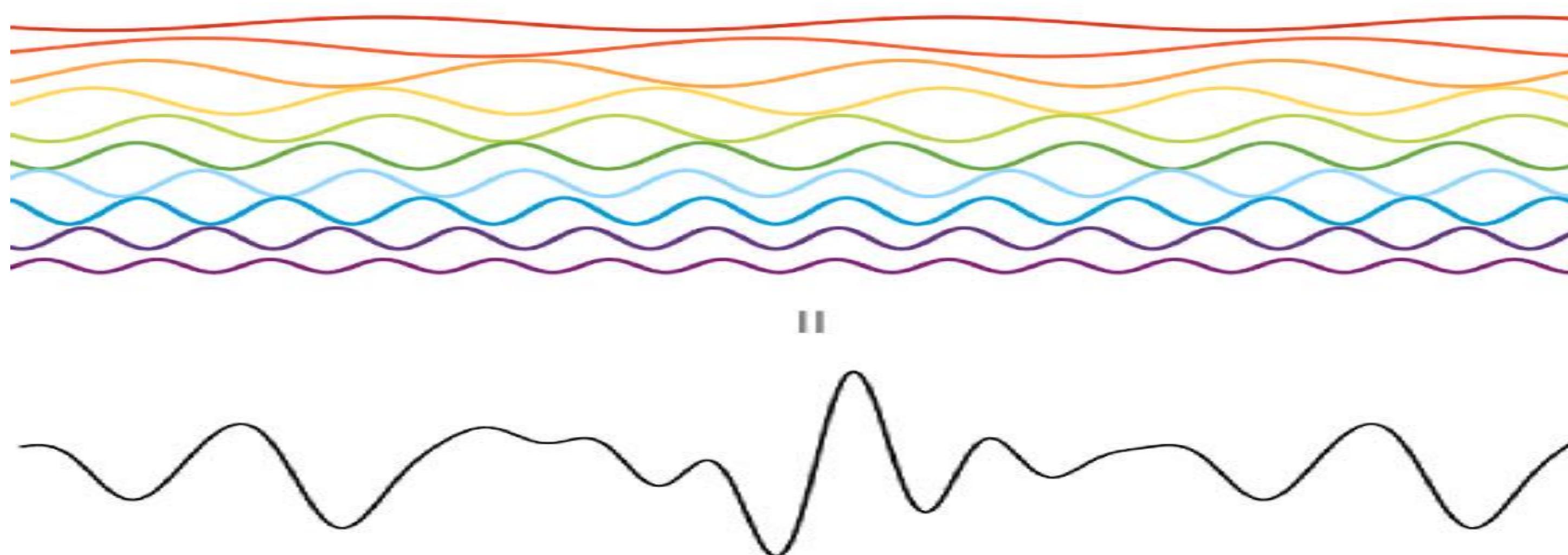
- Easy to adapt to different equations
- **Exponential convergence** for smooth functions
- Only possible in **simple geometries**
- **Fast** if discretized operators are **sparse**
- RHS terms require **spectral transforms**

Fourier spectral methods

Fourier series $\phi_n(x) = e^{inx}$

- **Exponential convergence** for smooth **periodic** functions
- **Fast transforms** for computing coefficients
- **Diagonal** derivative matrix:

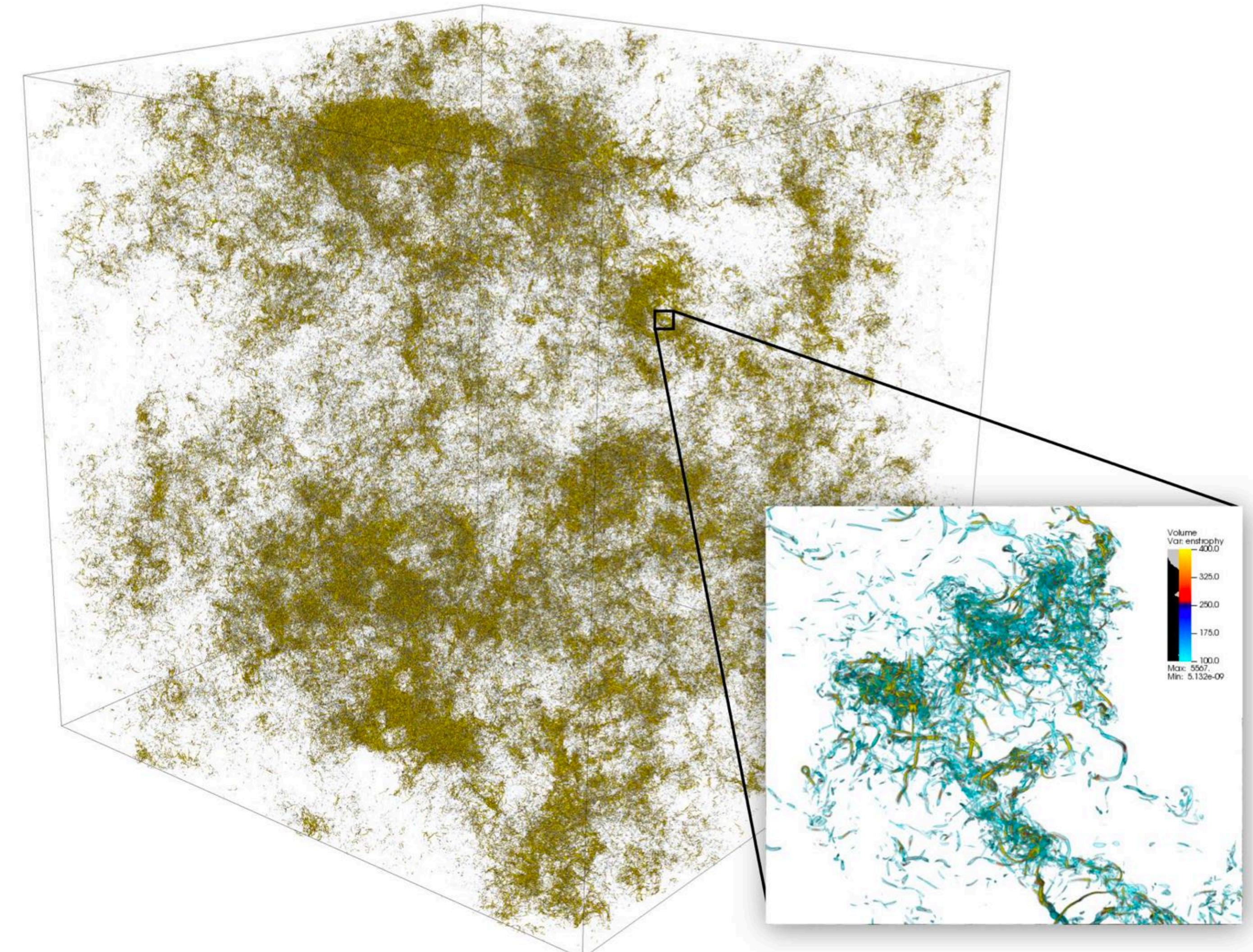
$$\langle \phi_m | \partial_x \phi_n \rangle = in\delta_{m,n}$$



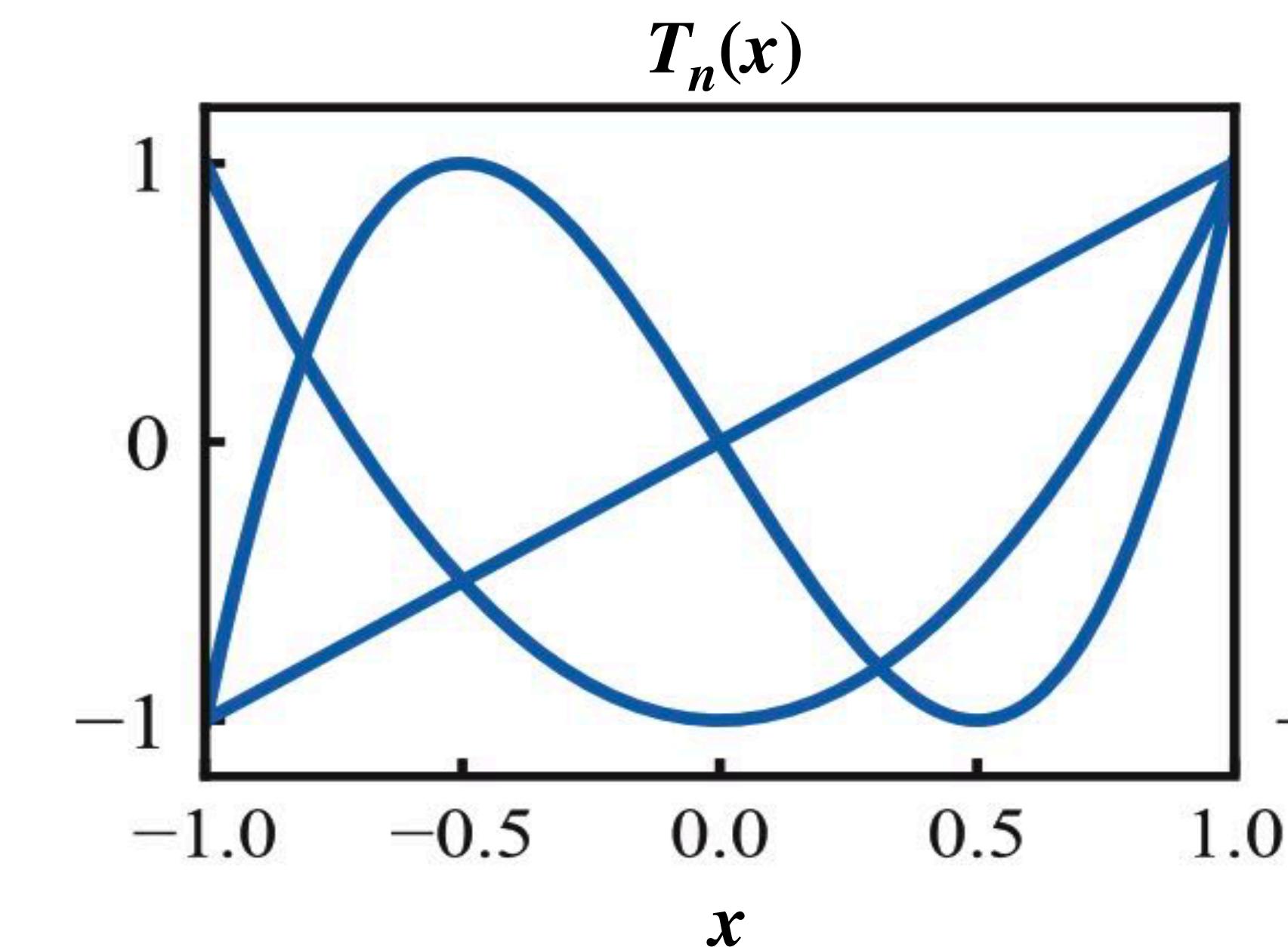
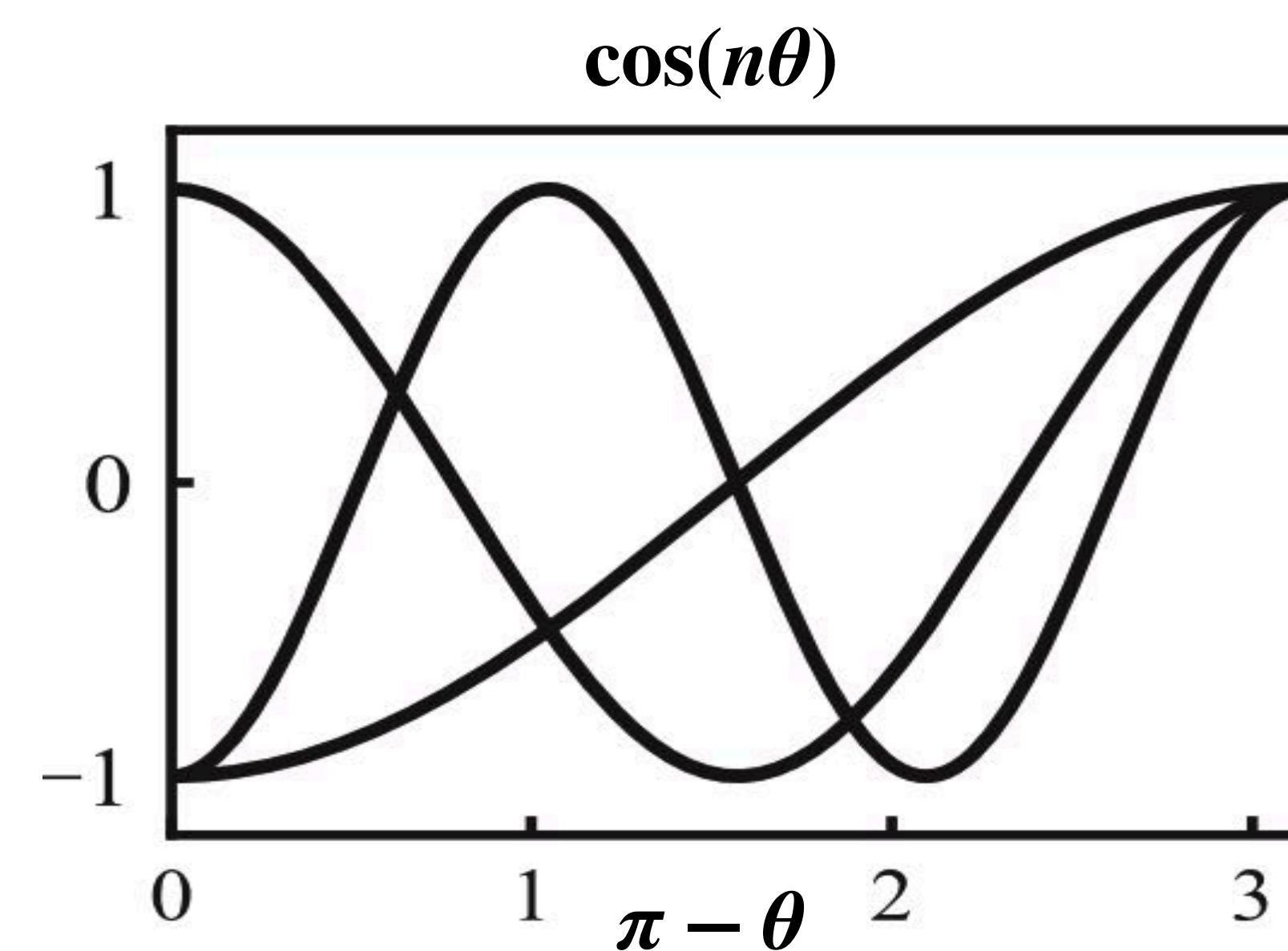
World's largest turbulence simulations

Yeung & Ravikumar, Phys. Rev. Fluids (2021)

- Fourier pseudospectral method (not Dedalus)
- $18,432^3$ grid points
- 18,432 GPUs



Chebyshev polynomials: cosines in disguise



Orthogonal polynomials for non-periodic intervals

Jacobi polynomials $P_n^{(\alpha,\beta)}(x) \in \Pi_n$

- Orthogonal under weight: $w(x) = (1 - x)^\alpha(1 + x)^\beta$
- Closed under differentiation: $\partial_x^k P_n^{(\alpha,\beta)} \propto P_{n-k}^{(\alpha+k,\beta+k)}$
- **Exponential convergence** for smooth functions on $[-1, 1]$

1) **Legendre polynomials** ($\alpha = \beta = 0$) $P_n(x)$

- **Best L2 approximations** $w(x) = 1$

2) **Chebyshev polynomials** ($\alpha = \beta = -1/2$) $T_n(x)$

- **Fast transforms** (DCT) for computing coefficients

3) **Ultraspherical / Gegenbauer polynomials** ($\alpha = \beta = k - 1/2$) $C_n^{(k)}(x)$

- k -th derivatives of Chebyshev polynomials

Classical Chebyshev Methods

Same trial & test functions:

E.g. Collocation

$$u(x) = \sum_{i=0}^N u(x_i) L_i(x)$$

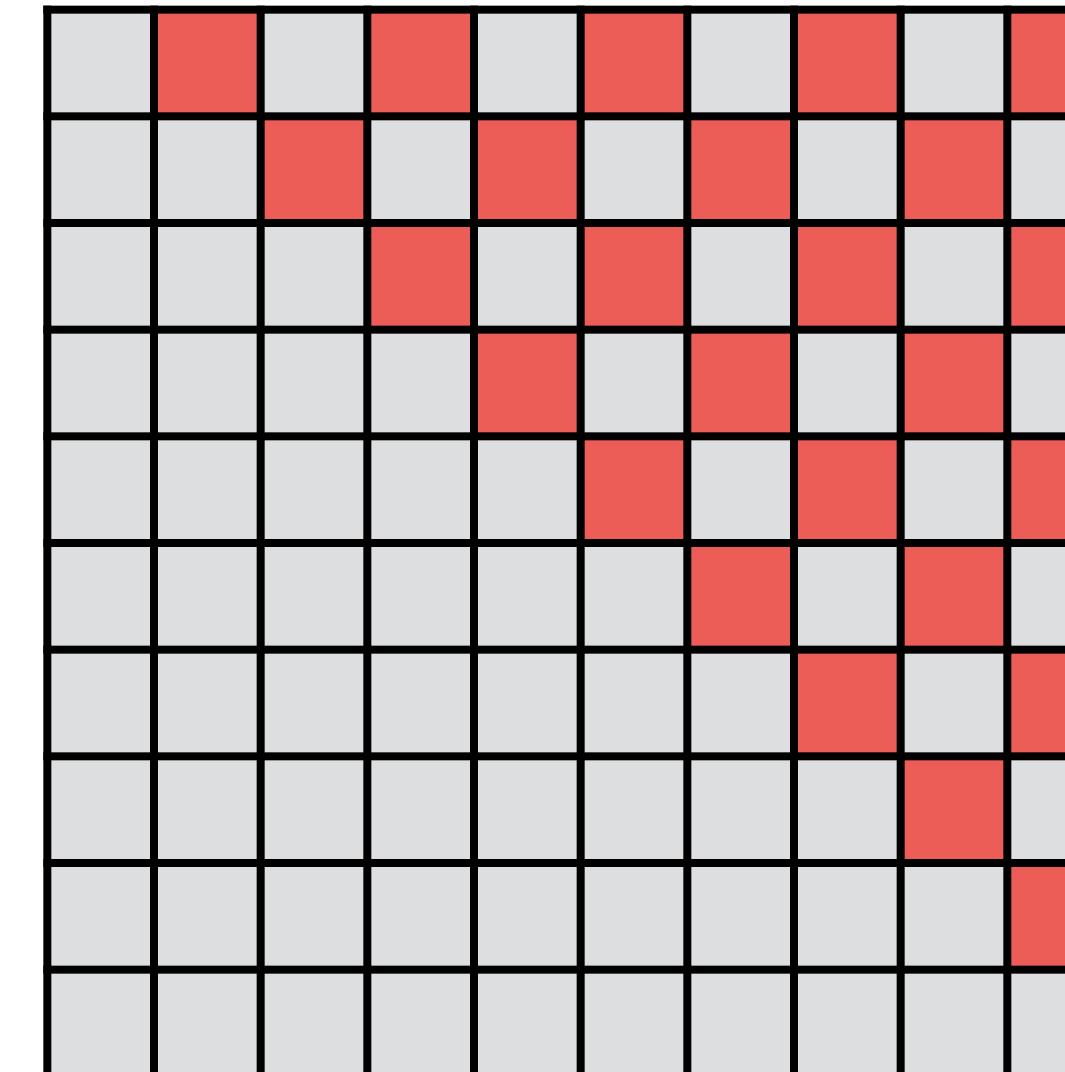
$$L_i(x) = \prod_{j \neq i} \frac{x - x_j}{x_i - x_j}$$

E.g. Chebyshev-tau

$$u(x) = \sum_{n=0}^N u_n T_n(x)$$

Differentiation:

$$\mathcal{D}_{m,n} = \langle T_m | \partial_x T_n \rangle$$



- Dense matrices
- Poor conditioning

Sparse Chebyshev Methods

Chebyshev trial functions:

$$u(x) = \sum_{n=0}^N u_n T_n(x)$$

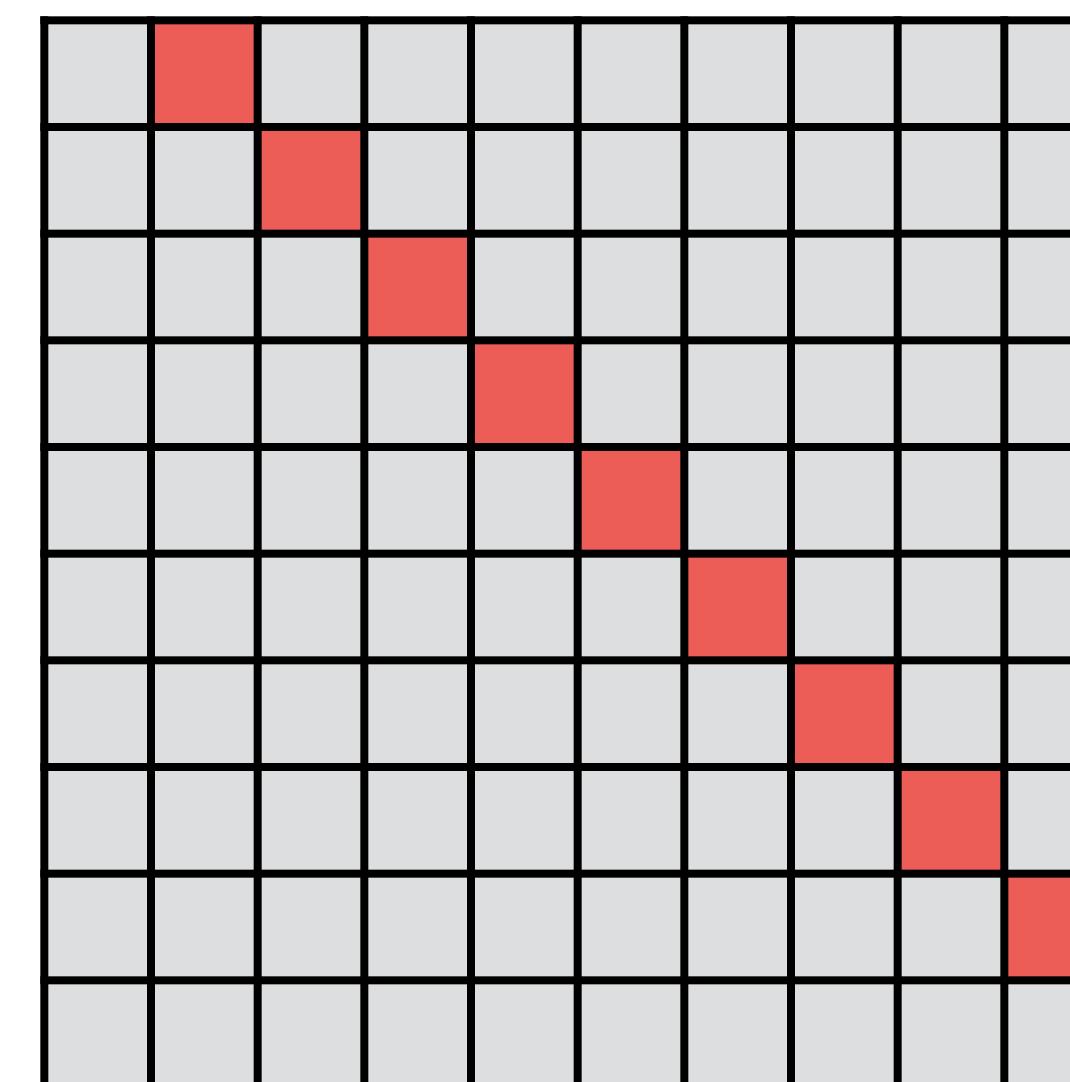
Ultraspherical test functions:

$$\alpha = \beta = k - 1/2$$

$$C_n^{(k)}(x) \propto \partial_x^k T_{n+k}(x)$$

Differentiation:

$$\mathcal{D}_{m,n} = \langle C_m^{(1)} | \partial_x T_n \rangle$$



- Banded
- Well conditioned

Key points for efficient spectral solvers

1. Spectrally accurate bases

- Rapidly convergent approximations

$$\{\phi_i(x)\}$$

2. Sparse differential operators

- Fast operator evaluation
- Fast direct solvers for LHS

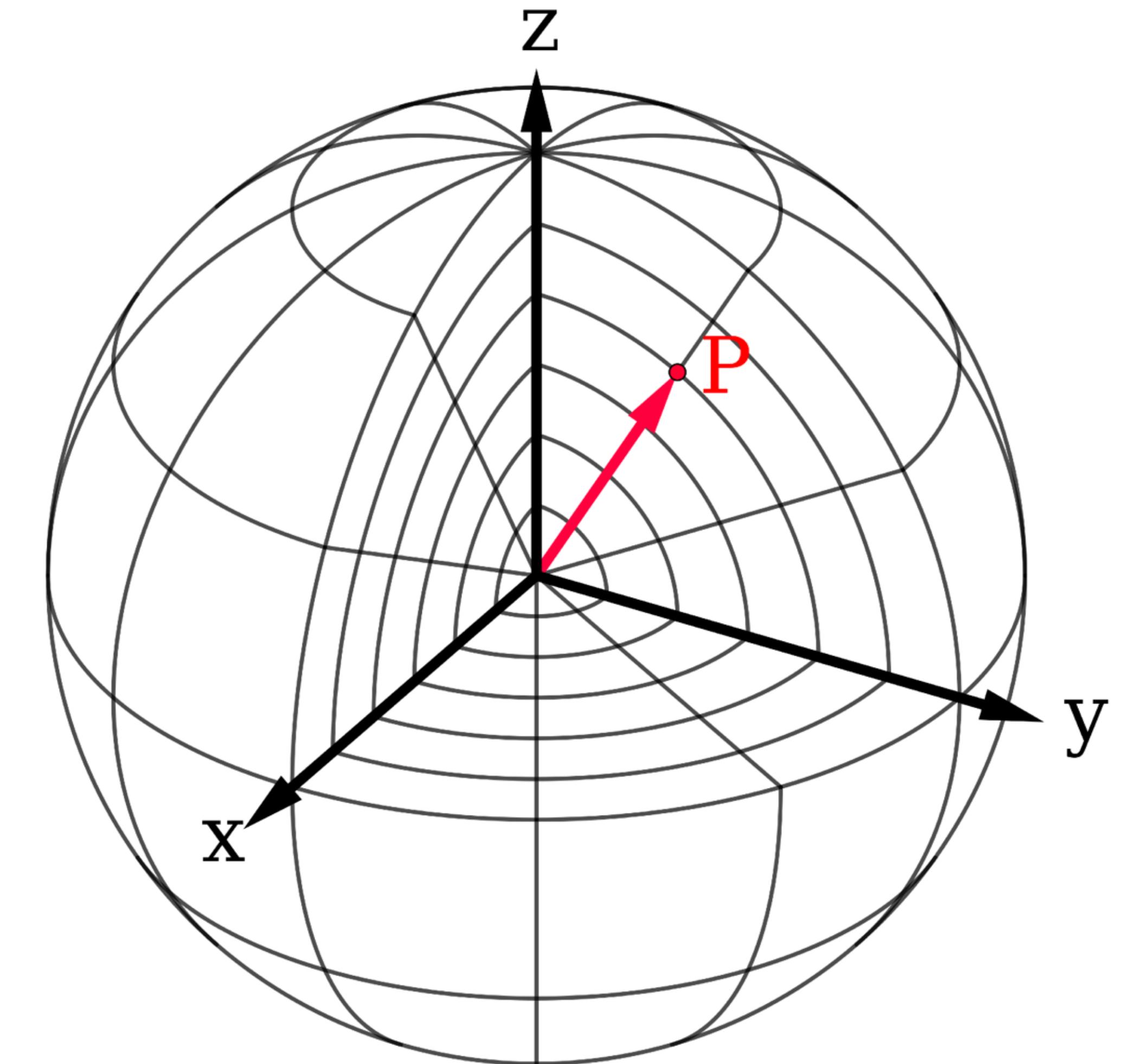
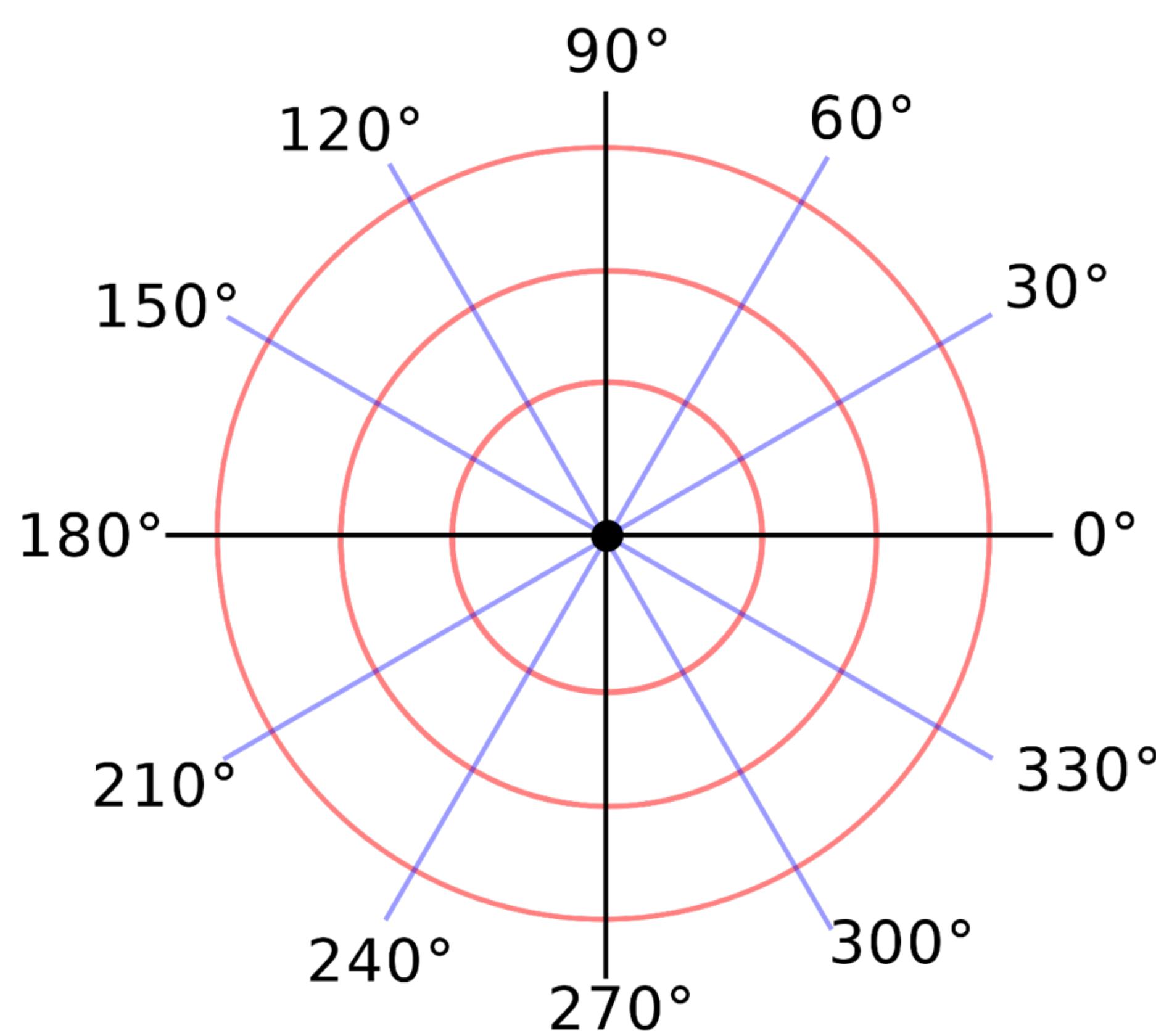
$$\langle \psi_i | H \phi_j \rangle$$

3. Fast spectral transforms

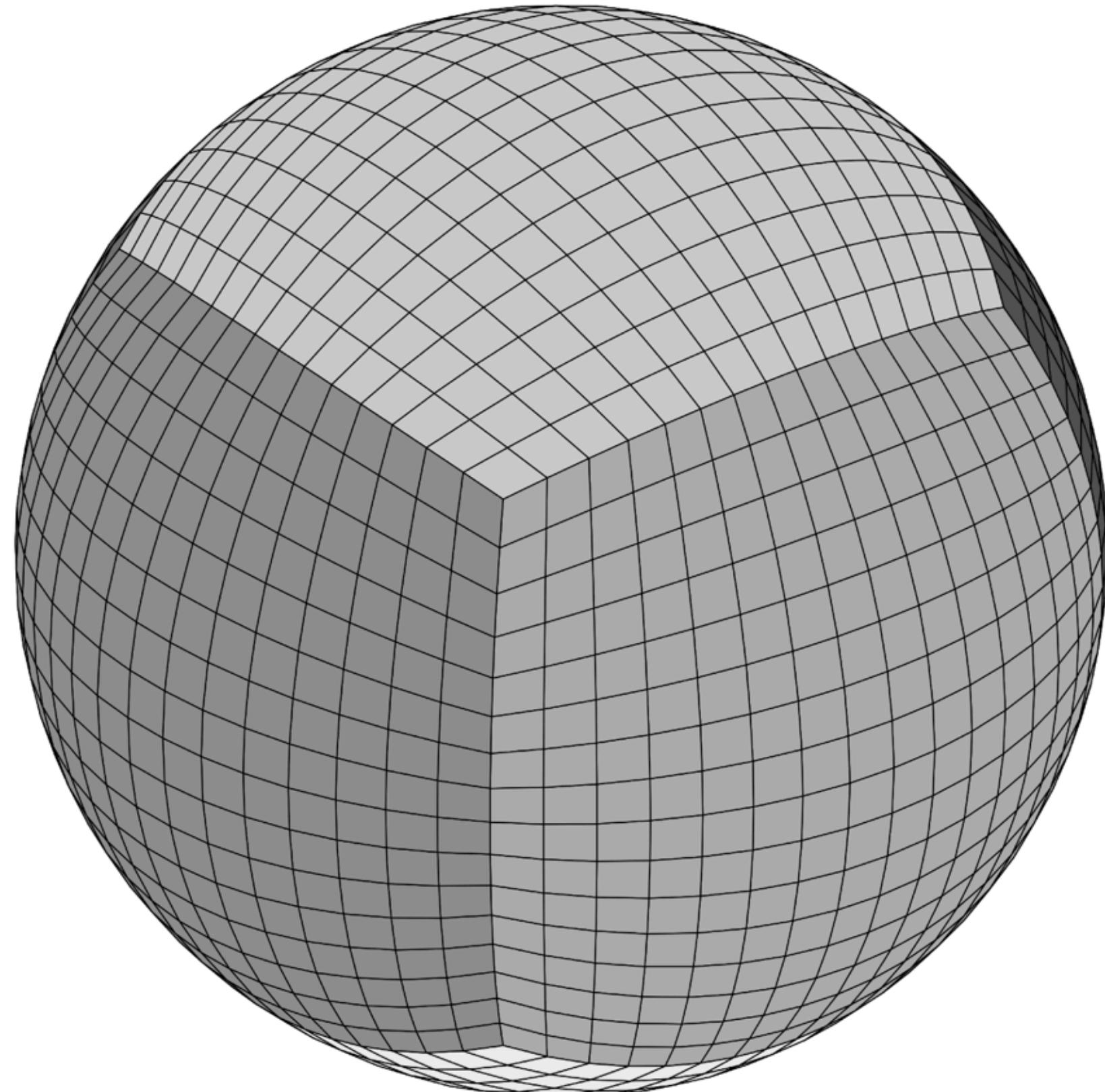
- Fast evaluation of nonlinear RHS

$$F(X)$$

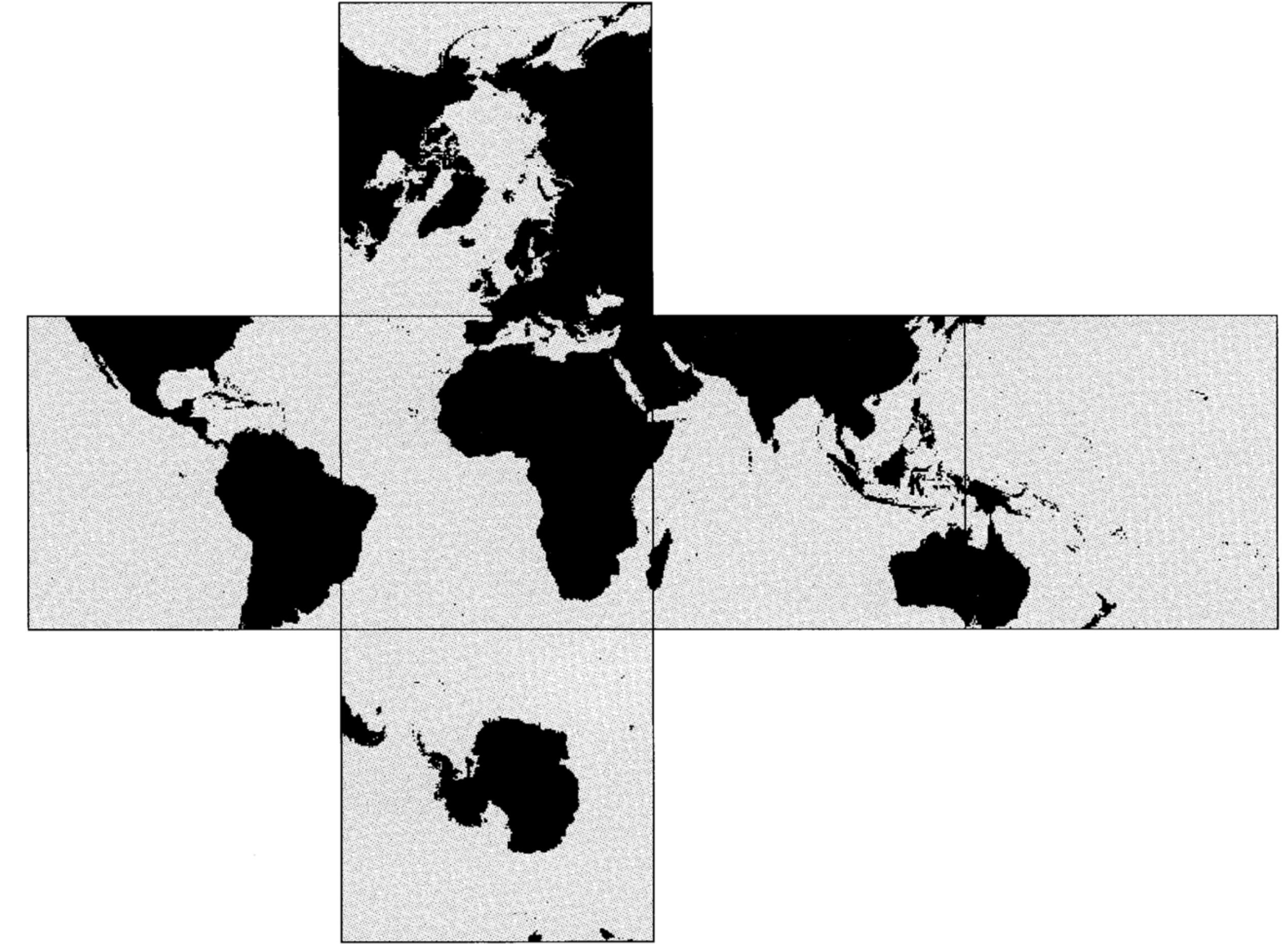
Polar & spherical coordinate singularities



The “cubed sphere” avoids the poles



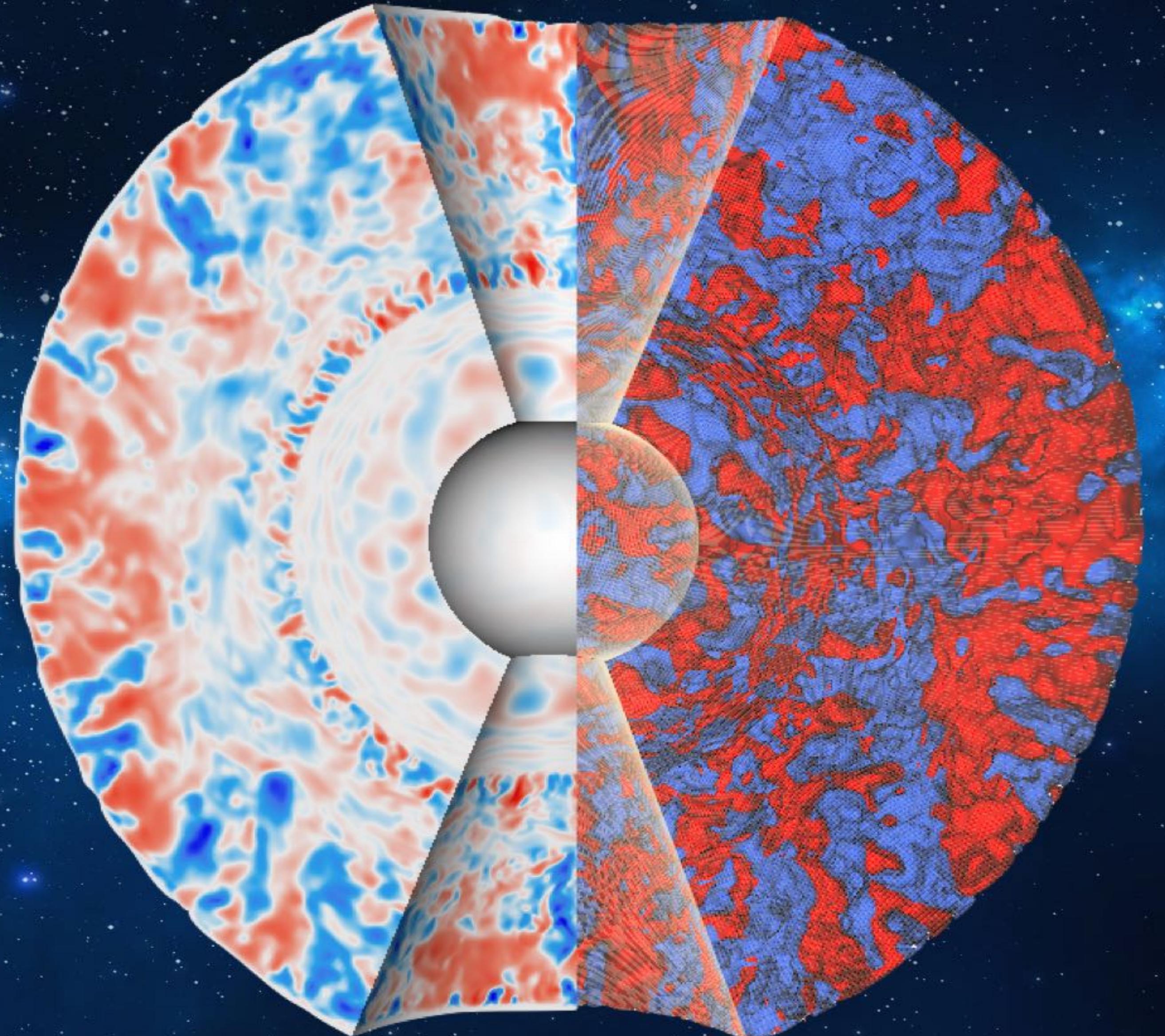
Ullrich (2014)



Rochi (1996)

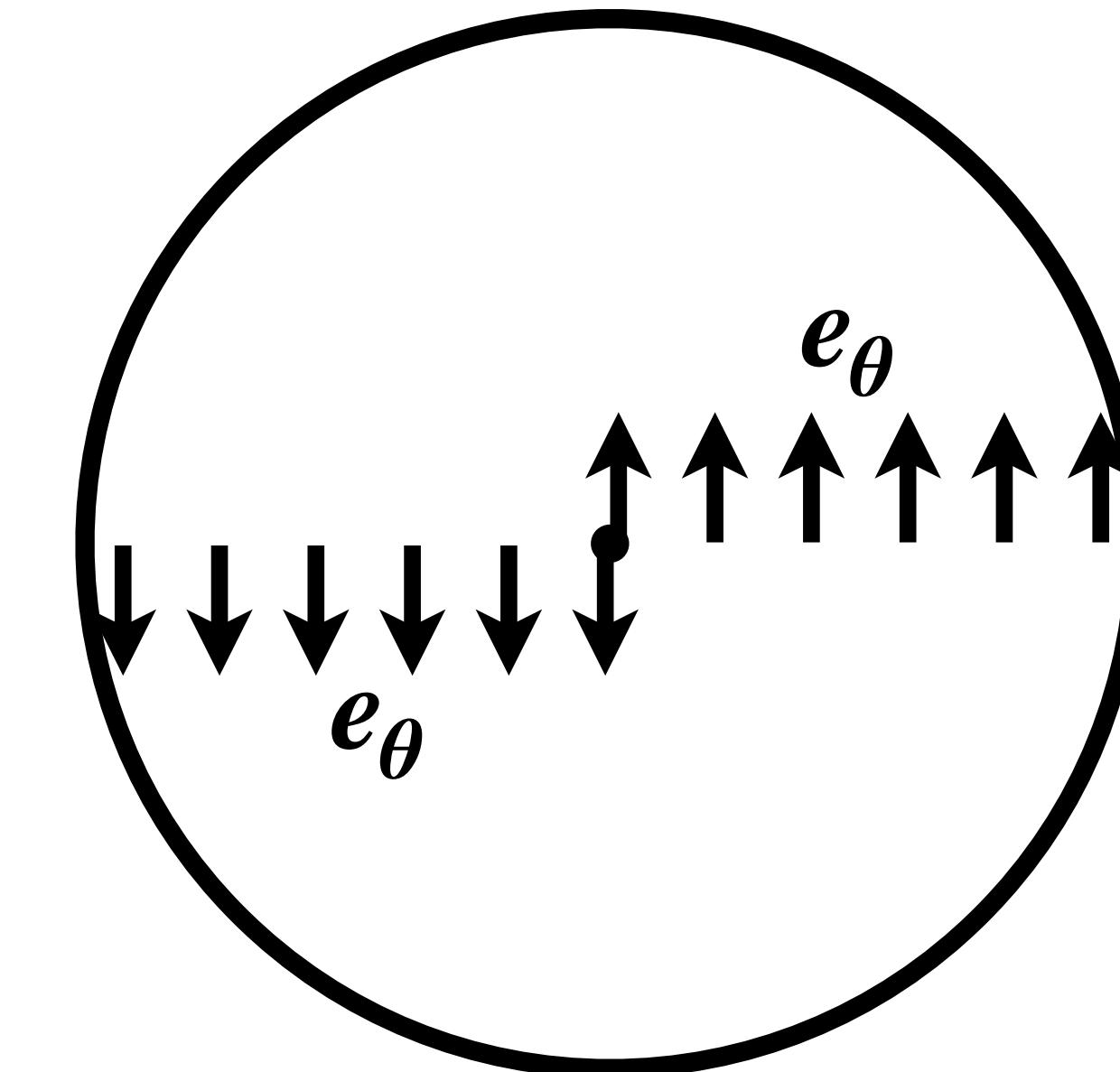
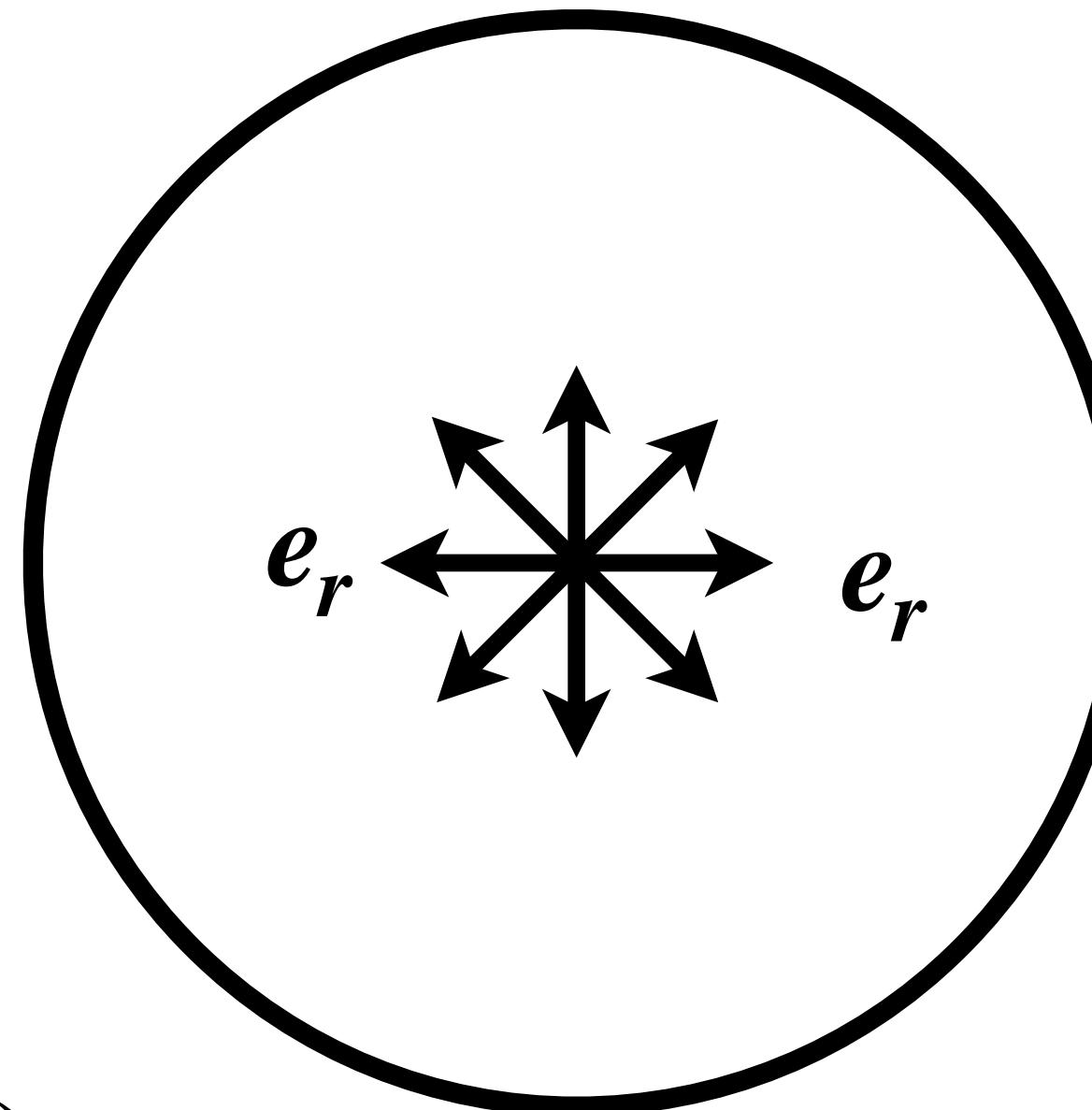
Most codes also cut out the origin

MULTIDIMENSIONAL Stellar Implicit Code



erc

Components of smooth tensors become singular



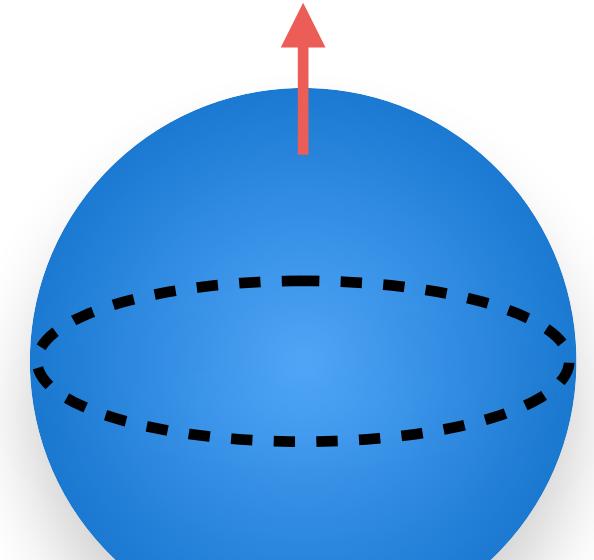
$f(x)$

$e_r \cdot \nabla f$

$e_\theta \cdot \nabla f$

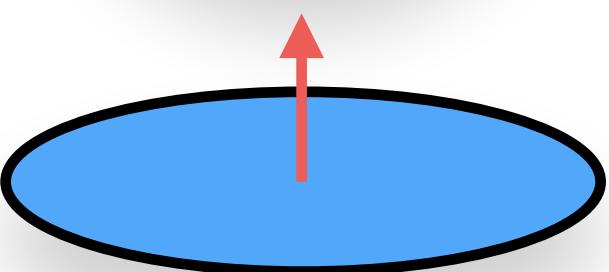


Regularity-aware curvilinear trial functions



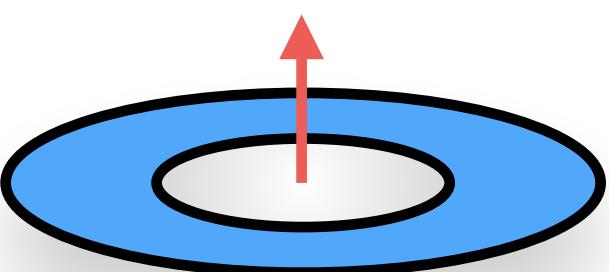
Spheres*: spin-weighted spherical harmonics
Newman & Penrose, JMP (1966)

$$Y_{l,m}^s(\phi, \theta)$$



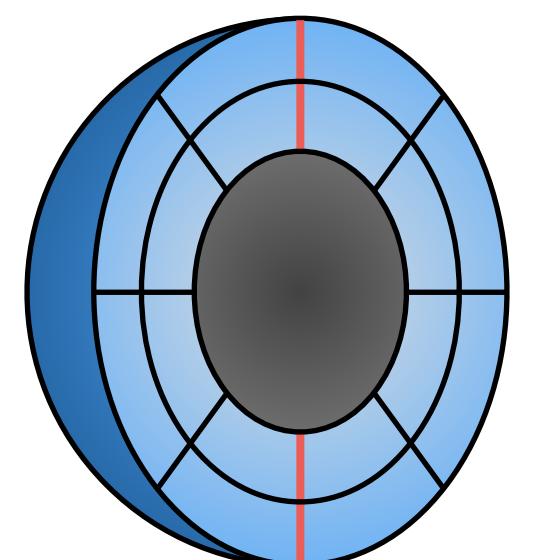
Disks: Fourier + generalized Zernike polynomials
Vasil et al (+KB)., JCP (2016)

$$e^{im\phi} r^{m+s} P_n^{(k,m+s)}(r')$$



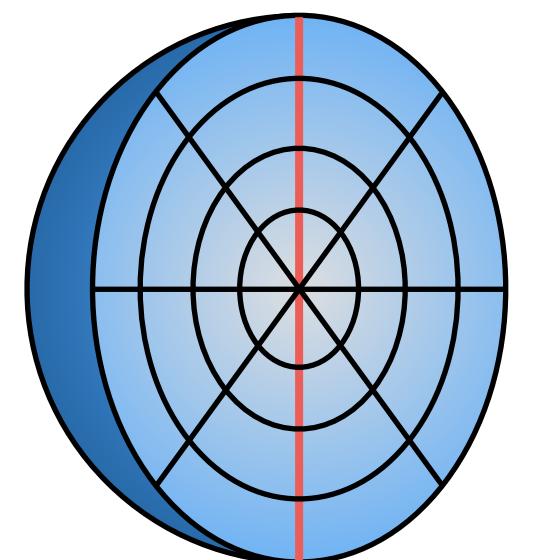
Arbitrary domains:
Spectral accuracy for arbitrary tensor fields
Sparse tensor calculus
No fast transforms*

$$e^{im\phi} r^{-k} T_n(r')$$



Spherical shells: SWSH + rational Chebyshev
Dedalus collab (+KB)., in prep.

$$Y_{l,m}^s r^{-k} T_n(r')$$



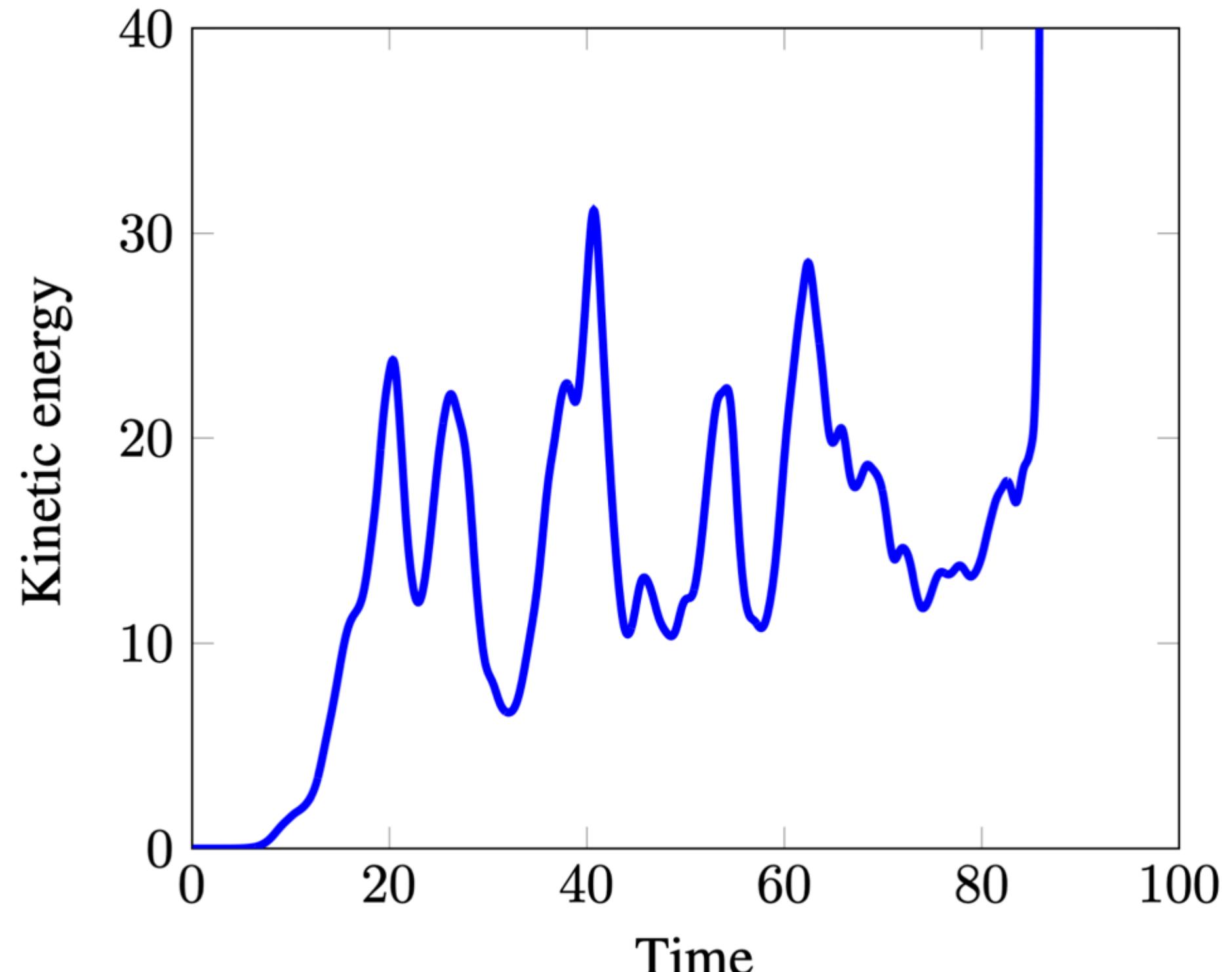
Balls: SWSH + one-sided Jacobi polynomials
Vasil et al (+KB)., JCPX (2019)

$$Y_{l,m}^s Q_l^{s,a} r^{l+a} P_n^{(k,l+a+1/2)}(r')$$

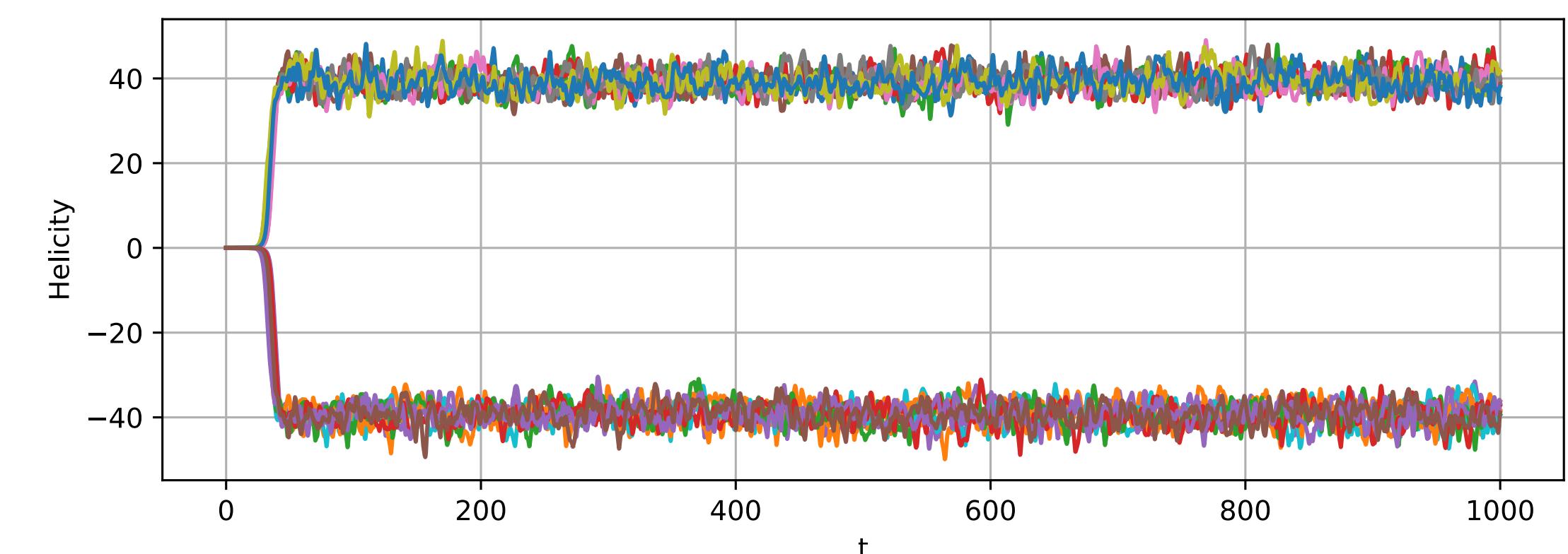
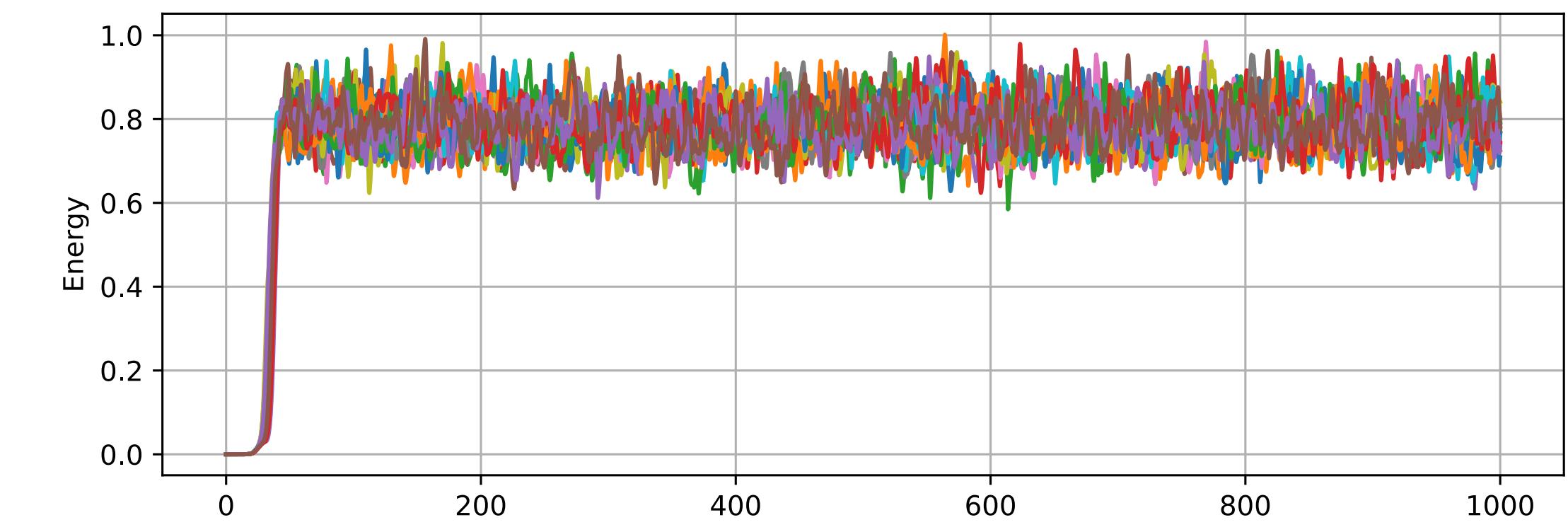
Confined active turbulence

Partial regularity (“Double Fourier”)

Boullé et al. 2021



Exact regularity (Dedalus)



w/ Nico Romeo

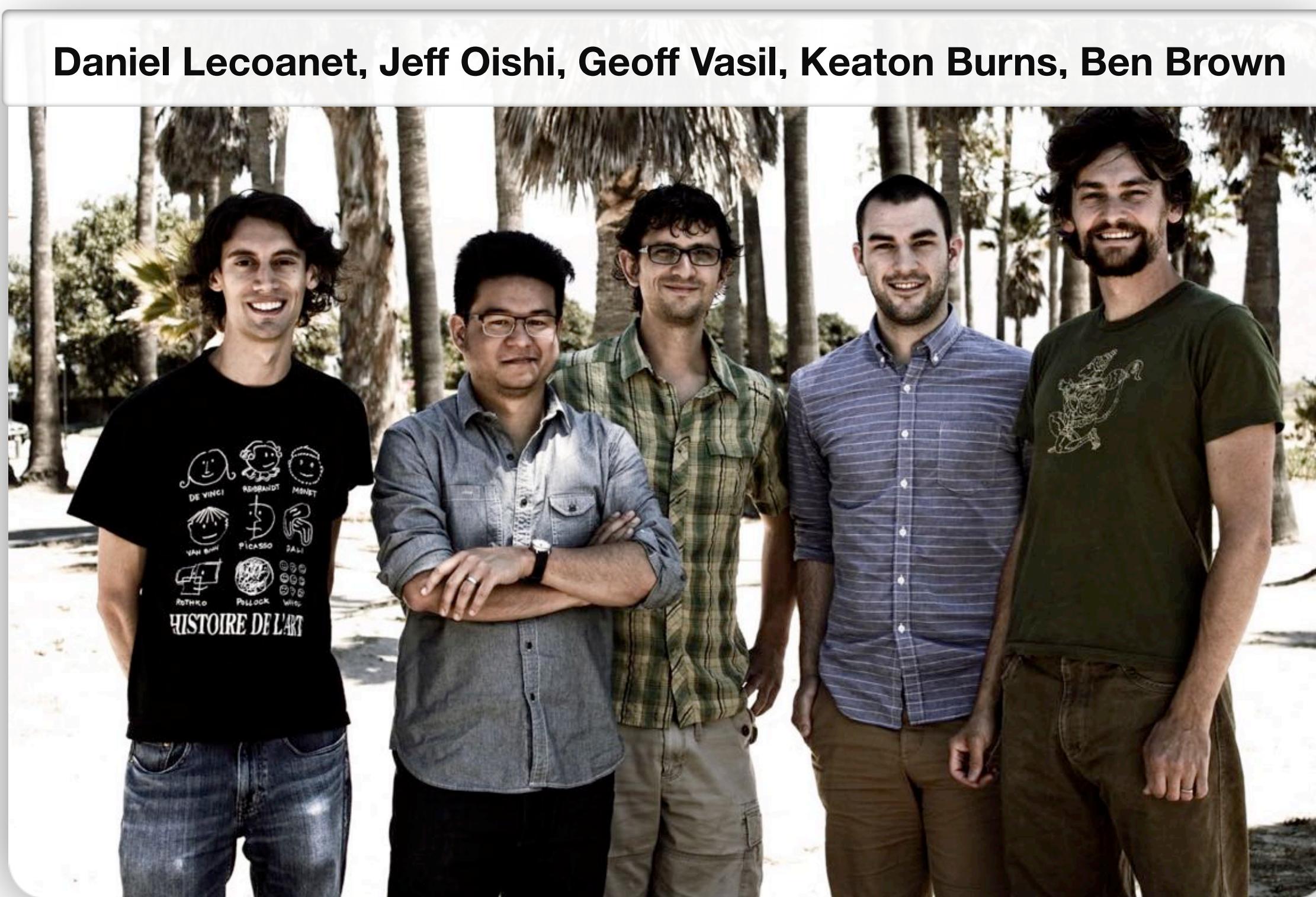
Dedalus Project

Dedalus Project

Community

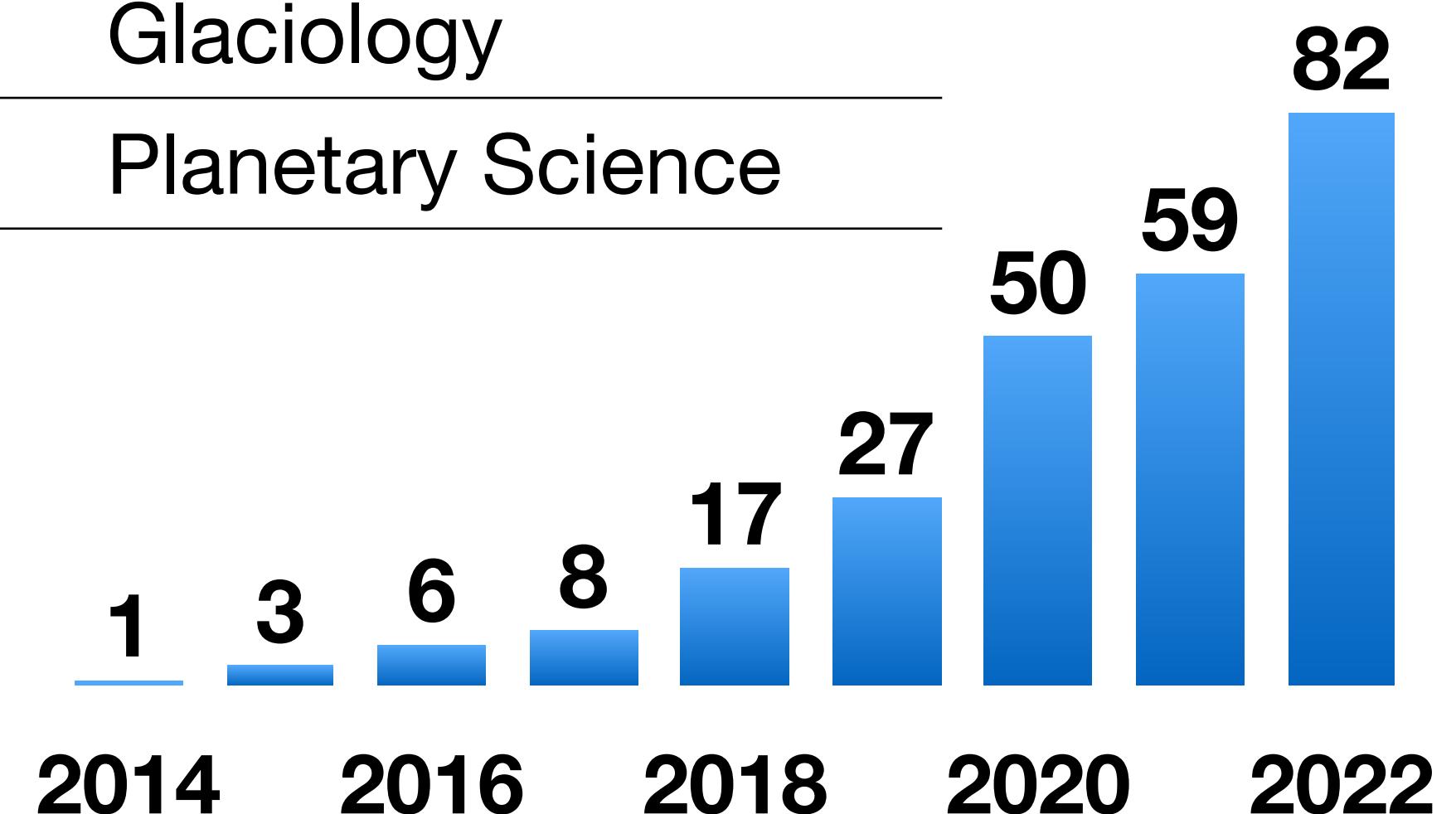
- 350+ members on user mailing list
- 19 contributors on GitHub
- NASA *High-value Open Source Tools* project

Core developers



Publications (300+)

25%	Fluid Dynamics
22%	Astrophysics
13%	Numerical analysis
10%	Plasma Physics
9%	Oceanography
6%	Atmospheric Science
5%	Biology
4%	Condensed Matter
3%	Glaciology
3%	Planetary Science



Parsing systems of equations

E.g wave equation:

$$\partial_t^2 u = c^2 \partial_x^2 u$$

$$u_t = \partial_t u$$

$$u_x = \partial_x u$$

$$\partial_t u_t = c^2 \partial_x u_x$$

Operator form:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \partial_t \begin{bmatrix} u \\ u_t \\ u_x \end{bmatrix} + \begin{bmatrix} 0 & -1 & 0 \\ \partial_x & 0 & -1 \\ 0 & 0 & -c^2 \partial_x \end{bmatrix} \begin{bmatrix} u \\ u_t \\ u_x \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Matrix form:

$$\begin{bmatrix} I & 0 & 0 \\ 0 & 0 & 0 \\ 0 & I & 0 \end{bmatrix} \partial_t \begin{bmatrix} u \\ u_t \\ u_x \end{bmatrix} + \begin{bmatrix} 0 & -I & 0 \\ D_x & 0 & -I \\ 0 & 0 & -c^2 D_x \end{bmatrix} \begin{bmatrix} u \\ u_t \\ u_x \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

General form:

$$\mathcal{M} \cdot \partial_t \mathcal{X} + \mathcal{L} \cdot \mathcal{X} = \mathcal{F}(\mathcal{X})$$

**Evaluated
pseudospectrally**

$$(D_x)_{ij} = \langle \psi_i | \partial_x \phi_j \rangle$$

$$(I)_{ij} = \langle \psi_i | \phi_j \rangle$$

**Maximize
sparsity**

Supported problem types

Initial value problems:

$$\mathcal{M} \cdot \partial_t \mathcal{X} + \mathcal{L} \cdot \mathcal{X} = \mathcal{F}(\mathcal{X})$$

Nonlinear boundary value problems:

$$\mathcal{L} \cdot \mathcal{X} = \mathcal{F}(\mathcal{X})$$

Eigenvalue problems:

$$\sigma \mathcal{M} \cdot \mathcal{X} + \mathcal{L} \cdot \mathcal{X} = 0$$

Pseudospectra:
(Eigentools package)

$$\sigma \mathcal{M} \cdot \mathcal{X} + (\mathcal{L} + \mathcal{N}) \cdot \mathcal{X} = 0, \quad \|\mathcal{N}\| \leq \epsilon$$

Vector-invariant PDE specification

```
# Bases
coords = SphericalCoords('phi', 'theta', 'r')
dist = Distributor(coords, mesh=64)
basis = SphereBasis(coords, shape=(1024, 512))

# Fields
p = ScalarField(dist, basis)
u = VectorField(dist, basis)

# Problem
problem = IVP(variables=[p, u])
problem.parameters['Re'] = 1e4
problem.add_equation("dt(u) - Lap(u)/Re + grad(p) = - u@grad(u)")
problem.add_equation("div(u) + integ(p) = 0")

# Solver
solver = problem.build_solver(timestepper='RK443')
solver.step(dt=1e-3)
```

Automatically MPI parallelized

No reduction to scalar potentials

Extends to compressible flows

LHS parsed into sparse system
for implicit integration of
stiff terms & constraints

Incompressible hydrodynamics

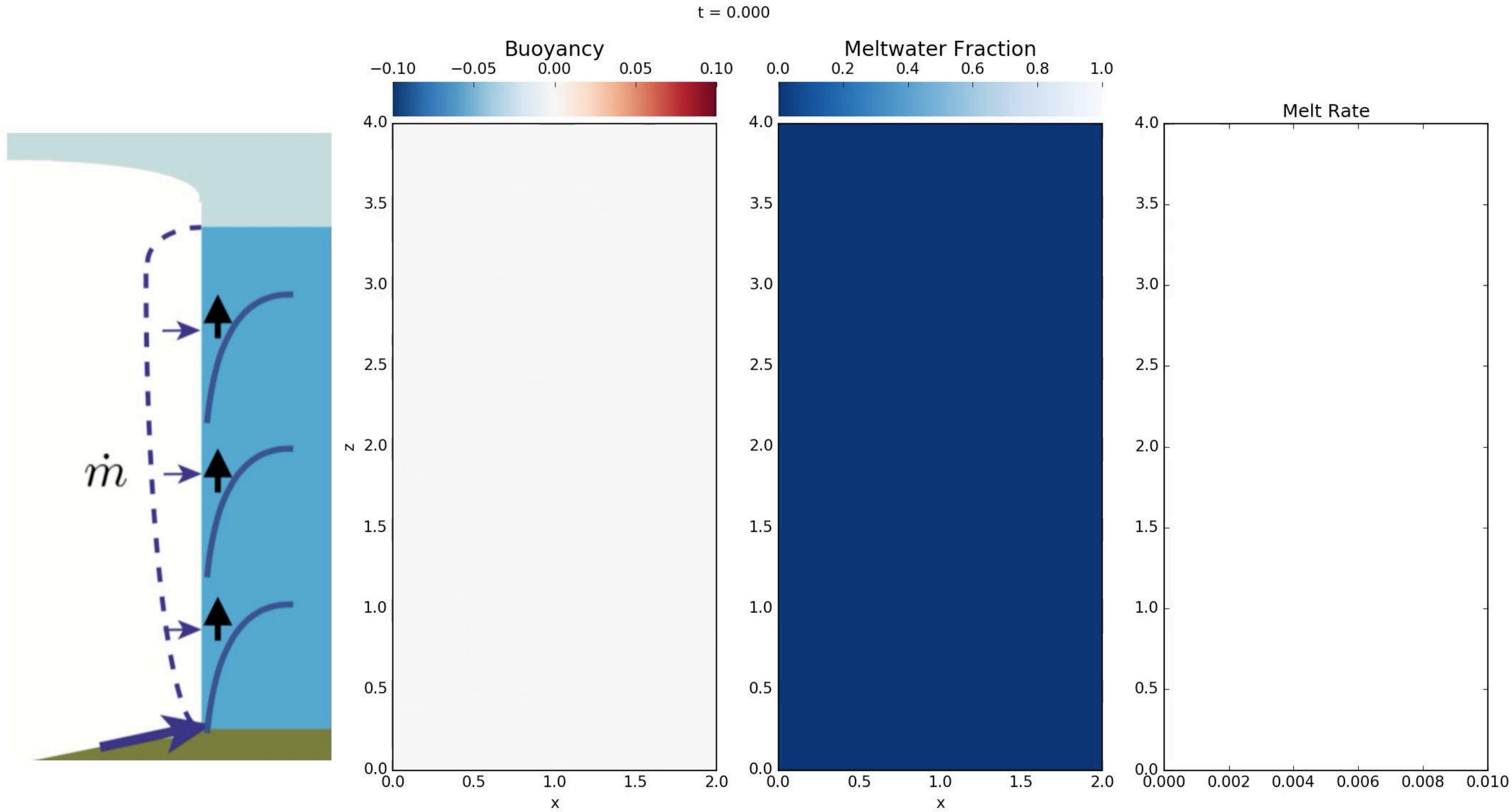
$$\mathcal{M} \cdot \partial_t \mathcal{X} + \mathcal{L} \cdot \mathcal{X} = \mathcal{F}(\mathcal{X})$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \partial_t \begin{bmatrix} u \\ v \\ p \end{bmatrix} + \begin{bmatrix} -\nu \nabla^2 & 0 & \partial_x \\ 0 & -\nu \nabla^2 & \partial_y \\ \partial_x & \partial_y & 0 \end{bmatrix} \begin{bmatrix} u \\ v \\ p \end{bmatrix} = \begin{bmatrix} -\vec{u} \cdot \nabla u \\ -\vec{u} \cdot \nabla v \\ 0 \end{bmatrix}$$

Directly coupled formulation:

- Explicitly enforce divergence constraint
- Pressure determined as Lagrange multiplier
- No splitting / pressure boundary conditions
- Allows for high-order DAE timesteppers

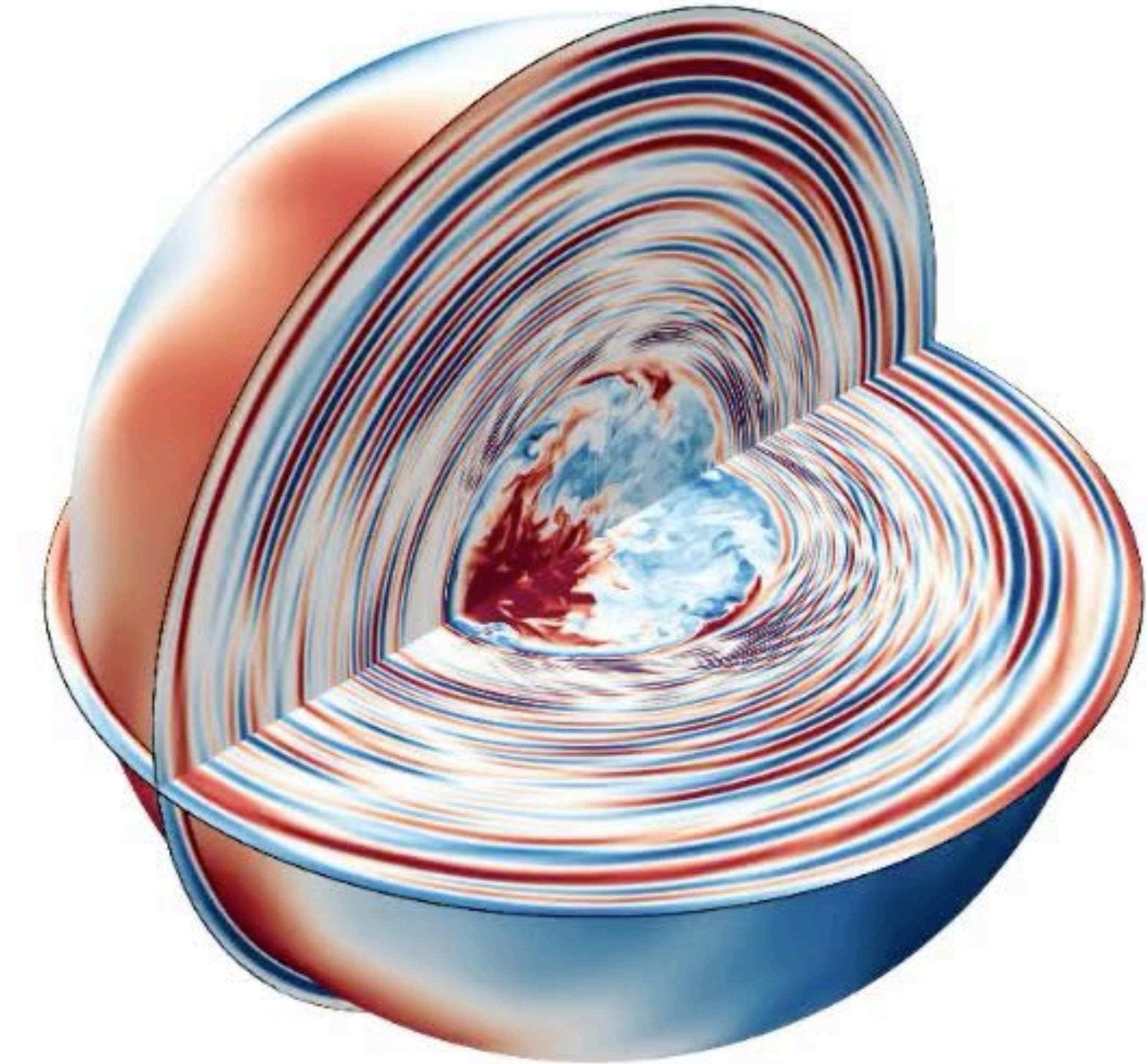
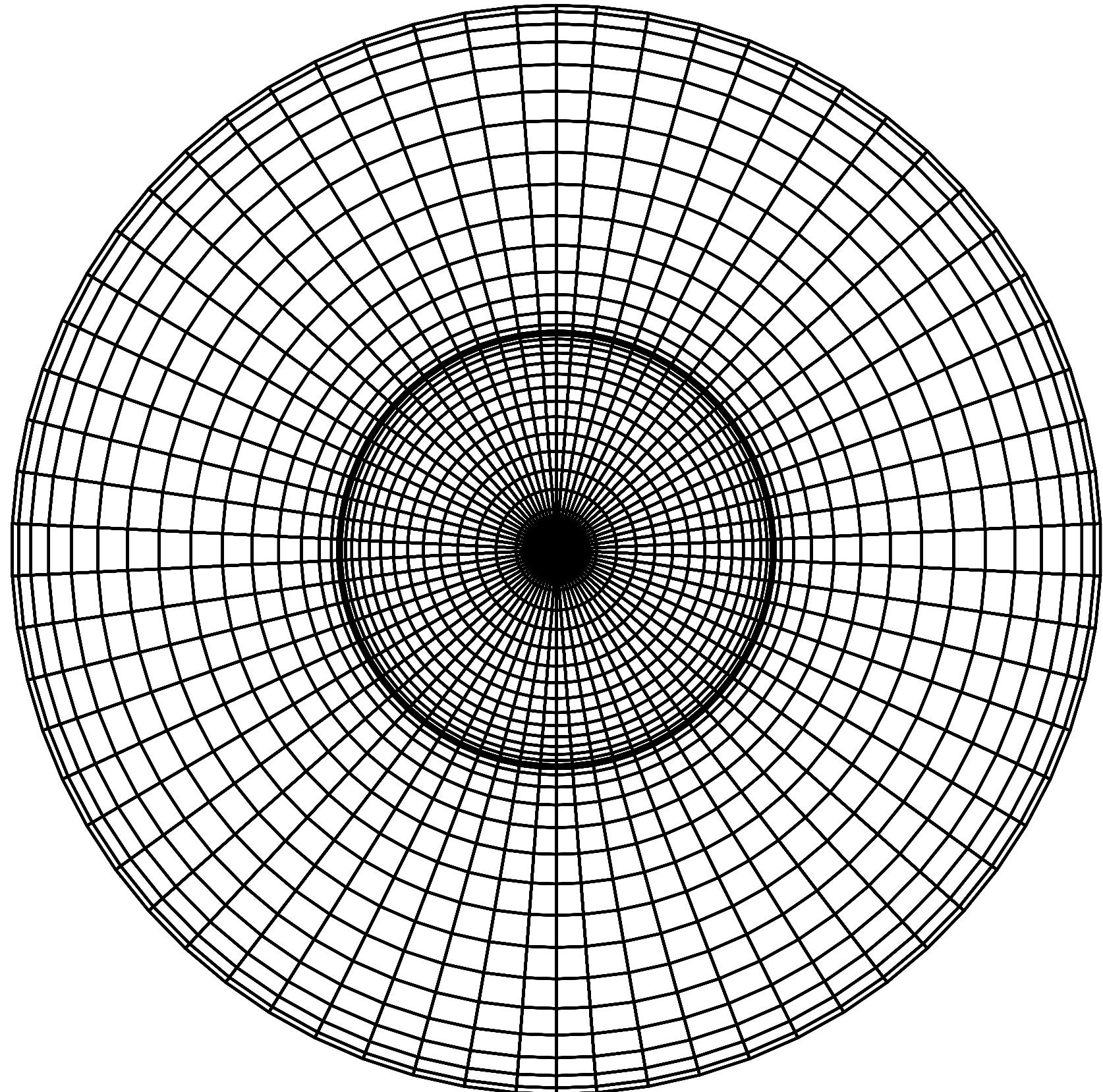
Turbulent enhancement of glacier melting



Burns (2018)

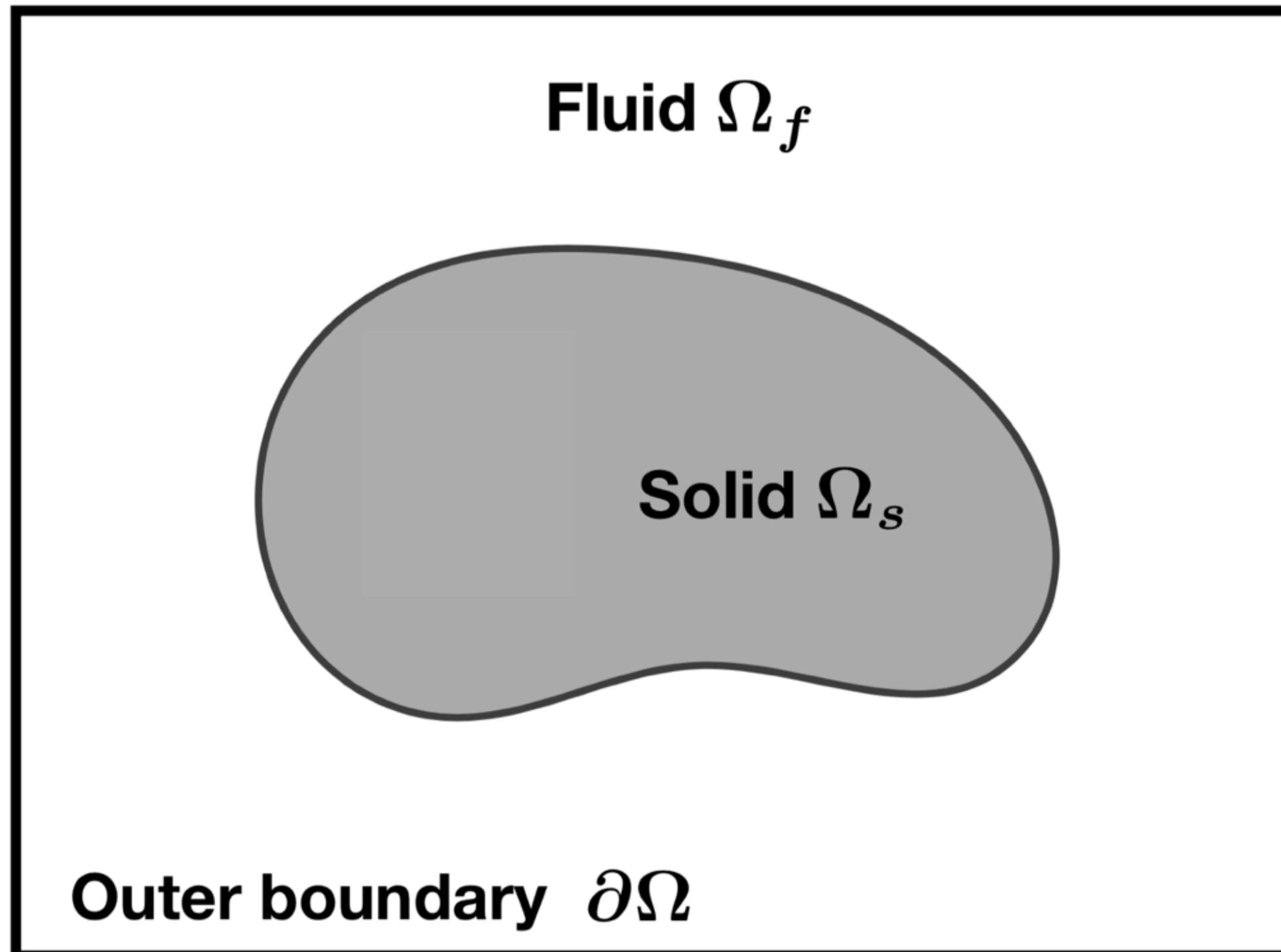
High- p spherical spectral elements

- Stacked ball and spherical shell bases
- Resolves internal/material boundaries



w/ Evan Anders

Immersed boundary methods



Volume penalization:

Damp solution to reference

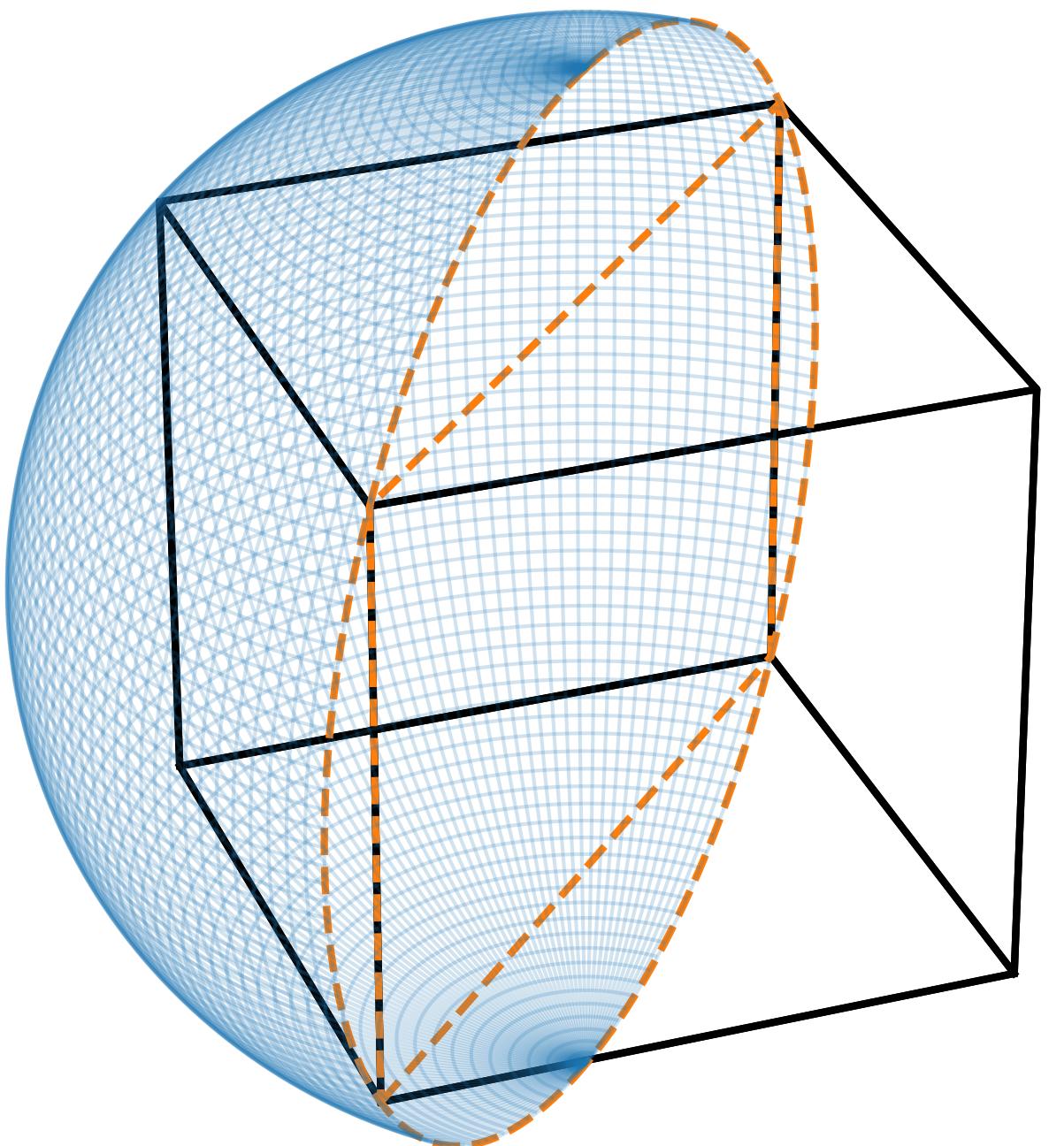
$$\partial_t \vec{u} = \dots - \gamma M(\vec{x})(\vec{u} - \vec{u}_{\text{ref}})$$

Dedalus: easily add forcing, modify mask

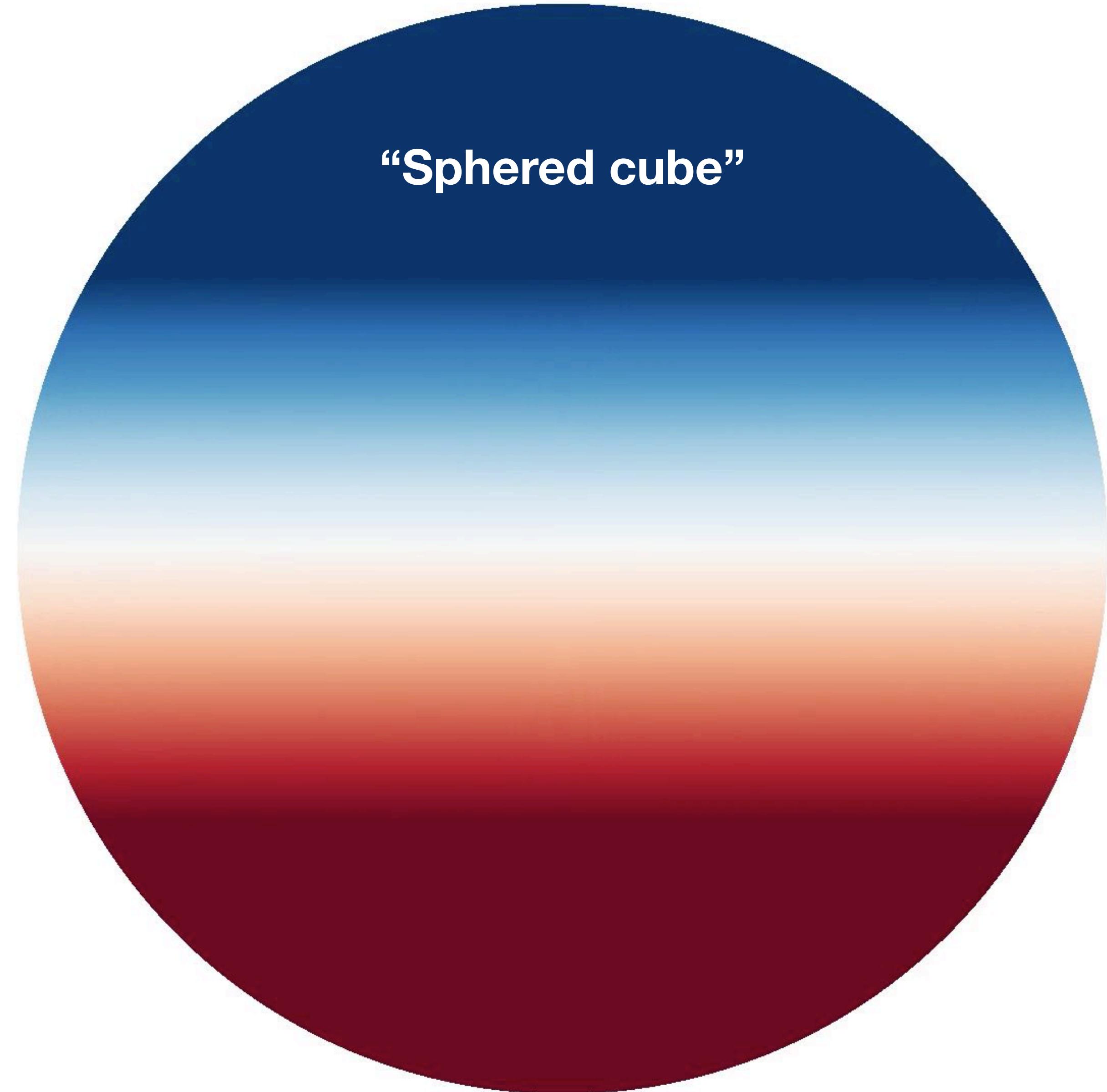
Recent work: optimize mask/damping for 2nd order convergence (*Hester et al. 2020*)

Convection in a cube

Immersed boundaries



“Sphered cube”



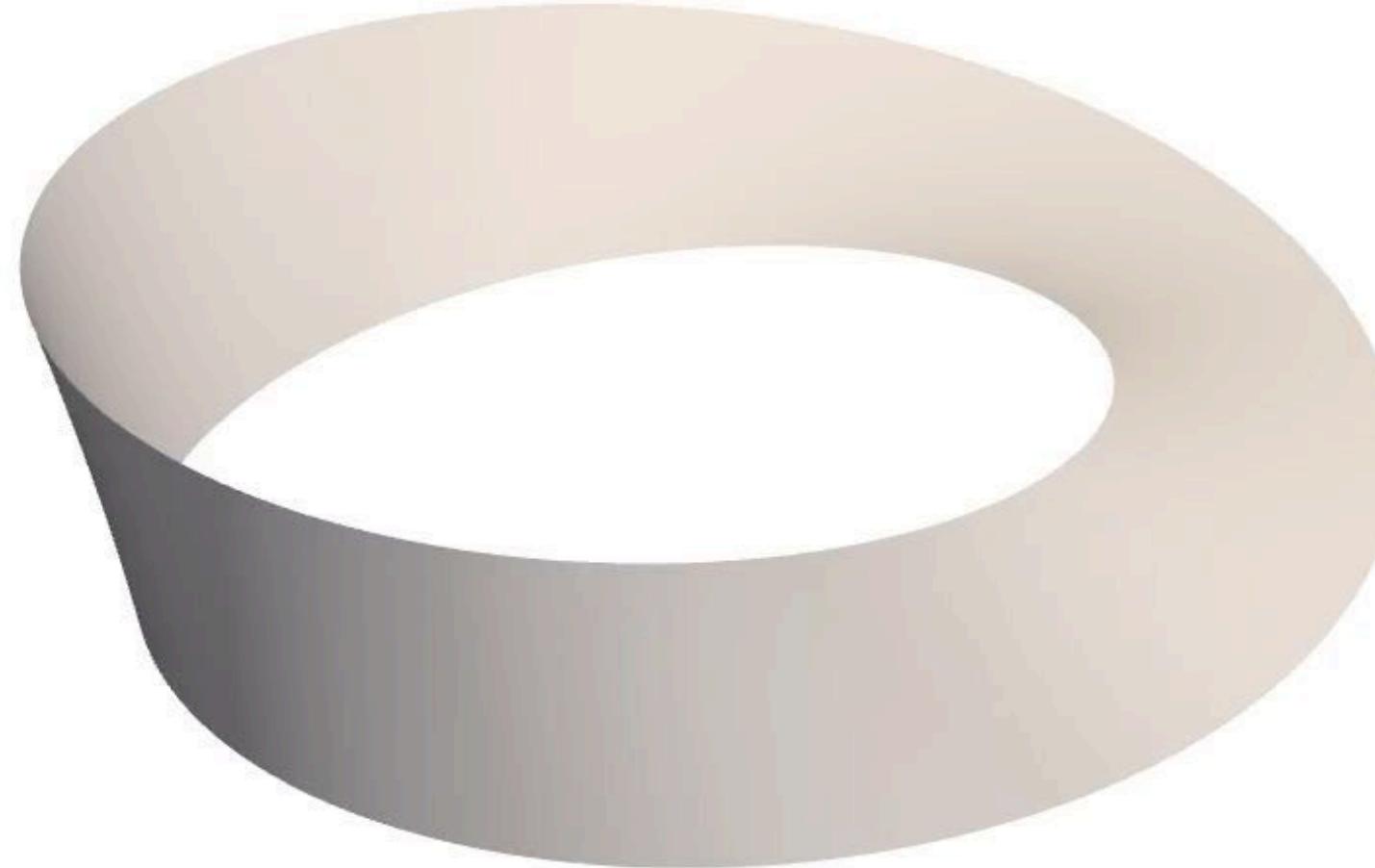
Quantum graphs

$$i\partial_t\psi + \frac{1}{2}\partial_x^2\psi = -|\psi|^2\psi$$



Non-orientable & symplectic manifolds

Möbius strip



Klein bottle



Real projective plane



Goals:

- Double-cover domains with exact symmetries
- Symplectic manifolds / phase-space simulations

