

# Axiomatic formulation of Topological Quantum Field Theory

From the mathematical point of view we expect that all quantum field theories keep

- general features of quantum theory (probabilistic)
- topological framework of spacetime

Both features are embraced by the precise notion of a topological quantum field theory.

M. Atiyah (1988) gave a formal mathematical framework to develop quantum theories in physics.

# Axiomatic formulation of Topological Quantum Field Theory

## Definition

*A topological quantum field theory (TQFT) in dimension  $d + 1$  consist of the following data:*

*Fixed an integer  $d$ , consider smooth oriented manifolds  $M$  of dimension  $d + 1$  (with boundary) and also smooth closed oriented manifolds  $X$  of dimension  $d$ .*

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- *To each  $X$  we associate functorially a **finite-dimensional complex vector space**  $\mathbf{Z}(X)$ .*
- *To each  $M$ , whose boundary is  $X$  we associate a **vector**  $\mathbf{Z}(M) \in \mathbf{Z}(X)$ .*

# Axiomatic formulation of Topological Quantum Field Theory

These data are subject to the following properties (**axioms**):

- 1) An orientation preserving diffeomorphism  $f : X \rightarrow X'$  induces an isomorphism

$$\mathbf{Z}(f) : \mathbf{Z}(X) \rightarrow \mathbf{Z}(X')$$

and if  $g : X' \rightarrow X''$  then

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- 2)  $\mathbf{Z}(X^*) = \mathbf{Z}(X)^*$  where  $X^*$  is  $X$  with opposite orientation and  $\mathbf{Z}(X)^*$  denotes the dual vector space.

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- 3)  $\mathbf{Z}$  is multiplicative.

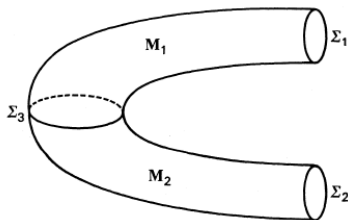
Thus, for disjoint unions

$$\mathbf{Z}(X_1 \cup X_2) = \mathbf{Z}(X_1) \otimes \mathbf{Z}(X_2).$$



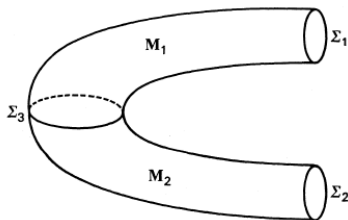
# Axiomatic formulation of Topological Quantum Field Theory

Moreover if  $\partial M_1 = X_1 \cup X_3$ ,  $\partial M_2 = X_2 \cup X_3^*$  and  $M = M_1 \cup_{X_3} M_2$  is the manifold obtained by identification of the common  $X_3$  – *component*.



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$$Z(\Sigma_1) \otimes Z(\Sigma_3) \otimes Z(\Sigma_3)^* \otimes Z(\Sigma_2) \rightarrow Z(\Sigma_1) \otimes Z(\Sigma_2)$$

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Note that when  $M$  is a closed  $d$ -dimensional manifold so that  $\partial M = \emptyset$ , then

$$\mathbf{Z}(\mathbf{M}) \in \mathbf{Z}(\emptyset) = \mathbb{C}$$

That means,  $\mathbf{Z}(\mathbf{M})$  is a **numerical invariant** of  $M$ .

# State sum model as a 3D TQFT of gravity

Einstein equations (movement equations) can be derived through minimizing the action  $S$ :

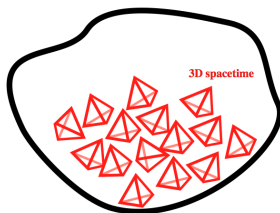
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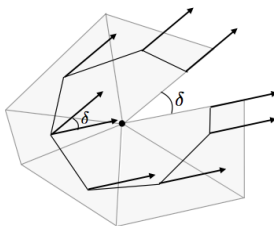
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1961 Regge gave a discrete formulation of general relativity using triangulated manifolds.



# State sum model as a 3D TQFT of gravity

Regge showed that the curvature of a triangulated  $n$  dimensional manifold is encoded in the  $(n - 2)$  skeleton.



The discrete form of the action  $S$  from which Einstein field equations are derived is given by

$$S_R = \sum |\sigma^i(T)| \varepsilon_i$$



# State sum model as a 3D TQFT of gravity

In quantum mechanics the action is replaced by a **partition function  $Z$** :

$$Z = \int e^{iS} D(x)$$

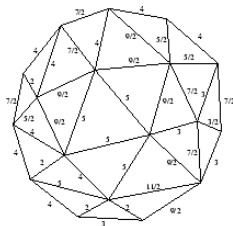
Given a manifold  $M$ ,  $Z(M)$  obtained from the TQFT will have the physical **meaning of the partition function**.

# State sum invariants

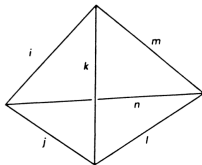
In 1991 Turaev-Viro developed a 3 dimensional TQFT of gravity called the **state sum model**.

## Definition

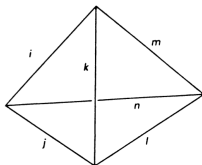
*Given a 3 dimensional manifold and a triangulation, a **state** is an assignment of an irreducible representation of  $SU(2)$  to each edge of the triangulation. This are labeled by a non-half integer parameter  $j$ .*



# State sum invariants



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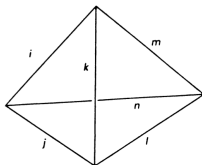


## Definition

The **weight** of the state is defined by

$$W = \prod_{\text{interior edges}} (-1)^{2j}(2j+1) \prod_{\text{interior triangles}} (-1)^{j_1+j_2+j_3} \prod_{\text{tetrahedra}} \begin{Bmatrix} j_1 & j_2 & j_3 \\ j_4 & j_5 & j_6 \end{Bmatrix}$$

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The **state sum** (partition function) is obtained by summing over all values of the variables, subject to fixed values on the boundary.

$$\mathbf{Z}(M) = \Sigma W$$