

# People

- UGent

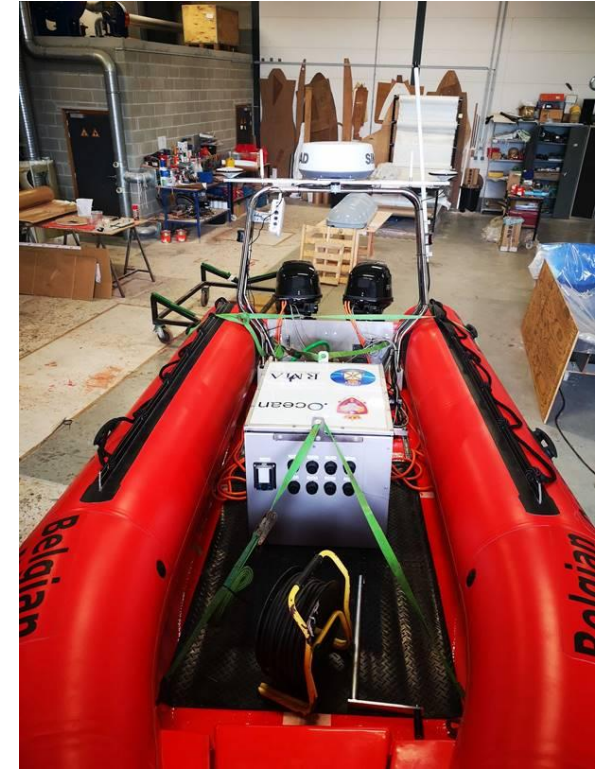
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- RMA

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- MarSur: Benoit Pairet [Benoit.Pairet@mil.be](mailto:Benoit.Pairet@mil.be)
- VR – SLAM: Charles Hamesse [Charles.Hamesse@mil.be](mailto:Charles.Hamesse@mil.be)

# Timeline

- Master thesis:
  - Oct 2021 – end of May 2022
  - Midterm presentation in November – January (!?)
    - 22nd Oct: work plan
    - 9th June: submit thesis
    - 29 June or 1st July: thesis defense
  - December – January: exam time
- Project
  - Data acquisition: planned for October (TBC)
    - ZED Mini: IMU, Stereo cameras
    - Data acquisition hardware: mid October (integrate with MarSur USV ?)
  - Problem formulation, workplan, [literature study]: 22nd October
  - Required skills (Python, Pytorch, RNN, time-series analysis ...): January
  - Work on problem: March
  - Writing thesis: May



# Motivation

- Estimate and predict the ship motion from IMU – and stereo vision
  - MarLand:
    - Define the optimum moment for the drones to land on the ship
      - Less impact on the drone
  - MarSur (!?):
    - Stabilize the sensor inputs
      - Filter out the ship movement
    - Horizon detection, could be used for control USV
- State prediction problem
  - Given current states (and states in the past): IMU data
  - Given latent space (images) of future action/input: images of incoming waves
  - Predict the states in future
  - Stock market example

# Problem

- Inputs:
  - Sequence of IMU data + stereo images in the timeframe  $(t-\Delta t_1, t)$ 
    - Other sensor maybe used – wind sensor, thrust of the USV
- Output
  - Ship motion: altitude ( $z$ ), roll, pitch, yaw (angles and angular velocities) in the time  $(t, t+\Delta t_2)$
- Challenges:
  - Estimation + prediction for time series sequences (visual features: water/waves)
  - Define  $\Delta t_1$  and  $\Delta t_2$
  - Realtime

# Way of Working

- Bi-weekly meeting with small presentation
  - Status/Result of given tasks (from previous meeting)
  - Issues
  - Plan for next 2 weeks
- 2 tasks will be given after each meeting
- Use Slack as communication channel
  - New ideas
  - Issues
  - Q&A