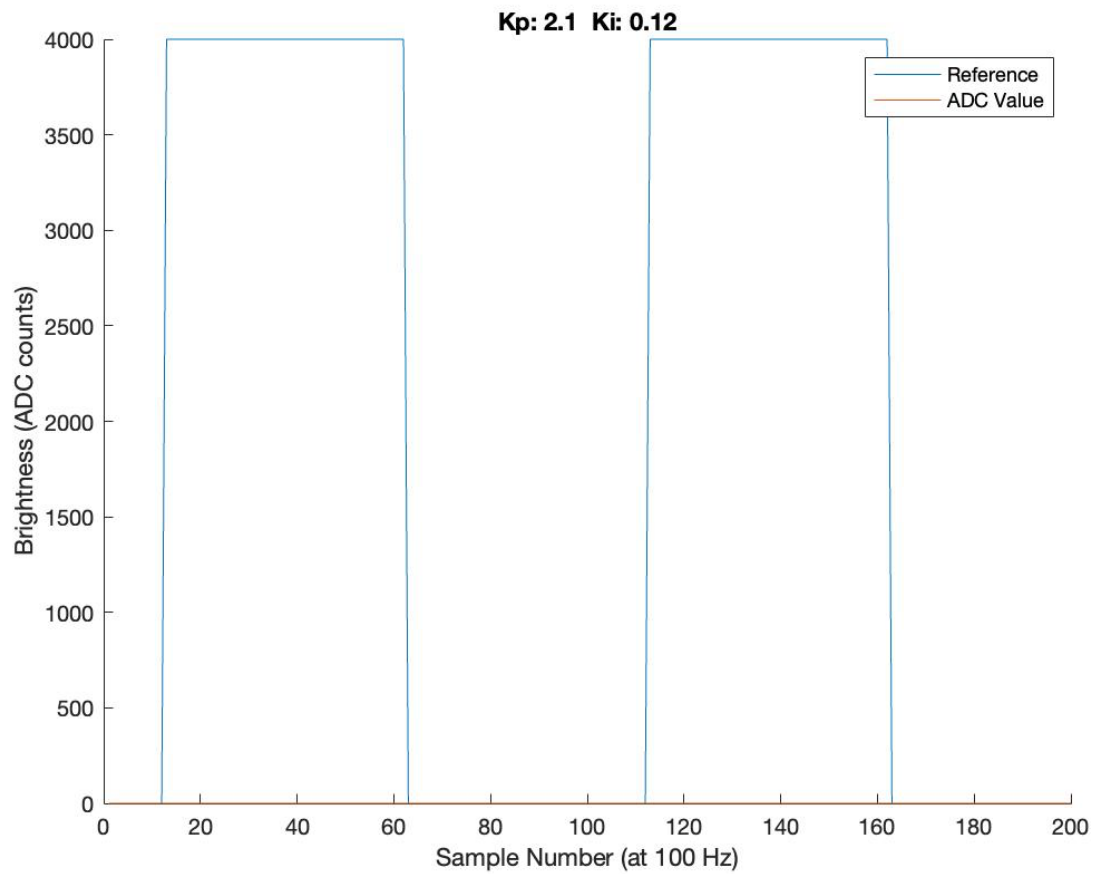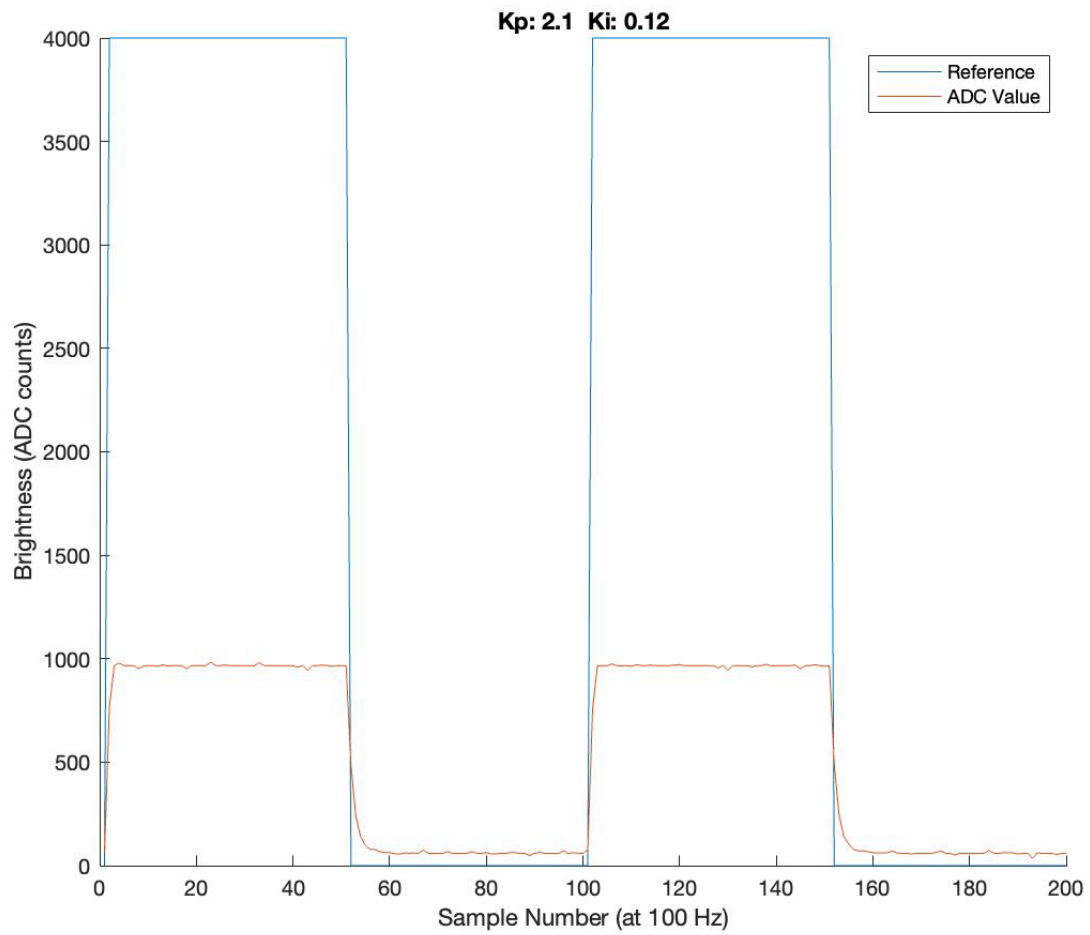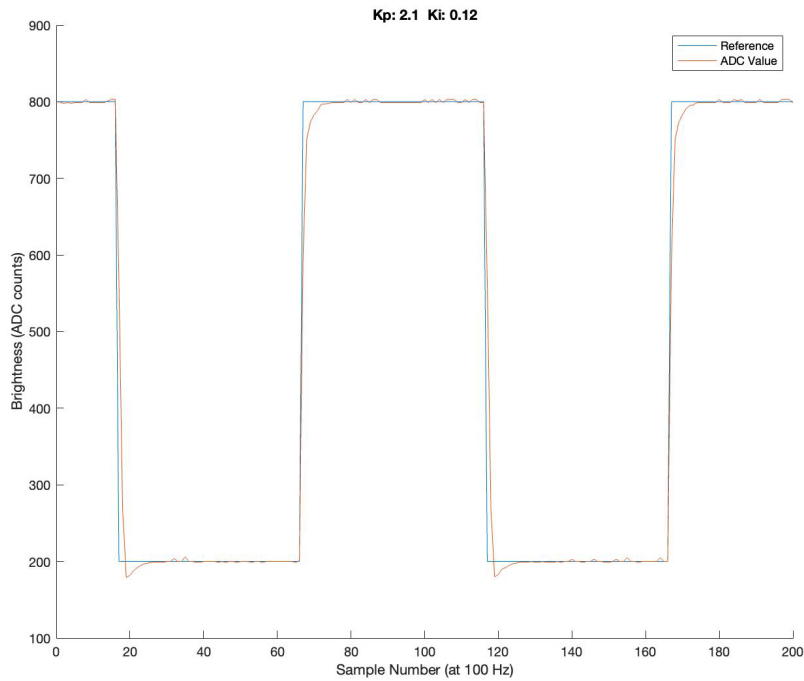HW 7
Lance Go
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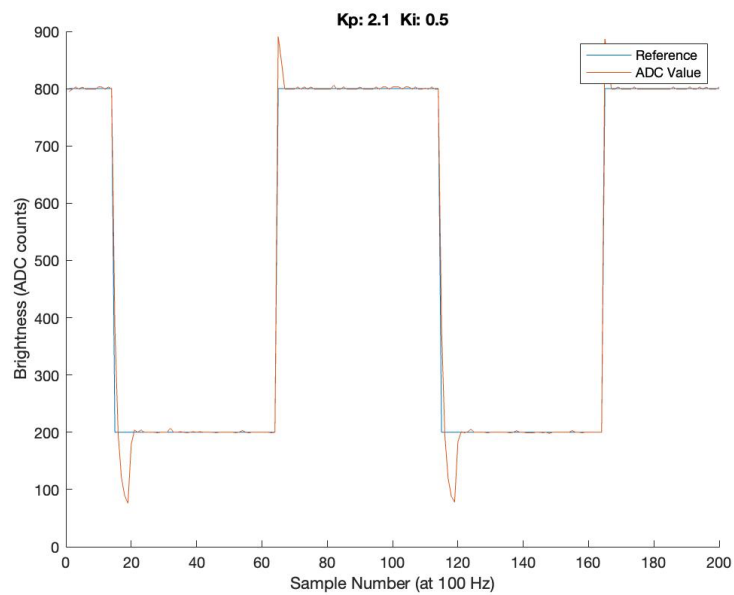## 24.5) Proof that there is communication between MATLAB and the PIC in my program

24.7) ADC value. Ignore the values for Kp and Ki, they have no effect on the ADC value

24.8) Tuning for the perfect response:

Kp=2.1 Ki=0.12, Follows the signal very closely

Kp=2.1 Ki=0.5, Plot that resembles figure 24.1 closer, but has some stuttering in the LED