

$$I = \sum_i m_i r_i^2$$

$$I = \int r^2 dm$$

$$x_{\text{cm}} = \frac{1}{M} \sum_i x_i m_i$$

$$I = I_{\text{cm}} + Md^2$$

$$K_{\text{rot}} = \frac{1}{2} I \omega^2$$

$$\tau = F_{\perp} r$$

$$\tau = F r_{\perp}$$

$$x_{\text{cm}} = \frac{1}{M} \int x dm$$

$$I = \sum_i m_i r_i^2 \quad [6]$$

$$I = \int r^2 dm \quad [4]$$

$$x_{\text{cm}} = \frac{1}{M} \sum_i x_i m_i \quad [8]$$

$$I = I_{\text{cm}} + M d^2 \quad [2]$$

$$[7] \quad K_{\text{rot}} = \frac{1}{2} I \omega^2$$

$$\tau = F_{\perp} r \quad [5]$$

$$\tau = F r_{\perp} \quad [1]$$

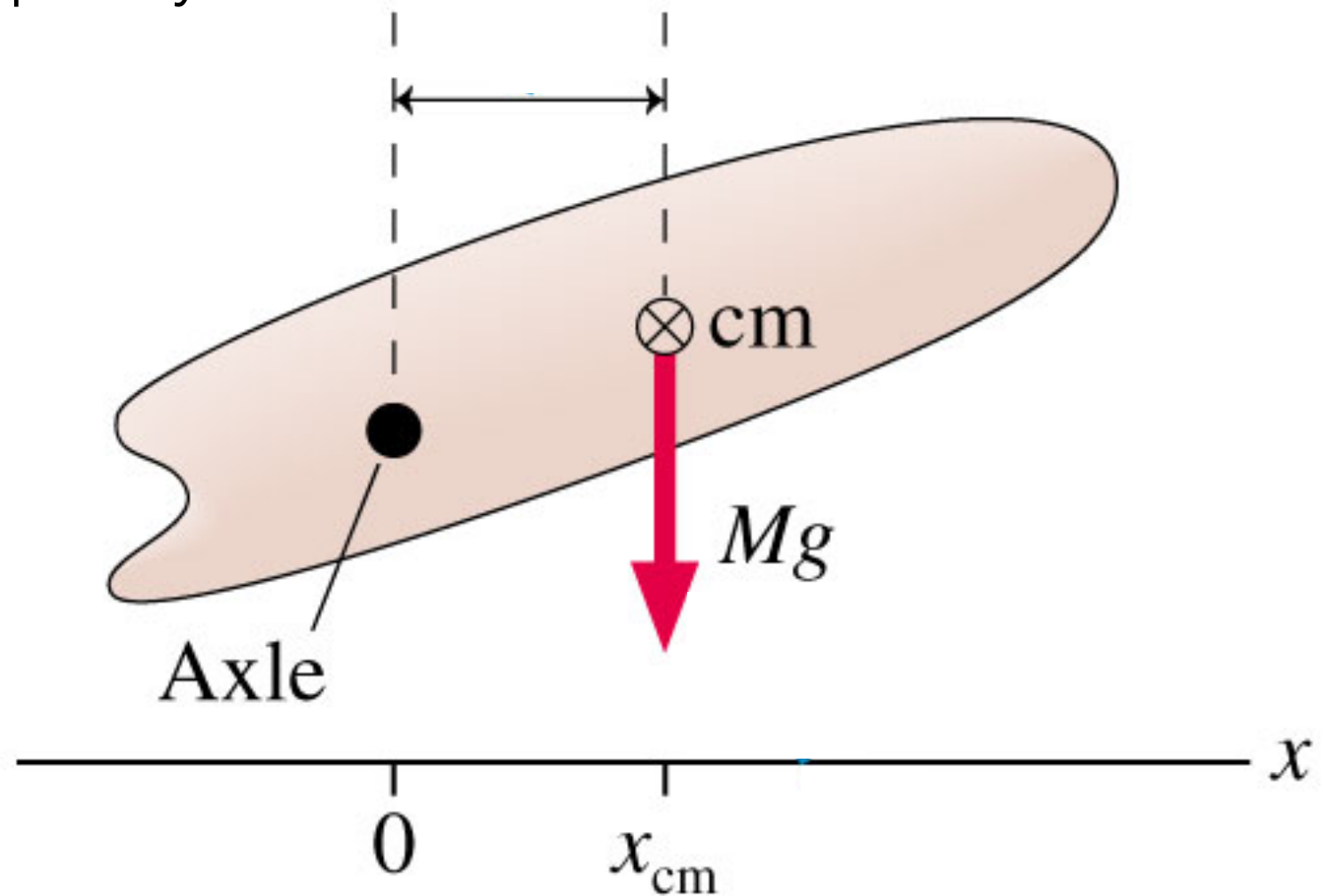
$$x_{\text{cm}} = \frac{1}{M} \int x dm \quad [3]$$

- (a) What is the equation used for?
- (b) What do each of the variables mean?
- (c) Make up a physical situation to illustrate.

Gravitational Torque

When I release the object what will happen?

- A) It will oscillate back and forth.
- B) Nothing. It will stay where you put it.
- C) It will first rotate and then quickly come to rest.

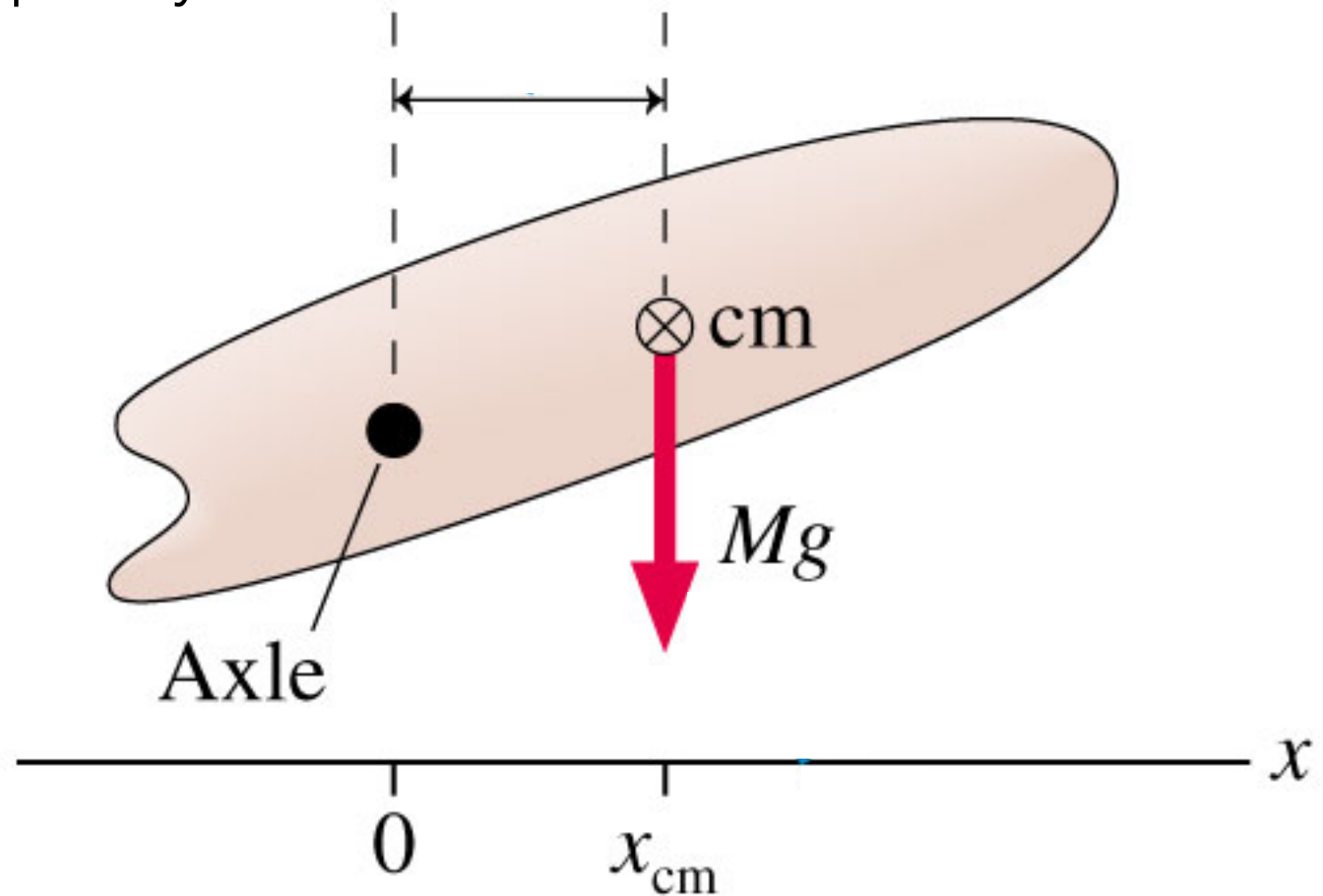


Question #21

Gravitational Torque

When I release the object what will happen?

- A) It will oscillate back and forth.
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- C) It will first rotate and then quickly come to rest.



Moment of Inertia

12.11

12.49

12.51

12.52 ← Parallel-axis theorem

12.53 ← Calculus

12.54 ← Calculus (more challenging)

Torque

12.18

12.8 12.19

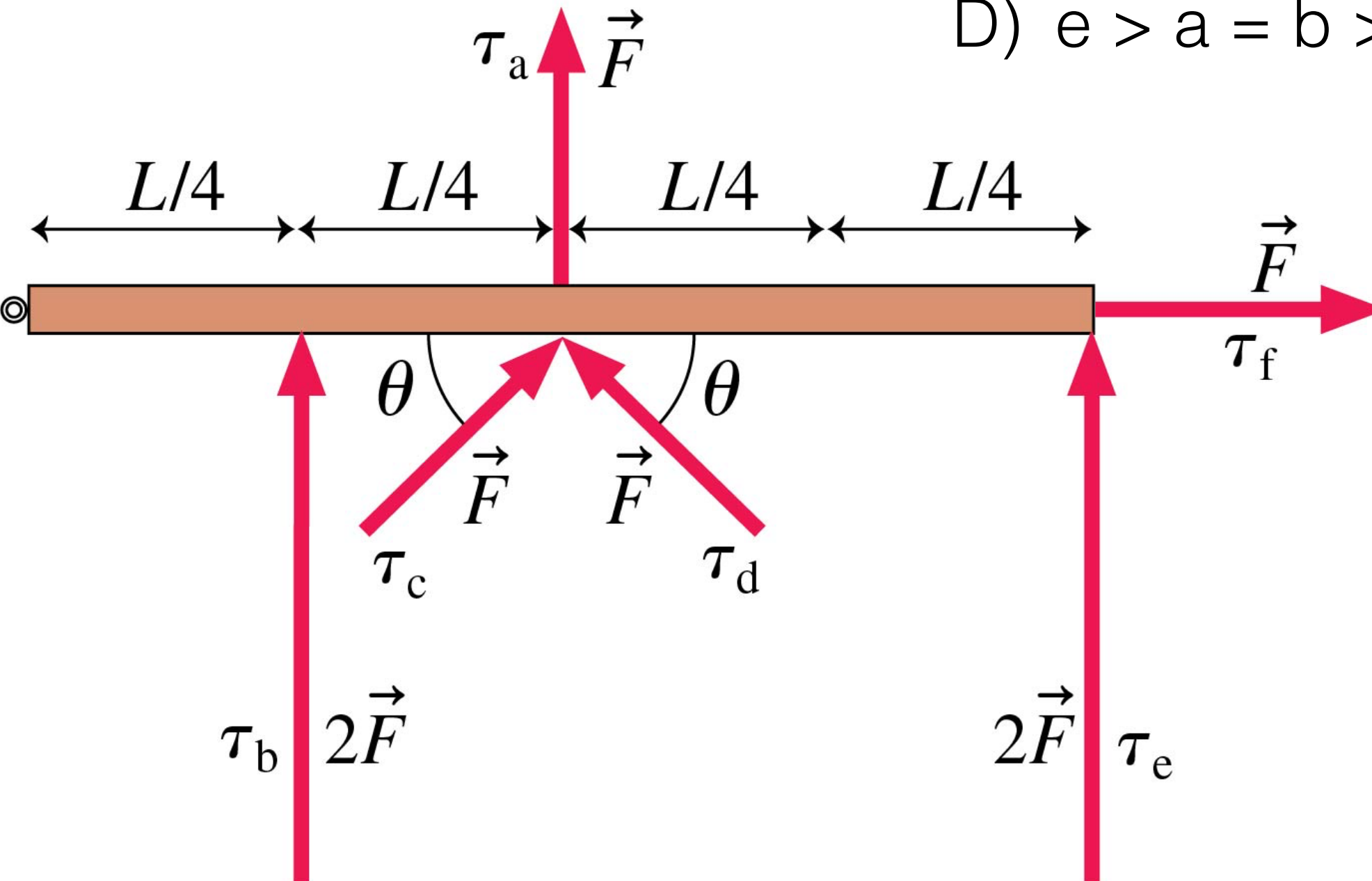
12.20 12.22

12.23

Question #22

Rank the torques

- A) $e = a > b > c > d > f$
- B) $a > e > d > f = d > c$
- C) $e > b > a > d = c > f$
- D) $e > a = b > c = d > f$



Question #23

Video question

- A) 10 cm from left end
- B) 25 cm from right end
- C) 10 cm from right end
- D) In the middle
- E) 25 cm from left end

Rotational Dynamics

- What does a torque do?
- For linear motion, a net force causes an object to accelerate.
- For rotation, **a net torque causes an object to have angular acceleration.**

$$\alpha = \frac{\tau_{\text{net}}}{I}$$

In the absence of a net torque ($\tau_{\text{net}} = 0$), the object either does not rotate ($\omega = 0$) or rotates with *constant* angular velocity ($\omega = \text{constant}$).

Rotational Dynamics

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Torque applet

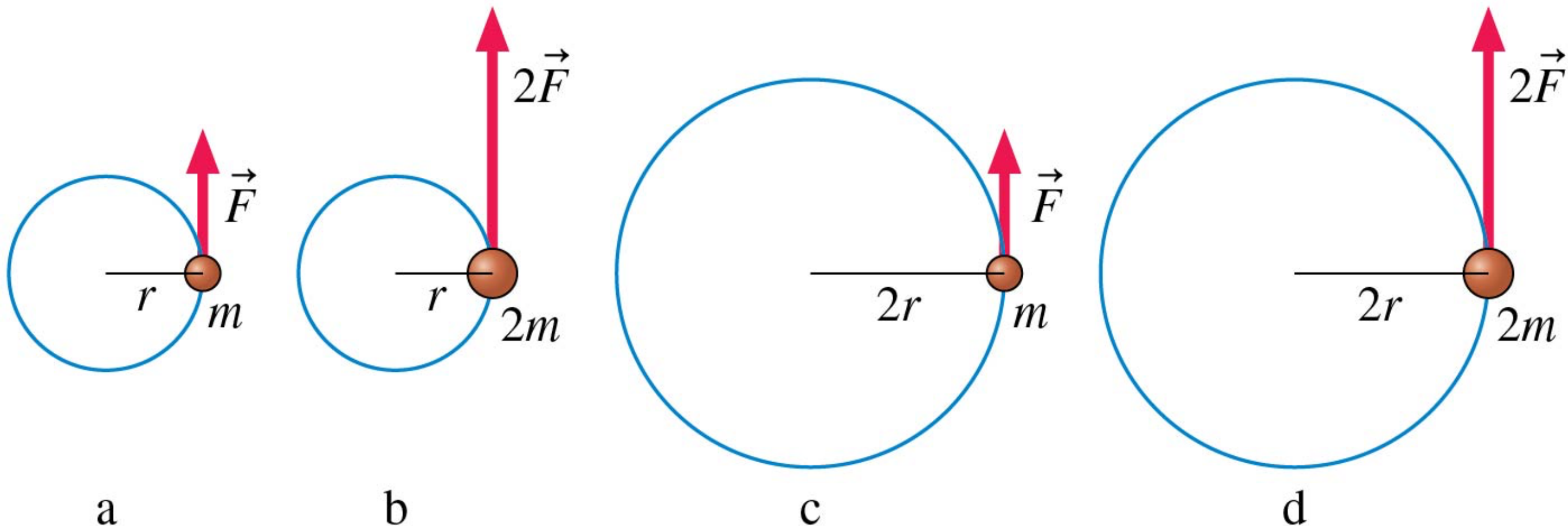
In the absence of a net torque ($\tau_{\text{net}} = 0$), the object either does not rotate ($\omega = 0$) or rotates with *constant* angular velocity ($\omega = \text{constant}$).

Analogies between linear and rotational dynamics

Rotational dynamics		Linear dynamics	
torque	τ_{net}	force	\vec{F}_{net}
moment of inertia	I	mass	m
angular acceleration	α	acceleration	\vec{a}
second law	$\alpha = \tau_{\text{net}}/I$	second law	$\vec{a} = \vec{F}_{\text{net}}/m$

Question #24

Rank the angular accelerations!



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B) $a > b = c > d$

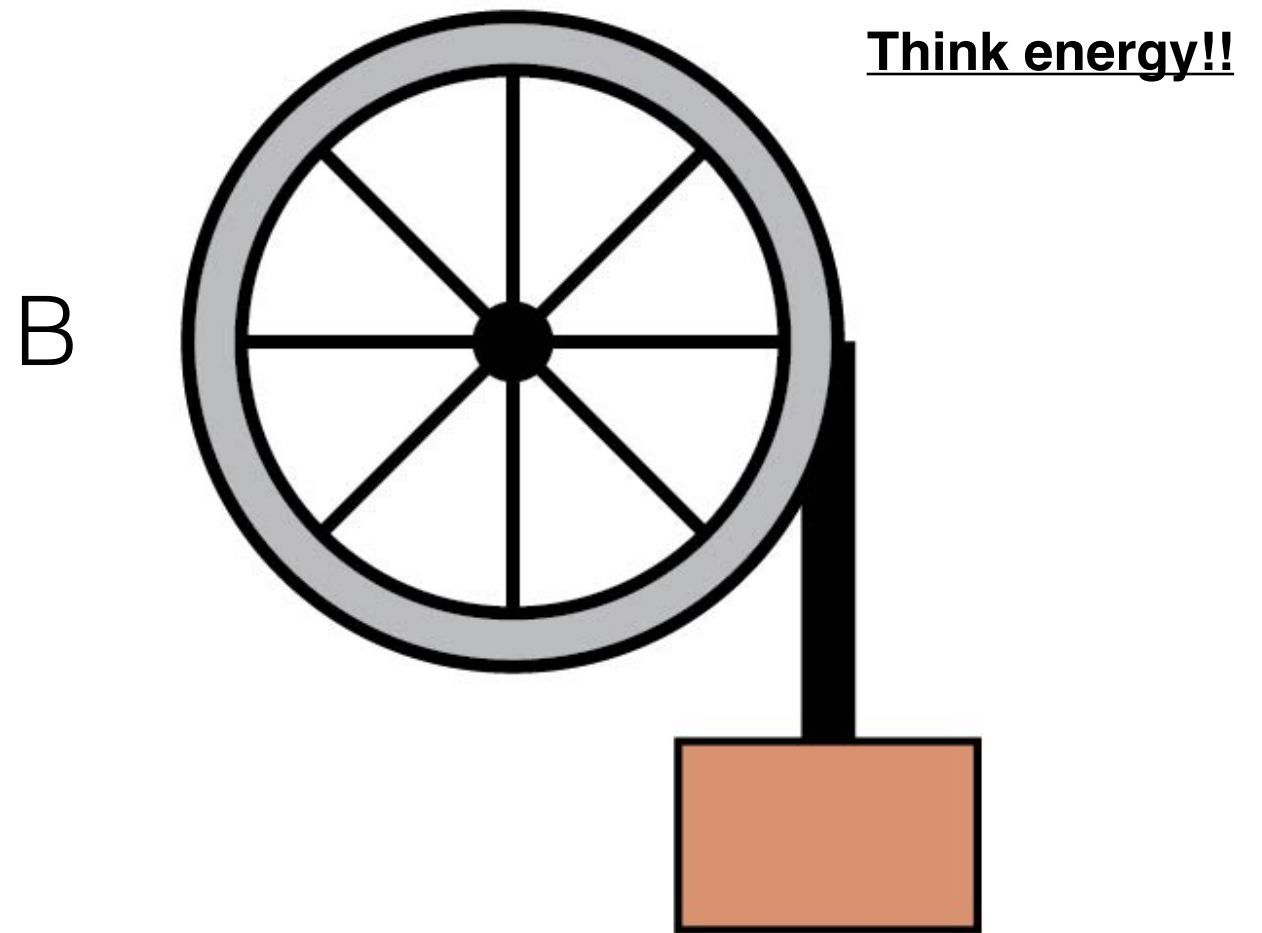
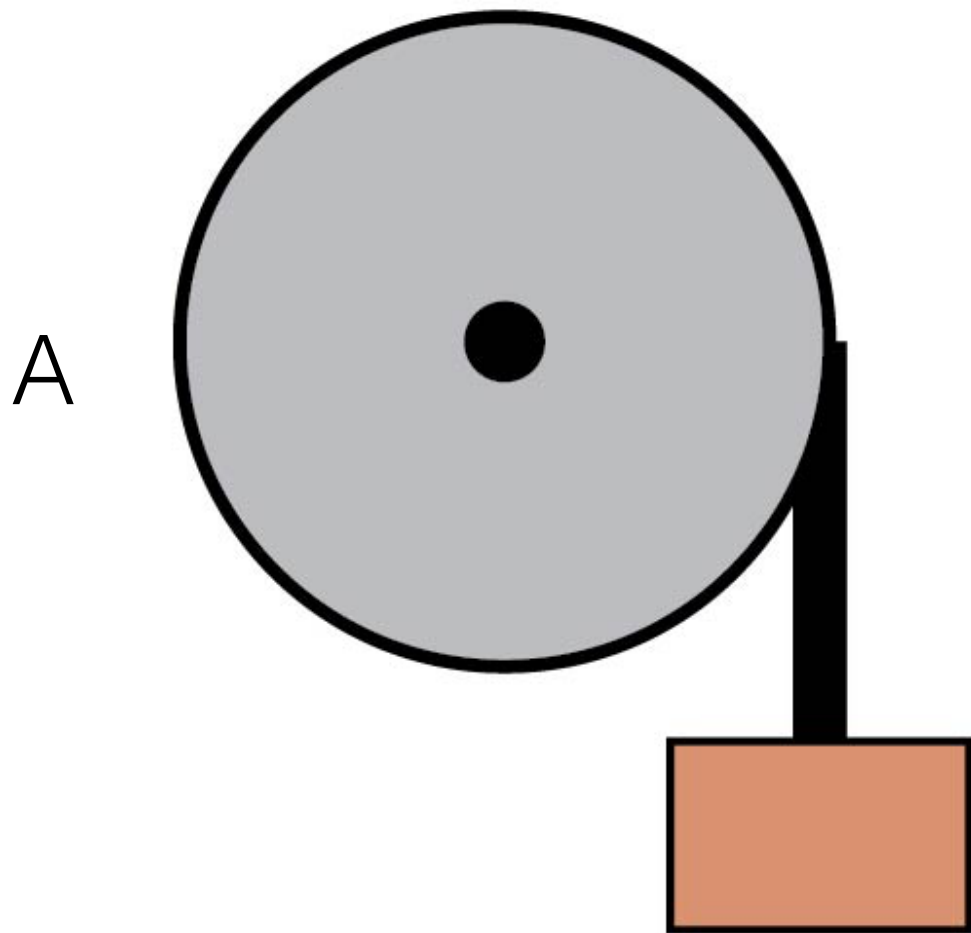
D) $c > d = a > c$

C) $a = b > c = d$

E) $b > d = a > c$

Question # 25

In which case will the block be moving faster just before it hits the floor?

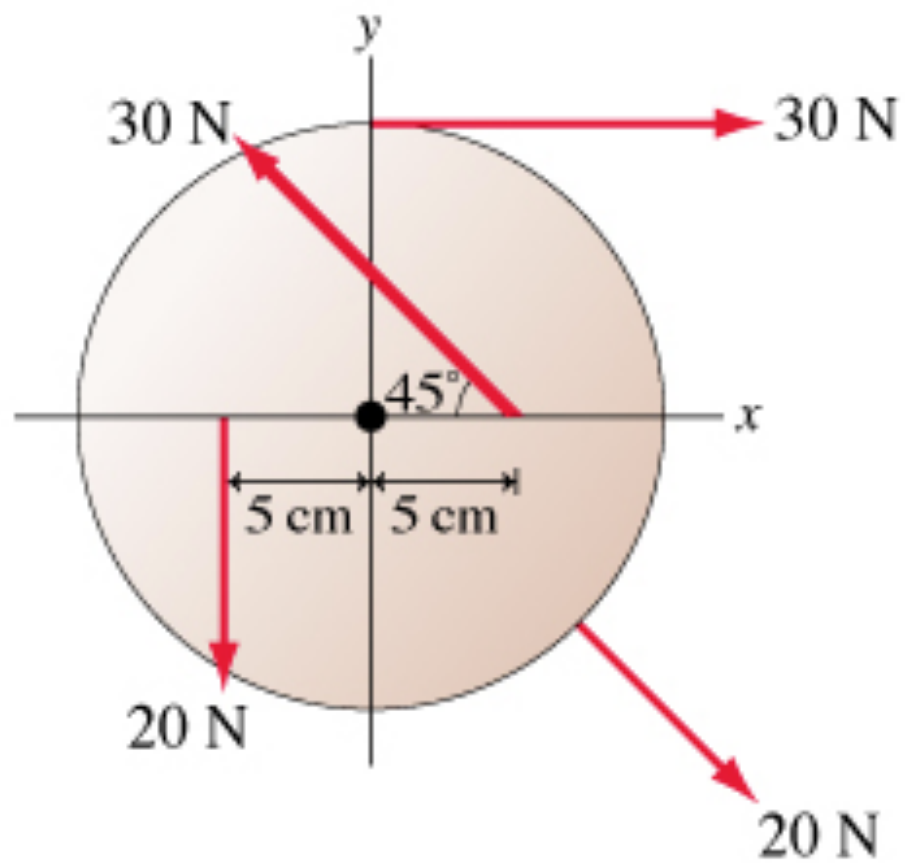


Think energy!!

HW-style problem

$$M = 2 \text{ kg}$$

Find the angular acceleration of the wheel



$$\tau_{\text{net}} = I\alpha$$

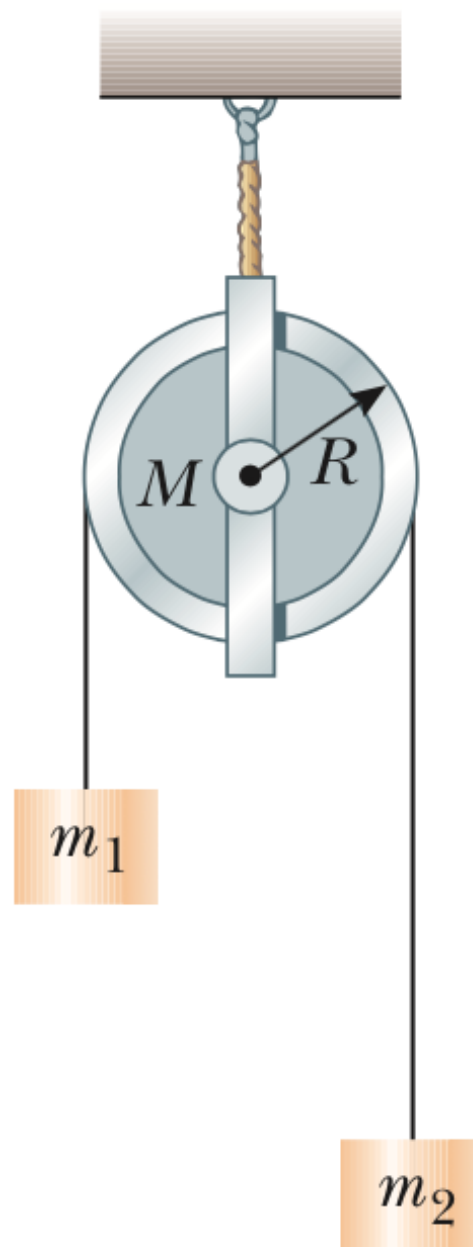
$$m_1 = 20.0 \text{ kg}$$

$$m_2 = 12.5 \text{ kg}$$

$$M = 5.00 \text{ kg}$$

$$R = 0.200 \text{ m}$$

m_1 is 4.00 m above m_2 initially. How long before m_1 hits the floor?



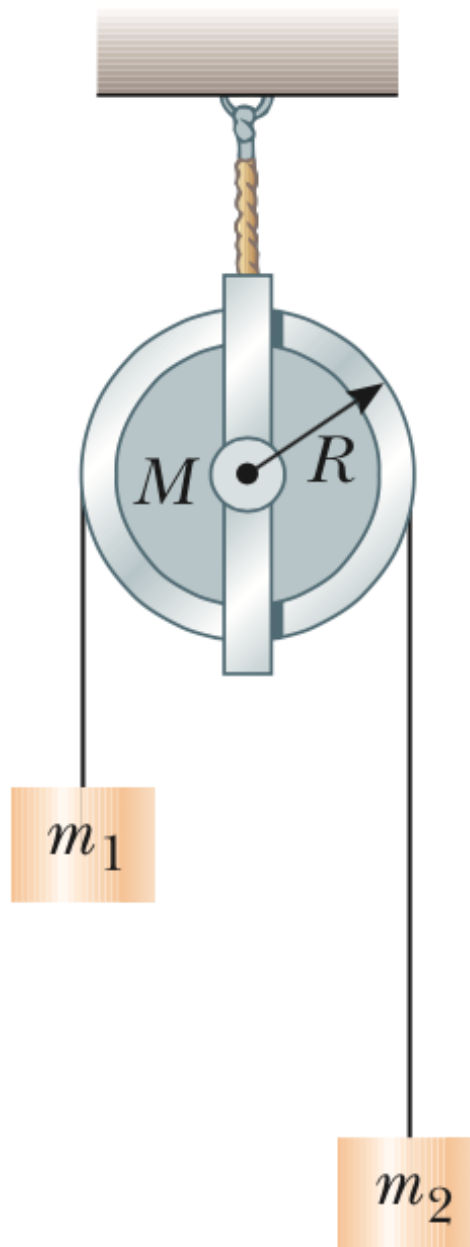
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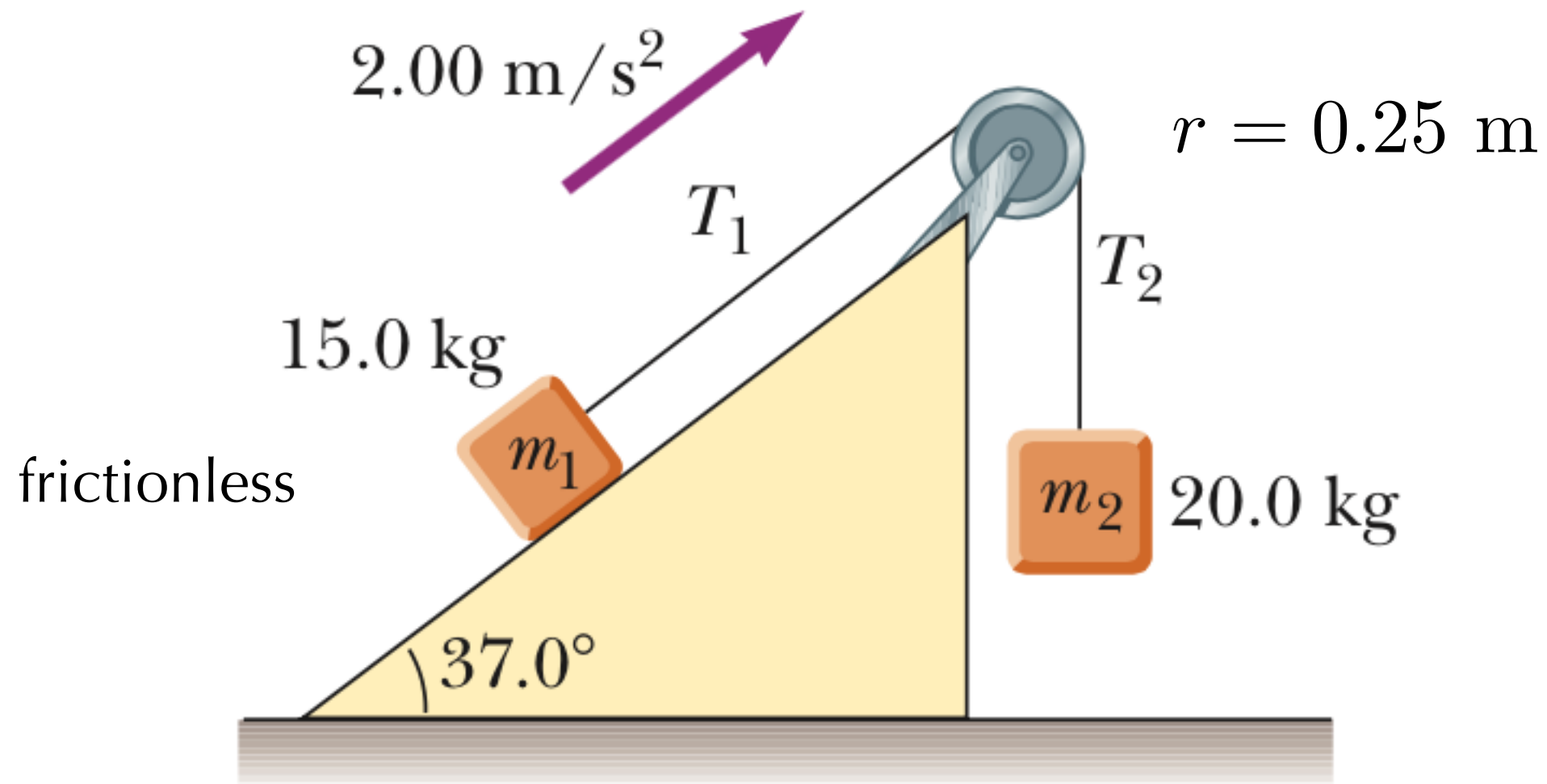
m_1 is 4.00 m above m_2 initially. How long before m_1 hits the floor?



$$a = 2.1 \text{ m/s}^2$$

$$t = 1.95 \text{ s}$$

Find T_1 , T_2 , and I (the moment of inertia of the pulley)



$$T_1 = 118 \text{ N} \quad T_2 = 156 \text{ N}$$

$$I = 1.17 \text{ kg m}^2$$