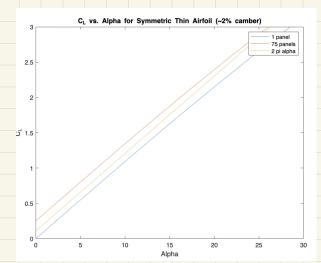
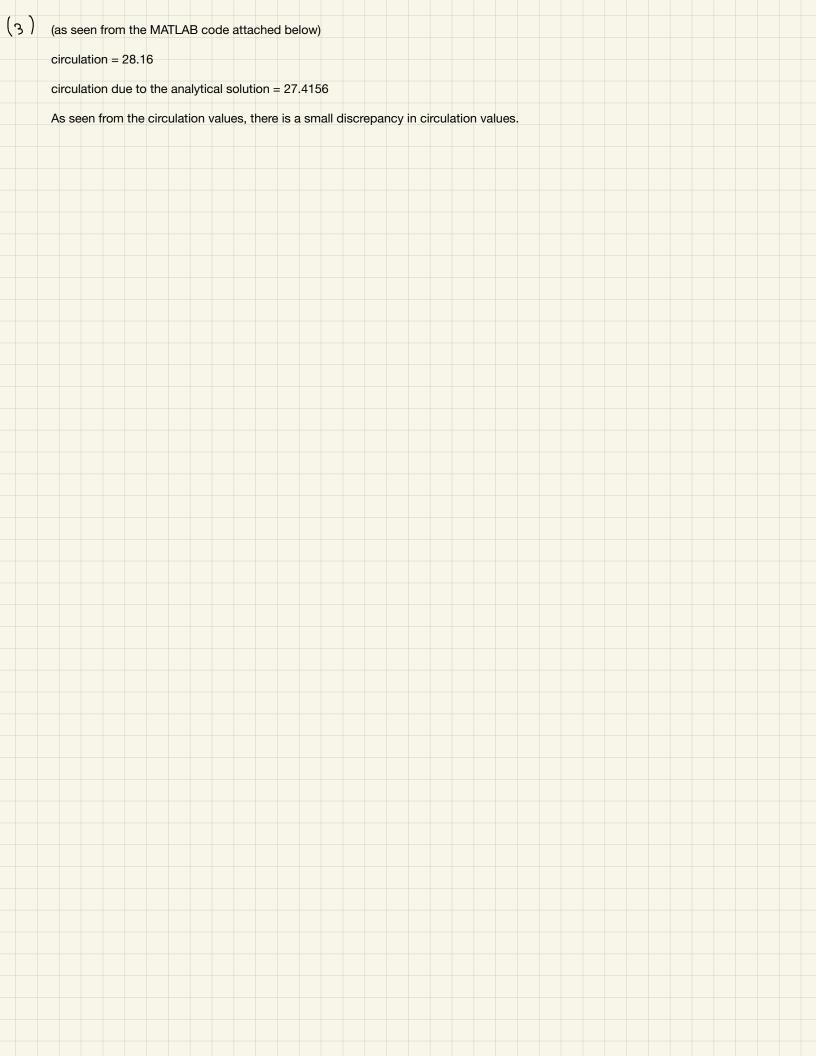


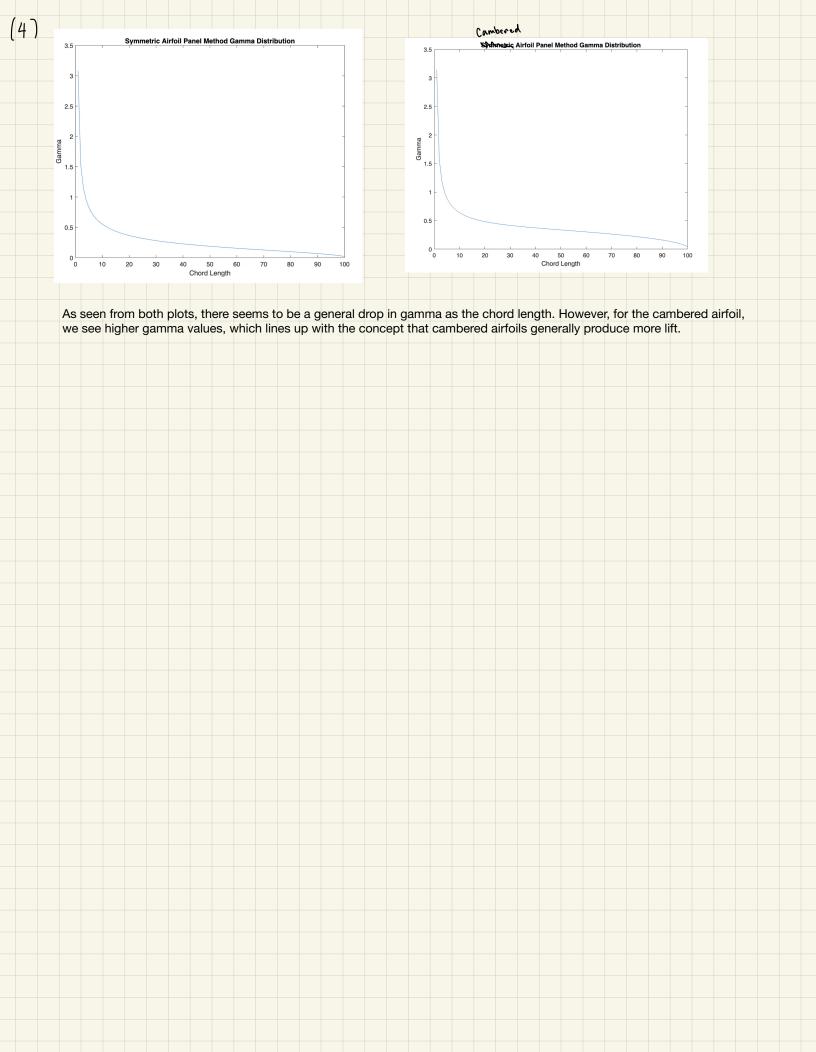
The computed plots seem to have the same linear trend that coincides with the C_L = 2*pi*alpha relationship. We can see closely that there seems to be a small discrepancy in the plots between 1 and 75 panels. This might be due to the fact that 75 panels shows a higher accuracy in describing the C_L across the panels, whereas 1 panel generalizes the relationship and loses that level of detail.

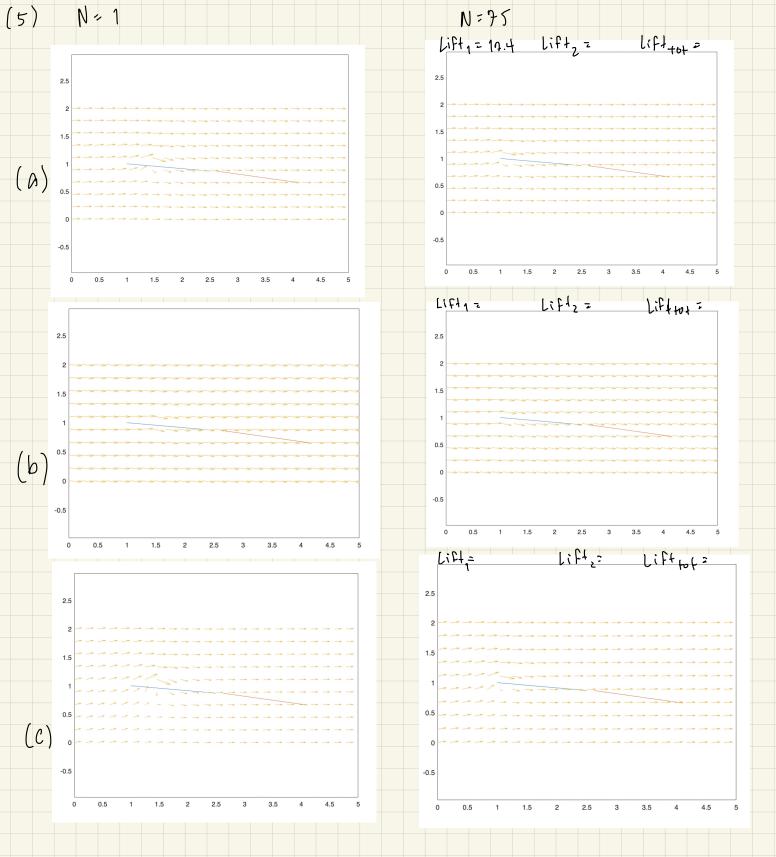




We can see a similar relationship between all 3 panels, with 75 panels having the most closest match to the expected properties of $C_L = 2*pi*alpha$. This is because we see a y-intercept in addition to seeing the linear relationship, which may be captured by having more panels, which add more detail to the plot.



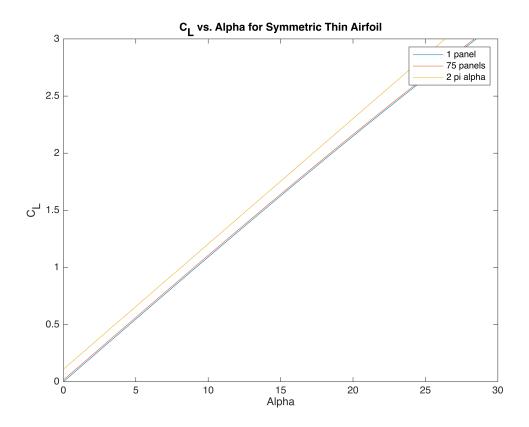




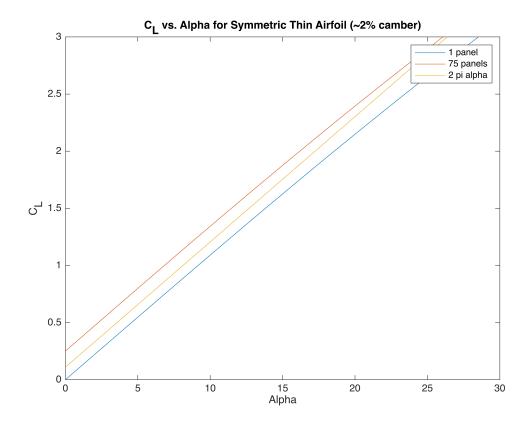
As seen from the plots, there is a strong similarity between the plots and lift values for both numbers of panels. However, as we change the conditions for climbing and descending, we see a change in the vortex shape.

```
clear all
close all
clc
```

```
% Problem 1
for alpha=1:31
    [\sim, C_1, \sim, \sim, \sim, \sim, \sim, \sim] = computePanelData(10, -1000, alpha-1, 1, 1);
    Cl_1_panel(alpha)=C_l;
    [\sim, C_1, \sim, \sim, \sim, \sim, \sim, \sim] = computePanelData(10, -1000, alpha-1, 75, 1);
    Cl_75_panel(alpha)=C_l;
    Cl_eqn(alpha)= 2*pi*(alpha*(pi/180));
end
alpha = linspace(0,30,31);
Cl_combined = [Cl_1_panel;Cl_75_panel;Cl_eqn];
plot(alpha,Cl_combined);
title('C_L vs. Alpha for Symmetric Thin Airfoil')
xlabel('Alpha')
ylabel('C_L')
legend('1 panel', '75 panels', '2 pi alpha')
ylim([0,3])
xlim([0,30])
```



```
% Problem 2
for alpha=1:31
    [\sim, C_1, \sim, \sim, \sim, \sim, \sim, \sim] = computePanelData(10, -62, alpha-1, 1, 1);
    Cl_1_panel(alpha)=C_l;
    [\sim, C_1, \sim, \sim, \sim, \sim, \sim] = computePanelData(10, -62, alpha-1, 75, 1);
    Cl_75_panel(alpha)=C_l;
    Cl_eqn(alpha) = 2*pi*(alpha*(pi/180));
end
alpha = linspace(0,30,31);
Cl_combined = [Cl_1_panel; Cl_75_panel; Cl_eqn];
plot(alpha,Cl_combined);
title('C_L vs. Alpha for Symmetric Thin Airfoil (~2% camber)')
xlabel('Alpha')
ylabel('C_L')
legend('1 panel', '75 panels', '2 pi alpha')
ylim([0,3])
xlim([0,30])
```



```
% Problem 3  [gamma, \sim, \sim, \sim, \sim, \sim, \sim, \sim] = computePanelData(10, -1000, 5, 75, 1);   circulation = sum(gamma)
```

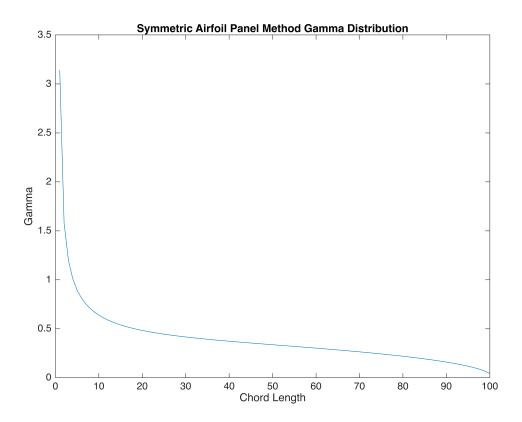
circulation = 28.1533

```
circulation_eqn = 10*10*pi*5*(pi/180)
```

circulation_eqn = 27.4156

```
% Problem 4

[gamma,~,camber,~,~,~,~,~] = computePanelData(10,-62,5,100,1);
l = linspace(1,length(gamma),length(gamma));
plot(l,gamma)
title('Symmetric Airfoil Panel Method Gamma Distribution');
xlabel('Chord Length');
ylabel('Gamma');
```



```
% Problem 5
N = 75;
% v_inf = 203.2;
v_{inf} = 202.5;
% alpha_d = 4.68;
alpha_d = 0;
alpha_r = alpha_d*(pi/180);
grid_res = 5;
v_inf_x = v_inf*cos(alpha_r);
v_inf_y = v_inf*sin(alpha_r);
rho = 0.00238;
% create the upstream airfoil
x_i_u = 1;
y_i_u = 1;
x_f_u = 2.494;
y_f_u = 0.869;
% create the downstream airfoil
x_i_d = 2.624;
y_i_d = 0.867;
x_f_d = 4.109;
y_f_d = 0.659;
```

```
% compute points for the upstream airfoil
x_u = linspace(x_i_u, x_f_u, N+1);
y_u = linspace(y_i_u, y_f_u, N+1);
plot(x_u,y_u);
hold on
% compute points for the downstream airfoil
x_d = linspace(x_i_d, x_f_d, N+1);
y_d = linspace(y_i_d, y_f_d, N+1);
plot(x_d,y_d);
axis equal
xlim([0,5])
ylim([0,2])
% creating the panels
panel_coords_g = zeros(N,4);
panel_coords_g_u = zeros(N,4);
panel coords q d = zeros(N,4);
for i=1:N
    panel\_coords\_g\_u(i, 1) = x\_u(i);
    panel_coords_g_u(i, 2) = y_u(i);
    panel\_coords\_g\_u(i, 3) = x\_u(i+1);
    panel\_coords\_g\_u(i, 4) = y\_u(i+1);
end
for i=1:N
    panel\_coords\_g\_d(i, 1) = x\_d(i);
    panel\_coords\_g\_d(i, 2) = y\_d(i);
    panel\_coords\_g\_d(i, 3) = x\_d(i+1);
    panel\_coords\_g\_d(i, 4) = y\_d(i+1);
end
panel_coords_g =[panel_coords_g_u; panel_coords_g_d];
% declaring panel length
L = 1.5/N;
% calculating the normal and tangential vectors
x q = zeros(2*N,2);
for i=1:2*N
    x_g(i,1) = (panel\_coords\_g(i,3)-panel\_coords\_g(i,1))/L;
    x_g(i,2) = (panel\_coords\_g(i,4)-panel\_coords\_g(i,2))/L;
end
```

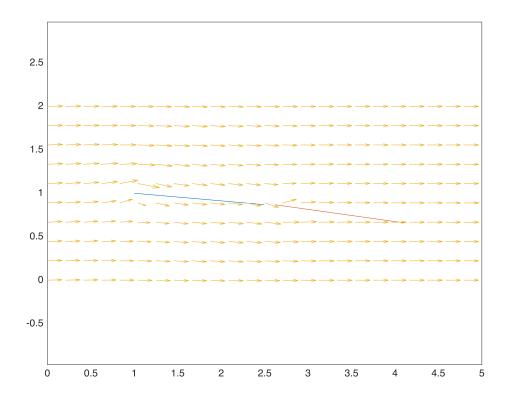
```
y_g = zeros(2*N,2);
y_g = [0 \ 1; -1 \ 0] * transpose(x_g);
y q = -transpose(y q);
% computing collocation points in global frame
collocation_g = zeros(2*N,2);
for i=1:2*N
    collocation_g(i,1) = panel_coords_g(i,1) + 0.75*L*x_g(i,1);
    collocation_g(i,2) = panel\_coords_g(i,2) + 0.75*L*x_g(i,2);
end
% creating icm
icm = zeros(2*N, 2*N);
for i=1:2*N
    for j=1:2*N
        % x and v distances
        x_dist = collocation_g(j,1) - panel_coords_g(i,1);
        y_dist = collocation_g(j,2) - panel_coords_g(i,2);
        % Panel Velocity (i frame)
        u_p = (1/(2*pi)) * (y_dist / ((y_dist)^2 + (x_dist-.25*L)^2));
        v_p = (-1/(2*pi)) * ((x_dist-.25) / ((y_dist)^2 + (x_dist-.25*L)^2));
        % Panel Velocity (global frame)
        B = inv([x_g(i,1) y_g(i,1); x_g(i,2) y_g(i,2)]);
        A = [u_p v_p];
        C = A * B:
        % updating icm matrix entry
        icm(j,i) = dot(C,y,q(j,:));
    end
end
% computing v_infinity normal and calculating gamma
v_{inf_norm} = zeros(2*N,1);
for i=1:2*N
    v_{inf_norm(i)} = -dot([v_{inf_x}, v_{inf_y}], y_{g(i,:));
end
gamma = icm \ v_inf_norm;
% visualizing flow
mesh_X = linspace(0,5,5*grid_res);
mesh_Y = linspace(0,2,2*grid_res);
[X,Y]=meshgrid(mesh X,mesh Y);
dim_x = length(mesh_X);
dim y = length(mesh Y);
U = zeros(dim_y, dim_x);
V = zeros(dim_y, dim_x);
```

```
for i=1:dim_y
    for j=1:dim_x
        u_p_g = 0;
        v_p_g = 0;
        for k=1:2*N
            x = mesh_X(j) - panel_coords_g(k,1);
            y = mesh_Y(i) - panel_coords_g(k, 2);
            u_p = (gamma(k)/(2*pi)) * (y/((y^2)+((x-.25*L)^2)));
            v_p = (-gamma(k)/(2*pi)) * ((x-.25*L)/((y^2)+((x-.25*L)^2)));
            B = inv([x_g(k,1) y_g(k,1); x_g(k,2) y_g(k,2)]);
            A = [u_p \ v_p];
            C = A * B;
            u_p_g = u_p_g + C(1);
            v_p_g = v_p_g + C(2);
        end
        U(i,j) = v_inf_x + u_p_g;
        V(i,j) = v_inf_y + v_p_g;
    end
end
quiver(X,Y,U,V);
h=gca; h.XAxis.TickLength = [0 0];
h=gca; h.YAxis.TickLength = [0 0];
axis equal
% title()
hold off
```

```
function [gamma,C_l,camber,X,Y,U,V,panel_origin_g] = computePanelData(v_inf,y_0,alpha_d, ∠
N, grid res)
    % initializing variables
    alpha_r = alpha_d*(pi/180);
    v_{inf}x = v_{inf}*cos(alpha_r);
    v_inf_y = v_inf*sin(alpha_r);
    rho = 1.225;
    % creating the airfoil
    L = 10;
    x_i = 5; y_i = 0;
    x_f = x_{i+L}; y_f = y_{i};
    x_0 = x_i + L/2;
    r = sqrt((x_i-x_0)^2+(y_i-y_0)^2);
    theta_i = 0.5 * (180-(2 * atand((x_0-x_i)/y_0-y_i)));
    theta_f = 90 + (90 - theta_i);
    theta = linspace(theta_i,theta_f,N+1)';
    panel_origin_g = [r * cosd(theta) + x_0, r * sind(theta)+y_0];
    camber = (max(panel_origin_g(:,2)))/L;
    % creating the panels
    panel\_coords\_g = zeros(N,4);
    for i=1:N
        panel_coords_g(i, 1) = panel_origin_g(i,1);
        panel_coords_g(i, 2) = panel_origin_g(i,2);
        panel_coords_g(i, 3) = panel_origin_g(i+1,1);
        panel_coords_g(i, 4) = panel_origin_g(i+1,2);
    end
    % computing panel lengths
    L = zeros(N,1);
    for i=1:N
        L(i) = qrt((panel\_coords\_g(i,1)-panel\_coords\_g(i,3))^2 + (panel\_coords\_g(i,2)-\checkmark
panel_coords_g(i,4))^2;
    end
    % computing collocation points in global frame
    x_g = zeros(N,2);
    for i=1:N
        x_g(i,1) = (panel\_coords\_g(i,3)-panel\_coords\_g(i,1))/L(i);
        x_g(i,2) = (panel\_coords\_g(i,4)-panel\_coords\_g(i,2))/L(i);
    end
    y_g = zeros(N,2);
    y_g = [0 \ 1; -1 \ 0] * transpose(x_g);
    y_g = -transpose(y_g);
    collocation_g = zeros(N,2);
    for i=1:N
        collocation g(i,1) = panel coords g(i,1) + 0.75 * L(i) * x g(i,1);
        collocation q(i,2) = panel coords q(i,2) + 0.75 * L(i) * x q(i,2);
    end
    % creating icm matrix
    icm = zeros(N, N);
    for i=1:N
```

```
for j=1:N
            % x and y distances
            x_dist = collocation_g(j,1) - panel_coords_g(i,1);
            y_dist = collocation_g(j,2) - panel_coords_g(i,2);
            % Panel Velocity (i frame)
            u_p = (1/(2*pi)) * (y_dist / ((y_dist)^2 + (x_dist-.25*L(i))^2));
            v_p = (-1/(2*pi)) * ((x_dist-.25*L(i)) / ((y_dist)^2 + (x_dist-.25*L(i))^2 \checkmark
));
            % Panel Velocity (global frame)
            B = inv([x_g(i,1) y_g(i,1); x_g(i,2) y_g(i,2)]);
            A = [u_p \ v_p];
            C = A * B;
            % updating icm matrix entry
            icm(j,i) = dot(C,y_g(j,:));
        end
   end
   % computing v_infinity normal and calculating gamma
   v inf norm = zeros(N,1);
    for i=1:N
          disp(size(y_g))
        v_inf_norm(i) = -dot([v_inf_x, v_inf_y], y_g(i,:));
   gamma = inv(icm) * v_inf_norm;
   % visualizing flow
   mesh_X = linspace(0,20,20*grid_res);
   mesh_Y = linspace(3,-3,6*grid_res);
    [X,Y]=meshgrid(mesh_X,mesh_Y);
    dim_x = length(mesh_X);
   dim_y = length(mesh_Y);
   U = zeros(dim_y, dim_x);
   V = zeros(dim_y, dim_x);
   C_l = 2*sum(gamma)/(v_inf*10);
   for i=1:dim y
        for j=1:dim x
            u_p_g = 0;
            v_p_g = 0;
            for k=1:N
                x = mesh_X(j) - panel_origin_g(k,1);
                y = mesh_Y(i) - panel_origin_g(k,2);
                u_p = (gamma(k)/(2*pi)) * (y/((y^2)+((x-.25*L(k))^2)));
                v_p = (-gamma(k)/(2*pi)) * ((x-.25*L(k))/((y^2)+((x-.25*L(k))^2)));
                B = inv([x_g(k,1) y_g(k,1); x_g(k,2) y_g(k,2)]);
                A = [u_p v_p];
                C = A * B;
                u_p_g = u_p_g + C(1);
                v_p_g = v_p_g + C(2);
            end
            U(i,j) = v_inf_x + u_p_g;
```

```
V(i,j) = v_inf_y + v_p_g;
end
end
% lift =
% disp()
end
```



lift = sum(gamma)*v_inf*rho

lift = 17.4098