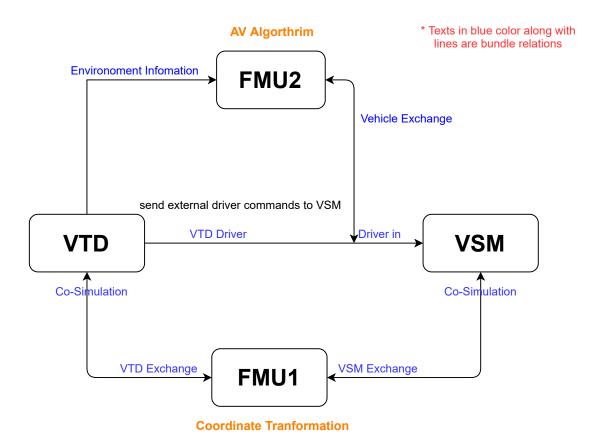
## **FMU Project Design**



Components	
VTD	<b><virtual drive="" test=""></virtual></b> Define <b>scenarios.xml</b> file which contains <ol> <li>Player/Obstacle's info: start &amp; end position, speed, waypoints/trajectory</li> <li>Ego/Bus's information: start &amp; end position, speed, waypoints/trajectory</li> <li>Define <b>configuration.xml</b> file which contains</li> <li>Sensor's information, such as front sensor</li> <li>Lidar's information: Pointcloud data, current position (Need to be implemented)</li> </ol>
VSM	< Vehicle Simulation Model > Define bus's modules : Vehicle, Steering system, gearbox
FMU1	<pre><functional (fmi)="" interface="" mockup="" standard=""> Coordinate Tranformation For data exchange between two system</functional></pre>
FMU2	<functional (fmi)="" interface="" mockup="" standard=""> AV bus algothrims such as Localization, Planning, Obstacle detection modules</functional>