

The Quantum Game

Applied Elementary Quantum Theory for Non-Physicists
0th Edition

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Introduction

Quantum Physics has spent near of the last hundred years being synonymous with the mysterious and inexplicable. This is perhaps rightfully so, as it's a topic almost never given attention outside of formal physics degree or career. This in part lies within it's general obscurity, bizarre nature, and also counter-intuitive set of rules. Other branches of Physics such as classical physics, or electricity and magnetism or special and general relativity are often regarded as far more well-defined branches of physics. There, we can predict a set of events given a circumstance, map it mathematically and then show that our theory is valid due to it's predictive reliability.

Quantum physics on the other hand, is far less well define, in part because it is the "newest" of these branches of physics. It's original conception could almost be considered accidental. It came up as a way of explaining strange phenomena that could not be touched by the laws of Newton or Maxwell. Over the last hundred years. This theory that covers the smallest known scale of the universe, and is considerably dense material wise. Everything in this text is a hyper-condensed amalgamation of the life's work of greats like *Erwin Schrodinger*, *Paul Dirac*, *Wolfgang Pauli*, *Werner Heisenburg* and *Max Born*. And no single book, paper or talk on the subject could every do the topic justice.

The Quantum Game has been written to serve as a very broad overview of elementary quantum mechanical theory. While that statement may seem like an oxymoron, the goal of this text is to show how despite it reputation, quantum physics is in fact a very reasonable and digestible subject, even for those outside of a formal physics degree or career. As with every text, every reader seeks to get something different, and it is my intention to satisfy most basic questions by outline much of the general functionality of this subject. My goal as the writer of this text is to show how to *do* quantum physics - from a mostly mathematical and computational prospective. By the end of this work, we will have built up a solid mathematical backbone, as well a new form a intuition to guide you through an possible future quantum - related endeavors.

Mathematical Conventions

Quantum physics is a mathematically heavy subject - the standardization of notation is essential for it's understanding. Here are the notation conventions that I will be using.

- A vector, v is \vec{v}
- The i -th component of \vec{v} is \vec{v}_i
- A ket, ψ is $|\psi\rangle$
- A bra, ϕ is $\langle\phi|$
- The inner product of $\langle\phi|$ and $|\psi\rangle$ is $\langle\phi|\psi\rangle$
- The outer product of $\langle\phi|$ and $|\psi\rangle$ is $|\psi\rangle\langle\phi|$
- A matrix or operator A is \hat{A}
- the complex conjugate of α is α^*
-
-
-

Preliminary Considerations

This text is designed to provide a brief survey of quantum physics. It's ideal use would be that of a classroom *supplement* or a workplace introduction. As a classroom aid, this work would be of best use when combined with a proper university course, along with a proper university book as well. Additionally if you have already finished a higher education, and are involved in a technical career that requires a small bit of understanding, this would be a great text to serve as a functional introduction.

In reading this work, it is assumed that you are at least slightly familiar with the following ideas:

- **Basic Algebra**
Arithmetic and basic algebraic manipulation are a necessary evils of quantum physics
- **Statistics**
Handling probability, statistics, distributions and functions. Finding means, deviations, variances and know how to interpret probability densities.
- **Differential Calculus**
Single and higher dimensional derivatives.
- **Integral Calculus**
Indefinite integral returns the anti-derivative of a function, and a definite integral returns the area between a function and it's respective axis over a certain bounds.
- **Differential Equations**
Equations that relate functions to one or more of that functions own higher derivatives.

- **Linear Algebra**

The study of vectors, matrices and spaces. Also allows for convenient organization of mathematics in higher dimensions.

- **Computer Programming**

Basic procedural programming. Most examples in this text will be done in *Python 3*.

This work does not require a thorough, 'classroom' level of comprehension, but rather a conceptual understanding will do quite fine. In areas that require a more heavy knowledge, I will elaborate on accordingly. In addition, I have included a *Mathematical Index* of math terms and concepts that may warrant some extra reading that may interfere with the pacing of this text. In most cases, any questions as far as math can be found within a few minutes of an internet search. In reality, most topics here will require not much more than a high school level of math for understanding.

Citations for this Text

- Griffiths, David J., and Darrell F. Schroeter. *Introduction to Quantum Mechanics*. 3rd ed., Cambridge University Press, 2018.
- Larson, Ron. *Elementary Linear Algebra*. 7th ed., Brooks/Cole, 2013.
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Chapter 1

The Name of the Game

1.1 The Schrodinger Equation

In classical physics, the description of all motion as we know it, can be in some way attributed to Issac Newton's second law of motion, which tell us that the force acting on an object is equal to the product of the objects mass and its acceleration. More conveniently written: $F = ma$. Or rather:

$$F = m \frac{d^2 r}{dt^2} \quad (1.1)$$

in a more mathematical expression. Where r , or rather $r(t)$ is a time dependent function that describes the position of the object in a single in some spatial coordinate system.

The forces acting on any arbitrary object in question can be equated to $m \frac{d^2 r}{dt^2}$ and the resulting differential equation can be solved to find the function $r(t)$, that tracks the position of the object with time. Admittedly, this proves to be quite difficult in some cases and literally impossible in other cases. Luckily for us, in the 21st century, we have the ability to use computers and have the benefit of numerical problem solving which will come in handy later on.

In quantum physics, we don't have such a nice, clean equation as Sir Newton has laid out for us, but a much, much messier one that behaves in a similar way. It was created around 1925 by the Austrian Physicist, *Erwin Schrodinger*. It looks something like:

$$-\frac{\hbar^2}{2m} \frac{\partial^2 \Psi}{\partial x^2} + V\Psi = i\hbar \frac{\partial \Psi}{\partial t} \quad (1.2)$$

This is called *Schrodinger's Equation* and almost everything about modern quantum physics in some way, either comes from, or comes back to this equation. Just like in classical physics,

Newton's second law of motion (1.1) becomes a dominant player in it's mathematical treatment, so too in quantum physics, Schrodinger's equation (1.2) becomes the major character of the subject.

Consider a point particle, of some mass, m , constrained to move along a one-dimensional, line, which we will conveniently choose to be the x -axis. If we know the mass, and the particles position as a function of time, $x(t)$ we can deduce several other properties of the system. By taking the derivative of $x(t)$ with respect to time, we can determine the particles velocity all time, $v(t)$. Here, we can compute the kinetic energy, $\frac{1}{2}mv^2$, and momentum, mv , at all points in time. Taking another time derivative gives us the acceleration of the particle at all time, $a(t)$. From there, we can find the net force, ma , and the even the potential energy function at all times if the system is closed.

Just by simply knowing the mass and position function for an object grants a great deal of information to you. We can find position, velocity, acceleration, force, energy, momentum and so many of these important dynamical variables by doing some simple bits of calculus or algebra. In all cases, we can evaluate these little formulas at any point in space or time to find *exactly* the value we want. Classical physics operates under this assumption, that we can accurately describe the world around us and it behaves according to these mathematical descriptions - and up until the early 20th century, this was thought to produce a near complete description of the universe.

Quantum physics holds a different sent of requirements from us however. Things tend to not be so well defined. Rather than being able to calculate or measure the *exact* value of the quantity that we want, we are forced to only be able to determine a *probabilistic* value of what we want. In other words, things are not entering values and parameters to find for *certain* what we want, but instead quantum physics becomes a game of *probability*.

This business of probability, called the **statistical interpretation** comes with it the idea of *uncertainty* and *ambiguity*. Our entire understanding of the macro universe relies on the idea that things are exactly measurable and perfectly determinant, but the universe on a quantum level cannot be described with anything more than statistics. And, as we'll see very shortly, it is this statistical information which shapes our understanding of the subject entirely - the fact that we can only talk about the *possible* results that happen with a certain *probability*. This lack of certainty is what is so strikingly dreadful about this field and has been source for countless restless nights over the decades. This poses the currently unanswerable question that arises: is this nature is a product of the universe or a product of our mathematical treatment?

Probability is *the name of the game* of quantum physics. The mechanics of a quantum system are not defined by a mass m and a position function, $x(t)$, but rather are defined by a probability amplitude function, *the wave function*, $\Psi(x, t)$ which is represented by the Greek letter Psi, and appears three times in the Schrodinger equation above.

This function, $\Psi(x, t)$, or often just Ψ , contains with it all possible information about a quantum mechanical system. With the wave function Ψ known, we can determine the relative probabilities of position, momenta and other system parameters. For example, the expression:

$$\int_a^b |\Psi(x, t)|^2 dx \quad (1.3)$$

gives the probability of finding some particle on the x -axis between the values of a and b at some fixed time t . This business of probability is called *The Statistical Interpretation* of Quantum Mechanics and is arguable the largest underlying points in quantum theory - that our entire model is based on statistically described behavior.

But how exactly do we *get* $\Psi(x, t)$? In Classical physics, we get $x(t)$ often by solving a second-order ordinary differential equation from Newton's laws. In Quantum physics, we get $\Psi(x, t)$ by solving the second-order, partial differential equation - Schrodinger's equation. As with classical physics, this tends to be a bit messy and often not really reasonable to do by hand- at least not without understanding some other concepts first. So, before we go off trying to *solve* equation (1.2) for the wave function, Ψ we must understand a little bit more about it first - what does it mean?

1.2 The Wave Function

Before we construct a means to finding this mysterious function, $\Psi(x, t)$ and treating it mathematically, we need to produce a more concrete understanding of what this function is trying to *tell* us. Outside of pure mathematics, we need a motivation to play this part of the game and It's such an important characteristic of quantum physics that we cannot afford to not set aside some time to understand how it works.

In one sentence: The wave function is a probability *amplitude* for finding a particle in some space, at some time. A common misconception is that the wave function itself is the probability *density* is incorrect. It is the quantity of the wave function, $\Psi(x, t)$, multiplied by it's complex conjugate, $\Psi^*(x, t)$, that gives the actual probability density of finding a particle at a space and a time. With this, we can equate that product to a probability density function:

$$\Psi^*(x, t)\Psi(x, t) = |\Psi(x, t)|^2 = P(x, t) \quad (1.4)$$

Then, as shown in equation (1.3), integrating this function over some spatial region, from a to b , gives the probability of finding a quantum particle, with the wave function, $\Psi(x, t)$, between the region a and b . Because of intuition about probability, integrating this function over all of space, (i.e., $-\infty$ to $+\infty$) would identically produce the result 1. Which would be the equivalent to saying that there is a 100% chance of finding the particle *somewhere* in all

of space. This make logical sense, because if we assert that there is a particle of interest, it cannot simply *remove* itself from existence altogether.

This is raises the problem that nearly all functions, when integrated over all of space, do *not* produce a value of 1. So, whenever we find the wave function, $\Psi(x, t)$, that satisfies the Schrodinger equation for a particle, we must first *normalize* it's area to 1 by finding the constant A , such that:

$$1 = \int_{-\infty}^{+\infty} A\Psi(x, t)dx = A \int_{-\infty}^{+\infty} \Psi(x, t)dx \quad (1.5)$$

and then this subsequently allows us to say that:

$$1 = \int_{-\infty}^{+\infty} \left(A\Psi(x, t) \right) \left(A^*\Psi^*(x, t) \right) dx = |A|^2 \int_{-\infty}^{+\infty} |\Psi(x, t)|^2 dx \quad (1.6)$$

Once we've found this normalization constant, A , we can evaluate the integral at various bounds to find the probability (out of 1) of find the particle in that regions. For Example if you have a wave function and a normalized probability density function, and found the result:

$$|A|^2 \int_c^d |\Psi(x, t)|^2 dx = 0.35 \quad (1.7)$$

and assuming the interval $[c, d]$ is not all of space, then there is a 35% chance of find the particle between the region c and d at some time t . This statistical interpretation comes with some other rules that may be worth writing out. Many of which some from simple calculus rules of integration.

- **Probability:**

A normalized wave function has the property

$$0 < |A|^2 \int_a^b |\Psi(x, t)|^2 dx \leq 1 \quad (1.8)$$

There is never more than a 100% chance of finding a particle over any interval, and that a particle must exist somewhere in a region. If the system demands that the particle can only be in the region a and b , then the integral over that region must be equal to 1. Additionally, once a particle is normalized at a time t , it is also normalized for all time as well.

- **Addition of Probability:**

If a region of space divided into segments, the sum of the probabilities of finding the particles in each regions must be equal to finding the total probability of the while region.

$$\int_a^b |\Psi(x, t)|^2 dx = \int_a^c |\Psi(x, t)|^2 dx + \int_c^b |\Psi(x, t)|^2 dx \quad (1.9)$$

- **Zero Probability**

The particle odds of a particle being *exactly* at are point b are identically *zero*. From calculus, when integrating a function over a region b to b the result is always zero independent of a the function, time or normalization.

$$\int_b^b |\Psi(x, t)|^2 dx = 0 \quad (1.10)$$

Aside from purely mathematical objects, $\Psi(x, t)$ must also have some physical properties - otherwise Quantum Physics would be purely Quantum Mathematics. This forces us to consider some other parameters that are not explicitly expressed from the mathematics.

- **Normalizeable**

Wave function *must* be normalizable. When we actually solve the Schrodinger equation, it must be a function that can be normalized. Otherwise, our statistical interpretation breaks down, and we find ourselves in trouble. For example, the function $\Psi(x, t) = 0$ is a valid solution to the partial differential equation, but it cannot be normalized over all of space, thus it is *not* a valid wave equation.

- **Continuity**

Wave functions must be continuous and continuously differentiable when subject to potentials that are also continuous are continuously differentiated. This means that if a potential function, $V(x)$ is perfectly smooth, so must the resulting wave function be. Only in cases where potentials are discontinuous (i.e. piece-wise defined) can the function and it's first derivative be discontinuous.

Believe it or now, we now have a very solid basis for what the wave function actually is and how it works. We are ready to proceed to break down the mechanisms of the Schrodinger equation, and start to solve it as well.

1.3 Breaking Down the Schrodinger Equation

If the name of the game in quantum physics is understanding probability densities and statistical behavior of systems, then the game is played by *finding* that probability function- which turns out to often by very difficult. This means to solve the Schrodinger equation for $\Psi(x, t)$, which gives the *probability amplitude*. At first glance, the equation:

$$-\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} [\Psi(x, t)] + V(x)\Psi(x, t) = i\hbar \frac{\partial}{\partial t} [\Psi(x, t)] \quad (1.11)$$

Which is just equation (1.2) expanded out a little bit, has a lot of information to unpack, even for a seasoned user of mathematics. For this section, we're going to try to determine what this equation is actually trying to tell us, and what each piece of it means. First off, lets take it apart, one tedious variable at a time.

The value \hbar is defined as $\frac{h}{2\pi}$ where h is *Planck's constant*. \hbar itself happens to be a more useful quantity in quantum mechanics, it has a value of 1.054573×10^{-34} Joule-seconds. The parameter m is the mass of the particle in question. When put together, the term $-\frac{\hbar^2}{2m}$ is simply a scalar value -i.e. it's just a number, a constant coefficient.

The term $V(x)$ represents the *potential function* of the quantum mechanical system. In almost all cases for this work, it will *just* be a function of space, *not* time- although this is not always the case. This describes the potential energy distribution over space along our one-dimensional system. When it comes to solving equation (1.11), this is really the limiting factor in what determines the shape of the solution, as we'll see in chapter 2.

The partial derivatives of $\Psi(x, t)$ are a little bit tougher to reason out, but they are very akin to the mechanics of the heat equation and wave equation from classical physics, hence why Ψ is named the wave equation. In the case of Schrodinger's equation, a second spatial derivative is proportional to a first time derivative. In a little while we'll see how this relationship relates to kinetic energy and allows for some nice simplifications to be made.

Now that We've broken down each part of the equation, we can begin to formulate an analytical solution. This in practice need only be done once because, where we will end up is a convenient starting place for the rest of all calculations to be done. As stated before, the goal of solving this partial differential equation (or PDE for short) is to find $\Psi(x, t)$, a function of both space, x and time, t . To do this, we will assume that $\Psi(x, t)$ is a composition, or the product of two 'smaller' functions, one of just space, and another of just time. This means that Ψ can be broken down into a spatial function, which we'll call $\psi(x)$ and a temporal function, which we'll call $\phi(t)$. This then allows for the very import relation that will come back to haunt us over and over again:

$$\Psi(x, t) = \psi(x)\phi(t) \quad (1.12)$$

The exact reasoning for this is quite unclear at first, and that's okay for now- it's use will become apparent later on. This new form for our equation allows us to write equation (1.11) as:

$$-\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} [\psi(x)\phi(t)] + V(x) [\psi(x)\phi(t)] = i\hbar \frac{\partial}{\partial t} [\psi(x)\phi(t)] \quad (1.13)$$

We can use the linear properties of the derivative operator to further help us out. Functions of time are not affected under a spatial derivative, and functions of space are not affected under a temporal derivative. This lets us conveniently remove those untouched functions as such, and use some short hand. $\psi(x)$ becomes ψ and $\phi(t)$ becomes ϕ .

$$-\frac{\hbar^2}{2m} \phi \frac{\partial^2 \psi}{\partial x^2} + V[\psi\phi] = i\hbar \psi \frac{\partial \phi}{\partial t} \quad (1.14)$$

Lastly, we can divide both sides of the equation by $\psi\phi$. Now, equation (1.14) becomes:

$$-\frac{\hbar^2}{2m} \frac{1}{\psi} \frac{\partial^2 \psi}{\partial x^2} + V = i\hbar \frac{1}{\phi} \frac{\partial \phi}{\partial t} \quad (1.15)$$

Now, we have all functions of *space* on the left side, and all functions of *time* on the right side. In order for both sides of this equation to be equal for *all of 1D space* and *all of time*, they must be identically constant. This fact is tough to grasp and it's true comprehension may have to be saved for another text, but in reality it is this mathematical rule that motivates us to choose the separable solution form in equation (1.12).

If we examine just the right side, the time function's side, we can set it to an 'arbitrary' constant E - for reasons we'll discover in just a moment. Now we can write:

$$E = i\hbar \frac{1}{\phi} \frac{d\phi}{dt} \quad (1.16)$$

Note that the partial derivatives are now full derivatives, which is again a product of this separation technique. This is a time dependent ordinary differential equation (or ODE for short). It can be conveniently be solved by using it's own method of separation for ODE's. The solution, $\phi(t)$ that satisfies this equation is:

$$\phi(t) = e^{-i\frac{E}{\hbar}t} \quad (1.17)$$

We can put this new constant, E , back into the left side of equation (1.15) and then multiply again by $\psi(x)$. The result is something new, but familiar:

$$-\frac{\hbar^2}{2m} \frac{d^2 \psi}{dx^2} + V(x)\psi(x) = E\psi(x) \quad (1.18)$$

This is called the **Time Independent Schrodinger Equation** (TISE). This equation, (1.18) is the convenient starting place for rest of the procedures in this text - and works consistently provided that the potential function, V does *not* change with time. By using this separation of variables technique, we have turned the full Schrodinger Equation, (1.11), a *partial* differential equation, into two separate, *ordinary* differential equations, (1.16) and (1.18).

What we've just done is set ourselves up so that solving the time- independent equation (1.18) will produce the spatial function, $\psi(x)$ and then solving the time dependent equation, (1.16) will produce the temporal function, $\phi(t)$. Just as prescribed by our separation relationship, (1.12), multiplying these two pieces together will produce our actual wave function, $\Psi(x, t)$.

It is important to know as well that using separation of variables provides an infinite set of solutions to the PDE. There are infinitely functions $\psi(x)$ that satisfy the equation given the way we have chosen to solve it. Furthermore, the separation technique, where $\Psi(x, t) = \psi(x)\phi(t)$ is only a part of the picture - for example one could choose to look at solutions of the form $\Psi(x, t) = \psi(x) + \phi(t)$ which would in turn provide another set of infinite solutions.

The separation technique does however allow for some convenient properties:

- **General Time Dependence**

Despite not having this function exactly, at the moment, we can still do a lot with the information that we currently have. We have established that the time portion is *not* dependent on the potential, so that whenever we do find $\psi(x)$, we can simply multiply the same function, (1.17) by any spatial solution. Thus any full solution as a form:

$$\Psi(x, t) = \psi(x)e^{-i\frac{E}{\hbar}t} \quad (1.19)$$

- **Linear Combination**

The Schrodinger equation is a *linear* partial differential equation. This means that a linear combination of known solutions is *also* a valid solution as well. So, if we have a collection of solutions scaled by some constant, $c_1\psi_1(x)$, $c_2\psi_2(x)$, ..., $c_N\psi_N(x)$, etc., adding them all together is yet *another* possible wave function. Thus now, any $\Psi(x, t)$ actually can be expressed as:

$$\Psi(x, t) = \sum_n c_n \psi_n(x) \phi_n(t) = \sum_n c_n \psi(x) e^{-i\frac{E_n}{\hbar}t} \quad (1.20)$$

Notice how $\phi(t)$ also changes with n , we will explore this in a little while.

- **Probability Density**

The complex exponential in the time function eliminates itself when multiplied by it's own complex conjugate. When we compute $|\Psi(x, t)|^2$, the quantity $e^{-i\frac{E}{\hbar}t}e^{+i\frac{E}{\hbar}t}$ becomes just $e^0 = 1$. Thus the time component does not affect our normalization constant from before.

The bulk of chapter 2 will be dedicated to solving equation (1.18) for very specific potential functions, $V(x)$ and why they are so important.

In short, we now have a more digestible way of handling quantum physics. What we've done here, is a means to an ends - or rather a means to a beginning of *playing* the game and quantum mechanics. While our treatment of the subject so far is *purely* mathematical, it's important to understand that it's very important to playing out the ground work for the rest of the subject.

1.4 The Language of the Game

As you can see from the previous sections of this chapter, quantum physics is very much a mathematically heavy topic. In classical physics, we can make qualitative observations of the universe and then build mathematical models around those observations. Early on, we established that Newton's 2nd Law, equation (1.1) becomes a dominant figure in the field and such second order, ordinary differential equations become the language of classical physics.

In quantum physics, the Schrodinger Equation, (1.2) is the dominant figure, and it would make such that second order partial differential equations become the language of quantum physics. As strange as it may sound, the dominant set of tools used for the mathematics of quantum mechanics is mostly based in *linear algebra*.

Linear algebra is a type of mathematics that deals largely with vectors, matrices and the idea of spaces and dimensions. However, English physicist Paul Dirac used principles from linear algebra to build in part, his own system of notations designed especially for handling the mathematics of quantum physics. In reality, this system of notation is not essential for quantum physics, but instead allows us to simplify a great deal of concepts, and convey information in a new way.

I shall assume that you are familiar with linear algebra, if not on a fully function level, at least in concept. As dense as a next few sections of read may be, it's important to remember that functionally, all of the math in quantum is just as you've been taught in the past, only expressed differently. In order to introduce each piece and rule of notation, I'll describes it's relation and origin from linear algebra as well.

Vectors, and Bras and Kets

A vector is a mathematical object that allows very simply to communicate the dimension, components, magnitude and orientation of a measurement all very conveniently. Typically, a vector is notated as a variable with a little arrow on top such as $\vec{\psi}$. The vector is then made up of N discrete components. They can be written out in columns or rows, for example:

$$\vec{\psi} = [\psi_0, \psi_1, \dots, \psi_{N-1}] = \begin{bmatrix} \psi_0 \\ \psi_1 \\ \vdots \\ \psi_{N-1} \end{bmatrix} \quad (1.21)$$

The number of components, N indicates the dimension of the vector, i.e., it is N -dimensional. The entry in each index represents the length or *measure* of the vector in that particular component. Note that each entry, a_n can be a real, imaginary or complex value. In quantum mathematics, we replace the linear algebra object of a *column* vector with the *new* mathematical object called a *ket*.

A ket is notated as $|\psi\rangle$

and has many of the same properties as a vector.

Just like a vector, a ket exists in a space, has components and can interact with other mathematical objects. It shares almost all of the same properties as vectors. A ket can be modified by a (real, imaginary or complex) scalar value and can also be multiplied by a matrix (which we'll call an *operator* later) to produce another ket. They can be compared to *bras* with inner products and outer products and can be arranged into linear combinations as well.

In addition to the ket, there is a related mathematical object called a *bra* which takes the place of a *row* vector, and has all of the same properties as a ket.

A bra is notated as $\langle\psi|$

The relationship between bras and kets is simply that they are each other's *transpose - complex conjugates*. More mathematically, a bra is this *dual space* counterpart to the ket vector space, and vice-versa. This means that:

$$\langle\psi| = |\psi\rangle^* \quad \text{and} \quad |\psi\rangle = \langle\psi|^* \quad (1.22)$$

Where the asterisk symbol denotes a transposition and complex conjugate operation to be applied. Every ket has a corresponding bra, and every bra has a corresponding ket.

$$|\psi\rangle \longleftrightarrow \langle\psi| \quad (1.23)$$

Suppose for example is the ket $|\alpha\rangle$ is defined by N real, imaginary or complex discrete components:

$$|\alpha\rangle \equiv \begin{bmatrix} \alpha_0 \\ \alpha_1 \\ \vdots \\ \alpha_{N-2} \\ \alpha_{N-1} \end{bmatrix} \quad (1.24)$$

Then it's dual space, or bra equivalent, $\langle\alpha|$ is then defined as it's *transpose, complex conjugate*:

$$\langle\alpha| = |\alpha\rangle^* \equiv [\alpha_0^* \quad \alpha_1^* \quad \dots \quad \alpha_{N-2}^* \quad \alpha_{N-1}^*] \quad (1.25)$$

There are some important distinctions between vectors, kets and bras that need to be outlined as they *are not* the same thing. Vectors typically have a finite number of discrete components in them, and thus are limited to finite dimensional spaces. A ket or bra on the other hand, can potentially have an infinite amount of components in it. Where a vector is a set of discrete indexes, a ket or bra can thought of as a set of continuous set of values. Furthermore, a ket or bra can be used to express a function, or rather the output of a function. A ket with infinite entries can be used to convey the output of a single, smooth, and continuous function.

For example, the ket, $|\beta\rangle$ could be used to represent the continuous output for the complex defined function:

$$|\beta\rangle = \beta(t) \equiv (a + ib)e^{-i\omega t} \quad (1.26)$$

Then it's dual space, or bra equivalent, $\langle\beta|$ is again defined as it's complex conjugate:

$$\langle\beta| = \beta^*(t) \equiv (a - ib)e^{+i\omega t} \quad (1.27)$$

Computationally, vectors and kets are handled in the exact same way because a computer cannot convey an infinite number of points to produce a line or function. Rather, they are limited to holding a discrete number of values. Because of this, vectors, kets and bras are all handled mostly as list or array - like mathematical objects. After all, they hold many of the same properties and can *often* be used interchangeably. If the notation $\langle\psi|$ or $|\psi\rangle$ ever confuses you, just remember that are *functionally vectors* with certain additional properties.

Vector Products and Bra-Kets

It may come as no surprise that Paul Dirac used the names "bra" and "ket" together. Very cleverly, and perhaps humorously, when they combine, they create a mathematical operation of a *bra-ket* or in linear algebra, the *dot product* (often also called scalar product or inner product). Image two discrete vectors, \vec{f} and \vec{g} , both of length N . The dot product between them is defined as:

$$(\vec{f} \cdot \vec{g}) \equiv \sum_{i=0}^{N-1} (\vec{f}_i)(\vec{g}_i) \quad (1.28)$$

In words, each index of one vector is multiplied by that same index in the other vector, and then each product is summed to output a single scalar number, real or complex.

The Dirac equivalent is the *inner product* and is notated by the combination of a bra and ket, conveniently called a *bra-ket*.

A bra-ket, or inner product, is notated as $\langle f|g\rangle$

Just like before, if the bra and ket are both discretely defined, $\langle f|$ and $|g\rangle$, then the inner product of them is similar to equation (1.28), except with the added complex conjugate:

$$\langle f|g\rangle \equiv \sum_{i=0}^N (f_i^*)(g_i) \quad (1.29)$$

Conversely, if a ket and bra are both continuously defined functions of x , $\langle f(x)|$ and $|g(x)\rangle$ as in (1.26) and (1.27), then the inner product takes as lightly modified form. The discrete sums from equation (1.29) now becomes a continuous, infinite sum, *an integral*! So, the inner product of $f(x)$ and $g(x)$ (on the basis of x) now becomes:

$$\langle f(x)|g(x)\rangle = \int f^*(x)g(x)dx \quad (1.30)$$

Furthermore, harking back to the wave function directly, we can use this new concept and notation to help. With the wave function, $\Psi(x, t)$, found, then we can write the probability density for the system, given in equation (1.4), as an inner product.

$$\langle \Psi | \Psi \rangle = \int \Psi^*(x, t) \Psi(x, t) dx \quad (1.31)$$

In the conventional notation for quantum physics, this is usually the standard way of expressing the probability density for a particle, given a wave function. This also usually comes with the implication that the function is already normalized, i.e. the constant A has been absorbed into the inner product such that it alone is equal to 1:

$$\langle \Psi | \Psi \rangle = 1 \quad (1.32)$$

This also introduces the idea of *orthonormality*, which we will expand upon later as it comes up so frequently in quantum physics. Two states, $|\psi_m\rangle$ and $|\psi_n\rangle$ are orthonormal if they are orthogonal, (ortho-) and normalized (-normal). IF the states are orthogonal, their dot product, or inner product in our case, is 0. We will see that states that are solutions to the Schrodinger equation almost always are orthonormal. We can conveniently express this by using the *Kronecker Delta* symbol, δ_{mn} which is defined:

$$\delta_{n,m} = \begin{cases} 1 & , n = m \\ 0 & , n \neq m \end{cases} \quad (1.33)$$

We usually indicate orthonormality between two states, we write: $\langle \psi_m | \psi_n \rangle = \delta_{mn}$.

In addition to the bra-ket combination representing the inner product of two states, the ket-bra combination is the *outer product* of two states. Where the inner product returns a scalar value, the outer product returns a matrix (or operator in our case).

A ket-bra , or outer product, is notated as $|f\rangle\langle g|$

For any state ψ , it's outer product return the identity matrix, or identity operator by definition:

$$|\psi\rangle\langle\psi| = \hat{1} \quad (1.34)$$

It is also important to note that the properties of bras and kets are preserved in the inner product operation as well. For example, the complex conjugates of an inner product has the property:

$$\langle \psi | \phi \rangle^* = \langle \phi | \psi \rangle \quad (1.35)$$

Where the complex conjugate operation is applied to $\langle \psi |$ and to $|\phi \rangle$ to becomes $|\psi \rangle$ and $\langle \phi |$ respectively.

And all of these relations for bras and kets hold true with the analog to vectors. For example, a set of three orthogonal basis vectors in 3D Cartesian space may define a coordinate system, just as three orthogonal kets or bras may be used to define the space or coordinate system. A linear combination of kets is also a valid concept, such as equation (1.20) would take the form:

$$\Psi(x, t) = \sum_n^{\infty} c_n |\psi_n(x)\rangle \phi_n(t) \quad (1.36)$$

Matrices and Operators

Another important tool from linear algebra is the *matrix* object. In some ways, a matrix is a concatenation of various column or row vectors that together produce a square or rectangular grid of entries. This matrix can be thought of as a *linear operator*- a mathematical object that takes some object - a vector (or a ket) and turns it into another object - another vector (or ket).

In quantum physics, this matrix concept is extremely important - but instead of being a matrix with finitely many components and entries, it is called an *operator* that has potentially infinity many entries. Because of this, a matrix in linear algebra becomes an operator in quantum physics.

An operator is notated as \hat{Q}

Just like before, this operator now possesses some neat intrinsic qualities. An $N \times M$ matrix A could take a $M \times 1$ vector, \vec{v} and transform it into a $N \times 1$ vector, \vec{w} - given by the matrix vector equation:

$$\vec{w} = A\vec{v} \quad (1.37)$$

With Dirac notation would then become:

$$|w\rangle = \hat{A} |v\rangle \quad (1.38)$$

Where all elements could be either finitely dimensional or infinitely dimensional.

All operators also have a respective *inverse* operator.

An inverse operator is notated as \hat{Q}^{-1}

This has the effect of sort of "undoing" what ever its counterpart did before. So, if operator \hat{Q} takes the state $|x\rangle$ and transforms it into the state $|y\rangle$, such that:

$$|y\rangle = \hat{Q} |x\rangle \quad (1.39)$$

Then the inverse operator \hat{Q}^{-1} takes the state $|y\rangle$ and then transforms it into $|x\rangle$ such that:

$$|x\rangle = \hat{Q}^{-1} |y\rangle \quad (1.40)$$

When operators are combined with their inverse, they have the net effect of doing nothing! Any operator combined with it's inverse produces the *identity operator*. In quantum physics, this is commonly called the *one - operator*, and in matrix form from linear algebra, it is simply the *identity matrix* - a matrix with all zeroes, and ones as the main diagonal.

$$\hat{1} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix} \quad (1.41)$$

Using this matrix of operator on any ket or vector has the effect of doing *nothing*:

$$|x\rangle = \hat{1} |x\rangle \quad (1.42)$$

Compared to other mathematical operations, this makes sense. When pairing an arithmetic operation with it's inverse, it returns the original value. For example. adding and subtracting the same value, multiplying and dividing and exponentiation and logarithms are operations and inverses respectively. We can summarize this by writing out this relationship mathematically. Any operator acting on it's inverse (or vice versa) returns the original state:

$$|x\rangle = \hat{Q}^{-1}\hat{Q} |x\rangle = \hat{Q}\hat{Q}^{-1} |x\rangle = \hat{1} |x\rangle \quad (1.43)$$

It is also convention of dirac notation that operators act on the state *to their right*. This means that when faced with the statement:

$$|x\rangle = \langle a | \hat{Q} | b \rangle \quad (1.44)$$

The correct order of application can be denoted by parentheses:

$$|x\rangle = \langle a | \left(\hat{Q} | b \rangle \right) \quad (1.45)$$

In some cases, operators *do* act on the state to their left, in which case, it is notated as:

$$|x\rangle = \left(\langle a | \hat{Q} \right) | b \rangle \quad \text{or} \quad |x\rangle = \left\langle \hat{Q} a \right| b \rangle \quad (1.46)$$

Discrete Probability

As expressed before, vast parts of understanding quantum physics relies on probability and statistical interpretations of mathematics. Since a large part of this text will be dedicated the *numerically* handling quantum systems, I want to take some time just out outline probability for discrete distributions, as computers would understand them. In order to better grasp these concepts, I want to establish common system of language and notation for dealing with this.

Suppose we have some discrete probability density ρ with k entries, and ρ_i means the number of samples at some index i . For most standard programming languages, this distribution would be modeled as a simple 1D array of values of length k .

$$\rho = [\rho_0, \rho_1, \rho_2, \dots, \rho_i, \dots, \rho_k] \quad (1.47)$$

The total number of samples would be given by summing up all of the numbers of sample at each index up to all k entries, or simply summing the contents of the array. Mathematically is given by:

$$N = \sum_{i=0}^k \rho_i \quad (1.48)$$

We can also multiply this sum by some constant A such that $N = 1$ and all probabilities are measured with respect to 1. We can use this probability density function, ρ to determine some other neat parameters for this functions as well:

- **The Probability of a Single Outcome**

The statistical likelihood of single outcome, i , occurring in the distribution ρ , can be thought of as the number of sample at that index, divided by the total number of sample at all indexes:

$$P(i) = \frac{\rho_i}{N} \quad (1.49)$$

If ρ is a normalized, then summing up all of the $P(i)$'s will result with the value 1.

- **The Probability of Multiple Outcomes**

The statistical likelihood of multiple outcomes, say m of them, is the sum of the m outcomes divided by the total number of outcomes.

$$P(i) = \frac{1}{N} \sum_{i=0}^m \rho_i \quad (1.50)$$

- **Average Value or Expectation Value**

The average of a function or distribution, *rho* is commonly denoted as $\bar{\rho}$ or in Dirac notation as: $\langle \rho \rangle$. It is given the sum all elements, divided by the number of elements, or by the sum of each index entry times the probability of each entry.

$$\langle \rho \rangle = \frac{1}{N} \sum_{i=0}^k i(\rho_i) = \sum_{i=0}^k i(P(i)) \quad (1.51)$$

- **Expectation of Squares**

Computing the expectation of each value squared, $\langle \rho^2 \rangle$ is another useful quantity in statistics. Take every element, square it, multiply by the probability of that element, then sum over each index:

$$\langle \rho^2 \rangle = \sum_{i=0}^k i^2(P(i)) \quad (1.52)$$

We can use these concepts to measure on average, how much each sample in our distribution or array differs from the average. This quantity is often informally referred to as the "spread" of the data. However, the average of the difference between each sample and the average will actually by definition equate to zero!

$$\Delta\rho = \sum_{i=0}^k (\rho_i - \langle\rho\rangle) = 0 \quad (1.53)$$

To get around this, we can deal only in absolute values, in the form of squaring the entries, and then averaging them. This paves the way for our last two quantities of interest.

- **Variance**

The variance of a distribution measures how much a data set differs from its average by ignoring the direction of the deviation:

$$\sigma_\rho^2 \equiv \langle(\Delta\rho)^2\rangle = (\langle\rho^2\rangle - \langle\rho\rangle^2) \quad (1.54)$$

- **Standard Deviation**

Finally, by taking the square root of both sides, we can compute the standard deviation of the distribution:

$$\sigma_\rho \equiv \sqrt{\langle(\Delta\rho)^2\rangle} = \sqrt{(\langle\rho^2\rangle - \langle\rho\rangle^2)} \quad (1.55)$$

Since we can confirm that for any data distribution, $\langle\rho^2\rangle \geq \langle\rho\rangle^2$, we can safely guarantee that both the variance and standard deviation of a data set will always be real and non-negative. Both these concepts will come in handy a great deal when we introduce *Heisenberg's Uncertainty Principle* in chapter 3.

1.5 The Characters in the Game

Dirac Notation

As I showed in the previous sections, the notation system developed by English physicist Paul Dirac, is a very powerful tool in not just understanding the math, but the intuition behind a lot of quantum physics. It is important to have the connection between the quantum mechanical objects and their linear algebra counterparts, but it's also important to understand how they differ. However, the big token of Dirac notation that I want to hit on in this subsection is the difference between

$$|\psi_n\rangle \quad \text{and} \quad \psi_n(x) \quad \text{and} \quad |\psi_n(x)\rangle \quad (1.56)$$

This distinction is often overlooked, or taught and then dismissed shortly afterwards. So in that spirit, the same will only be partly done here, however for the sake of clear conscience before we proceed, let's address this.

The object $\psi_n(x)$ is simply a *function* of the input variable x . If we were to treat Schrodingers as a purely mathematical object, with no implications of physics, then we could say that $\psi_n(x)$ is one possible spatial solution to the partial differential equation. Again, because of the linearity of the PDE, then a linear combination of these *functions* is also a valid solution.

The object $|\psi_n\rangle$ is a *state*, typically on the x -basis unless specified. A state is a possible condition that a quantum system can be in. in particle $|\psi_n\rangle$ is the n -th possible value for that state. Often, a state is not represented by an explicit function, so we simply use Dirac notation. It is also worth noting that a linear combination of these states is also a valid way to express a solution to Schrodingers Equation.

In reality, these two can be used almost interchangeably without too much harm done. In fact, they are essentially convey *almost* the same idea. When you see the object $\psi_n(x)$, you should think to yourself, " $\psi_n(x)$ is a spatial solution to Schrodinger's Equation, which corresponds to the state $|\psi_n\rangle$ ". Similarly, when you see $|\psi_n\rangle$, you should think " $|\psi_n\rangle$ is a possible state for the quantum system to be in, which is given by the function $\psi_n(x)$ ".

Finally, this leads us to the object $|\psi_n(x)\rangle$, which is simply the bastardization of the two previous examples. In fact, there is actually nothing wring with using this notation, as is does really drive the relationship home. Depending on the context, it is however, more conventional to use one as oppose to the other three. When talking about purely solving differential equation, or just equations in general, it is more consistent to use $\psi_n(x)$ over the Dirac notion. After all, we first learned about a ket to be analogous to a vector, and we don't generally think of derivatives of a vector. So, when dealing with things like a full mathematical equation, we use the function. Conversely, when dealing with operators and linear combinations, we tend to work more this Dirac notion.

Spaces and Basis

One of the strangest concepts from quantum physics and linear algebra is the idea of *spaces*. It's very abstract idea, and is often tossed around without much care or attention to it fully. For the purposes of this work, we can treat *space* as the quantity in which values are measured with respect to. For example, if we track the position of a vibrating mass on a spring as as function of time, $x(t)$, we are producing measurements in *time-space* or we are operating in a *time-basis*.

If we apply the Fourier Transform to this time - space, we then have the equivalent function, $x(f)$, but now in *frequenecy - space*. Similarly, Applying a Laplace Transformation moves us into *Lapace - space*, or applying the derivative operator to to the original $x(t)$ function moves us into *velocity - space*. This is a rather incomplete and perhaps paralytically oversimplified idea of this mathematical concept, but the true understanding of the nature of a space is left as an excessive to the reader.

It is important not to confuse space and basis ideas with dimensionality. That is, for the purpose of everyday life, we live in three-spatial dimensions, each component is a measurement in a position basis (we sometimes call this the x -basis as x is often used by convention to denote position). Vectors in this 3D space, have three components in it. However, As I introduced earlier on, there may be *many* more than three dimensions contained within *aket*, which we recall is the quantum mechanical equivalent to a vector object. When we handle kets numerically, in computer program, they may be represented as arrays of thousands of floating-point numbers. And when we show them symbolically, they may be representative of entire functions, thus making them out to have *infinite* components, thus making them practically *infinitely* dimensional.

Part of the trouble comes from trying to geometrically justify everything, and trying to expand our brains to picture something beyond 3D. Unfortunately, this is rather difficult, which serves as an immediate turn-off to most people when first working with linear algebra. One of the pitfalls of our mathematical description of the quantum universe is the necessity of working in these higher dimensional spaces - in which we cannot simply draw a picture of or imagine in our minds. Instead, we have to rely on the math, which fortunately, does *not* change. Meaning, that if we are comfortable working with 3×3 matrices, and 3 -vectors, all of the axioms and rules that apply to those objects also apply to our new quantum objects.

For a quick few examples, let $|a\rangle$, $|b\rangle$ and $|c\rangle$ all be kets in some N (possibly infinite) dimensional space- commonly notated as \mathbb{R}^N for a real space. Let α , β and γ be scalars.

- **Consistency of Dimensions**

All mathematical operations below produce resulting kets or bras that remain in the \mathbb{R}^N space.

- **Community of Addition**

When adding $|a\rangle$ and $|b\rangle$, changing the order of the elements does not matter: $|a\rangle + |b\rangle = |b\rangle + |a\rangle$.

- **Associativity of Addition**

When adding combinations of $|a\rangle$, $|b\rangle$ and $|c\rangle$, changing the order of the elements does not matter: $(|a\rangle + |b\rangle) + |c\rangle = |a\rangle + (|b\rangle + |c\rangle)$.

- **Identity of Addition**

Under the addition operation, there is some ket, $|0\rangle$ such that when added to a ket $|c\rangle$, it retains all properties as before the operations: $|c\rangle + |0\rangle = |c\rangle$. In linear algebra, this is referred to at the *zero- vector* or *null-space*. In Dirac notation, this is called the *zero-ket* or *null- ket*.

- **Inverse of Addition**

There exists an operation, much that it has the opposite effect of addition - subtraction. This works such that it 'undoes' addition: $|a\rangle + (-|a\rangle) = |0\rangle$. It also follows such that if $|a\rangle + |b\rangle = |c\rangle$, then $|c\rangle - |b\rangle = |a\rangle$.

- **Distributivity of Multiplication**

Multiplication operation in a vector space has a distributive property: $\alpha(|b\rangle + |c\rangle) = \alpha|b\rangle + \alpha|c\rangle$.

- **Associativity of Multiplication**

Multiplication operation in a vector space has an associative property: $\beta(\gamma|a\rangle) = (\beta\gamma)|a\rangle$.

- **Identity of Multiplication**

Under the multiplication, there is some operator, $\hat{1}$, such that when multiplied by a ket, $|c\rangle$, it retains all properties as before the operation: $|c\rangle = \hat{1}|c\rangle$. In linear algebra, this takes the form of the identity matrix. It is also to note that the outer product product of a normalized kets and bra has the property such that: $|b\rangle\langle b| = \hat{1}$.

Any mathematical object that adheres to these rules - bras, kets, vectors, matrices, operators, polynomials, etc - is an R^N dimension space. It is also important to write out that despite dealing with *infinite* or higher dimensions, I am *not* saying that as you get down to the quantum level, that the universe is no longer 3 dimensional. The universe, to our best knowledge, and as a reasonable assumption for this text is strictly based in 3 spatial and 1 time dimension. When we say, that these objects like matrices, bras and kets are N dimensional, we are talking about our mathematical treatment of the subject, and asserting that the physical universe still is 3D.

Position Space

Position space, also referred to the *position basis* functions as a system of measurement. For systems in one dimension, we commonly call this the x - *basis*, in reference to the x - *axis* of a Cartesian coordinate system. Regardless of exact nomenclature, a measurement in position space, is a measurement of the particles position. So, when we write $\Psi(x, t)$, this is a probability amplitude of the particle on the x -*basis*. If we were to measure $\Psi(y, t)$, this is a wave function on the y -*basis* or $\Psi(r, t)$ is on the r or *radial* - *basis*. All are still position - basis measurements.

For most of the topics in this text, everything will be measured with respect to some form of a position basis, be it Cartesian, spherical, or cylindrical. This works nicely due to its intuitive nature. Just like in classical physics, we generally measure a particles position (usually as a function of time), and then build up the rest of our model from there. Much of quantum physics works in the same way, except obviously, instead of a well-defined position function $x(t)$, we have this information encoded in our wave function, $\Psi(x, t)$.

Momentum Space

The other common space, or basis to use in quantum physics is the *momentum basis*. While indeed less common, it is also very useful to measure the momentum of a particle. In

classical physics, momentum is just defined as the product of a particles mass and velocity, however in quantum physics, momentum comes with a different set of properties. Momentum is measured on a different *basis*, which means that we cant just multiply the change of the particles position, by it's mass, we require some mathematical way to move between position space and momentum space - we require a *transform*.

The exact derivation of this transform is a tricky one, and once again will be left a much more detailed text. However, very simply, we can recognize that the Schrodinger equation has a simple, plane wave solution:

$$\Psi(x, t) = e^{\frac{i}{\hbar}(px - Et)} \quad (1.57)$$

By taking the partial *spatial* derivative, we can be that:

$$\frac{\partial}{\partial x} [\Psi(x, t)] = \left(\frac{i}{\hbar}p\right) e^{\frac{i}{\hbar}(px - Et)} \quad (1.58)$$

When then then algebraically solve for the operator \hat{p} acting on the state Ψ . This then show us that the momentum measurement of the state $|\psi\rangle$ would be notated as:

$$\hat{p}|\psi\rangle = -i\hbar \frac{\partial}{\partial x} |\psi\rangle \quad (1.59)$$

And just the momentum operator on the x - *basis* is given by:

$$\hat{p} = -i\hbar \frac{\partial}{\partial x} \quad (1.60)$$

This is fairly complicated idea, that we need a sort of transform or operator to move between measurements of position and momentum. Classically, this makes very little sense, and seems to essentially come from nowhere. But this is just one of the many oddities that arises out of our mathematical description of quantum physics.

It works a lot like the *Fourier Transform* in other mathematical and engineering disciplines. That transform takes some period signal function of time, $g(t)$ and transforms it into a function of frequency, $g(f)$. In doing this, the exact same information is contained in both functions, but the information is contained in different ways. In the function $g(t)$ a signal is represented in a time domain - or a *time basis*, and the function $g(f)$ is represented in the frequency domain, or a *frequency - basis*.

The same idea holds true for this position - momentum relationship. They contain very similar bits of information - just encoded in a different way. There is also the added concept of *uncertainty*, which actually prohibits us from knowing both position and momentum at the same time - but we will get to that later. But just as we can express momentum in position- space , we must also be able to express position in momentum space. This would be akin to an *inverse Fourier transform*.

Position on the momentum basis, acting on the state $|\psi\rangle$ would be notated as:

$$\hat{x}|\psi\rangle = -i\hbar \frac{\partial}{\partial p} |\psi\rangle \quad (1.61)$$

And just the (x) position operator on the p - basis is given by:

$$\hat{x} = -i\hbar \frac{\partial}{\partial p} \quad (1.62)$$

Hilbert Space

Hilbert space carries different rules and definitions in the worlds of physics and mathematics. It also serves a very different purpose than the other basis measurements in this section. Rather than try to define it, it would be better to simply explain its place in quantum physics and what it's used for. Very basically, **functions can only exist in Hilbert Space if they are square - normalizable over defined bounds**. This means that wave functions live in Hilbert space, and any function whose inner product with itself is a real, finite number is also in Hilbert space. In practice, for this text, your knowledge of Hilbert space need not extend much beyond this, but to seal the deal, I'll just cover some quick rules and examples.

- **Finite Inner Product**

A function or state, $f(x)$, exists in Hilbert space if and only if its inner product with itself is a finite value:

$$\langle f(x)|f(x)\rangle = \int_a^b |f(x)|^2 dx < \infty \quad (1.63)$$

- **Normalization Constant**

Similarly, there must be *some* constant A to scale $f(x)$ by such that its inner product becomes normalized to one.

$$\langle f(x)|f(x)\rangle = |A|^2 \int_a^b |f(x)|^2 dx = 1 \quad (1.64)$$

- **Domains**

Functions can exist or not exist in Hilbert space depending on their domain. For example, the state $|f(x)\rangle = e^{Kx}$ (where $K > 0$) over all of space, $(-\infty, +\infty)$ *does not* live in Hilbert space because it cannot be normalized. Similarly, the same can be said about the function over the bounds $[0, +\infty)$. However on the bounds, $(-\infty, 0]$, $f(x)$ *does* exist in Hilbert space because it can be normalized.

- **Boundary Conditions**

A general rule of thumb is that when dealing with infinite bounds, a function or state, $f(x)$, is only in Hilbert space if it goes to 0 in the limit of approaching positive or negative infinity:

$$\lim_{x \rightarrow \pm\infty} f(x) = 0 \quad (1.65)$$

For example, a Gaussian function, $f_1(x) = e^{-x^2}$, or the sinc function, $f_2(x) = \sin(x)/x$ both live in Hilbert space over infinitive bounds. However, other exponentials, $f_3(x) = e^x - x$ or $f_4(x) = \cos^2(x)$ do not live in Hilbert space over infinite bounds because they do not abide by equation (1.65).

1.6 The Eigenvalue Problem

Now that we have more solid foundation for the mathematics of quantum physics, we can really break down Schrodinger's equation, and turn it into something truly nice and simple - and something far more reasonable to handle numerically. We have to make the starting realization that **this equation, is nothing more than measuring the total energy of the quantum system**, with something called the *Hamiltonian*!

The Hamiltonian

The Hamiltonian is a concept from classical physics, far predating quantum mechanics. It's exact derivation, rules and properties are quite complicated, and yet another task for a different text. For now, just know that the Hamiltonian is an operation that returns the *total energy* of a particle or system by summing the kinetic and potential energies. So, lets create an operator \hat{T} that when acting on a particle in the state, $|\psi\rangle$ for example, it returns the total *kinetic* energy of that particle in that state. Similarly, create an operator \hat{V} that when acting on a particle in the state, $|\psi\rangle$ it returns the total *potential* energy of that particle in that state. So summing the operators has the result of returning the *total* energy:

$$\hat{H} |\psi\rangle = \hat{T} |\psi\rangle + \hat{V} |\psi\rangle = \text{Total Energy of State } |\psi\rangle \quad (1.66)$$

Breaking down the potential energy operator, \hat{V} , it loosely can be seen that $\hat{V} |\psi\rangle$ very closely resembles the terms from the time independent Schrodinger equation, $V(x)\psi(x)$. Now other than convenient constancy of letter choices, this may be quite tough to see at first. But all long, that's what the function $V(x)$ has been telling us. It can be very loosely thought of as:

$$\hat{V} |\psi\rangle \approx V(x)\psi(x) \quad (1.67)$$

When multiplied by the wave function, $\psi(x)$, that term in the TISE gives us the potential energy distribution. This term, $V(x)\psi(x)$, tells us how the potential energy function over space $V(x)$ *interacts* with the particle's wave function $\psi(x)$.

Now examining the kinetic energy operator, \hat{T} , this may be hard to fathom as well. From classical physics, we know that the kinetic energy of a particle of mass m , moving at velocity v is given by: $T = \frac{1}{2}mv^2$. But in quantum physics, velocity is not something that we commonly work with, its not really a valid measurement to make. Instead, we measure the *momentum* of the particle. Classically, momentum is given by $p = mv$, and thus we can use this to

re-express our kinetic energy function: $T = \frac{p^2}{2m}$. We can express this again as operators in our quantum language:

$$\hat{T} |\psi\rangle = \frac{1}{2m} \hat{p}^2 |\psi\rangle = \frac{1}{2m} \hat{p} \hat{p} |\psi\rangle \quad (1.68)$$

And knowing how the momentum operator is defined from equation (1.60), we can apply the operator twice as noted by \hat{p}^2 , and see that the kinetic energy can be expressed as:

$$\hat{T} |\psi\rangle = \frac{1}{2m} \left(-i\hbar \frac{\partial}{\partial x} \right) \left(-i\hbar \frac{\partial}{\partial x} \right) |\psi\rangle \quad (1.69)$$

(Remember that the momentum operator is applied to the state $|\psi\rangle$ twice, *not* multiplied by each other) Which can be simplified down into the familiar form:

$$\hat{T} |\psi\rangle = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} |\psi\rangle \quad (1.70)$$

Lets revisit the time dependent Schrodinger equation, (1.2) in the form:

$$-\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} |\psi\rangle + V(x) |\psi\rangle = i\hbar \frac{\partial}{\partial t} |\psi\rangle \quad (1.71)$$

Now we can see that each term functions as an energy measurement:

$$\textbf{Kinetic} \quad \hat{T} |\psi\rangle = -\frac{\hbar^2}{2m} \frac{d^2}{dx^2} |\psi\rangle \quad (1.72)$$

$$\textbf{Potential} \quad \hat{V} |\psi\rangle = V(x) |\psi\rangle \quad (1.73)$$

$$\textbf{Total} \quad E |\psi\rangle = i\hbar \frac{\partial}{\partial t} |\psi\rangle \quad (1.74)$$

Putting all of these pieces together, allows to *rewrite* the Time Independent Schrodinger Equation, (2.1), using the Hamiltonian from equation (1.66). We can take the *whole* second - order, linear, partial differential equation and turn it into:

$$\hat{T} |\psi\rangle + \hat{V} |\psi\rangle = E |\psi\rangle \quad (1.75)$$

or more compactly:

$$\hat{H} |\psi\rangle = E |\psi\rangle \quad (1.76)$$

The Hamiltonian operator, that returns the total energy is equal to the total energy? *Yes!* It seems almost obvious now, except this one equation has something else hidden in it. This equation tells is that an operator acting on a ket, is equal to a scalar times that same ket. In linear algebra, this is equivalent to a matrix acting on a vector begin equal to a scalar times that same vector. **Equation (1.76) is an *Eigenvalue Problem!*** In linear algebra, this is most commonly written in the general form:

$$A\vec{v} = \lambda\vec{v} \quad (1.77)$$

This is a *staggering* realization, and the entirety of the first chapter of this text has been in service to this moment! If we can encode the total energy of a quantum system into some matrix/operator, \hat{H} , then we can treat almost all of quantum physics as an eigenvalue problem. No need to build some complex algorithm to numerically model a partial differential equation, as long as we have an algorithm that can compute the eigenvalues and eigenvectors of an $N \times N$ matrix, we can produce a numerical solution to almost any 1D quantum system, provided that $V(x)$ does not change with time.

Once we build this \hat{H} operator/matrix in some computer program, we can have it solve the eigenvalue problem for us! The resulting N *eigenvectors* are the quantum states $\psi_n(x)$ or $|\psi_n\rangle$ and the resulting N *eigenvalues* are the corresponding energies for each quantum state.

And with this eigenvalue interpretation of the Time Independent Schrodinger Equation, also comes some other consequences. Each energy-eigenstate, $|\psi_0\rangle, |\psi_1\rangle, \dots |\psi_{N-1}\rangle$ is *orthonormal* to all of the other energy-eigenstates. This means that is each eigen ket is appropriately normalized to 1, then each ket's inner product with any other ket is identically 0. We right this as:

$$\langle\psi_n|\psi_m\rangle = \delta_{n,m} \quad (1.78)$$

Where $\delta_{n,m}$ is the Kronecker Delta function as from equation (1.33).

The very last peice of the puzzle that we have to put together for this section is to take equation (1.76), and insert a specific eigen-energy state $|\psi_n\rangle$, with energy E_n , in place of $|\psi\rangle$ and left multiply it by the bra $\langle\psi_n|$. In doing so, the new eigen-equation becomes an expectation value, equated to an inner product:

$$\langle\psi_n|\hat{H}|\psi_n\rangle = \langle\psi_n|E|\psi_n\rangle \quad (1.79)$$

And since energy, E_n is a scalar, we can factor it out of the inner product. So the right-hand side of the equation above becomes equal to $E \langle\psi_n|\psi_n\rangle$. We have also learned that the orthonormality of eigen-states from equation (1.78), causes the right side just becomes E_n . The left hand side is then $\langle\psi|\hat{H}|\psi\rangle$ the expectation value of the Hamiltonian operator in the state $|\psi_n\rangle$ or more compactly $\langle\hat{H}\rangle$. This leads us to a very useful piece of information:

$$\langle \hat{H} \rangle = \langle \psi_n | \hat{H} | \psi_n \rangle = E_n \quad (1.80)$$

The expectation value, or average value of the Hamiltonian operator in some energy-eigenstate, $|\psi_n\rangle$, *is the energy in that state!*, E_n . This further shows the very intimate relationship between the Hamiltonian, the energy-eigenstate and the energy eigen-values, which will drive forward much of our understanding of quantum physics in the chapters that follow.

1.7 Analyzing a Quantum System

We've spent the entirety of this chapter diving pretty far down the rabbit hole for just a few pages. In reality, much of the information here is covered over the course of a few chapters of many standard quantum mechanical texts. To put it all together, we'll use some of the concepts that we've discovered in this chapter to do a very basic (and admittedly very 'scripted') quantum mechanics problem from a *somewhat* of a start, to a *somewhat* of a finish.

Putting a System Together

So, suppose we've solved, or set up a quantum mechanical system, and found that it is a *two-state* system, it is composed of two energy-eigenstates: $|\psi_1\rangle$ and $|\psi_2\rangle$, with respective energies E_1 and E_2 . Recall that these two kets are the eigenkets of the eigenvalue problems from equation (1.76) and their function counter parts, $\psi_1(x)$ and $\psi_2(x)$ are all *also* solutions to the time independent Schrodinger equation, (1.18). Because of the linearity of the problem, we can use equation (1.36) to fully describe the system. Recall that a linear combination of solution is also a solution:

$$|\Psi(x, t)\rangle = \sum_n^{\infty} c_n |\psi_n\rangle \phi_n(t) \quad (1.81)$$

Each energy - eigenstate becomes n -th ket in the sum. And each energy - eigenvalue becomes E_n from equation (1.17), which in turn becomes the n -th time dependent function in the sum. Using our model, evaluated at time $t = 0$ becomes:

$$\Psi(x, 0) = c_1 |\psi_1\rangle + c_2 |\psi_2\rangle \quad (1.82)$$

To account for the time dependent factor, we simply *tack-on* the $\phi_n(t)$ function from (1.17). This makes our state become:

$$\Psi(x, t) = c_1 |\psi_1\rangle e^{-iE_1 t/\hbar} + c_2 |\psi_2\rangle e^{-iE_2 t/\hbar} \quad (1.83)$$

At this point, we have constructed all that we can about our quantum state. However, now suppose that we make some measurements, adjust some dials, and run some calculations and find that $c_1 = 4i$ and $c_2 = 5$. Additionally, we must impose that this state itself be normalized to 1, by multiplying the whole linear combination by some constant A . We can then finish our mathematical model by saying that our wave function for this particular quantum mechanical system is given by:

$$|\Psi(x, t)\rangle = A\left(4i|\psi_1\rangle e^{-iE_1t/\hbar} + 5|\psi_2\rangle e^{-iE_2t/\hbar}\right) \quad (1.84)$$

Recall that this is also equivalent to writing:

$$\Psi(x, t) = A\left(4i\psi_1(x)e^{-iE_1t/\hbar} + 5\psi_2(x)e^{-iE_2t/\hbar}\right) \quad (1.85)$$

And that both of these equations stem from the idea of *linear combinations of separable solutions*.

Building the Probability Density

Now that we have a complete description of our state, given by the wave function $|\Psi(x, t)\rangle$, we can build our probability density and normalize it accordingly. To produce the probability density function, we need to compute the value:

$$|\Psi(x, t)|^2 \quad \text{which can be notated:} \quad \langle\Psi(x, t)|\Psi(x, t)\rangle \quad (1.86)$$

although $\langle\Psi(x, t)|\Psi(x, t)\rangle$ implies the evaluation of the inner product over all of space.

We have already constructed the ket $|\Psi(x, t)\rangle$, so now we must construct the bra $\langle\Psi(x, t)|$. Recall the relationship between the two is given by equation (1.22). So in our case: $\langle\Psi(x, t)| = |\Psi(x, t)\rangle^*$. We compute the complex conjugate of (1.84) by applying the operation to each term. The sign in front of every term with an i gets reversed. The bra representation of our system is then:

$$\langle\Psi(x, t)| = A^*\left(-4i\langle\psi_1| e^{+iE_1t/\hbar} + 5\langle\psi_2| e^{+iE_2t/\hbar}\right) \quad (1.87)$$

which is again, equivalent to:

$$\Psi^*(x, t) = A^*\left(-4i\psi_1(x)e^{+iE_1t/\hbar} + 5\psi_2(x)e^{+iE_2t/\hbar}\right) \quad (1.88)$$

Once again, the goal is to evaluate the inner product, or simply build the integral:

$$\langle\Psi(x, t)|\Psi(x, t)\rangle = |A|^2 \int_{-\infty}^{+\infty} \Psi^*(x, t)\Psi(x, t)dx \quad (1.89)$$

And we must find some constant $|A|^2$ to multiply the integral in (1.89) by such that it is equal to 1. because just A normalizes either the bra or the ket.

Now the tricky bit comes here, when we actually have to multiply the two values together to form the inner product. However, doing out the math fully will be exhausting, especially since the resulting expansion will have *four* rather messy terms left in it — Except that it wont. If we had a three or four state system, the resulting expansion would have nine or sixteen terms respectively, but instead we can recall two important concepts:

- **Multiplying exponentials of the same base**

Multiplying exponentials of the same base requires that we sum the exponents together. So, $e^\alpha \times e^\beta = e^{\alpha+\beta}$. So in our case, every term will have an exponential function resembling $e^{-i(E_n+E_m)t/\hbar}$ in it. In the case where the energies are equal, i.e from the same state: $E_n = E_m$, then that whole function evaluates to e^0 or very simply 1! So, in the two terms where a eigen-ket is multiplied by it's corresponding eigen-bra, the time dependence exactly eliminates itself! Which is another justification why we just separable solutions to solve the TSDE.

- **Orthonormality of Energy- Eigenstates**

The orthonormality of the eigenstates harkons back to the vital idea from equation (1.78). Each of the four terms will have some inner product in it resembling $\langle \psi_n | \psi_m \rangle$ in it. If $n = m$, then the inner product evaluate to 1 since each bra and ket is appropriately normalized. This will happen in two of the four terms: $\langle \psi_1 | \psi_1 \rangle$, and $\langle \psi_2 | \psi_2 \rangle$ all evaluate to 1. In the two other terms, the orthonormality forces the inner product to evaluate to zero, and thus those same size terms all evaluate to zero.

Putting these two concepts together *drastically* simplifies our endeavor here. We've gone from this inner product, to its corresponding integral who's integrand has four separate terms in it. However, orthonormality dictates that two of those terms go to zero immediately. The remaining three terms cause their own exponential portions to evaluate to 1, and then furthermore, their inner products do the same.

For the sake of argument, we do evaluate the inner product out completely:

$$|A|^2 \left(-4i \langle \psi_1 | e^{+iE_1 t/\hbar} + 5 \langle \psi_2 | e^{+iE_2 t/\hbar} \right) \left(4i | \psi_1 \rangle e^{-iE_1 t/\hbar} + 5 | \psi_2 \rangle e^{-iE_2 t/\hbar} \right) \quad (1.90)$$

Distributing each term, allowing certain exponential to simply to e^0 :

$$\begin{aligned} \langle \Psi(x, t) | \Psi(x, t) \rangle = & \\ & \left(-16i^2 \langle \psi_1 | \psi_1 \rangle e^0 \right) - \left(20i \langle \psi_1 | \psi_2 \rangle e^{-i(E_1 - E_2)t/\hbar} \right) + \\ & \left(20i \langle \psi_2 | \psi_1 \rangle e^{-i(E_2 - E_1)t/\hbar} \right) + \left(25 \langle \psi_2 | \psi_2 \rangle e^0 \right) \end{aligned} \quad (1.91)$$

Apply the principles of orthonormality, $\langle \psi_n | \psi_m \rangle = 0$ if $n \neq m$:

$$\langle \Psi(x, t) | \Psi(x, t) \rangle = \left(-16i^2 \langle \psi_1 | \psi_1 \rangle \right) + \left(25 \langle \psi_2 | \psi_2 \rangle \right) \quad (1.92)$$

Since $\langle \psi_n | \psi_n \rangle = 1$, the result is actually just the coefficients of the two surviving terms.

$$\langle \Psi(x, t) | \Psi(x, t) \rangle = \left(|4i|^2 + |5|^2 \right) \quad (1.93)$$

Because we must have a normalized probability density, we must equate all of this to the value of 1. i.e., the inner product of the state with itself must be 1, so we multiply by some constant $|A|^2$.

$$|A|^2(|4i|^2 + |5|^2) = |A|^2(16 + 25) = 1 \quad (1.94)$$

and finally, it can be found that $A^2 = \frac{1}{41}$ and thus $A = A^* = \frac{1}{\sqrt{41}}$.

At this, our *normalized* probability density for our wave function $\Psi(x, t)$ from equation (1.89) becomes:

$$P(x, t) = \langle \Psi(x, t) | \Psi(x, t) \rangle = \frac{1}{41} \int_{-\infty}^{+\infty} \Psi^*(x, t) \Psi(x, t) dx \quad (1.95)$$

As in accordance to our rules of the wave function earlier in this chapter, evaluating this integral over all of space will produce the value 1. And evaluating the integral between some bounds a to b where $a \neq b$ gives the probability of finding the particle on the x - axis between those bounds at some time t .

Lastly, we cannot forget to apply the new normalization constant to the original bras and kets that we constructed earlier, This has the effect of absorbing the constant A and A^* *inside* the integrand. The linear combination ket becomes:

$$|\Psi(x, t)\rangle = \frac{4i}{\sqrt{41}} |\psi_1\rangle e^{-iE_1t/\hbar} + \frac{5}{\sqrt{41}} |\psi_2\rangle e^{-iE_2t/\hbar} \quad (1.96)$$

and the linear combination bra becomes:

$$\langle \Psi(x, t) | = -\frac{4i}{\sqrt{41}} \langle \psi_1 | e^{+iE_1t/\hbar} + \frac{5}{\sqrt{41}} \langle \psi_2 | e^{+iE_2t/\hbar} \quad (1.97)$$

Energy Measurements

Finally, we can analyze the energy of this quantum system. We know that there are two possible energy eigenstates, and two corresponding energy eigenvalues. This means that if we choose to measure the energy of this system, we can only get one of two values: E_1 or E_2 . But since we know that quantum physics is a game of probability, what is the *probability* that we measure one state with its particular energy over the other?

The answer lies with the coefficients of our linear combination of solutions. **The actual physical representation of the c_n coefficients is that $|c_n|^2$ gives the probability of the state $|\psi_n\rangle$ occurring.** So then the probability of measuring each energy state is given by:

$$\begin{aligned}
P(E_1) &= |c_1|^2 = \left(\frac{+4i}{\sqrt{41}}\right)\left(\frac{-4i}{\sqrt{41}}\right) = \frac{16}{41} \\
P(E_2) &= |c_2|^2 = \left(\frac{5}{\sqrt{41}}\right)\left(\frac{5}{\sqrt{41}}\right) = \frac{25}{41}
\end{aligned}
\tag{1.98}$$

Thus, state $|\psi_1\rangle$ will appear 16/41 times and state $|\psi_2\rangle$ will appear the remaining 25/41 times when the energy is measured. Notice also how as a product of the normalization, the sum of the probability coefficients is 1. Thus, you are always guaranteed to measure *some* state at all times. Suppose there are k possible states in our quantum system, then we must have:

$$\sum_n^k |c_n|^2 = 1 \tag{1.99}$$

And similarly, the expectation value of the Hamiltonian operator in a quantum system is the sum of all possible energies, *weighted* by their respective probability of occurring.

$$\langle \hat{H} \rangle = \sum_n^k |c_n|^2 E_n \tag{1.100}$$

Thus for the system above,

$$\langle \hat{H} \rangle = |c_1|^2 E_1 + |c_2|^2 E_2 = \frac{16}{41} E_1 + \frac{25}{41} E_2 \tag{1.101}$$

A more *complete* or more simplified expectation value cannot be determined unless values for E_1 and E_2 are explicitly given.

1.8 Takeaways from this Chapter

Finishing up this chapter, I want to highlight the important things that we've learned. After all we've gone through, we'll finish with a short list of the more important things to remember from this chapter.

Sections 1 - 3

- **The Schrodinger Equation** is the governing equation for all of elementary quantum physics:

$$-\frac{\hbar^2}{2m} \frac{\partial^2 \Psi}{\partial x^2} + V(x)\Psi = i\hbar \frac{\partial \Psi}{\partial t} \tag{1.102}$$

- Quantum physics relies on **statistical interpretation** to interpret past measurements and predict future measurements on a system. Exact values cannot be determined, and can only be predicted according to probability densities.

- The **wave function** is the solution to the Schrodinger equation, and takes the separated form:

$$\Psi(x, t) = \psi(x)\phi(t) \quad (1.103)$$

It contains encoded within it, all possible information that can be known about a quantum particle. mathematically, it gives a probability amplitude.

- The exact **probability density function** is given by multiplying the wave function by it's own complex conjugate.

$$P(x, t) = \Psi^*(x, t)\Psi(x, t) = |\Psi(x, t)|^2 \quad (1.104)$$

By convention, we normalize this function to the value 1, such that all evaluated probabilities are measured out of 1.

- Evaluating this **probability density between the bounds a and b gives the probability of the particle existing in the space between position a and position b** . If the bounds are $-\infty$ and $+\infty$ respectively, the integral *must* evaluate to 1.
- The wave function and it's first derivative **must be continuous**, except where the potential function takes on infinite values.
- By assuming a potential function, $V(x)$ to be constant with respect to time, we derive the **Time Independent Schrodinger Equation** with the separation of variables technique.

$$-\frac{\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2} + V(x)\psi = E\psi \quad (1.105)$$

- This allows all time dependence to become a complex exponential, which cancels itself out when taking the inner product:

$$\phi_n(t) = e^{-iE_n t/\hbar} \quad (1.106)$$

- The Schrodinger equation is a linear partial differential equation, so a linear combination of solutions is also a valid solution:

$$\Psi(x, t) = \sum_n^{\infty} c_n \psi_n(x) \phi_n(t) \quad (1.107)$$

Sections 4 - 5

- Quantum physics is a mathematically intensive branch of physics that relies on **linear algebra and Dirac notation** to express itself effectively. This involves the use of bras and kets to take the place of vectors, operators to replace matrices and other notation tricks for convenience. Operators, bras, kets and combinations of make up most of the backbone for the mathematics.

- **Statistics also allows for some important measurements in quantum physics.** These includes, expectation values, variances, standard deviations, and general probability functions.
- Linear ket spaces play a large role in the math of quantum physics and when combined with diraction notation allows us to express information in higher dimensions in the same way we mathematically handle lower dimensions. Typically, measurements on a quantum system are made in *position space*, *momentum space*, and occasionally *energy space*. These spaces require mathematical transforms to move between them.

Sections 6 - 7

- Schrodinger's equation uses the hamiltional operator from classical physics to *measure the total energy of a quantum mechanical particle*. Using that Hamiltonian operator, it sums the kinetic and potential energy of the system. We can then turn the entirety of the Schrodinger equation into a simple *energy eigen equation*:

$$\hat{H} |\psi\rangle = E |\psi\rangle \quad (1.108)$$

- Each ket, $|\psi\rangle$ that **satisfies this eigenvalue problem is also solution to the Schrodinger equation for the specific potential function**. The corresponding eigenvalue, E , is the energy for that particular solution. This *vastly* simplifies our system when trying to solve it numerically.
- Each energy -eigen state, $|\psi_0\rangle, |\psi_1\rangle, \dots, |\psi_N\rangle$; is orthogonal to all of the other kets when it is normalized to 1. This principle is called **orthonormality** and once again does a great distance when simplifying our mathematical description.

Chapter 2

Playing the Game: Quantum Physics in 1 Dimension

This chapter of this text will be devoted to applying what we've learned about the basic and the mathematical behavior of quantum physics to specific potential cases in one spatial dimension. Over the course of this chapter, the specific potential cases examined are very similar to cases explored in other quantum texts. This similarity is due to the interesting cases, and important lessons that arise from each possible potential function. It is important to take all of this with a grain of salt, however as these are obviously over-idealized circumstances, that need to be heavily expanded upon before becoming of any real-world use or application.

For this chapter, the 1-Dimensional Time Independent Schrodinger Equation (1D TISE) will be the starting place for each particular case, as we will assume to that all of these potentials exist on a single, infinitely long line, and remain constant with time. The 1D TISE is again:

$$-\frac{\hbar^2}{2m} \frac{d^2\psi}{dx^2} + V(x)\psi = E\psi \quad (2.1)$$

Which can also be written in it's operator eigenvalue form:

$$\hat{H}|\psi\rangle = E|\psi\rangle \quad (2.2)$$

In Each potential case, as part of the nature of this text, I will discuss the methods used in numerically solving the Schrodinger equation. As modern the complexity of modern science and engineering increases, it becomes more obvious that the ability to solve such a complicated partial differential equation is an effort in faultily. Because of this, I will present the analytical solution to the equation, as it would be solve by hand, and than compare that result to something produced numerically. This way, you have a mathematical foundation to sit upon and a more reasonable way to go about solving any arbitrary quantum system. This of course is not to discredit the hard work of pre-computation physicists and mathematicians,

but rather allows us to solve for systems that are increasing complex, and even systems that *cannot* simply be solved in terms of any arbitrary functions.

2.1 The Infinite Square Well

Analyzing the System

Arguably the simplest case for a potential function (and among the most unreasonable), the *infinite square well* is a sort of *rite-of-passage* for students learning about quantum physics. It uses a very simple potential function case and allows for some nice simplifications to be made, and it can be used as a great start to see how some of the math and physics of the subject really start to fit together.

We start with a potential function, $V(x)$, peicewise defined:

$$V(x) = \begin{cases} +\infty & , \quad x < 0 \\ 0 & , \quad 0 \leq x \leq L \\ +\infty & , \quad x > L \end{cases} \quad (2.3)$$

Before we even do math, we can take some time to analyze the physical nature of the system. The first thing that comes to mind is the presence of the $+\infty$ values outside the range 0 to some arbitrary position L . We have essentially used the potential function values to create a well, of some width, L , with walls that infinitely high - hence the name of "the infinite square well". From classical physics, you may interpret this as being stuck between two infinitely tall mountains or something of the sort. Either way, the infinite potential value forces the particle to be confined in this regions of length L , because no matter how much energy or force is applied to that particle, it *can never escape* the infinite square well.

Right off of that bat, this allows for some great simplifications. First off, no matter what, Our particle cannot exist in the region $x < 0$ or $x > L$ because of the infinite amount of energy required to get there. Therefore, this quantum mechanical particle can *only* exist in the region $0 \leq x \leq L$. With this, can can focus all of our attention to this region of space. All of the rules outline in the previous chapters still apply, but now we only have this small region of space to worry about.

Solving the System 'By Hand'

For the region between $x = 0$ and $x = L$, the TISE reads:

$$-\frac{\hbar^2}{2m} \frac{d^2\psi}{dx^2} = E\psi \quad (2.4)$$

Notice how the $V(x)\psi(x)$ term from equation (2.1) is gone because $V(x) = 0$ in these bounds. Now, we actually have much simpler equation to solve. We can use some algebraic manipulation to rearrange equation (2.4) into something very familiar from classical physics.

$$\frac{d^2\psi}{dx^2} = -\frac{2mE}{\hbar^2}\psi \quad (2.5)$$

This is the standard ordinary differential equation for a mass-spring or any sort of harmonic oscillator -like system. This comes up all of the time in classical physics and is usually formed by equating Newton's second law, to Hooke's Law of ideal springs. For simplicity's sake, lets make the assertion that a new constant can be created: $k = \frac{\sqrt{2mE}}{\hbar}$. (Note that is relies on the assumption that E must be a positive value.) This changes the differential equation to:

$$\frac{d^2\psi}{dx^2} = -k^2\psi \quad (2.6)$$

Which has the solution:

$$\psi(x) = \alpha e^{+ikx} + \beta e^{-ikx} \quad (2.7)$$

Which thanks to *Euler's Identity*, can be rewritten as:

$$\psi(x) = a \sin(kx) + b \cos(kx) \quad (2.8)$$

Here, a and b are constants chose based on initial condition or boundary conditions. From chapter 1, we learned that the wave function, $\psi(x)$ must be continuous over all space, and must be continuously differentiable over all of space. Since the potential function itself is not continuous differentiable (i.e. is peicewise defined), we can break this second rule. Regardless, since $\psi(x < 0) = 0$, and $\psi(x > L) = 0$, we can impose the boundary conditions on our system such that $\psi(x = 0) = 0$ and $\psi(x = L) = 0$.

Applying these boundary conditions:

$$\psi(0) = a \sin(0) + b \cos(0) \quad \text{and} \quad \psi(L) = a \sin(kL) + b \cos(kL) \quad (2.9)$$

Because of the nature of the sine and cosine functions, the only way for these equations to hold true is one of two ways. If $a = b = 0$, the whole wave function becomes $\psi(x) = 0$ which is a valid solution to the PDE, but not normalizeable, thus conflicts with one of our rules. Hence, the other option, just $b = 0$ is the valid conclusion. The resulting wave function for the infinite square well of width L is:

$$\psi(x) = a \sin(kx) = a \sin\left(\frac{\sqrt{2mE}}{\hbar}x\right) \quad (2.10)$$

Where kx must be an integer multiple of π : $kx = \pm\pi, \pm2\pi, \pm3\pi, \dots, \pm n\pi, \dots$

Because of the rotational symmetry of sine, ($-\sin(\theta) = +\sin(\theta)$), the negative integers become redundant, and since the function must fit "neatly" into a region L , the distinct spatial solutions to the problem become:

$$\psi_n(x) = A \sin\left(\frac{n\pi}{L}x\right) \quad (2.11)$$

These n functions are the stationary *energy eigenstates* to this problem and can be notated with kets: $\psi_n(x) = |\psi_n\rangle$. The constant that normalizes this ket is $A = \sqrt{\frac{2}{L}}$. Just as prescribed by the equivalent eigenvalue problem, each eigenstate is appropriately orthonormal to the other eigenkets.

$$\langle\psi_n|\psi_m\rangle = \frac{2}{L} \int_0^L \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{m\pi x}{L}\right) dx = \delta_{n,m} \quad (2.12)$$

Recall that $\delta_{n,m}$ returns 1 if $n = m$ and 0 if $n \neq m$.

Note that because we have eliminated all imaginary numbers from the time independent solutions for this problem, each ket is also its own complex conjugate: $|\psi_n(x)\rangle = \langle\psi_n(x)|$

Since we now have a collection of infinitely many eigenkets, we must also find each energy - eigenvalue as well - E_n . Since we know that $\frac{n\pi}{L} = \frac{\sqrt{2mE}}{\hbar}$, we can algebraically solve for E_n and see that:

$$E_n = \frac{n^2\pi^2\hbar}{2mL^2} \quad (2.13)$$

Now we have a complete set of energy - eigenstates, given by $|\psi_n\rangle$ and all the corresponding energy - eigenvalues, given by E_n . Note that there are in infinite amount of both and perfectly match one - to - one. Every unique state $\psi_n(x)$ has a unique energy E_n and vice-versa. Finally, to complete our analytical solution, we can form a linear combination all states, and include the general time dependence onto our solution from eqn.(1.16) . This the full solution to the infinite square well of width L is given by:

$$\Psi(x, t) = \sqrt{\frac{2}{L}} \sum_n c_n \sin\left(\frac{n\pi x}{L}\right) e^{-i\left(\frac{n^2\pi^2}{2mL^2}\right)t} \quad (2.14)$$

The value of each c_n is the square root of the probability of the particular eigen-state of occurring after an energy measurement. In most cases, this value can only be determined empirically.

Solving the System Numerically

Be sure to read the Mathematical Appendix for note on how to build the Hamiltonian operator for some arbitrary potential!

2.2 The Finite Square Well

Analyzing the Problem

The setup for the finite square problem is almost identical to the infinite square well problem, except that the walls of the well that contain our particle are now finite - as the name of the problem would suggest. To, ease the computations in this problem, we will move the well to be centered with our coordinate origin now. So, let's keep the box of width L , and push it $L/2$ units to the left, and create side walls each having the same potential to be a finite value, V_0 , which can be positive or negative.

The potential function is defined:

$$V(x) = \begin{cases} V_0 & , \quad x < -\frac{L}{2} \\ 0 & , \quad -\frac{L}{2} \leq x \leq +\frac{L}{2} \\ V_0 & , \quad x > +\frac{L}{2} \end{cases} \quad (2.15)$$

Again, just as before, the peice-wise definition of the potential allows us to solve the TISE individually for the three separate regions. Despite not being able to make some immediate simplifications as we did with the infinite square well, the newly imposed symmetry will help us soon.

Solving the System 'By Hand'

Beginning with the edges of the systems, the potential is a constant value, V_0 , which can be positive or negative. For the regions $-\infty < x < -L/2$, and $+L/2 < x < +\infty$, the TISE reads:

$$-\frac{\hbar^2}{2m} \frac{d^2\psi}{dx^2} + V_0\psi = E\psi \quad (2.16)$$

Which looks a little bit more challenging to solve than the previous problem, however, we can subtract the quantity $V_0\psi$ from both sides. We can then factor out the wave function ψ from the potential and energy constants, thus our equation now reads:

$$-\frac{\hbar^2}{2m} \frac{d^2\psi}{dx^2} = (E - V_0)\psi \quad (2.17)$$

Now, we realize that this equation here is *very* similar to the ODE that we built for the infinite square well in equation (2.4). Infact, our procedure to solve this equation is almost identical to the way we solved that ODE. Lets do some quick algebraic manipulation again.

$$\frac{d^2\psi}{dx^2} = -\frac{2m}{\hbar^2}(E - V_0)\psi \quad (2.18)$$

Now we are ready to solve our the equation again, except we need to take a closer look at the quantity contained within the parenthesis above. This quantity is telling us the difference between the total energy of the particle E and the potential function energy V_0 . Depending on how these values related to each other, it changes to possible solution to the wave equation.

Solving the System Numerically

Be sure to read the Mathematical Appendix for note on how to build the Hamiltonian operator for some arbitrary potential!

2.3 Multiple Square Wells

2.4 The Harmonic Oscillator

2.5 The Free Particle

Analyzing the Problem

The free particle, while once again physically unproducable, serves as an interesting study case because of how different it is than the previous systems that we've described so far. The system begins with a potential function that is simply defined:

$$V(x) = 0 \tag{2.19}$$

Which then causes the TISE to become:

$$-\frac{\hbar^2}{2m} \frac{d^2\psi}{dx^2} = E\psi \tag{2.20}$$

To which we know is a second-order differential equation with the solution:

$$\psi(x) = \alpha e^{+ikx} + \beta e^{-ikx} \tag{2.21}$$

This may at first look rather convenient, because we've started in the exact same place that the infinite square well has, except that that system was neatly confined into a space between $x = 0$ and $x = L$, to which we could impose boundary conditions and derive an analytically solution. Here however, rather than the particle stuck within the region of space, it is free to move wherever it pleases in the vast expanse of space. Image the entire observable universe (collapsed into one dimension) devoid of all matter and life, expect for a single quantum mechanical particle. It is free to travel and move as it pleases (while still subject to Schrodinger's Laws).

Because of this lack of boundary conditions, it appears that the particle can take on *any* possible energy value

2.6 The Delta Function

Chapter 3

The Rules of the Game

Just like any other subject, game or endeavor, quantum physics has a great many rules that go along with it. Be already outlined a great deal of these rules from a mathematical context, but this is not what I mean. Sure we can talk about how the same rules of linear algebra, differential equations and calculus all play roles in the physics, but getting bogged down in the math would be a great disservice. Instead, we'll call the rules of the game more like "formalisms" or "extra notes" on some of the topics that we've discovered already.

3.1 Observables and Hermitian Operators

Operators are a huge part of quantum physics. They allow us to both conceptually and mathematically gather so much information about a quantum state. For example, if we had some quantum system described the the ket $|\psi_\alpha\rangle$, and then we wanted to know the total energy of this system, we just act on it with the Hamiltonian operator \hat{H} . Even if we don't know *exactly* how this operator works, or it's composition in a linear algebra context, we know that the quantity:

$$E_\alpha = \langle \psi_\alpha | \hat{H} | \psi_\alpha \rangle = \langle \hat{H} \rangle \quad (3.1)$$

is the total energy of the state $|\psi_\alpha\rangle$.

Furthermore, without anything anything else, we can find the *average* total energy of the system across a linear combination of quantum states, $|\Psi\rangle$, would be given by:

$$\langle E \rangle = \int \Psi^* \hat{H} \Psi dx = \langle \Psi | \hat{H} | \Psi \rangle \quad (3.2)$$

Any operator that returns a *physical* measurement on a state such as position, momentum, or energy is called an *observable*. This concept is very important because being an operator also being an observable implies some extraneous conditions. We could for instance define some arbitrary operator, \hat{Q} , that returns some undetermined or unimportant quantity of our

state. This operator comes with no external consequences- the value or values returned can be essentially anything.

Observables on the other hand, require that any measurements returned from them be *real* values. Intutively, this makes a lot of sense, because we cant have an imaginary or complex measurement for average energy, it just doesn't make sense. Imaginary numbers are brilliant and useful mathematical tools for handling waves and oscillations and so many other topics, but in the real world, they aren't physical values. So, the outcome of a physical measurement, but be a physically realistic value, it must be real. So if \hat{Q} is some arbitrary observable operator, then:

$$\langle \hat{Q} \rangle = \langle \hat{Q} \rangle^* \quad (3.3)$$

This also forces us to recall some properties about Dirac notation. We know equation (3.3) is true, and the expectation value of an operator is given by (3.2), furthermore, the complex-conjugate of an inner product reverses the bra and kets with in. Thus:

$$\langle \Psi | \hat{Q} | \Psi \rangle = \left(\langle \Psi | \hat{Q} | \Psi \rangle \right)^* = \left(\langle \Psi | \hat{Q} \right) | \Psi \rangle = \langle \hat{Q} \Psi | \Psi \rangle \quad (3.4)$$

This property must hold true for all wave functions and states. An operator that is an observable has this very unique property. We can extend this property even a step further here, and define something called a *Hermitian Operator*, which has an additional requirement:

$$\langle \Psi_a | \left(\hat{Q} | \Psi_b \rangle \right) = \left(\langle \Psi_a | \hat{Q} \right) | \Psi_b \rangle \quad (3.5)$$

The operator acting in either direction produces the same result. Any operator that has all of these properties, is then a Hermetian operator. **In quantum physics, all observables are given by Hermitian operators.**

3.2 Commutivity

In mathematics, operations can have the property of commutivity: that is: they commute. This means, that the order that they are applied to each other, or to another object is irrelevant to the outcome of that procedure. For example, multiplication is the most common and intuitive example of this. If we have two scalar values, a and b , the order that they are multiplied- that is the order that they *operate* on one another does not change the outcome. the product $a(b)$ is identical to the product $b(a)$. Thus the difference between ab and ba is zero.

In linear algebra and matrix multiplication, this is not always the case. Matrix A acting on matrix B may not not always be the same as matrix B operating on matrix A : thus they *do not* commute. So we have the property: $AB \neq BA$. There are some very specific exceptions to this rule, but more often than not in practice, matrices will not commute.

If two matrices - or in quantum physics, two *operators* commute, their *commutivity* is said to be zero. We test this relationship with the *commutivity operator* defined below for two arbitrary operators \hat{Q} and \hat{R} :

$$[\hat{Q}, \hat{R}] \equiv \hat{Q}\hat{R} - \hat{R}\hat{Q} \quad (3.6)$$

All this operator does is return the difference between the order of the operators acting on some state. If the operator returns zero, then \hat{Q} and \hat{R} commute. If the result is non-zero, the operators do not commute. From this commutator, we can also establish some important rules for the operator. For any operator , A , B and scalar α , β :

- | | |
|---|--|
| <ul style="list-style-type: none"> • Self Commutivity:
 $[A, A] = 0$ • Commutivity with Scalars:
 $[\alpha, A] = 0$ • Anti-symmetry:
 $[A, B] = -[B, A]$ • Hermitian Conjugates:
 $[A, B]^\dagger = [B^\dagger, A^\dagger]$ | <ul style="list-style-type: none"> • Factorization of Scalars:
 $[\alpha A, B] = \alpha[A, B]$ • Distributive across addition:
 $[A + B, C] = [A, C] + [B, C]$ • Multiplication:
 $[AB, C] = A[B, C] + [A, C]B$ • Multiplication:
 $[A, BC] = [A, B]C + B[A, C]$ |
|---|--|

Many of these rules can be extended to include nested commutation relations and various interactions with scalars and other mathematical objects.

The role of the commutator operator is very important in quantum physics, and will especially carry us through our discussion of uncertainty. It also gives rise to some helpful relations, most notably the *canonical uncertainty relation* that relates the position and momentum operators:

$$[\hat{x}, \hat{p}] = \hat{x}\hat{p} - \hat{p}\hat{x} = i\hbar \quad (3.7)$$

3.3 More on the Statistical Interpretation

The *statistical interpretation* of quantum physics is really the model that governs our understanding of the subject. It's arguably both a mathematical and philosophical logic that we use to describe this branch of physics. As we discussed early on, one of the most challenging parts of quantum is to accept the idea that unlike classical physics, almost nothing can be known with complete certainty. Always with every measurement outcome comes a deal of uncertainty and we handle this with elementary statistics.

We we first looked at the Schrodinger equation, we also noticed how it is a *linear* partial differential equation, which has the property that a linear combination of solutions is also a valid solution. This means that when we find a single solution, $|\Psi_1\rangle$, then scaling that by some constant is also a solution $c_1 |\Psi_1\rangle$. Furthermore, we found that in some cases for time independent potentials, like the infinite square well, the solution may take the form of infinite series, where each term is scaled by some coefficient c_n .

As it follows, then it turns out that that when multiplying that number by it's own complex conjugate: $|c_n|^*|c_n|$, it's winds up being the relative chance of the particular state $|\Psi_n\rangle$ of occurring. So, just like at the end of chapter 1, we can explore another example of how the statistical interpretation works:

Suppose we have a quantum mechanical system composed of infinitely many energy-eigen states. We can express this as:

$$\Psi(x, t) = \sum_{n=1}^{+\infty} c_n |\Psi_n\rangle \quad (3.8)$$

Recall that each state $|\Psi_n\rangle$ is composed of a spatial component $\psi_n(x)$ and a time component $\phi_n(t)$ as per our separable solutions in chapter 1, equation (1.12). Each state also has a unique energy- eigenvalue as well E_n .

We then hand our mathematical model and system setup a well- qualified experimentalist. She then takes our setup, and applies what she knows about both the mathematical and practical end of quantum physics (beyond the scope of this work) to our system. She returns to us soon after with some great news! After much testing she has found the results:

$$c_1 = -2 \quad c_2 = 3i \quad c_3 = 1 - 6i \quad c_4 = 16 \quad c_5 = 3 + 4i \quad c_{(n>5)} = 0 \quad (3.9)$$

Furthermore, she and her team have also determined that the energy of each state is just given by the values:

$$E_1 = \alpha\hbar\omega \quad E_2 = \beta\hbar\omega \quad E_3 = \gamma\hbar\omega \quad E_4 = \zeta\hbar\omega \quad E_5 = \eta\hbar\omega \quad (3.10)$$

Given her incredible reputation, you take these results be to 100% accurate with no error at all! So, let's build the linear combination of quantum states that describes our system:

$$\Psi(x, t) = -2 |\Psi_1\rangle + 3i |\Psi_2\rangle + (1 - 6i) |\Psi_3\rangle + 16 |\Psi_4\rangle + (3 + 4i) |\Psi_5\rangle \quad (3.11)$$

We now are faced with the great simplification that this is a *five - state syetem*. Now, there are only five possible quantum states that this particle can take. For whatever reason the experimental results have shown that is is *impossible* to have an energy - eigen state above $n = 5$, which is mathematically represented by the fact that all states above $n = 5$ have a coefficient of zero.

You are then asked by another physicist to analyze and determine as much about the system as you can! right away, we can determine the *relative* probability of each state to occur. As previously discussed, this is given by the particular coefficient, multiplied by it's own complex conjugate.

3.4 The Uncertainty Principle

The concept of uncertainty has become the poster child for quantum physics. No doubt that before you knew a single bit of quantum mechanics, you had probably heard someone tell you about this radical concept of *uncertainty*. Mostly likely this came in the form of being able to know either the position or the momentum of a quantum system - but *never* both. This idea stands out because its so counter intuitive that maybe it's forgivable that so many people see this as one of defining characteristics of the field.

In reality, it is *certain* that *uncertainty* really is a large part of quantum physics, any one the reasons that Schrodinger's theory was met with such distaste back in the 20th century. Even Albert Einstein who developed our models of special and general relativity thought the idea to be preposterous. The topic of uncertainty however, goes much farther than just not being able to know position and momentum together, but it really does shape our understanding of quantum physics - at least at this level.

Just like we discussed in chapter 1, all of our intuition of the macroscopic world is confirmed by our ability to take accurate and definite measurements. If we want to know position at any time, we can take a series of sample at regular time intervals to build some function to describe it as some $x(t)$. We can then compute our velocity, $v(t)$, and multiply it by our mass, m , and there we have it! Classical physics allows us to take a series of *exact* measurement that can give us our *absolute* position and out *absolute* momentum at any time. Thus we know them without any uncertainty, provided we have accurate measurements, our position and momentum values.

Part of the enigma of the situation is the fact that this not to a problem that any level of technology, or a skilled engineer or physicist can solve. Uncertainty is something baked into the laws of the natural universe. It's sort of like the speed of light, no matter how big, or powerful, or efficient the engine on your space ship is, it can *never* travel faster than the speed of light- the universe simply forbids it. Similarly in quantum physics, we will see that there are a set of measurements can are just *not compatible*! NO matter how careful we are, or how accurate a machine we build to measure these quantities, the universe prevents us from knowing some of these quantities concurrently.

The exact reasoning for this is pretty hard to justify intuitively, so just like earlier on, we are going to push through the mathematics of the situation and then use that to augment

our understanding. Recall that for any operator, \hat{Q} , the expectation value, or average value with respect to some state $|\psi\rangle$ is given by:

$$\langle \hat{Q} \rangle = \langle \psi | \hat{Q} | \psi \rangle \quad (3.12)$$

And the statistical variance of that operator is given by:

$$\sigma_{\hat{Q}}^2 = \langle \hat{Q}^2 \rangle - \langle \hat{Q} \rangle^2 \quad (3.13)$$

The variance, according to many introductory statistics references measures the *spread* of the data set. The greater the variance, the more the data is *smear*ed across your measurement basis. In classical physics, we have the luxury of a measurement variance approaching zero, as described on Chapter 1. In quantum physics, we do not have such well-defined systems and the variance, or spread of possible measurements, is almost always non-zero.

3.5 Superposition

3.6 The Ehrenfest Theorem

Chapter 4

The Next Level: The Hydrogen Atom

It may seem strange to have an entire chapter dedicated to the hydrogen atom. After all, it's the simplest atom with one proton in the nucleus, and a single electron bound to it. The Bohr model of the atom indicates that the electron "orbits" this nucleus constantly in discrete "shells", however a chemistry class would introduce to you the concept of the *Aufbau Principle* where electrons are actually bound within orbital "clouds" instead.

When Schrodinger originally published some of his work on the beginnings of quantum theory, it is the theory's ability to accurately describe the Hydrogen atom that affirmed it's validity. Because of the theory that Schrodinger and so many other developed matched the experimental behavior of Hydrogen, we accepted the place of quantum mechanics in our model of physics today. Naturally then, it's a great place to take all of the concepts that we've explored so far, along with our 1-Dimensional problems, and push ourselves to begin to solve a slightly more realistic problem.

4.1 The Schrodinger Equation in 3 Dimensions

It also follows from the hydrogen atom, that we need to expand our description of the quantum world from one spatial dimension, into three spatial dimensions. To do this, let's revisit the one dimension Schrodinger equation, aligned with the x -axis.

$$-\frac{\hbar^2}{2m} \frac{\partial^2 \Psi}{\partial x^2} + V\Psi = i\hbar \frac{\partial \Psi}{\partial t} \quad (4.1)$$

We've also learned that this equation is the quantum mechanical equivalent to the Hamiltonian operator which sums the kinetic and potential energy of a system: $\hat{H} = \hat{T} + \hat{V}$. In chapter 1, we showed how the first term in equation (4.1) was derived from the classical description of kinetic energy: $T = \frac{p^2}{2m}$.

Cartesian Basis

Since we are operating in the x dimension, we can say that the momentum measurement is solely the x -axis component of some greater *vector operator*. So, the operator \hat{p} is actually the vector operator $\vec{\hat{p}}$, and the x -axis component is given by \hat{p}_x . In the case of the kinetic energy, this operator acts twice, to give us \hat{p}_x^2 . This then forces us to recognize that there are also a \hat{p}_y^2 and a \hat{p}_z^2 component to the Kinetic Energy Operator.

So the momentum operator, is now a vector defined operator:

$$\vec{\hat{p}} = [\hat{p}_x, \hat{p}_y, \hat{p}_z] \quad (4.2)$$

And using the magnitude of that vector, we can also state that:

$$\hat{p}^2 = \hat{p}_x^2 + \hat{p}_y^2 + \hat{p}_z^2 \quad (4.3)$$

So our kinetic energy operator is actually:

$$\hat{T} = \frac{1}{2m} \hat{p}^2 = \frac{1}{2m} (\hat{p}_x^2 + \hat{p}_y^2 + \hat{p}_z^2) \quad (4.4)$$

We can also deconstruct each momentum component based on it's definition from chapter 1, equation (1.60):

$$\hat{p}_x = -i\hbar \frac{\partial}{\partial x} \quad \hat{p}_y = -i\hbar \frac{\partial}{\partial y} \quad \hat{p}_z = -i\hbar \frac{\partial}{\partial z} \quad (4.5)$$

Thus the component "squared", or rather acting twice becomes:

$$\hat{p}_x^2 = -\hbar^2 \frac{\partial^2}{\partial x^2} \quad \hat{p}_y^2 = -\hbar^2 \frac{\partial^2}{\partial y^2} \quad \hat{p}_z^2 = -\hbar^2 \frac{\partial^2}{\partial z^2} \quad (4.6)$$

We can then insert this back into the kinetic energy operator show:

$$\hat{T} = -\frac{\hbar^2}{2m} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \quad (4.7)$$

Which can be equivalently written using the *Laplacian Operator* which is defined in a 3D cartesian basis as:

$$\nabla^2 = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \quad (4.8)$$

Note that although we do not use the standard *hat* notation, the Laplacian is in fact a linear operator. We can now take this and re-write the kinetic energy operator:

$$\hat{T} = -\frac{\hbar^2}{2m} \nabla^2 \quad (4.9)$$

Finally, we can take this kinetic energy operator, now accounting for three cartesian spatial dimension and re-insert it back into the Schrodinger equation:

$$-\frac{\hbar^2}{2m} \left(\frac{\partial^2 \Psi}{\partial x^2} + \frac{\partial^2 \Psi}{\partial y^2} + \frac{\partial^2 \Psi}{\partial z^2} \right) + V\Psi = -i\hbar \frac{\partial \Psi}{\partial t} \quad (4.10)$$

Or with the Laplacian:

$$-\frac{\hbar^2}{2m} \nabla^2 \Psi + V\Psi = -i\hbar \frac{\partial \Psi}{\partial t} \quad (4.11)$$

Equation (??) is the most common way to represent the Schrodinger Equation in Higher Dimensions. This is because it appropriately generalized to cover any number of dimensions, in any coordinate systems. In each case, the Laplacian must be evaluated for that particular dimension and coordinate basis. In the case of our 3D Cartesian system, The wave function Ψ is a function of 3D space and time, $\Psi(x, y, z, t)$. Depending on the context of the situation, the potential may also be a function of all three dimensions, or even time as well.

Now we have a solid foundation for expressing Schrodinger's equation in any dimensions and in any coordinate system. It also follows, that in many cases, our method of *separation of variables* can be used under constant potential (with time) systems. Instead of a case like in equation (1.12), we may choose to separate out all three dimensions and time into *four* separate equations.

$$\Psi(x, y, z, t) = \psi_x(x)\psi_y(y)\psi_z(z)\phi(t) \quad (4.12)$$

Note that this can only be done for potential functions V that are independent of time, and *also* separable into the same basis components. The result will be the same time independent Schrodinger Equation as one dimension, just now with the Lapacian Operator taking the place of the sole second partial derivative:

$$-\frac{\hbar^2}{2m} \nabla^2 \Psi + V\Psi = E\Psi \quad (4.13)$$

And the value for $\phi_n(t)$ still holds from chapter one, equation (1.16).

It's also important to note that *every single* one of the rules and properties that we have established for the wave function, Ψ in a single dimension, also applies here. For example, We must still be able to normalize a solution for this to be a valid wave function. However, instead of the single dimensional integral normalized to 1, the full 3D volume integral must be normalized to 1. The orthogonality of two energy eigen-states also holds:

$$\langle \Psi_n(x, y, z, t) | \Psi_m(x, y, z, t) \rangle = \delta_{n,m} \quad (4.14)$$

For appropriately normalized states. In this case, normalization occurs over all of space (or at least defined regions) such that:

$$|A|^2 \int \Psi^*(x, y, z, t) \Psi(x, y, z, t) dx dy dz = 1 \quad (4.15)$$

Spherical Basis

As it turns out in Quantum Physics, Cartesian coordinate system is not always the best tool for the job. In many practical cases, such as dealing with the electromagnetic interactions between subatomic particles, a spherical coordinate system may be far more appropriate. So now we've spent all this time expanding the Schrodinger equation into a 3D Cartesian system just to move out of it? Well yes, except not all that much changes.

In the Hydrogen atom, the potential function, V , is now a function of r, θ , and ϕ instead of x, y and z axes. Similarly, we just need to adjust our Laplacian operator accordingly as well. In 3D spherical coordinates, it's defined:

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{r^2}{\sin^2 \theta} \left(\frac{\partial^2}{\partial \phi^2} \right) \quad (4.16)$$

With this in mind, we still write the Schrodinger equation and it's time independent counterpart exactly the same! (Except, of course we know that $V = V(r, \theta, \phi) \neq V(x, y, z)$) Furthermore, our separation of variables also can be done in the same way. Generally, potentials are mostly radial, and not angular, so we can simply our separation as assert our new separable solutions can take the form:

$$\Psi(r, \theta, \phi, t) = R(r)Y(\theta, \phi)T(t) \quad (4.17)$$

Notice we use $T(t)$ instead of $\phi(t)$ in order to distinguish the coordinate basis from the function, which are almost never related.

4.2 The Hydrogen Atom Structure

From basic chemistry, we know that a hydrogen atom is the simplest possible atomic structure. As mentioned before, it is composed of a single electron, bound to a proton. Both have equal magnitude, and opposite polarity charges: $q_e = -q_p$. We can then take our knowledge from electrostatics to begin to build the potential function for the electron. For simplicity of this problem, we'll consider the case where the proton is fixed to a coordinate origin, that is well-defined (as in, we are all certain exactly where the proton is)

From *Coulomb's Law*, we can integrate the force between the two particles over distance to find the governing potential function. We can also use the variable e to denote the elementary charge magnitude (1.973×10^{-19} [Coulombs]), thus the product of the electron and proton charges reduces to $-e^2$. We can then write $V(r)$ as:

$$V(r) = -\frac{1}{4\pi\epsilon_0} \frac{e^2}{r} \quad (4.18)$$

Notice how the potential is spherically symmetric (not a function of the θ or ϕ coordinate) and constant with respect to time.

Since we know how the Schrodinger equation functions in a spherical basis, we can simply insert our potential into the equation:

$$-\frac{\hbar^2}{2m}\nabla^2\Psi + \left(-\frac{1}{4\pi\epsilon_0}\frac{e^2}{r}\right)\Psi = E\Psi \quad (4.19)$$

And we hold in the back of our minds that the Laplacian operator above is define in eqn. (4.16).

We once again must solve the differential equation for the appropriate wave function. As standard, we revert to our separable, time independent solution space:

$$\psi(r, \theta, \phi) = R(r)Y(\theta, \phi) \quad (4.20)$$

Thus we can place this into the spherical TISE (4.13):

$$-\frac{\hbar^2}{2m}\left[\frac{Y}{r^2}\frac{\partial}{\partial r}\left(r^2\frac{dR}{dr}\right) + \frac{R}{r^2\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial Y}{\partial\theta}\right) + \frac{R}{r^2\sin^2\theta}\frac{\partial^2 Y}{\partial\phi^2}\right] + VRY = ERY \quad (4.21)$$

We can divide this mess by the wave function RY , multiply by $-2mr^2/\hbar^2$ and rearrange the system:

$$\left[\frac{1}{R}\frac{d}{dr}\left(r^2\frac{dR}{dr}\right) - \frac{2mr^2}{\hbar^2}[V(r) - E]\right] + \frac{1}{Y}\left[\frac{1}{\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial Y}{\partial\theta}\right) + \frac{1}{\sin^2\theta}\frac{\partial^2 Y}{\partial\phi^2}\right] = 0 \quad (4.22)$$

In writing the differential equation as such, the elements in the left bracket are only dependent of the radial component r , and the elements in the right bracket are only functions of the angular components, θ and ϕ . Just like in chapter 1, where we separated space, and time, here we separate radial space from angular space. And just as such, since they are equated to each other, each side must again be identically constant. However, instead of conveniently choosing a scalar, E , which nicely works out to be the energy of the system, we'll choose to use the quantity $l(l+1)$!

$$\left[\frac{1}{R}\frac{d}{dr}\left(r^2\frac{dR}{dr}\right) - \frac{2mr^2}{\hbar^2}[V(r) - E]\right] = l(l+1) \quad (4.23)$$

$$\frac{1}{Y}\left[\frac{1}{\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial Y}{\partial\theta}\right) + \frac{1}{\sin^2\theta}\frac{\partial^2 Y}{\partial\phi^2}\right] = -l(l+1) \quad (4.24)$$

What is l exactly? Mathematically, it is just a way of expressing the constant value of both sides. Physically, it is *quantum number*, which is an excellent topic for another section!

4.3 Quantum Numbers

By now we've seen the rise of a few very distinct quantities called quantum numbers,

Chapter 5

The Next Level: Spin and Angular Momentum

The discussion of angular momentum and spin is often left to the first few weeks of a second semester Quantum Physics course, but nonetheless is useful to have a head-start with. As we've come to see in chapter 4, physically realizable quantum mechanical systems tend to exist in three spatial dimensions, and to fully develop our understanding of 3D quantum systems, we'll need to understand angular momentum.

Just like in classical physics, angular momenta and related quantities play a great role in systems with spherically defined potentials. In the case where the potential is explicitly radially defined, $V = V(r)$, such as the hydrogen atom, orbital angular momentum becomes a physically conserved quantity. In this chapter, we'll break down the details of orbital angular momentum, spin angular momentum and how they relate to the physical system.

Before we formally begin, I want to introduce an inexplicably useful mathematical tool called the *Levi-Civita Tensor*. Don't let the fancy Italian name or word "tensor" scare you,, because it works very simply. In three dimensions, the Levi-Civita tensor is a $3 \times 3 \times 3$ perfectly *anti-symmetric* 3D tensor notated by ε_{ijk} . The symbol ε is the tensor itself, and i, j, k are indices along each axis.

Typically the indices i, j, k are used to correspond to orthogonal spatial components x, y, z . The actual numerical value of the tensor alternates between $+1$ and -1 each time i, j, k are permuted, and it becomes 0 if either i, j, k is repeated more than once. As an example, suppose i, j, k correspond to x, y, z , then:

$$\begin{aligned}\varepsilon_{ijk}, \varepsilon_{kij}, \varepsilon_{jki} &= +1 \\ \varepsilon_{ikj}, \varepsilon_{kji}, \varepsilon_{jik} &= -1 \\ \text{otherwise} &= 0\end{aligned}\tag{5.1}$$

For a practical example, we know that $[r, p] = i\hbar$, and the components

5.1 Orbital Angular Momentum

In classical physics, orbital angular momentum, \vec{L} is a vector quantity given by the cross product of position \vec{r} and momentum \vec{p} . In quantum physics, the exact same is true, and we treat angular momentum as *vector* operator:

$$\hat{\vec{L}} = \hat{\vec{r}} \times \hat{\vec{p}} \rightarrow -i\hbar \vec{r} \times \nabla \quad (5.2)$$

And thus we can resolve each Cartesian component from the cross-product, and use the quantum mechanical representation of momentum:

$$\begin{aligned} \hat{L}_x &= \hat{r}_y \hat{p}_z - \hat{r}_z \hat{p}_y \rightarrow -i\hbar \left(\hat{r}_y \frac{\partial}{\partial z} - \hat{r}_z \frac{\partial}{\partial y} \right) \\ \hat{L}_y &= \hat{r}_z \hat{p}_x - \hat{r}_x \hat{p}_z \rightarrow -i\hbar \left(\hat{r}_z \frac{\partial}{\partial x} - \hat{r}_x \frac{\partial}{\partial z} \right) \\ \hat{L}_z &= \hat{r}_x \hat{p}_y - \hat{r}_y \hat{p}_x \rightarrow -i\hbar \left(\hat{r}_x \frac{\partial}{\partial y} - \hat{r}_y \frac{\partial}{\partial x} \right) \end{aligned} \quad (5.3)$$

And Just like the momentum vector operator as a whole can relate to it's components, we can similarly write:

$$\hat{L}^2 = \hat{L}_x^2 + \hat{L}_y^2 + \hat{L}_z^2 \quad (5.4)$$

Since angular is an observable, the vector operator and each of it's components are Hermitian.

Using the definition of orbital angular momentum, and the relation $[r_x, p_x] = i\hbar$, we can work out the operator's commutivity relations. Note that all variables are operators, but the 'hat' has been omitted for readability

$$\begin{aligned} [L_x, L_y] &= [r_y p_z - r_z p_y, r_z p_x - r_x p_z] \\ &= [r_y p_z, r_z p_x] - [r_y p_z, r_x p_z] - [r_z p_y, r_z p_x] + [r_z p_y, r_x p_x] \\ &= r_y [p_z, r_z] p_x - r_x [r_z, p_z] p_y = i\hbar (r_x p_y - r_y p_x) \\ [L_x, L_y] &= i\hbar L_z \end{aligned} \quad (5.5)$$

Thus we can also show that for the other components:

$$[L_x, L_y] = i\hbar L_z \quad [L_y, L_z] = i\hbar L_x \quad [L_z, L_x] = i\hbar L_y \quad (5.6)$$

Or much more compactly with our fancy Levi-Civita Tensor:

$$[L_i, L_j] = i\hbar (\varepsilon_{ijk}) L_k \quad (5.7)$$

Since the operators do not commute, it is impossible to measure more than one component of orbital angular momentum without any uncertainty. Thus, when placed into the uncertainty principle, we can show that:

$$\sigma_{L_i}^2 \sigma_{L_j}^2 \geq \left(\frac{1}{2i} \langle i\hbar (\varepsilon_{ijk}) L_k \rangle \right)^2 = \frac{\hbar^2}{4} \langle L_k \rangle^2 \quad (5.8)$$

Additionally, as an exercise to the reader, it may be worthwhile to show the following relationships as well:

$$[r_i, L_j] = i\hbar(\varepsilon_{ijk})L_k \quad (5.9)$$

$$[p_i, L_j] = i\hbar(\varepsilon_{ijk})p_k \quad (5.10)$$

$$[L^2, L_x] = 0 \quad [L^2, L_y] = 0 \quad [L^2, L_z] = 0 \quad (5.11)$$

There also exists an angular momentum ladder operator, much like the one back from the 1D harmonic oscillator:

$$\hat{L}_{\pm} \equiv \hat{L}_x \pm i\hat{L}_y \quad (5.12)$$

Once all of these relationships have been established, you are actually reasonably far into the topic of orbital angular momentum. Much of the rules from this section can be extended into spin as well as generalized angular momentum.

Chapter 6

Mathematical Index

6.1 Building the Hamiltonian Operator Numerically in One Dimension

At the end of the first chapter, we discussed how the Time-Independent Schrodinger Equation can also be interpreted as an Energy - Eigenvalue problem. Rather than building a complicated algorithm to solve a partial differential equation that evolves with time and space, we can build a much simpler algorithm that assumes a potential function that is constant with time that solves the eigenvalue equivalent of the Schrodinger Equation. Recall the Cartesian 1-Dimensional Time Independent Schrodinger Equation is given by:

$$-\frac{\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2} + V(x)\psi = E\psi \quad (6.1)$$

And it's equivalent Energy-Eigenvalue form:

$$\hat{H} |\psi\rangle = E |\psi\rangle \quad (6.2)$$

Where $\hat{H} |\psi\rangle$ is given by the summation of the kinetic and potential energy operators:

$$\hat{H} |\psi\rangle = \hat{T} |\psi\rangle + \hat{V} |\psi\rangle \quad (6.3)$$

Numerical solutions force us to resort to discrete versions of everything in the equations above. Operators will become square matrices and functions will become arrays of floating-point numbers. As a consequence, we will also not be able to develop symbolic or *analytically* solutions. So, instead of having an energy-eigenstate defined as function in terms of the parameters of our system, we will have 1D array of numbers that will approximate the wave function. Similarly, instead of an energy-eigenvalue defined in terms of the parameters of our system, we will have a single floating-point number that approximates the energy of that state.

Notice also how the execution of a numerical solution involves *approximations* of values. This comes down to two main factors: the discrete nature of matrices and arrays, and the numerical accuracy of floating-point numbers. When operators are discretized into matrices, some information is lost, much like how a if an integral is converted into a Reimann Sum. Floating-point numbers are a computers' standard method of storing numerical values that aren't integers. They function as a sort of scientific notation in a base-2 number system instead of the human base-10 system. Given the limited number of bits, floating point numbers often are faced with rounding or small numerical deviations from expected values.

In order to mitigate some of these errors, we can choose to use an alternative unit system, sometimes called *naturalized units*. Rather than use the SI value for Plank's constant over 2π , as $\hbar \approx 1.0545... \times 10^{-34}$ kilogram-meters-squared per second, we can choose to set \hbar to have units of *itself*, i.e. $\hbar = 1$. Similarly, we can assert that the mass of the particle in question m , is also in units of *itself*, thus $m = 1$. These adjustments will reduce initial errors that result from numerical mathematics, and can always be converted back into SI units at the end of a long string of computations to reduce compounding error.

Otherwise, we transform a section of continuous space (Ideally centered about 0, but not required), $x \in [-L, +L]$ into a approximate space of N unique discrete points $x \in \{-L, -L + 1, -L + 2, \dots, +L - 2, +L - 1, +L\}$. Again, potential function $V(x)$ and wave functions $\Psi(x)$ will all be transformed into $1 \times N$ arrays $V[x]$ or $\Psi[x]$, with $x \in \{-L, -L + 1, -L + 2, \dots, +L - 2, +L - 1, +L\}$. The choice of the number of points is also important in the results of the solution as well. With a small value for N , the result will be an approximation of little physical value, and with an large value of N , the system may become too large to handle.

6.1.1 The Kinetic Energy Operator

Recall the quantum kinetic energy operator is given by:

$$\hat{T}|\psi\rangle = -\frac{\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2} \quad (6.4)$$

The goal of this section is to express this operator, \hat{T} as an $N \times N$ matrix. Firstly, we need to be able to express the second-derivative operator as a matrix.

If we examine, the first derivative operator definition we can see that is literally measuring the slope of a function $f(x)$ over an infinitesimal spatial step, h , in the limit that $h \rightarrow 0$.

$$\frac{d}{dx} [f(x)] = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h} \quad (6.5)$$

As previously stated, a computer will not allow us to use a formally defined function $f(x)$, but rather an array of discrete values. To numerically simulate a first derivative, we must use the *Finite-Element Difference Method*. We assume each index of the array, $f[x]$ is separated by some value dx such that $f[x+1] - f[x] = dx$.

With this in mind, we can rewrite the definition of a derivative for a $1 \times N$ array f of discrete values. The i -th element of the derivative array will be:

$$f'[i] = \frac{f[i+1] - f[i]}{dx} \quad (6.6)$$

Note that the array f' will contain $N-1$ elements. Using some clever arrangement of numbers in an $N \times N$ matrix, we can express a matrix-vector equation of the first-derivative operator. The $1 \times N$ array f has been transposed into an $N \times 1$ array.

$$\begin{bmatrix} f'_0 \\ f'_1 \\ f'_2 \\ \vdots \\ f'_{N-2} \\ f'_{N-1} \end{bmatrix} = \frac{1}{dx} \begin{bmatrix} -1 & 1 & 0 & \dots & 0 & 0 \\ 0 & -1 & 1 & \dots & 0 & 0 \\ 0 & 0 & -1 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & -1 & 1 \\ 0 & 0 & 0 & \dots & 0 & -1 \end{bmatrix} \begin{bmatrix} f_0 \\ f_1 \\ f_2 \\ \vdots \\ f_{N-2} \\ f_{N-1} \end{bmatrix} \quad (6.7)$$

In the case of the matrix, the f' array, has N elements, but the last point will be inconsistent due to having no difference taken.

6.2 The Eigenvalue Problem

6.3 Dirac Notation